

Paper Sharing

- *LRC-BERT*: Latent-representation Contrastive Knowledge Distillation for Natural Language Understanding
- Logic-guided Semantic Representation Learning for Zero-Shot Relation Classification
- *LayoutLMv2*: Multi-modal Pre-training for Visually-Rich Document Understanding

—2021/01/21 朱静丹

LRC-BERT: Latent-representation Contrastive Knowledge Distillation for Natural Language Understanding

**Hao Fu,^{1*} Shaojun Zhou,^{2*} Qihong Yang,² Junjie Tang,^{2†} Guiquan Liu,¹
Kaikui Liu,² Xiaolong Li²**

¹School of Computer Science and Technology, University of Science and Technology of China

²Alibaba Group

hfu@mail.ustc.edu.cn, {zsj148798, xiaokui.yqh, lixi.tjj}@alibaba-inc.com, gqliu@ustc.edu.cn,
{damon, xl.li}@alibaba-inc.com

——高德(AAAI2021)

The contributions of this paper:

- They propose a **knowledge distillation** method **LRC-BERT** based on **contrastive learning** .
- A new contrastive loss **COS-NCE** is proposed to effectively capture the structural characteristics between different samples.
- They introduce a **gradient perturbation-based training architecture** in the training phase to increase the **robustness** of LRC-BERT.
- They design a **two stage** training method for the total distillation loss.

Background

模型压缩

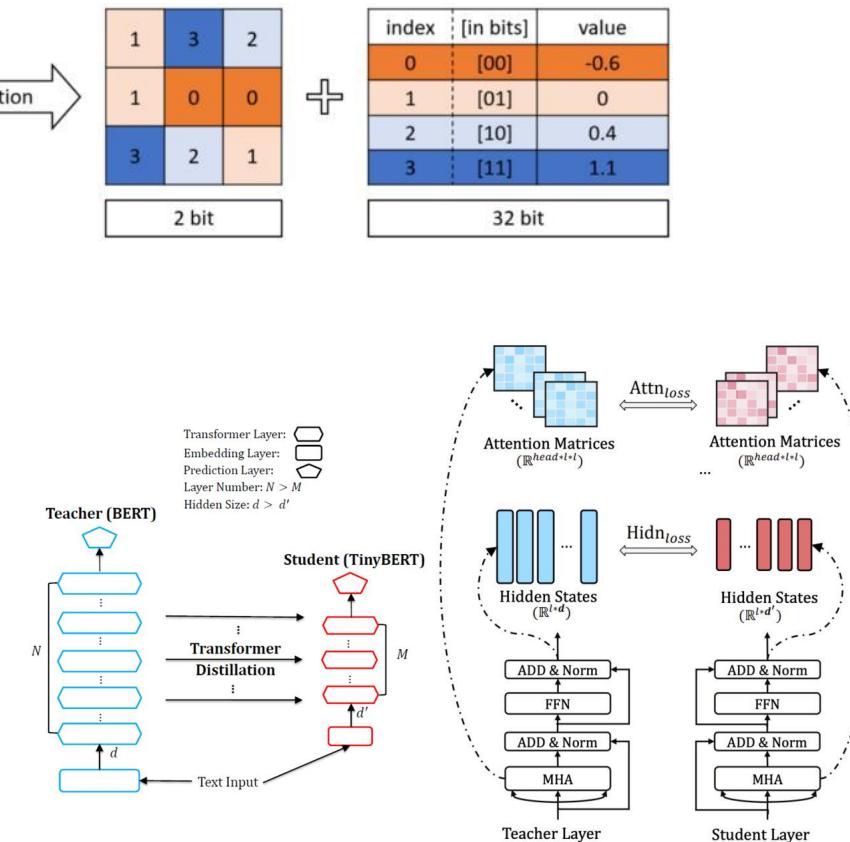
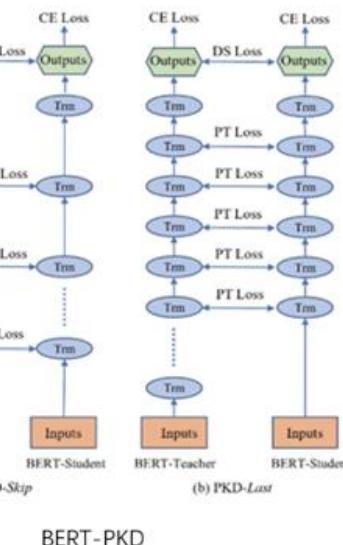
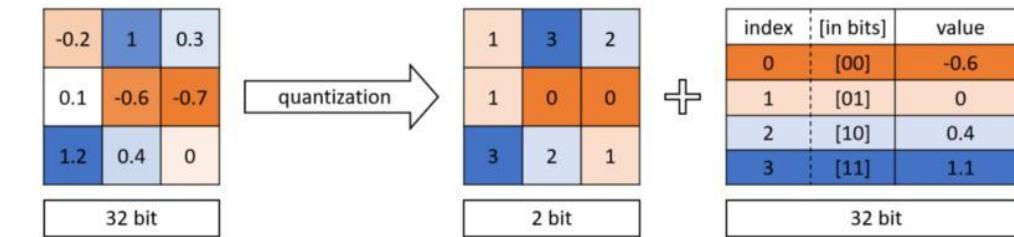
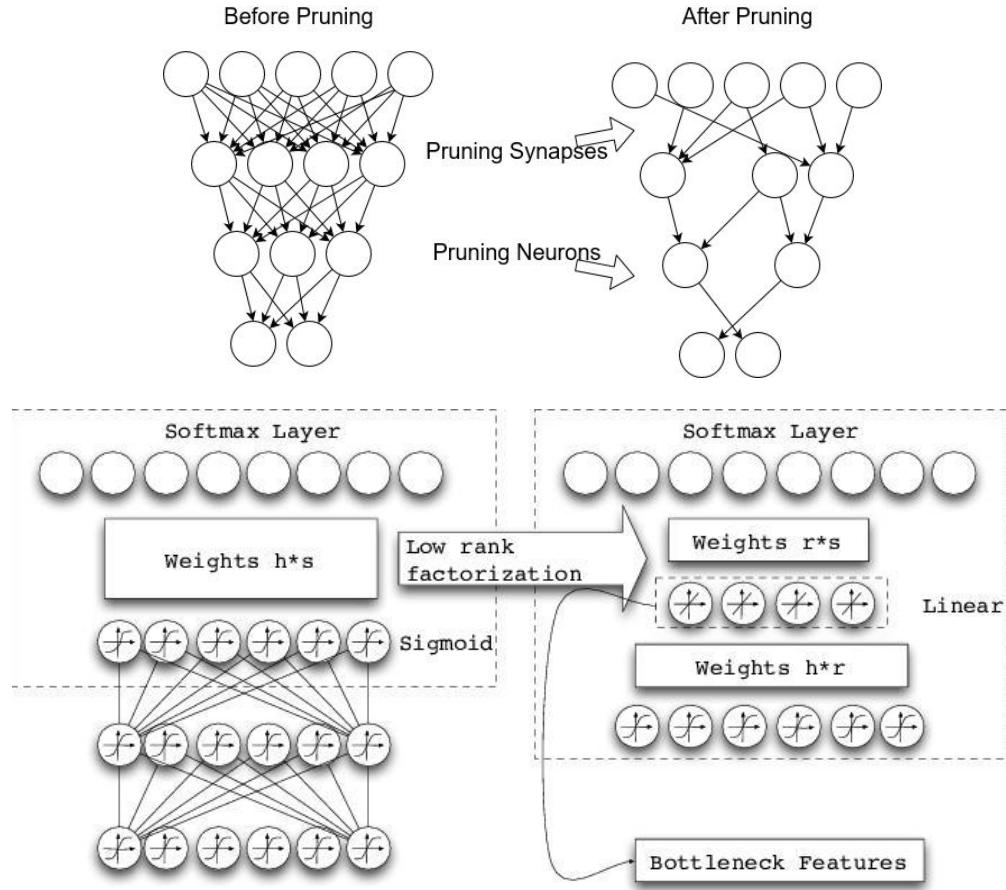
Pruning
裁剪

