1. I File Explorer navigate to your repositories workspace folder and then find the project you are currently working on and want to Flash to the robot. You also must have successfully built your code in Code Composer using CPU1\_FLASH. When you successfully build your code there should be a directory named CPU1\_FLASH and in it a file named FlashIt.ehx. Do not enter the CPU1\_FLASH folder but instead select it and the hold the Shift key and Right-Click. This should bring up an option “Open PowerShell Window here”. Select that option and a Command window will open at that folder location.
2. Now you need to copy the FlashIt.ehx file to your Raspberry Pi. Type the following command replaceing the ?? with your robot’s ip number:

pscp FlashIt.ehx pi@192.168.1.??:/home/pi/c2prog\_test/.

The . at the end is needed

1. Now you will need to putty into your PI. putty pi@192.168.1.??
2. Change directory to the c2prog\_test folder by typing “cd /home/pi/c2prog\_test”
3. Then run the command “./Flash\_F28379D.sh” This takes a bit so be patient. Printed to the putty window should be $Done$ @1@ and then fifteen GPIO prints when the flash is complete