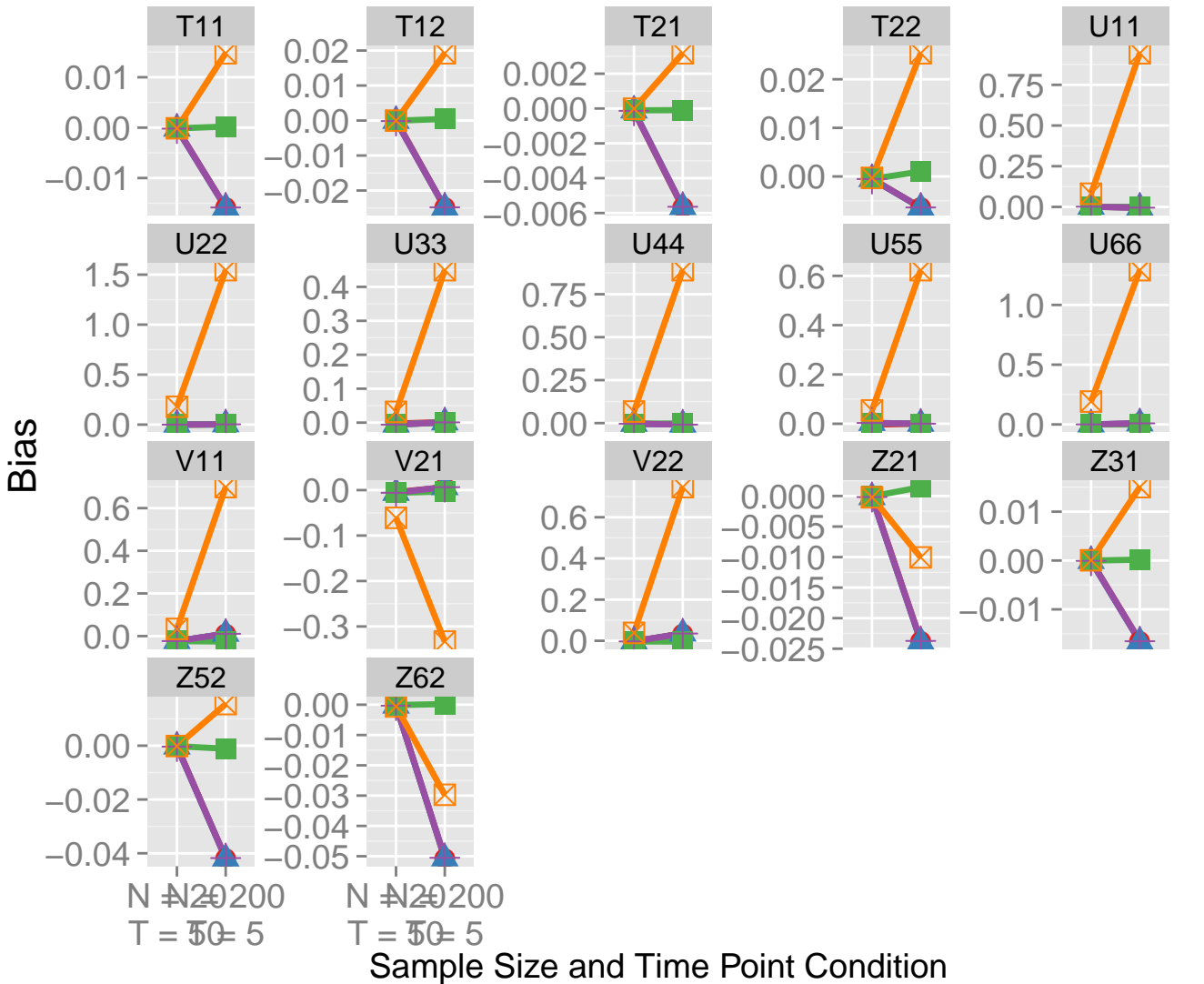
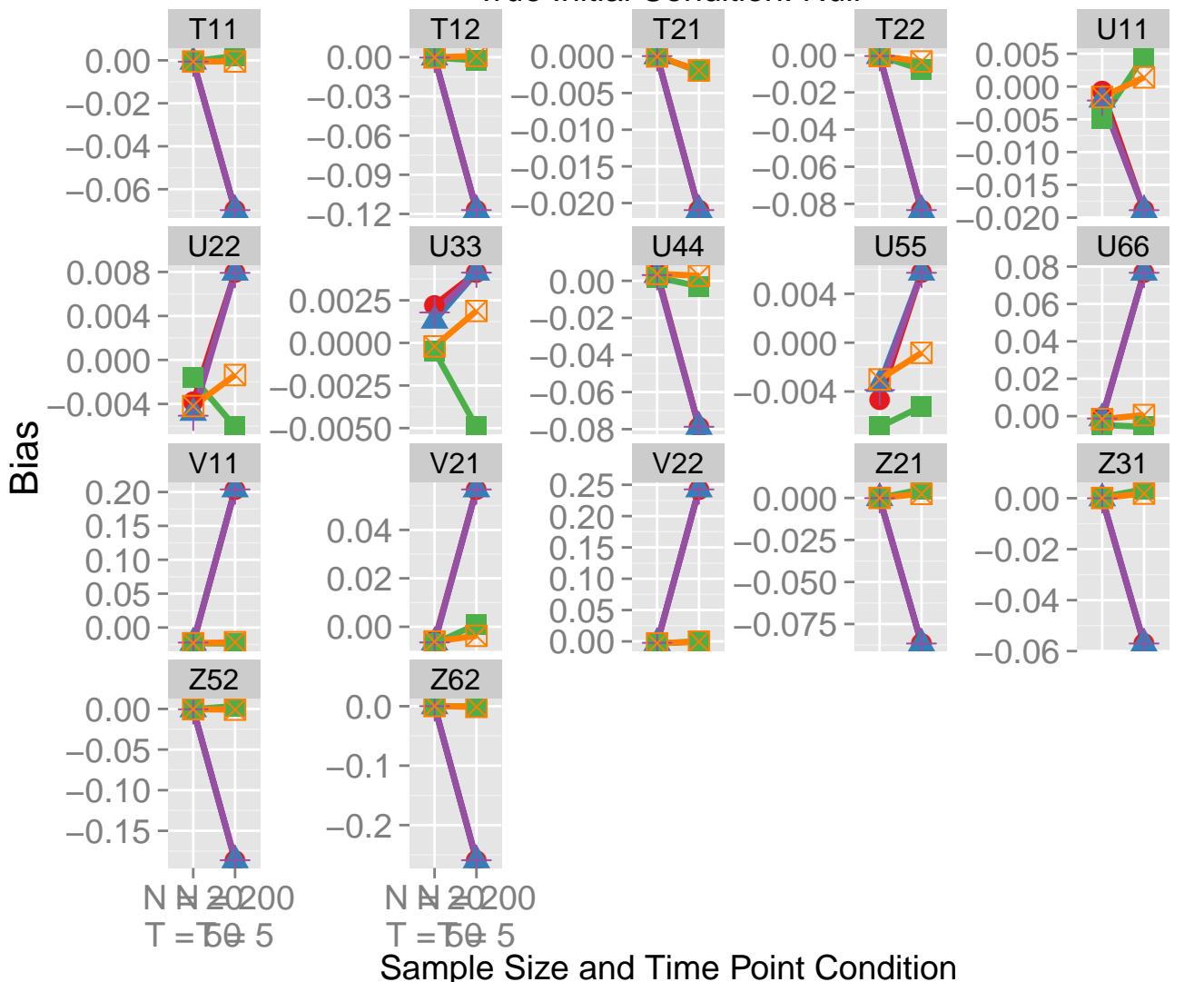


# Non-Stationary Model True Initial Condition: diffuse

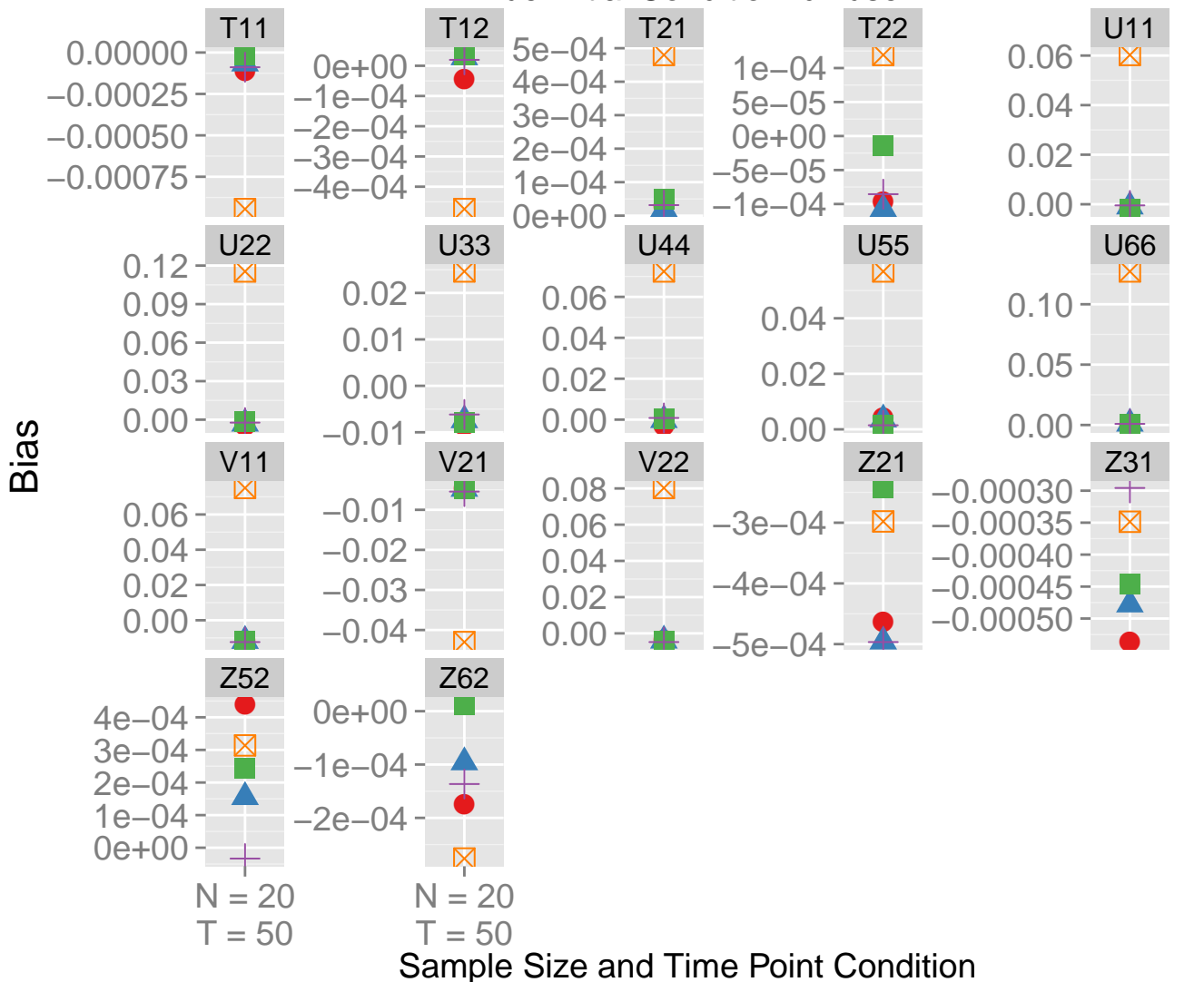




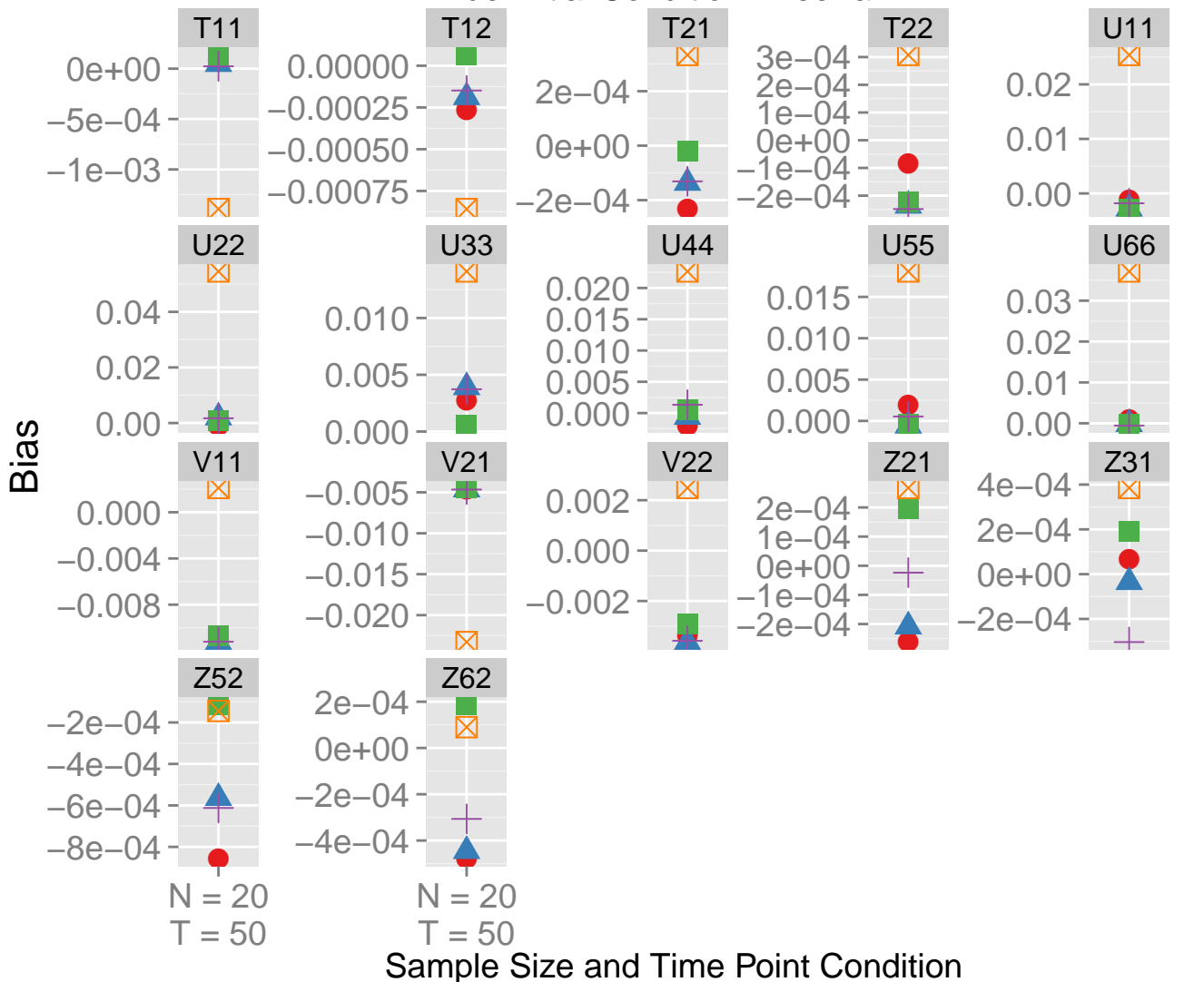
# Non-Stationary Model True Initial Condition: Null



