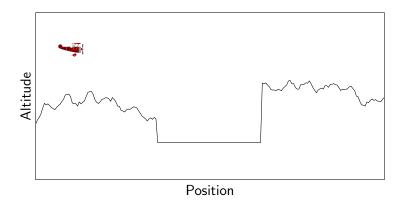
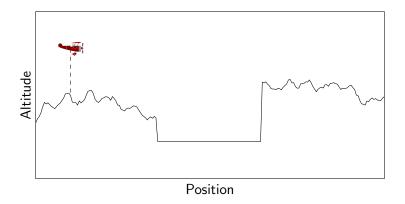
# A Sequential Monte Carlo Example

Daniel Lundén

April 16, 2020







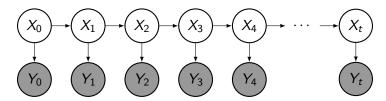
▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$ 

- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$

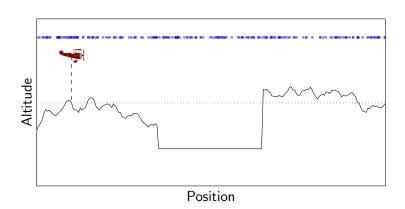
- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\mathsf{map}(X_t), 5)$

- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find  $p(x_t | y_{0:t})$

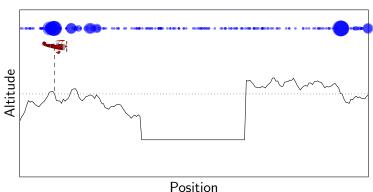
- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find  $p(x_t | y_{0:t})$



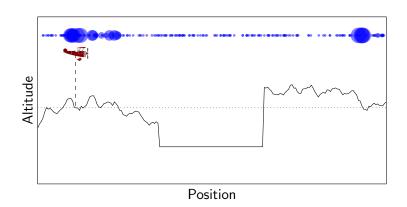
Initialize 200 samples from  $X_0$ 



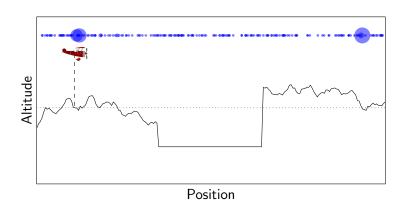
#### Weigh samples using observation model



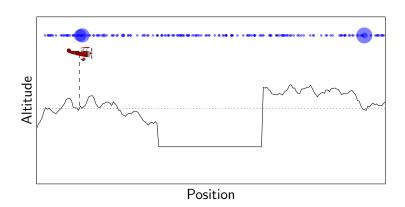
#### Propagate samples using transition model



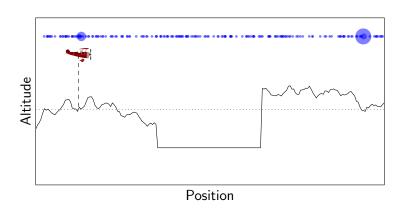
#### Weigh samples using observation model

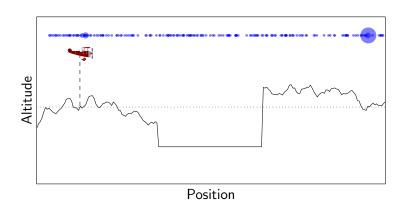


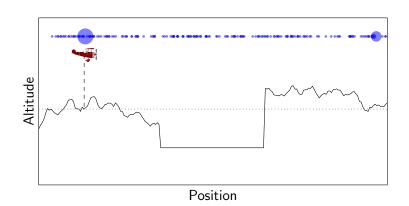
#### Propagate samples using transition model

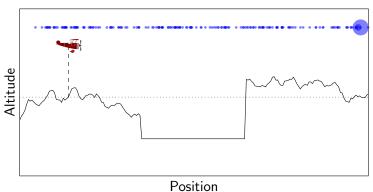


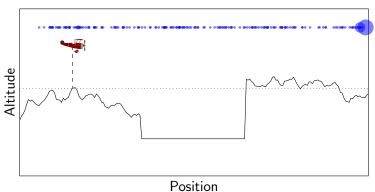
#### Weigh samples using observation model

