

Project 2 Review

Image Morphing

Content



- Overview



- Correspondence



- Triangulation



- Thin Plate Spline



- Midterm Review

Overview

- Goal:
 - Understand and implement two morphing techniques, namely, **Triangulation** and **TPS**.
- Results: (**4 videos** in total)
 - Customized face morphing (YOUR face -> someone's face)
 - One for triangulation, one for TPS
 - 60 frames of animation. (.avi movie)
 - Standard testing morphing (a square consisting of 4 triangles)
 - One for triangulation, one for TPS

Procedure

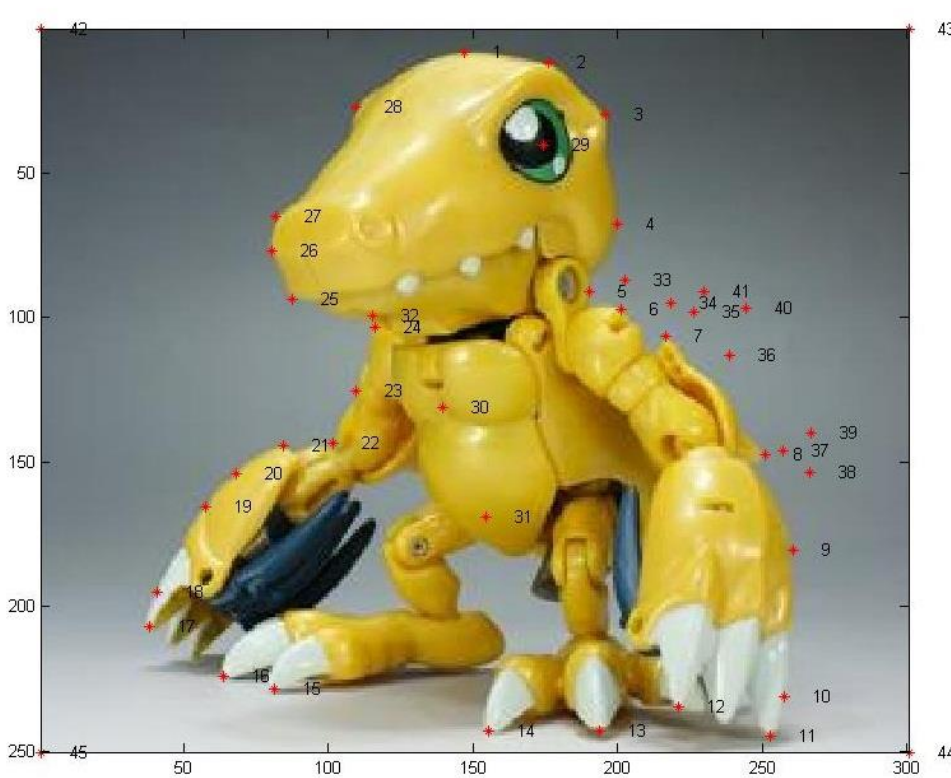
- Task 1: Define Correspondences
 - `[im1_pts, im2_pts] = click_correspondences(im1, im2)`
- Task 2: Image Morph via Triangulation
 - `morphed_im = morph(im1, im2, im1_pts, im2_pts, warp_frac, dissolve_frac);`
- Task 3: Image Morph via Thin Plate Spline
 - `[a1, ax, ay, w] = est_tps(ctr_pts, target_value)`
 - `morphed_im = morph_tps(im_source, a1_x, ax_x, ay_x, w_x, a1_y, ax_y, ay_y, w_y, ctr_pts, sz)`
 - `morphed_im = morph_tps_wrapper(im1, im2, im1_pts, im2_pts, warp_frac, dissolve_frac)`

Example

- (You need a face instead of a cute dinosaur...)

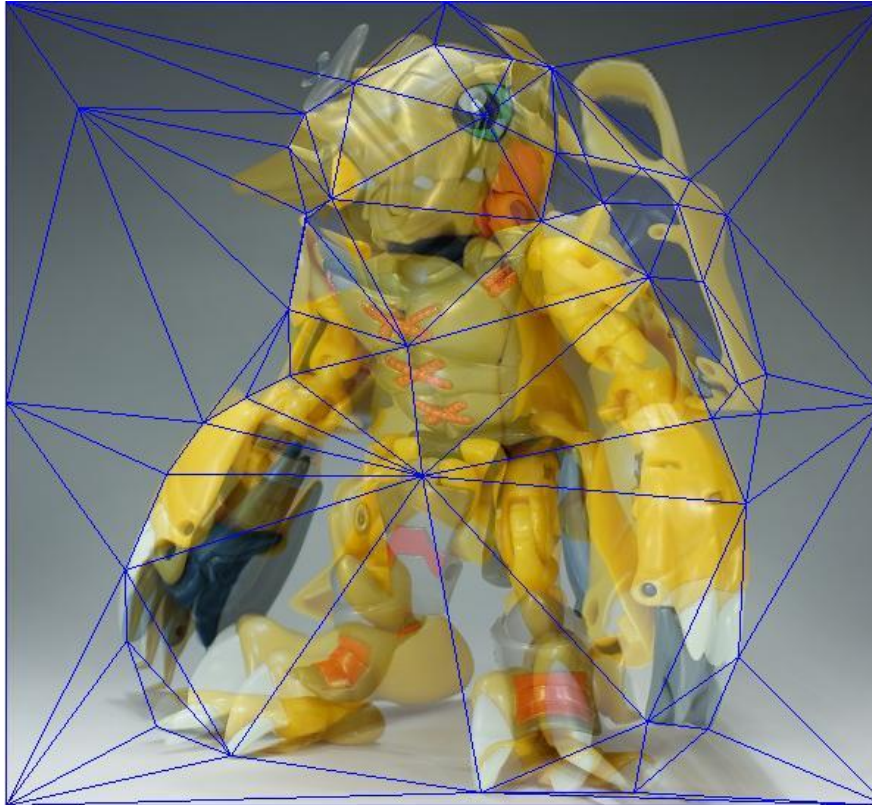


Define Correspondences



- Recommended function: `cpselect(moving, fixed, CPSTRUCT_IN)`

Define Triangular Mesh



- Recommended function: **TRI = delaunay(X,Y)**
- Note: Better to use control points at the midway shape (mean)

Image Morphing

- We know how to warp one image into the other, but how do we create a morphing sequence?
 1. Create an intermediate shape (by interpolation)
 2. Warp both images towards it
 3. Cross-dissolve the colors in the newly warped images