# Non-Stationary Mild Model True Initial Condition: diffuse

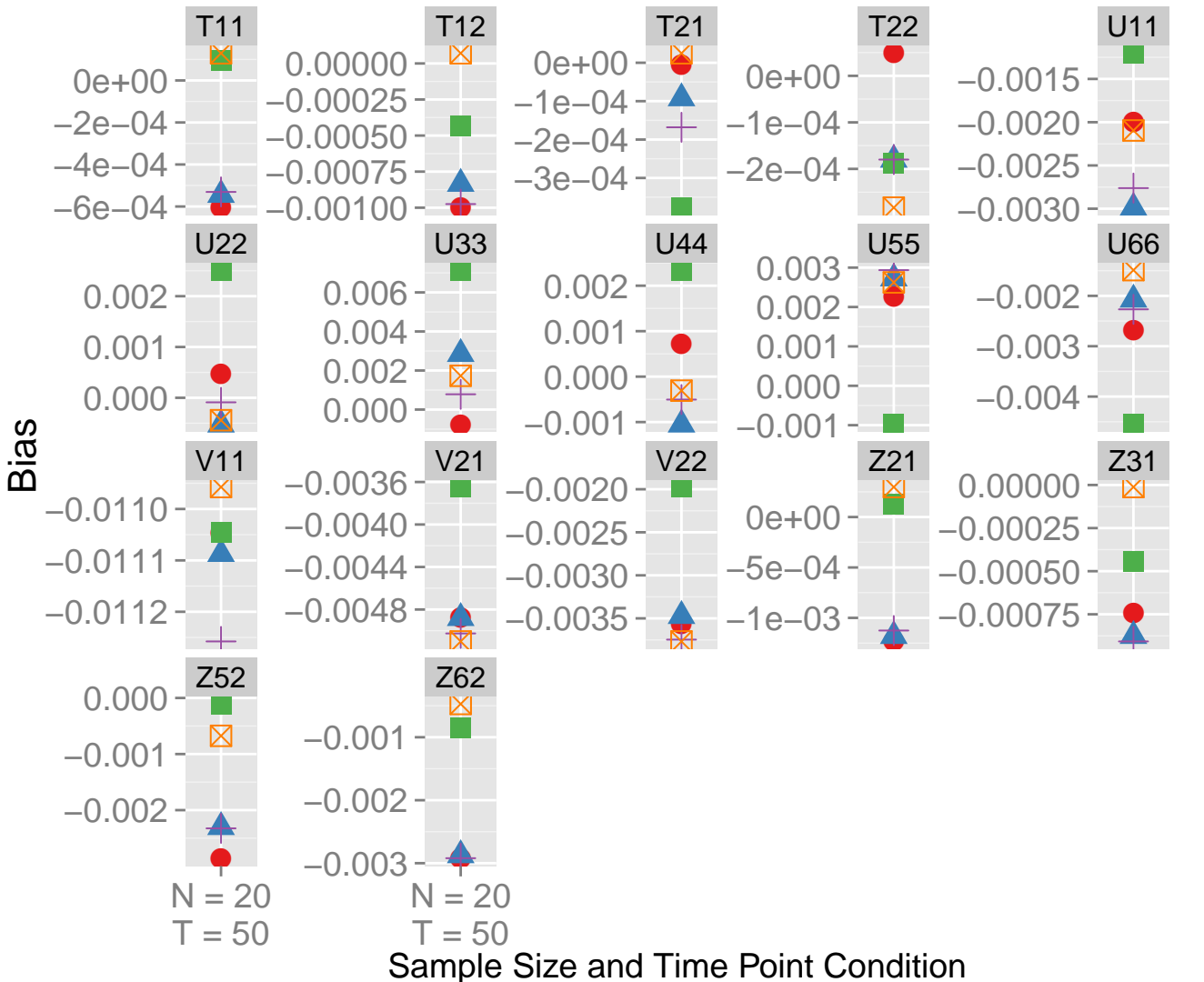


# Non-Stationary Mild Model True Initial Condition: FreeParam



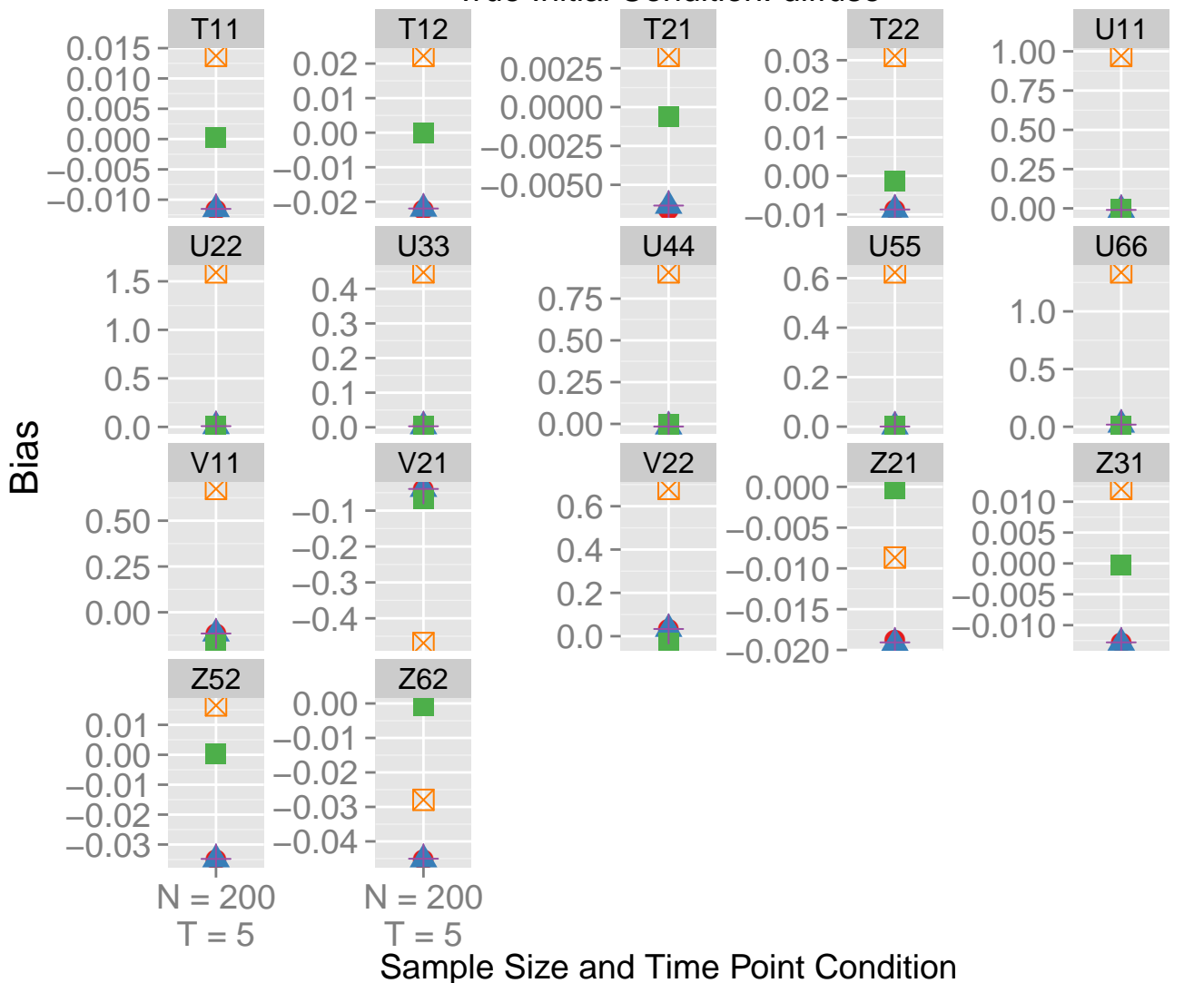
# Non-Stationary Mild Model

True Initial Condition: Null



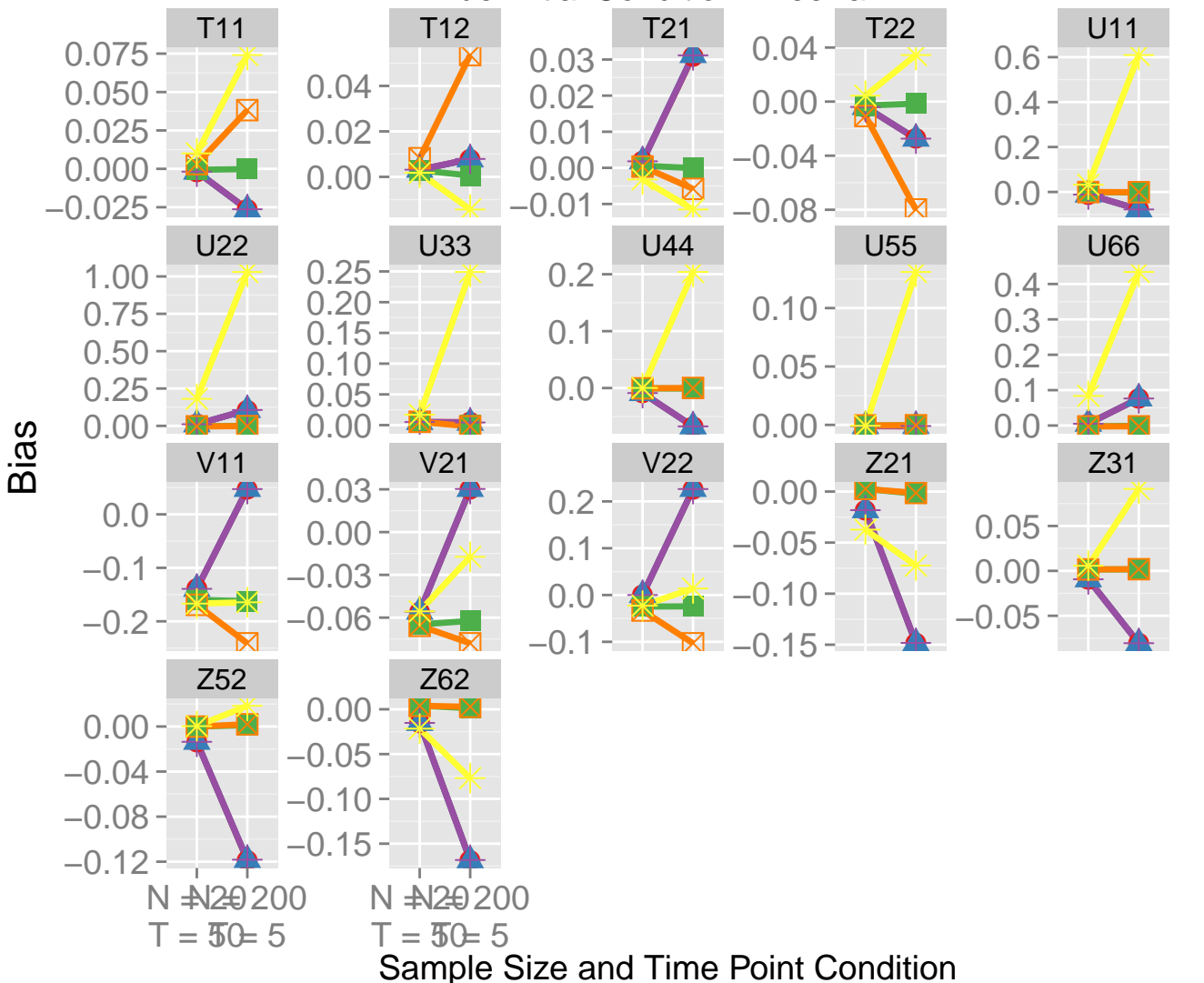
# Non-Stationary Moderate Model

True Initial Condition: diffuse



# Stationary Model

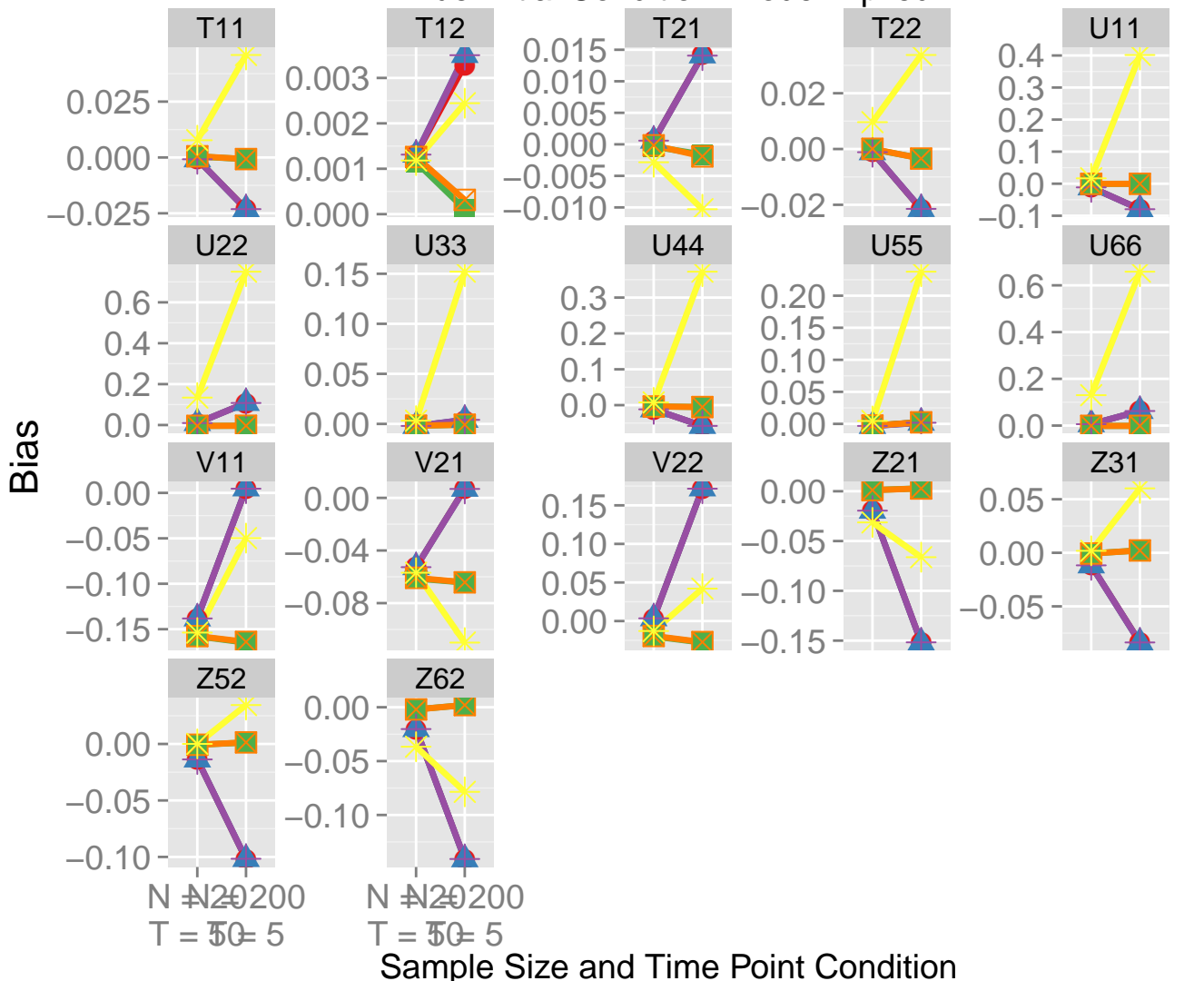
## True Initial Condition: FreeParm



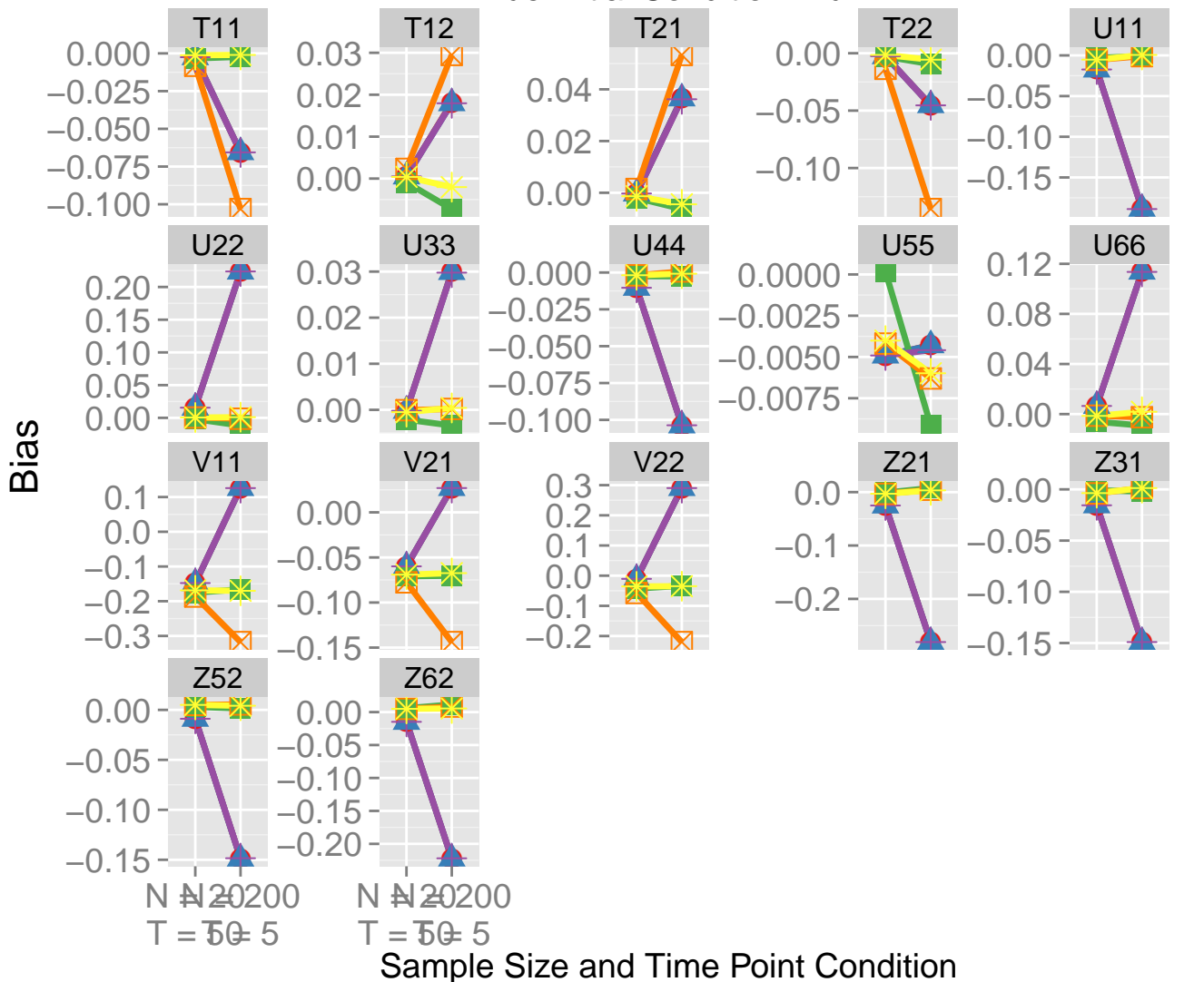


# Stationary Model

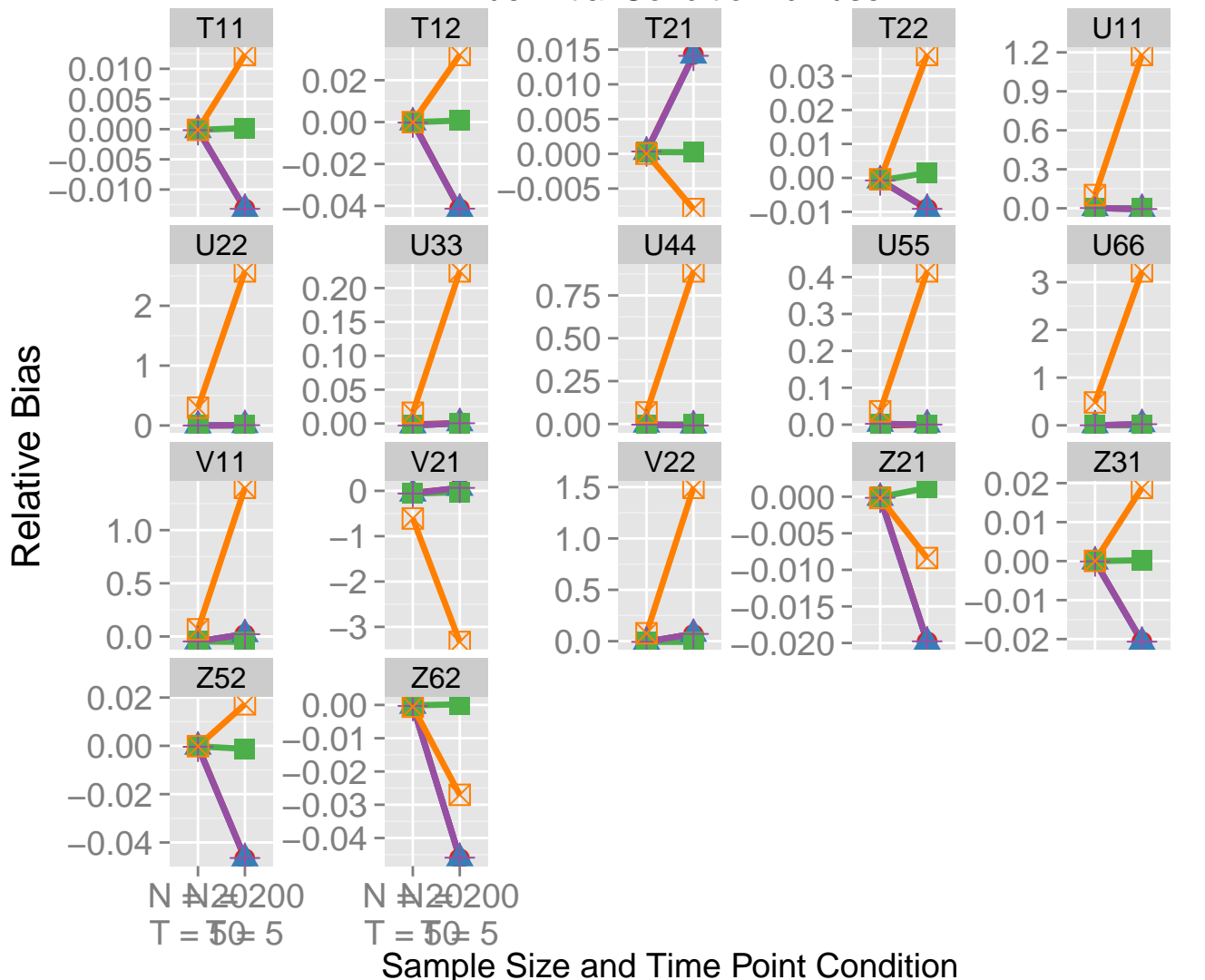
## True Initial Condition: ModelImplied



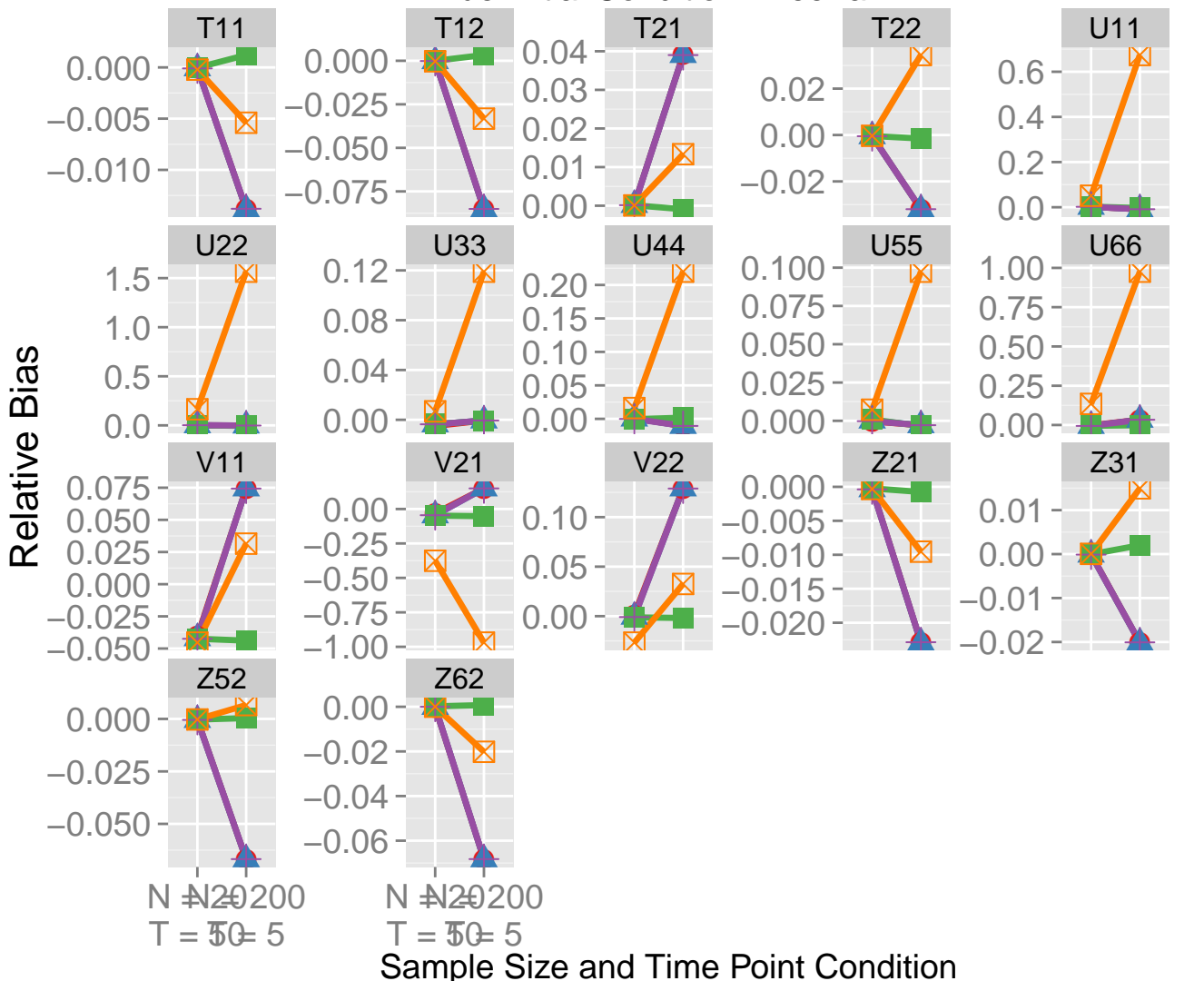
# Stationary Model True Initial Condition: Null



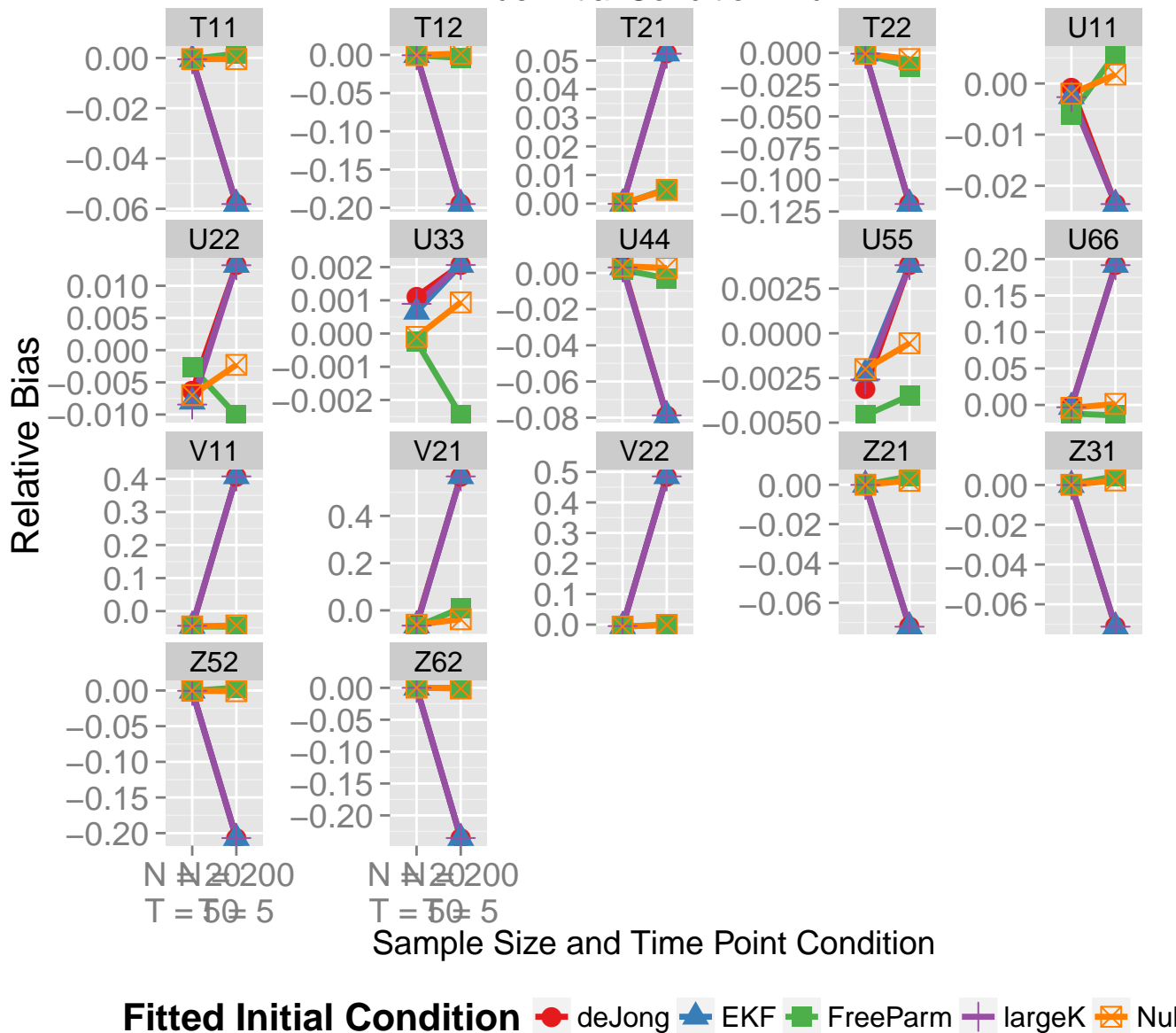
# Non-Stationary Model True Initial Condition: diffuse



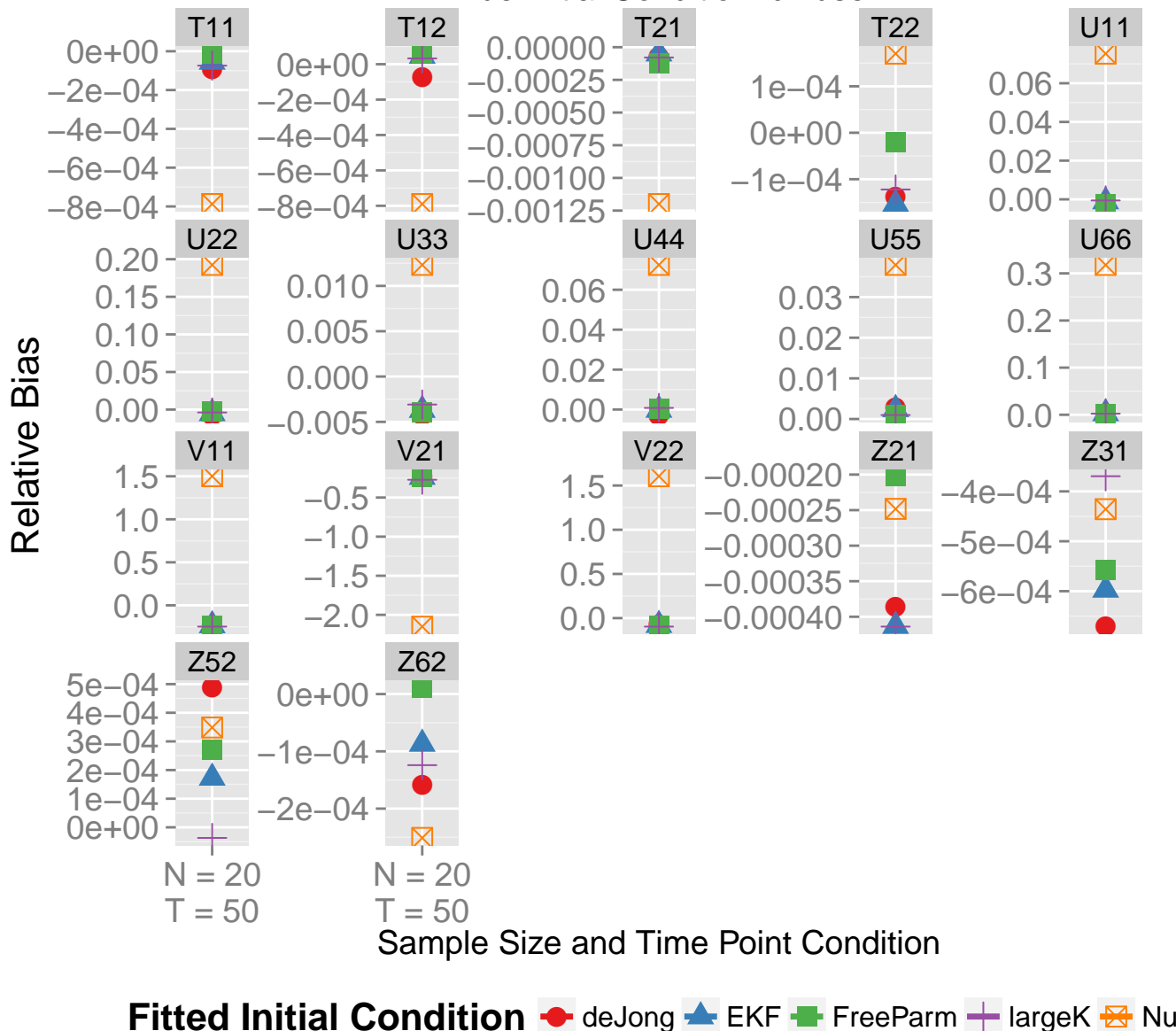
# Non-Stationary Model True Initial Condition: FreeParm



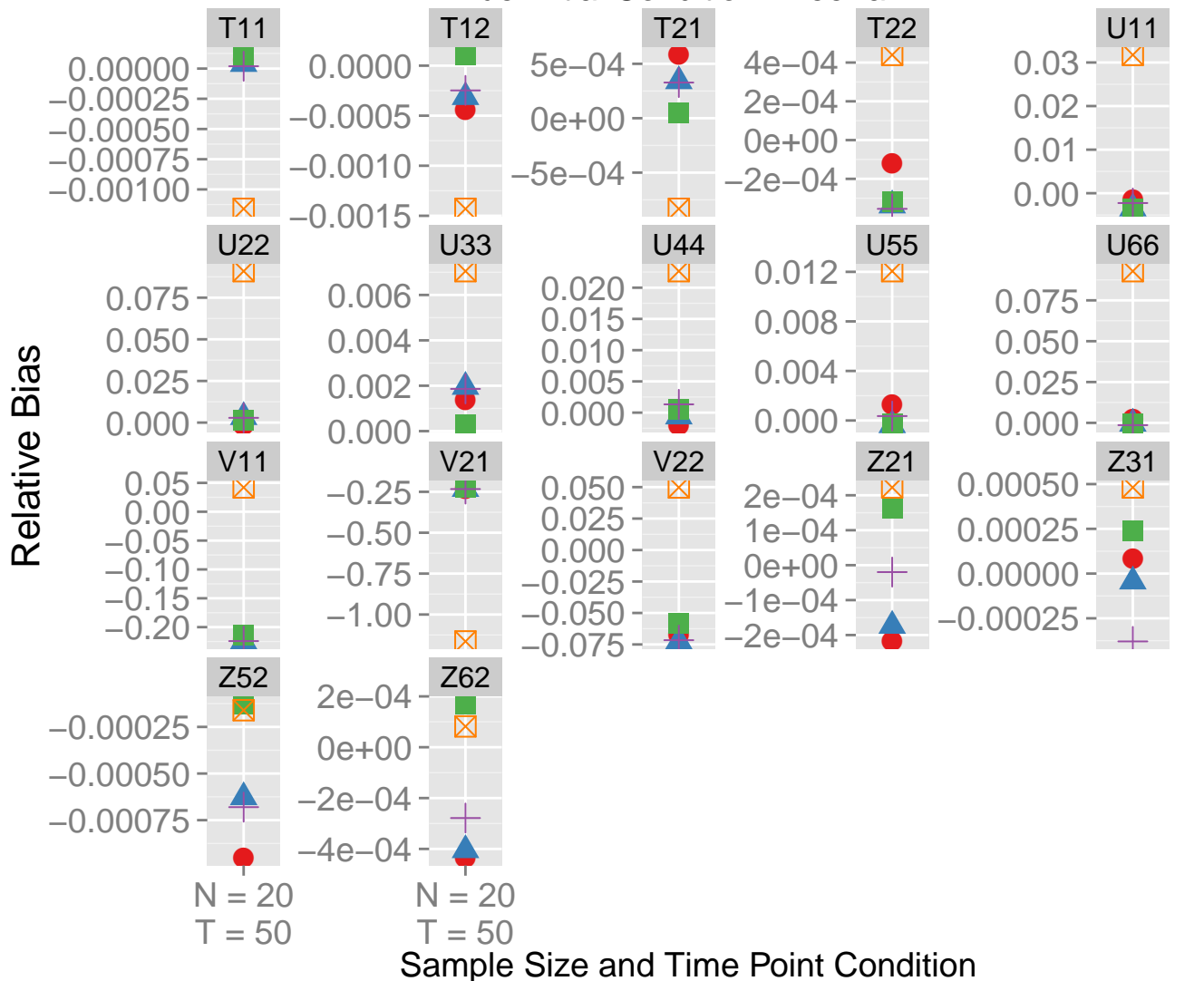
# Non-Stationary Model True Initial Condition: Null



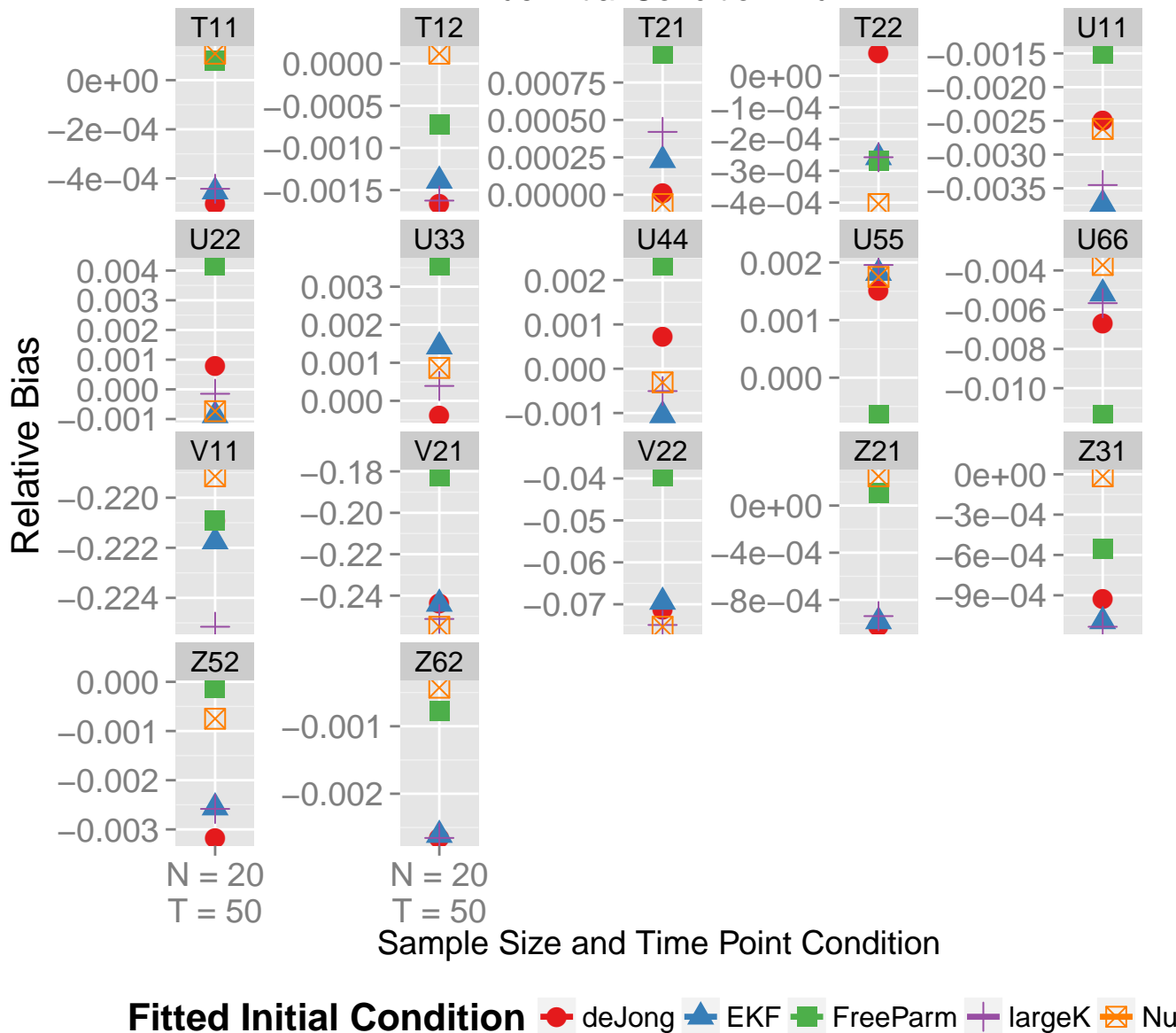
# Non-Stationary Mild Model True Initial Condition: diffuse



