

*What build environment are you using?*

STM32CubeIDE version 1.9.0 on STM32L476RG development board.

*Can you step through the code to see what each line does?*

From the “main.c” file:

```

196 /
197  * @brief GPIO Initialization Function
198  * @param None
199  * @retval None
200  */
201 static void MX_GPIO_Init(void)
202 {
203     GPIO_InitTypeDef GPIO_InitStructure = {0};
204
205     /* GPIO Ports Clock Enable */
206     __HAL_RCC_GPIOC_CLK_ENABLE();
207     __HAL_RCC_GPIOH_CLK_ENABLE();
208     __HAL_RCC_GPIOA_CLK_ENABLE();
209     __HAL_RCC_GPIOB_CLK_ENABLE();
210
211     /*Configure GPIO pin Output Level */
212     HAL_GPIO_WritePin(LD2_GPIO_Port, LD2_Pin, GPIO_PIN_RESET);
213
214     /*Configure GPIO pin : Blue_Btn_Pin */
215     GPIO_InitStructure.Pin = Blue_Btn_Pin;
216     GPIO_InitStructure.Mode = GPIO_MODE_IT_FALLING;
217     GPIO_InitStructure.Pull = GPIO_NOPULL;
218     HAL_GPIO_Init(Blue_Btn_GPIO_Port, &GPIO_InitStructure);
219
220     /*Configure GPIO pin : LD2_Pin */
221     GPIO_InitStructure.Pin = LD2_Pin;
222     GPIO_InitStructure.Mode = GPIO_MODE_OUTPUT_PP;
223     GPIO_InitStructure.Pull = GPIO_NOPULL;
224     GPIO_InitStructure.Speed = GPIO_SPEED_FREQ_LOW;
225     HAL_GPIO_Init(LD2_GPIO_Port, &GPIO_InitStructure);
226
227     /* EXTI interrupt init*/
228     HAL_NVIC_SetPriority(EXTI15_10_IRQn, 0, 0);
229     HAL_NVIC_EnableIRQ(EXTI15_10_IRQn);
230
231 }
232

```

→ Clock is enabled for GPIO A, B, C and H

→ LED2 pin is set to 0V

→ Blue button pin: input, interrupt on falling edge, no internal pullup (4.7k connected outside the µC)

→ LED2 pin: output, push-pull mode, no pullup, low speed

→ External interrupts initialization (#10 to #15) priority (0) and preemption priority (0).

→ Interrupts #10 to #15 are enabled within the Nested vectored interrupt controller (NVIC)

The interrupt service routine from the “stm32l4xx\_it.c” file:

```

193
194- /******
195 /* STM32L4xx Peripheral Interrupt Handlers                               */
196 /* Add here the Interrupt Handlers for the used peripherals.           */
197 /* For the available peripheral interrupt handler names,               */
198 /* please refer to the startup file (startup_stm32l4xx.s).           */
199 /******
200
201- /**
202  * @brief This function handles EXTI line[15:10] interrupts.
203  */
204- void EXTI15_10_IRQHandler(void)
205 {
206     /* USER CODE BEGIN EXTI15_10_IRQn 0 */
207
208     /* USER CODE END EXTI15_10_IRQn 0 */
209     HAL_GPIO_EXTI_IRQHandler(Blue_Btn_Pin);
210     /* USER CODE BEGIN EXTI15_10_IRQn 1 */
211
212     /* USER CODE END EXTI15_10_IRQn 1 */
213 }
214

```

Interrupt Handler attached to the blue button pin

Push-button debouncing and LED toggling

```

233 /* USER CODE BEGIN 4 */
234
235 // External Interrupt ISR Handler CallbackFun
236- void HAL_GPIO_EXTI_Callback(uint16_t GPIO_Pin)
237 {
238     counterOutside++;
239     currentMillis = HAL_GetTick();
240
241     if (GPIO_Pin == Blue_Btn_Pin && (currentMillis - previousMillis > 10))
242     {
243         /* Check that interrupt source is the button external interrupt
244         Debounce delay set to 10ms but adjustable according to button type; any new interrupts during the delay are ignored */
245         {
246             counterInside++;
247             HAL_GPIO_TogglePin(LD2_GPIO_Port, LD2_Pin); // Toggle the LED
248             previousMillis = currentMillis;
249         }
250     }
251 }
252 /* USER CODE END 4 */

```

The debouncing routine is not mine, it originates from this [website](#). Two counters are put in place, for the sake of the demo: one adds up the interrupt events outside the “if” code while the other takes care of the events inside the “if”. A higher outside counter value indicates that bounces happened which were masked thanks to the 10ms delay.

