Tutorial 1

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If you use git, update the exercises-folder by running: cd DynSysBio2019; git pull

1 Exercise 5: Lotka-Volterra

The ODEs of the Lotka-Volterra model $\dot{\vec{x}} = f(\vec{x})$ are given by:

$$\dot{x}(t) = a \cdot x(t) - b \cdot x(t) \cdot y(t), \tag{1}$$

$$\dot{y}(t) = c \cdot x(t) \cdot y(t) - d \cdot y(t), \tag{2}$$

where all parameters $(a, b, c, d) \in \mathbb{R}^4_+$ are positive.

- Write a 'function euler (ini, pars, dt, tmax)' integrating the LV system via the Euler method for a set of initial values ini, parameters pars and stepsize dt for $t \in [0, tmax]$. The function should return the variables time and \vec{x} .

Reminder Euler method: $\vec{x}_{n+1} = \vec{x}_n + f(\vec{x}_n) \cdot dt$.

- Plot solutions of the LV system in configuration (t, \vec{x}) and phase space (x, y) for a = 2/3, b = 4/30, c = 1/10, d = 1 and a set of initial values $(x(t = 0), y(t = 0)) = \{(10, 15), (15, 10)\}.$
- Add a noise term to the euler integration: $\vec{x}_{n+1} = \vec{x}_n + f(\vec{x}_n) \cdot dt + \epsilon \cdot \sqrt{dt}$ with $\epsilon \propto \mathbb{N}(0, sd)$. Use sd = [sdx, sdy] as additional argument of your euler function and avoid $x_n < 0$. Compare the solutions obtained with sd = [.3, .3] to the standard solutions without noise by plotting.

2 Exercise 6: Lotka-Volterra extended

The LV system can be extended to:

$$\dot{x}(t) = a \cdot x(t) \cdot \left(1 - \frac{x(t)}{K}\right) - b \cdot \frac{x(t)}{x(t) + S} \cdot y(t),\tag{3}$$

$$\dot{y}(t) = c \cdot \frac{x(t)}{x(t) + S} \cdot y(t) - d \cdot y(t), \tag{4}$$

where also K and S are positive parameters.

- Repeat Exercise 5 for the extended equations using $a = b = c = 1; d = \frac{1}{3}; K = 30, S = 10$ and $(x(0), y(0)) = \{(1, 1), (10, 10)\}.$
- Interpret the extended system:
- What is the meaning of the parameters?
- What are the qualitative differences of both systems?
- Compare how the noise affects both systems.

3 Cathedral exercise

The choir of the cathedral is slightly inclined relative to the main nave. Why?