# Non-Stationary Mild Model True Initial Condition: FreeParm



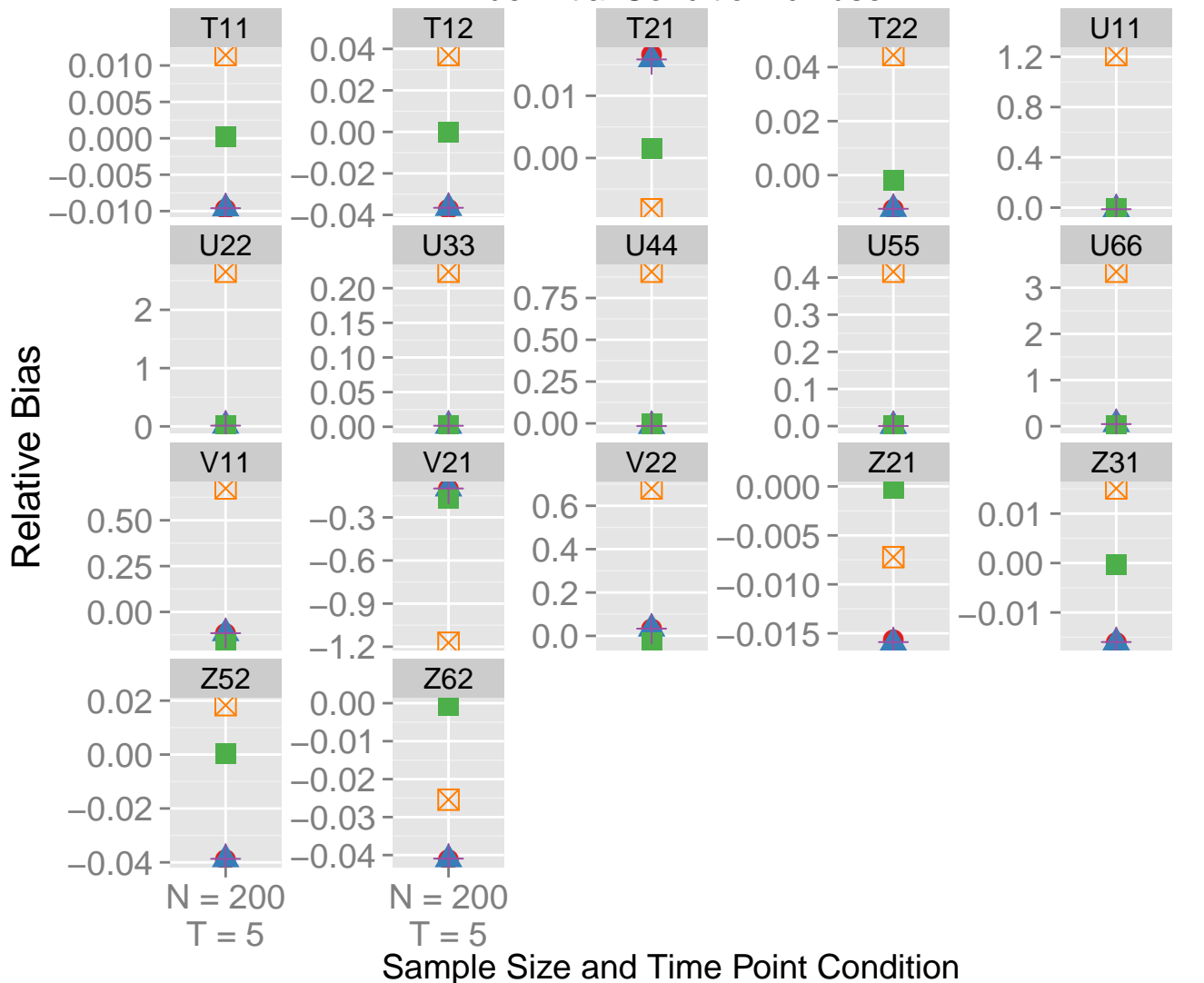
# Non-Stationary Mild Model True Initial Condition: Null





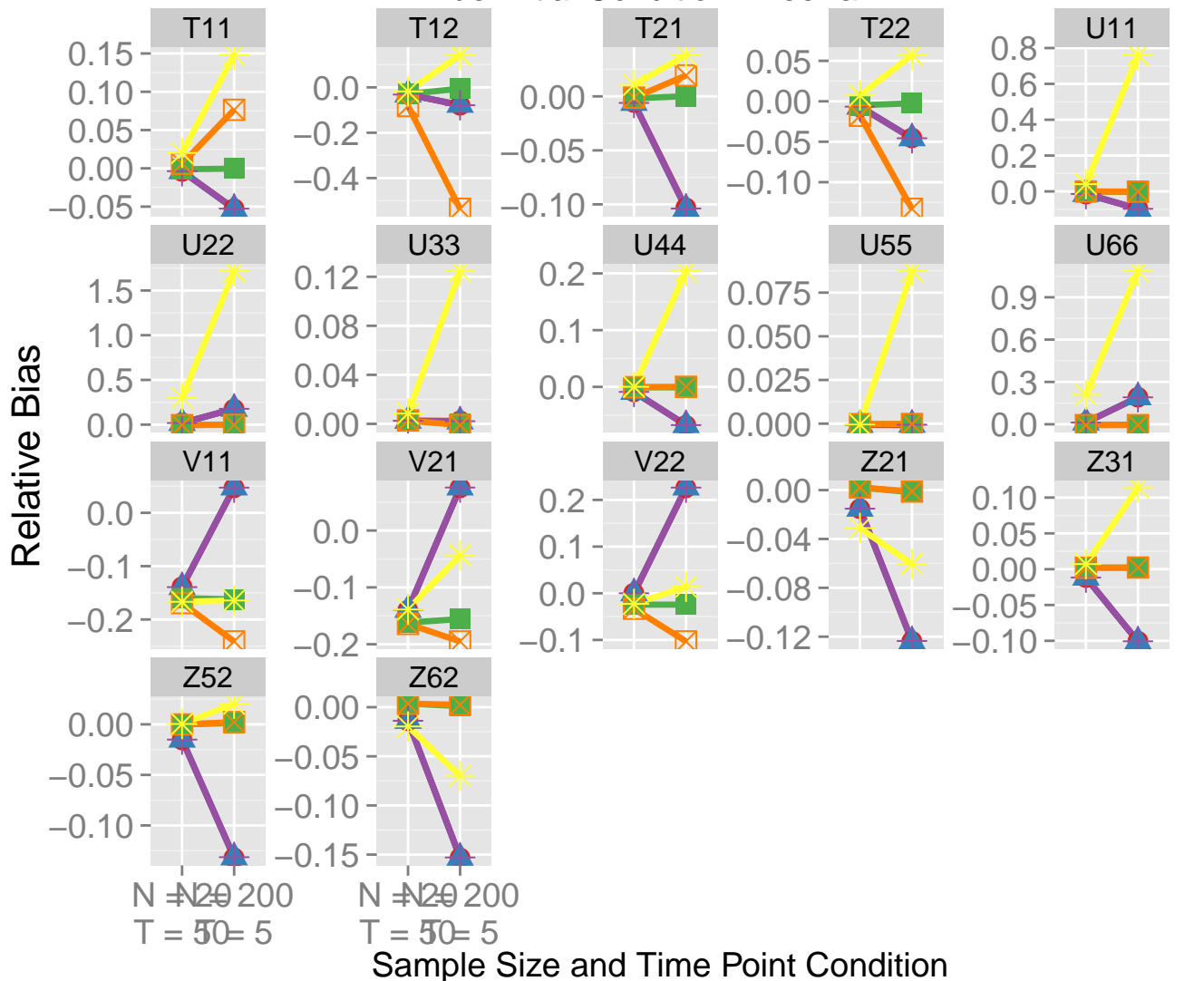
# Non-Stationary Moderate Model

True Initial Condition: diffuse



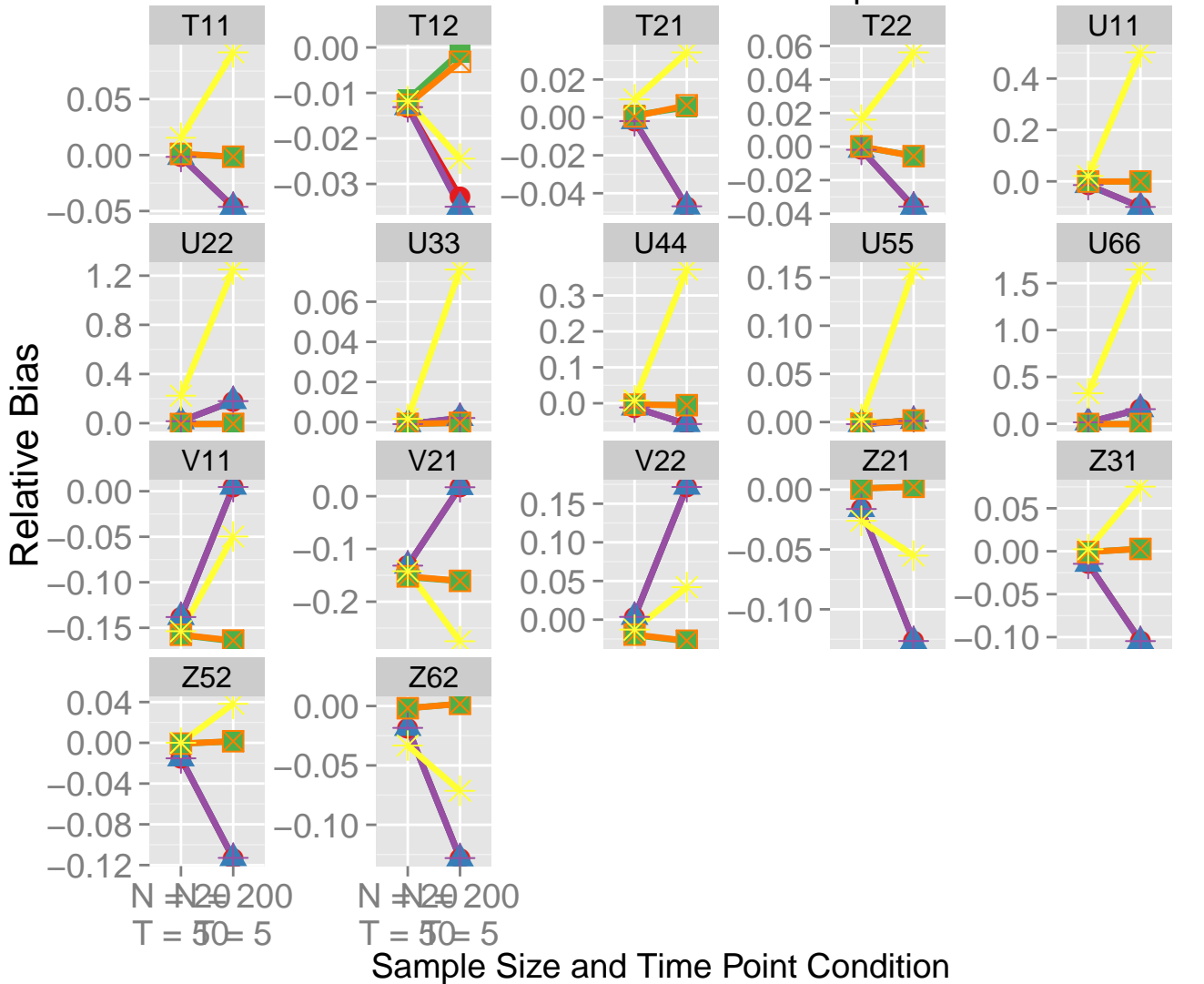
# Stationary Model

## True Initial Condition: FreeParm

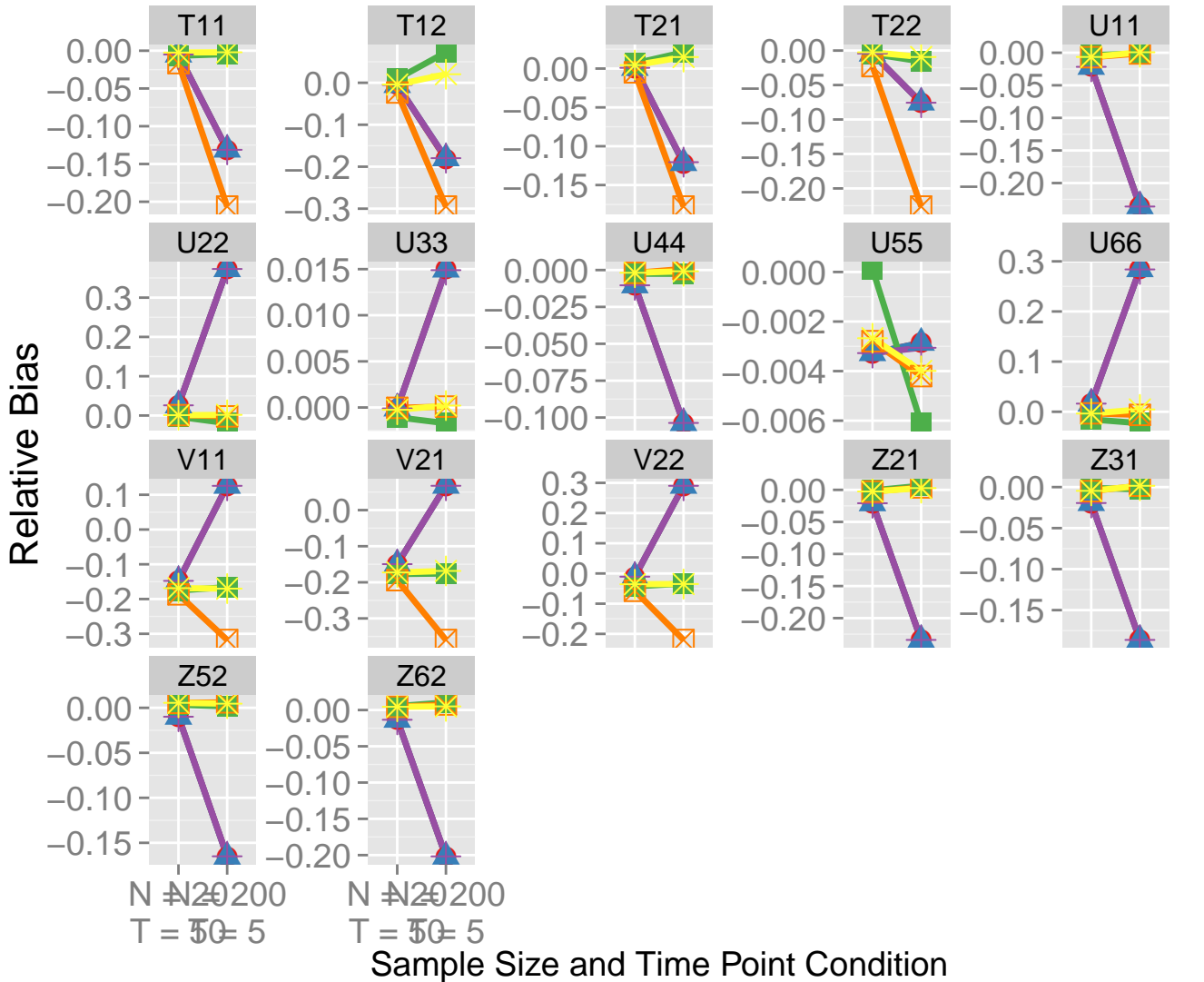


# Stationary Model

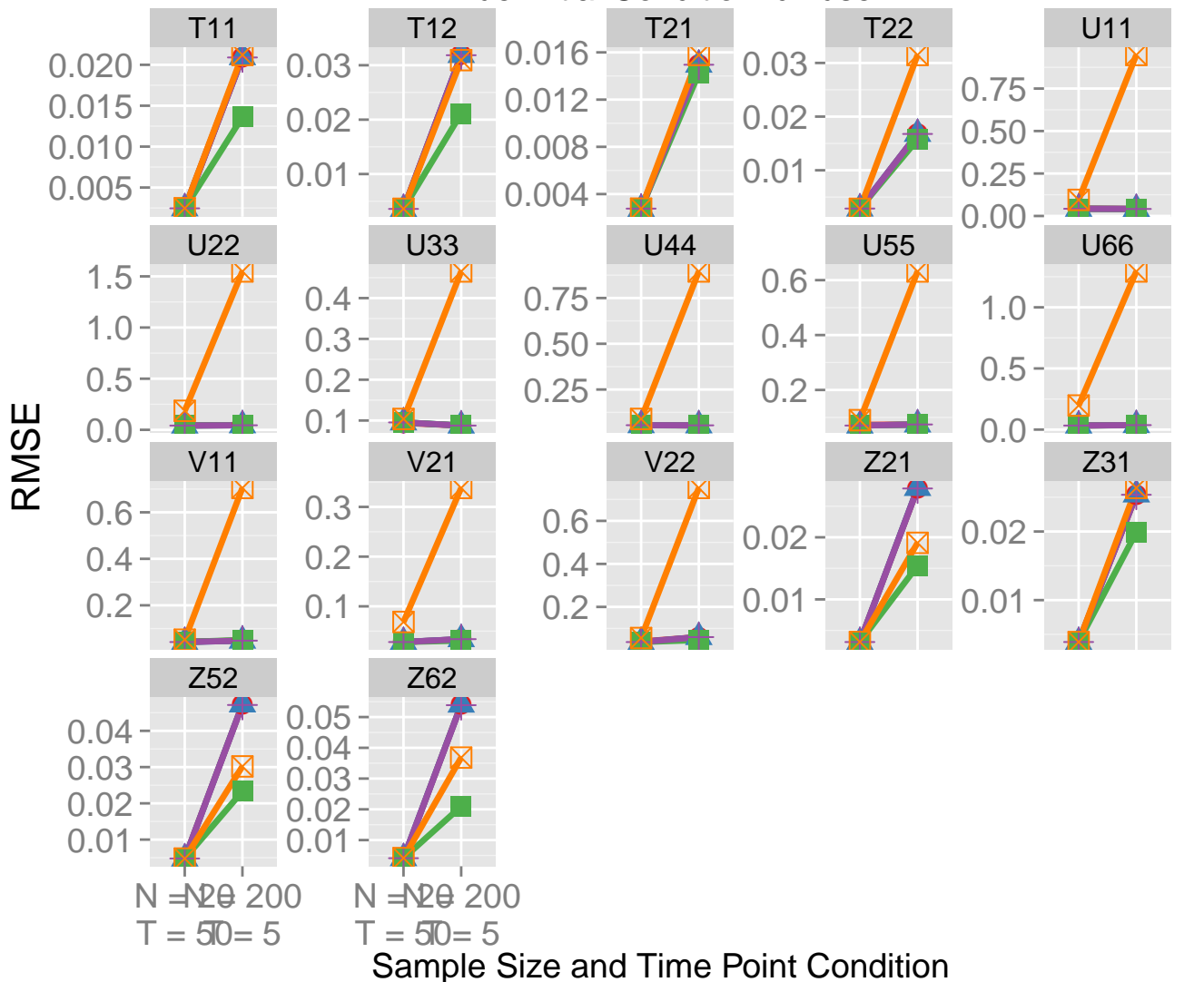
## True Initial Condition: ModelImplied



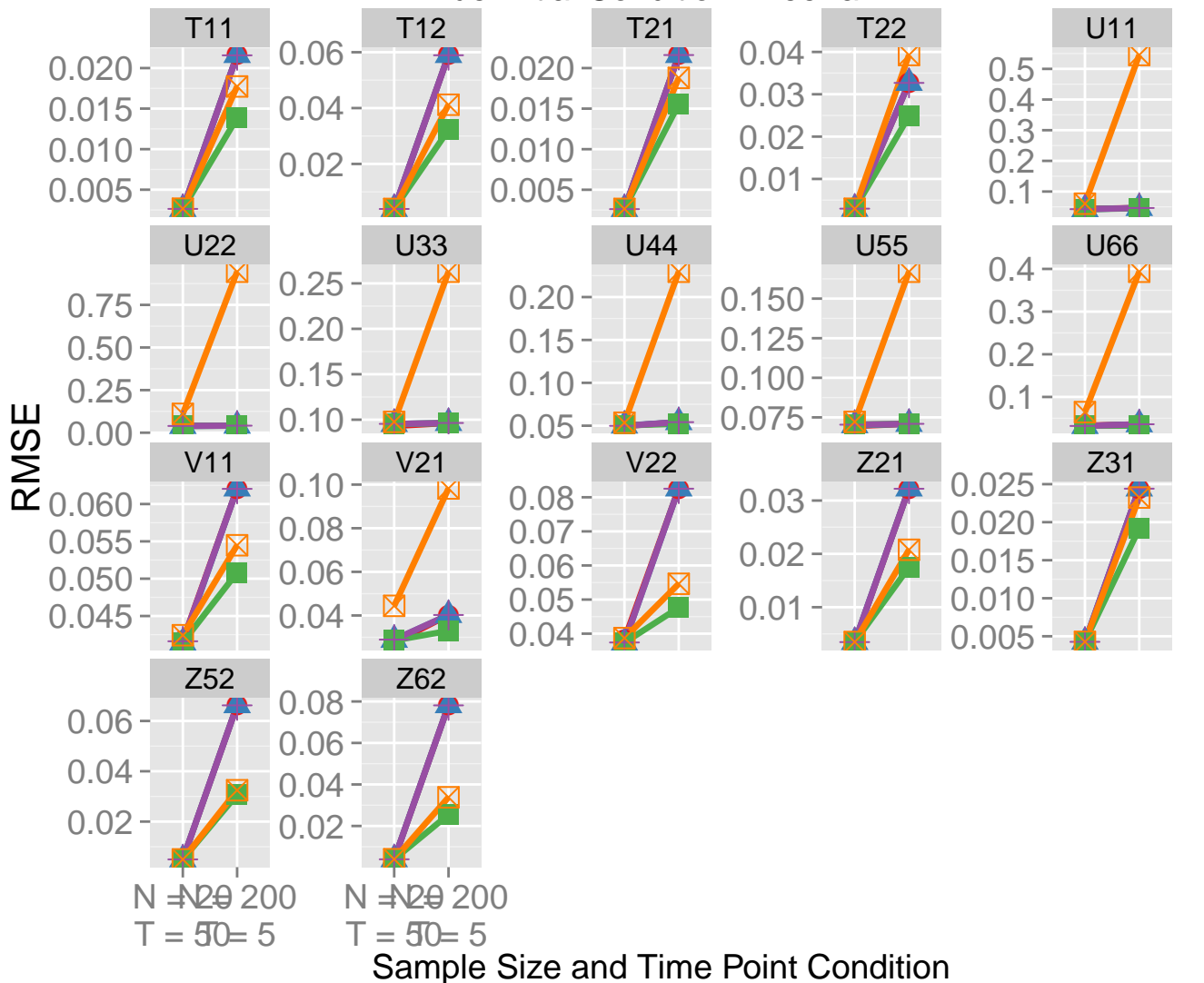
# Stationary Model True Initial Condition: Null