Weight Sharing
权重共享

Factorization
因子分解

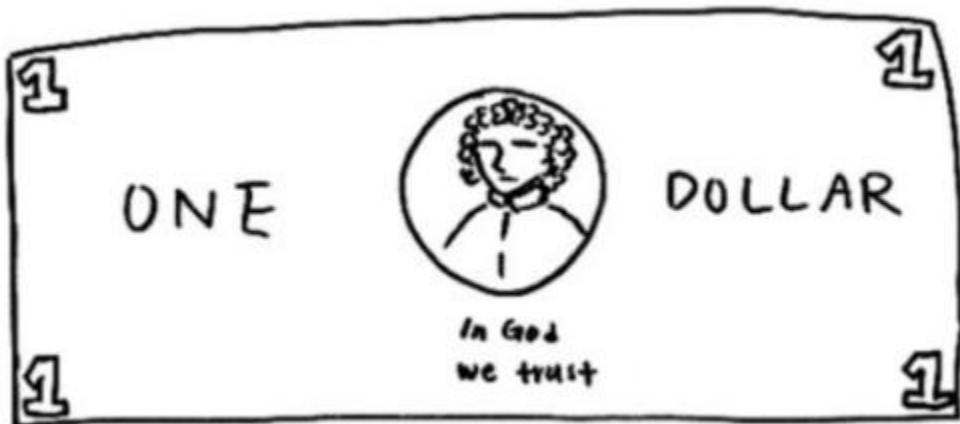
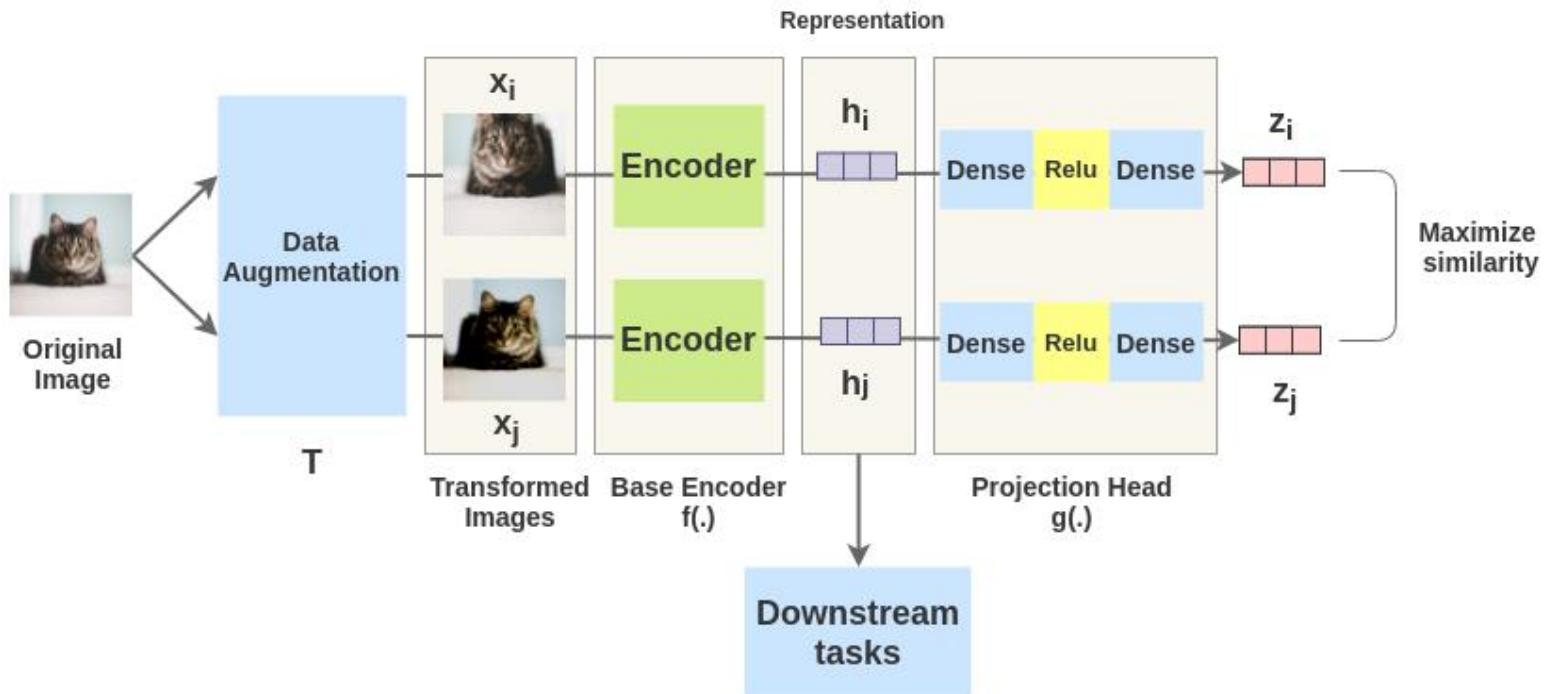
Quantization
量化

