

Smooth Manifolds

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1. MANIFOLDS

1.1. Smooth structure.

1.2. Partition of unity. We prove the existence of partition of unity and exhaustion function.

2. TANGENT BUNDLE

2.1. Definition of tangent space. We will provide four different definitions of tangent spaces:

- (1) the space of equivalence classes of smooth curves,
- (2) the space of tangent vectors embedded in an ambient space,
- (3) the space of derivations on the ring of smooth functions,
- (4) the dual space of algebraically defined cotangent spaces.

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2.2. Definition of tangent bundle. Consider the disjoint union of tangent spaces where the base points run through the whole manifold. This subsection discusses two ways of giving topology on the disjoint union to make it a vector bundle: one uses the local trivializations and coefficients to make a map to a Euclidean space, and the other inherits the topology of the ambient space. Both topologies are so sufficiently smooth that we can settle a smooth structure, which are identical.

The latter case is essentially same with the topologize pullback bundle with respect to the embedding $M \rightarrow \mathbb{R}^A$ for some A . We need to show it does not depend on the choice of the index set A . (We have checked that there is a natural choice of $A = C^\infty(M)$ with embedding $i : M \rightarrow \mathbb{R}^{C^\infty(M)}$ such that $\pi_f(i(x)) = f(x)$.)

3. CATEGORICAL ASPECTS

3.1. Immersion and submersion.

3.2. Submanifolds. Recall that in the category of manifolds a monomorphism is an injective smooth map. A subobject in category theory is usually defined as an equivalence class of monomorphisms. Note that *submanifold is not an equivalent notion to subobject*.

Unlike topological spaces, we cannot start from set-theoretic functions. More precisely, there is no way to give a unique smooth structure as we did in giving initial topology. So, we want to consider a submanifold as a injective smooth map with a ready-made smooth structure on domain, and check if the smooth structures of domain and target are compatible. In this reason, it is convenient to think that there will be no submanifold tests for a subset, but rather we have for smooth injections.

Example 3.1. Consider two smooth structures on a set

$$M = \{(x, 0) \in \mathbb{R}^2\}$$

generated by two charts $\varphi_1 : (x, 0) \mapsto x$ and $\varphi_2 : (x, 0) \mapsto \sqrt[3]{x}$ respectively. In a smooth structure by φ_1 , the inclusion is immersion, while φ_2 is not. That is, the first condition is not enough.

Example 3.2. There are two different smooth structures on a lemniscate. Both make the inclusion an immersion.

However, the following proposition suggests a good definition of submanifolds.

Proposition 3.1. *Let $i : M \rightarrow N$ be a smooth map. Then, TFAE:*

- (1) *i is an injective immersion;*
- (2) *a universal property is satisfied: a set-theoretical function $f : L \rightarrow M$ on a manifold L is smooth if $if : L \rightarrow N$ is smooth.*

Embedding.

Definition 3.1. A *smooth embedding* is a regular monomorphism in the category of smooth manifolds.

Proposition 3.2. *A smooth map $i : M \rightarrow N$ is a smooth embedding iff it is a topological embedding.*

3.3. Basic differential topology. We are going to summary the basic tools to investigate the nature of smooth manifolds. These includes the inverse function theorem, the implicit function theorem, the slice lemma, the constant rank theorem.

3.3.1. Contant rank theorem. Let $f : M \rightarrow N$ be a smooth map. Let $\varphi : U \rightarrow \mathbb{R}^m$ and $\psi : V \rightarrow \mathbb{R}^n$ be coordinate maps such that $p \in U$ and $df : TU \rightarrow TV$ has a constant rank k .

