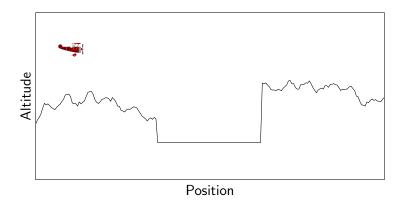
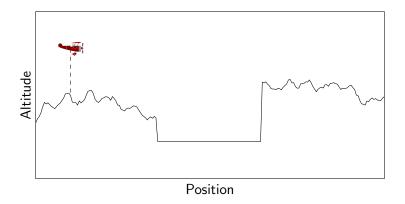
# A Sequential Monte Carlo Example

Daniel Lundén

October 11, 2019







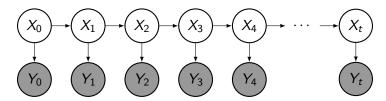
▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$ 

- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$

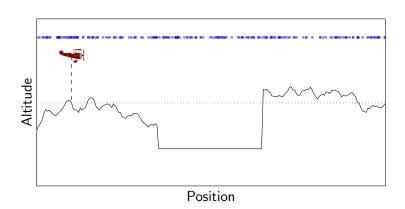
- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\mathsf{map}(X_t), 5)$

- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find  $p(x_t | y_{0:t})$

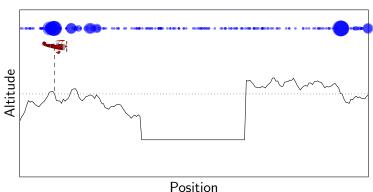
- ▶ Initial position:  $X_0 \sim \mathcal{U}(0, 100)$
- ▶ Transition model:  $X_t \sim \mathcal{N}(X_{t-1} + 2, 0.5)$
- ▶ Observation model:  $Y_t \sim \mathcal{N}(\text{map}(X_t), 5)$
- ▶ Problem: Find  $p(x_t | y_{0:t})$



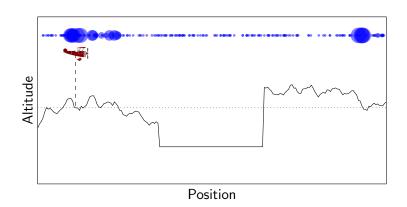
Initialize 200 samples from  $X_0$ 



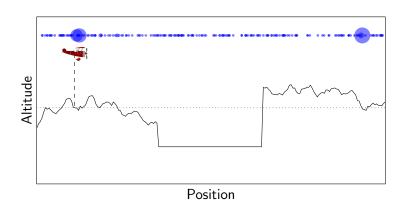
#### Weigh samples using observation model



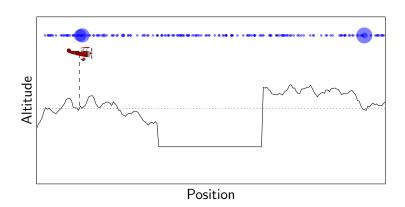
#### Propagate samples using transition model



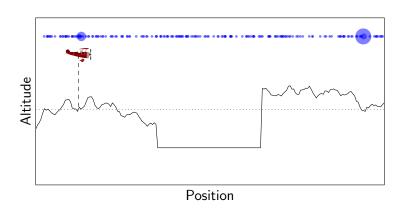
#### Weigh samples using observation model

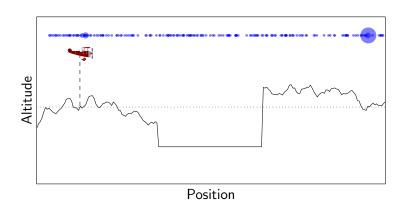


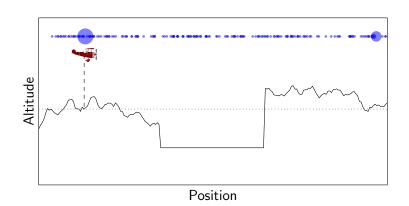
#### Propagate samples using transition model