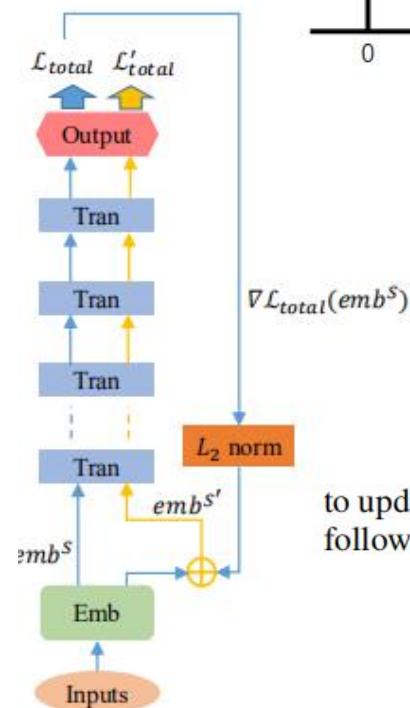
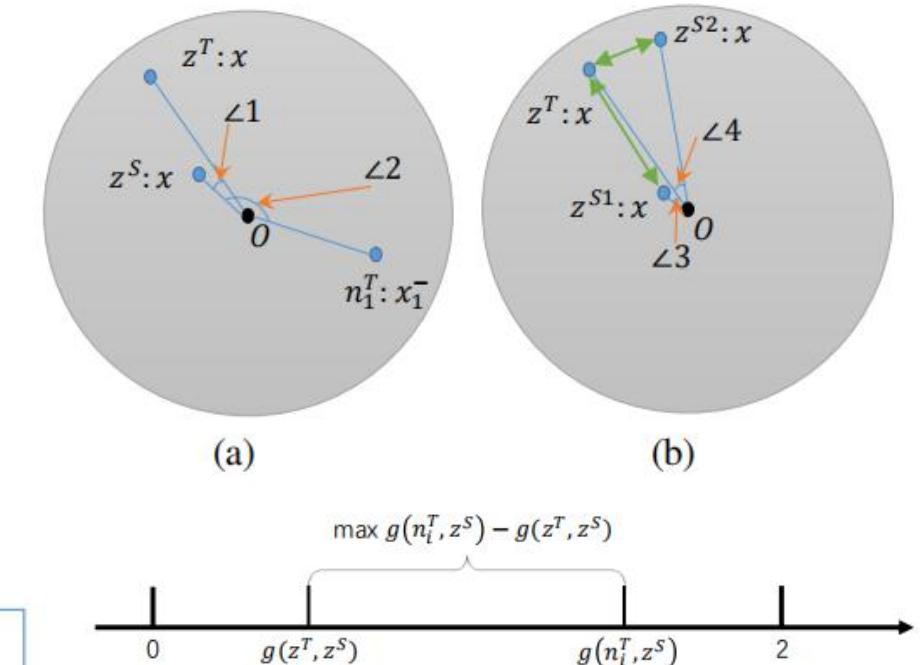
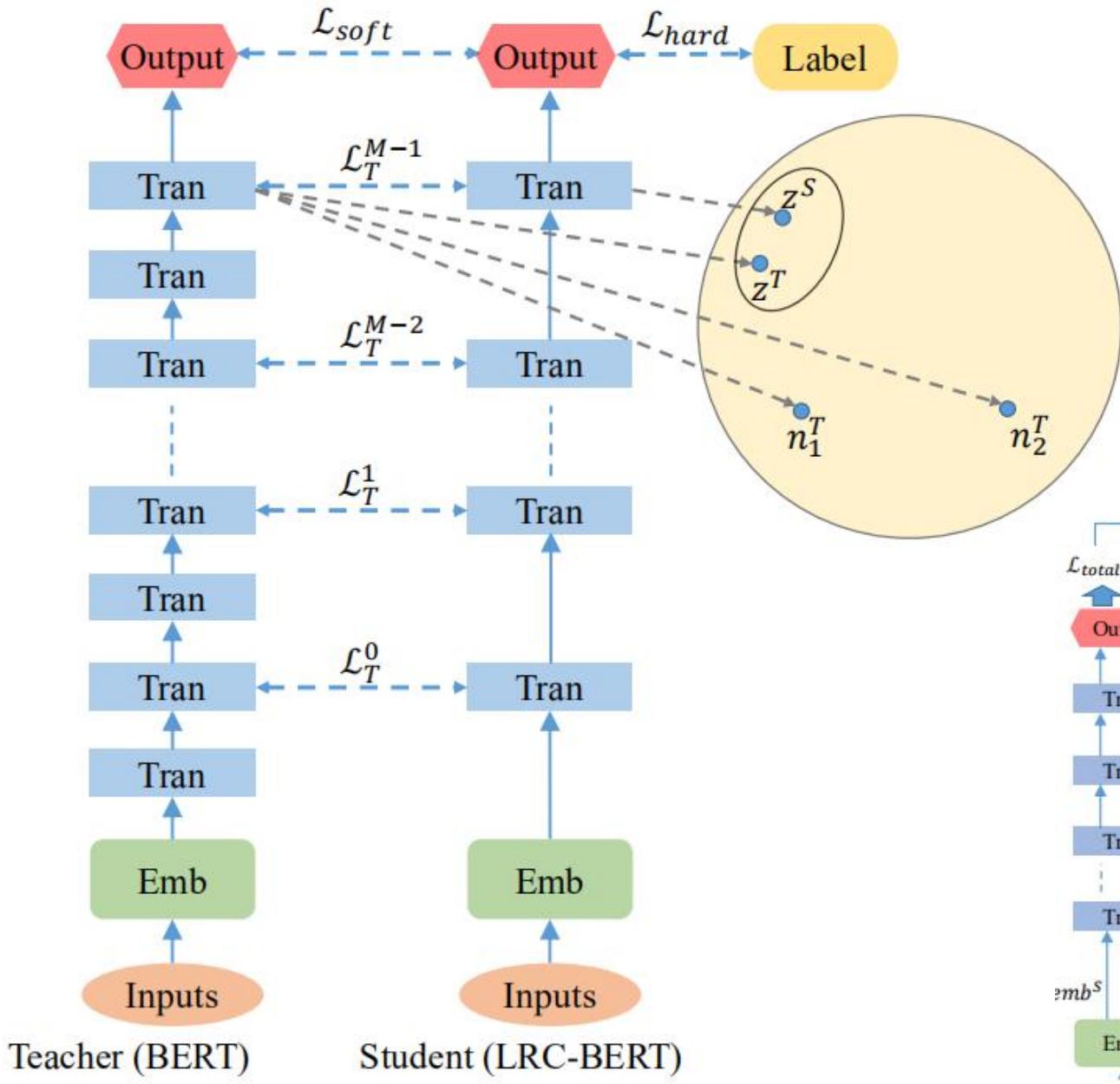
Knowledge distillation
知识蒸馏



Background

SimCLR Framework





to update the network parameters. The specific process is as follows:

$$emb^{S'} = emb^S + g/\|g\|_2, \quad (7)$$

$$g = \nabla \mathcal{L}_{total}(emb^S). \quad (8)$$

Setting

Distillation Setup

We use BERT-base (Devlin et al. 2019) as our teacher.

For the distillation of each task on GLUE, we fine-tune a BERT-base teacher, choosing learning rates of 5e-5, 1e-4, and 3e-4 with batchsize of 16 to distill LRC-BERT and LRC-BERT₁. For each sample, we choose the remaining 15 samples in batchsize as negative samples, i.e. $K = 15$. Among them, 90 epochs of distillation are performed on the MRPC, RTE, and CoLA with the training dataset less than 10K, and 18 epochs of distillation on other tasks. For the proposed two-stage training method, the first 80% of the steps are chosen as the first stage of training, the rest 20% of

Datasets

We evaluate LRC-BERT on GLUE benchmark. The datasets

Results

Model	Accuracy
LRC-BERT	83.4
LRC-BERT ₂	79.4

Table 4: Effect of two-stage training method on MNLI-m task (dev).

Results

Model	Params	MNLI-m (393k)	MNLI-mm (393k)	QQP (364k)	SST-2 (67k)	QNLI (105k)	MRPC (3.7k)	RTE (2.5k)	CoLA (8.5k)	STS-B (5.7k)	Avg
BERT-base (teacher)	109M	84.3	83.8	71.4	93.6	90.9	88.0	66.4	53.0	84.8	79.6
DistilBERT	52.2M	78.9	78.0	68.5	91.4	85.2	82.4	54.1	32.8	76.1	71.9
BERT-PKD	52.2M	79.9	79.3	70.2	89.4	85.1	82.6	62.3	24.8	79.8	72.6
TinyBERT	14.5M	82.5	81.8	71.3	92.6	87.7	86.4	62.9	43.3	79.9	76.5
LRC-BERT ₁	14.5M	82.8	82.6	71.9	90.7	88.3	83.0	51.0	31.6	79.8	73.5
LRC-BERT	14.5M	83.1	82.7	72.2	92.9	88.7	87.0	63.1	46.5	81.2	77.5

Table 1: The results are evaluated from the official website of GLUE benchmark, and the optimal experimental results are identified in bold. The number under each dataset represents the corresponding number of training samples.

Model	transformer layers	hidden size	Params	inference time(s)
BERT-base	12	768	109M	121.4
LRC-BERT	4	312	14.5M	12.7

Table 2: The number of parameters and inference time before and after model compression.

Model	MNLI-m	MNLI-mm	MRPC	CoLA
LRC-BERT	83.4	83.5	89.0	50.0
LRC-BERT _C	78.0	78.2	81.5	37.0
LRC-BERT _S	82.7	83.0	89.4	48.8
LRC-BERT _H	83.0	83.5	88.7	48.6

Table 3: Ablation studies of different loss functions (dev).

Logic-guided Semantic Representation Learning for Zero-Shot Relation Classification

Juan Li^{1,2*}, Ruoxu Wang^{1,2*}, Ningyu Zhang^{1,2*†}, Wen Zhang^{1,2},
Fan Yang^{1,2}, Huajun Chen^{1,2 †}

¹ Zhejiang University

² AZFT Joint Lab for Knowledge Engine

{lijuan18, ruoxuwang, zhangningyu, wenzhang2015, 21821249, huajunsir}@zju.edu.cn

—浙大(COLING2020)

The contributions of this paper:

- To **recognize unseen relations** at test time, they explore the problem of **zero-shot** relation classification.
- They propose a novel **logic-guided semantic representation learning model** for zero-shot relation classification.