Expression	Type	Value
(x)= counterOutside	uint32_t	10
(x)= counterInside	uint32_t	9
Add new expression		

*What are the hardware registers that cause the LED to turn on and off?*

From the STM32L476RG Reference Manual RM0351, the relevant registers for turning the LED (LED2 on Port A, Pin 5) on and off are:

- The GPIOx\_MODER, to set the pin as input, output, alternate function or analog
- The GPIOx\_BSRR, which allows the application to set and reset each individual bit in the output data register (GPIOx\_ODR)
- The GPIOx\_ODR, which stores the data to be output the pin

*What are the registers that you read in order to find out the state of the button?*

The blue button pin is initialized as an input on Port C, Pin 13. The register used to read the pin state is GPIOx\_IDR. The pull-up/pull-down register GPIOx\_PUPDR is not used due to the presence of an external 4.7kohm resistor on that pin. An external interrupt EXTI is set to trigger on a falling edge.

PC13	n/a	n/a	External In...	No pull-up ...	n/a	n/a	Blue_Btn	<input checked="" type="checkbox"/>
------	-----	-----	----------------	----------------	-----	-----	----------	-------------------------------------

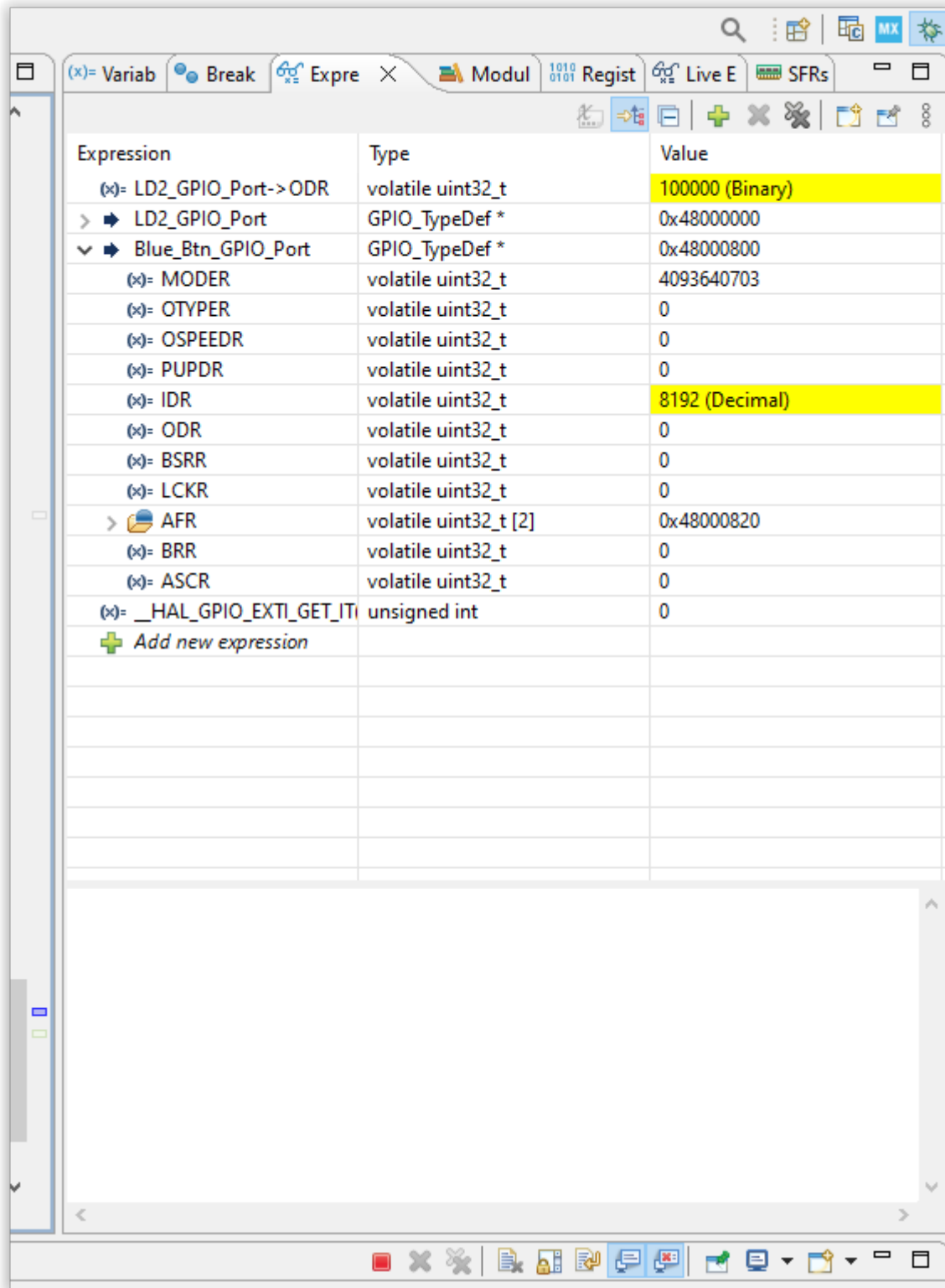
  

PC13 Configuration :