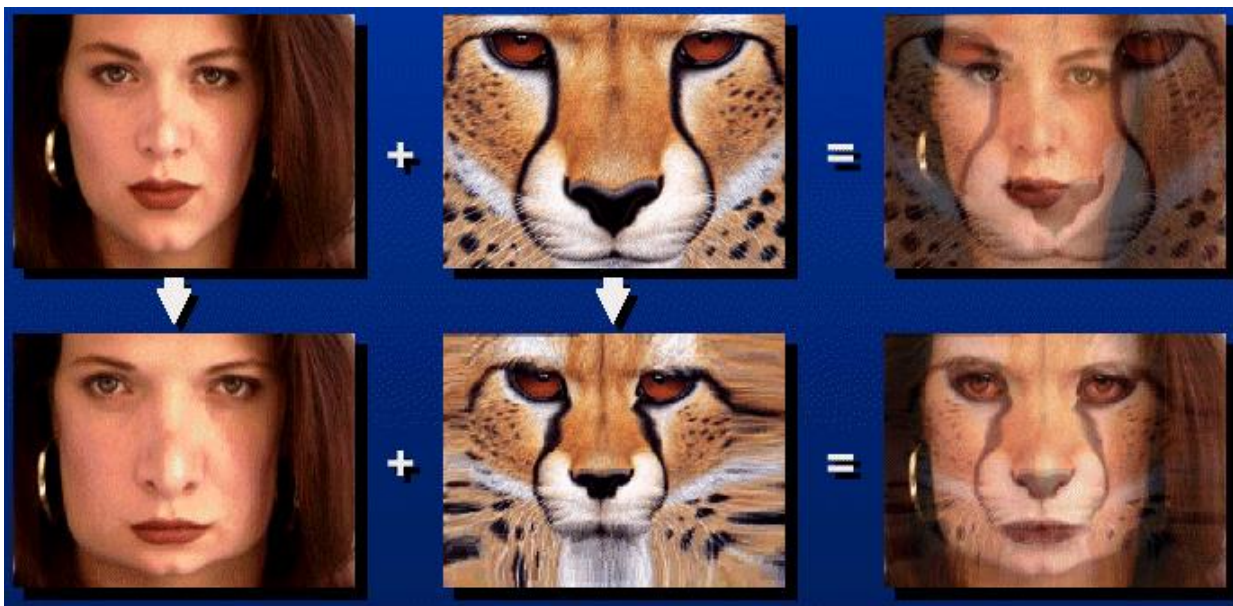
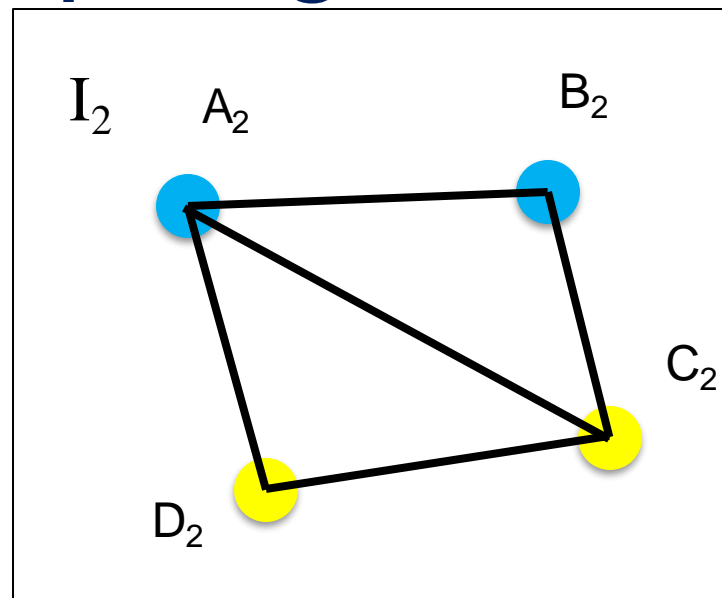
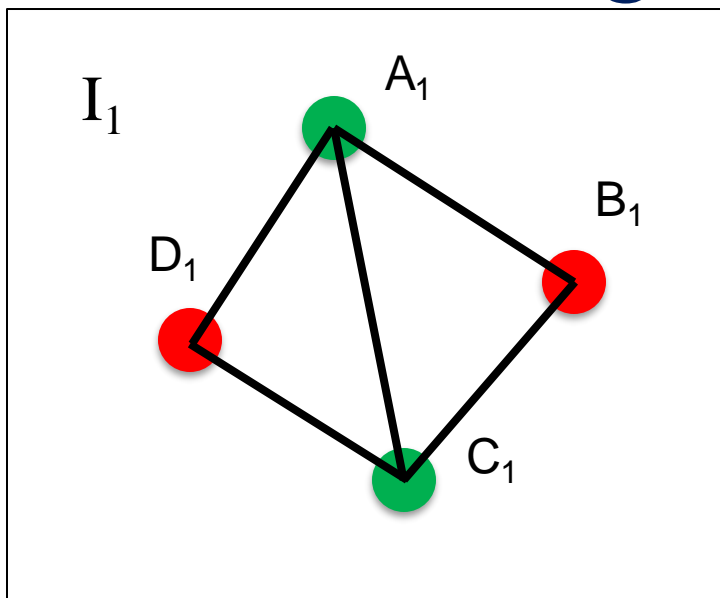