# Non-Stationary Model True Initial Condition: diffuse

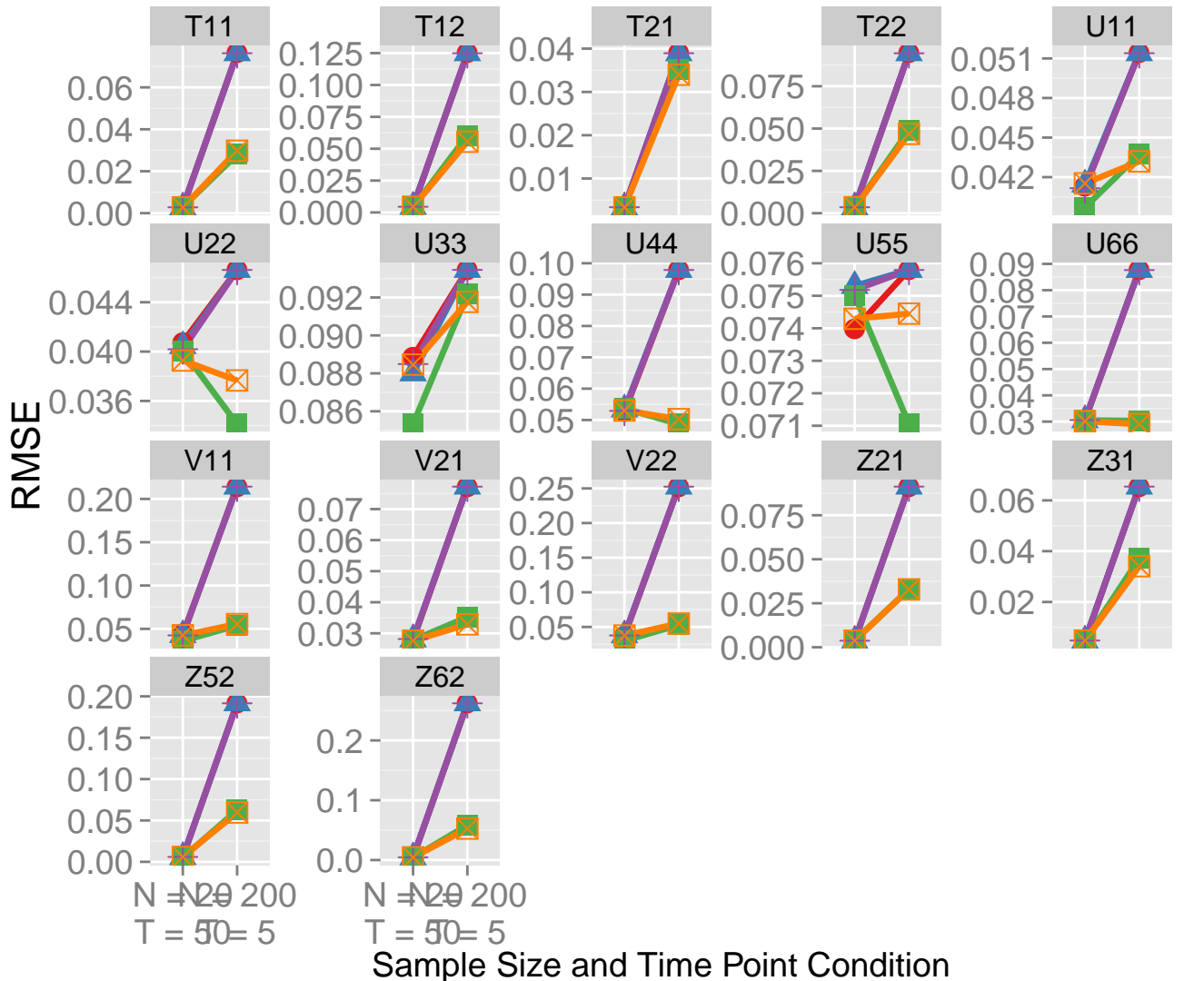


# Non-Stationary Model True Initial Condition: FreeParm

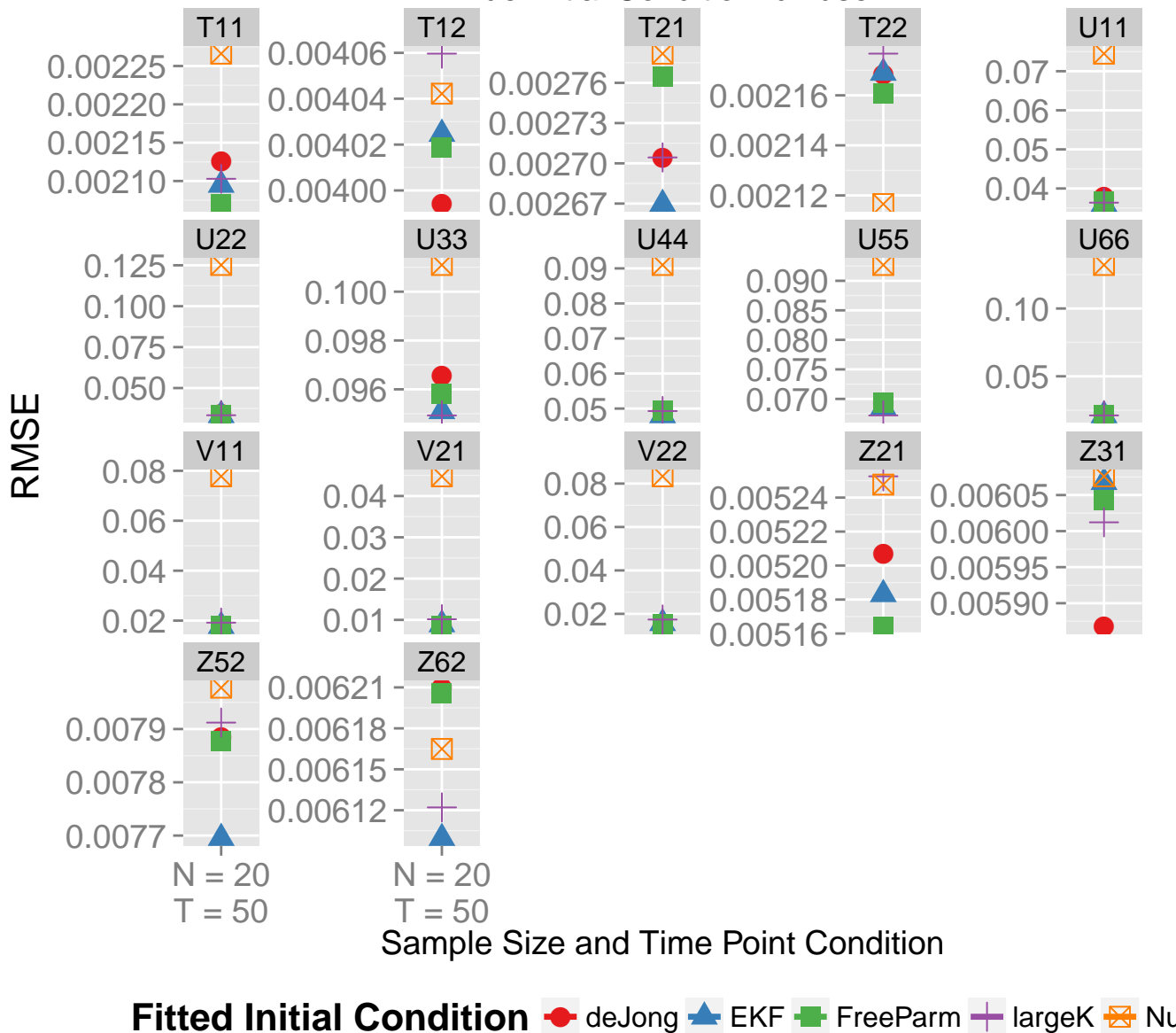


**Fitted Initial Condition** deJong EKF FreeParm largeK Null

# Non-Stationary Model True Initial Condition: Null

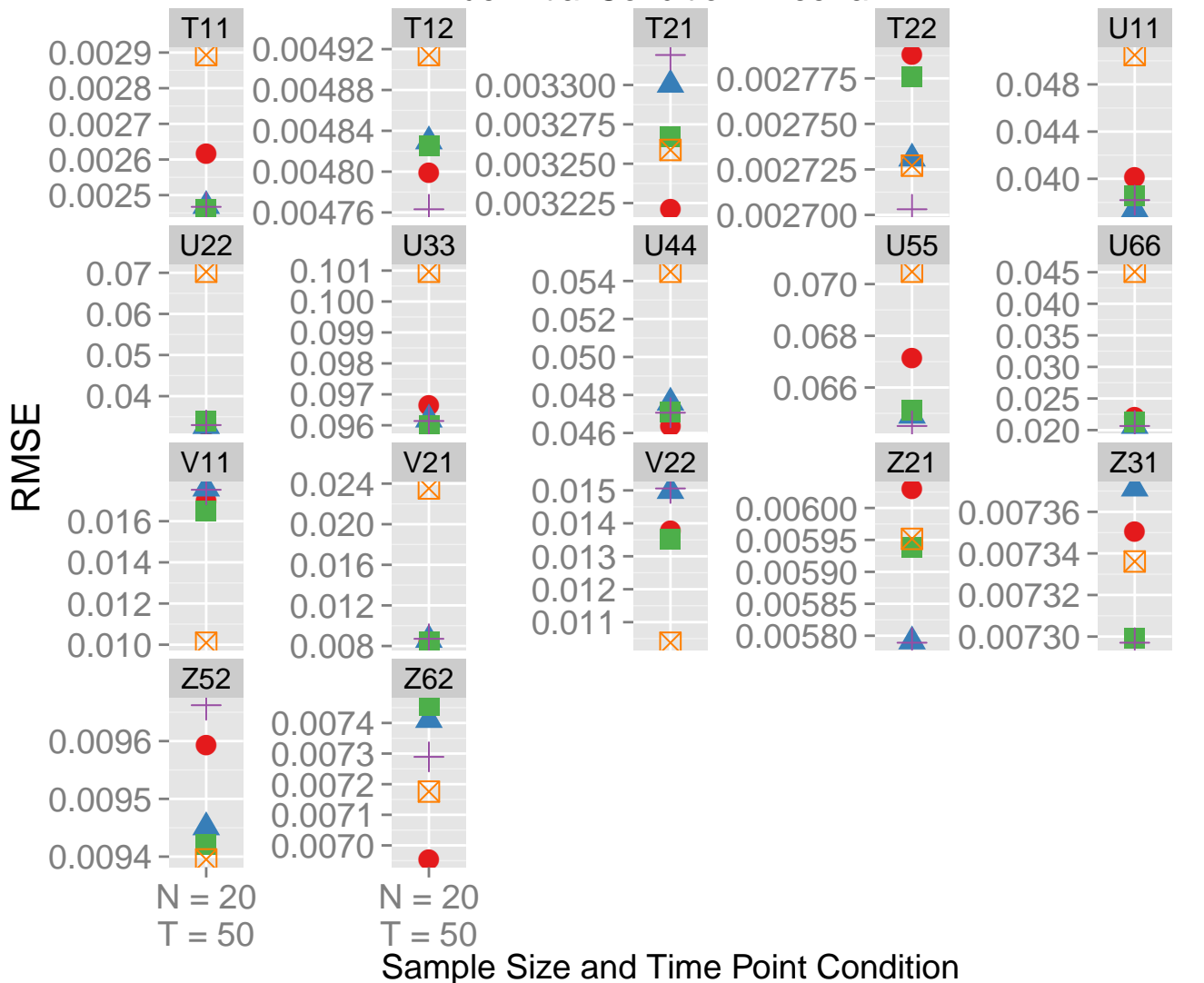


# Non-Stationary Mild Model True Initial Condition: diffuse



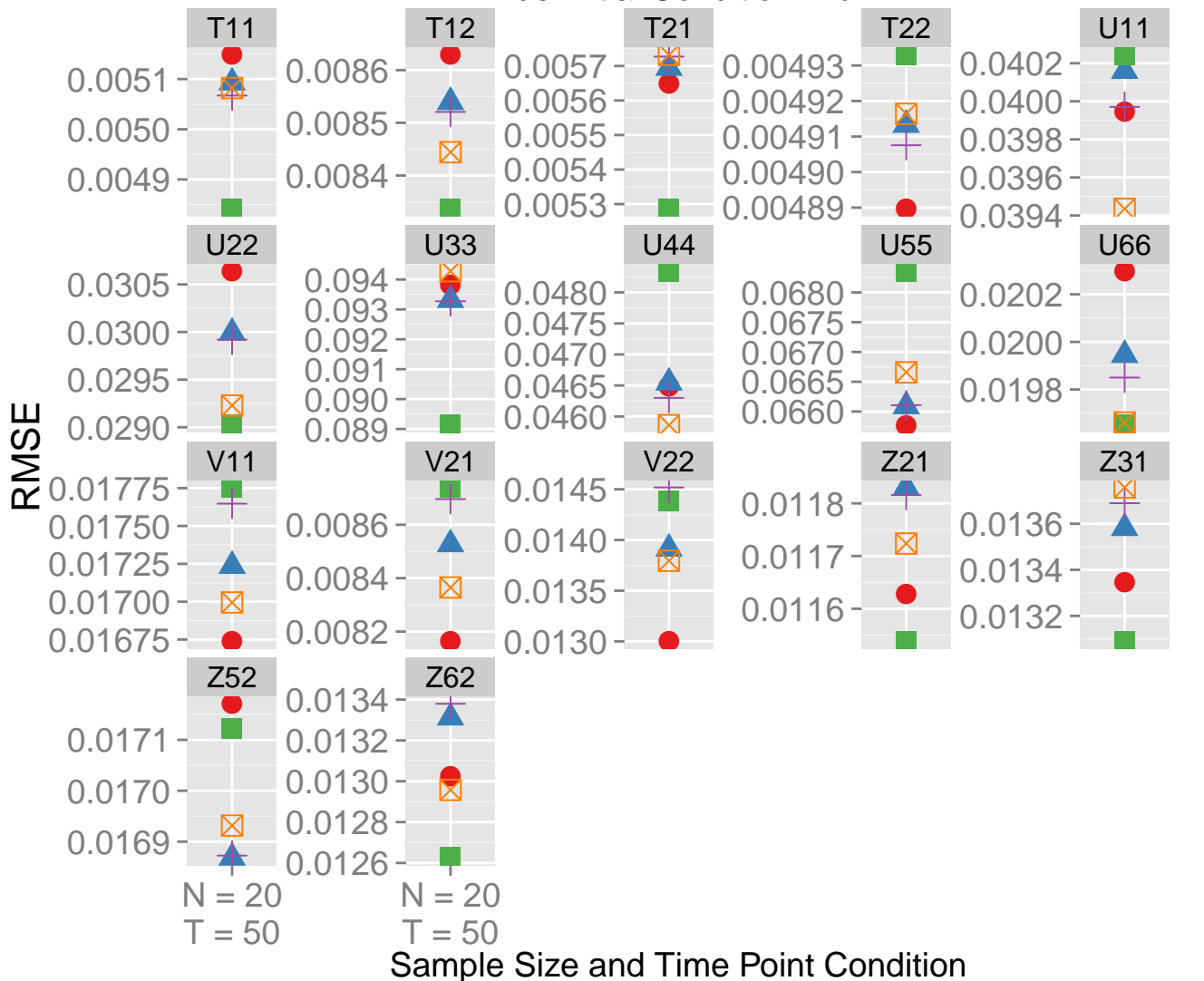


# Non-Stationary Mild Model True Initial Condition: FreeParm



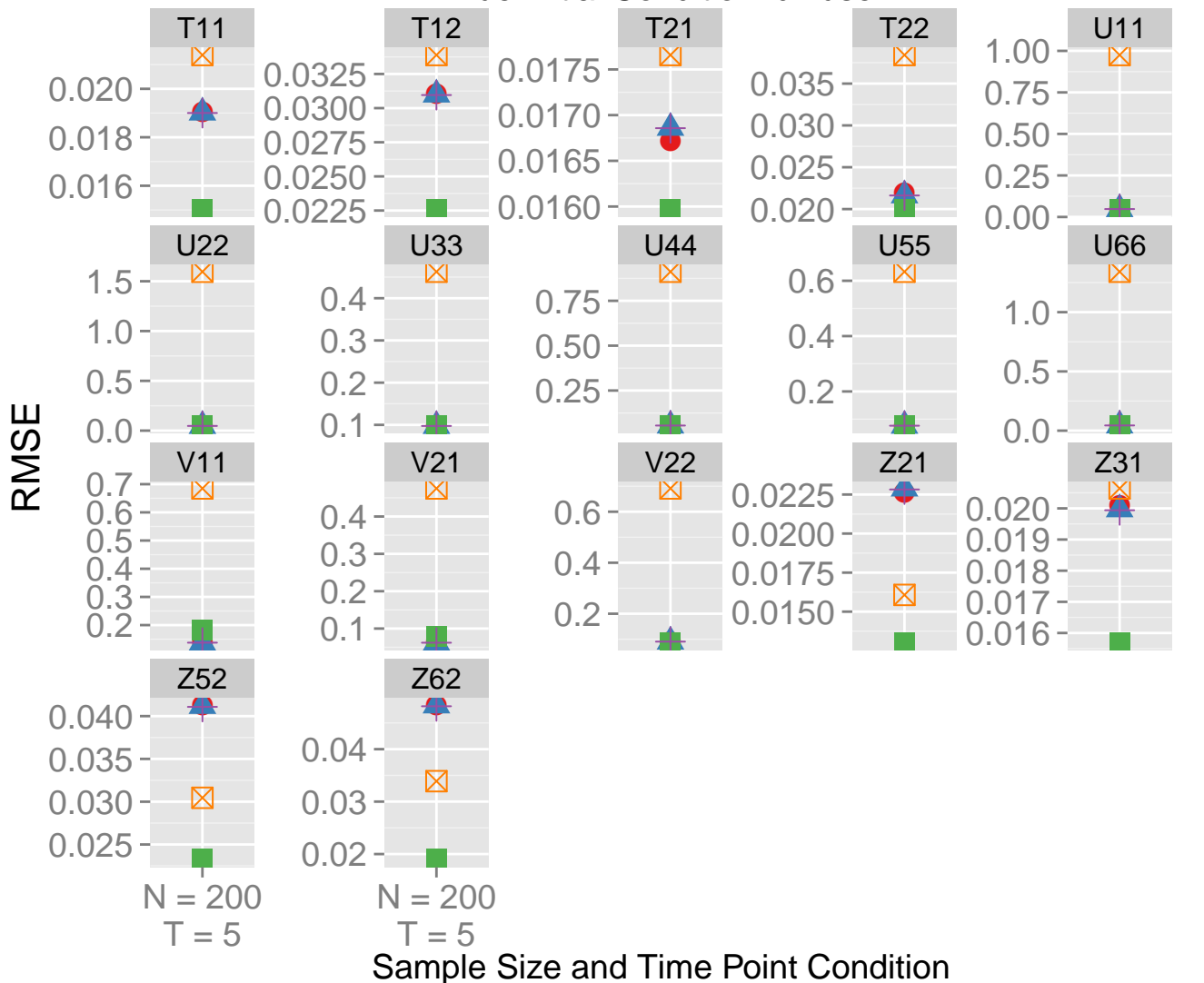
# Non-Stationary Mild Model

True Initial Condition: Null



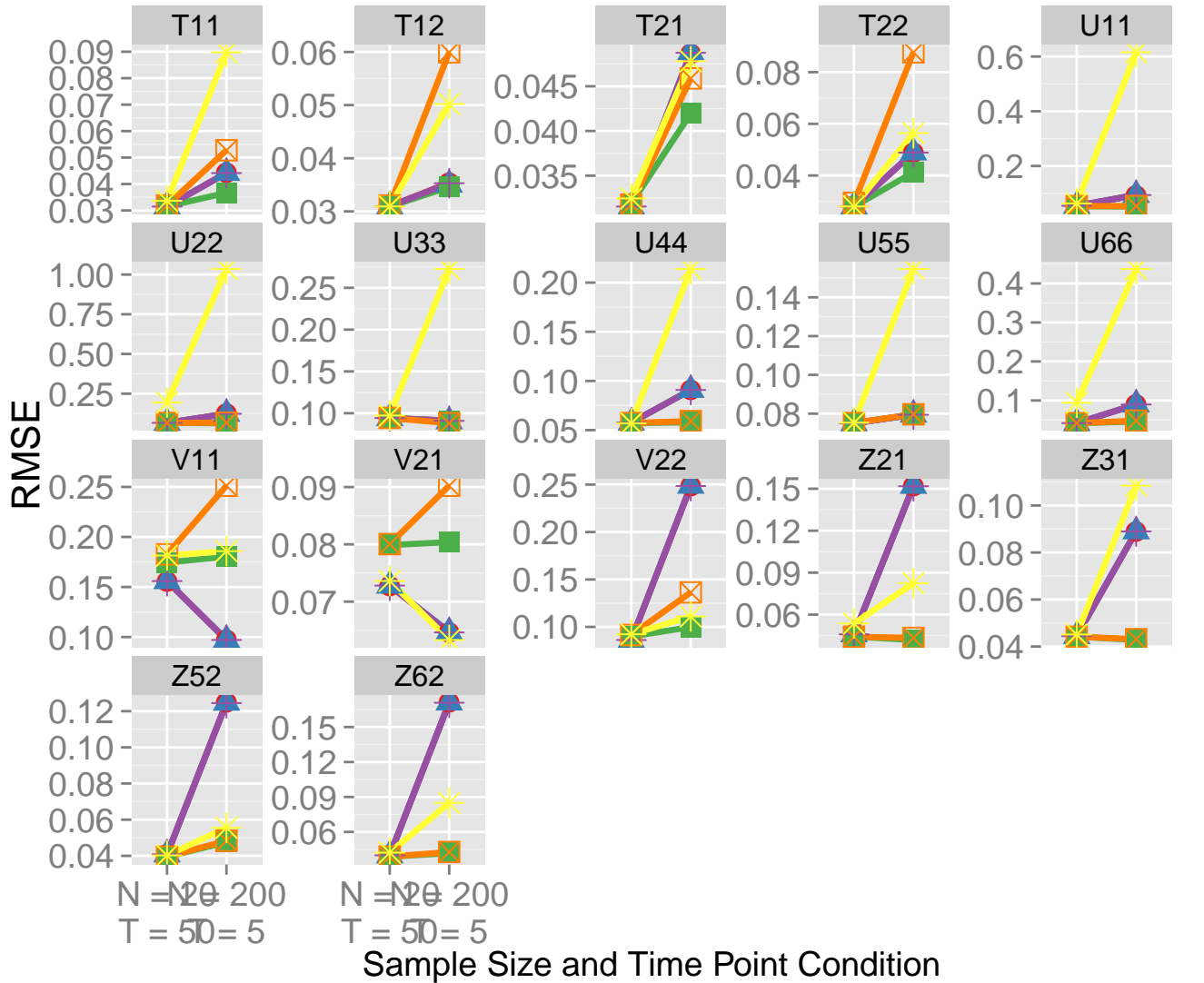
# Non-Stationary Moderate Model

True Initial Condition: diffuse



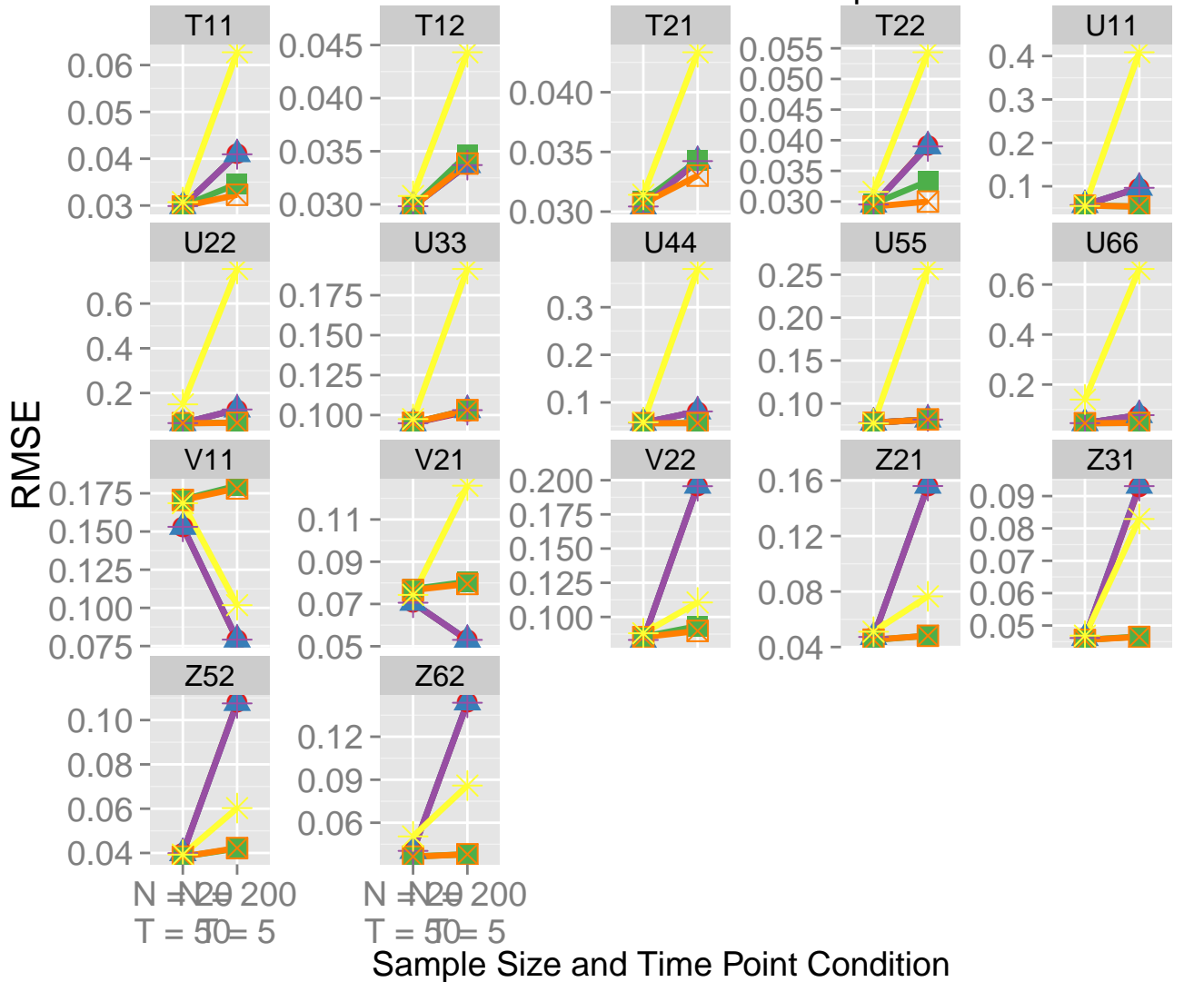
# Stationary Model

## True Initial Condition: FreeParm

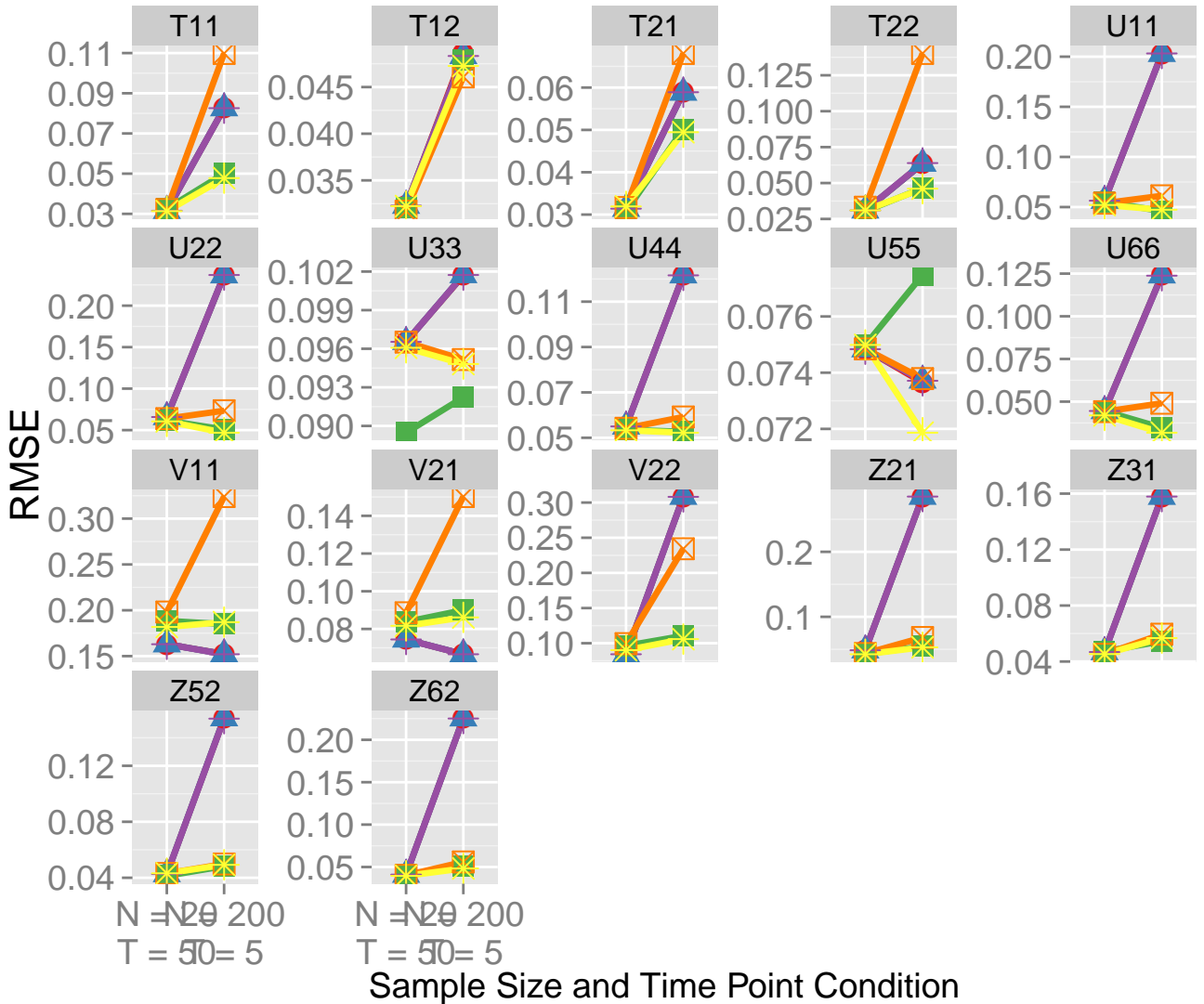