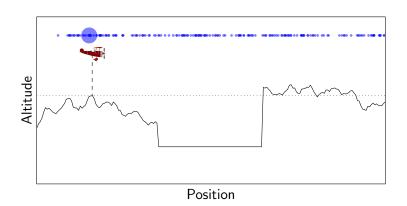


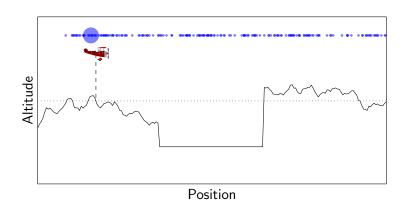


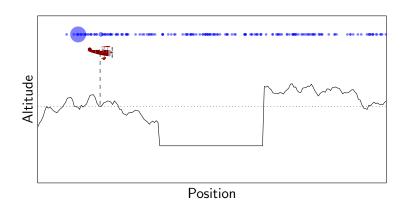


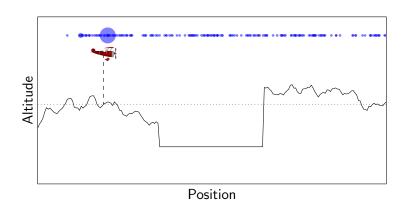


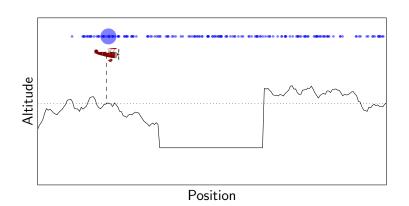


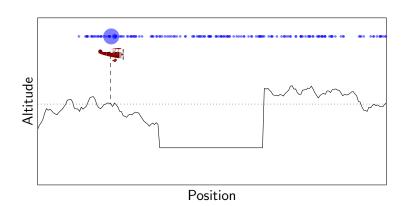


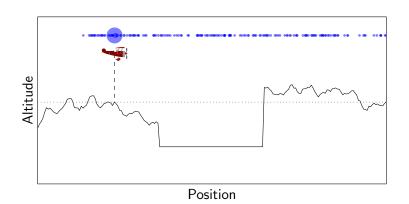


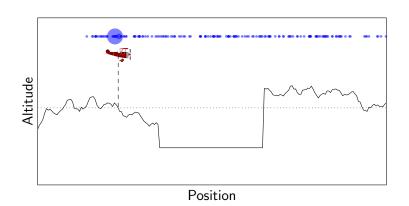


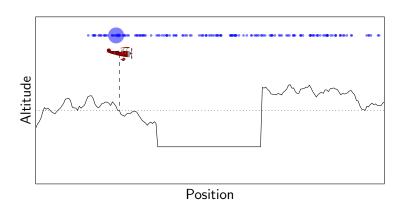


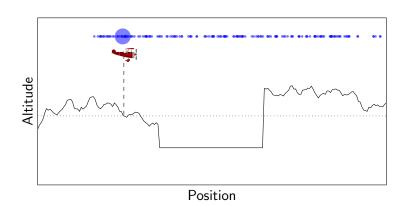


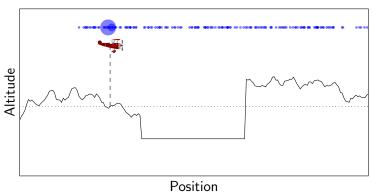


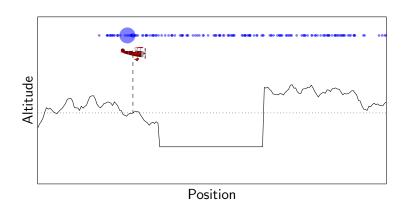


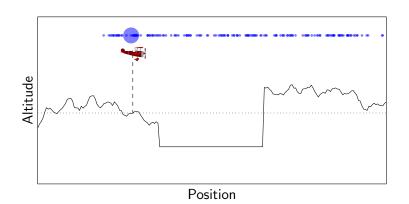


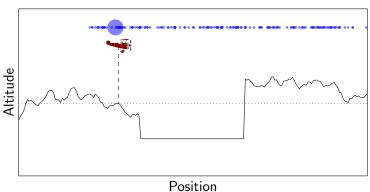


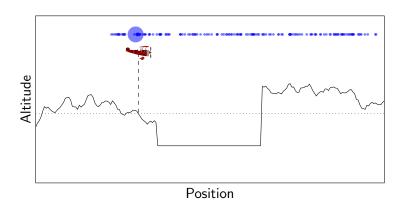