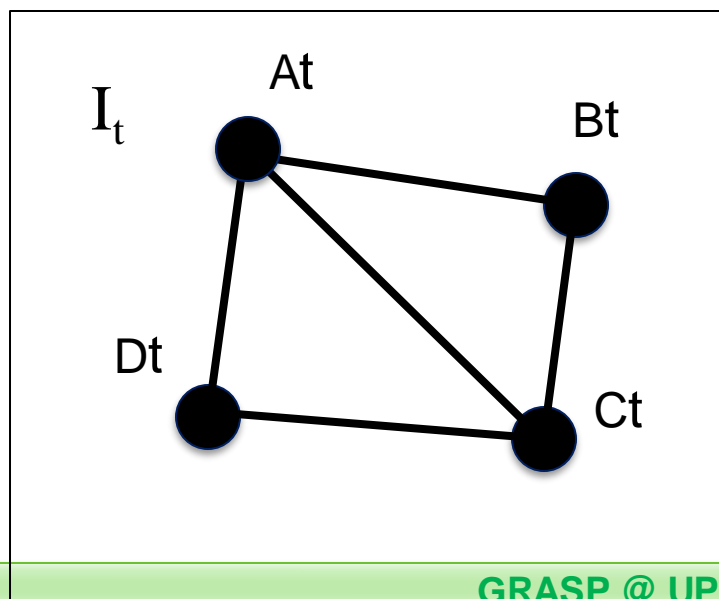
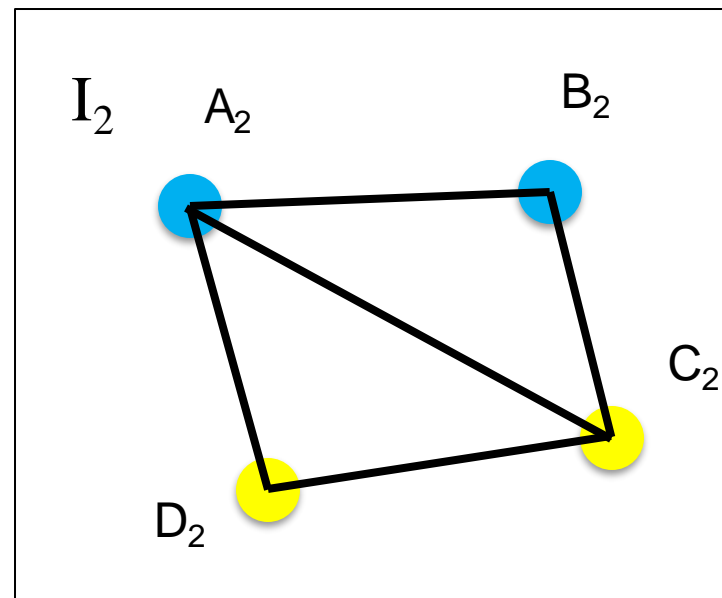
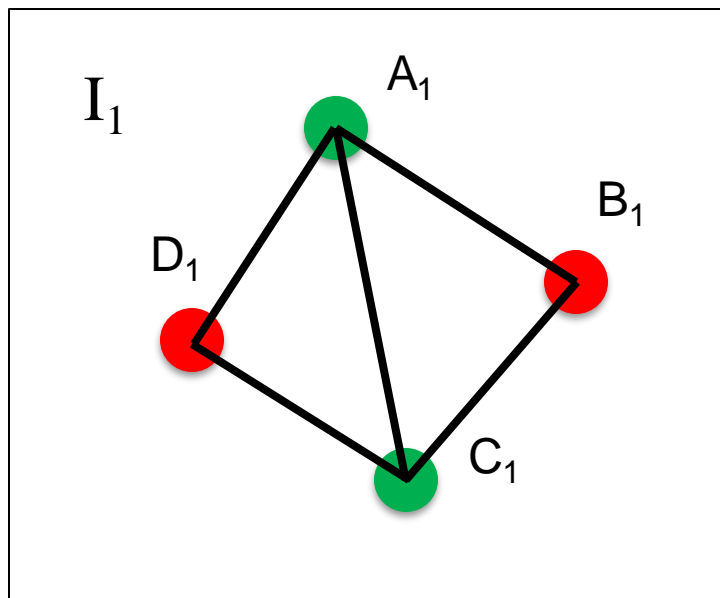


