

# Deep Learning

week 2

# The Plan

- Discuss homework:
  - [NN&DL book](#), ch1 + ch2
  - ideas for pet projects
- Watch (short) talk by Hinton
- talk, read, code, repeat



# Neural Networks & Deep Learning

## Chapters:

1. Basics (neurons, networks)
2. Basic learning (backprop)
3. Improvements
4. Intuitive proof function learning
5. Why is DL hard
6. Deep Learning

24p

12p

44p

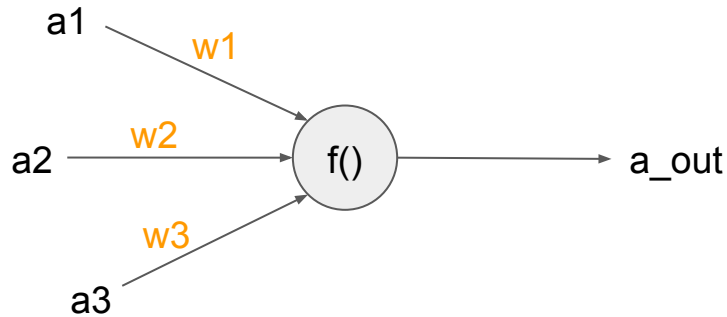
16p

09p

26p

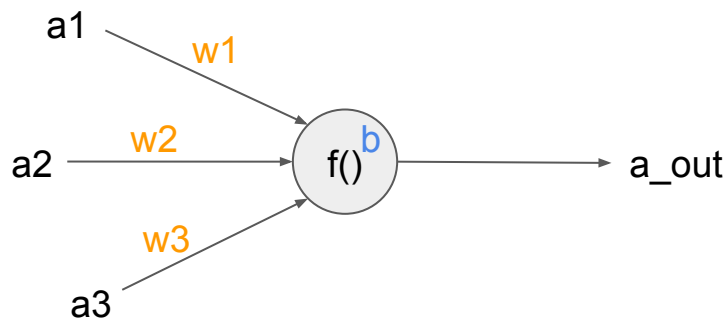
# Neural Networks & Deep Learning - Ch1 + Ch2

