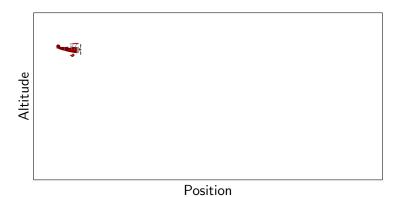
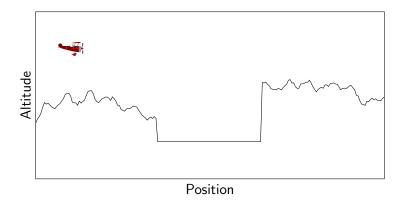
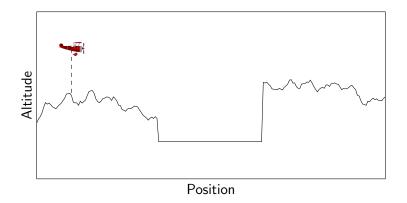
A Sequential Monte Carlo Example

Daniel Lundén

April 13, 2022







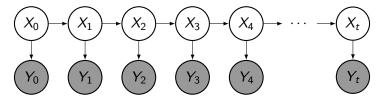
▶ Initial position: $X_0 \sim \mathcal{U}(0, 100)$

- ▶ Initial position: $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model: $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$

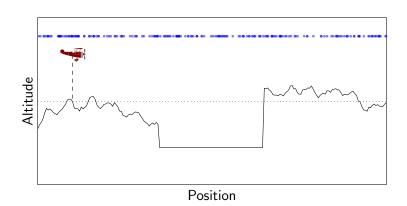
- ▶ Initial position: $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model: $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model: $Y_t \sim \mathcal{N}(\mathsf{map}(X_t), 5)$

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- ▶ Transition model: $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model: $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find $p(x_t | y_{0:t})$

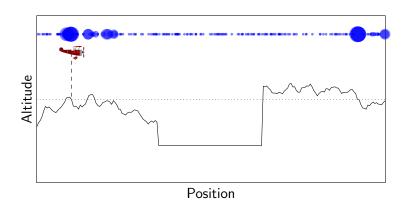
- ▶ Initial position: $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model: $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model: $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find $p(x_t | y_{0:t})$



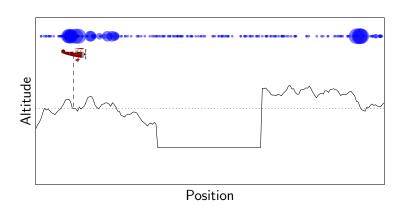
Initialize 200 samples from X_0



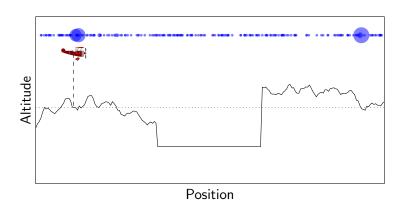
Weigh samples using observation model



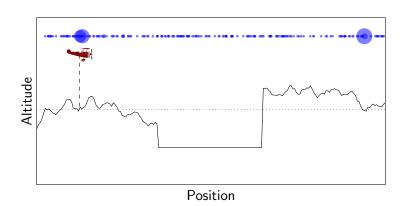
Propagate samples using transition model



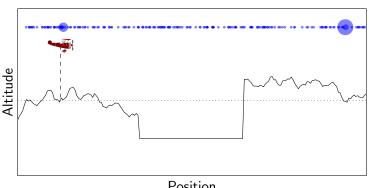
Weigh samples using observation model

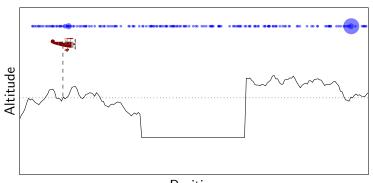


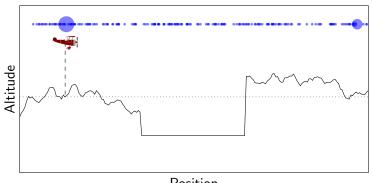
Propagate samples using transition model