Image Morphing



- Corresponding points:
 - $A_1 - A_2$, $B_1 - B_2$, $C_1 - C_2$, $D_1 - D_2$
- Step1: Create an intermediate shape (by interpolation)
- Step2: Warp both images towards the shape
- Step3: Cross-dissolve the color

Image Morphing: Intermediate Shape



$$\begin{aligned}A_t &= tA_1 + (1 - t)A_2 \\B_t &= tB_1 + (1 - t)B_2 \\C_t &= tC_1 + (1 - t)C_2 \\D_t &= tD_1 + (1 - t)D_2 \\0 &\leq t \leq 1\end{aligned}$$

Image Morphing: Warping

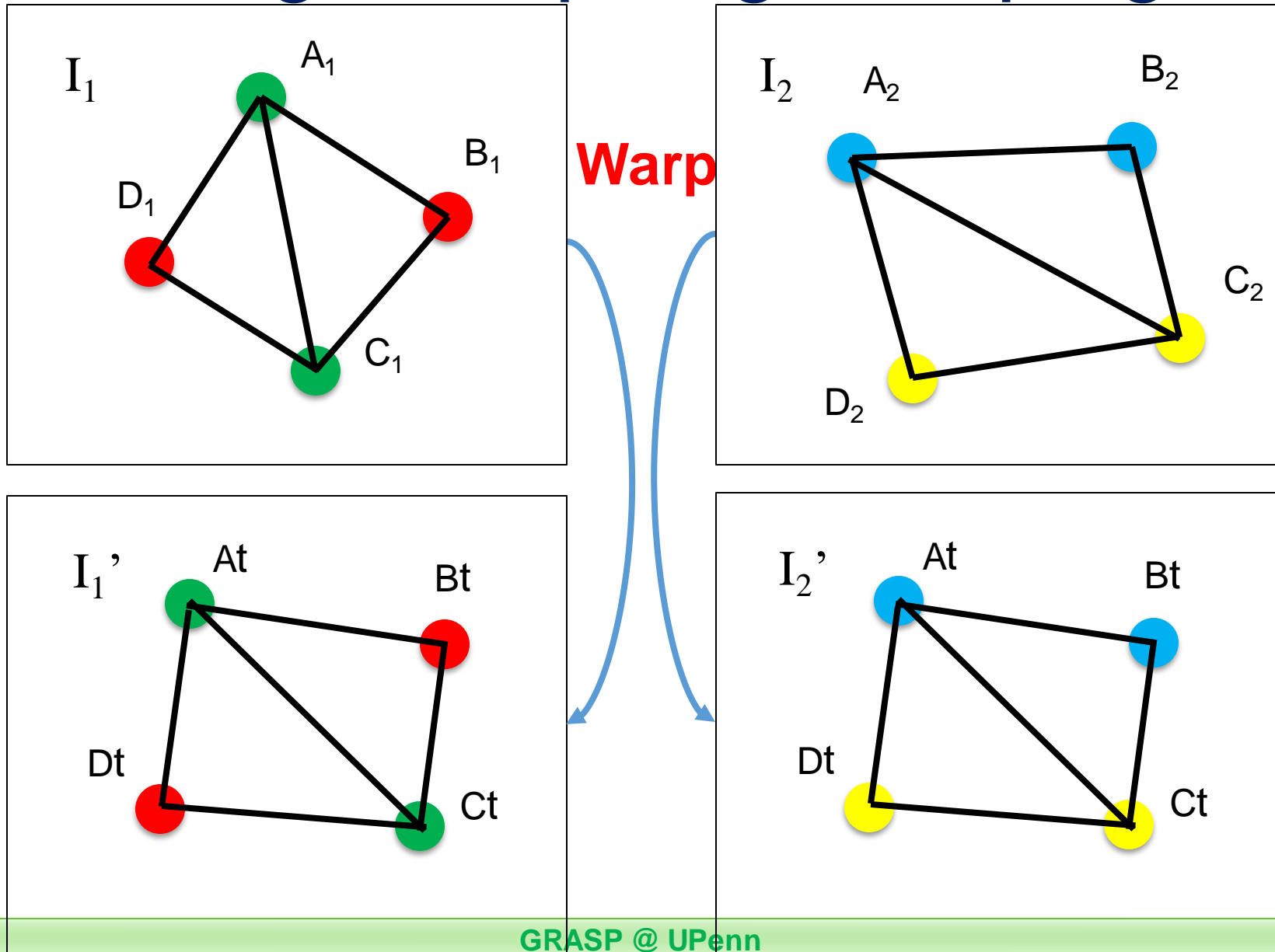
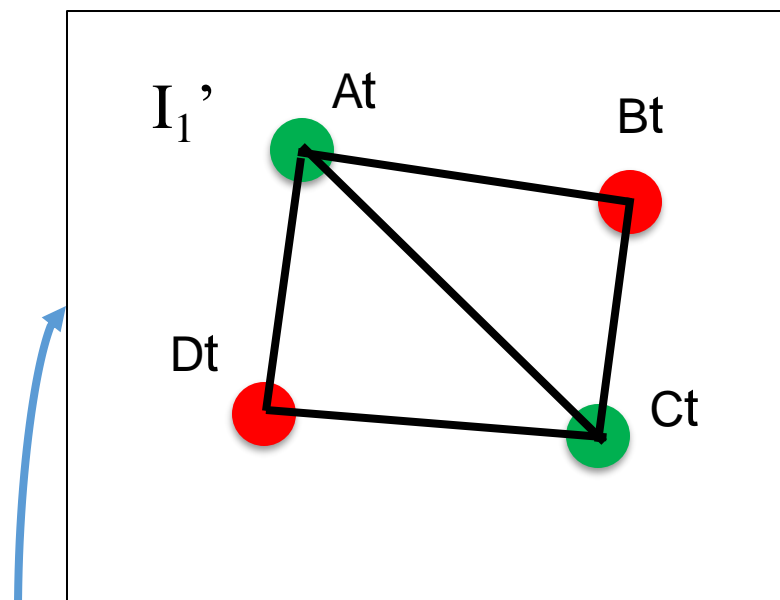
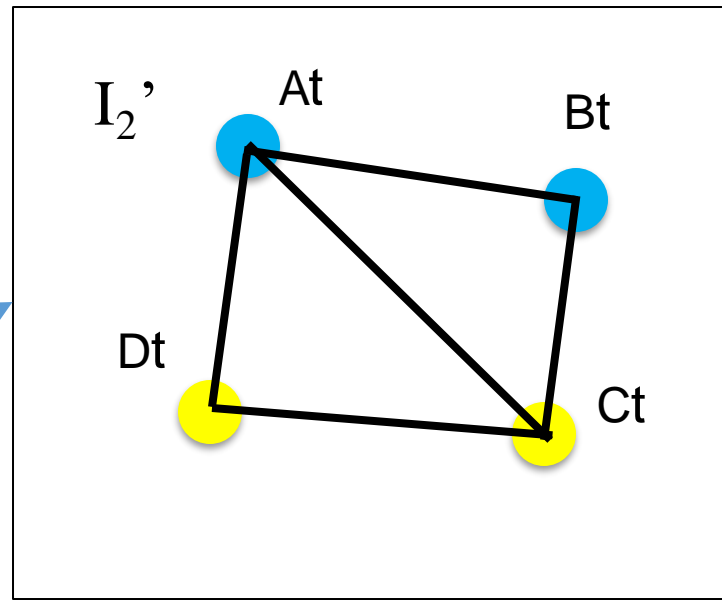
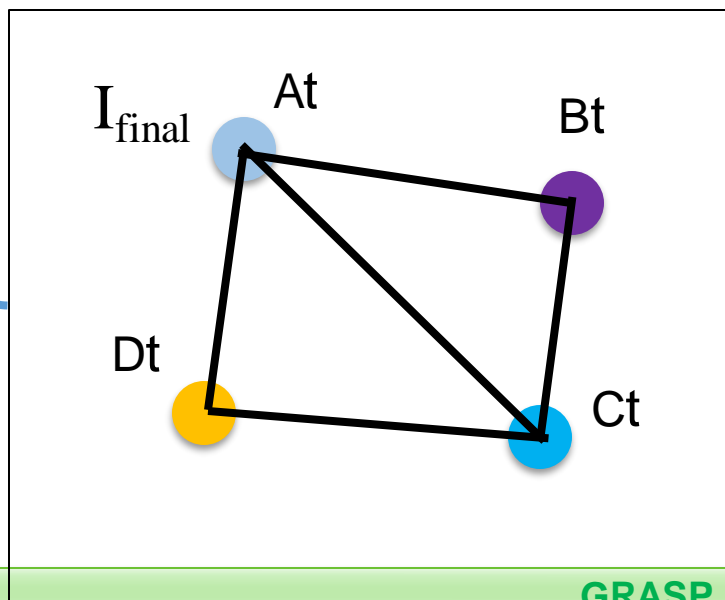