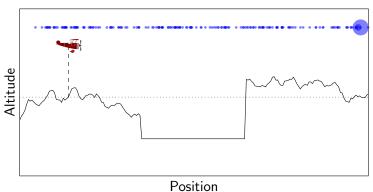


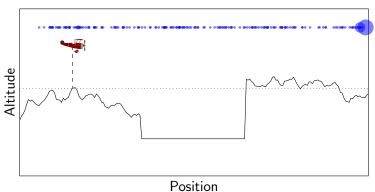
#### Weigh samples using observation model

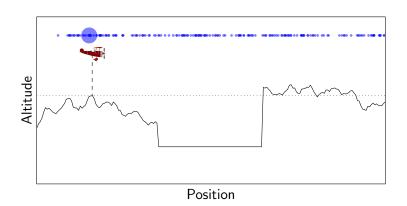


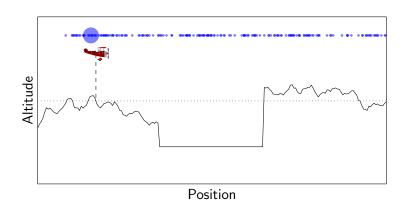


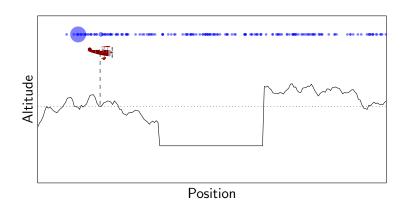


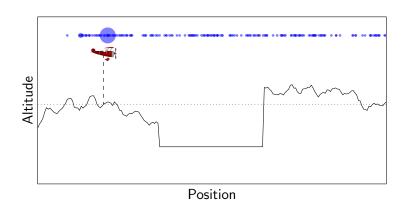


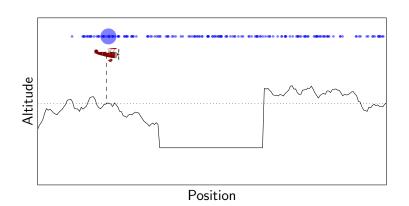


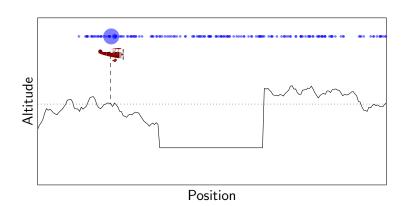


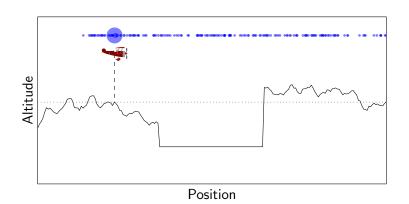


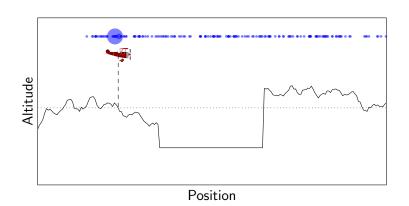


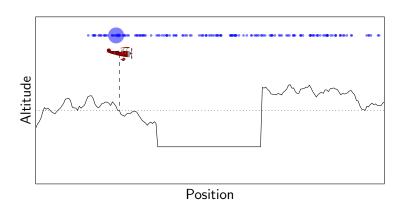


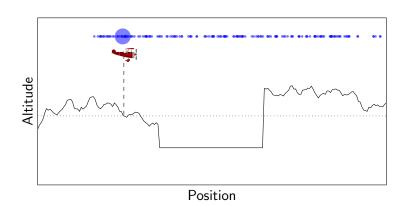


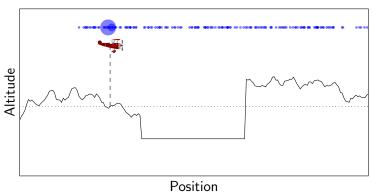


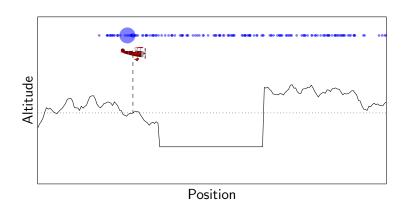


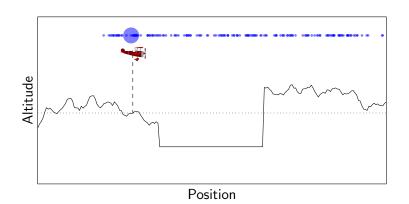


