

Isotropic smoothing of image via Heat equation

import library

```
In [3]: import numpy as np
import matplotlib.image as img
import matplotlib.pyplot as plt
from matplotlib import cm
import matplotlib.colors as colors
from skimage import color
from skimage import io
```

load input image

- filename for the input image is 'barbara_color.jpeg'

```
In [4]: IO = io.imread('barbara_color.jpeg')
```

check the size of the input image

```
In [5]: # *****
# complete the blanks
#
num_row    = IO.shape[0]
num_column = IO.shape[1]
num_channel = IO.shape[2]
#
# *****

print('number of rows of IO = ', num_row)
print('number of columns of IO = ', num_column)
print('number of channels of IO = ', num_channel)

number of rows of IO = 512
number of columns of IO = 512
number of channels of IO = 3
```

convert the color image into a grey image

```
In [6]: # *****
# complete the blanks
#
I = color.rgb2gray(IO)

num_row    = I.shape[0]
num_column = I.shape[1]
#
# *****

print('number of rows of I = ', num_row)
print('number of columns of I = ', num_column)

number of rows of I = 512
number of columns of I = 512
```

normalize the converted image

- normalize the converted grey scale image so that its maximum value is 1 and its minimum value is 0

```
In [7]: # *****
# complete the blanks
#
I = (I - np.min(I))/(np.max(I) - np.min(I))
#
# *****

print('maximum value of I = ', np.max(I))
print('minimum value of I = ', np.min(I))

maximum value of I = 1.0
minimum value of I = 0.0
```

define a function to compute the derivative of input matrix in x(row)-direction

- forward difference: $I[x+1,y] - I[x,y]$

```
In [9]: def compute_derivative_x_forward(I):

    D = np.zeros(I.shape)

    # *****
    # complete the blanks
    # x = row y = column
    # I = [[A],[B],[...],[O]]
    # I_ = [[B],[A],[...],[O]]
    I_ = np.vstack([I[1:], I[:-1]])

    D = I_ - I
    #
    # *****

    return D

• backward difference:  $I[x,y] - I[x-1,y]$ 
```

```
In [10]: def compute_derivative_x_backward(I):

    D = np.zeros(I.shape)

    # *****
    # complete the blanks
    # x = row y = column
    # I = [[A],[B],[...],[O]]
    # I_ = [[A],[B],[...],[O]]
    I_ = np.vstack([I[0], I[:-1]])

    D = I - I_
    #
    # *****

    return D

define a function to compute the derivative of input matrix in y(column)-direction
```

- forward difference: $I[x,y+1] - I[x,y]$

```
In [11]: def compute_derivative_y_forward(I):

    D = np.zeros(I.shape)

    # *****
    # complete the blanks
    #
    I_t = np.transpose(I)
    D_t = np.zeros(I_t.shape)
    I_t = np.vstack([I_t[1:], I_t[:-1]])

    D_t = I_t - I_t
    D = np.transpose(D_t)
    #
    # *****

    return D

• backward difference:  $I[x,y] - I[x,y-1]$ 
```

```
In [12]: def compute_derivative_y_backward(I):

    D = np.zeros(I.shape)
    # *****
    # complete the blanks
    #
    I_t = np.transpose(I)
    D_t = np.zeros(I_t.shape)

    I_ = np.vstack([I_t[0], I_t[:-1]])

    D_t = I_t - I_
    D = np.transpose(D_t)
    #
    # *****

    return D
```

define a function to compute the laplacian of input matrix

- $\Delta I = \nabla^2 I = \frac{\partial^2 I}{\partial x^2} + \frac{\partial^2 I}{\partial y^2}$
- $\Delta I = I[x+1,y] + I[x-1,y] + I[x,y+1] + I[x,y-1] - 4 * I[x,y]$
- $\Delta I = \text{derivative_x_forward} + \text{derivative_x_backward} + \text{derivative_y_forward} + \text{derivative_y_backward}$

```
In [13]: def compute_laplace(I):

    laplace = np.zeros(I.shape)

    # *****
    # complete the blanks
    #
    laplace = compute_derivative_x_forward(I) - compute_derivative_x_backward(I) + compute_derivative_y_forward(I) - compute_derivative_y_backward(I)
    #
    # *****

    return laplace
```

