

2020.10.9

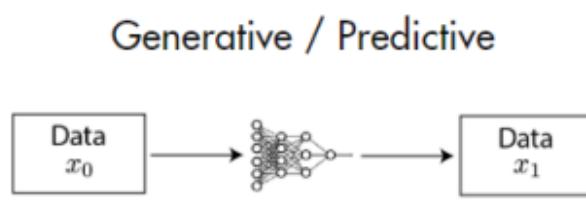
Paper Sharing (Rec)

S³-Rec:

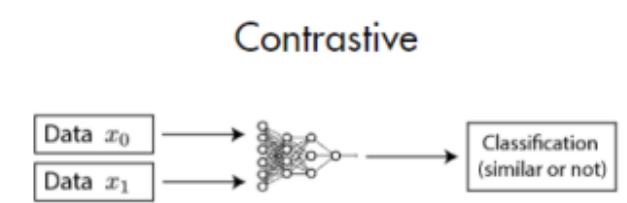
- Self-Supervised Learning for Sequential Recommendation with Mutual Information Maximization, CIKM 2020
 - Self-Supervised – Learning from intrinsic structure of raw data
- Contrastive Learning
 - A Simple Framework for Contrastive Learning of Visual Representations, ICML 2020
 - Understanding Contrastive Representation Learning through Alignment and Uniformity on the Hypersphere, ICML 2020

Contrastive Learning

- Self-Supervised

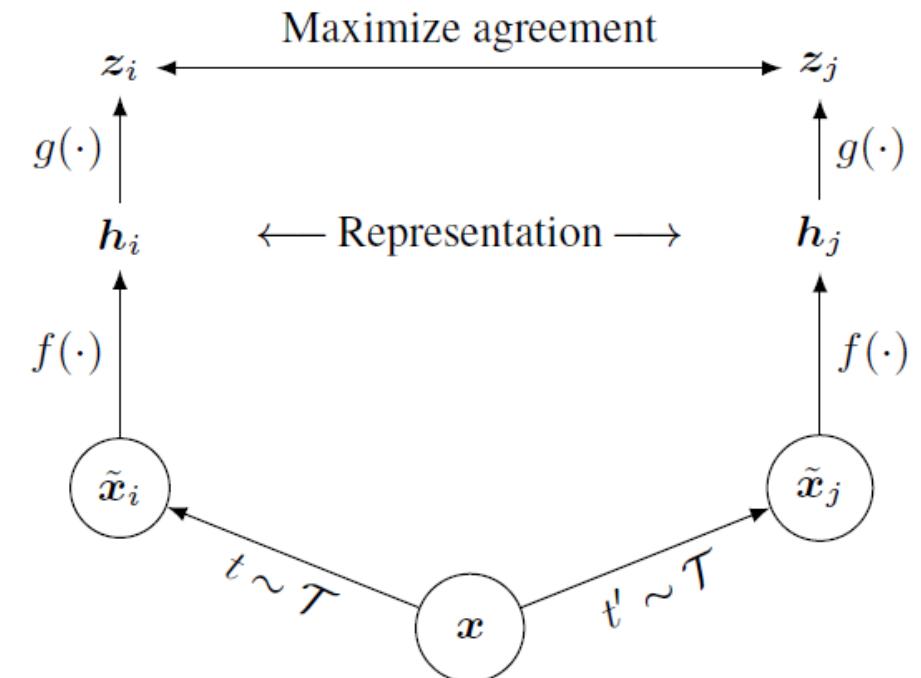


Loss measured in the output space
Examples: Colorization, Auto-Encoders



Loss measured in the representation space
Examples: TCN, CPC, Deep-InfoMax

- SimCLR



Contrastive learning



(a) Original



(b) Crop and resize



(c) Crop, resize (and flip)



