

# Finite element models for the study of hydrogen embrittlement of steel structures

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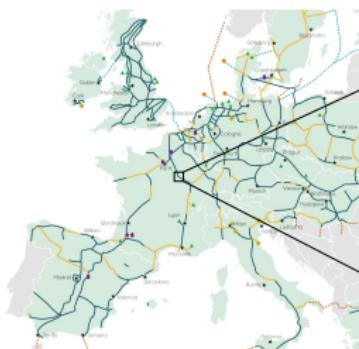
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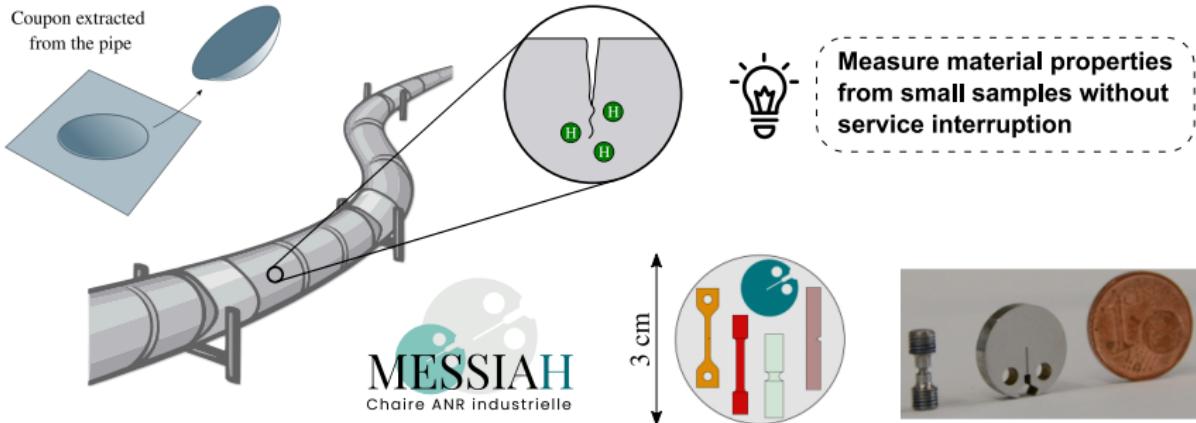
**Thesis defense**

March 7<sup>th</sup> 2025

- ▶ In the context of **energy transition**, **hydrogen** plays an important role as an **energy vector**
- ▶ Hydrogen can be produced from other **renewable sources**, such as wind and solar
- ▶ Hydrogen transport using **existing natural gas pipelines** (40,000 km in France, 50 billion in assets, up to 80 years old) is a proposal for hydrogen transport



- ▶ **Hydrogen embrittlement:** ductility and toughness reduction, premature failure



## Objectives:

- ▶ Develop a model coupling plasticity, damage and hydrogen diffusion
- ▶ Validate this model on experimental results
- ▶ Simulate size and thickness effect on toughness with sub-size specimens

## Introduction

## Hydrogen inside metals

## Finite element formulation

## Numerical simulations

Pressurized disks tests

Hydrogen uptake during a tensile test

Hydrogen embrittlement modeling

Simulation of fracture toughness tests

## Conclusions

## Perspectives

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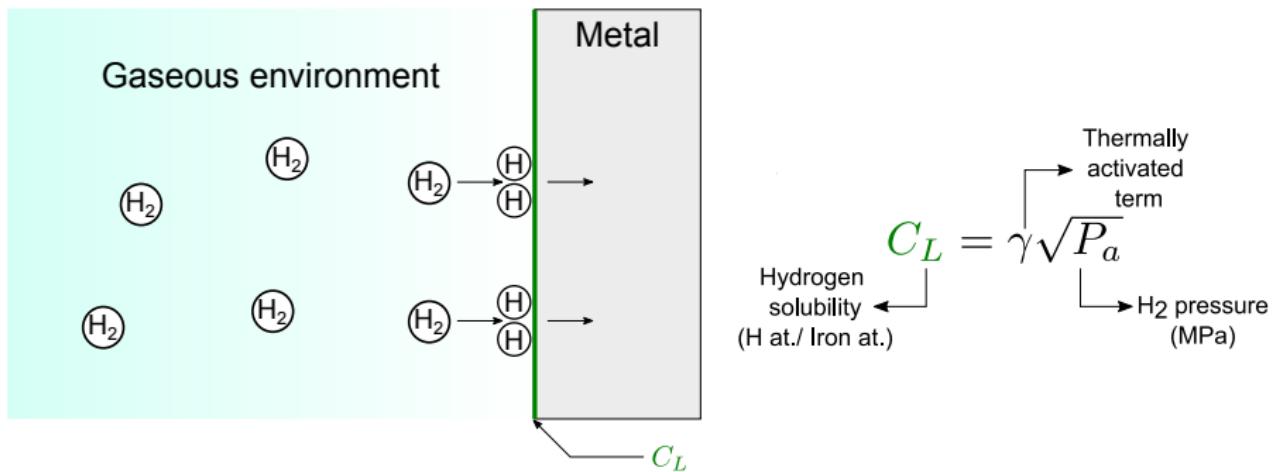
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- ▶ **Sieverts' law:** The solubility of a diatomic gas in a metal is proportional to the square root of the gas pressure