Image Morphing: Cross Dissolve Colors

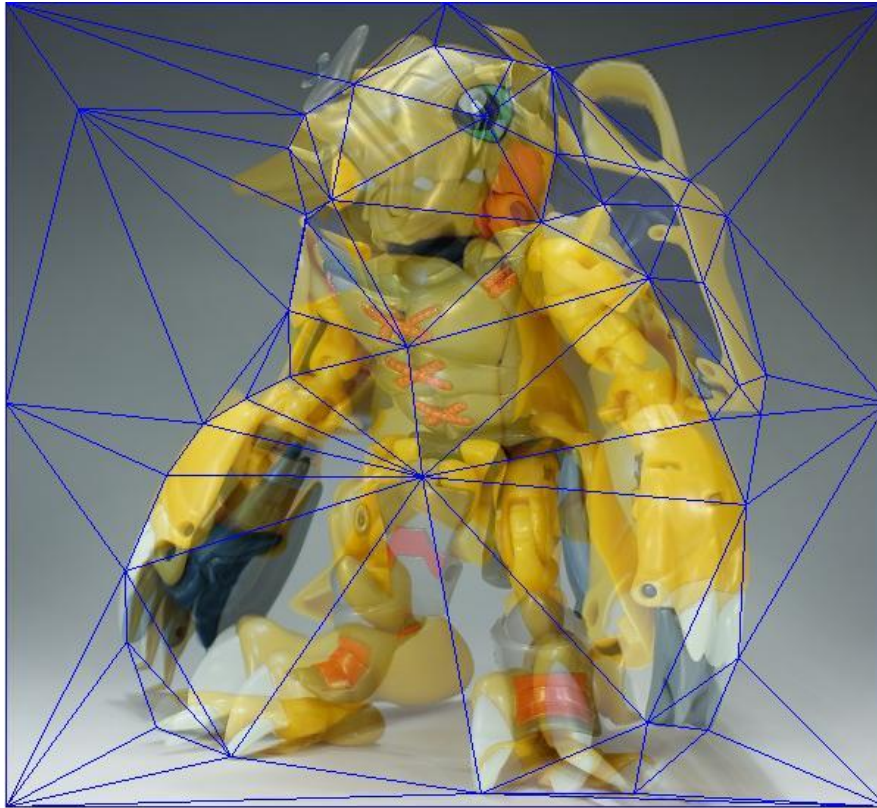
 T^{-1}  T^{-1} 

- Cross-dissolve the colors by **inverse triangle warping**

- A_t : Cyan = Green + Blue
- B_t : Purple = Red + Blue
- C_t : Blue = Green + Yellow
- D_t : Orange = Red + Yellow

Compute Intermediate Shape

- $\text{impoints} = (1 - \text{warpFrac}) * \text{im1points} + \text{warpFrac} * \text{im2points}$;



Compute Barycentric Coordinate

- Find which triangle a point is in:
 - $t = \text{tsearchn}(X, TRI, XI)$
 - Note: You are NOT allowed to use this function directly for barycentric coordinate.
- Compute barycentric coordinate in target image (α, β, γ)
 - Note: compute the inverse matrix for each triangle once.

$$\begin{bmatrix} a_x & b_x & c_x \\ a_y & b_y & c_y \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

Inverse Warping

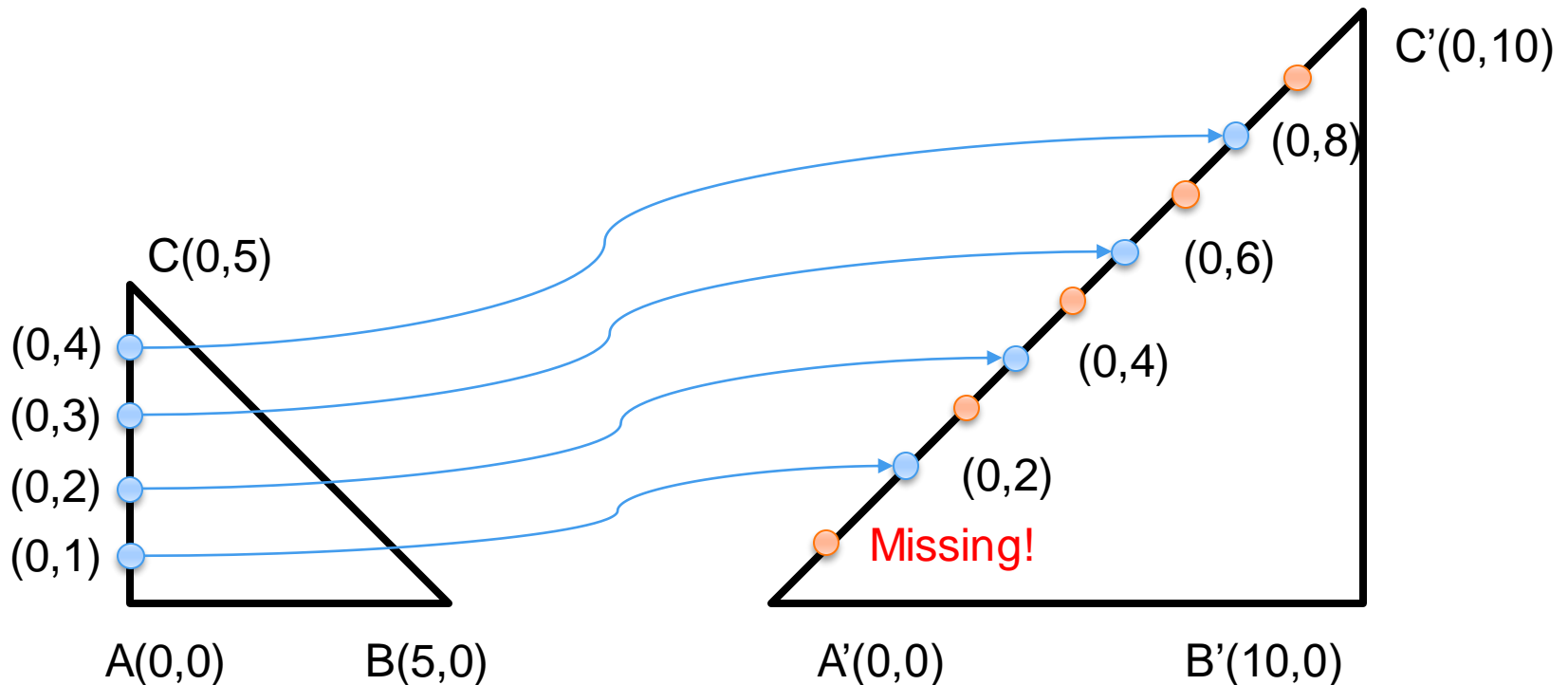
- Use barycentric coordinate to get the pixel values in two source images (im1 & im2)

$$\begin{bmatrix} a_x^s & b_x^s & c_x^s \\ a_y^s & b_y^s & c_y^s \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$$

- Round the pixel location or use **interp2**
- What will happen if you don't use inverse warping?

Forward Warping (Wrong)

- What will happen if you use forward warping?