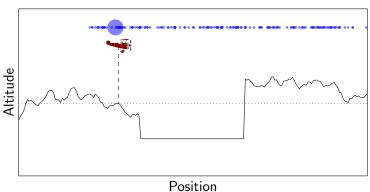


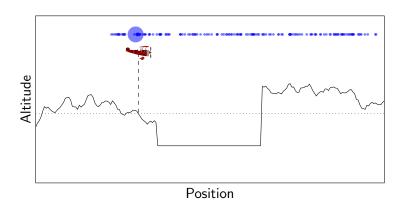


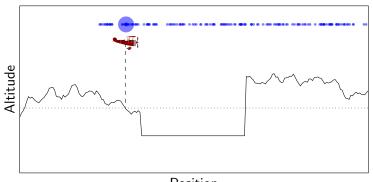


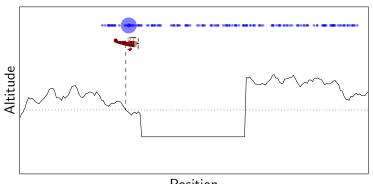


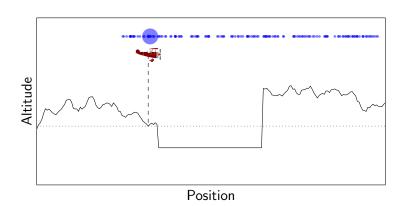


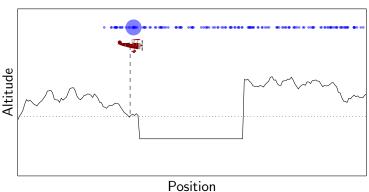


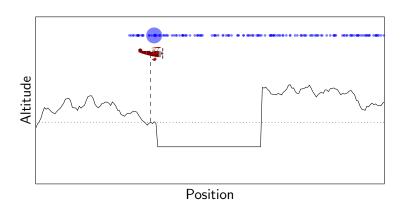


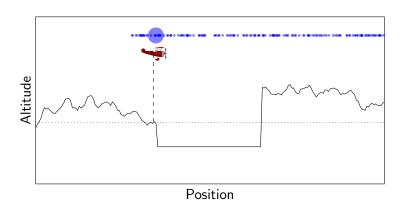


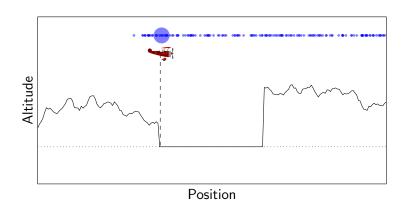


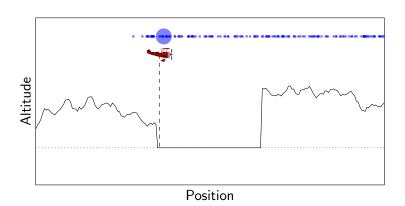


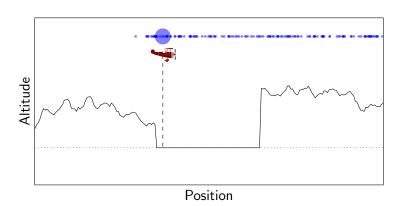


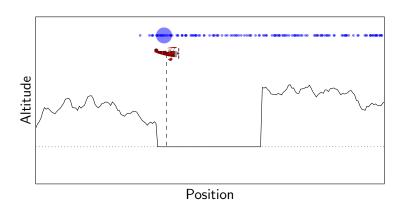


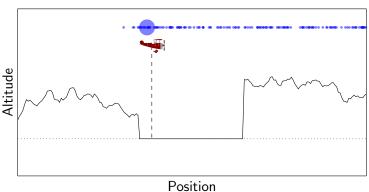


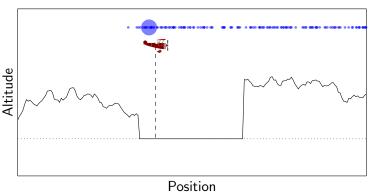


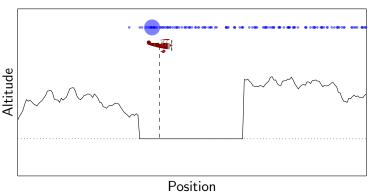