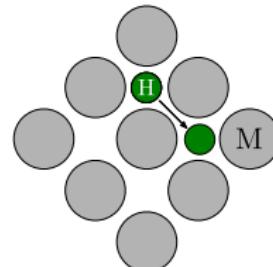


- Model from Sofronis and McMeeking (1989) and corrected by Krom *et al.* (1999)

- **Hydrogen concentration:**  $C = C_L + C_T$

- Lattice concentration:  $C_L = \beta N_L \theta_L$

- Trapped concentration:  $C_T = \sum_i^N C_T^i = N_T^i(\kappa) \theta_T^i$



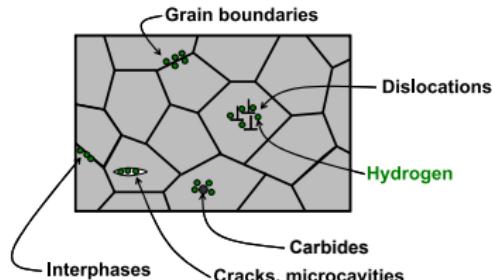
- **Hydrogen flux:**

$$J = -D_L \nabla C_L + \frac{D_L C_L V_H}{RT} \nabla p$$

- **Oriani's equilibrium:**

$$\frac{1 - \theta_L}{\theta_L} \frac{\theta_T^i}{1 - \theta_T^i} = K$$

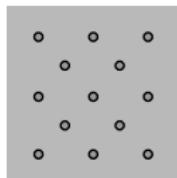
(Coupling terms)



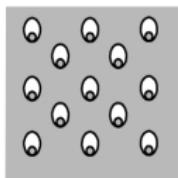
- The **ductile behavior** of the metal is described by the **GTN model** (Tvergaard *et al.* 1984):

$$\frac{\sigma_{eq}^2}{\sigma_F^2} + 2q_1 f_* \cosh \left( \frac{q_2}{2} \frac{\sigma_{ii}}{\sigma_F} \right) - 1 - q_1^2 f_*^2 = 0$$

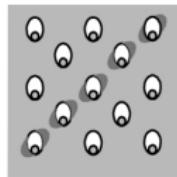
$$\dot{f} = \dot{f}_{nucleation} + \dot{f}_{growth}$$



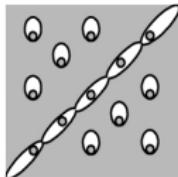
Impurities or second phase particles



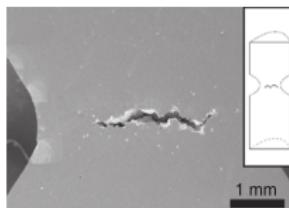
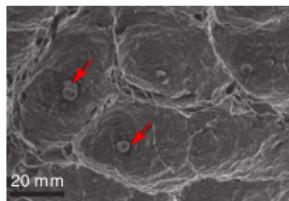
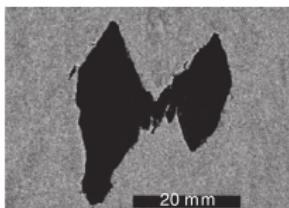
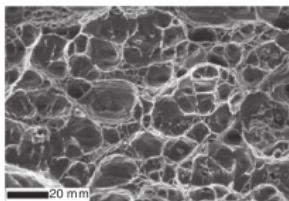
Void nucleation and growth



Strain localization



Void coalescence and fracture

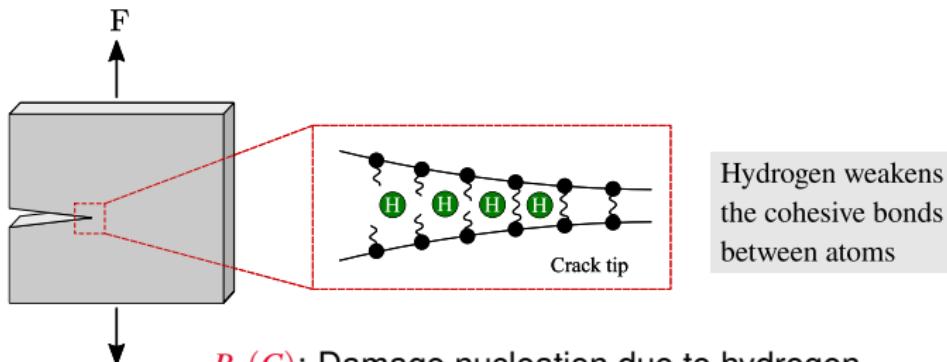


- **Void growth:** Unchanged due to mass conservation

$$\dot{f}_g = (1 - f_g) \text{trace}(\dot{\varepsilon}_p)$$

- **Void nucleation:** Proposed dependence on hydrogen concentration

$$\dot{f}_n = A_n(\kappa)\dot{\kappa} + B_n(C)\dot{\kappa} \quad (\text{Coupling terms})$$



$B_n(C)$ : Damage nucleation due to hydrogen  
**HEDE** (Hydrogen Enhanced Decohesion)