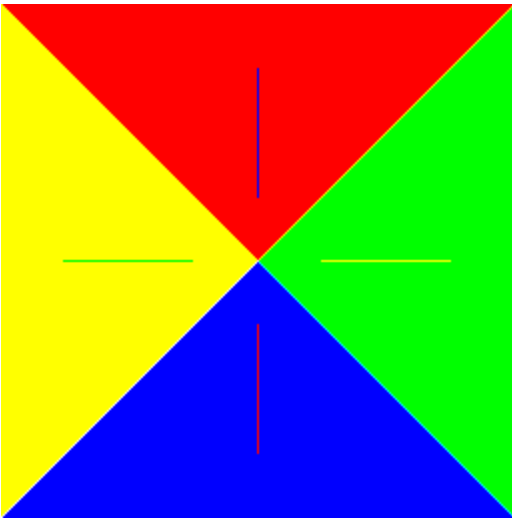
Cross Dissolve

$\text{morphed_im} = (1 - \text{dissolve_frac}) * \text{morphed_im1} + \text{dissolve_frac} * \text{morphed_im2}$

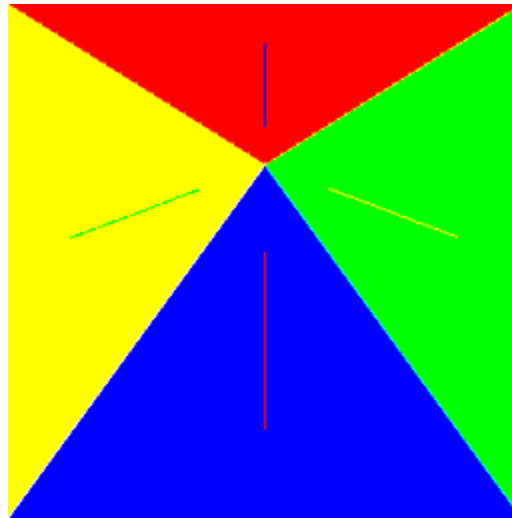


Example

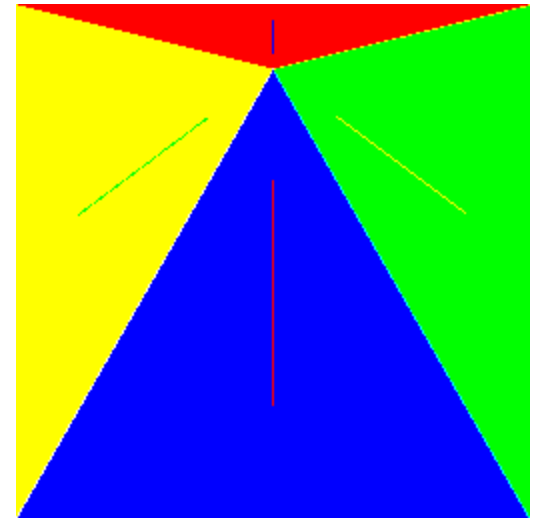
Frac = 0



Frac = 0.5



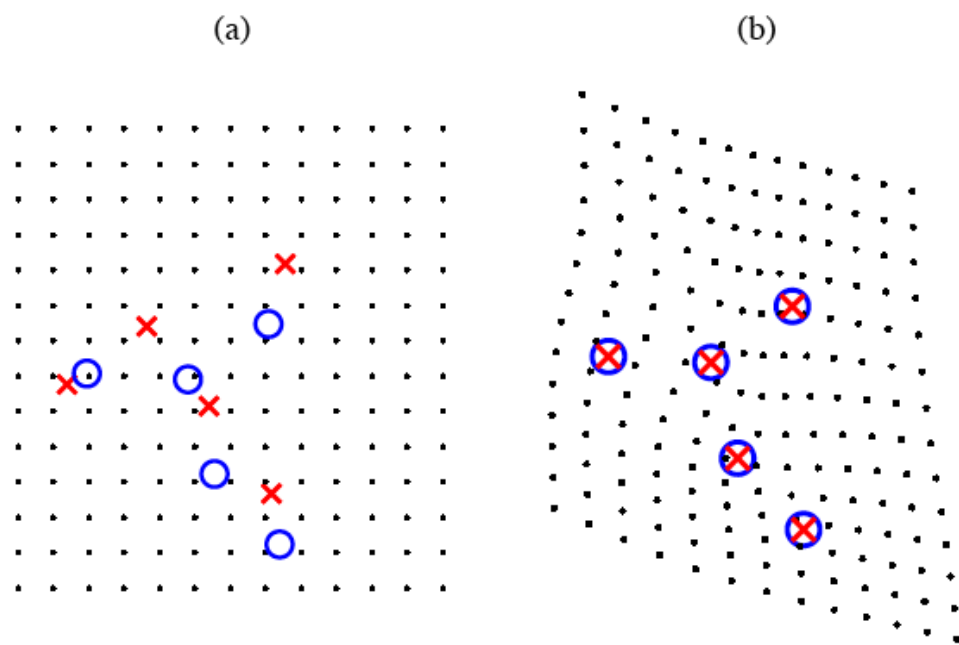
Frac = 1



Last Year's Testing Results

- Triangulation
- <https://www.youtube.com/watch?v=48LHPImEPws>
- TPS
- https://www.youtube.com/watch?v=23S8B38rD_E

Thin Plate Splines



$$\left\{ \begin{array}{l} \forall i \ f_x(x_i, y_i) = x'_i \\ f_x = \operatorname{argmin}_g \left\{ I_g = \int \int_{\mathbb{R}^2} \left(\frac{\partial^2 g}{\partial x^2} \right)^2 + \left(\frac{\partial^2 g}{\partial x \partial y} \right)^2 + \left(\frac{\partial^2 g}{\partial y^2} \right)^2 \right\} \\ f_x(x, y) = v + v_x x + v_y y + \sum_{i=1}^n w_i U(\|(x_i, y_i) - (x, y)\|) \end{array} \right. \quad (17)$$

Compute TPS Coefficients (est_tps)

$$f(x, y) = a_1 + a_x \cdot x + a_y \cdot y + \sum_{i=1}^P W_i U(||(x_i, y_i) - (x, y)||),$$

$$U(r) = r^2 \log(r^2)$$

- Compute two sets of coefficients for x and y:
 - $x' = f_x(x, y)$
 - $y' = f_y(x, y)$
- Note: Take care of $r = 0$.