Background

① 知识图嵌入的隐含语义联系

Implicit Semantic Connection with Knowledge Graph Embedding. Previous studies (Yang et al., 2014) have shown that the Knowledge Graph Embeddings (KGEs) of semantically similar relations are located near each other in the latent space.

② 规则学习明确的语义联系

Explicit Semantic Connection with Rule Learning. We human can easily recognize unseen relations via symbolic reasoning. As the example shown in Figure 1, with the rule that $\text{basin_country_of}(y,z)$ can be deduced if $\text{located_in_country}(x,y)$ and $\text{next_to_body_of_water}(x,z)$, we can recognize the unseen relation basin_country_of based on seen relations $\text{located_in_country}$ and $\text{next_to_body_of_water}$. To this end, it is intuitive to infuse rule knowledge to bridge the connections between seen and zero-shot relations.

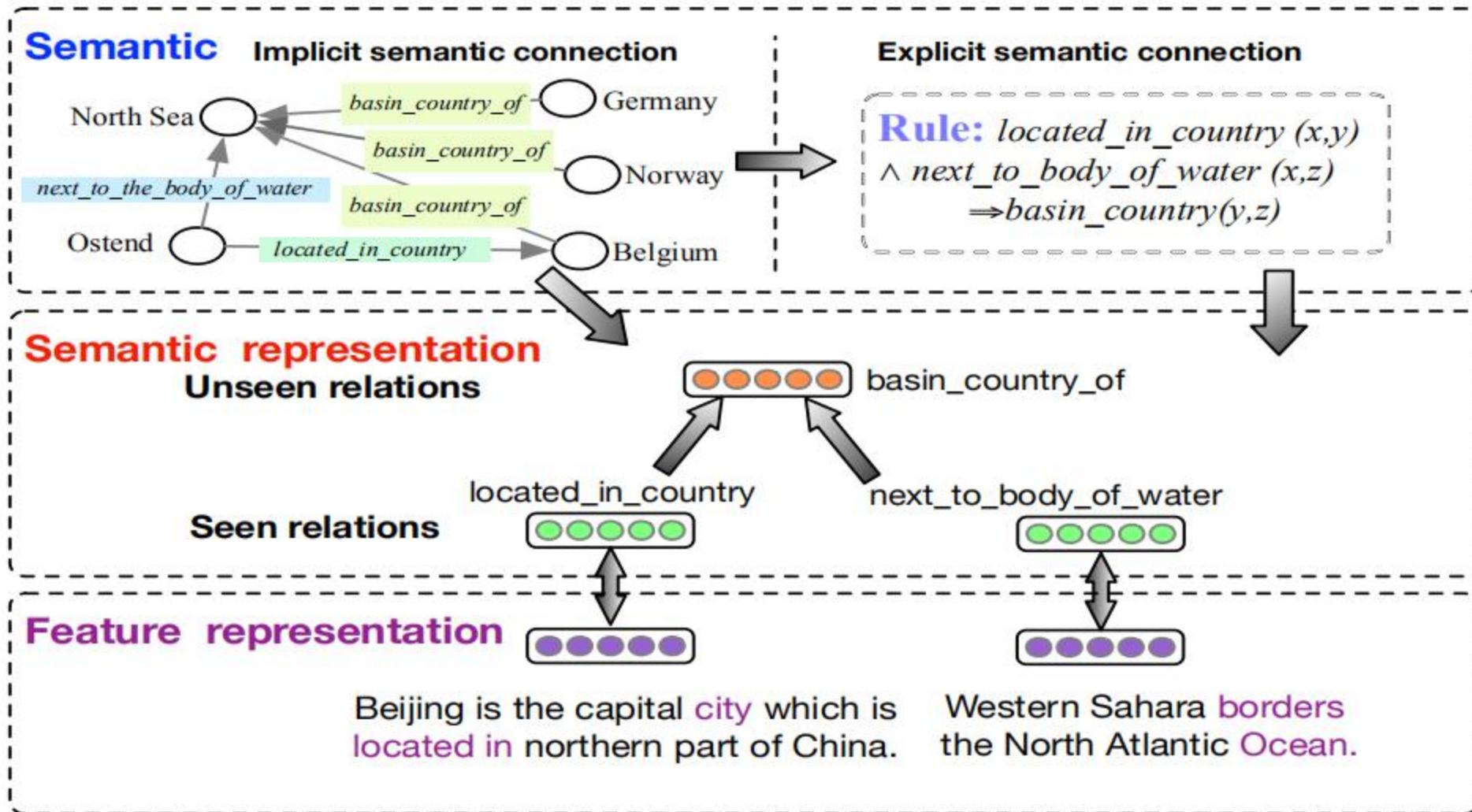


Figure 1: Knowledge graph embedding and rule learning for zero-shot relation classification.

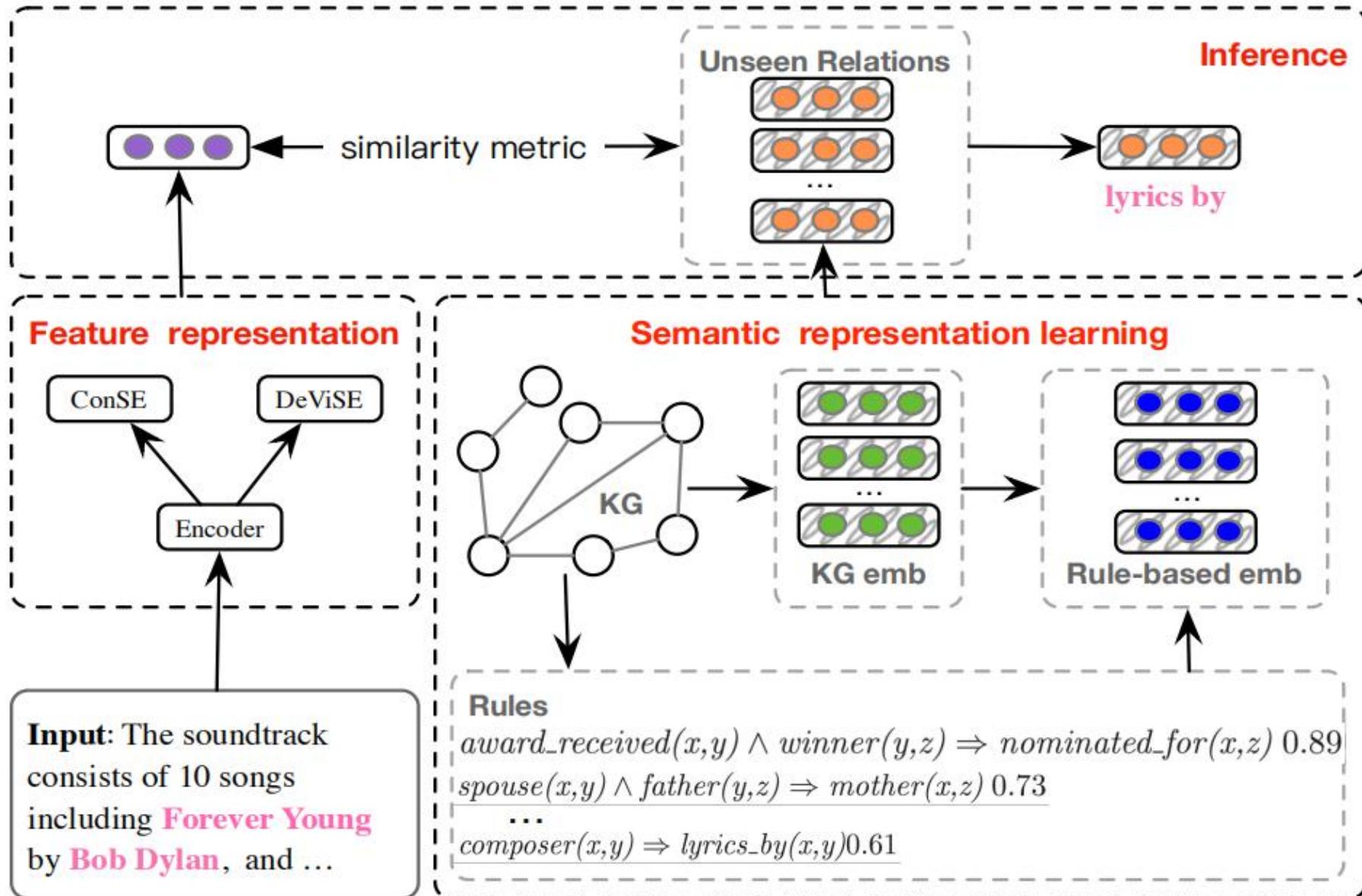
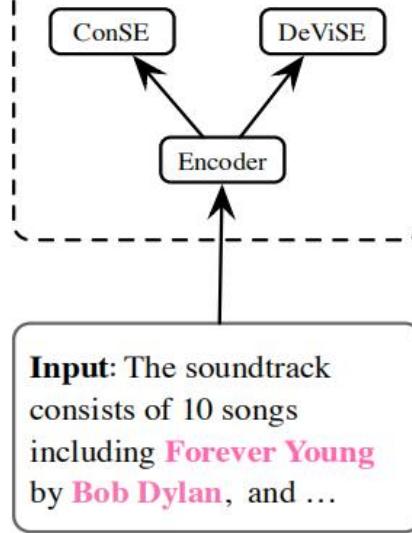