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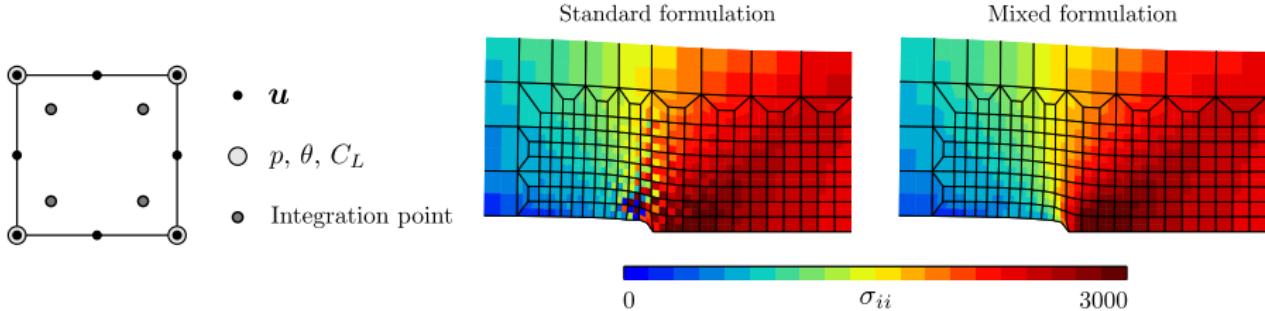
- ▶ Fully implicit finite strain framework
- ▶ Based on a mixed formulation:  $\underline{u}, P, \theta$  (Zhang et al. 2017) and  $C_L$
- ▶ Quadratic elements with reduced integration
- ▶ **Aim:** better pressure fields by avoiding volumetric locking



## Advantage

$\nabla p$  can be directly computed from nodal values

$$J = -D_L \nabla C_L + \frac{D_L C_L V_H}{RT} \nabla p$$



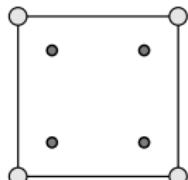
- ▶ The use of **quadratic elements** with additional dofs lead to **high simulation times**

- $B$ -bar (or  $\bar{B}$ ) formulation (Hughes, 1980):

- ▶ Linear elements with full integration
  - ▶ Solves volumetric locking by modifying the strain-displacement matrix:

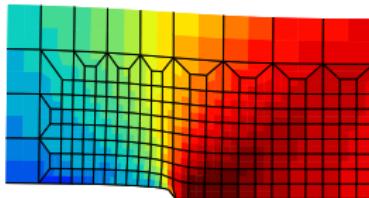
$$\bar{B} = B_d + \bar{B}_h$$

- To avoid extrapolating  $p$  to the nodes for  $\nabla p$  computation, it is considered as a dof

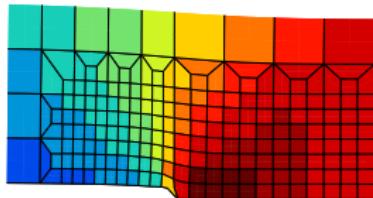


- $\mathbf{u}, p, C_L$
- Integration point

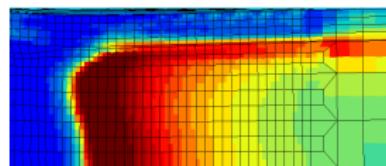
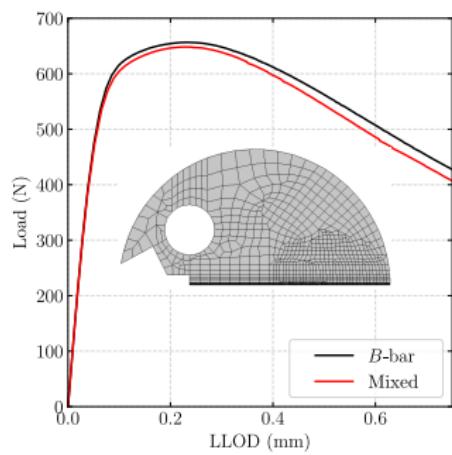
### Mixed formulation



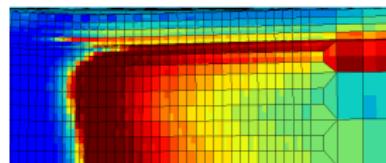
### B-bar formulation



- ▶ Test on a Disk Compact Tension (DCT) specimen with 5200 elements:
  - ▶ **Mixed formulation:** 103,762 dofs, 1h 40 minutes to complete
  - ▶ **B-bar formulation:** 33,974 dofs, 18 minutes to complete
- ▶ Slightly higher force for the **B-bar** formulation → Linear elements are inherently stiffer since they have less nodes