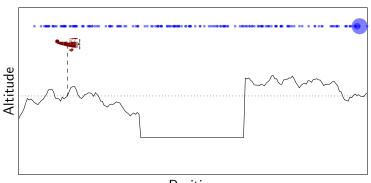


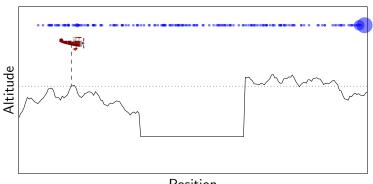
Weigh samples using observation model

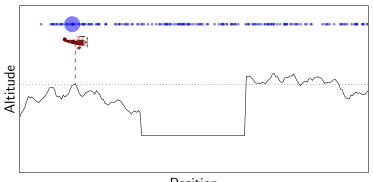


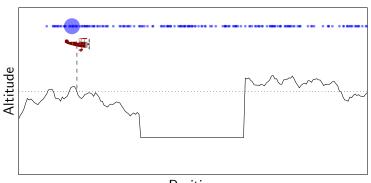


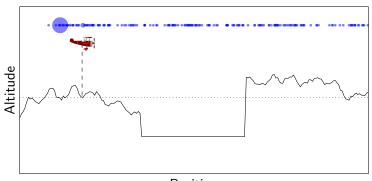


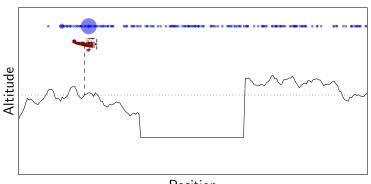




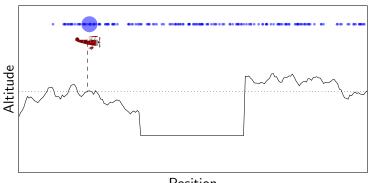




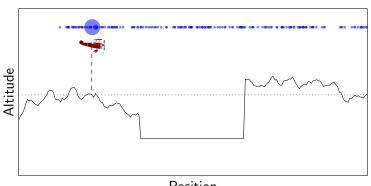


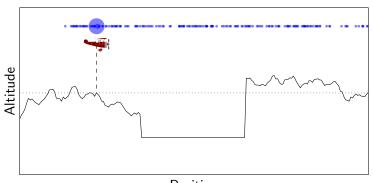


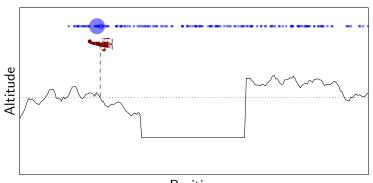
Propagate, weigh

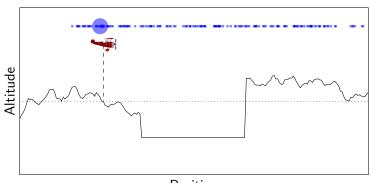


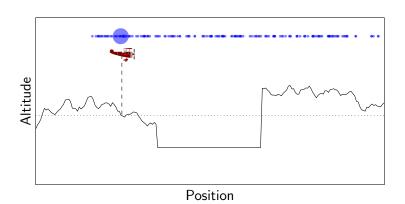
Position

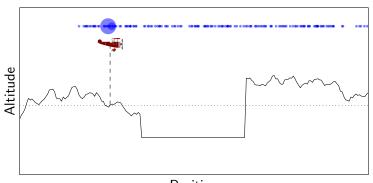


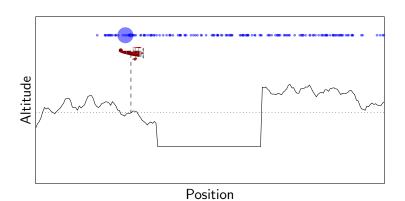


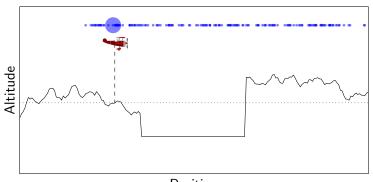


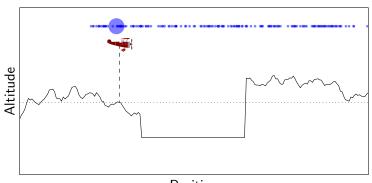


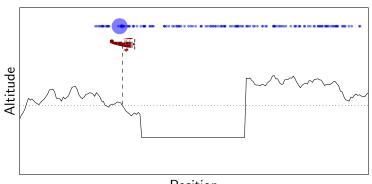