# Stationary Model

## True Initial Condition: ModelImplied

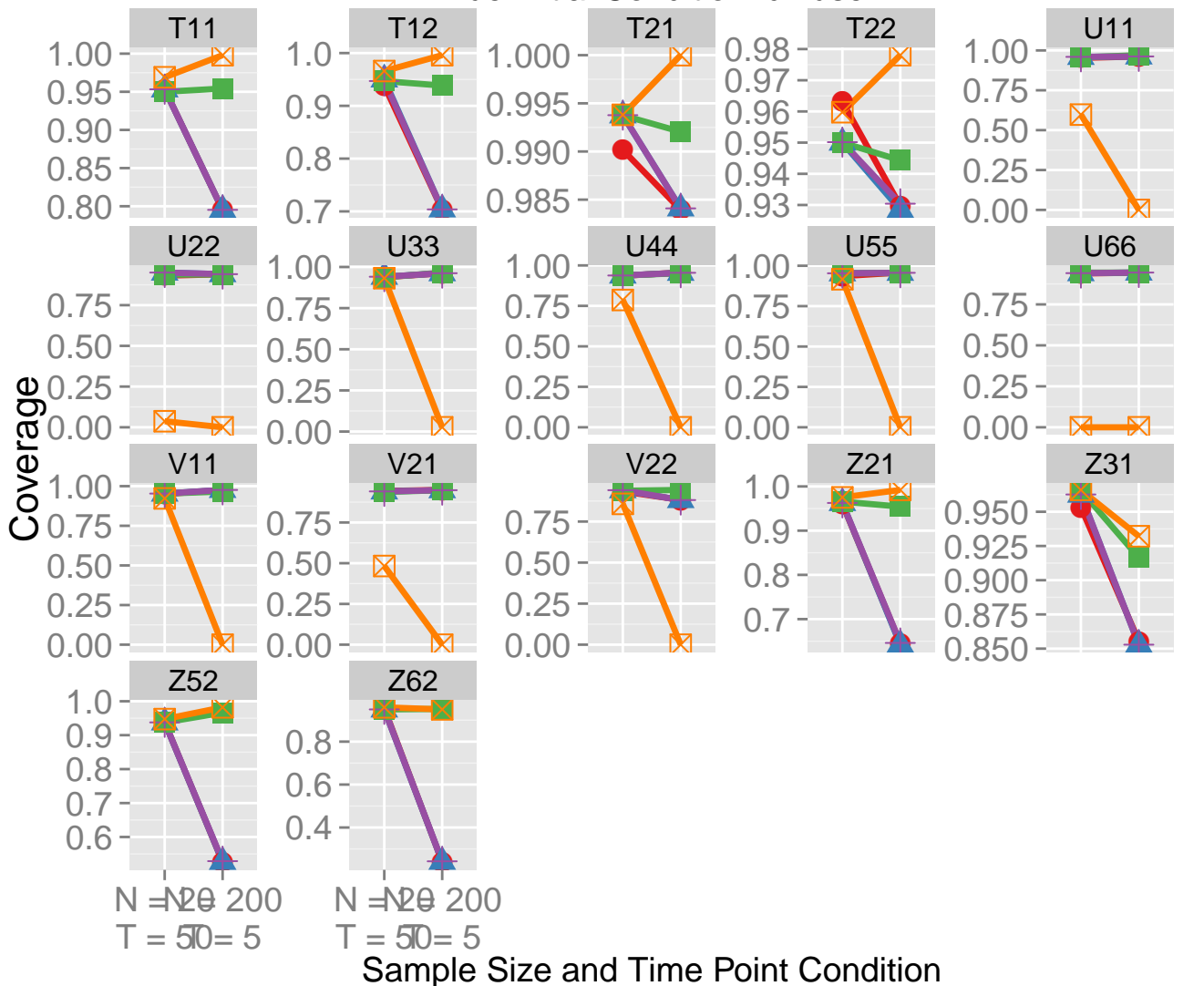


Stationary Model  
True Initial Condition: Null

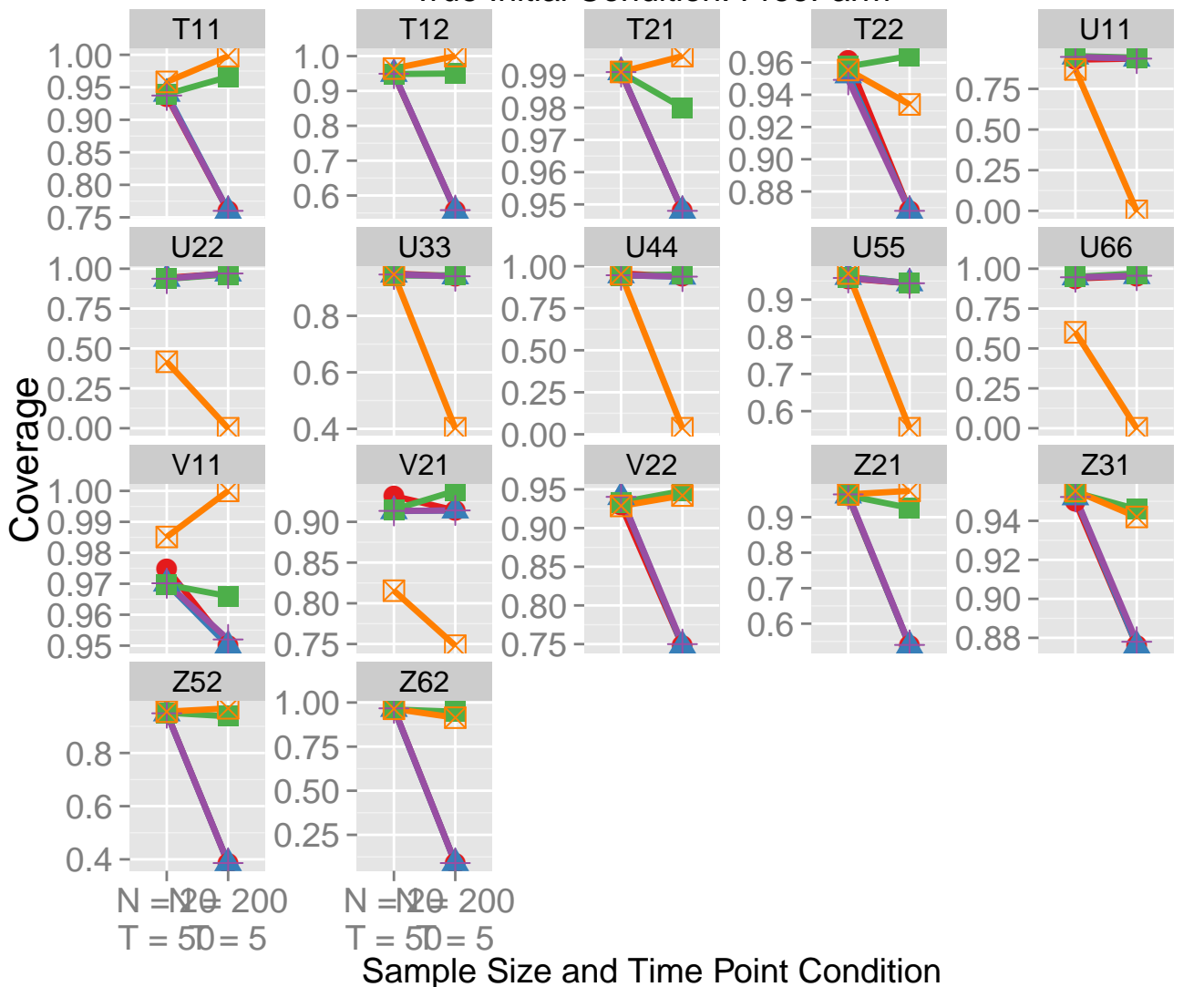


**Fitted Initial Condition**  deJong  EKF  FreeParm  largeK  ModelImplied

# Non-Stationary Model True Initial Condition: diffuse

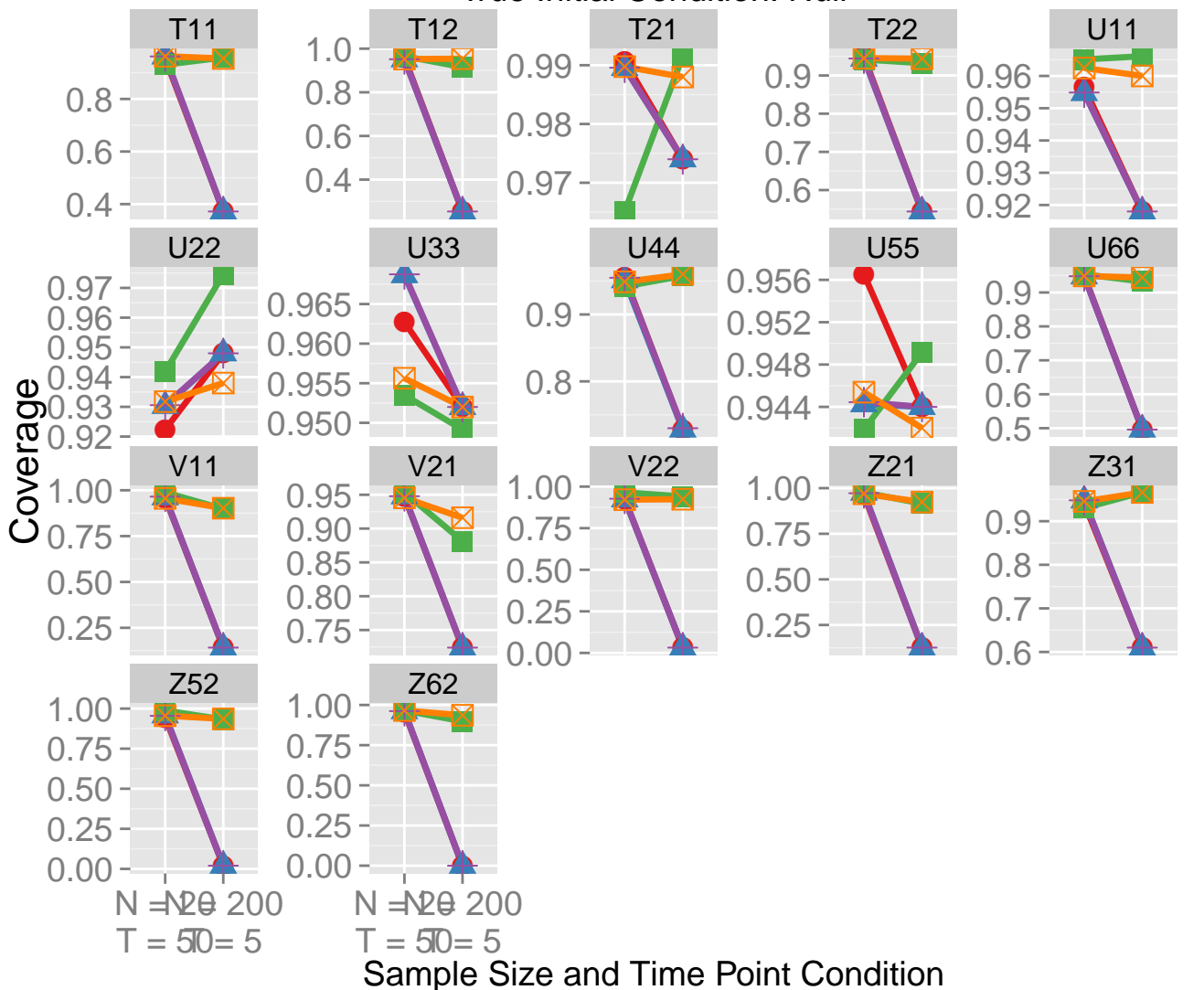


# Non-Stationary Model True Initial Condition: FreeParm

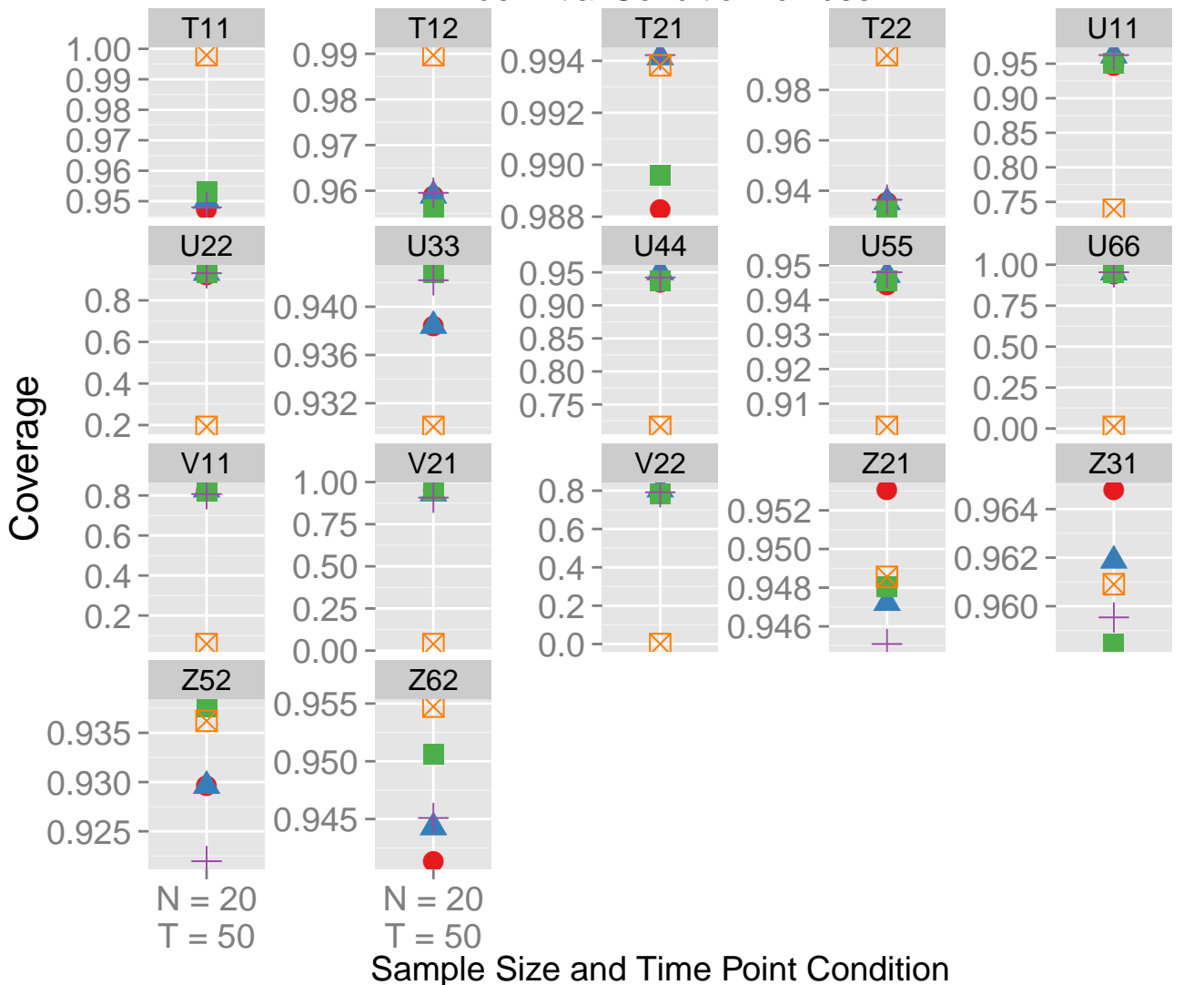




# Non-Stationary Model True Initial Condition: Null



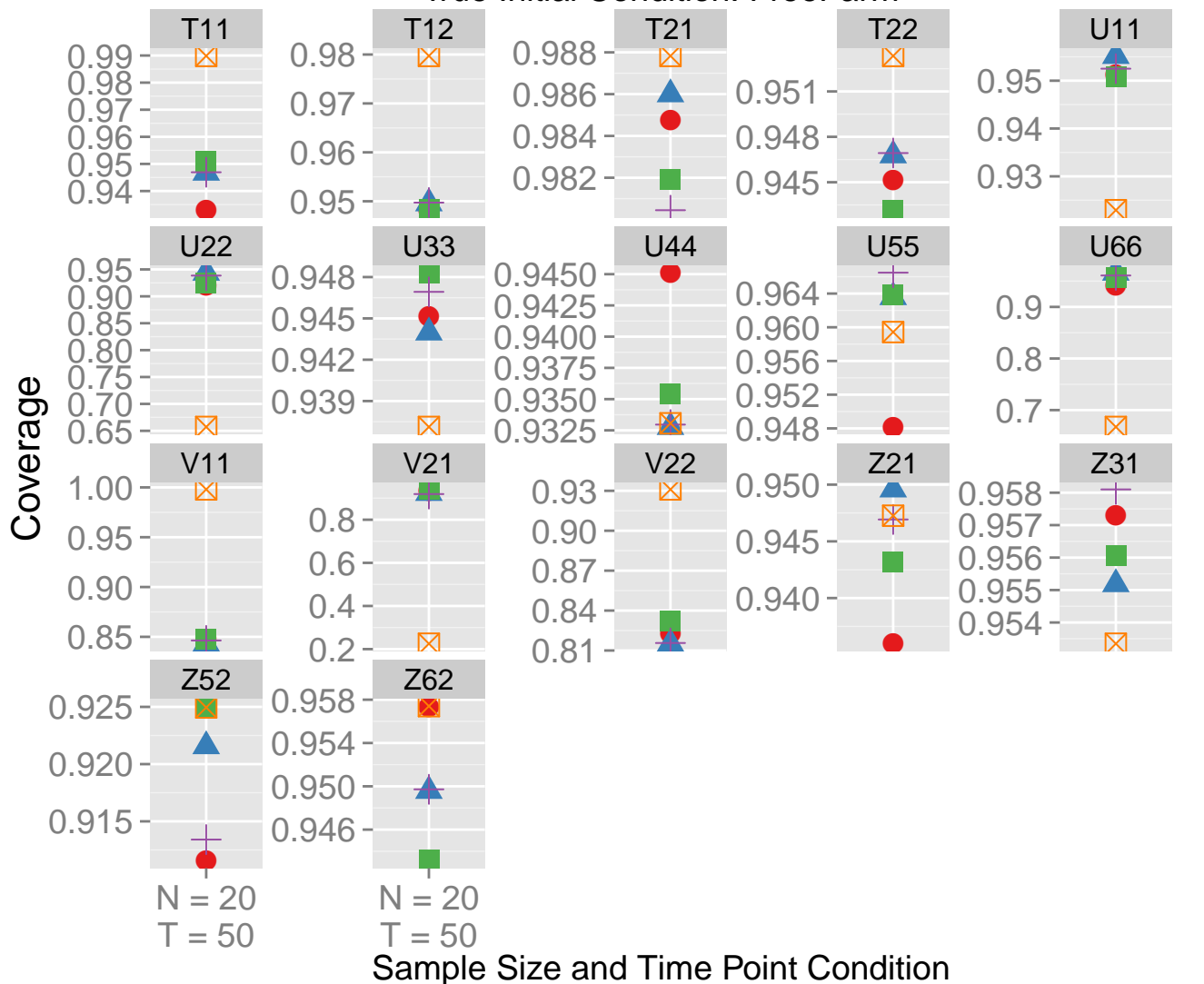
# Non-Stationary Mild Model True Initial Condition: diffuse



**Fitted Initial Condition**

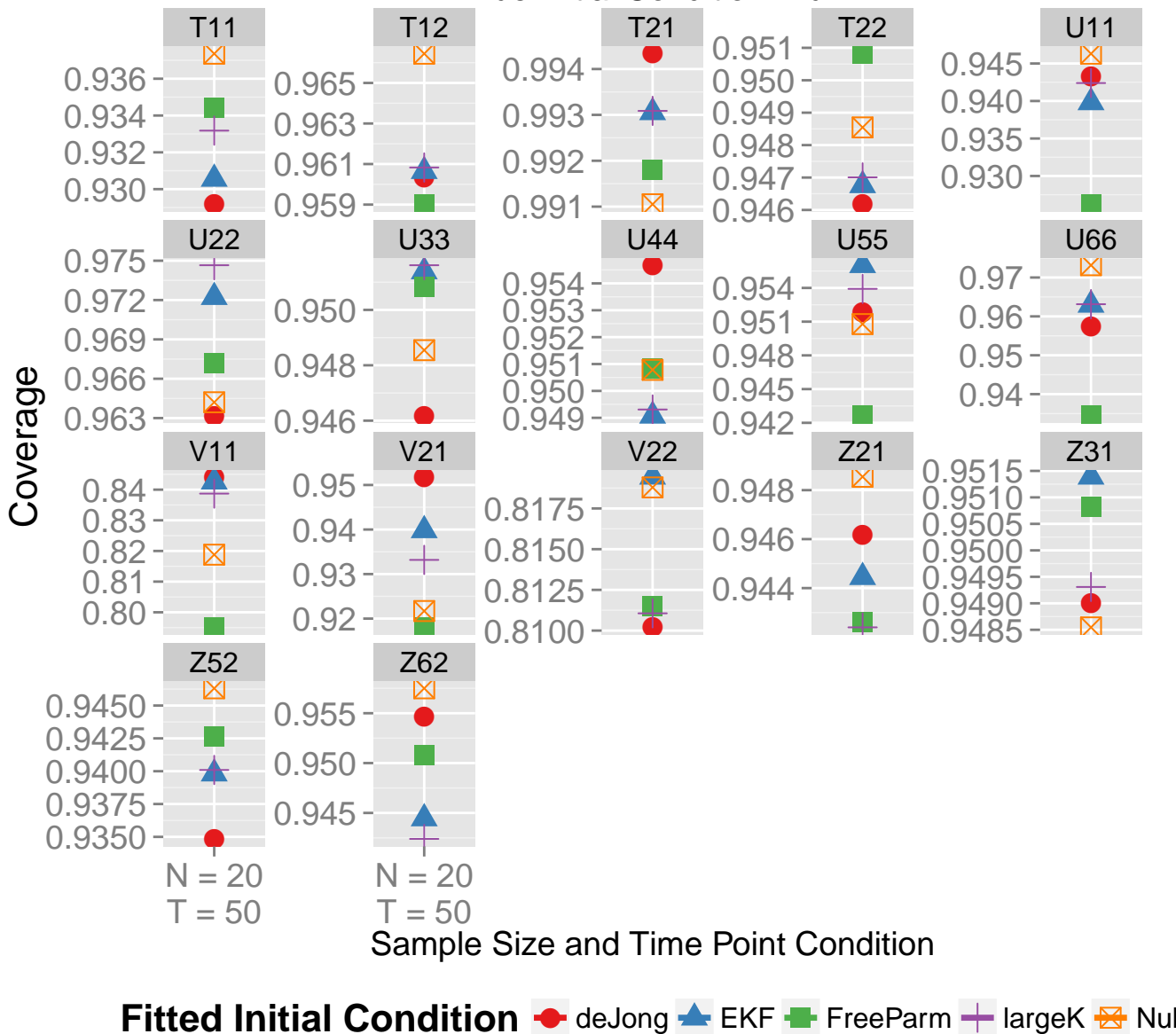
deJong EKF FreeParm largeK Null

# Non-Stationary Mild Model True Initial Condition: FreeParm



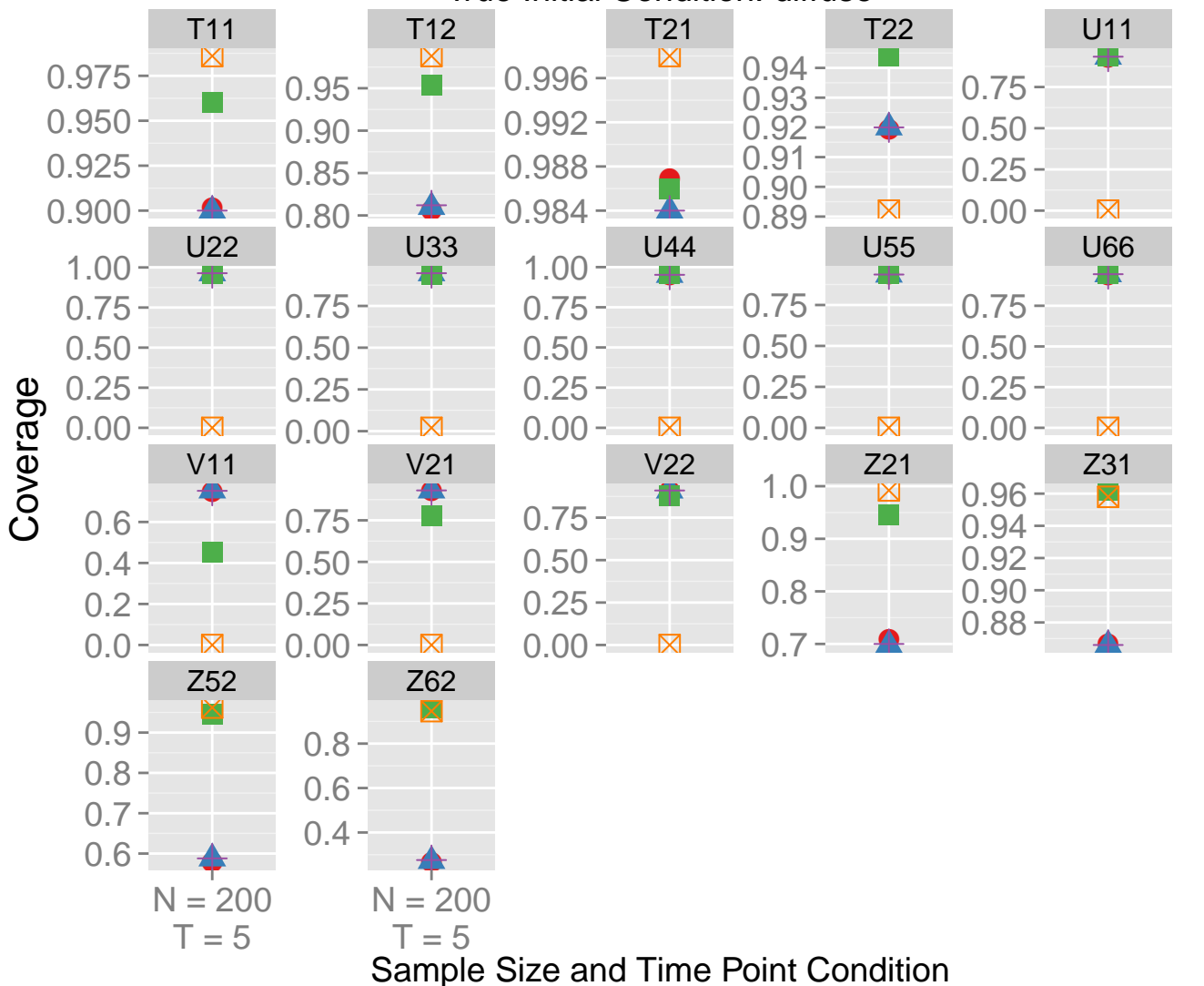
**Fitted Initial Condition** deJong EKF FreeParm largeK Null