define a function to compute the heat equation of data I with a time step

- $I = I + \delta t * \Delta I$

```
In [14]: def heat_equation(I, time_step):

    I_update = np.zeros(I.shape)

    # *****
    # complete the blanks
    #
    I_update = I + time_step * compute_laplace(I)
    #
    # *****

    return I_update
```

run the heat equation over iterations

```
In [16]: def run_heat_equation(I, time_step, number_iteration):

    I_update = np.zeros(I.shape)

    for t in range(number_iteration):
        # *****
        # complete the blanks
        #
        I = heat_equation(I, time_step)
        #
        # *****

    I_update = I
    return I_update
```

functions for presenting the results

```
In [17]: def function_result_01():

    plt.figure(figsize=(8,6))
    plt.imshow(IO)
    plt.show()

In [18]: def function_result_02():

    plt.figure(figsize=(8,6))
    plt.imshow(I, cmap='gray', vmin=0, vmax=1, interpolation='none')
    plt.show()

In [19]: def function_result_03():

    L = compute_laplace(I)
    plt.figure(figsize=(8,6))
    plt.imshow(L, cmap='gray')
    plt.show()

In [20]: def function_result_04():

    time_step    = 0.25
    I_update     = heat_equation(I, time_step)

    plt.figure(figsize=(8,6))
    plt.imshow(I_update, vmin=0, vmax=1, cmap='gray')
    plt.show()

In [21]: def function_result_05():

    time_step    = 0.25
    number_iteration = 128

    I_update = run_heat_equation(I, time_step, number_iteration)

    plt.figure(figsize=(8,6))
    plt.imshow(I_update, vmin=0, vmax=1, cmap='gray')
    plt.show()

In [22]: def function_result_06():

    time_step    = 0.25
    number_iteration = 512

    I_update = run_heat_equation(I, time_step, number_iteration)

    plt.figure(figsize=(8,6))
    plt.imshow(I_update, vmin=0, vmax=1, cmap='gray')
    plt.show()

In [23]: def function_result_07():

    L = compute_laplace(I)

    value1 = L[0, 0]
    value2 = L[-1, -1]
    value3 = L[100, 100]
    value4 = L[200, 200]

    print('value1 = ', value1)
    print('value2 = ', value2)
    print('value3 = ', value3)
    print('value4 = ', value4)

In [24]: def function_result_08():

    time_step    = 0.25
    I_update     = heat_equation(I, time_step)

    value1 = I_update[0, 0]
    value2 = I_update[-1, -1]
    value3 = I_update[100, 100]
    value4 = I_update[200, 200]

    print('value1 = ', value1)
    print('value2 = ', value2)
    print('value3 = ', value3)
    print('value4 = ', value4)

In [25]: def function_result_09():

    time_step    = 0.25
    number_iteration = 128

    I_update = run_heat_equation(I, time_step, number_iteration)

    value1 = I_update[0, 0]
    value2 = I_update[-1, -1]
    value3 = I_update[100, 100]
    value4 = I_update[200, 200]

    print('value1 = ', value1)
    print('value2 = ', value2)
    print('value3 = ', value3)
    print('value4 = ', value4)

In [26]: def function_result_10():

    time_step    = 0.25
    number_iteration = 512

    I_update = run_heat_equation(I, time_step, number_iteration)

    value1 = I_update[0, 0]
    value2 = I_update[-1, -1]
    value3 = I_update[100, 100]
    value4 = I_update[200, 200]

    print('value1 = ', value1)
    print('value2 = ', value2)
    print('value3 = ', value3)
    print('value4 = ', value4)
```

```

*****
## [RESULT 01]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 02]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 03]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 04]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 05]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 06]
*****
0
100
200
300
400
500
0 100 200 300 400 500

*****
## [RESULT 07]
*****
value1 = 0.3807383220073646
value2 = 0.350344089528004
value3 = -0.12053874833921746
value4 = -0.058957586858053
*****
## [RESULT 08]
*****
value1 = 0.11620040458063048
value2 = 0.15748602906042
value3 = 0.5091846216611501
value4 = 0.592768775993218
*****
## [RESULT 09]
*****
value1 = 0.5809698793594928
value2 = 0.4801111466554692
value3 = 0.366490919303763
value4 = 0.6016268938857371
*****
## [RESULT 10]
*****
value1 = 0.490069282490228
value2 = 0.4078906535948143
value3 = 0.344931493278954
value4 = 0.631389096075725
*****
In [ ]:
In [ ]:
```