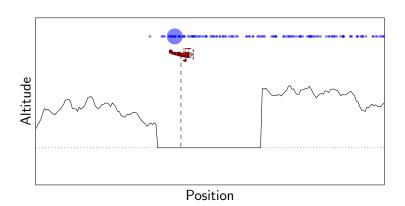




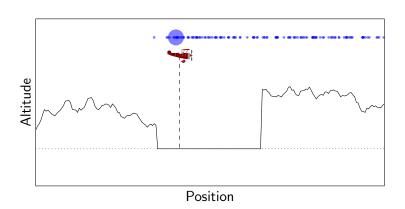


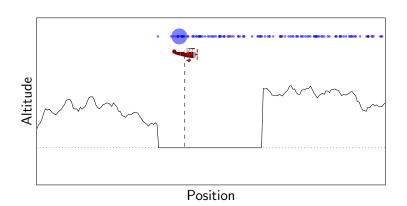


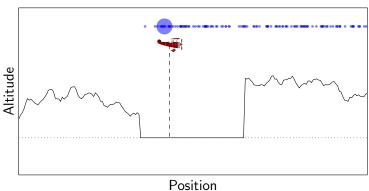


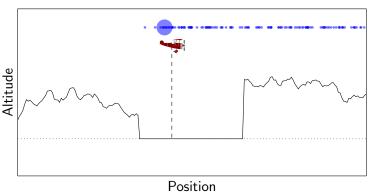


Propagate, weigh

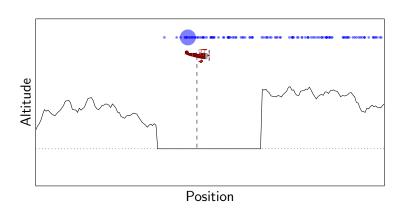




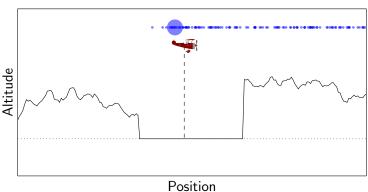




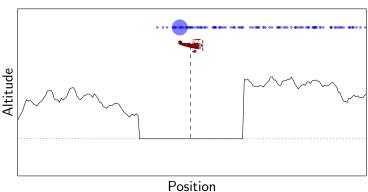
Propagate, weigh

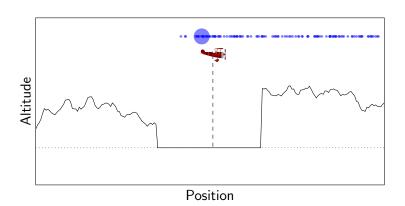


Propagate, weigh

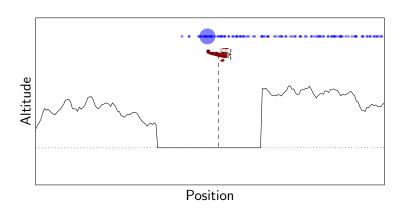


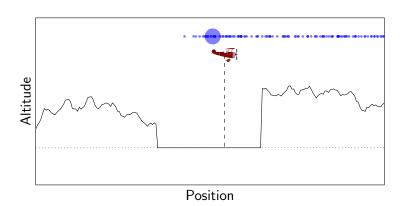
Propagate, weigh



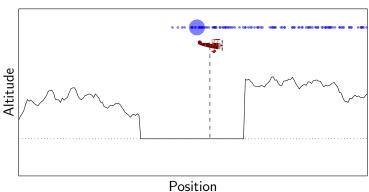


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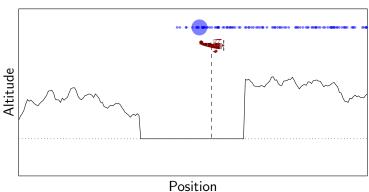


