

Mini-projet d'analyse numérique (MAP431)

Calcul de fréquences propres de vibration

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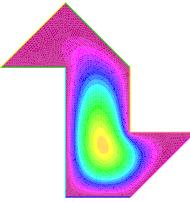
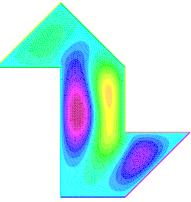
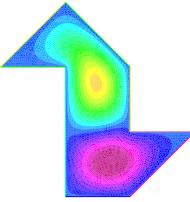
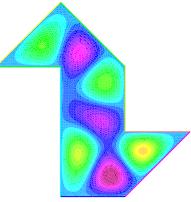
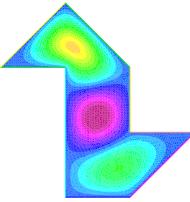
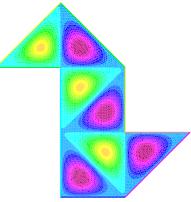
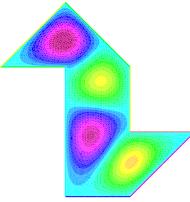
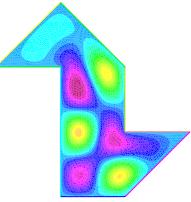
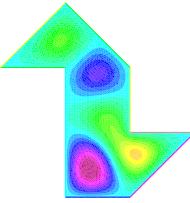
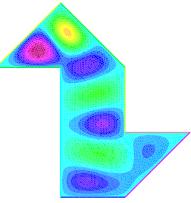
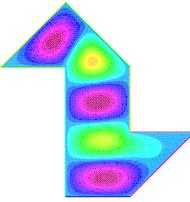
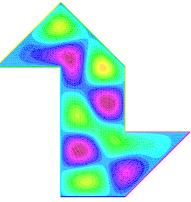
1 Code source

```
1  /* Mini-projet d'analyse numérique (MAP431)
2   * Calcul de fréquences propres de vibration
3   * Dimitri Lozeve, Philippe Cherabier
4   */
5
6  load "Element_P3";
7
8  // Mesh generation
9
10 // number of vertices for each edge
11 int n = 10;
12 /*
13 int n;
14 cout << "Number of vertices = ? ";
15 cin >> n;
16 */
17
18 /**
19 // Cocotte
20 border c01(t=0,1){ x=t; y=2+t; }
21 border c02(t=0,1){ x=t; y=2; }
22 border c03(t=0,1){ x=1; y=2*t; }
23 border c04(t=0,1){ x=1+t; y=0; }
24 border c05(t=0,1){ x=2+t; y=t; }
25 border c06(t=0,1){ x=2+t; y=1; }
26 border c07(t=0,1){ x=2; y=1+t; }
27 border c08(t=0,1){ x=2-t; y=2+t; }
28
29 plot(c01(-n)+c02(n)+c03(-2*n)+c04(n)+c05(n)+c06(-n)+c07(n)+c08(n),wait=1);
30 mesh Th = buildmesh(c01(-n)+c02(n)+c03(-2*n)+c04(n)+c05(n)+c06(-n)+c07(n)+c08(n));
31 /**
32 /*
33 // Flèche
34 border c01(t=0,1){ x=0; y=2+t; }
```