# Non-Stationary Mild Model True Initial Condition: Null



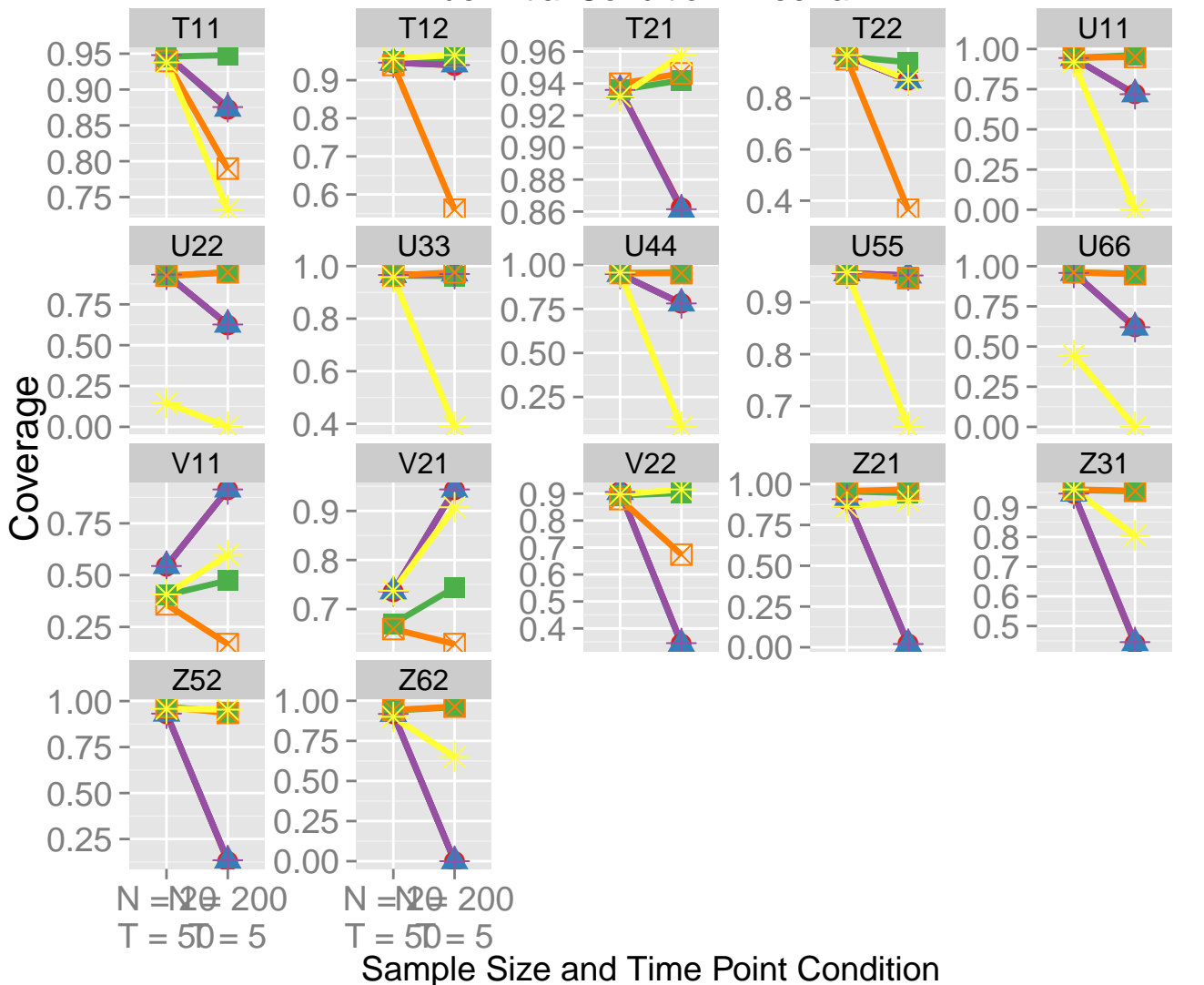
# Non-Stationary Moderate Model

True Initial Condition: diffuse



# Stationary Model

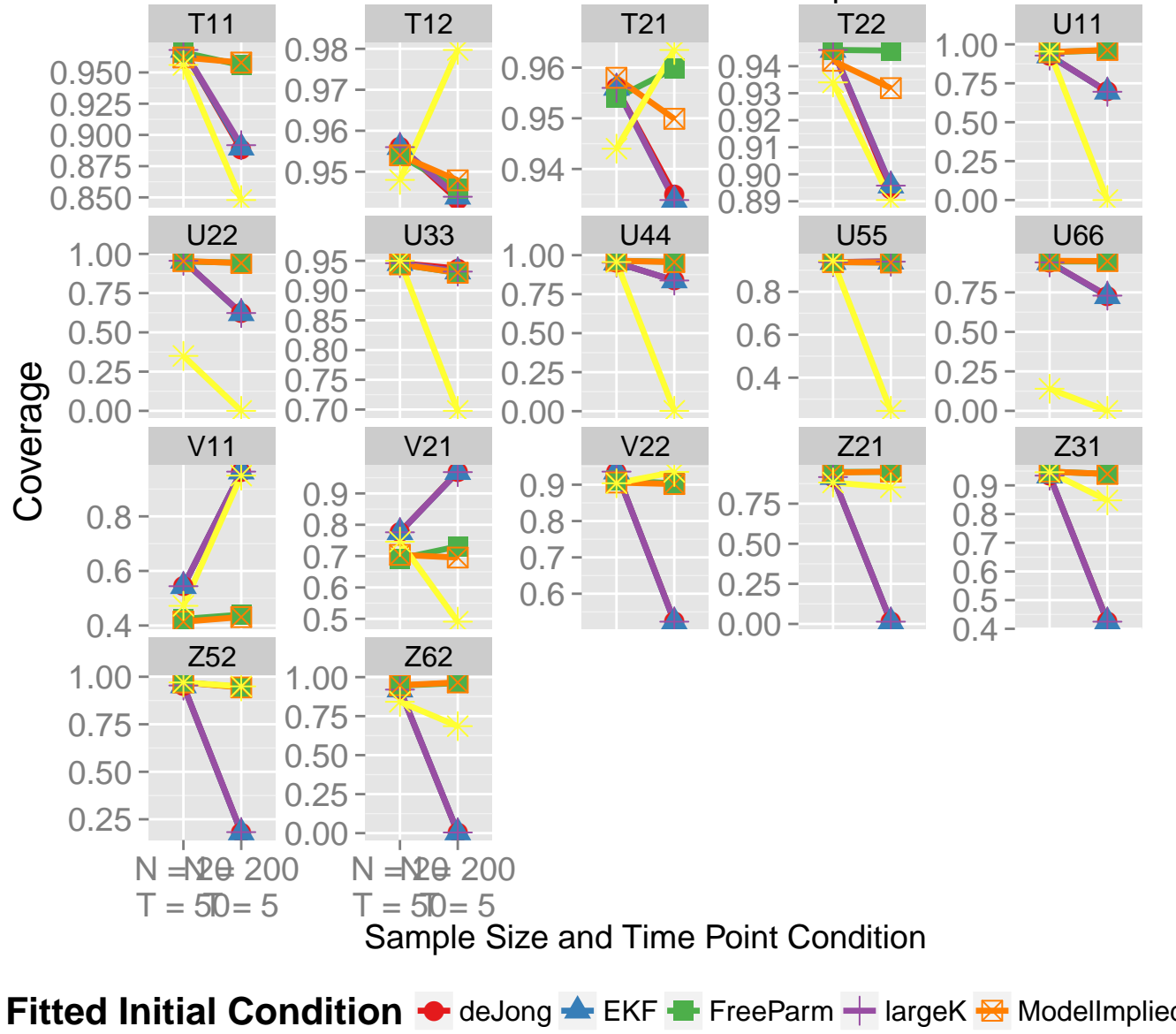
## True Initial Condition: FreeParm



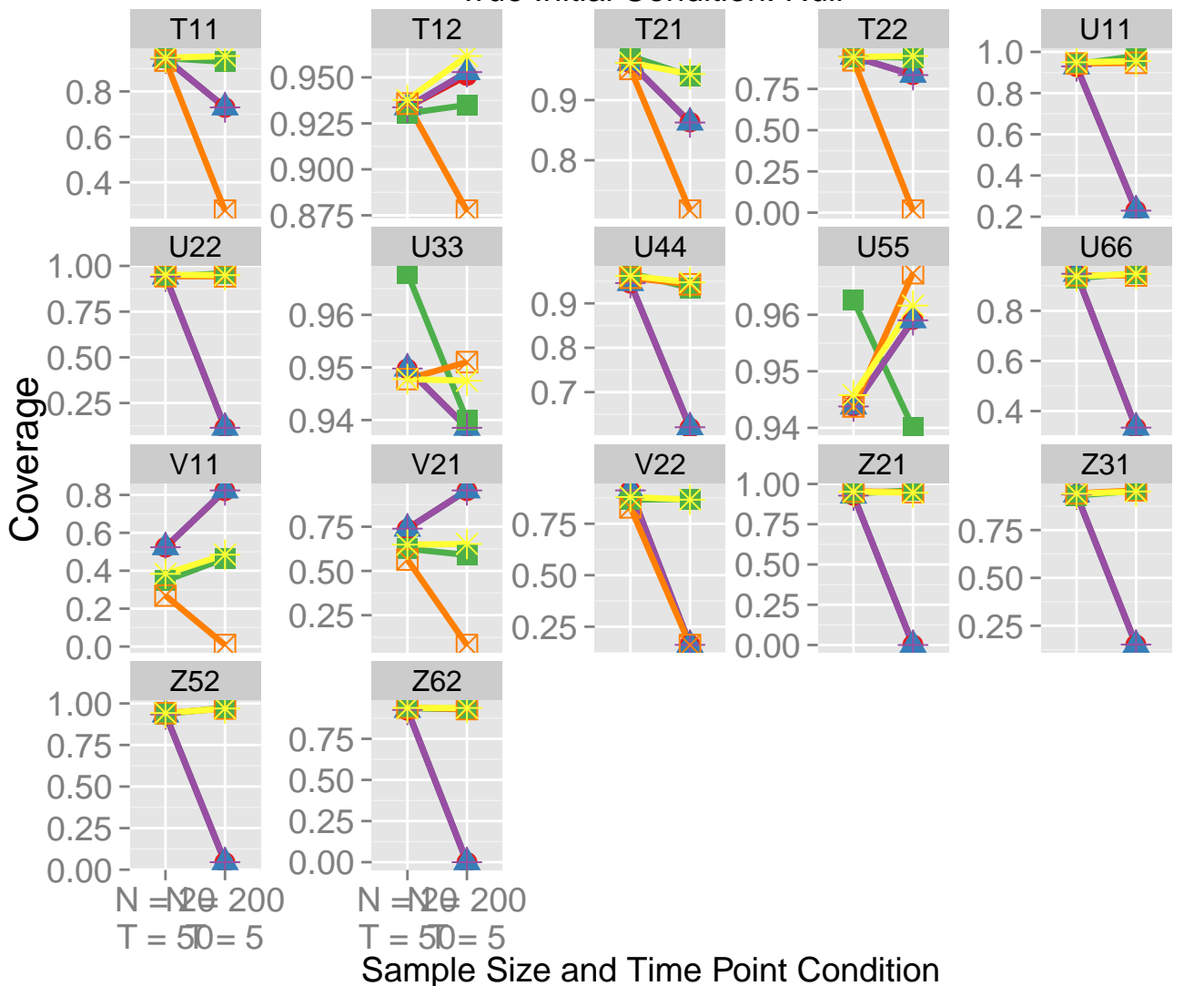
**Fitted Initial Condition** deJong EKF FreeParm largeK ModelImplied

# Stationary Model

## True Initial Condition: ModelImplied



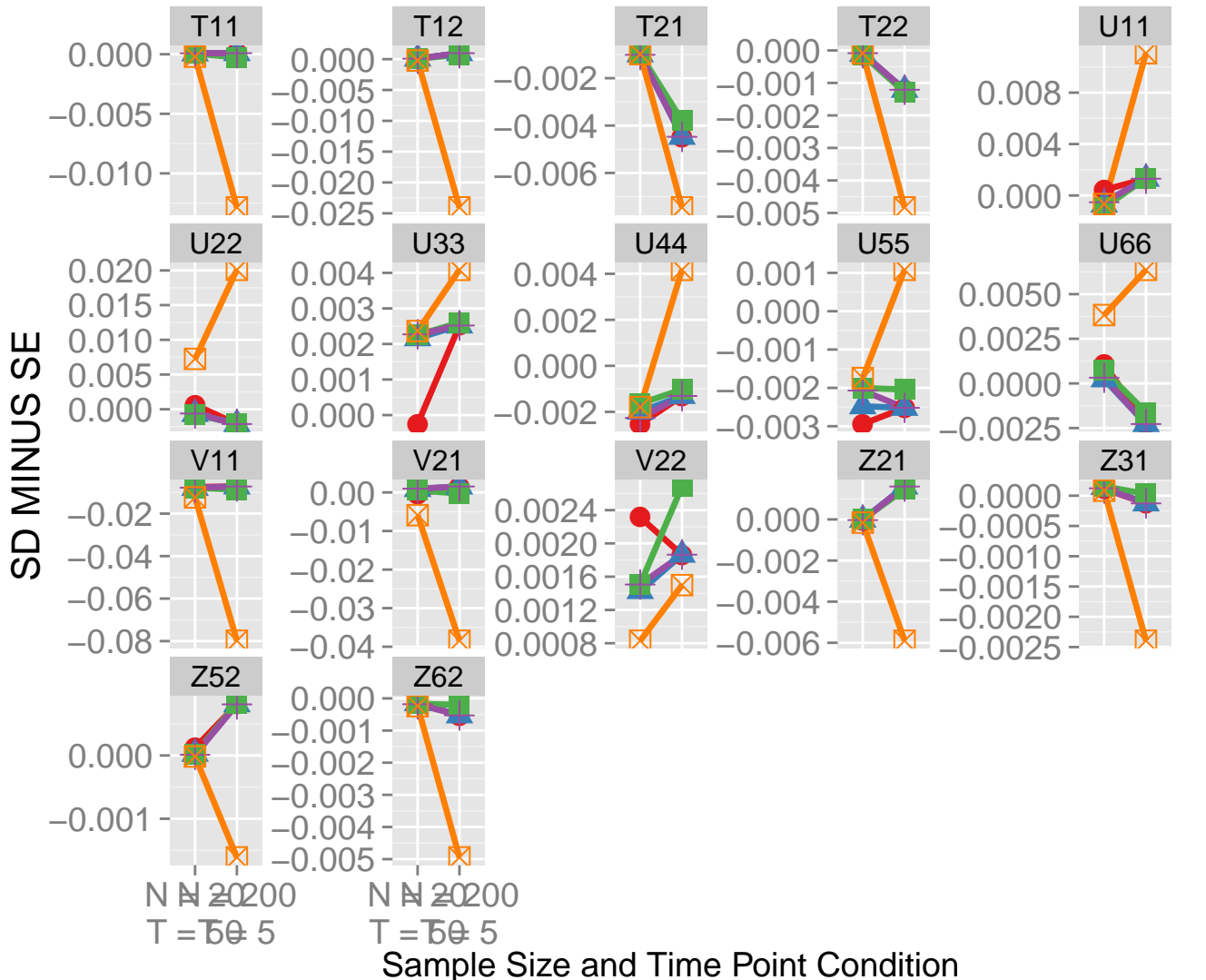
# Stationary Model True Initial Condition: Null



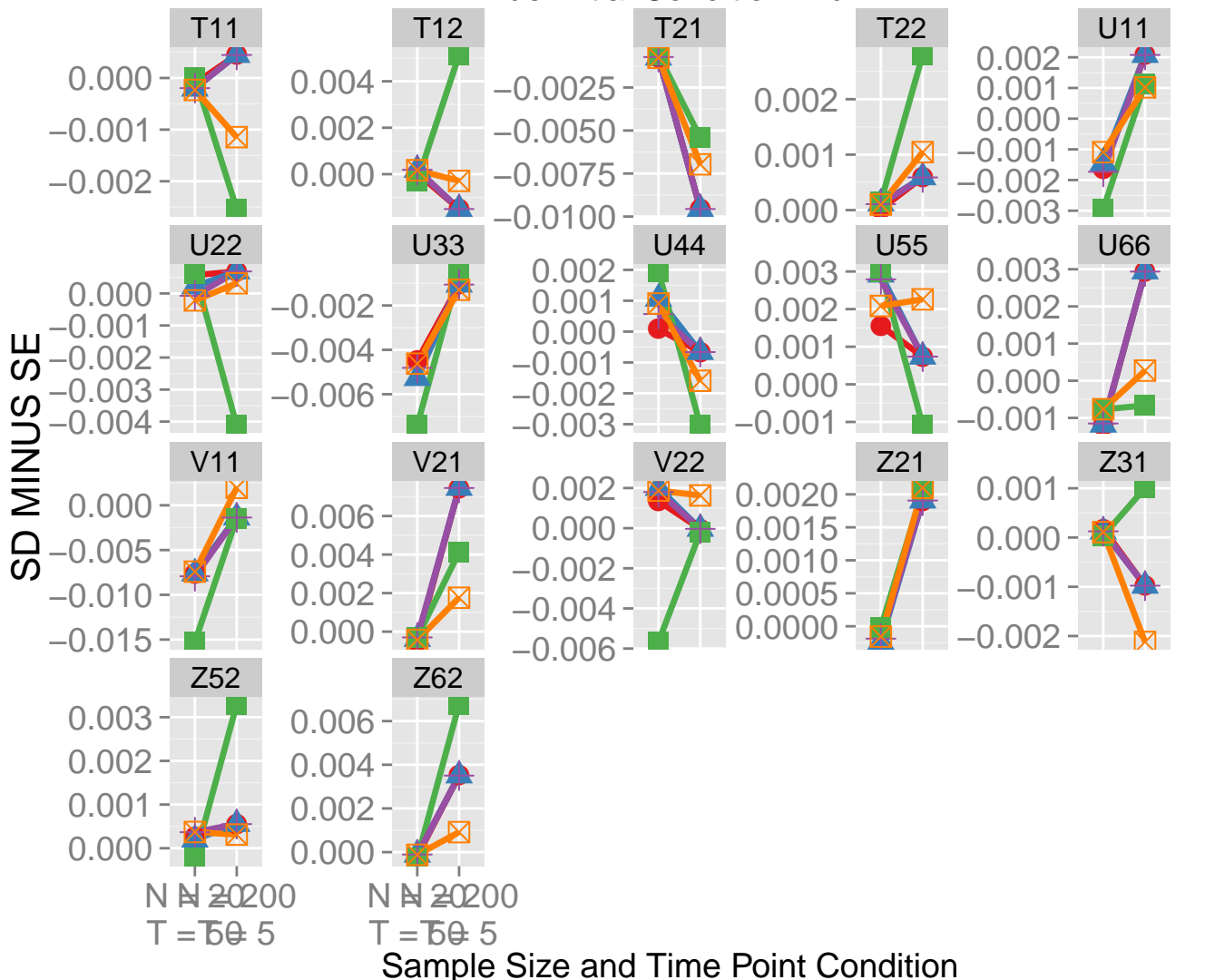




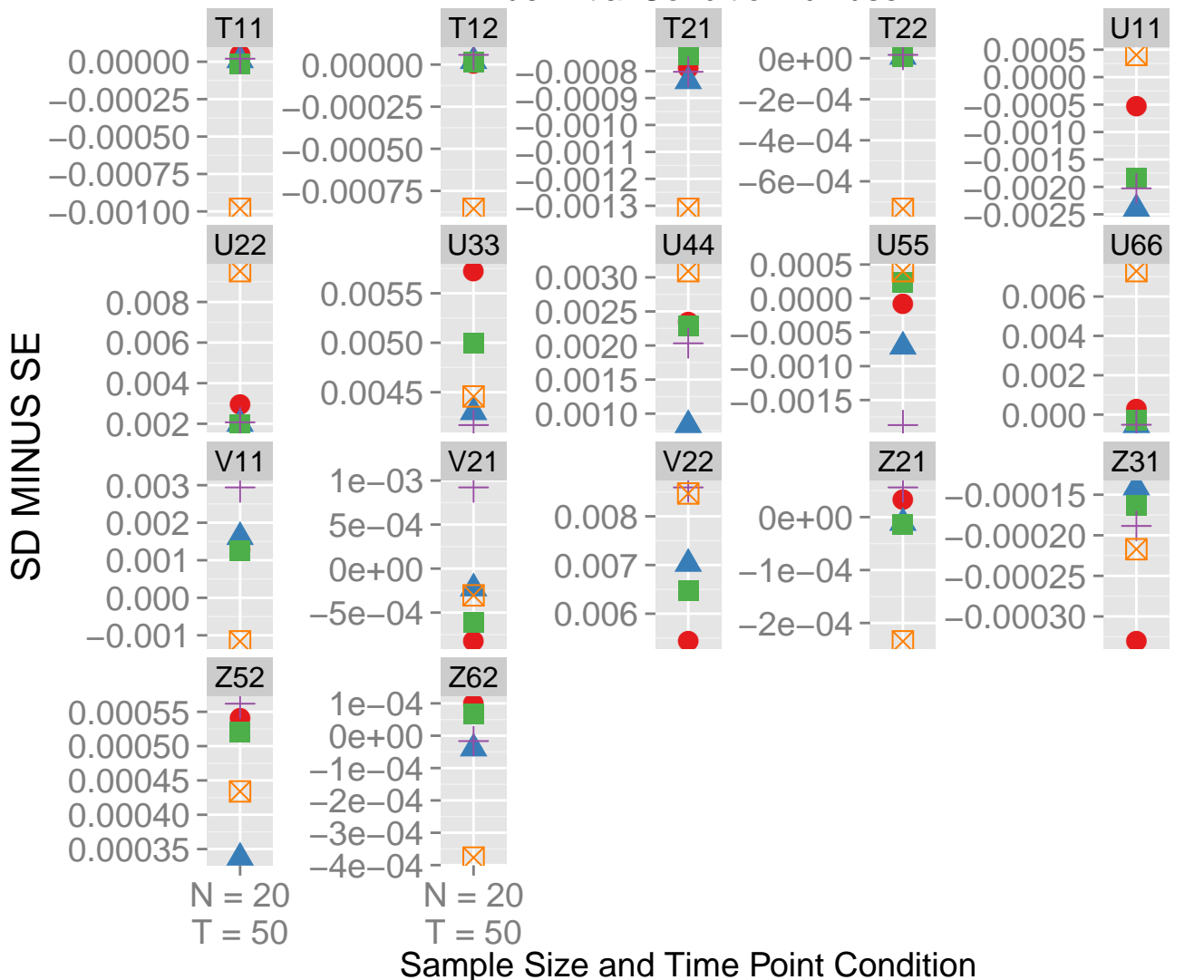
# Non-Stationary Model True Initial Condition: FreeParm