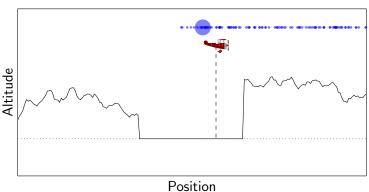


Propagate, weigh

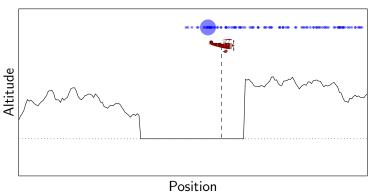


Propagate, weigh

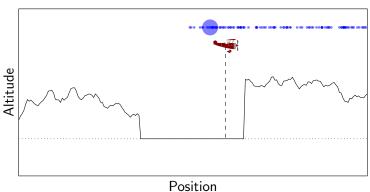


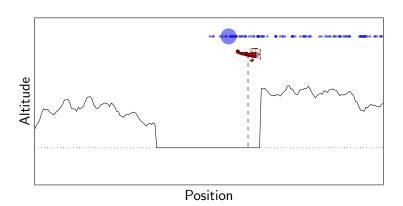


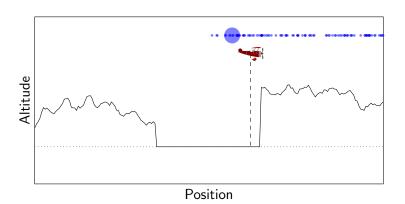
Propagate, weigh

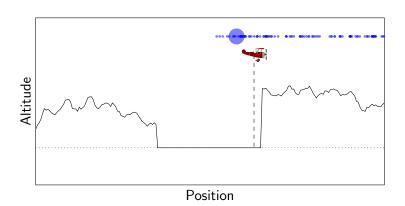


Propagate, weigh

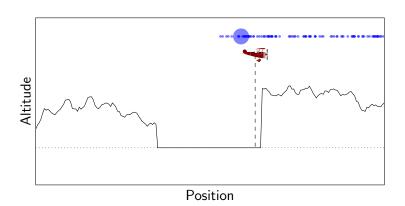




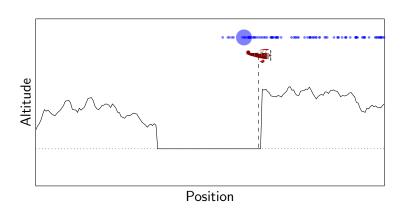


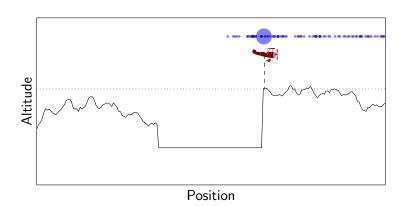


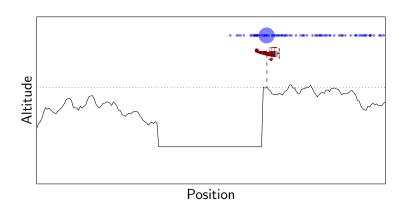
Propagate, weigh



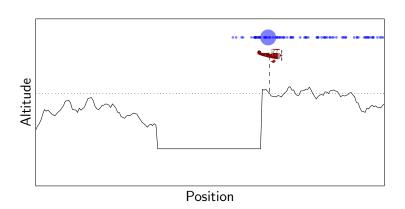
Propagate, weigh

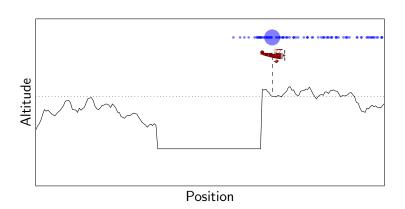


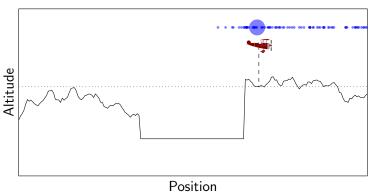