Proof. The follwoing diagram would be helpful.

$$\begin{array}{ccccc}
 M \supset & U & \xrightarrow{f} & V & \subset N \\
 & \varphi \downarrow & & \downarrow \psi & \\
 \mathbb{R}^m \supset & \varphi(U) & \xrightarrow{f_{(0)} = \psi \circ f \circ \varphi^{-1}} & \psi(V) & \subset \mathbb{R}^n \\
 & \cup & & \cup & \\
 & U_1 & \xrightarrow{f_{(0)}|_{U_1}} & V_1 & \\
 & \varphi_1 \downarrow & & \downarrow \psi_1 & \\
 & \varphi_1(U_1) & \xrightarrow{f_{(1)}} & \psi_1(V_1) & \\
 & \cup & & \cup & \\
 & U_2 & \xrightarrow{f_{(1)}|_{U_2}} & V_2 & \\
 & \varphi_2 \downarrow & & \downarrow \psi_2 & \\
 & \varphi_2(U_2) & \xrightarrow{f_{(2)}} & \psi_2(V_2) &
 \end{array}$$

Consider a map

$$f_{(0)} := \psi \circ f \circ \varphi^{-1} : \varphi(U) \rightarrow \psi(V).$$

It is smooth becuase of definition of smooth maps. Since $Df_{(0)}|_{\varphi(p)} : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is a matrix of rank k , there is an invertible $k \times k$ minor submatrix. Let $A : \mathbb{R}^m \rightarrow \mathbb{R}^m$ and $B : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be permutation matrices that reorder the coordinates in such a way that the invertible $k \times k$ minor submatrix becomes the leading principal minor submatrix.

Define coordinate maps $\varphi_1 : U_1 \rightarrow \varphi_1(U_1)$ and $\psi_1 : V_1 \rightarrow \psi_1(V_1)$ such that

$$\varphi_1(v) := A(v - \varphi(p)), \quad \psi_1(v) := B(v - \psi(f(p))),$$

where U_1 and V_1 are arbitrarily taken open subsets of $\varphi(U)$ and $\psi(V)$ respectively. Check that they are clearly diffeomorphisms. Then,

$$f_{(1)} := \psi_1 \circ f_{(0)} \circ \varphi_1^{-1} : \varphi_1(U_1) \rightarrow \psi_1(V_1)$$

is written as

$$f_{(1)}(x, y) = (a(x, y), b(x, y))$$

for $(x, y) \in \varphi_1(U_1) \subset \mathbb{R}^k \times \mathbb{R}^{m-k}$ and for some $a : \varphi_1(U_1) \subset \mathbb{R}^m \rightarrow \mathbb{R}^k$ such that

$$f_{(1)}(0, 0) = (0, 0) \quad \text{and} \quad \frac{\partial a}{\partial x} \Big|_{\varphi_1(\varphi(p))} \quad \text{is invertible.}$$

Define $\varphi_2 : \varphi_1(U) \rightarrow \mathbb{R}^k \times \mathbb{R}^{m-k}$ such that

$$\varphi_2(x, y) := (a(x, y), y).$$

Then,

$$D\varphi_2 = \begin{pmatrix} \frac{\partial a}{\partial x} & \frac{\partial a}{\partial y} \\ 0 & \text{id}_{m-k} \end{pmatrix}.$$

Since $D\varphi_2$ is smooth and $D\varphi_2|_{\varphi_1(\varphi(p))}$ is invertible, there exists an open set $U_2 \subset \varphi_1(U_1)$ such that the restriction $\varphi_2 : U_2 \rightarrow \varphi_2(U_2)$ on an open subset $U_2 \subset \varphi_1(U_1)$ is a diffeomorphism. Then,

$$\begin{aligned} D(f_{(1)} \circ \varphi_2^{-1}) &= Df_{(1)} \circ D\varphi_2^{-1} \\ &= \begin{pmatrix} \frac{\partial a}{\partial x} & \frac{\partial a}{\partial y} \\ \frac{\partial b}{\partial x} & \frac{\partial b}{\partial y} \end{pmatrix} \cdot \begin{pmatrix} \left(\frac{\partial a}{\partial x}\right)^{-1} & -\left(\frac{\partial a}{\partial x}\right)^{-1} \frac{\partial a}{\partial y} \\ 0 & \text{id}_{m-k} \end{pmatrix} = \begin{pmatrix} \text{id}_k & 0 \\ * & * \end{pmatrix} = \begin{pmatrix} \text{id}_k & 0 \\ * & 0 \end{pmatrix}. \end{aligned}$$