Figure 2: The architecture of Logic-guided Semantic Representation Learning model.

Feature representation



3.2 Feature Representation

The input of feature representation is a sentence, and the output is its vector representation. Firstly, we use the **Piecewise Convolutional Neural Networks(PCNNs)** (Zeng et al., 2015) model to encode input instance, and then use two types of projection functions including **DeViSE** and **ConSE** to get the final feature representation of the input instance.

$$f = PCNN(x_1, \dots, x_n)$$

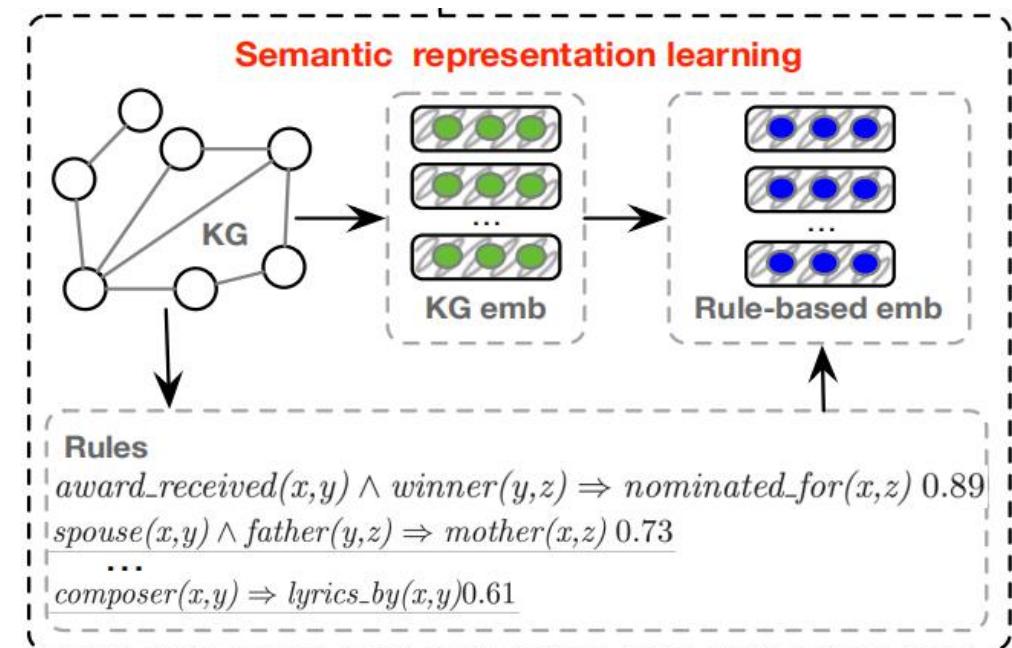
$$g = W * f + b \quad \xleftarrow{\text{DeViSE}}$$

$$R_t^S, p_t, E(R_t^S) = C(f), t = 1, \dots, T \quad \xleftarrow{\text{ConSE}}$$

$$g = \sum_{t=1}^T p_t * E(R_t^S) \quad \xleftarrow{\text{Feature Representation}}$$

$$E_{rl}(R_i^U) = \frac{\sum_{j=1}^K conf_j * E_{kg}(Rule_{ij}^U)}{\sum_{j=1}^K conf_j} \quad \xleftarrow{\text{Rule Embedding}}$$

$$E_{kr} = \lambda * E_{rl} + (1 - \lambda) * E_{kg} \quad \xleftarrow{\text{Rule+Word Embedding}}$$



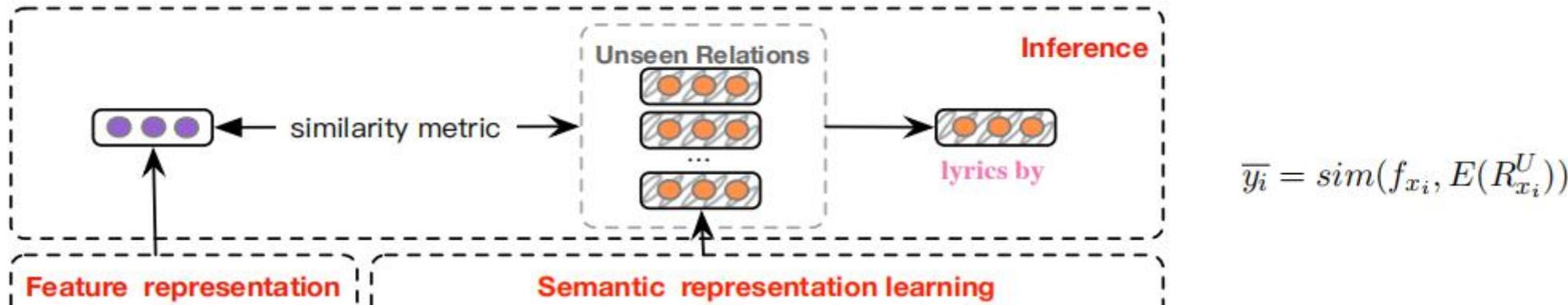
3.3 Semantic Representation Learning

Semantic representation builds connections between unseen and seen relations in ZSRC via external resources. We describe the following **three kinds** of embedding representations in a semantic space.

Word EmbeddingKG Embedding

KG+Word embedding

$$E_{kw} = W_2 * ([E_{kg}; E_{wd}] + b_2)$$



Dataset

We construct a new dataset based upon Wikipedia-Wikidata (Sorokin and Gurevych, 2017) relation extraction dataset which contains 353 relations and 856,217 instances. To evaluate the capability of injecting rule logic into the zero-shot prediction models, we ensure that relations have certain connections in our dataset.

Results

	ConSE(Hit@n)			DeViSE(Hit@n)		
	1	2	5	1	2	5
$+E_{wd}$	0.21	0.30	0.43	0.11	0.19	0.39
$+E_{kg}$	0.39	0.53	0.69	0.22	0.38	0.57
$+E_{rl}$	0.40	0.54	0.72	0.23	0.39	0.58
$+E_{kw}$	0.39	0.55	0.72	0.23	0.40	0.59
$+E_{rw}$	0.40	0.55	0.70	0.23	0.34	0.57
$+E_{kr}$	0.43	0.57	0.74	0.25	0.39	0.59

Table 2: Performance of DeViSE and ConSE in the case of different embedding methods, including Word(E_{wd}), KG(E_{kg}), Rule(E_{rl}), KG+Word(E_{kw}), Rule+Word(E_{rw}) and KG+Rule(E_{kr}) embeddings.