Compute TPS Coefficients cont.

$$\begin{bmatrix} K & P \\ P^T & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ \dots \\ w_n \\ a_x \\ a_y \\ a_1 \end{bmatrix} = \begin{bmatrix} v_1 \\ v_2 \\ \dots \\ v_n \\ 0 \\ 0 \\ 0 \end{bmatrix},$$

where

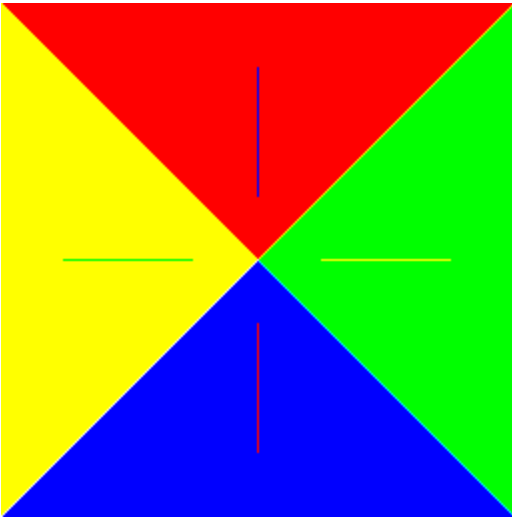
$$K_{ij} = U(\|(x_i, y_i) - (x_j, y_j)\|),$$

$$\begin{bmatrix} w_1 \\ w_2 \\ \dots \\ w_n \\ a_x \\ a_y \\ a_1 \end{bmatrix} = inv\left(\begin{bmatrix} K & P \\ P^T & 0 \end{bmatrix} + \lambda * I(n+3, n+3)\right) \begin{bmatrix} v_1 \\ v_2 \\ \dots \\ v_n \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

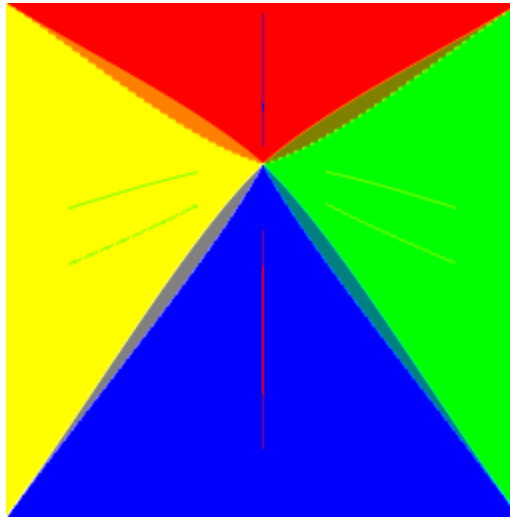
- Note: λ should be very small.

Example

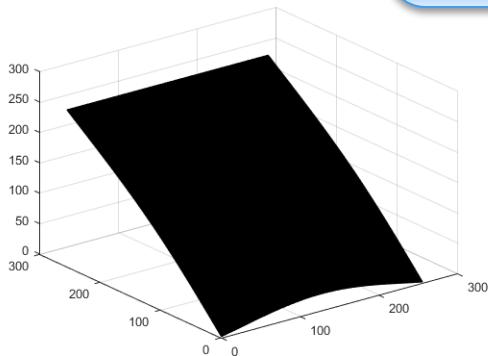
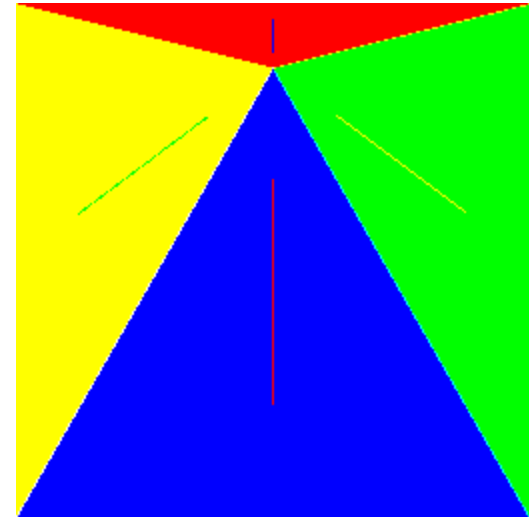
Frac = 0



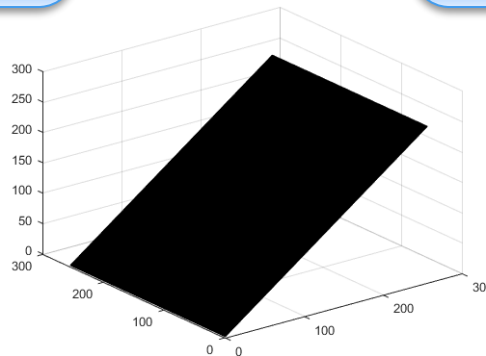
Frac = 0.5



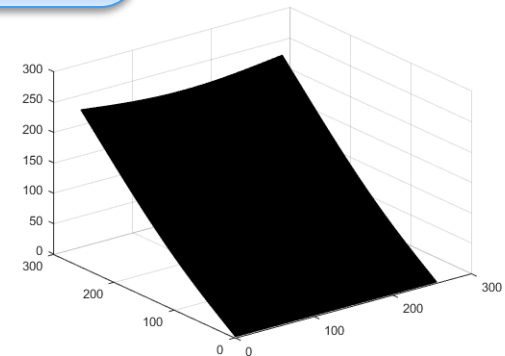
Frac = 1



X surface



Y unchanged



X surface

Last Year's Testing Results

- Triangulation
- <https://www.youtube.com/watch?v=48LHPImEPws>
- TPS
- https://www.youtube.com/watch?v=23S8B38rD_E

Generate Customized Videos

1. VideoWriter

- `video = VideoWriter(filename, 'Uncompressed AVI');`
- `video.FrameRate = framerate;`
- `video.open();`
- `video.writeVideo(image);`
- `video.close();`