The last equality is because the matrix should have rank k on U_2 . Thus we have

$$f_{(1)} \circ \varphi_2^{-1}(x, y) = (x, c(x))$$

for some $c : \varphi_2(U_2) \subset \mathbb{R}^{m-k} \rightarrow \mathbb{R}^{n-k}$. Define $\psi_2 : V_2 \rightarrow \psi_2(V_2)$ by

$$\psi_2(x, z) = (x, z - c(x)),$$

where $V_2 \subset \psi_1(V_1)$ is arbitrarily taken such that $f_{(1)}(U_2) \subset V_2$. We can check ψ_2 is a diffeomorphism by computing the differential

$$D\psi_2 = \begin{pmatrix} \text{id}_k & 0 \\ -\frac{\partial c}{\partial x} & \text{id}_{n-k} \end{pmatrix}.$$

Then,

$$f_{(2)} := \psi_2 \circ f_{(1)} \circ \varphi_2^{-1} : \varphi_2(U_2) \rightarrow \psi_2(V_2)$$

satisfies

$$f_{(2)}(x, y) = (x, 0).$$

Define coordinate charts $(\tilde{U}, \tilde{\varphi})$ and $(\tilde{V}, \tilde{\psi})$ around p and $f(p)$ such that

$$\tilde{\varphi} := \varphi_2 \circ \varphi_1 \circ \varphi, \quad \tilde{\psi} := \psi_2 \circ \psi_1 \circ \psi,$$

and

$$\tilde{U} := \tilde{\varphi}^{-1}(\varphi_2(U_2)), \quad \tilde{V} := \tilde{\psi}^{-1}(\psi_2(V_2)).$$

The new charts are compatible with old charts since the transitions $\varphi_2 \circ \varphi_1 : \varphi(\tilde{U}) \rightarrow \tilde{\varphi}(\tilde{U})$ and $\psi_2 \circ \psi_1 : \psi(\tilde{V}) \rightarrow \tilde{\psi}(\tilde{V})$ are diffeomorphisms. Then, the map f has the coordinate representation $f_{(2)} : (x, y) \mapsto (x, 0)$ on $(\tilde{U}, \tilde{\varphi})$ and $(\tilde{V}, \tilde{\psi})$. \square

3.4. Category of smooth manifolds.

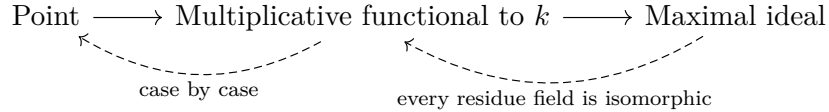
3.5. Tangent bundle functor.

Theorem 3.3. *The tangent bundle functor T preserves finitary products*

3.6. Pullbacks. When is the pullback possible?

4. SHEAF THEORETICAL ASPECTS

Consider a (commutative unital) ring A such that every residue field is isomorphic to a field k . Familiar examples include any Banach algebras by the Gelfand-Mazur theorem. The unital condition is attached because we want to treat maximal ideals. Then, maximal ideals correspond to a nonzero multiplicative linear functional to k because the residue field is k . Therefore, the set of maximal ideals can be identified with the set of all nonzero multiplicative linear functionals.



4.1. The ring $C^\infty(M)$. The following theorem is presented as the problem 1-C in the book of Milnor and Stasheff about characteristic classes.

Theorem 4.1. *Every ring homomorphism $C^\infty(M) \rightarrow \mathbb{R}$ is obtained by an evaluation at a point of M .*

Proof. Suppose $\phi : C^\infty(M) \rightarrow \mathbb{R}$ is not an evaluation. Let h be a positive exhaustion function. Take a compact set $K := h^{-1}([0, \phi(h)])$. For every $p \in K$, we can find $f_p \in C^\infty(M)$ such that $\phi(f_p) \neq f_p(p)$ by the assumption. Summing $(f_p - \phi(f_p))^2$ finitely on K and applying the extreme value theorem, we obtain a function $f \in C^\infty(M)$ such that $f \geq 0$, $f|_K > 1$, and $\phi(f) = 0$. Then, the function $h + \phi(h)f - \phi(h)$ is in kernel of ϕ although it is strictly positive and thereby a unit. It is a contradiction. \square