



Missouri University of Science and Technology

# A Hands-on Introduction to Physics-Informed Neural Networks

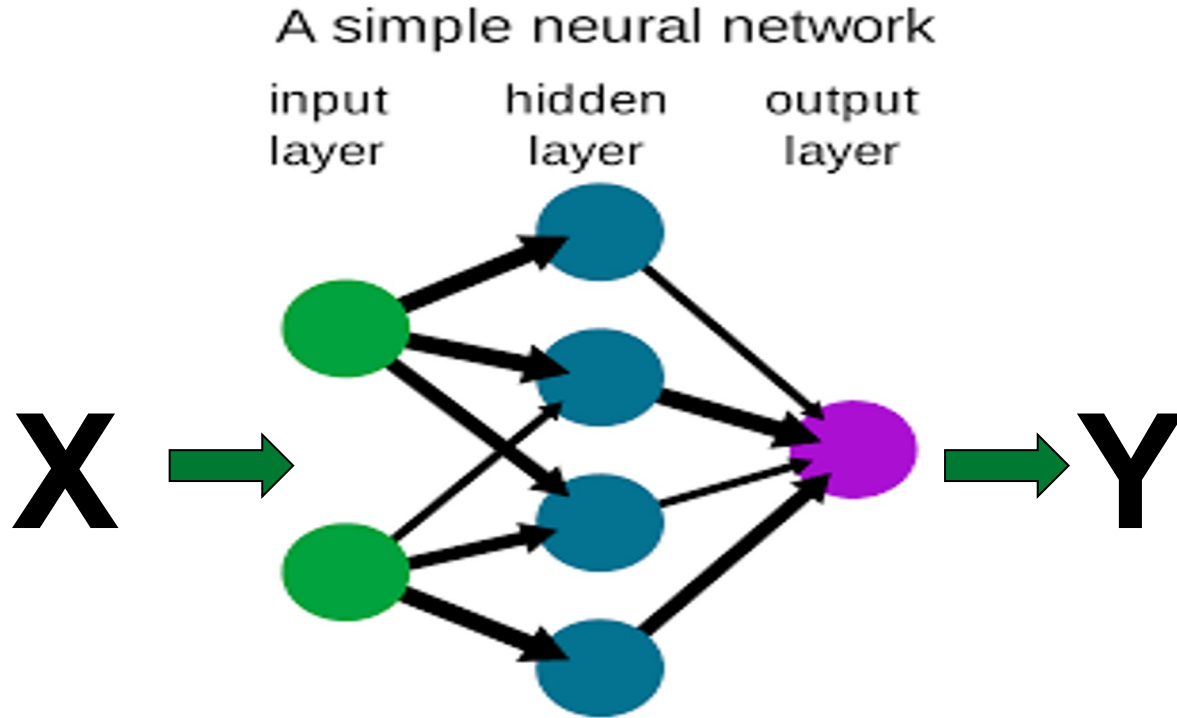
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May 20, 2024

# Objective

**How can we incorporate physical information in the form of differential equations to regularize neural networks?**

# Reminder: what's a neural network?



# Reminder: how to train a NN?

1. Mainly trained using **maximum likelihood estimation**
2. **MLE** takes the form of *squared L2 loss* when the input,  $\mathbf{X} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  (*regression*)
3. **MLE** is equivalent to *crossentropy loss* (used mainly in classification)
4. NN parameters are updated using an optimization algorithm:
  - a. **Gradient Descent (stochastic)** :

# Reminder: how to train a NN?

Repeat Until Convergence {

$$\omega \leftarrow \omega - \alpha * \nabla_w \sum_1^m L_m(w)$$

}

The diagram illustrates the weight update step in training a neural network. The equation  $\omega \leftarrow \omega - \alpha * \nabla_w \sum_1^m L_m(w)$  is shown. Three components are highlighted with red circles and arrows pointing to explanatory text: the learning rate  $\alpha$  is labeled 'learning rate'; the gradient  $\nabla_w$  is labeled 'performed using Automatic Differentiation in Tensorflow, Pytorch'; and the batch size  $m$  is labeled 'batch size'.

# Illustrative Example: Solving an ODE

❖ Is solving a Differential Equation using Artificial Neural Network completely new?

➤ **NO!**

Lagaris, Isaac E., Aristidis Likas, and Dimitrios I. Fotiadis. "Artificial neural networks for solving ordinary and partial differential equations." *IEEE transactions on neural networks* 9.5 (1998): 987-1000.

# From ODE to loss function

- ❖ Consider the IVP:

$$\frac{d\Psi}{dx} = f(x, \Psi) \quad \Psi(0) = V$$

- ❖ Can analytically satisfy the initial condition, by parameterizing  $\theta$

$$\hat{\Psi}(x; \theta) = V + x \cdot DNN(x; \theta)$$

# From ODE to loss function

❖ But how do we learn  $\theta$  ?

➤ **minimize** the *Integrated Squared Residual* of the ODE:

■ 
$$J(\theta) = \int_0^1 \left[ \frac{d}{dx} \left( \hat{\Psi}(x; \theta) \right) - f\left(x, \hat{\Psi}(x; \theta)\right) \right]^2 dx$$

■ weight update rule (Robbins, Monro (1951)):

$$\theta_{t+1} = \theta_t - \frac{\alpha_t}{m} \sum_{j=1}^m \nabla_{\theta} \left[ \frac{d}{dx} \left( \hat{\Psi}(x_t; \theta_t) \right) - f\left(x_t, \hat{\Psi}(x_t; \theta_t)\right) \right]^2$$



# Illustrative Example: Solving a PDE

❖ Elliptic PDE :

$$\text{➤ } -\nabla[a(x)\nabla u(x)] + c(x)u(x) = f(x)$$

➤ parameterize  $u(x; \theta)$  with a NN to satisfy, say the Dirichlet Boundary Condition

➤ **Solve?**

■ *Squared Integral Approach:*

$$\min. \int \left[ \nabla[a(x)\nabla \hat{u}(x; \theta)] + c(x)\hat{u}(x; \theta) - f(x) \right]^2 dx$$

# From PDE to loss function

❖ the *Squared Integral Approach* does not necessarily give us a *unique solution*

❖ Need something better!

➤ **Dirichlet's Principle:**

■ 
$$\min. \int \left[ \frac{1}{2} a(x) \nabla u(x; \theta) + c(x) \hat{u}^2(x; \theta) - f(x) u(\hat{x}; \theta) \right] dx - \int_{\Gamma_s} g_s u(\hat{x}; \theta) d\Gamma_s$$

■ also called the *energy equation*

- gives a *unique solution* to satisfy the PDE (same thing also holds for ODE)

# Motivation for using DNN to solve ODE/PDEs

- ❖ A single ODE/PDE can be solved using numerical approximation methods. Then why look into NNs?
  - You can solve for multiple number of parameters, with multiple different boundary conditions, **in a single sweep!**

# Some of its applications

- ❖ high-dimensional uncertainty propagation through PDEs
- ❖ solve problems having *free boundaries* and also *Stefan problem*
- ❖ inverse / model calibration problems
- ❖ data filtering
- ❖ ....

# Will it work everytime?

## ❖ Short answer:

➤ No!

### ➤ Problems:

- *vanishing gradients*

- *spectral bias*

- DNN first finds the low-frequency components
- the high-frequency parts take forever to learn

- .....

## Practical Applications

Time for some hands-on  
training for PINNs.....

Any questions????