Neurons



# Neural Networks & Deep Learning - Ch1 + Ch2

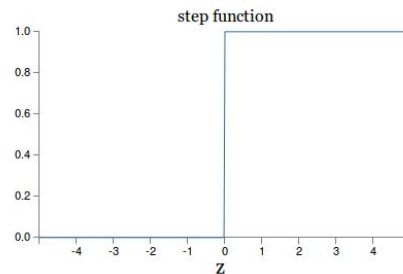
## Neurons



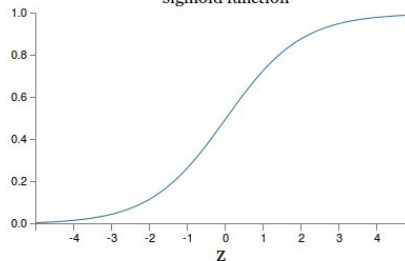
$$a_{out} = f(w \cdot a + b)$$

Choices for  $F()$

perceptron



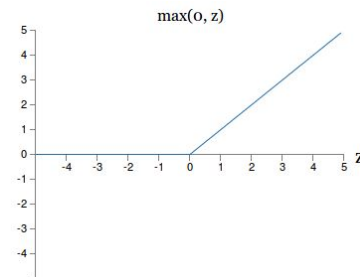
sigmoid function



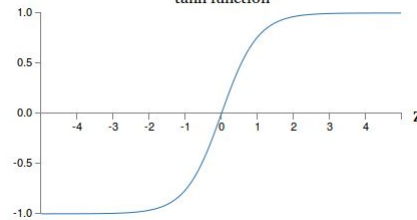
probabilities

$$\text{softmax}(x^{(k)}) = \frac{e^{x^{(k)}}}{\sum_j e^{x^{(j)}}}$$

rectified linear neuron

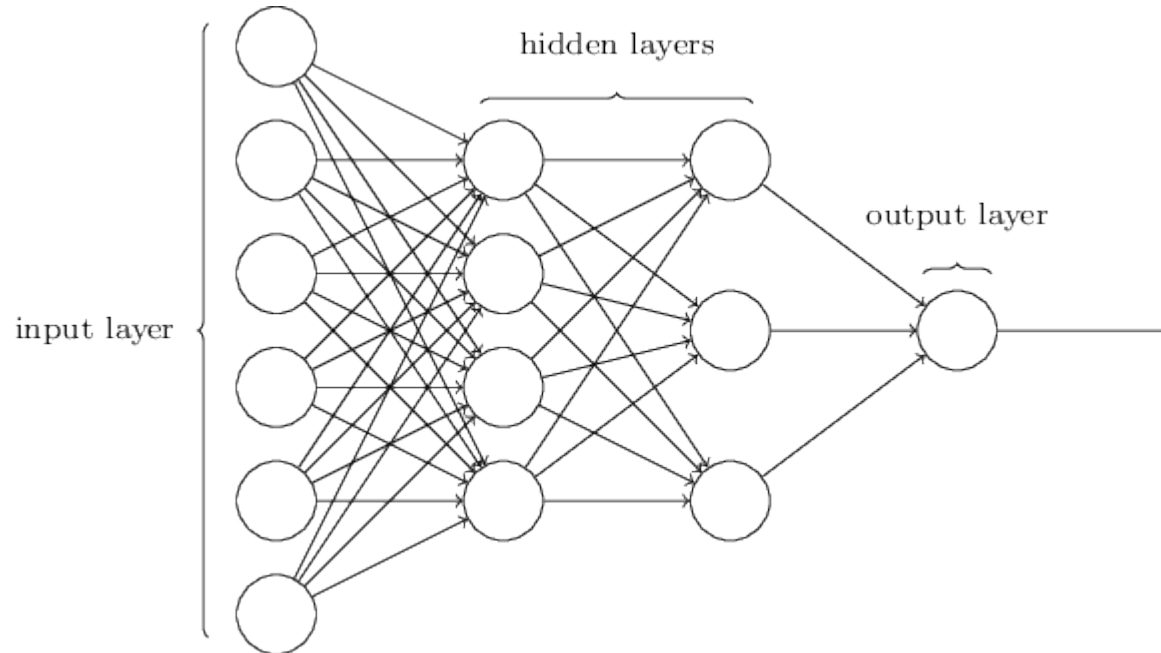


tanh function



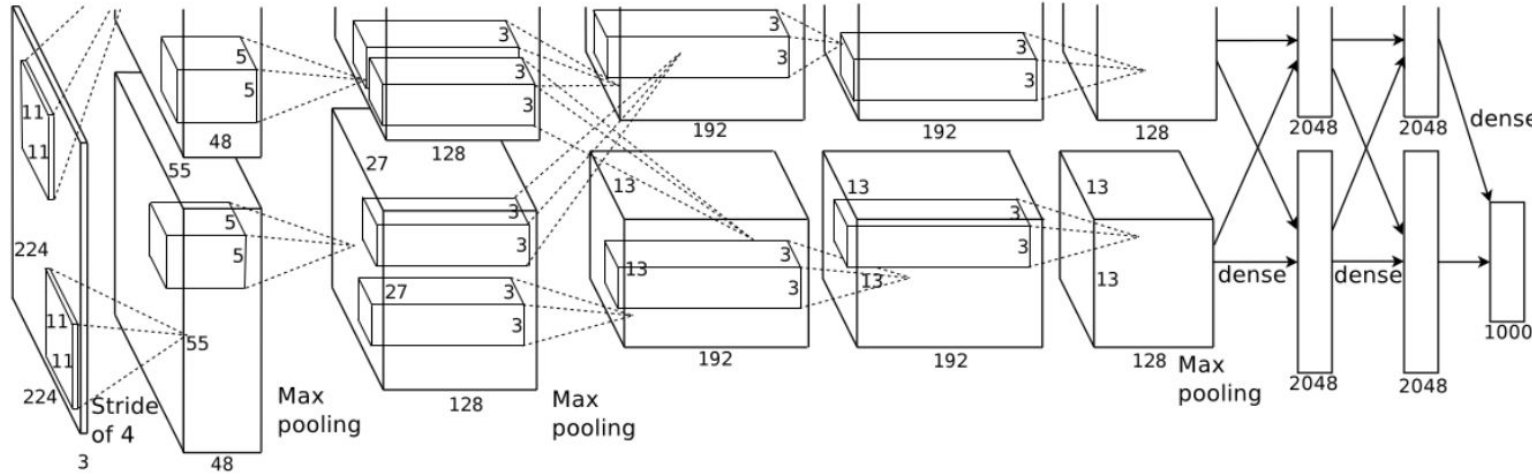
# Neural Networks & Deep Learning - Ch1 + Ch2