Results

Unseen Relations	F1-score		Top 3 Related Seen Relations			
	+E _{kg}	+E _{wd}	+E _{kg}	+E _{wd}	+E _{wd}	+E _{kr}
lyrics_by	0.52	0.06	performer	influenced_by		
			composer	spouse		
			cast_member	cast_member		
after_a_work_by	0.51	0.01	author	named_after		
			screenwriter	author		
			creator	characters		
location_ofFormation	0.46	0.02	headquarters_location	subclass_of		
			location	opposite_of		
			capital	part_of		
nominated_for	0.97	0.56	award_received	award_received		
			winner	part_of		
			participant_of	member_of		
mother	0.40	0.83	follows	child		
			spouse	spouse		
			twinned_administrative_body	father		
developer	0.38	0.49	publisher	manufacturer		
			manufacturer	publisher		
			owned_by	owned_by		
office_contested	0.26	0.00	position_held			
			successful_candidate			
			applies_to_jurisdiction			
occupant	0.31	0.00	owned_by			
			location			
			headquarters_location			
drafted_by	0.81	0.00	member_of_sports_team			
			educated_at			
			member_of			

Table 3: Results of KG embedding and word embedding on F1 score when using ConSE as projection function. And top 3 most influential seen relations of the corresponding unseen relation are presented.

Unseen Relations	F1-score						Related rules w.r.t. unseen relations
	+E _{wd}	+E _{kg}	+E _{rl}	+E _{kw}	+E _{rw}	+E _{kr}	
mother	0.83	0.40	0.77	0.53	0.80	0.78	$mother(x,z) \Leftarrow spouse(x,y) \wedge father(y,z)$ $mother(x,y) \Leftarrow child(y,x)$
lyrics_by	0.06	0.52	0.51	0.49	0.48	0.52	$lyrics_by(x,y) \Leftarrow composer(x,y)$
nominated_for	0.56	0.97	0.96	0.97	0.96	0.96	$nominated_for(x,z) \Leftarrow award_received(x,y) \wedge winner(y,z)$
producer	0.41	0.52	0.55	0.54	0.52	0.53	$producer(x,y) \Leftarrow director(x,y)$ $producer(x,y) \Leftarrow screenwriter(x,y)$ $producer(x,y) \Leftarrow cast_member(x,y)$
field_of_work	0.04	0.14	0.29	0.11	0.29	0.37	$field_of_work(x,y) \Leftarrow occupation(x,y)$
connecting_line	0.00	0.10	0.43	0.28	0.42	0.47	$connecting_line(x,z) \Leftarrow adjacent_station(y,x) \wedge part_of(y,z)$
residence	0.01	0.32	0.30	0.30	0.38	0.39	$residence(x,y) \Leftarrow place_of_birth(x,y)$ $residence(x,y) \Leftarrow place_of_death(x,y)$

Table 4: Results of all different embeddings on F1 score when regarding ConSE as project function, and related rules w.r.t unseen relations.

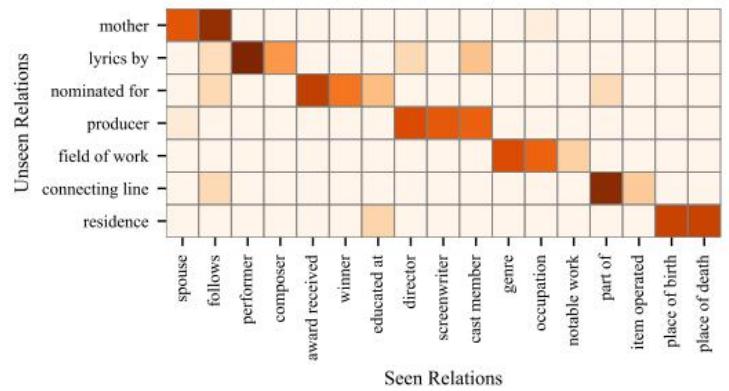


Figure 3: This heatmap is constructed from the result of ConSE+KG, reflecting the incidence of seen relations on unseen relations. Where the horizontal axis represents seen classes and the vertical axis represents unseen classes.

LayoutLMv2: Multi-modal Pre-training for Visually-Rich Document Understanding

Yang Xu^{1*}, Yiheng Xu^{2*}, Tengchao Lv^{2*}, Lei Cui², Furu Wei², Guoxin Wang³, Yijuan Lu³,
Dinei Florencio³, Cha Zhang³, Wanxiang Che¹, Min Zhang⁴, Lidong Zhou²

¹Harbin Institute of Technology

²Microsoft Research Asia

³Microsoft Cloud&AI Team

⁴Soochow University

{yxu,car}@ir.hit.edu.cn

{v-yixu,v-telv,lecu,fuwei,lidongz}@microsoft.com

{guow,yijlu,dinei,chazhang}@microsoft.com

minzhang@suda.edu.cn

—微软亚洲研究院(KDD2020)

The contributions of this paper:

- This paper presents an improved version of LayoutLM (Xu et al., 2020), aka **LayoutLMv2**.
- Extending the existing research work, they propose **new model architectures** and pre-training objectives in the LayoutLMv2 model.
- <https://github.com/microsoft/unilm/tree/master/layoutlm>

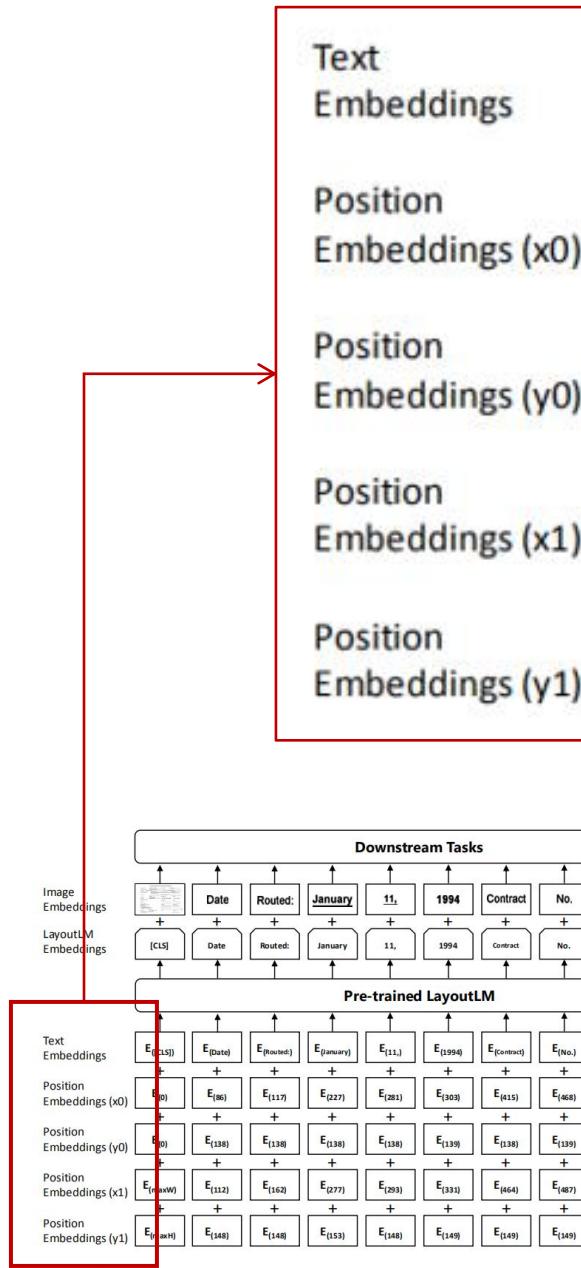


Figure 2: An example of LayoutLM, where 2-D layout and image embeddings are integrated into the original BERT architecture. The LayoutLM embeddings and image embeddings from Faster R-CNN work together for downstream tasks.