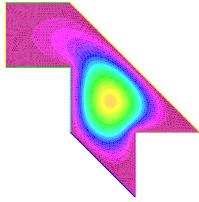
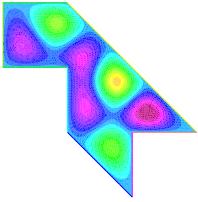
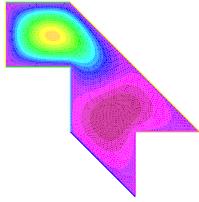
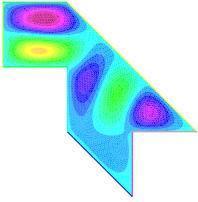
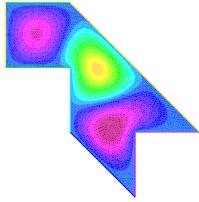
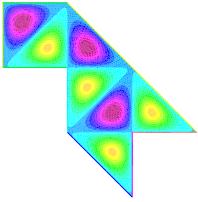
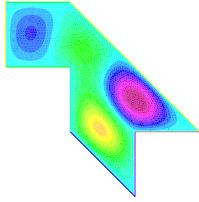
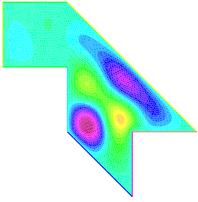
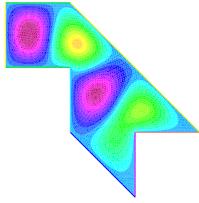
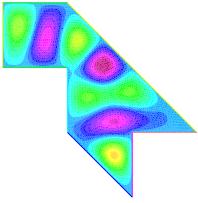
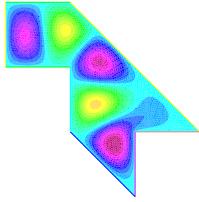
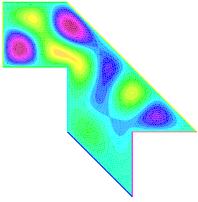
1. CODE SOURCE

```
35 border c02(t=0,1){ x=t; y=2; }
36 border c03(t=0,1){ x=1; y=1+t; }
37 border c04(t=0,1){ x=1+t; y=1-t; }
38 border c05(t=0,1){ x=2; y=t; }
39 border c06(t=0,1){ x=2+t; y=1; }
40 border c07(t=0,1){ x=1+2*t; y=3-2*t; }
41 border c08(t=0,1){ x=t; y=3; }
42
43 plot(c01(-n)+c02(n)+c03(-n)+c04(n)+c05(n)+c06(n)+c07(-2*n)+c08(-n),wait=1);
44 mesh Th = buildmesh(c01(-n)+c02(n)+c03(-n)+c04(n)+c05(n)+c06(n)+c07(-2*n)+c08(-n));
45 /**
46
47 plot(Th,wait=1,ps="mesh.eps");
48
49 // Variational space definition
50 fespace Vh(Th,P3);
51
52 // Variational problem definition
53 varf a(u,v) = int2d(Th)(dx(u)*dx(v) + dy(u)*dy(v))
54     + on(c01,c02,c03,c04,c05,c06,c07,c08,u=0);
55
56 varf b(u,v) = int2d(Th)(u*v);
57
58 // Matrices computation
59 matrix A = a(Vh,Vh,solver=sparsesolver);
60 matrix B = b(Vh,Vh,solver=sparsesolver);
61
62 // Number of eigenvalues desired
63 int nev = 12;
64 // Arrays to keep eigenvalues and eigenvectors
65 real[int] lambda(nev);
66 Vh[int] u(nev);
67
68 // Resolution of the problem
69 int k = EigenValue(A,B,sym=true,sigma=0,
70                     value=lambda,vector=u,tol=1.e-10,ncv=0,maxit=0);
71
72 /*
73 // Saving eigenvalues
74 {
75     ofstream f("eigenvalues.txt",append);
76     for (int i=0; i<nev; i++) {
77         f << lambda[i] << "\t";
78     }
79 }
80 */
81
82 // Plotting eigenvectors
83 for (int i=0; i<nev; i++) {
84     plot(u[i],wait=1,fill=1,ps="cocotte"+(i+1)+".eps");
85     //      cmm="Eigenvalue: "+lambda(i));
86 }
```

2 Résultats pour la cocotte

| Valeur propre | Mode propre | Valeur propre | Mode propre |
|---------------|---|---------------|---|
| 10.1521 |  | 42.3883 |  |
| 14.6223 |  | 46.1657 |  |
| 20.7028 |  | 49.348 |  |
| 26.1503 |  | 52.2155 |  |
| 28.9929 |  | 57.2557 |  |
| 36.8374 |  | 63.4864 |  |

3 Résultats pour la flèche

| Valeur propre | Mode propre | Valeur propre | Mode propre |
|---------------|---|---------------|---|
| 10.1520 |  | 42.3882 |  |
| 14.6223 |  | 46.1657 |  |
| 20.7027 |  | 49.3480 |  |
| 26.1503 |  | 52.2154 |  |
| 28.9928 |  | 57.2557 |  |
| 36.8374 |  | 63.4863 |  |