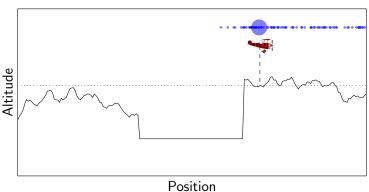


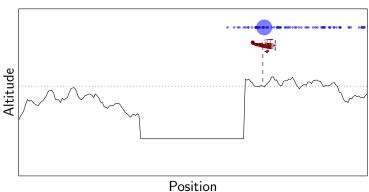
Propagate, weigh



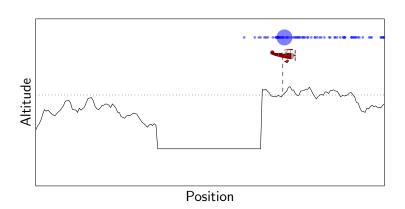


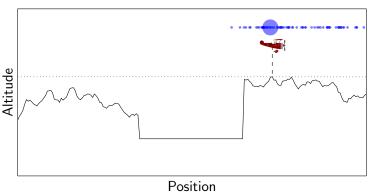




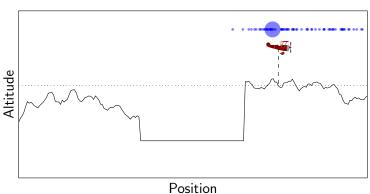


Propagate, weigh

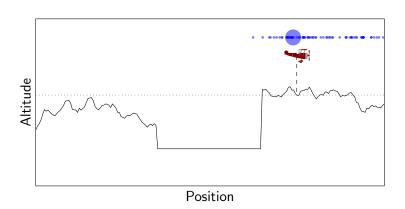


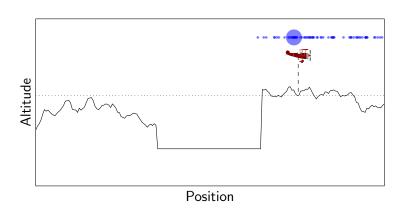


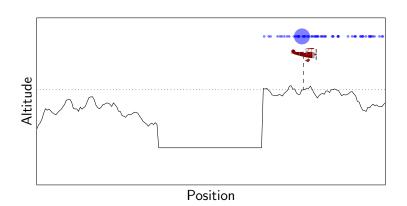
Propagate, weigh

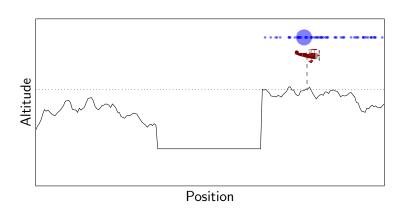


Propagate, weigh

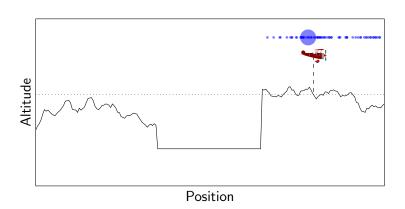


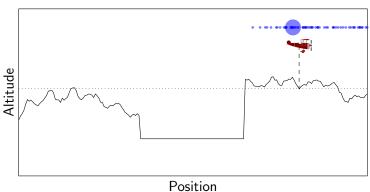


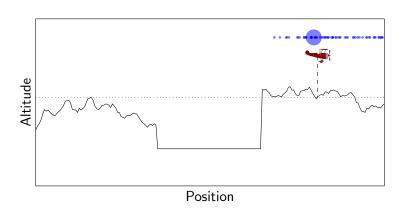


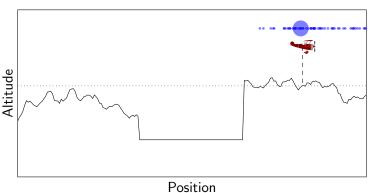


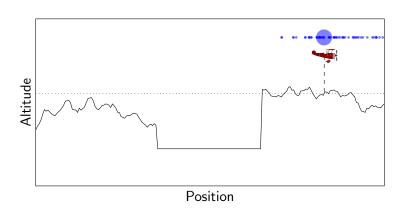
Propagate, weigh