## Networks



# Neural Networks & Deep Learning - Ch1 + Ch2

## Deep Networks



2012 →

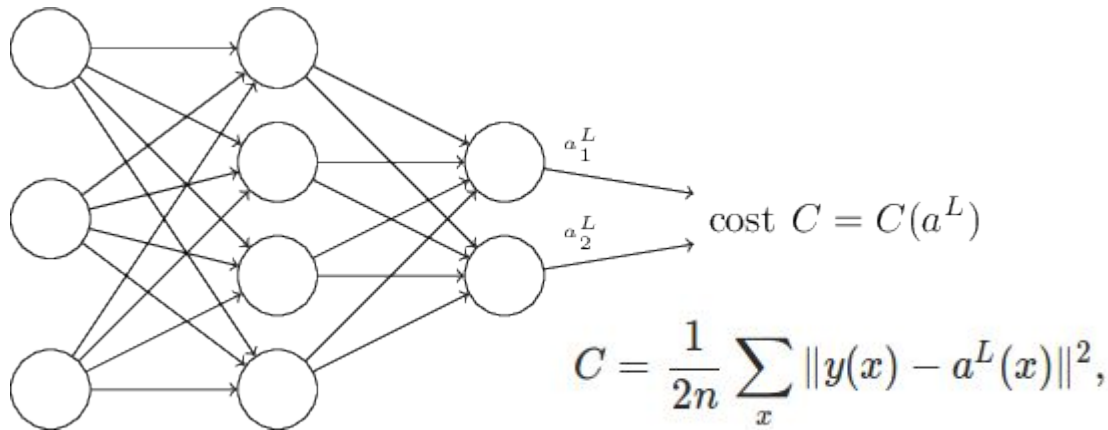
2014 →

2015 →

# Neural Networks & Deep Learning - Ch1 + Ch2

## Learning: backpropagation

- learning parameters (but hyper parameters up to engineer)
- stochastic (batched) gradient descent: avg partial derivatives
- intuitively: how does output error change for small change in parameter?  
but now all together in 1 fwd + bwd pass



### Summary: the equations of backpropagation

$$\delta^L = \nabla_a C \odot \sigma'(z^L) \quad (\text{BP1})$$

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l) \quad (\text{BP2})$$

$$\frac{\partial C}{\partial b_j^l} = \delta_j^l \quad (\text{BP3})$$

$$\frac{\partial C}{\partial w_{jk}^l} = a_k^{l-1} \delta_j^l \quad (\text{BP4})$$



# Demo

Network 1 (vanilla implementation) from Nielson, trained on MNIST, but with real-time classification on live webcam stream



Much harder with real data (centred, line thickness, rotation), but can be stable

# DL intro Talk by Hinton

<https://www.youtube.com/watch?v=l2dVjADTEDU>

???

- talk, read, code, repeat