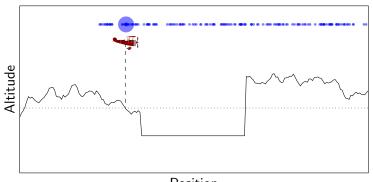


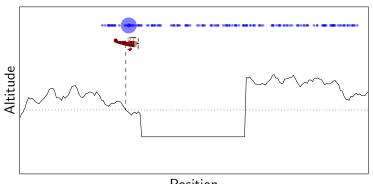


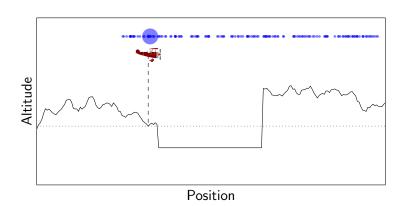


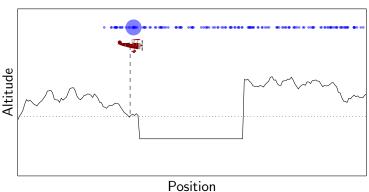


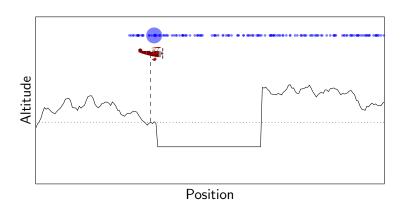


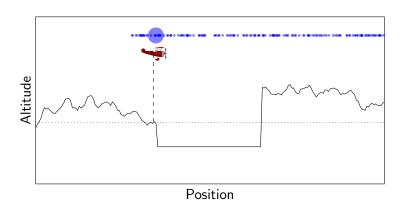


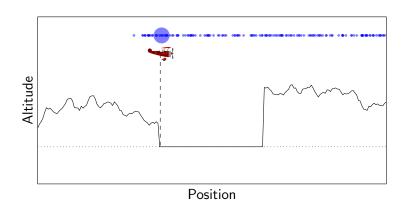


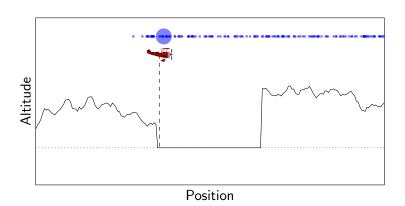


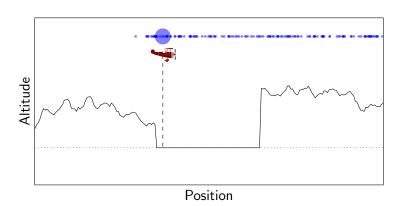


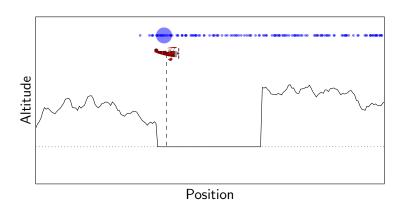


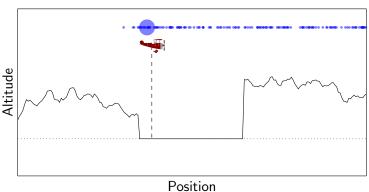


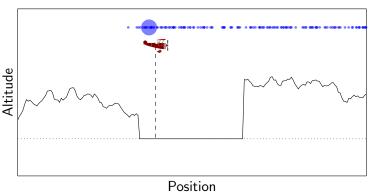


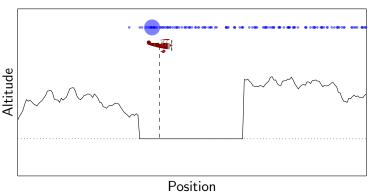


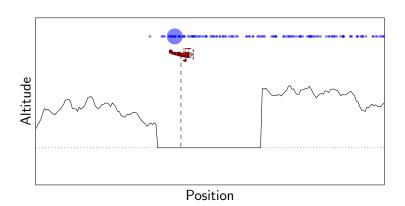




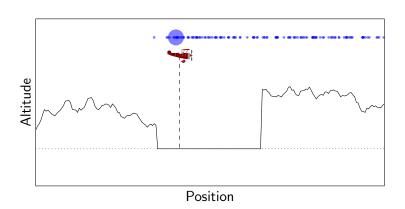