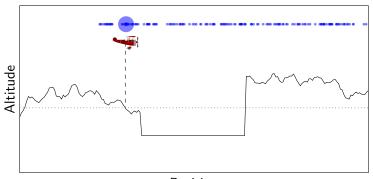






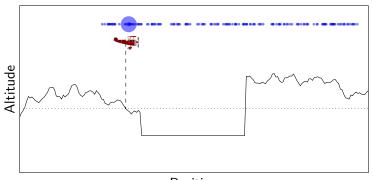


Propagate, weigh

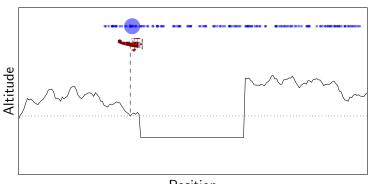


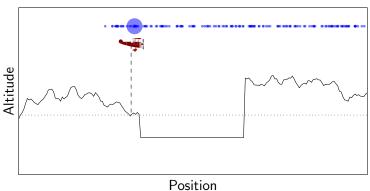
Position

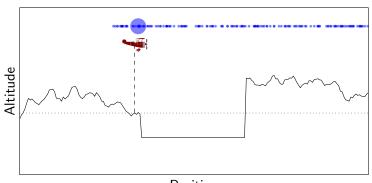
Propagate, weigh

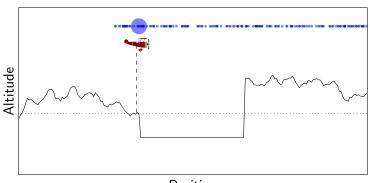


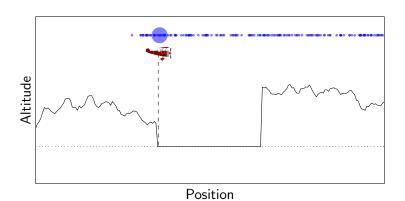
Position

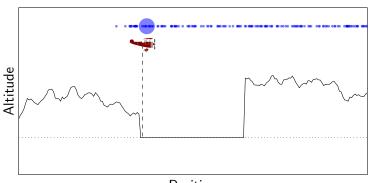


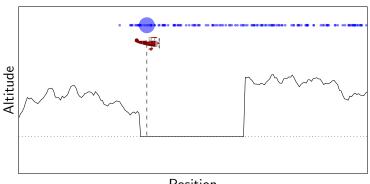


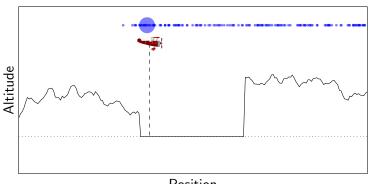


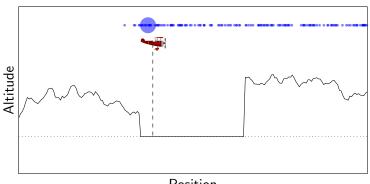


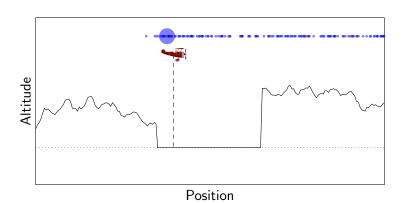


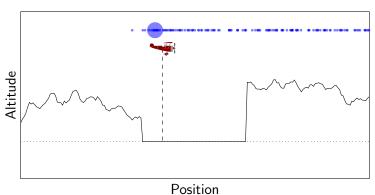


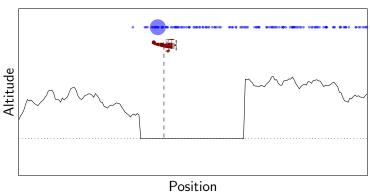


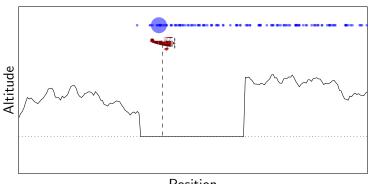


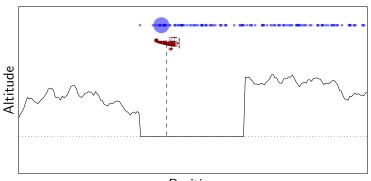


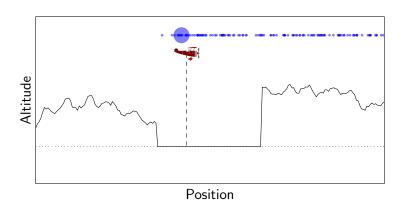