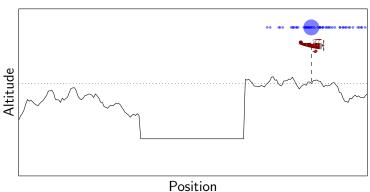


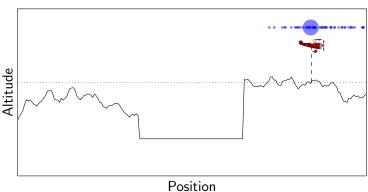


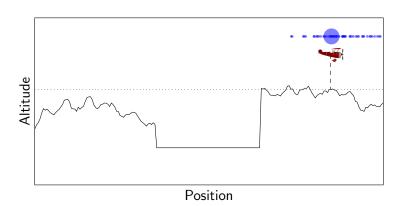


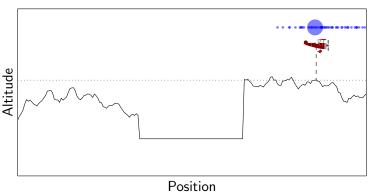


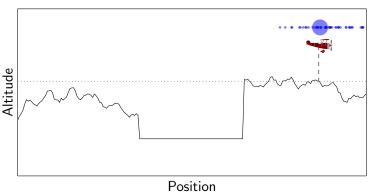


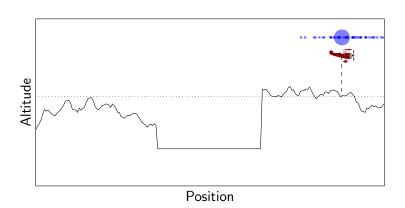


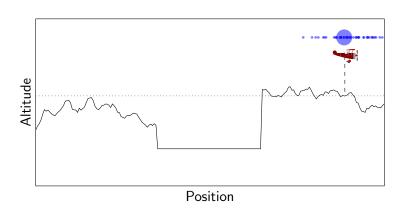


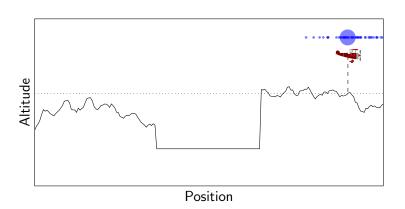


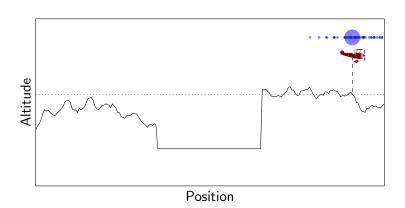


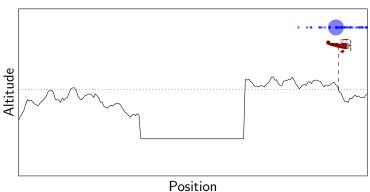


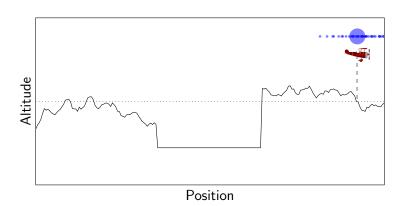


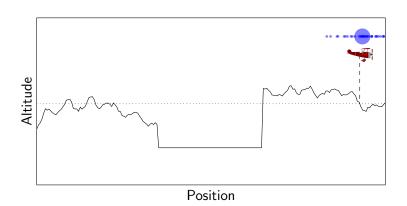




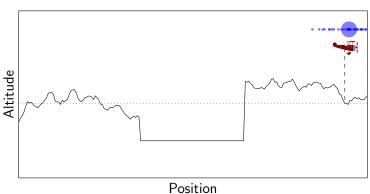


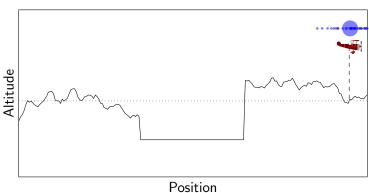




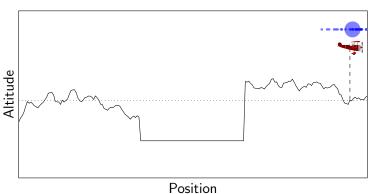


Propagate, weigh