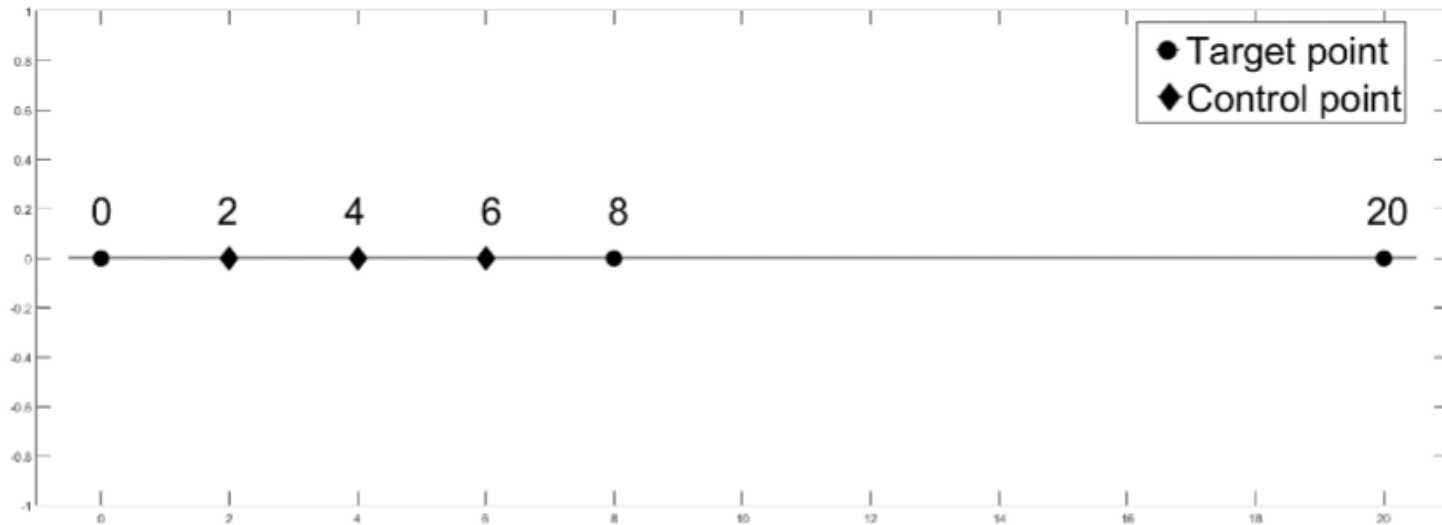
2. avifile

- `video = avifile(filename, 'FPS', framerate);`
- `video = addframe(video, image);`
- `video = close(video);`

Common Mistakes

- Image array data type: should be uint8 -> double -> uint8
- Mess up the coordinate (flip x and y)
- Inconsistent correspondences
- Boundary issue
 - How to deal with points outside of boundaries?
- Forget inverse warping
- λ in TPS is not well chosen

2015 Midterm Review (TPS)



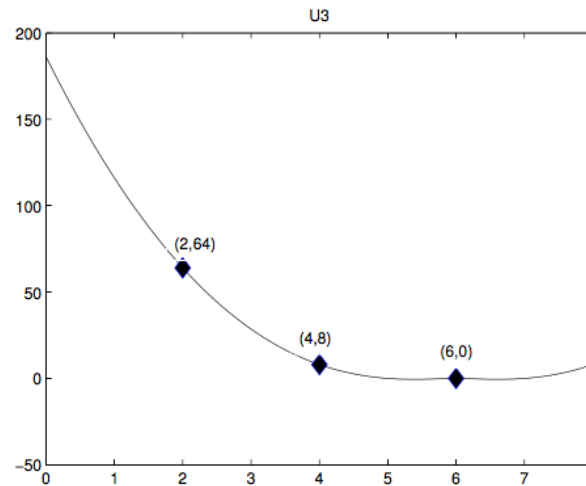
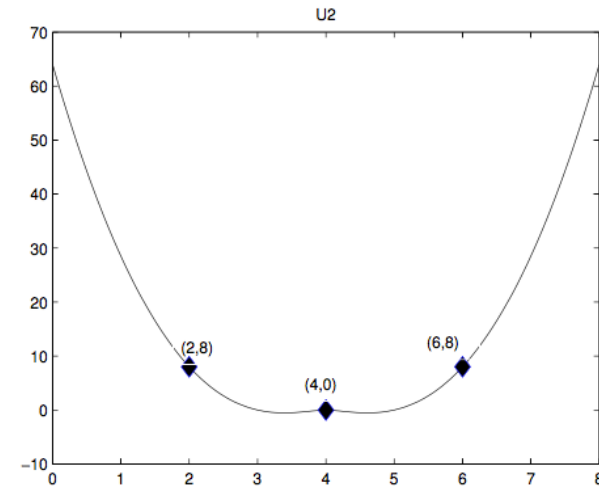
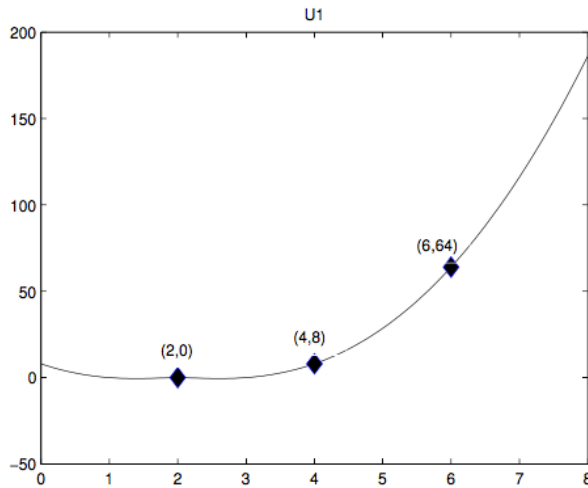
Consider the plot above. We want to find a function that maps the control points to the target points (2 to 0, 4 to 8, 6 to 20). Our model will be:

$$f(x) = \sum_{i=1}^3 w_i U_i(x)$$

Where the U_i are basis functions given by the plots below and the w_i are the parameters in the model. (Note that the affine terms that would be present in a TPS model have been removed to reduce the number of variables)

Solve for w_1 , w_2 , and w_3 .

2015 Midterm Review (TPS) cont.



2015 Midterm Review (TPS) sol.

$$f(2) = w_1 U_1(2) + w_2 U_2(2) + w_3 U_3(2) = 0w_1 + 8w_2 + 64w_3 = 0$$

$$f(4) = w_1 U_1(4) + w_2 U_2(4) + w_3 U_3(4) = 8w_1 + 0w_2 + 8w_3 = 8$$

$$f(6) = w_1 U_1(6) + w_2 U_2(6) + w_3 U_3(6) = 64w_1 + 8w_2 + 0w_3 = 20$$

$$\begin{bmatrix} 0 & 8 & 64 \\ 8 & 0 & 8 \\ 64 & 8 & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 8 \\ 20 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \rightarrow \mathbf{w} = \left[\frac{21}{32} \quad -\frac{11}{4} \quad \frac{11}{32} \right]^\top$$