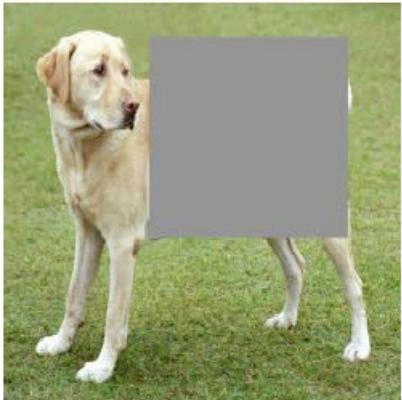
(d) Color distort. (drop)



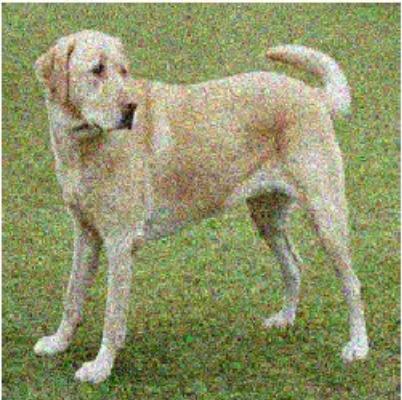
(e) Color distort. (jitter)



(f) Rotate $\{90^\circ, 180^\circ, 270^\circ\}$



(g) Cutout



(h) Gaussian noise



(i) Gaussian blur



(j) Sobel filtering

S^3 -Rec:

- Objective - Mutual Information Maximization

$$I(X, Y) = H(X) - H(X|Y) = H(Y) - H(Y|X)$$

- Given two random variables X and Y, it can be understood as how much knowing X reduces the uncertainty in Y or vice versa.
- Intractable – find a lower bound(InfoNCE)

- Base Model (Transformer?)

- Embedding Layer
- Self-Attention Block (Bidirectional)
- Prediction Layer

- 4 task

- Associated Attribute Prediction
- Masked Item Prediction
- Masked Attribute Prediction
- Segment Prediction

S³-Rec:

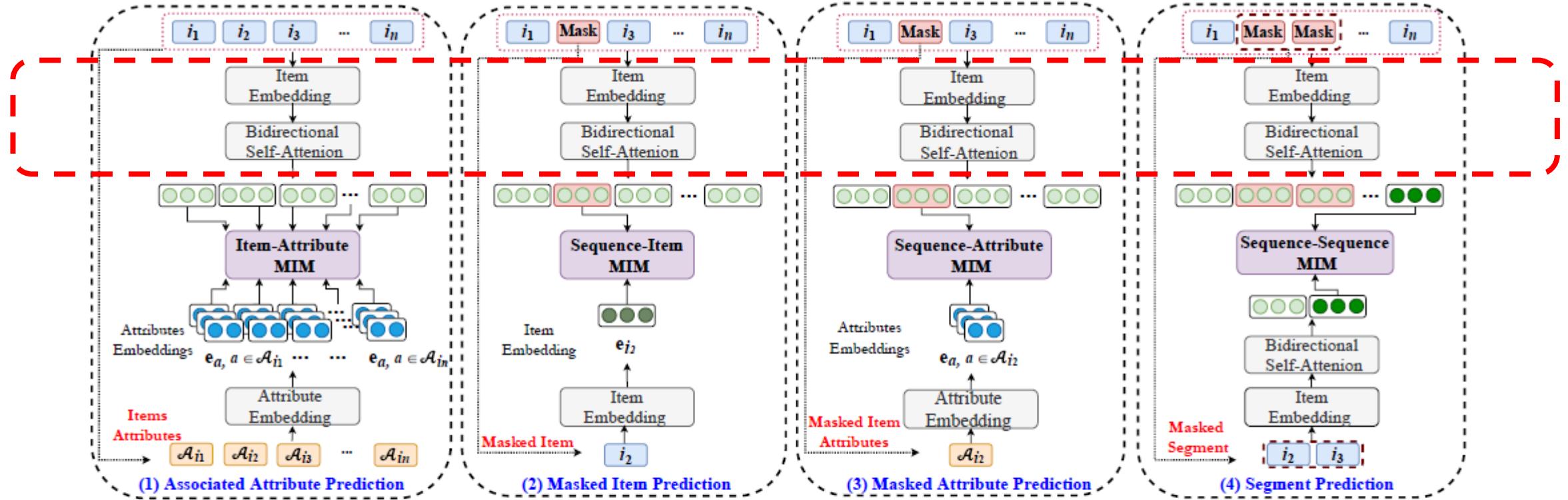


Figure 1: The overview of S³-Rec in the pre-training stage. We assume that the user sequence is $\{i_1, \dots, i_n\}$ and each item i is associated with several attributes $\mathcal{A}_i = \{a_1, \dots, a_m\}$. We incorporate four self-supervised learning objectives: (1) Associated Attribute Prediction (AAP), (2) Masked Item Prediction (MIP), (3) Masked Attribute Prediction (MAP), and (4) Segment Prediction (SP). The embedding layers and bidirectional self-attention blocks are shared by the four pre-training objectives.

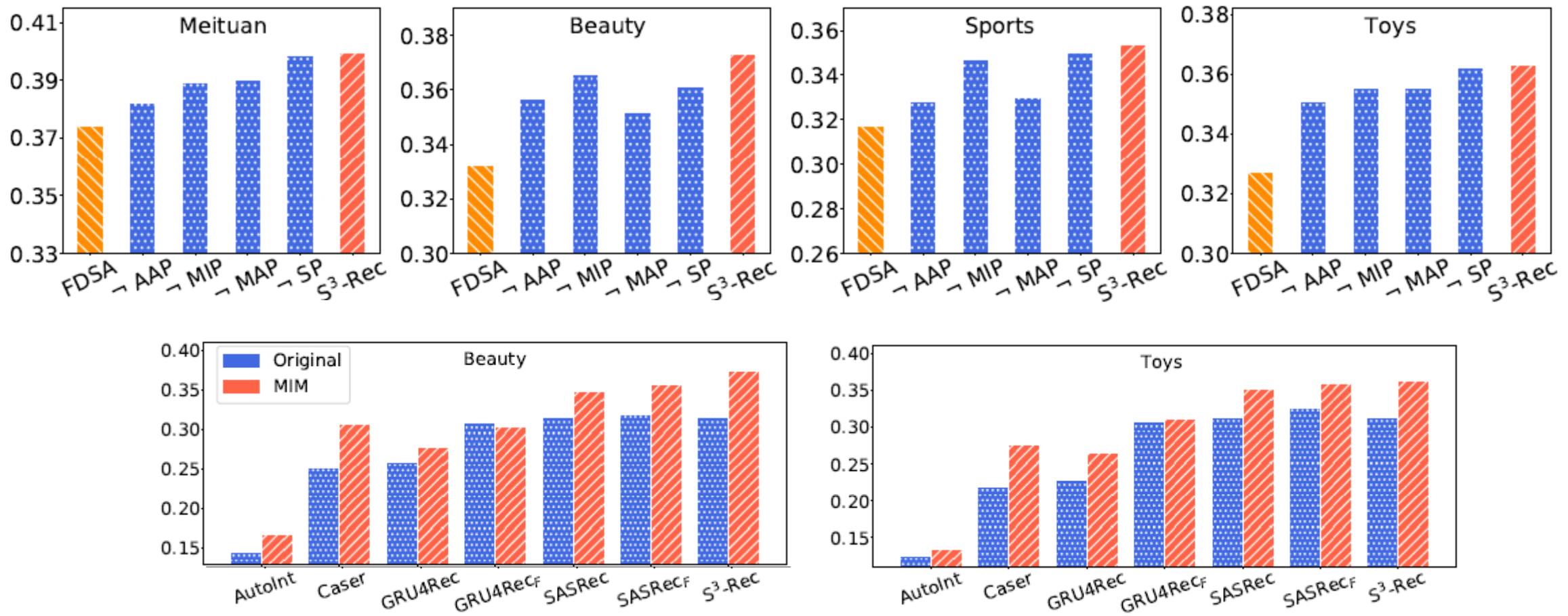
S^3 -Rec:

- Experiment
 - Dataset: Meituan(6 years in Beijing), Amazon, Yelp, LastFM
 - “we only keep the 5-core datasets, and filter unpopular items and inactive users with fewer than five interaction records”

Datasets	Metric	PopRec	FM	AutoInt	GRU4Rec	Caser	SASRec	BERT4Rec	HGN	GRU4Rec _F	SASRec _F	FDSA	S^3 -Rec	Improv.
Meituan	HR@1	0.0946	0.1084	0.0804	0.1194	0.1368	<u>0.1797</u>	0.1381	0.1603	0.1436	0.1746	0.1778	0.2040*	13.52%
	HR@5	0.2660	0.3218	0.2662	0.3382	0.3812	0.4524	0.3985	0.4110	0.3799	0.4386	<u>0.4595</u>	0.4925*	7.18%
	NDCG@5	0.1813	0.2170	0.1739	0.2303	0.2619	0.3207	0.2713	0.2887	0.2639	0.3098	<u>0.3236</u>	0.3527*	8.99%
	HR@10	0.3863	0.4709	0.4077	0.4881	0.5267	0.6053	0.5514	0.5573	0.5378	0.5962	<u>0.6164</u>	0.6368*	3.31%
	NDCG@10	0.2200	0.2651	0.2194	0.2787	0.3090	0.3700	0.3208	0.3359	0.3149	0.3607	<u>0.3743</u>	0.3994*	6.71%
	MRR	0.1923	0.2242	0.1854	0.2359	0.2617	0.3146	0.2689	0.2863	0.2666	0.3064	<u>0.3167</u>	0.3421*	8.02%
Yelp	HR@1	0.0801	0.0624	0.0731	0.2053	0.2188	0.2375	0.2405	<u>0.2428</u>	0.2293	0.2301	0.2198	0.2591*	6.71%
	HR@5	0.2415	0.2036	0.2249	0.5437	0.5111	0.5745	<u>0.5976</u>	0.5768	0.5858	0.5937	0.5728	0.6085*	1.82%
	NDCG@5	0.1622	0.1333	0.1501	0.3784	0.3696	0.4113	<u>0.4252</u>	0.4162	0.4137	0.4178	0.4014	0.4401*	3.50%
	HR@10	0.3609	0.3153	0.3367	0.7265	0.6661	0.7373	<u>0.7597</u>	0.7411	0.7574	<u>0.7706</u>	0.7555	0.7725	0.25%
	NDCG@10	0.2007	0.1692	0.1860	0.4375	0.4198	0.4642	<u>0.4778</u>	0.4695	0.4694	0.4751	0.4607	0.4934*	3.26%
	MRR	0.1740	0.1470	0.1616	0.3630	0.3595	0.3927	<u>0.4026</u>	0.3988	0.3929	0.3962	0.3834	0.4190*	4.07%

S^3 -Rec

- Ablation study



Recent reading

- Deconstructing the Filter Bubble: User Decision-Making and Recommender Systems
 - Debiasing Item-to-Item Recommendations With Small Annotated Datasets
 - ~~Few-shot~~ => In its design, IPS learning only requires a small annotated dataset
 - Unbiased Ad Click Prediction for Position-aware Advertising Systems
 - Imputation model for unrevealed
 - Bias from observation
 - Inverse Propensity Score(IPS) - $1/P(O=1|U,V)$
 - $P(C,U,V,O=1) = P(C|U,V,O=1) P(U,V,O=1)$
 $= P(C|U,V,O=1) P(U,V) P(O=1|U,V)$
- $P(O=1|U,V)$ is not uniform