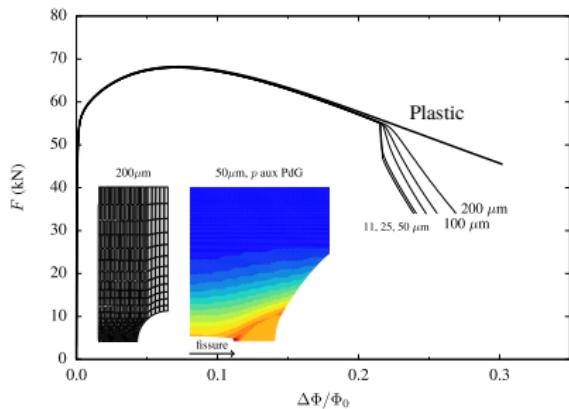
Mixed formulation



B-bar formulation

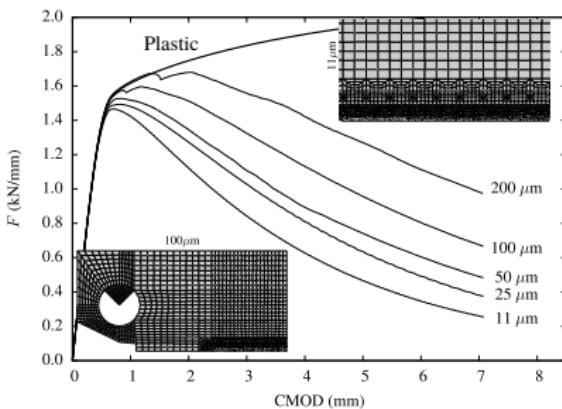


- ▶ Damage models such as the GTN model are known to induce **spurious mesh dependency** (element size, type and orientation)
- ▶ To solve this problem, it is proposed to use a **nonlocal damage model** based on the **implicit gradient** by Peerlings *et al.*, 1996



Notched tensile (NT) specimen

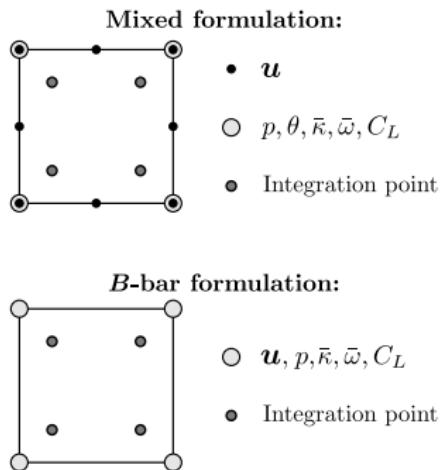
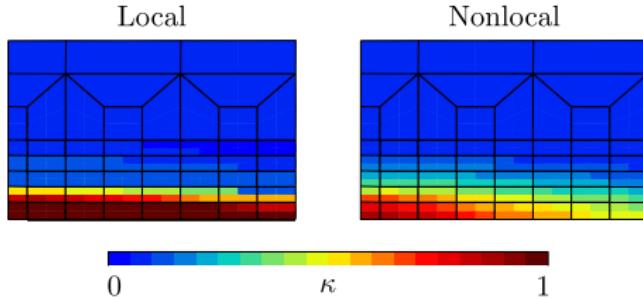
(Besson, 2021)



Compact tension (CT) specimen

- ▶ Two variables are used (two associated internal lengths:  $\bar{\omega}$  and  $\bar{\kappa}$ ):
    - ▶ **Plastic volume variation:**  $\bar{\omega} - \ell_{\omega}^2 \Delta \bar{\omega} = \omega$  where  $\omega = \text{trace}(\dot{\varepsilon}_p)$
    - ▶ **Accumulated plastic strain:**  $\bar{\kappa} - \ell_{\kappa}^2 \Delta \bar{\kappa} = \kappa$  - ▶ The modified evolution laws for the damage variables are now:

- ▶ **Void growth:**  $\dot{f}_g = (1 - f_g) \dot{\bar{\omega}}$
  - ▶ **Void nucleation:**  $\dot{f}_n = A_n \dot{\bar{\kappa}} + B_n(C) \dot{\bar{\kappa}}$



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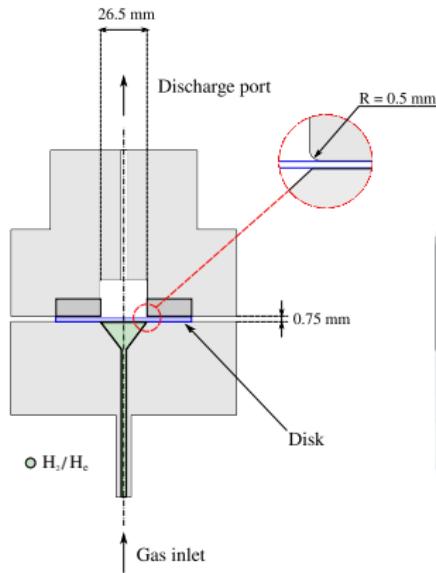
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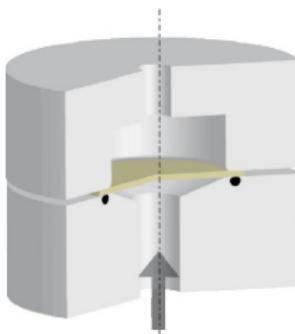
Conclusions