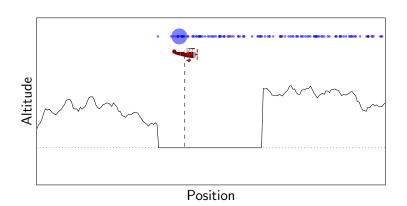


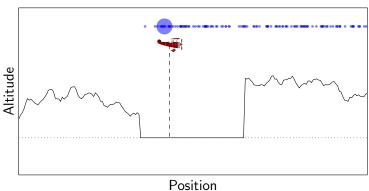


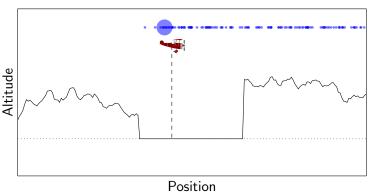


Propagate, weigh

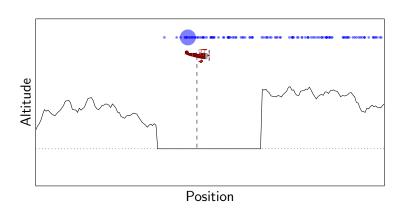




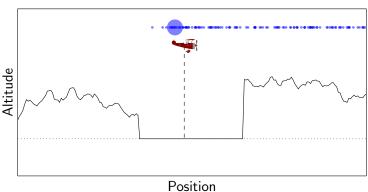




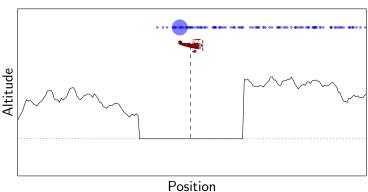
Propagate, weigh

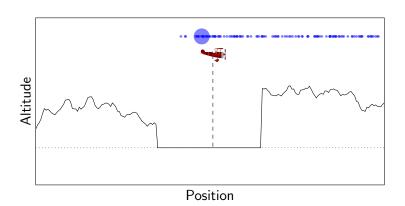


Propagate, weigh

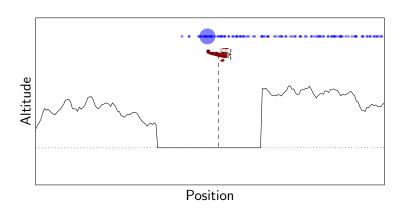


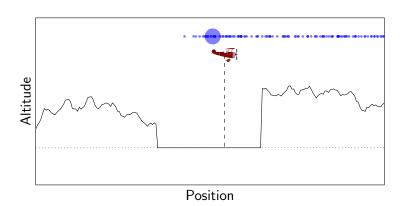
Propagate, weigh



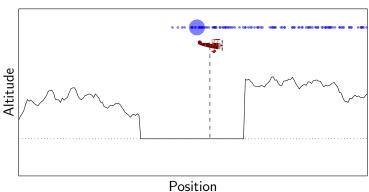


Propagate, weigh

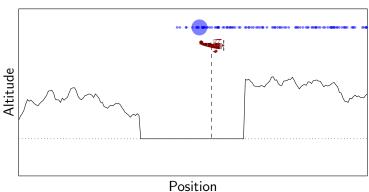


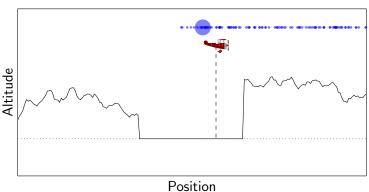


Propagate, weigh

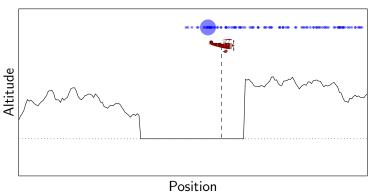


