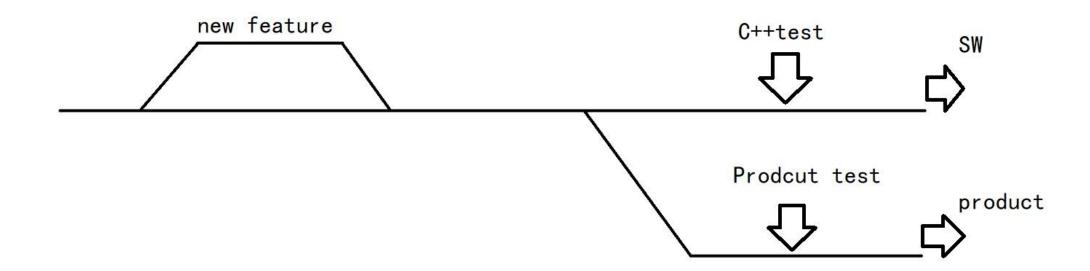
C++test _{李卓}

background

- 机器人有很多传感器,用于对未知环境做出判断。
- •由于实验环境条件的限制和对复杂环境的未知,很难在实验室模拟现实中的环境。不仅成本而且覆盖率低。
- 基于Googletest框架的cppunit可以很好的模拟、仿真传感器的各种组合输入,成本低、覆盖率高。

软件测试/产品测试

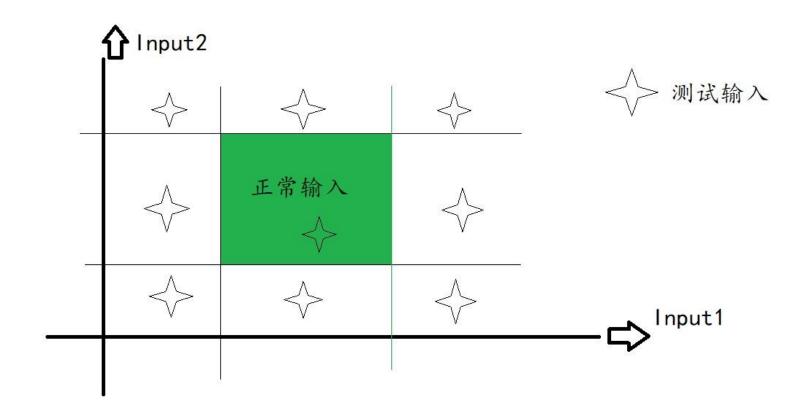


软件测试/产品测试

软件测试:专注软件质量,新功能集成、迭代开发。稳定性。

产品测试:专注客户定制,客户需求验证与验收方案确认。

二维Sensor输入



Sensor_controller

```
#include <iostream>
   class Sensor_control {
   private:
            int Sensor_one, Sensor_two, Sensor_three;
   public:
            Sensor_control(int one, int two, int three);
            long get() {
                         return Sensor_one * Sensor_two * Sensor_three;
   Sensor_control::Sensor_control(int one, int two, int three) {
            Sensor_one = one;
            Sensor_two = two;
            Sensor_three = three;
int main()
            Sensor_control sc(-50, 0, 20);
            std::cout << sc.get()<<"\n";
```

Test case

• Three sensor input (include range)

Sensor_1	Sensor-2	Sensor-3	Assert
max:145 min:-145	max:60 min:0	max:120 min:-160	

Test case

ensor_1	Sensor-2	Sensor-3	Assert
nax:145	max:60	max:120	
nin:-145	min:0	min:-160	
160	80	160	0
160	80	100	0
160	80	-140	0
160	80	-220	0
160	50	160	0
160	50	100	0
160	50	-140	0
160	50	-220	0
160	-20	160	0
160	-20	100	0
160	-20	-140	0
160	-20	-220	0
140	80	160	0
140	80	100	0
140	80	-140	0
140	80	-220	0
140	50	160	0
140	50	100	700000
140	50	-140	-980000
140	50	-220	0
140	-20	160	0
140	-20	100	0
140	-20	-140	0
140	-20	-220	0
-120	80	160	0
-120	80	100	0
-120	80	-140	0
-120	80	-220	0
-120	50	160	0
-120	50	100	-600000
-120	50	-140	840000
-120	50	-220	0
-120	-20	160	0
-120	-20	100	0
-120	-20	-140	0
-120	-20	-220	0
-150	80	160	0
-150	80	100	0
-150	80	-140	0
-150	80	-220	0
-150	50	160	0
-150	50	100	0
-150	50	-140	0
-150	50	-220	0
-150	-20	160	0
-150	-20	100	0
-150	-20	-140	0
-150	-20	-220	0

Test result(part)

```
Microsoft Visual Studio 调试控制台
                                                                                                         sc.get()
   Which is: 2048000
           Sensor test. 16080160 (2 ms)
           Sensor test. 14050100
      OK ] Sensor_test.14050100 (0 ms)
           Sensor test. nagative 12050100
      OK ] Sensor_test.nagative12050100 (0 ms)
           Sensor_test.nagative150nagative20nagative220
 :\Users\liouh\Documents\Cpp\Sensor controller test\test.cpp(32): error: Expected equality of these values:
 sc.get()
   Which is: -660000
           Sensor test.nagative150nagative20nagative220 (0 ms)
           4 tests from Sensor_test (5 ms total)
           Global test environment tear-down
           4 tests from 1 test case ran. (5 ms total)
           2 tests.
  PASSED
         1 2 tests, listed below:
  FAILED
           Sensor test. 16080160
  FAILED
  FAILED ] Sensor test. nagative150nagative20nagative220
2 FAILED TESTS
C:\Users\liouh\Documents\Cpp\Sensor_controller_test\Release\Sensor_controller_test.exe (进程 2136)己退出,返回代码为: 1
若要在调试停止时自动关闭控制台,请启用"工具"->"选项"->"调试"->"调试停止时自动关闭控制台"。
按任意键关闭此窗口...
```