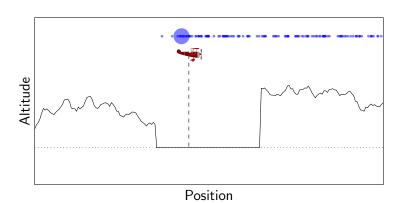


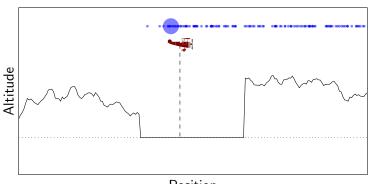


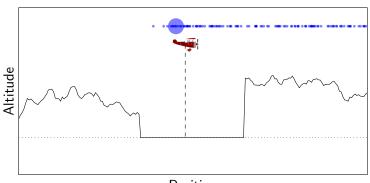


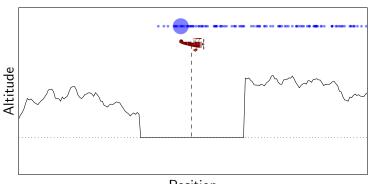


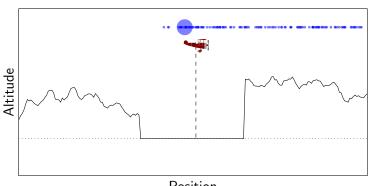




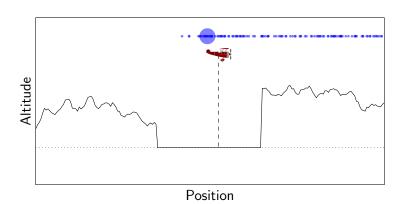




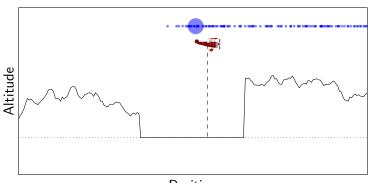




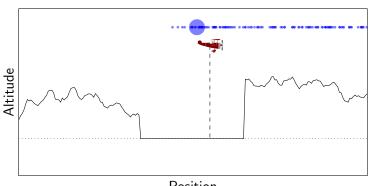
Propagate, weigh



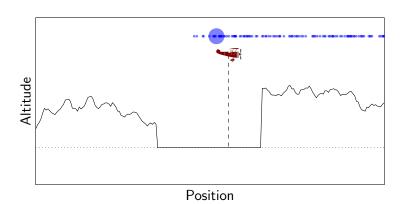
Propagate, weigh

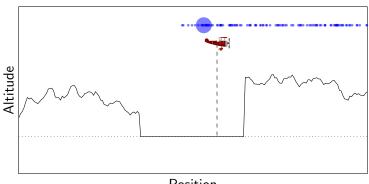


Propagate, weigh

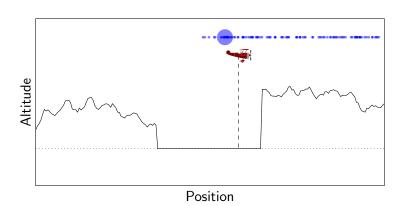


Propagate, weigh

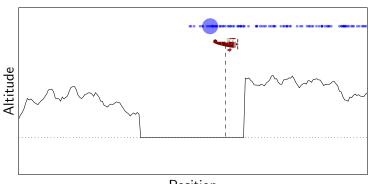


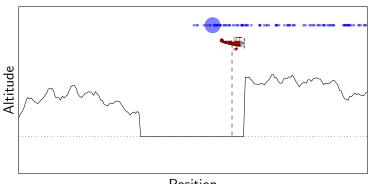


Propagate, weigh

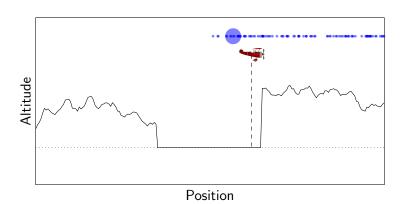


Propagate, weigh

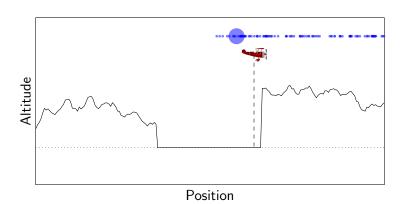




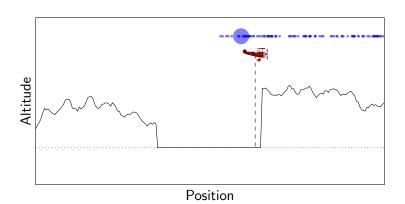