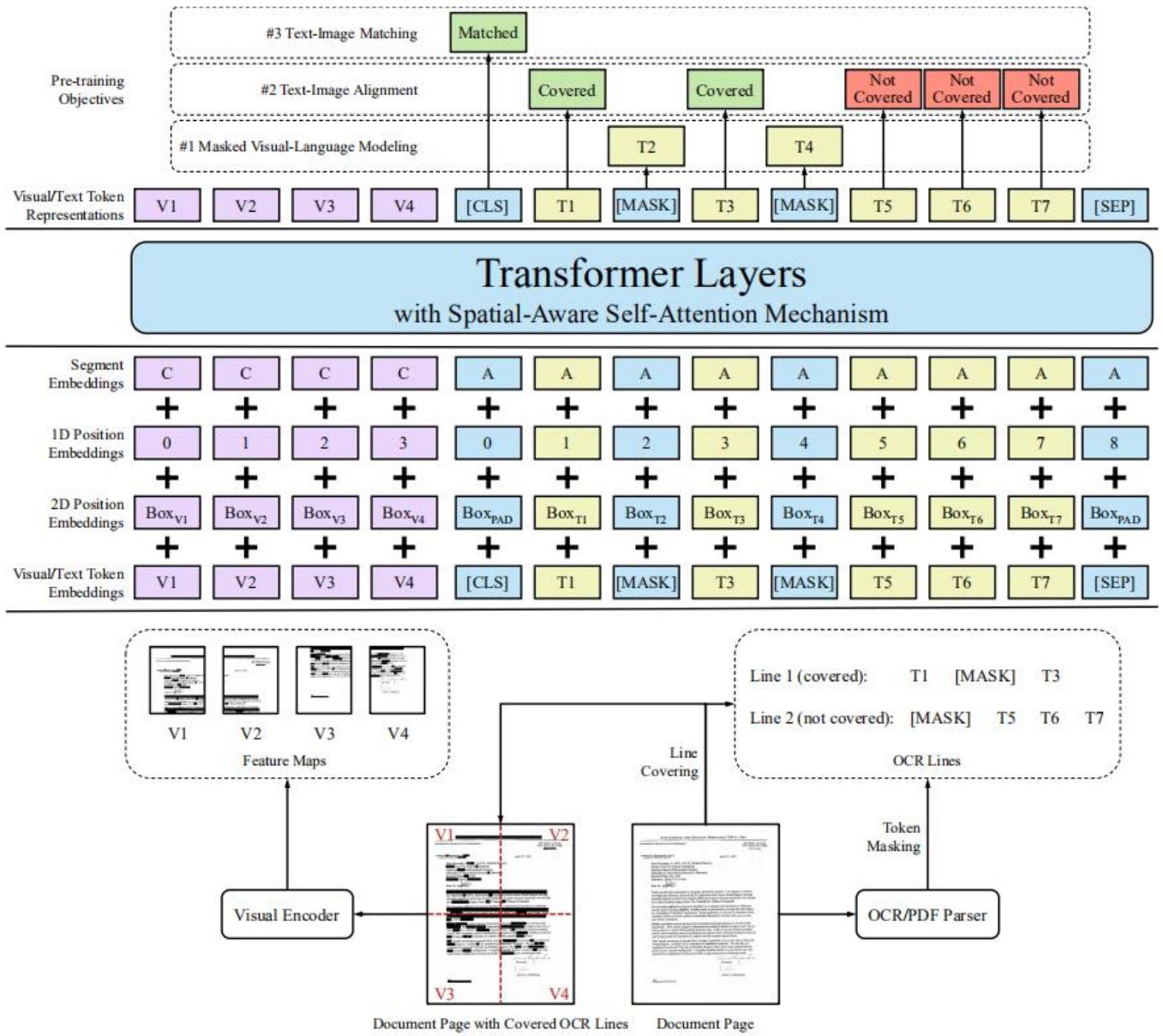
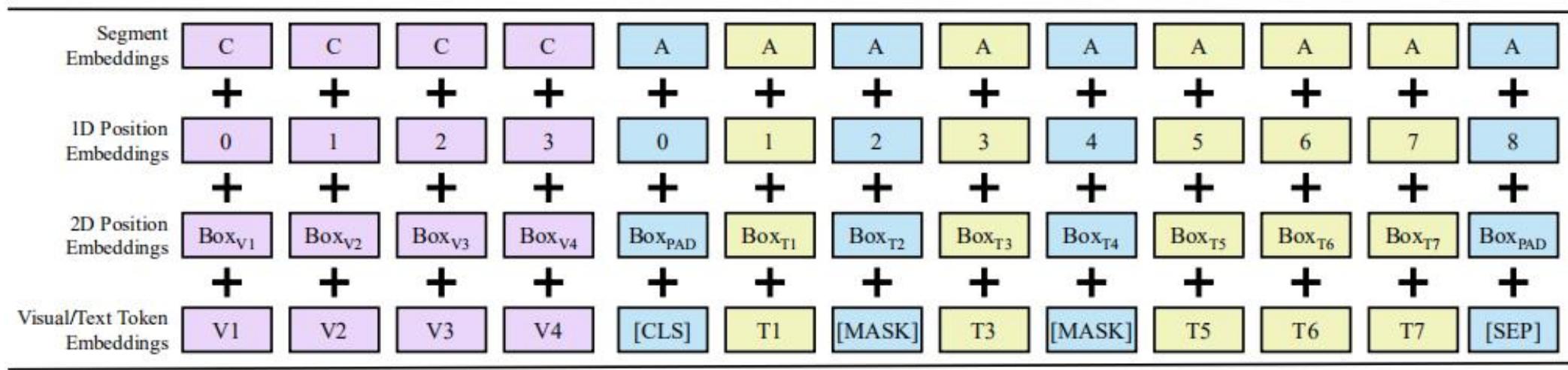


Figure 2: An illustration of the model architecture and pre-training strategies for LayoutLMv2



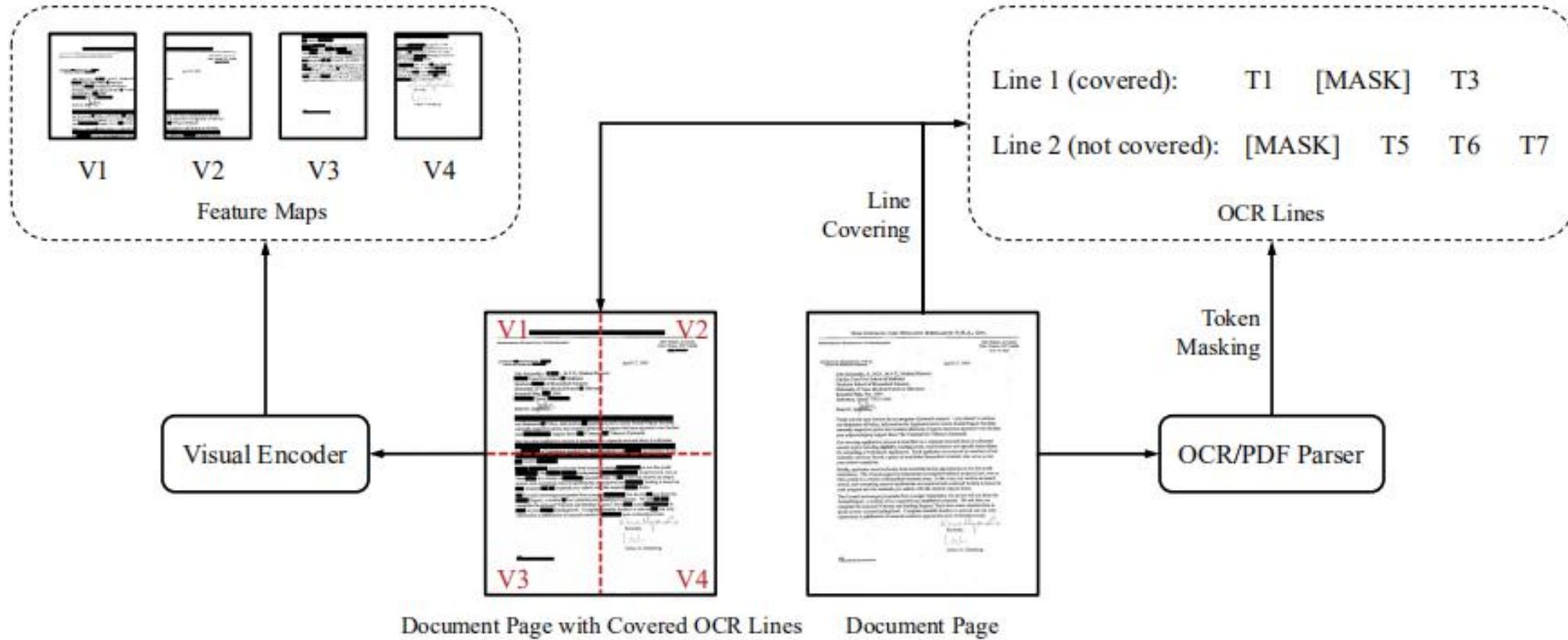
Text Embedding We recognize text and serialize it in a reasonable reading order using off-the-shelf OCR tools and PDF parsers. Following the common practice, we use WordPiece (Wu et al., 2016).