Propagate, weigh

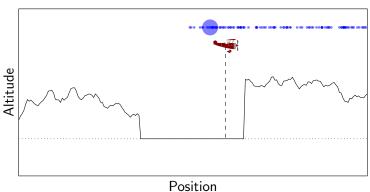


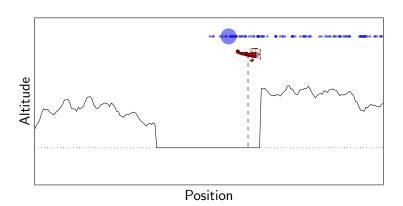


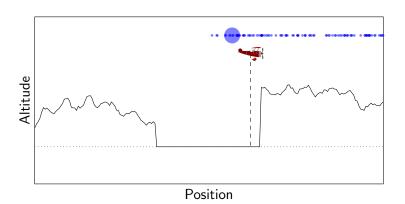
Propagate, weigh

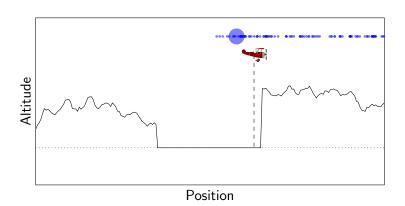


Propagate, weigh

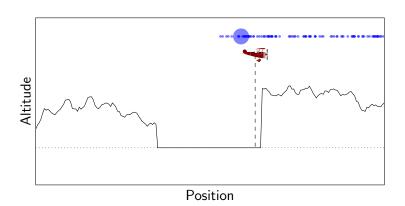




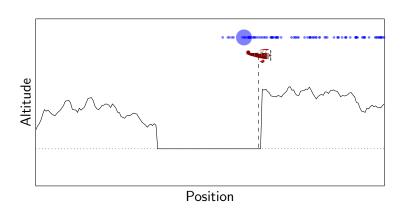


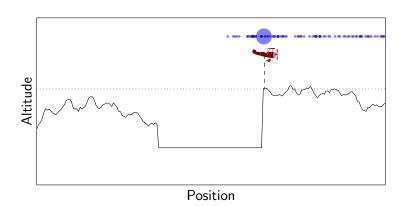


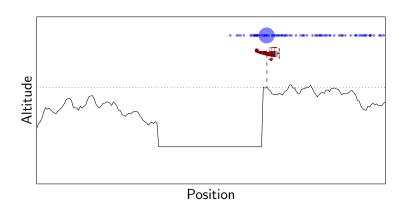
Propagate, weigh



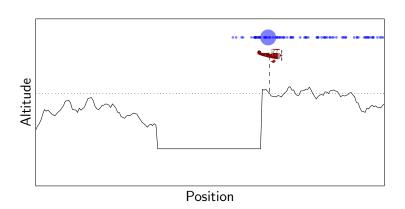
Propagate, weigh

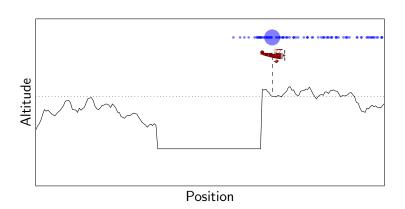


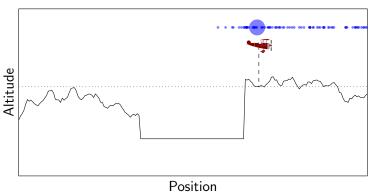


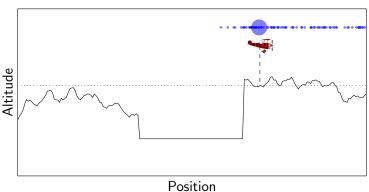


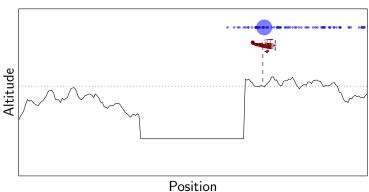