Propagate, weigh

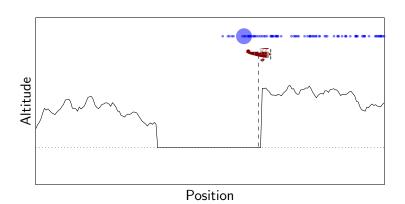


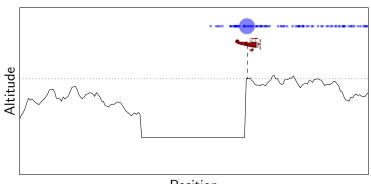
Propagate, weigh

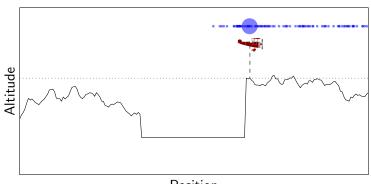


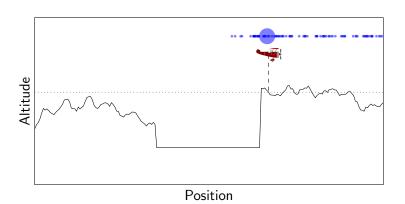
Propagate, weigh

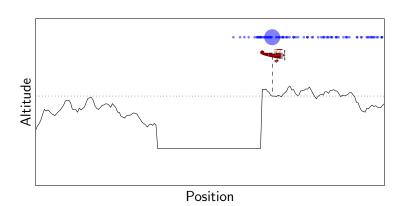


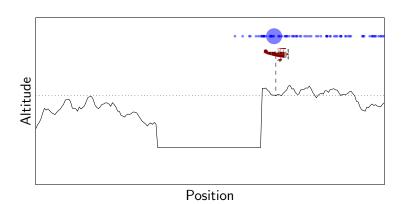


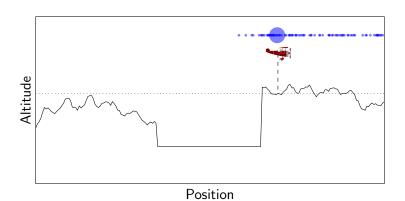


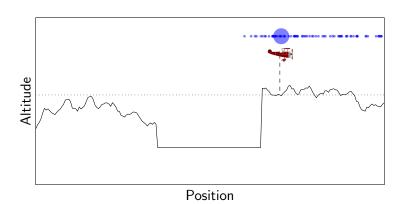


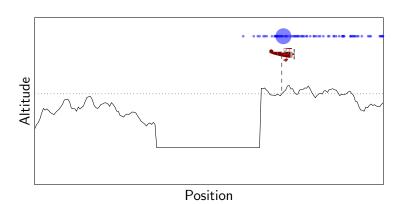


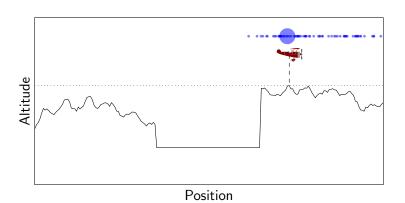


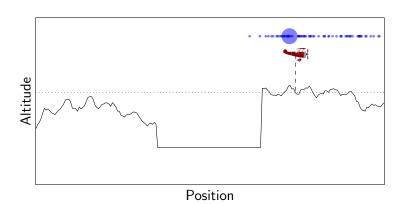


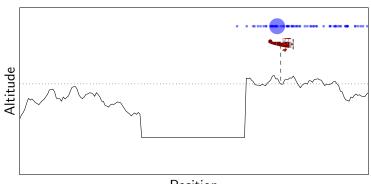




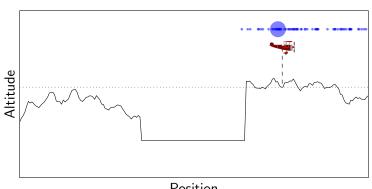




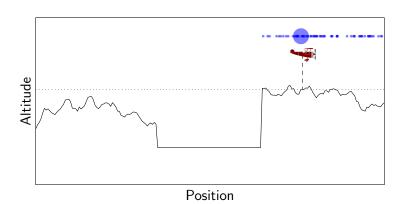


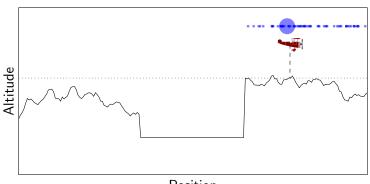


Propagate, weigh

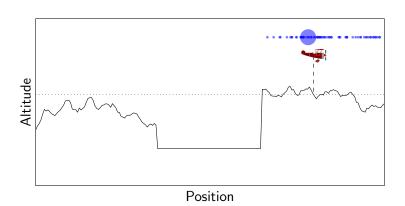


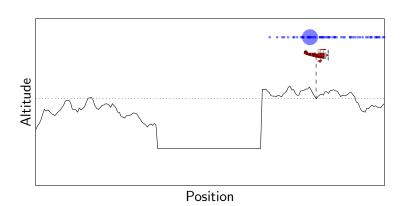