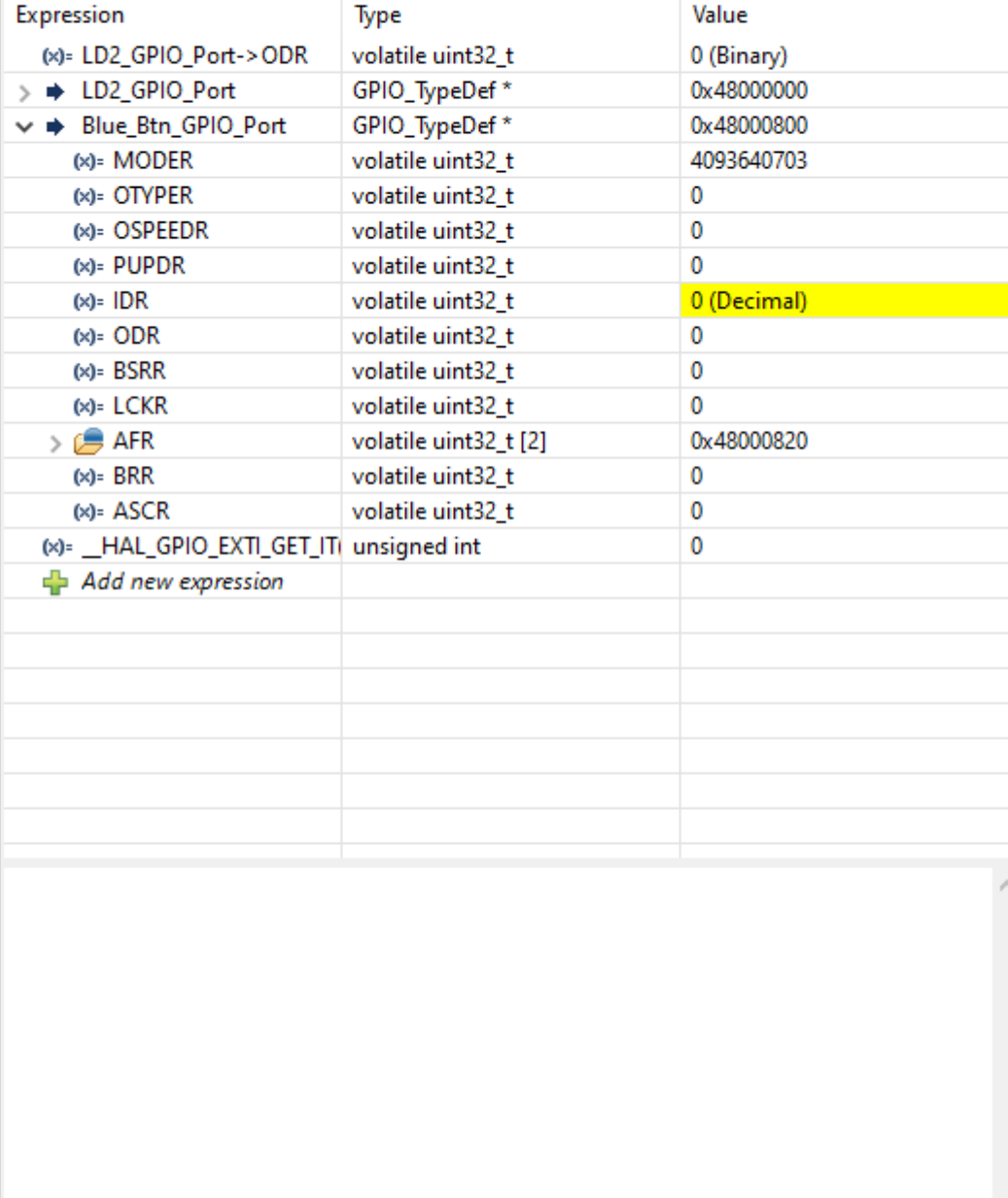
GPIO mode	External Interrupt Mode with Falling edge trigger detection
GPIO Pull-up/Pull-down	No pull-up and no pull-down
User Label	Blue_Btn

*Can you read the register directly and see the button change in a debugger or by printing out the value of the memory at the register's address?*

Button released (Idle state – Pin 13 pulled to VCC)



IDR decimal value is 8192 that is 0010 0000 0000 0000 in binary. Therefore, bit 13's value is indeed set to 1.



Expression	Type	Value
(x)= LD2_GPIO_Port->ODR	volatile uint32_t	0 (Binary)
> ➔ LD2_GPIO_Port	GPIO_TypeDef *	0x48000000
▼ ➔ Blue_Btn_GPIO_Port	GPIO_TypeDef *	0x48000800
(x)= MODER	volatile uint32_t	4093640703
(x)= OTYPER	volatile uint32_t	0
(x)= OSPEEDR	volatile uint32_t	0
(x)= PUPDR	volatile uint32_t	0
(x)= IDR	volatile uint32_t	0 (Decimal)
(x)= ODR	volatile uint32_t	0
(x)= BSRR	volatile uint32_t	0
(x)= LCKR	volatile uint32_t	0
> 📁 AFR	volatile uint32_t [2]	0x48000820
(x)= BRR	volatile uint32_t	0
(x)= ASCR	volatile uint32_t	0
(x)= __HAL_GPIO_EXTI_GET_IT	unsigned int	0
➕ Add new expression		