4 Convergence des valeurs propres

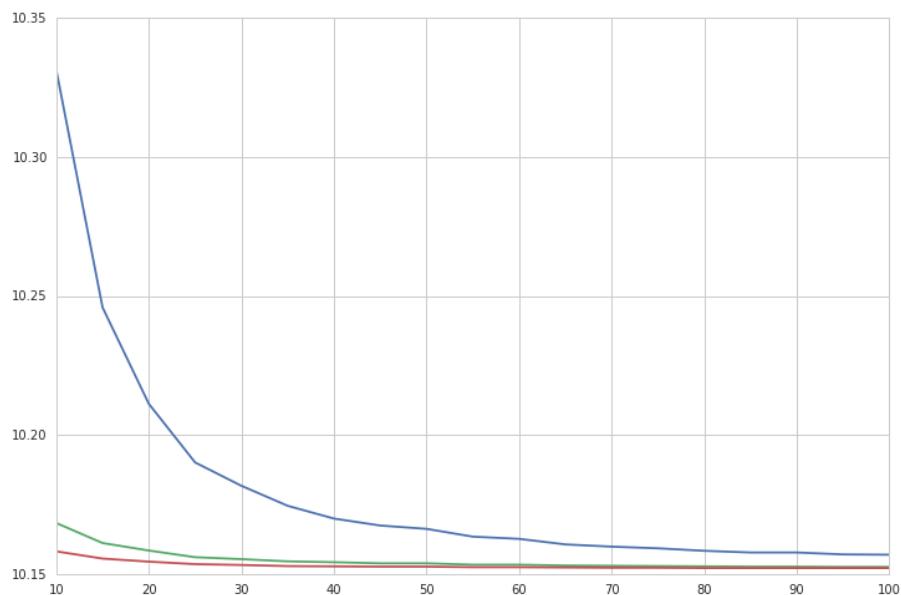


FIG. 1 : Convergence de la première valeur propre de la cocotte, pour les éléments finis \mathbb{P}_1 , \mathbb{P}_2 et \mathbb{P}_3 , par ordre croissant de vitesse de convergence

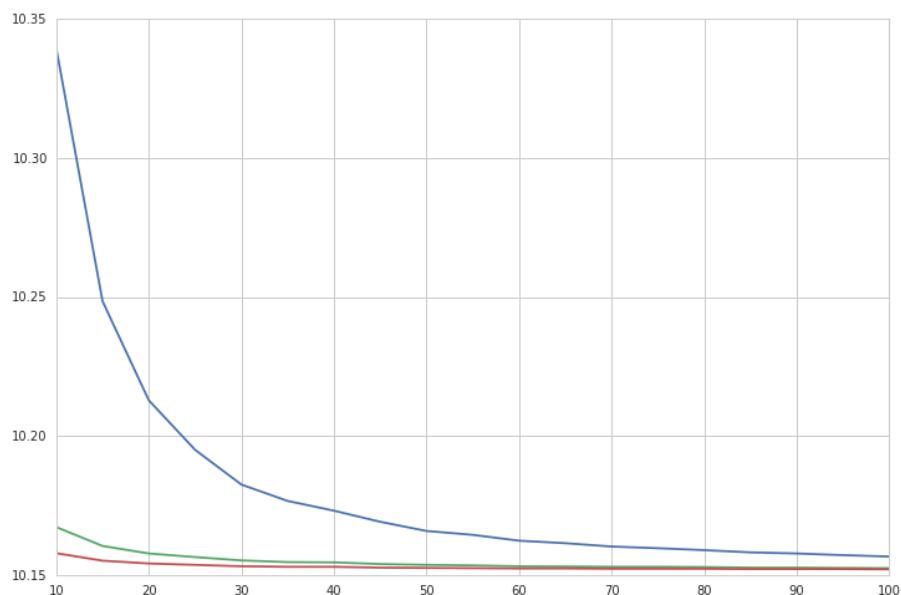


FIG. 2 : Convergence de la première valeur propre de la flèche, pour les éléments finis \mathbb{P}_1 , \mathbb{P}_2 et \mathbb{P}_3 , par ordre croissant de vitesse de convergence