# Non-Stationary Model True Initial Condition: Null

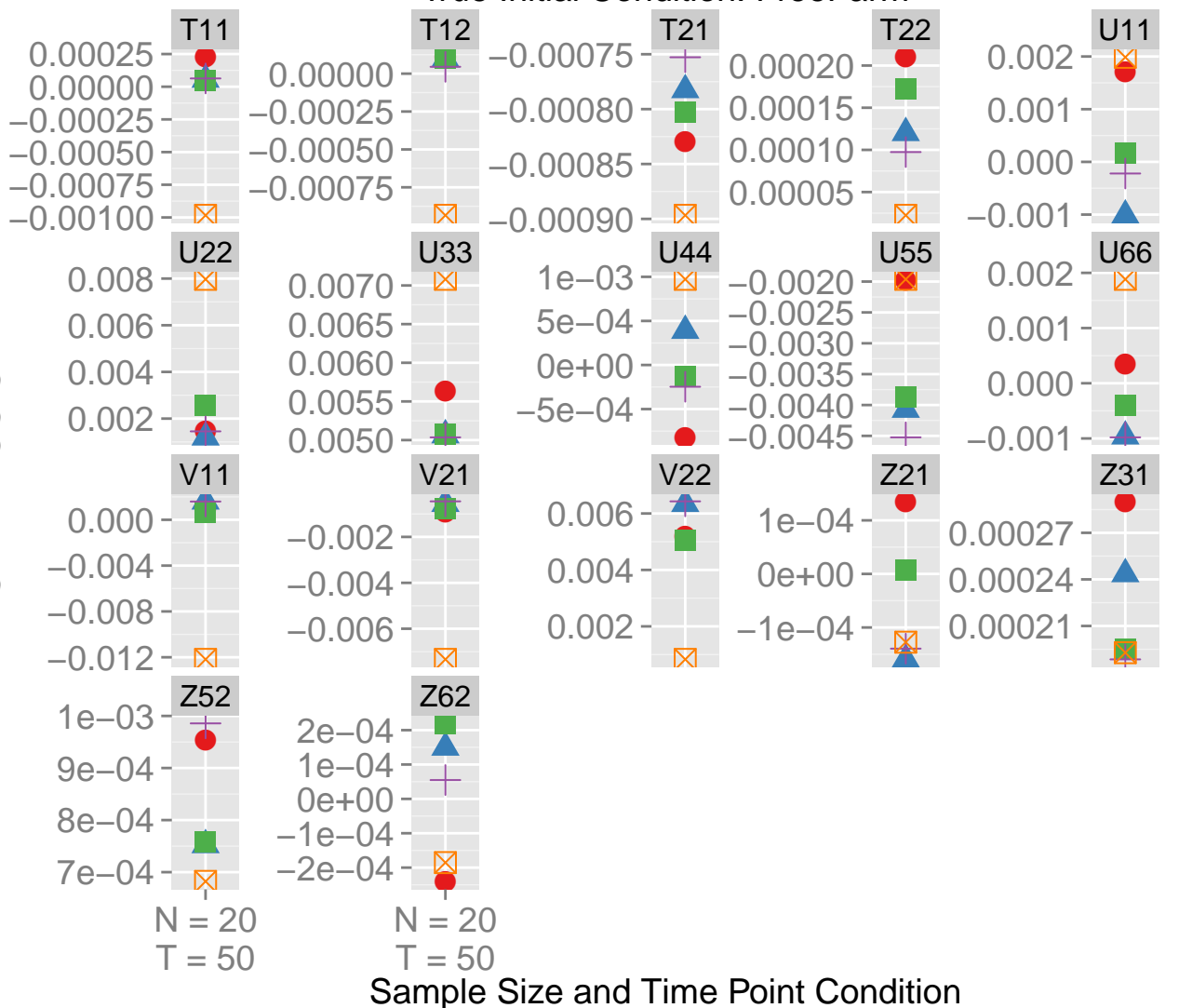


# Non-Stationary Mild Model True Initial Condition: diffuse



# Non-Stationary Mild Model True Initial Condition: FreeParm

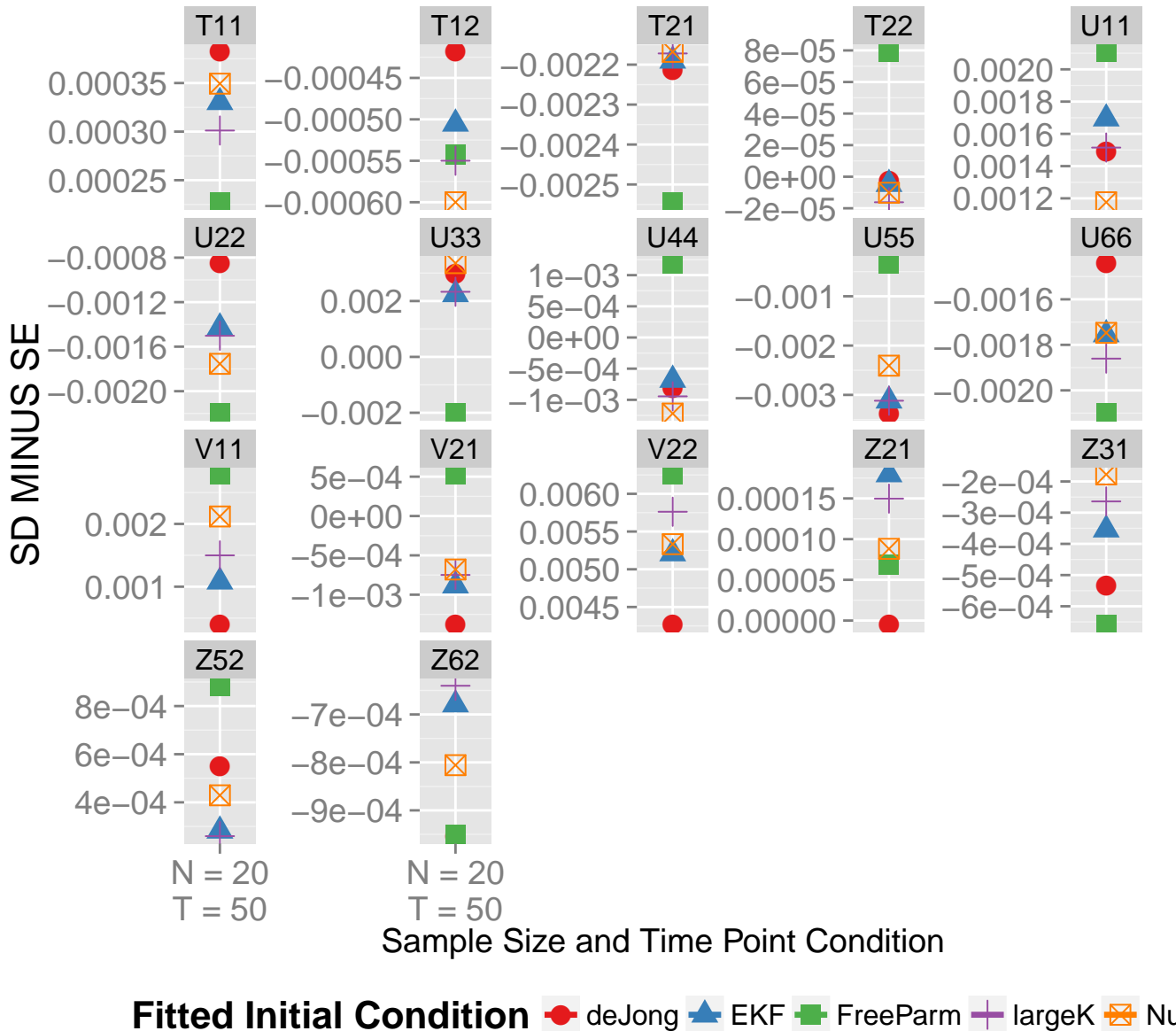
SD MINUS SE



**Fitted Initial Condition**

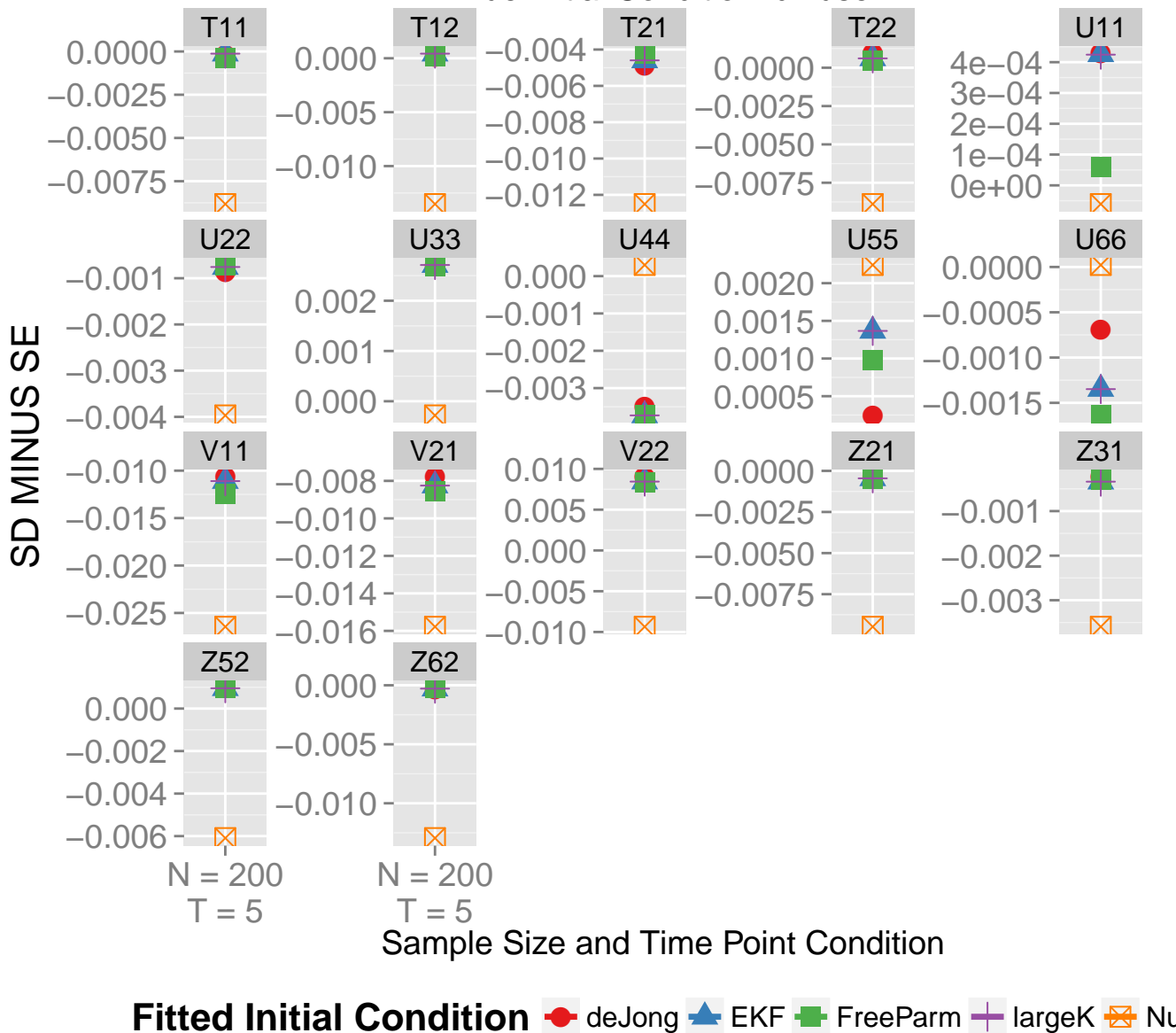
deJong EKF FreeParm largeK N

# Non-Stationary Mild Model True Initial Condition: Null



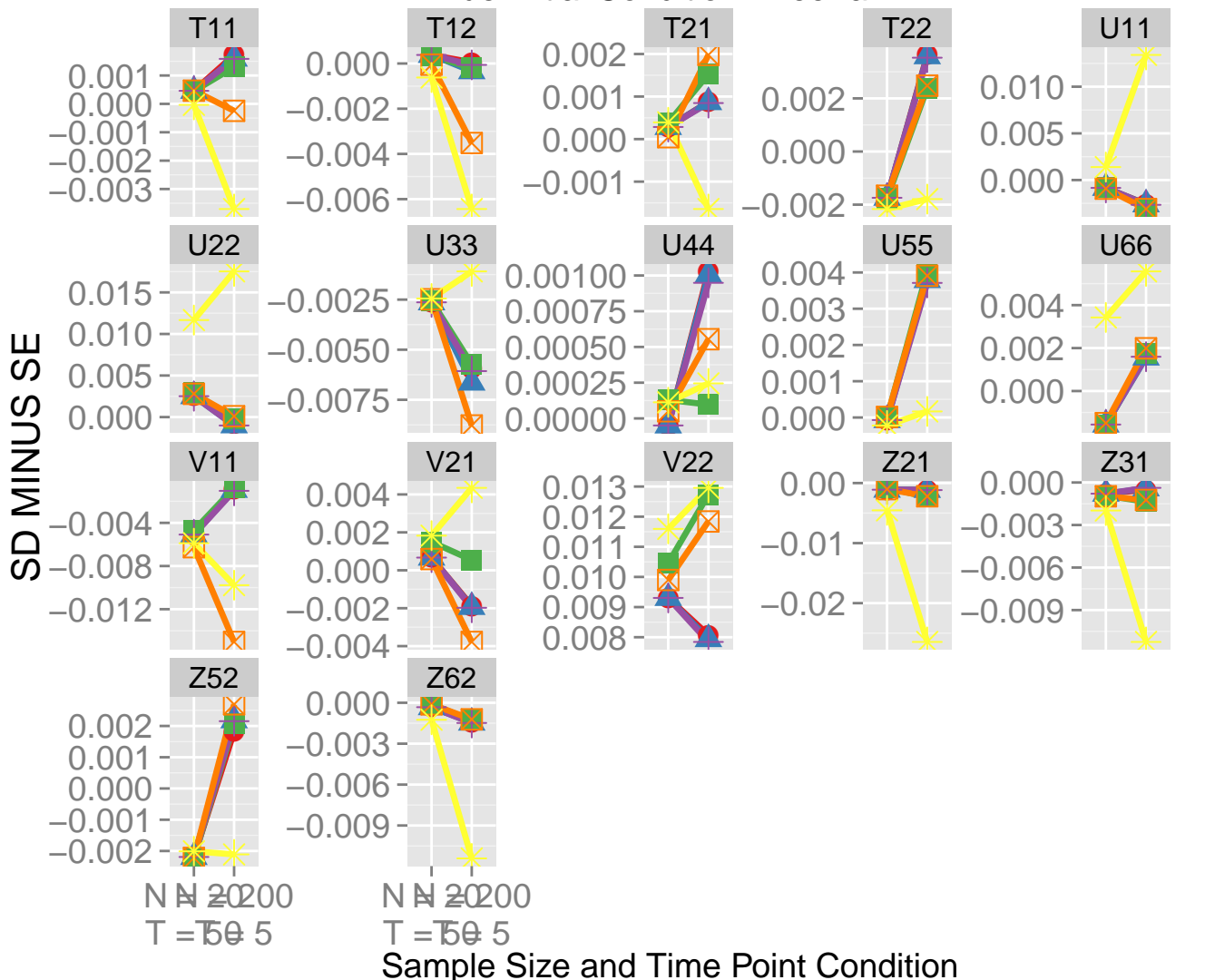
# Non-Stationary Moderate Model

True Initial Condition: diffuse



# Stationary Model

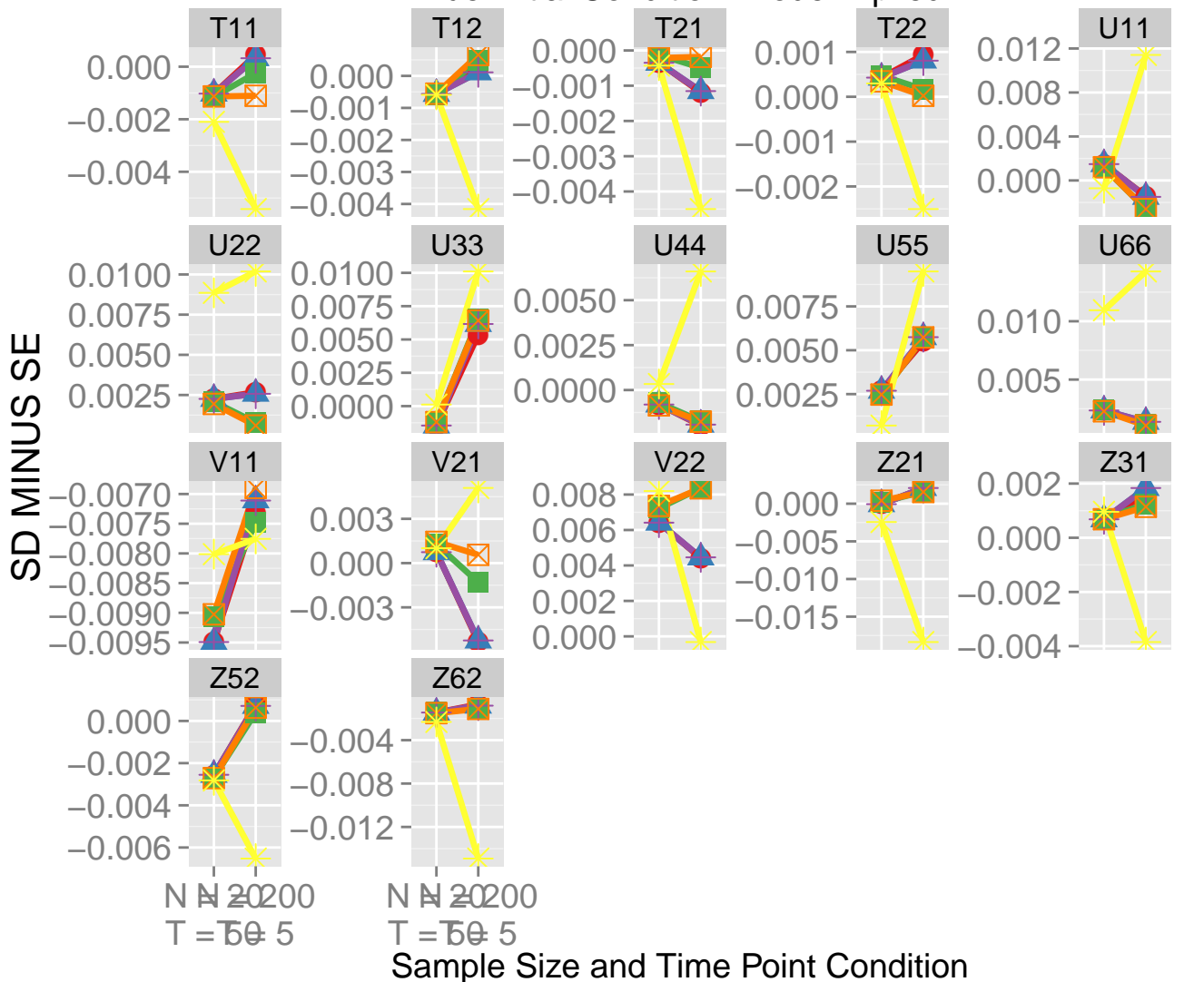
## True Initial Condition: FreeParm



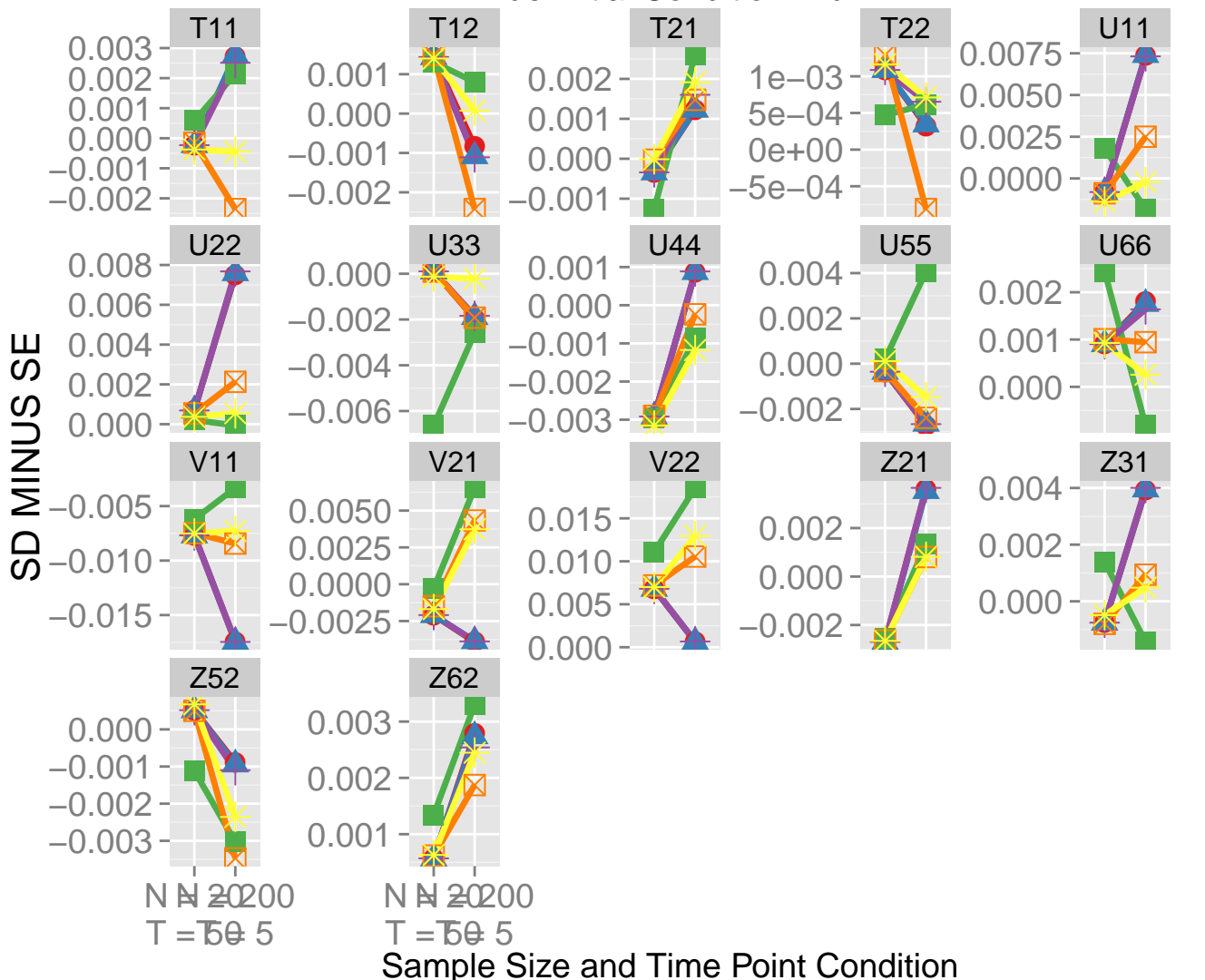


# Stationary Model

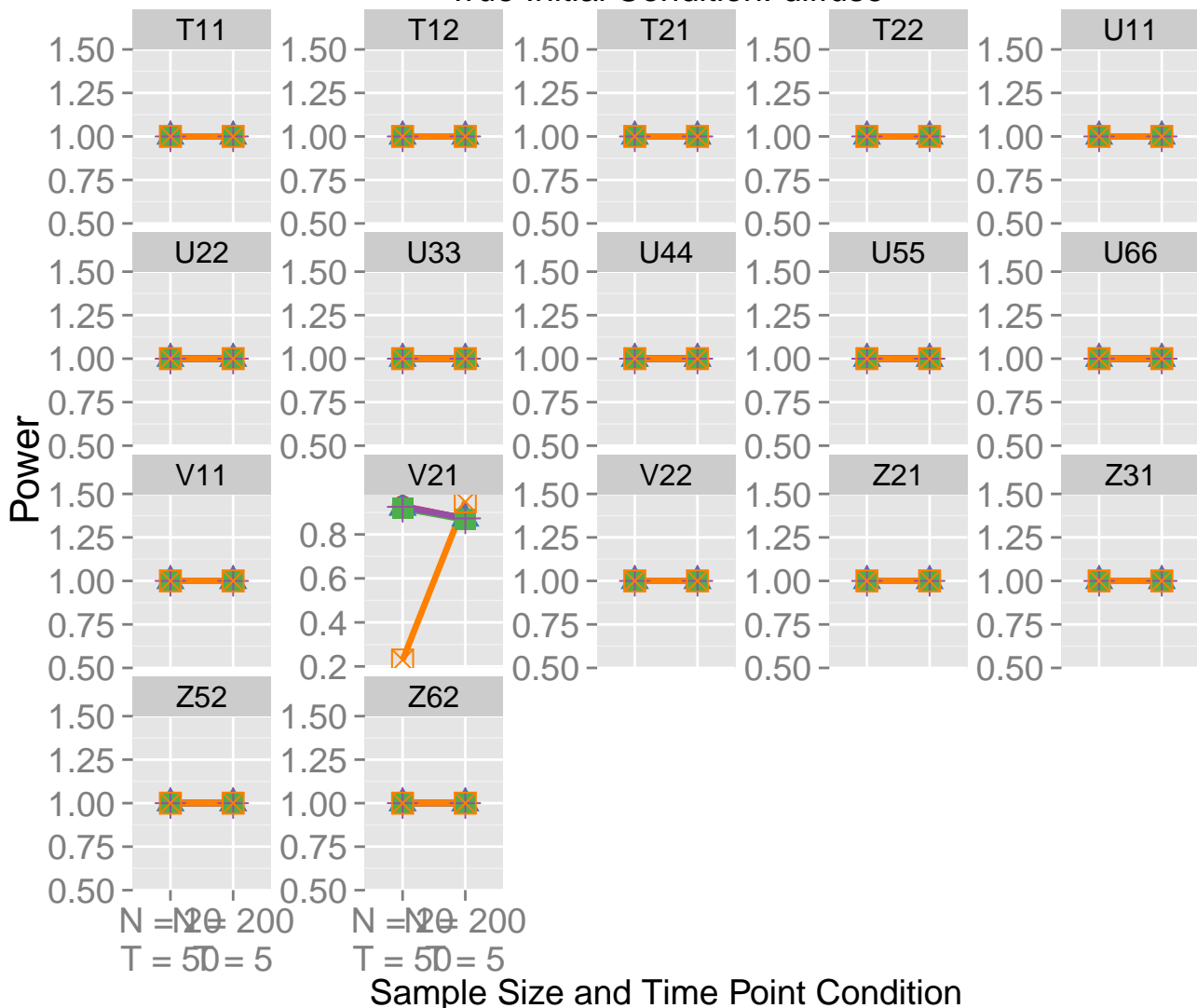
## True Initial Condition: ModelImplied



# Stationary Model True Initial Condition: Null

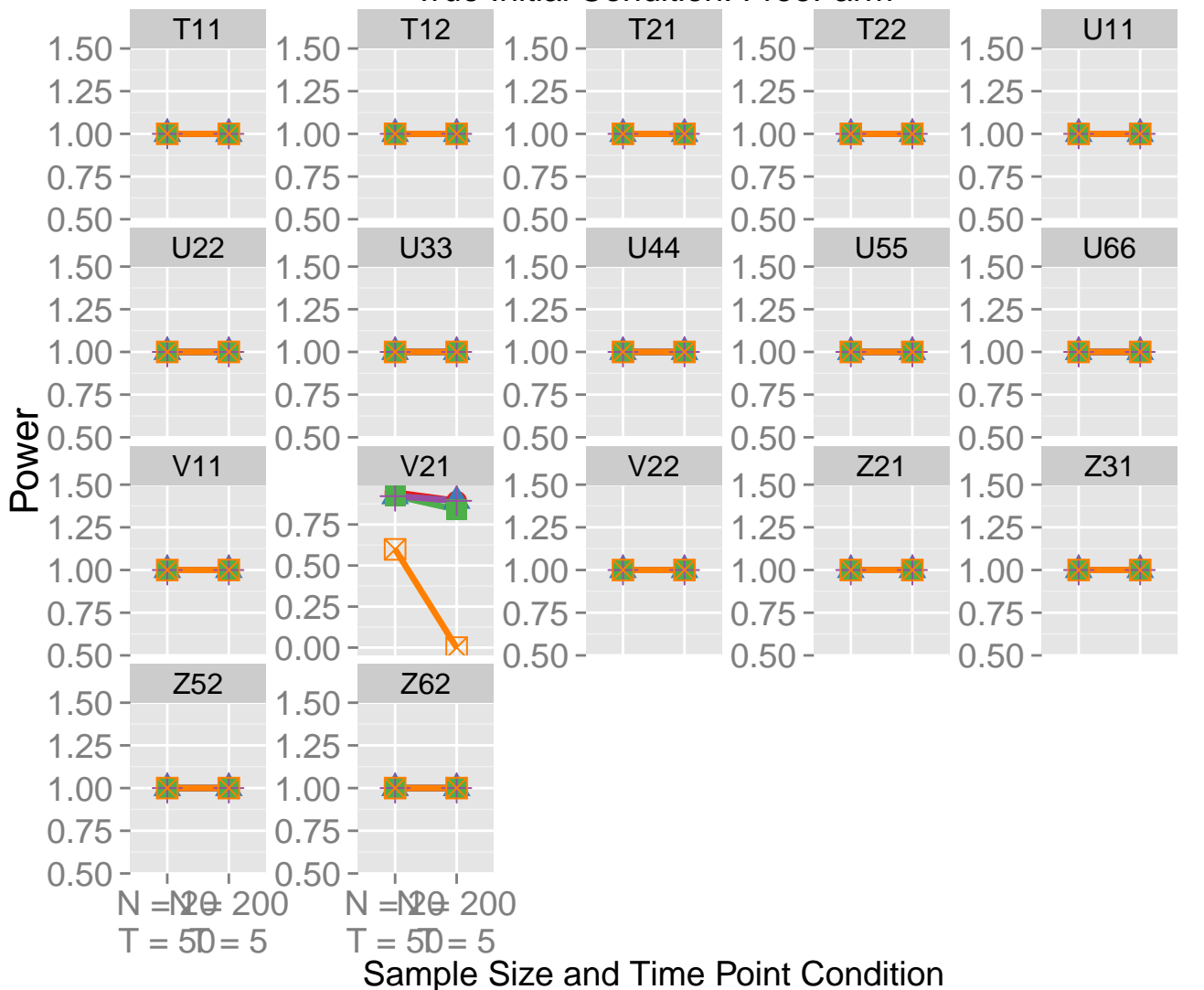


# Non-Stationary Model True Initial Condition: diffuse



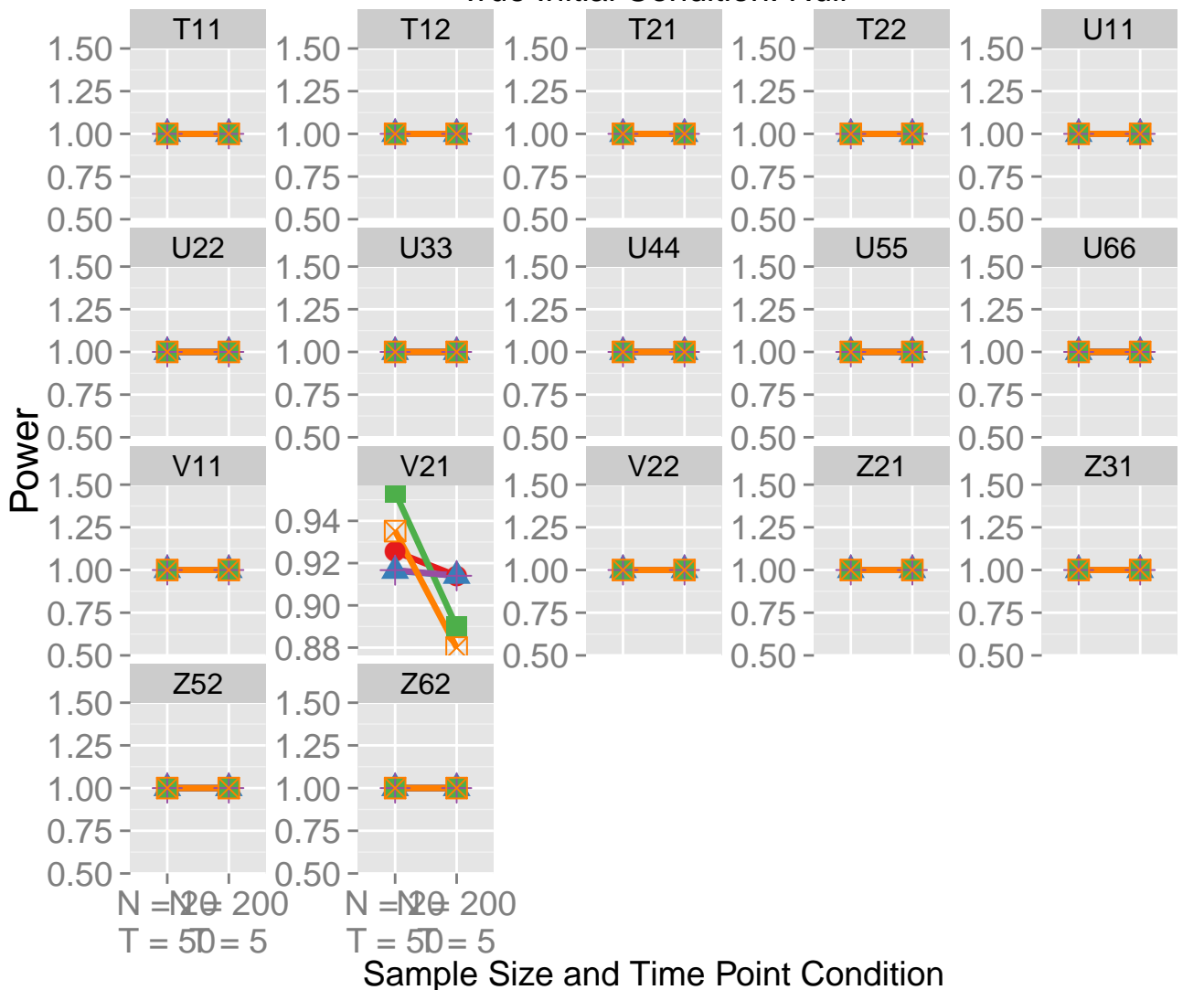
**Fitted Initial Condition** deJong EKF FreeParm largeK Null