Propagate, weigh



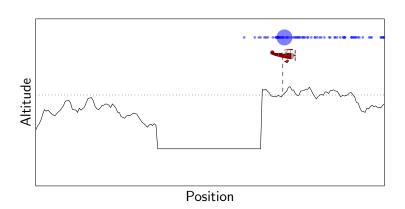


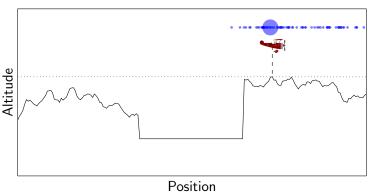




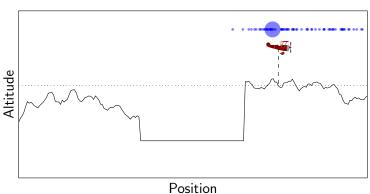


Propagate, weigh

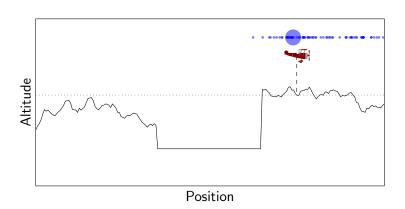


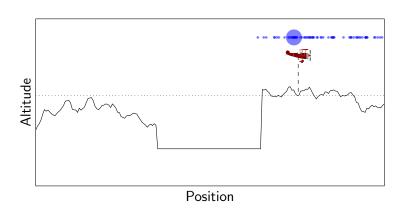


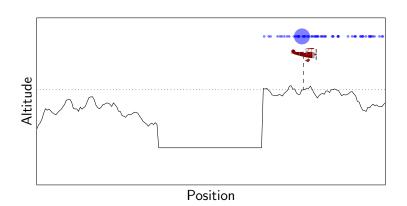
Propagate, weigh

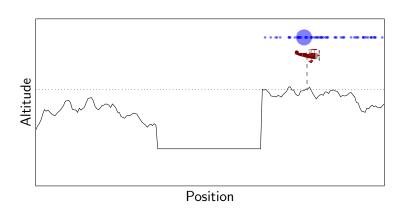


Propagate, weigh

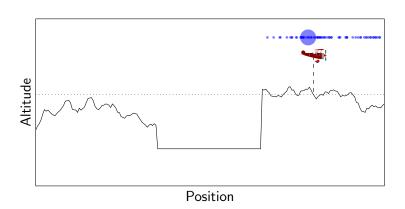


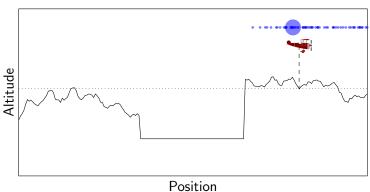


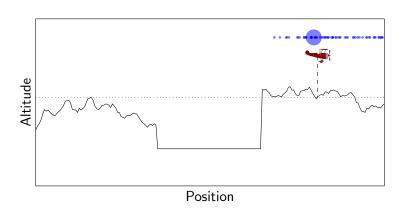


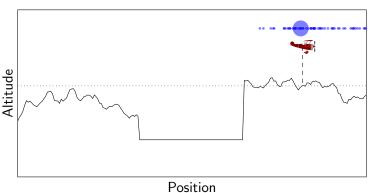


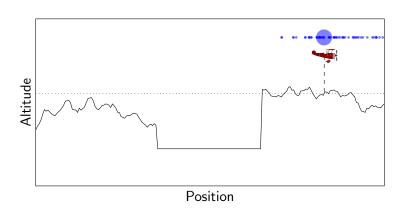
Propagate, weigh

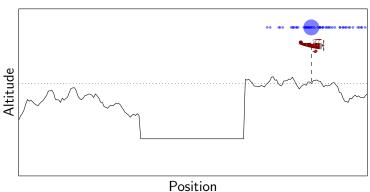