Perspectives

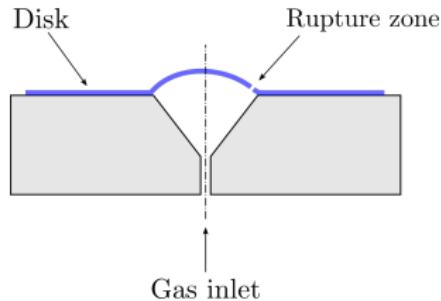
- ▶ **ISO 11114-4 standard:** uses pressurized disk tests for selecting metallic materials resistant to hydrogen embrittlement
- ▶ Disk often fails in the clamping zone
- ▶ **First step:** redesigning the disk geometry to control failure location



$$\text{HEI} = \frac{P_r(\text{He})}{P_r(\text{H}_2)}$$

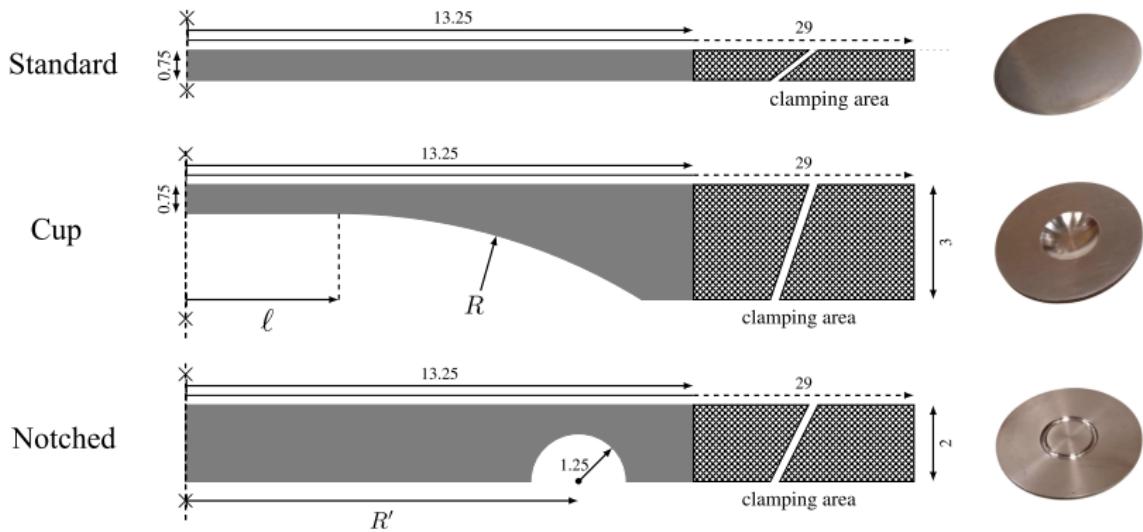


Disk specimen:

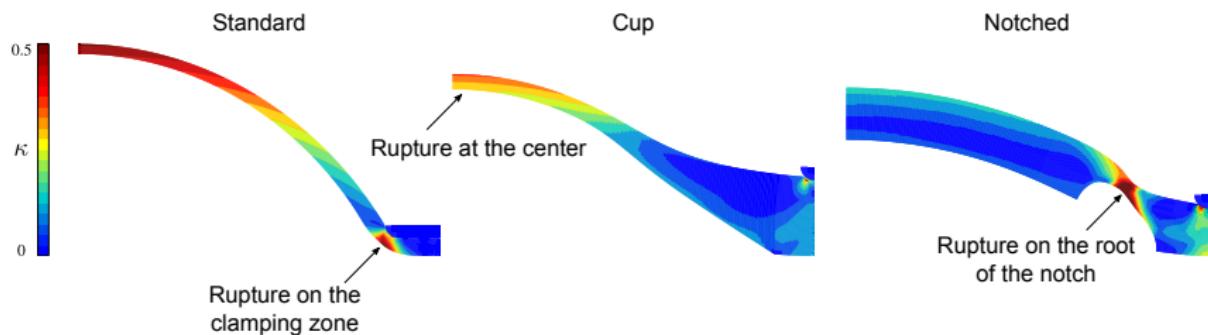


# Redesign of the disk geometry

- ▶ New proposed geometries:
  - ▶ No need to modify the test setup
  - ▶ Keep the same minimum thickness of the standard (0.75 mm)
- ▶ Optimization with respect to  $\ell$ ,  $R$  and  $R'$  with FE simulations considering an elasto-plastic behavior



- ▶ The location of the maximum accumulated plastic strain ( $\kappa$ ) corresponds to the failure location



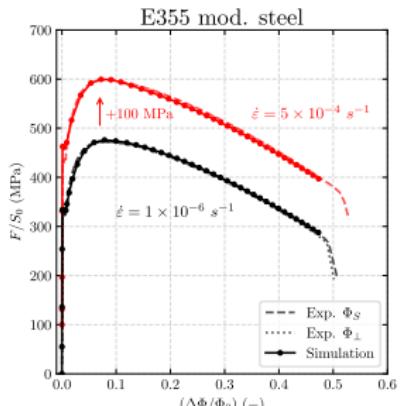
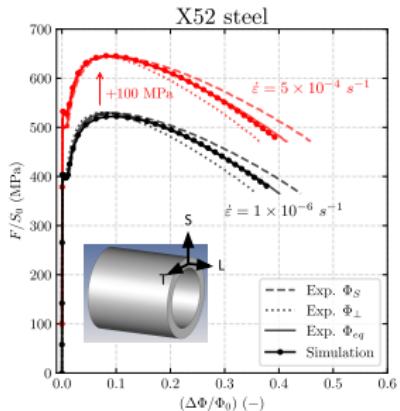
► **X52 vintage steel:**

- ▶ Yield strength: 400 MPa
- ▶ Different elongation at rupture in T and L directions