# Non-Stationary Model True Initial Condition: FreeParm



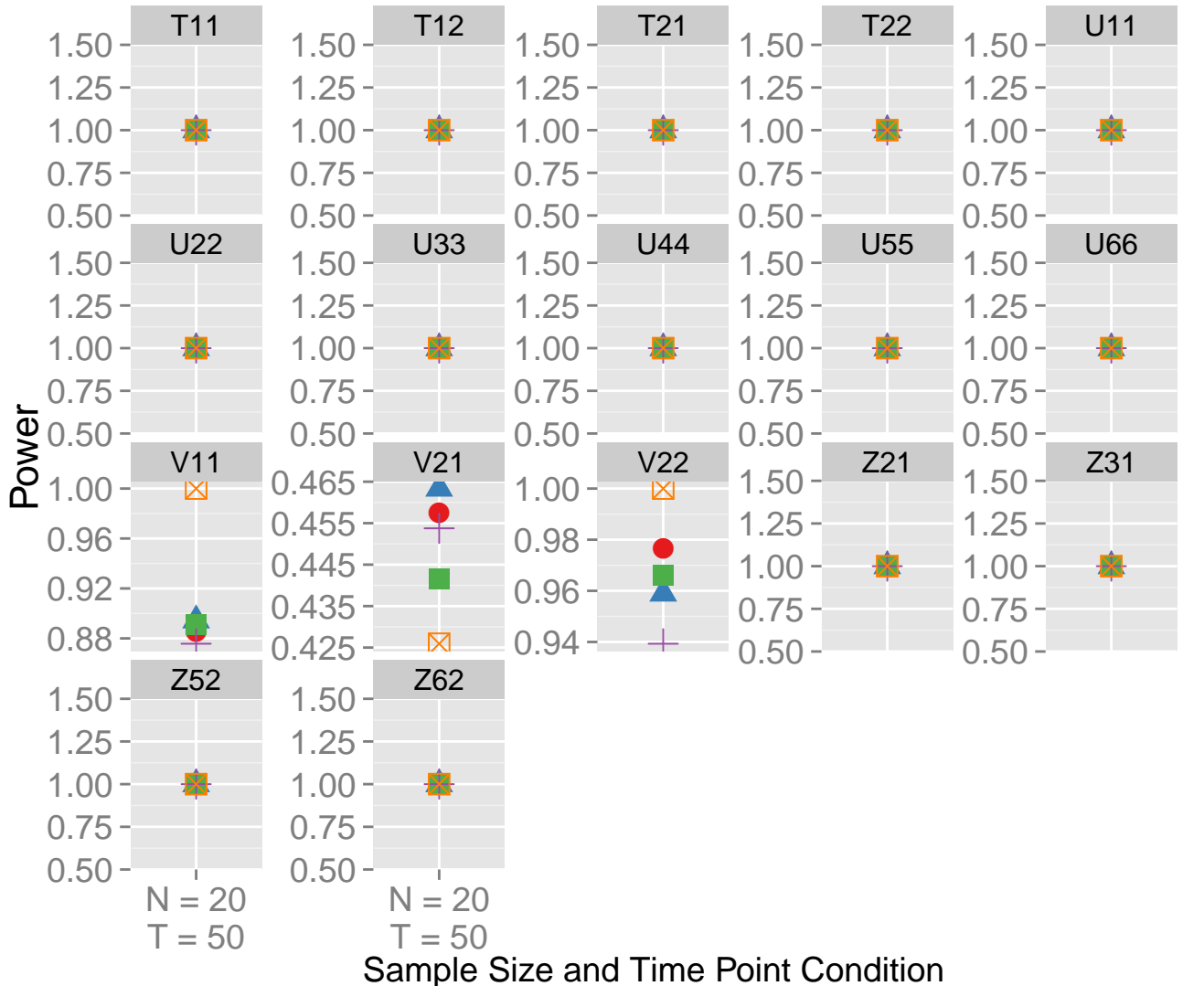
**Fitted Initial Condition** deJong EKF FreeParm largeK Null

# Non-Stationary Model True Initial Condition: Null

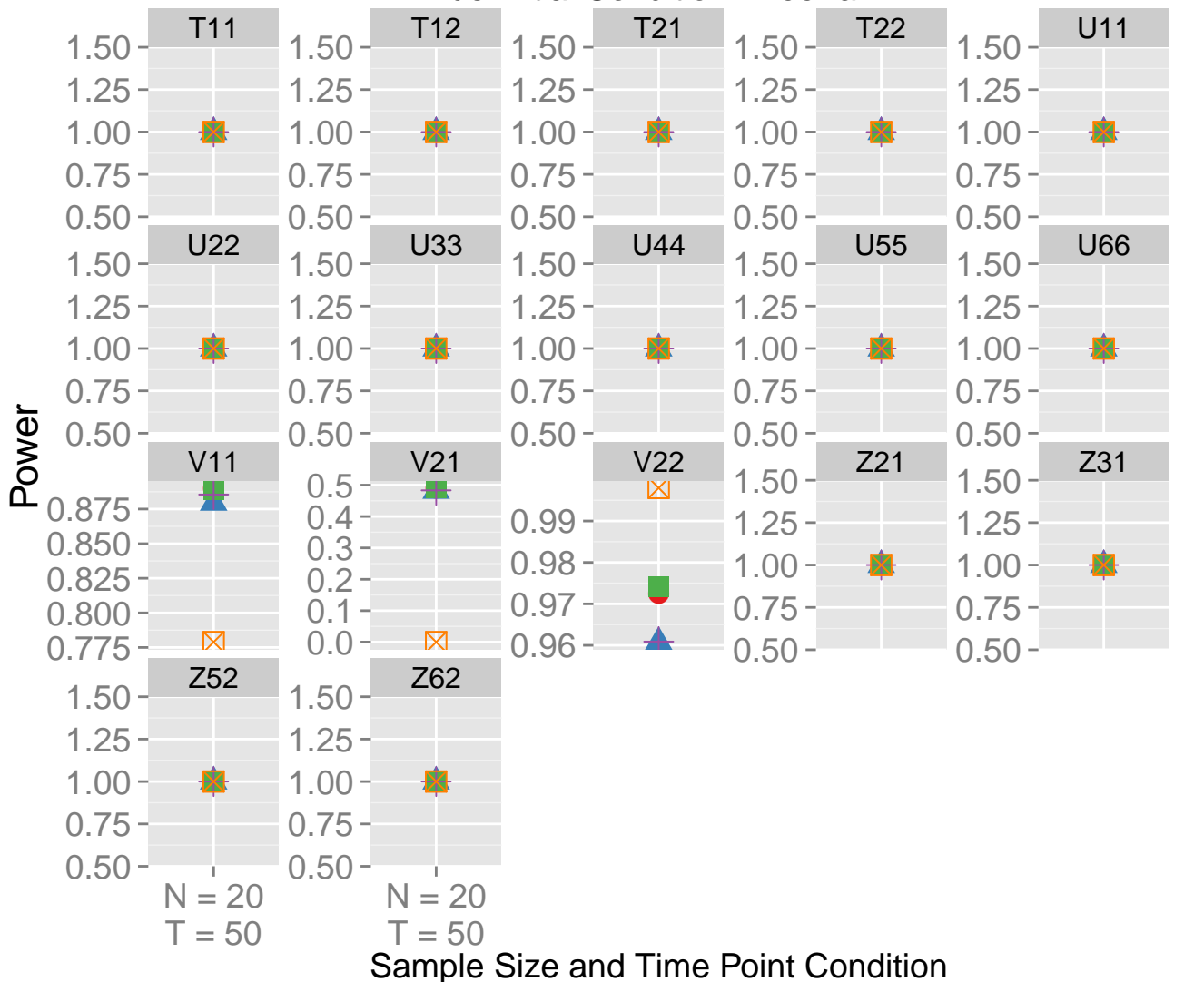


**Fitted Initial Condition** deJong EKF FreeParm largeK Null

# Non-Stationary Mild Model True Initial Condition: diffuse

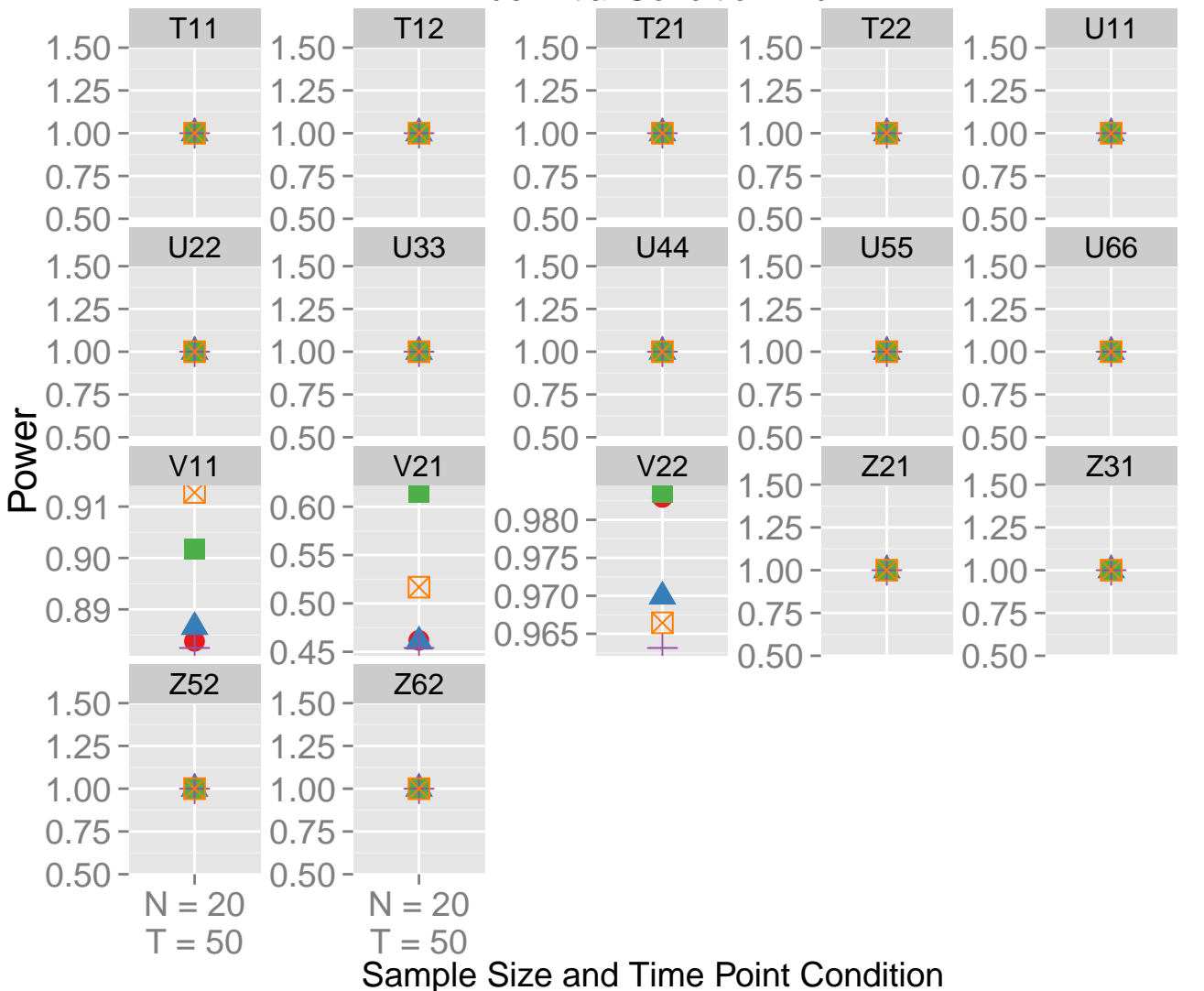


# Non-Stationary Mild Model True Initial Condition: FreeParm



# Non-Stationary Mild Model

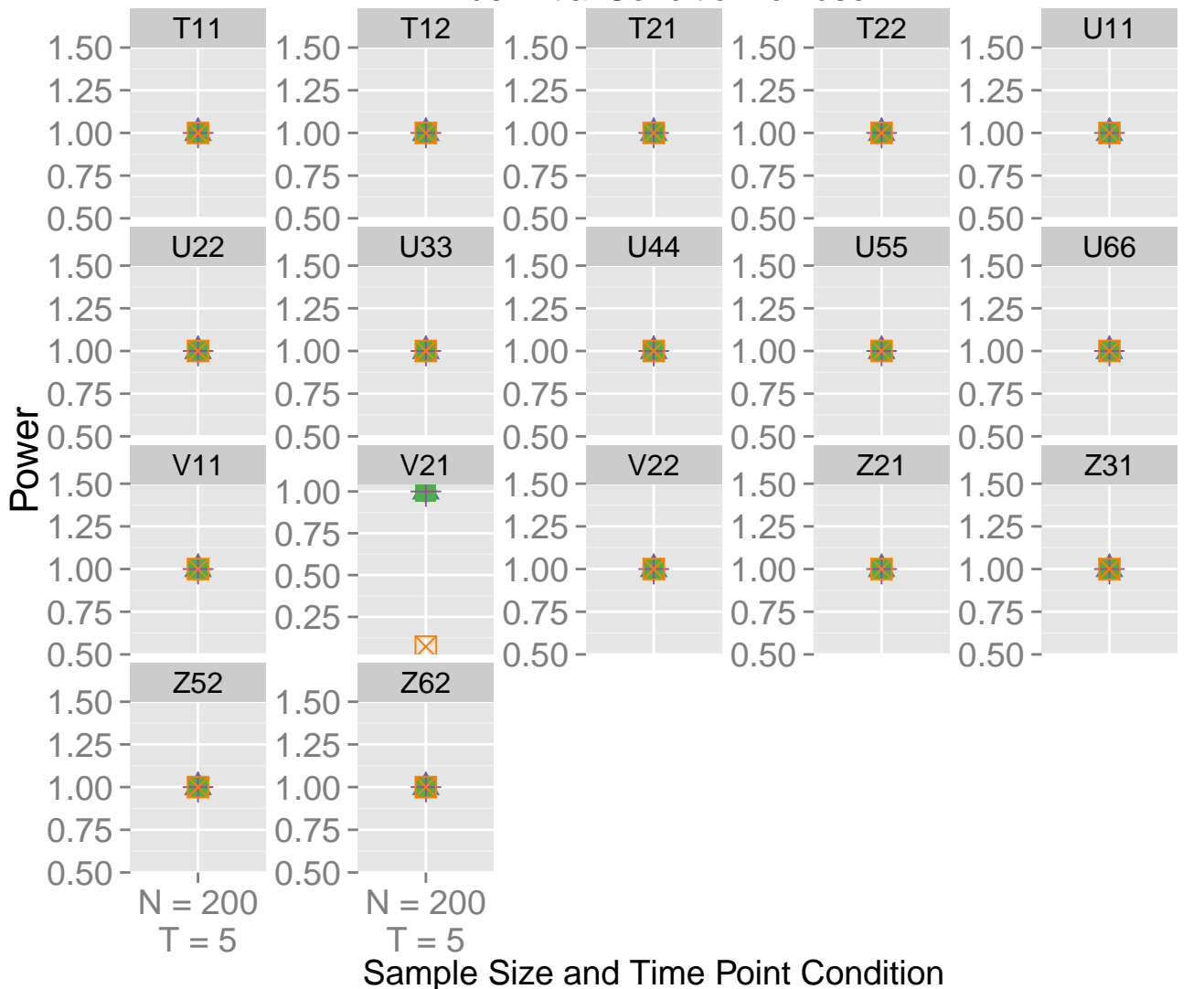
True Initial Condition: Null





# Non-Stationary Moderate Model

True Initial Condition: diffuse

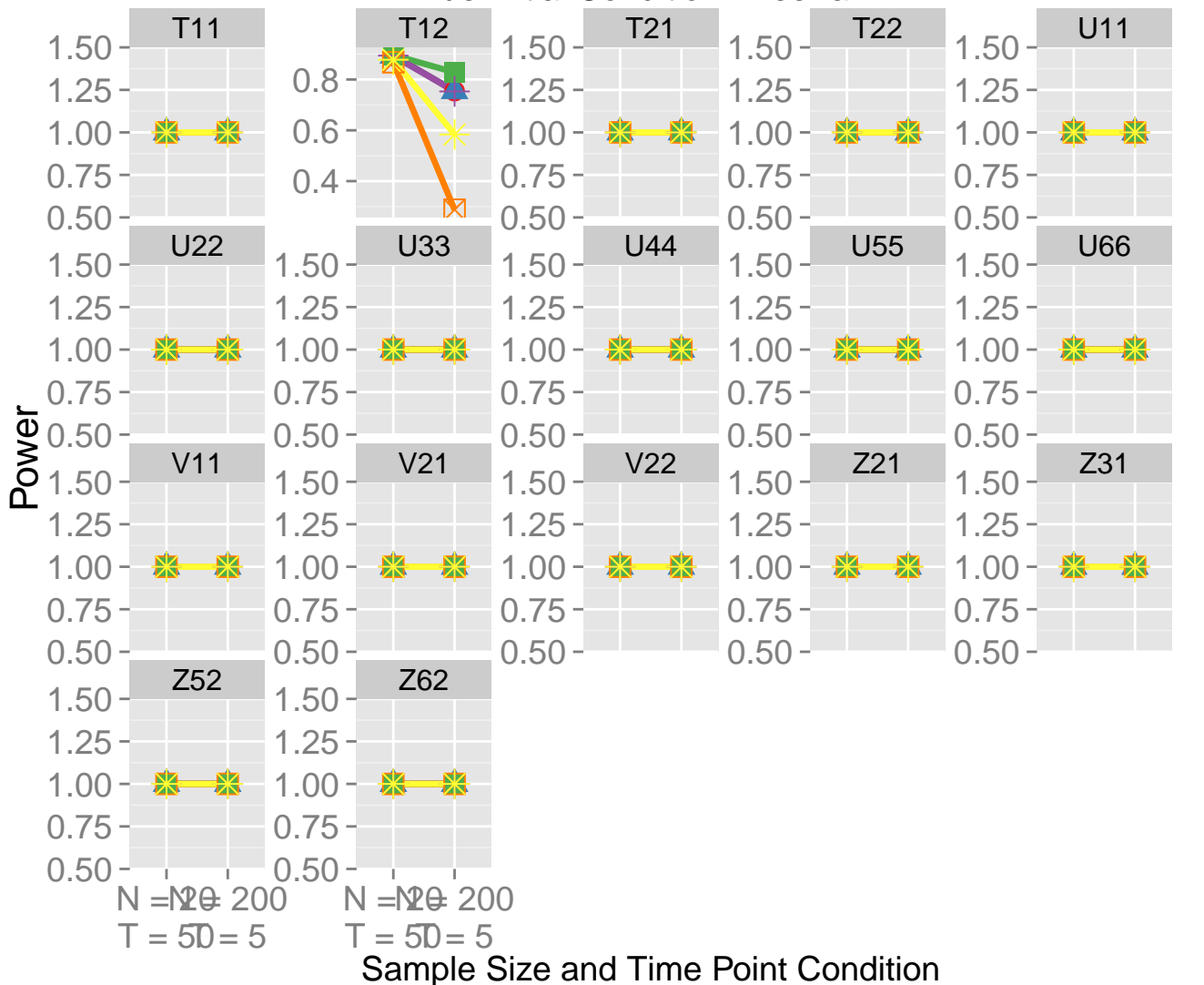


**Fitted Initial Condition**

deJong EKF FreeParm largeK Null

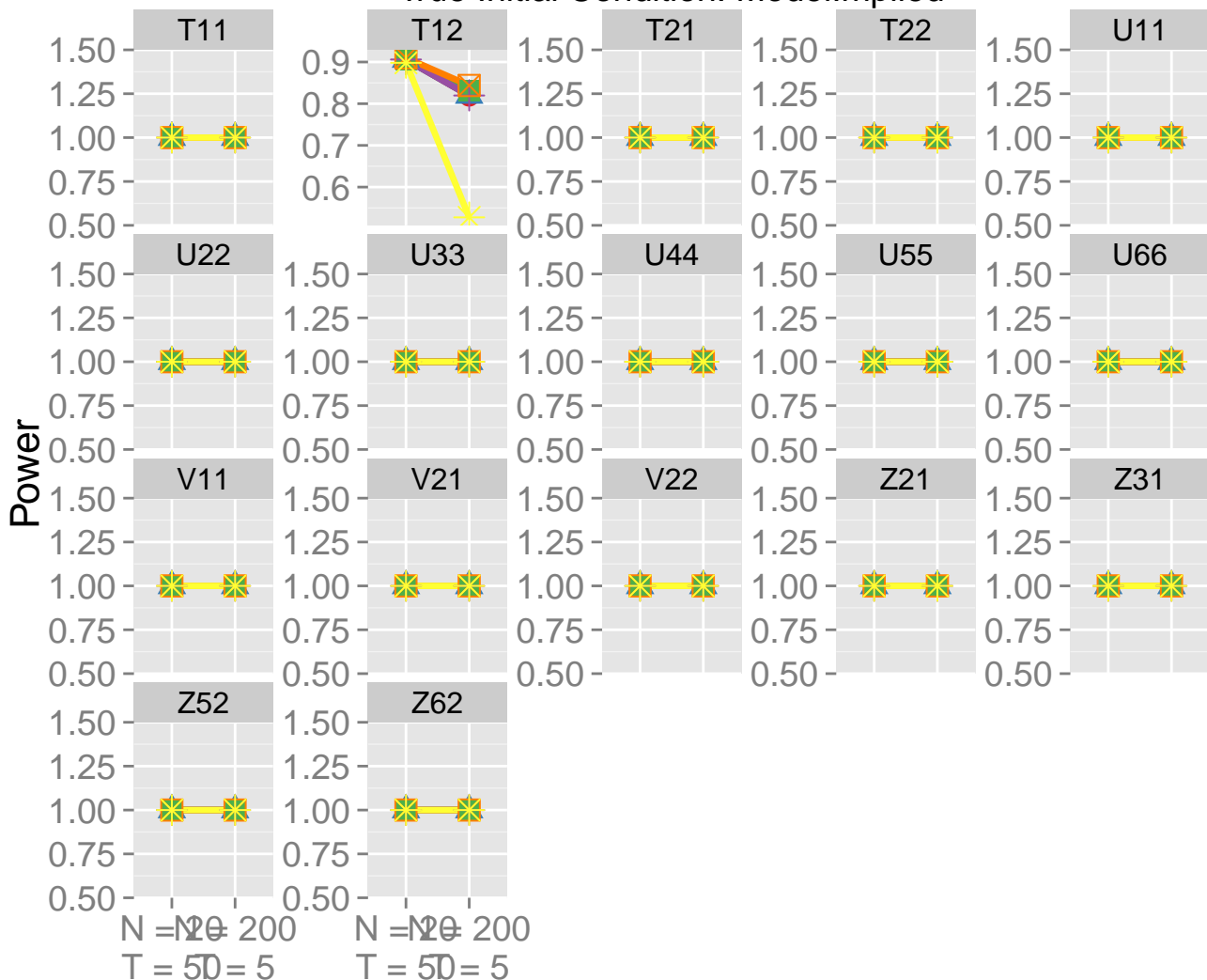
# Stationary Model

## True Initial Condition: FreeParm



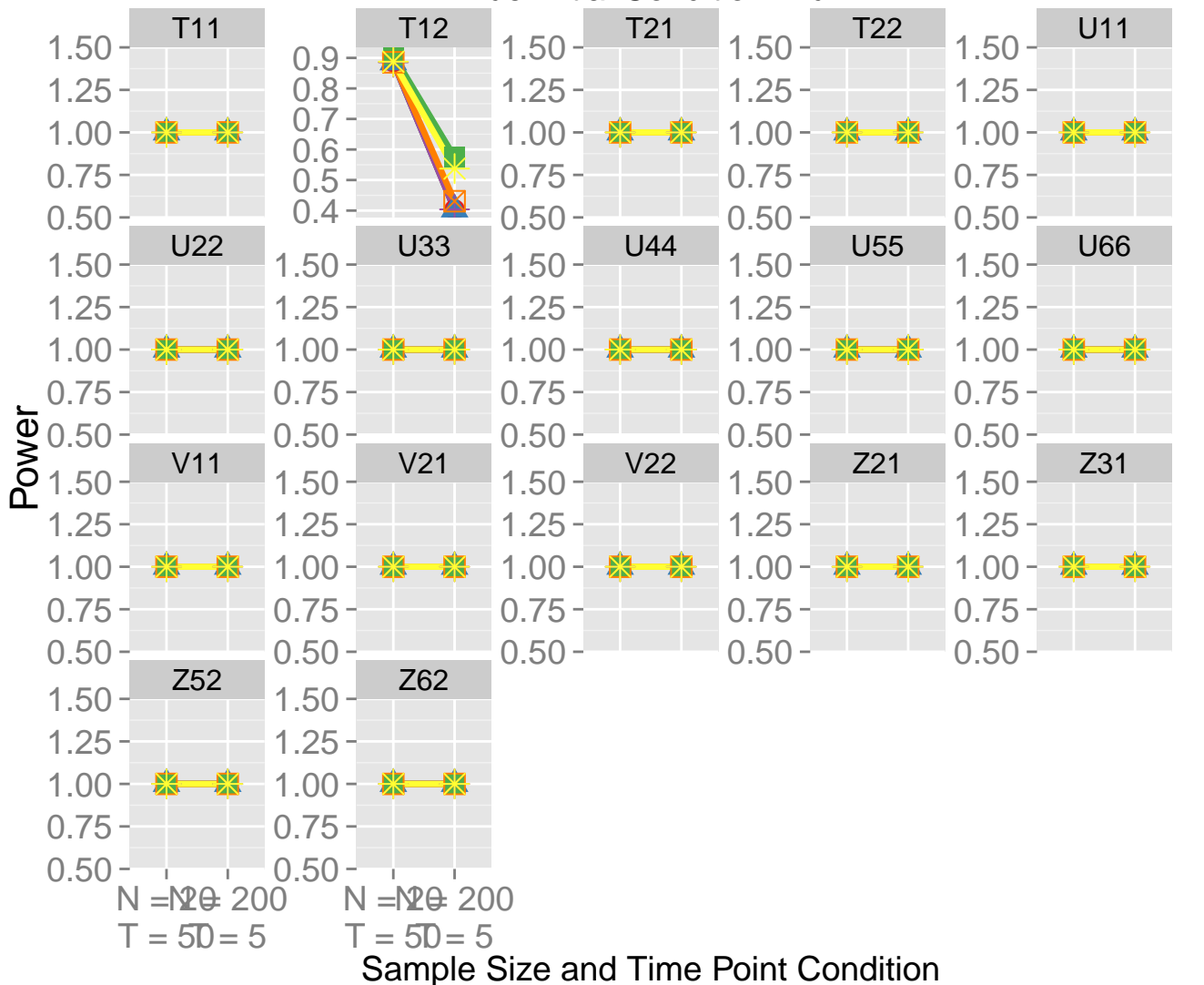
# Stationary Model

## True Initial Condition: ModelImplied



**Fitted Initial Condition** deJong EKF FreeParm largeK ModelImplied

# Stationary Model True Initial Condition: Null



**Fitted Initial Condition** deJong EKF FreeParm largeK ModelImplied