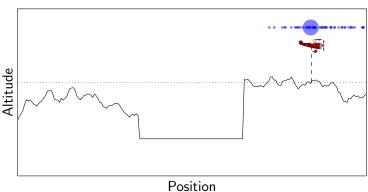


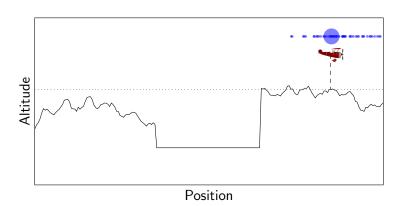


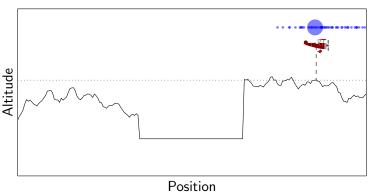


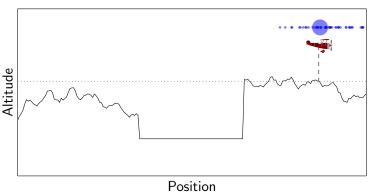


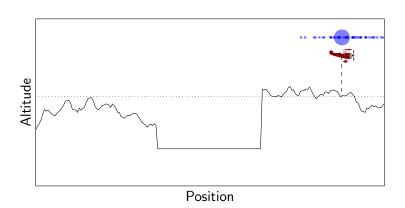


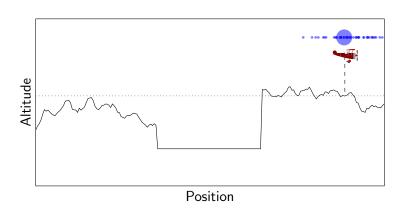


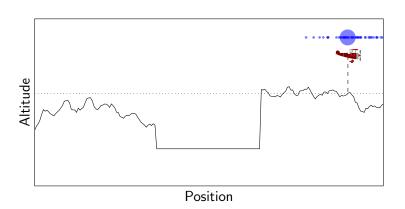


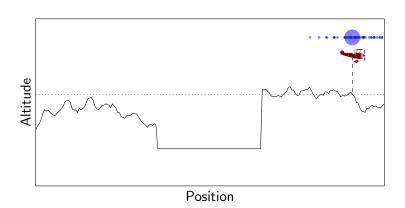


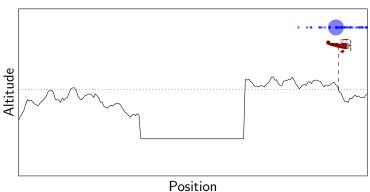


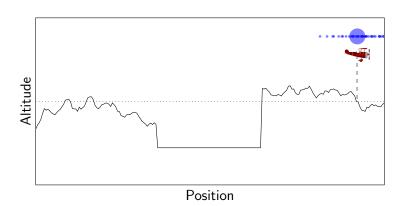


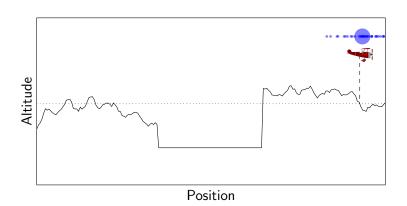




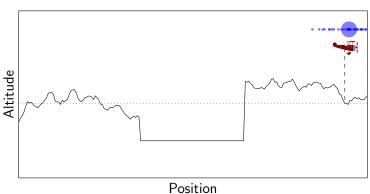


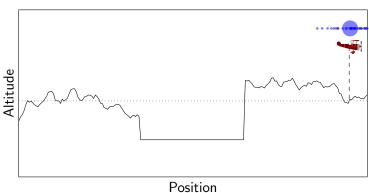




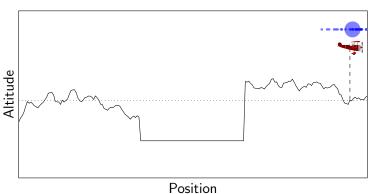


Propagate, weigh

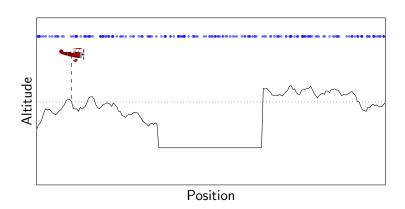