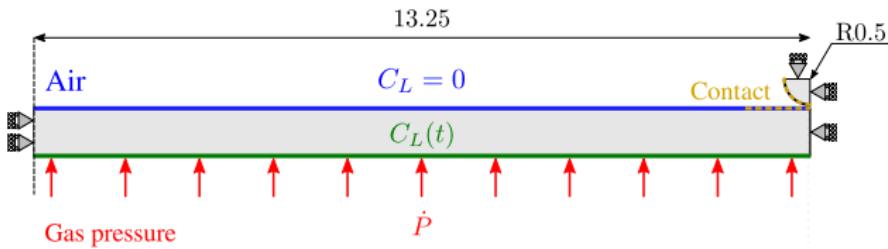
► **E355 mod. steel:**

- ▶ Yield strength: 330 MPa
  - ▶ Higher elongation at rupture and lower Ultimate Tensile Strength in relation with the vintage material
  - ▶ Similar elongation at rupture in both directions
- Elasto(visco)-plastic model coefficients' identified through optimization:

$$\sigma_F(p) = \max(\sigma_L, \sigma_0 + Q_1(1 - \exp(-b_1 p)) + Q_2(1 - \exp(-b_2 p)) + H p)$$

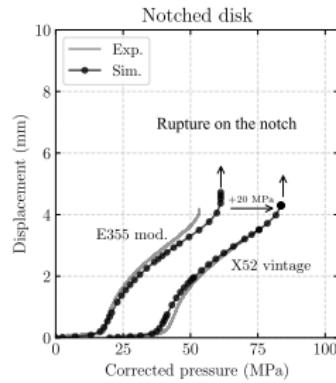
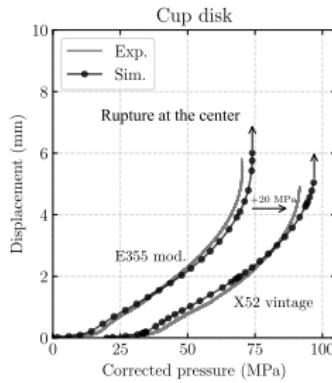
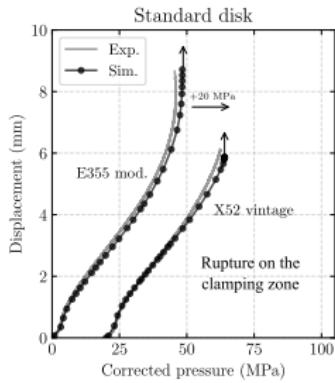
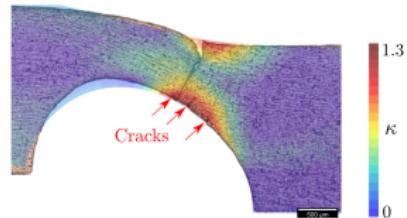


- ▶ Axisymmetric model, quadratic elements with reduced integration (mixed formulation)
- ▶ Hydrogen diffusion parameters taken from the literature
- ▶ Since damage is not considered into the numerical model, the simulations were stopped once they reached experimentally observed rupture pressure ( $P_r$ )
- ▶ Model's boundary conditions:

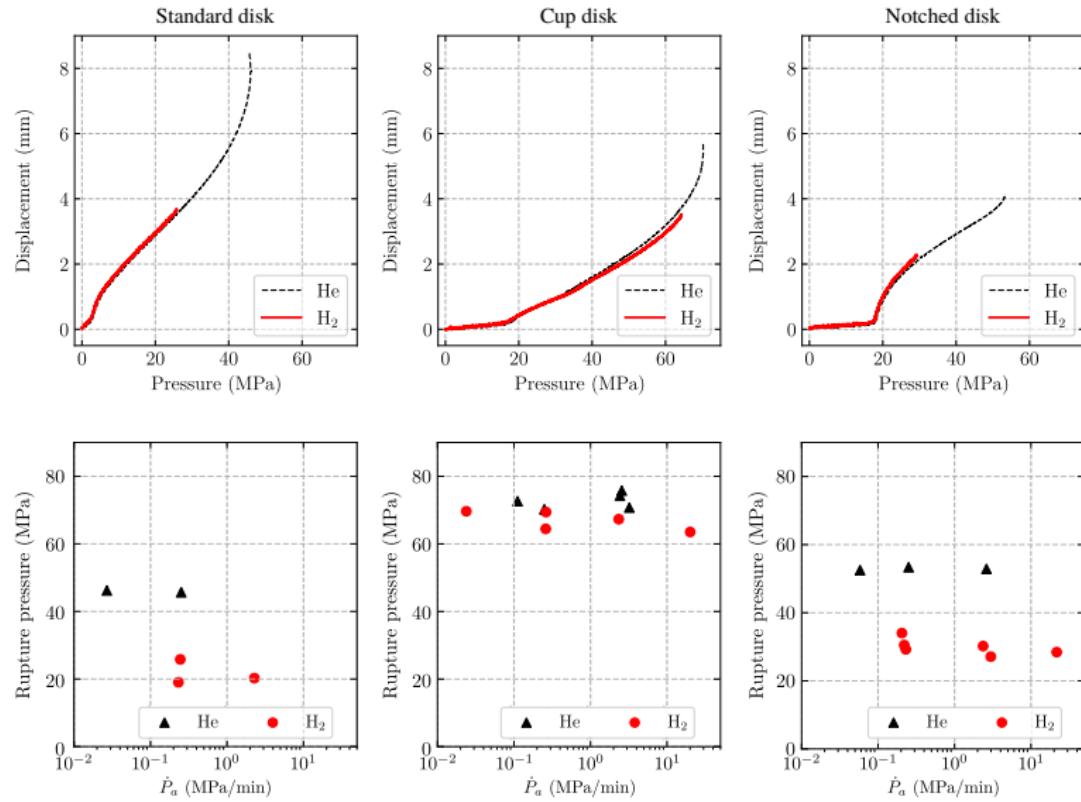


# Results under helium

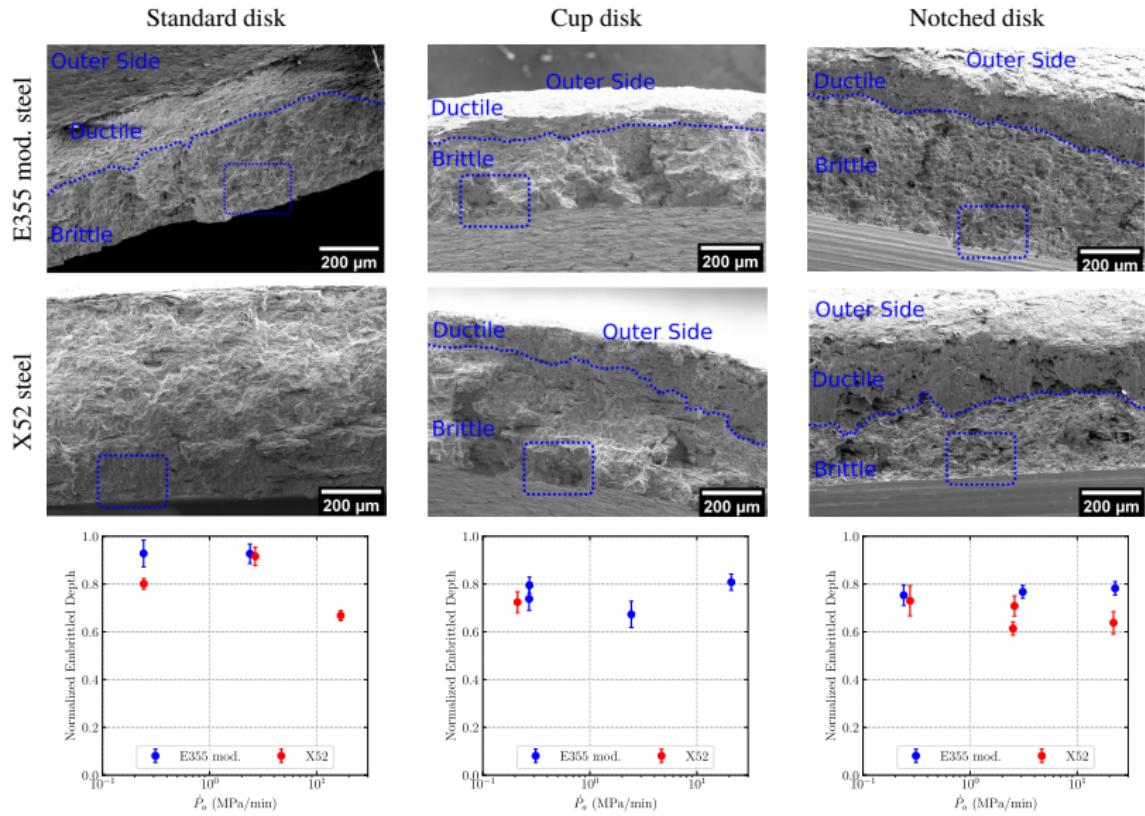
- ▶ Experiments carried out by Luciano Santana
- ▶ Successfully modification of fracture location
- ▶ Failure is primarily driven by plasticity and occurs under a limit load scenario