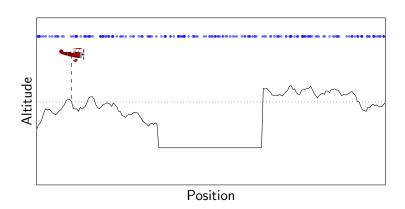




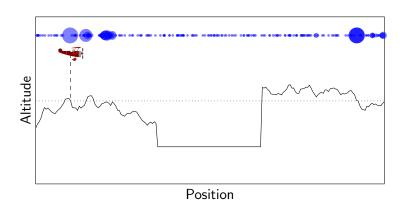
Propagate, weigh



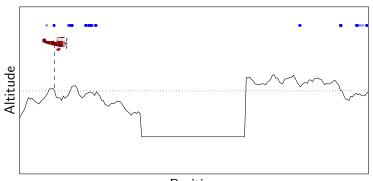
Initialize 200 samples from  $X_0$ 



#### Weigh samples using observation model

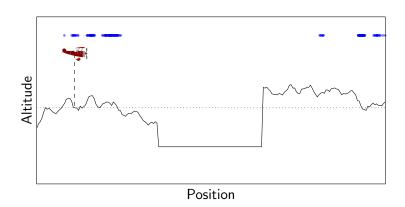


### Resample

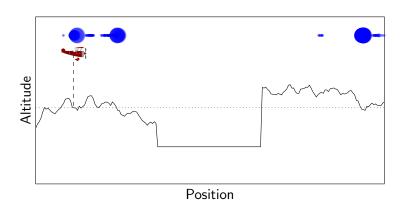


Position

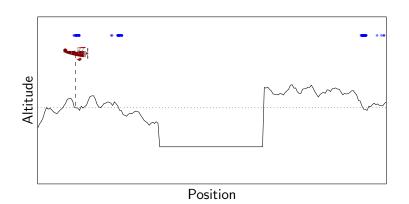
#### Propagate samples using transition model



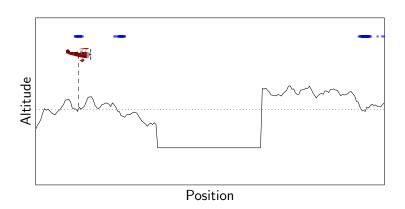
#### Weigh samples using observation model



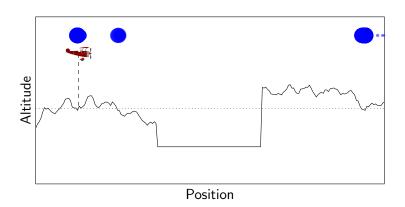
### Resample



#### Propagate samples using transition model



#### Weigh samples using observation model



### Resample