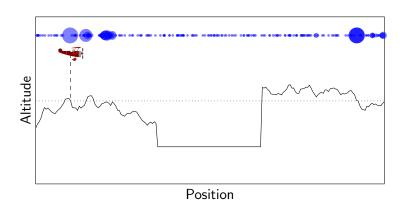
Propagate, weigh



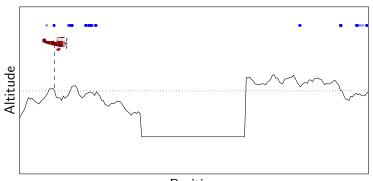
Initialize 200 samples from  $X_0$ 



#### Weigh samples using observation model

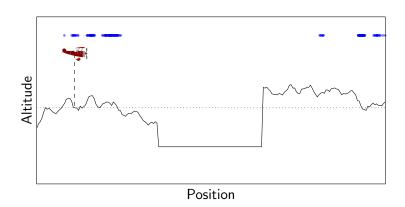


### Resample

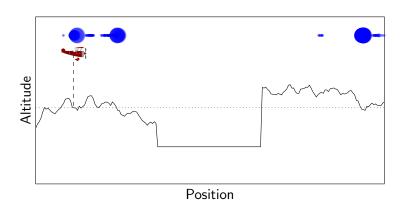


Position

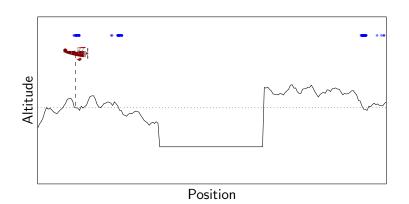
#### Propagate samples using transition model



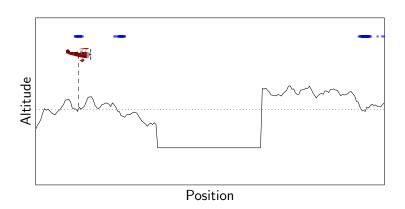
#### Weigh samples using observation model



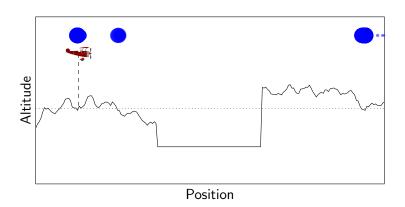
### Resample



#### Propagate samples using transition model



#### Weigh samples using observation model



### Resample