# Results under hydrogen (E355 mod. steel)



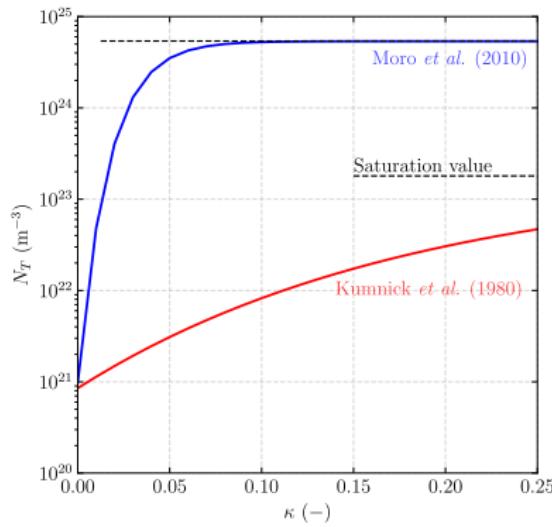
# Hydrogen embrittled depth



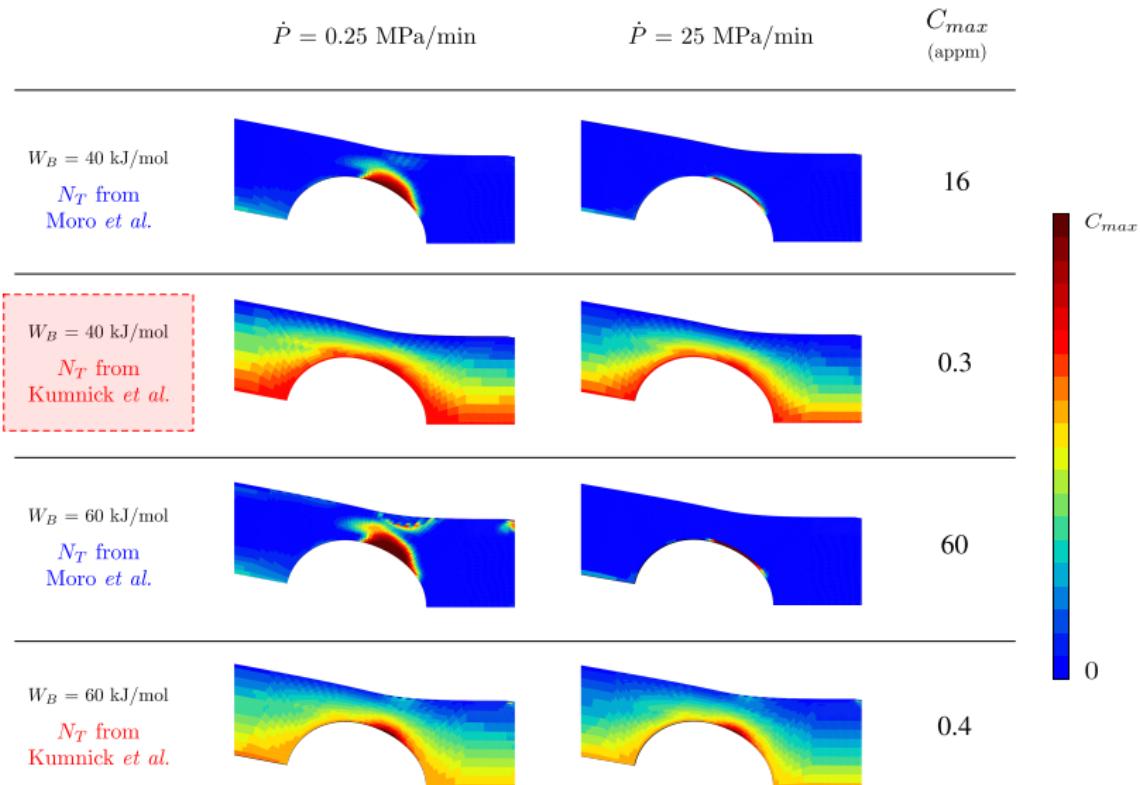
- ▶ Considers only one kind of trap: dislocations
- ▶ Trap binding energies ( $W_B$ ) and trap densities ( $N_T$ ) were taken from the literature and analyzed based on the experimental observations
- ▶ Based on the models proposed by Moro *et al.* (2010) and Kumnick *et al.* (1980), four cases emerge

$$W_B = \begin{cases} 40 \text{ kJ/mol} \\ 60 \text{ kJ/mol} \end{cases}$$

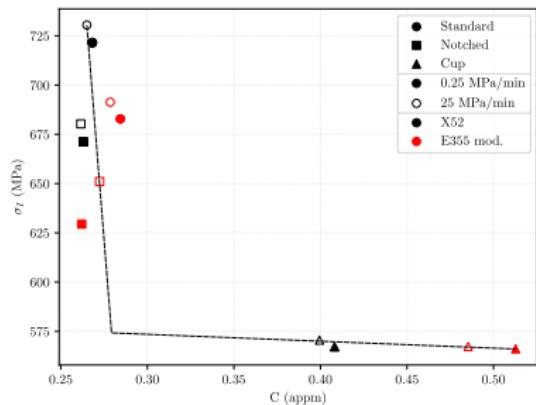
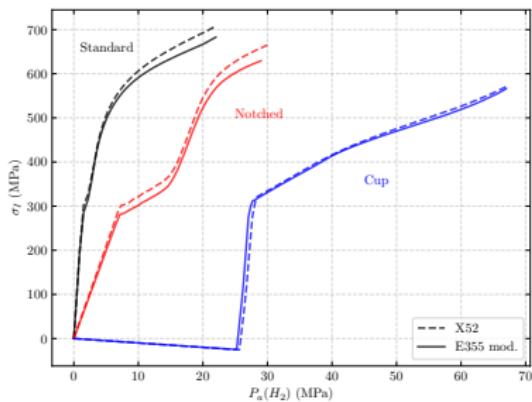
$$N_T = \begin{cases} \log_{10} N_T = 24.73 - 3.74 \exp(-60.17\kappa) \\ \log_{10} N_T = 23.26 - 2.33 \exp(-5.5\kappa) \end{cases}$$



# Hydrogen embrittled depth



- ▶ Specimens that develop higher principal stress ( $\sigma_I$ ) in the fracture zone fail at a lower hydrogen pressure ( $P_a(H_2)$ )
- ▶ The total hydrogen concentration reduces the maximum principal stress that triggers fracture



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