Propagate, weigh



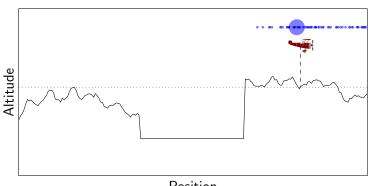


Propagate, weigh

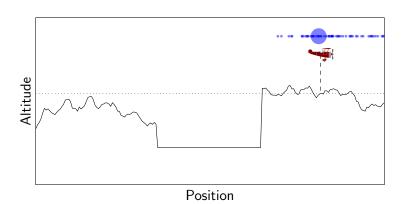




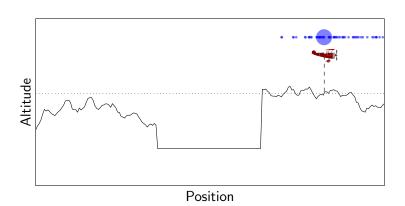
Propagate, weigh

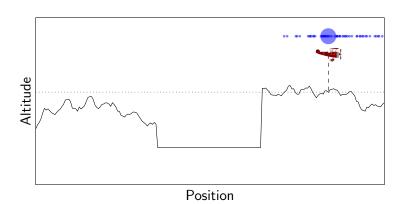


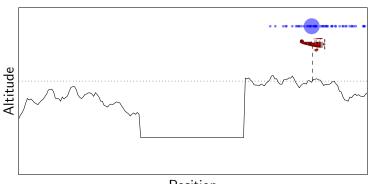
Propagate, weigh

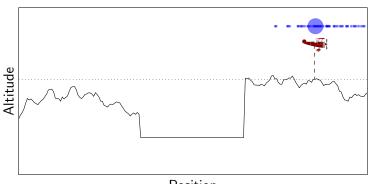


Propagate, weigh

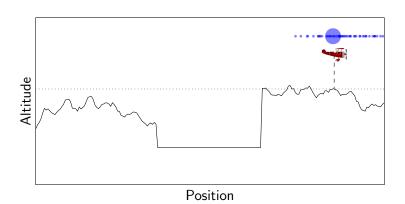




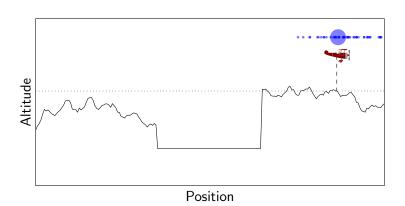




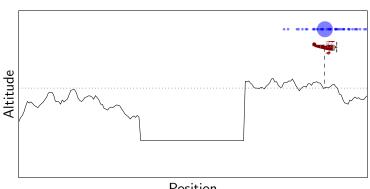
Propagate, weigh



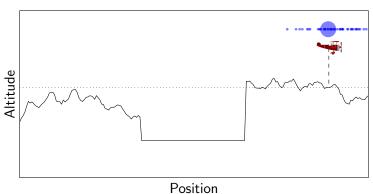
Propagate, weigh



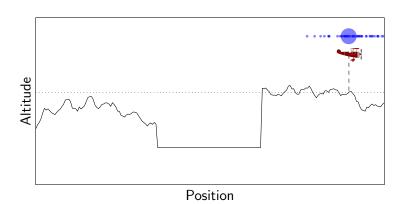
Propagate, weigh

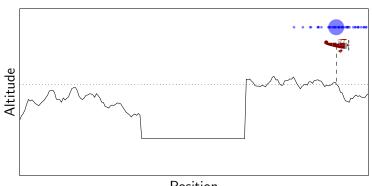


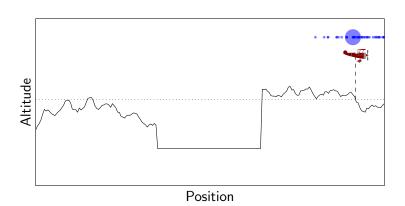
Propagate, weigh

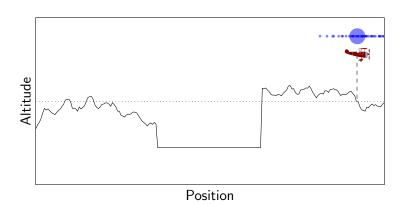


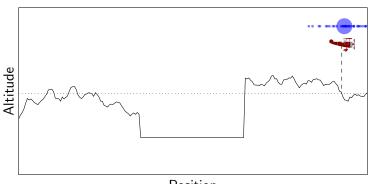
