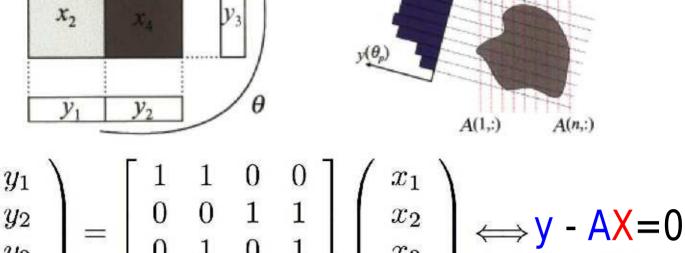


 $y_3$ 

 $y_4$ 



 $x_3$ 

 $x_4$ 

 $y(\theta_1)$