Propagate, weigh

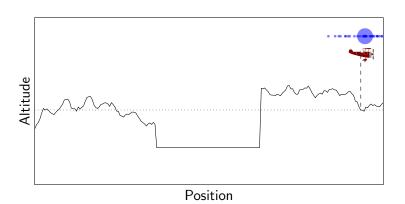




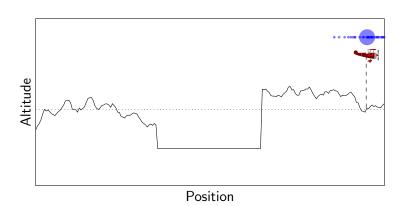


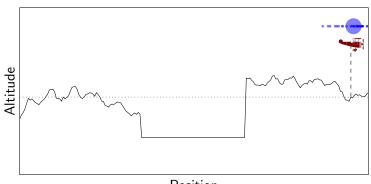




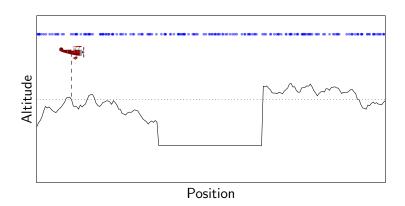


Propagate, weigh

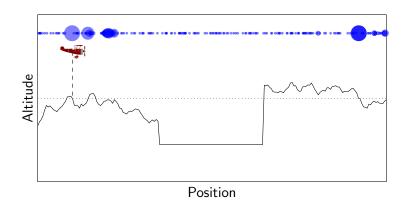




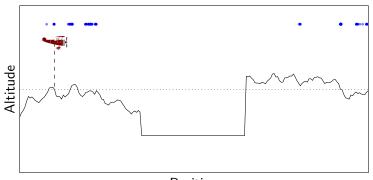
Initialize 200 samples from X_0



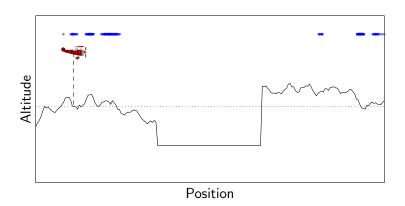
Weigh samples using observation model



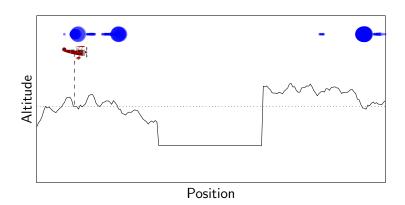
Resample



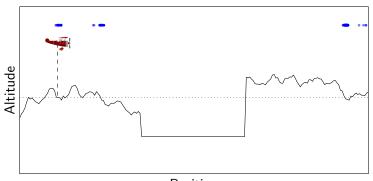
Propagate samples using transition model



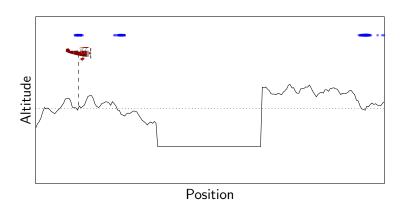
Weigh samples using observation model



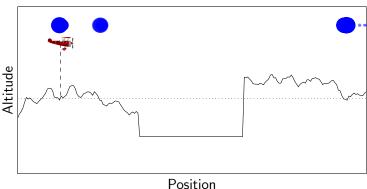
Resample



Propagate samples using transition model



Weigh samples using observation model



Resample