$$S = \{ [\text{CLS}], w_1, w_2, \dots, [\text{SEP}], [\text{PAD}], [\text{PAD}], \dots \}, |S| = L$$

$$\mathbf{t}_i = \text{TokEmb}(w_i) + \text{PosEmb1D}(i) + \text{SegEmb}(s_i), 0 \leq i < L$$

Layout Embedding The layout embedding layer aims to embed the spatial layout information represented by token bounding boxes in which corner coordinates and box shapes are identified explicitly. Following the vanilla LayoutLM, we normalize and discretize all coordinates to integers in the range [0, 1000], and use two embedding layers to embed x-axis features and y-axis features separately.

$$\mathbf{l}_i = \text{Concat}(\text{PosEmb2D}_x(x_0, x_1, w), \text{PosEmb2D}_y(y_0, y_1, h)), 0 \leq i < WH + L$$



Visual Embedding We use ResNeXt-FPN (Xie et al., 2016; Lin et al., 2017) architecture as the backbone of the visual encoder. Given a document page image I , it is resized to 224×224 then fed

$$\mathbf{v}_i = \text{Proj}(\text{VisTokEmb}(I)_i) + \text{PosEmb1D}(i) + \text{SegEmb}([\text{C}]), \quad 0 \leq i < WH$$

Transformer Layers

with Spatial-Aware Self-Attention Mechanism

基于空间感知自注意力机制的多模态编码器

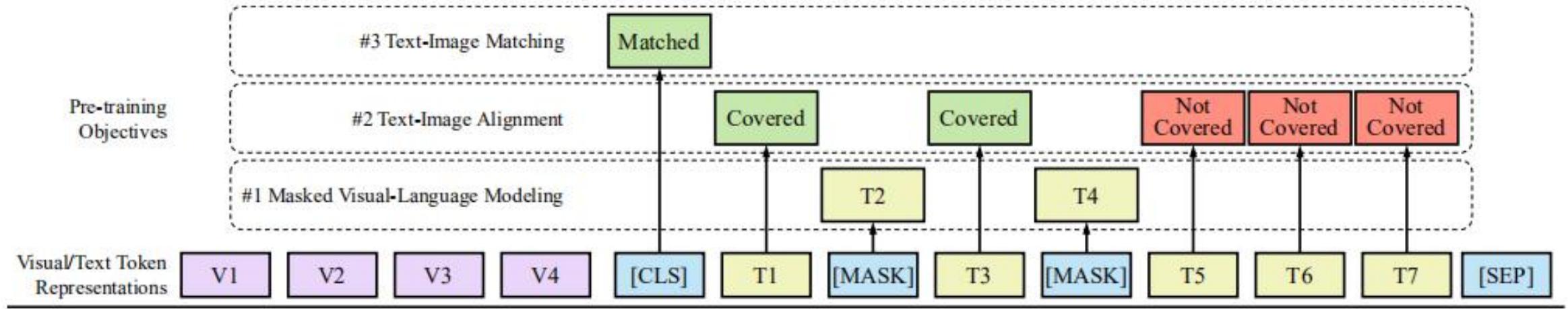
Multi-modal Encoder with Spatial-Aware Self-Attention Mechanism The encoder concatenates visual embeddings $\{\mathbf{v}_0, \dots, \mathbf{v}_{WH-1}\}$ and text embeddings $\{\mathbf{t}_0, \dots, \mathbf{t}_{L-1}\}$ to a unified sequence X and fuses spatial information by adding the layout embeddings to get the first layer input $\mathbf{x}^{(0)}$.

$$\mathbf{x}_i^{(0)} = X_i + \mathbf{l}_i, \text{ where } X = \{\mathbf{v}_0, \dots, \mathbf{v}_{WH-1}, \mathbf{t}_0, \dots, \mathbf{t}_{L-1}\}$$

$$\alpha_{ij} = \frac{1}{\sqrt{d_{head}}} (\mathbf{x}_i \mathbf{W}^Q) (\mathbf{x}_j \mathbf{W}^K)^\top$$

$$\alpha'_{ij} = \alpha_{ij} + \mathbf{b}_{j-i}^{(1D)} + \mathbf{b}_{x_j - x_i}^{(2D_x)} + \mathbf{b}_{y_j - y_i}^{(2D_y)}$$

$$\mathbf{h}_i = \sum_j \frac{\exp(\alpha'_{ij})}{\sum_k \exp(\alpha'_{ik})} \mathbf{x}_j \mathbf{W}^V$$



Masked Visual-Language Modeling Similar to the vanilla LayoutLM, we use the Masked Visual-Language Modeling (MVLM) to make the model learn better in the language side with the cross-modality clues.

Text-Image Alignment In addition to the MVLM, we propose the Text-Image Alignment (TIA) as a fine-grained cross-modality alignment task.

Text-Image Matching Furthermore, a coarse-grained cross-modality alignment task, Text-Image Matching (TIM) is applied during the pre-training stage.

Results

Model	Precision	Recall	F1	#Parameters
BERT _{BASE}	0.5469	0.6710	0.6026	110M
UniLMv2 _{BASE}	0.6349	0.6975	0.6648	125M
BERT _{LARGE}	0.6113	0.7085	0.6563	340M
UniLMv2 _{LARGE}	0.6780	0.7391	0.7072	355M
LayoutLM _{BASE}	0.7597	0.8155	0.7866	113M
LayoutLM _{LARGE}	0.7596	0.8219	0.7895	343M
LayoutLMv2 _{BASE}	0.8029	0.8539	0.8276	200M
LayoutLMv2 _{LARGE}	0.8324	0.8519	0.8420	426M
BROS (Anonymous, 2021)	0.8056	0.8188	0.8121	-

Table 1: Model accuracy (entity-level Precision, Recall, F1) on the FUNSD dataset

Model	Precision	Recall	F1	#Parameters
BERT _{BASE}	0.8833	0.9107	0.8968	110M
UniLMv2 _{BASE}	0.8987	0.9198	0.9092	125M
BERT _{LARGE}	0.8886	0.9168	0.9025	340M
UniLMv2 _{LARGE}	0.9123	0.9289	0.9205	355M
LayoutLM _{BASE}	0.9437	0.9508	0.9472	113M
LayoutLM _{LARGE}	0.9432	0.9554	0.9493	343M
LayoutLMv2 _{BASE}	0.9453	0.9539	0.9495	200M
LayoutLMv2 _{LARGE}	0.9565	0.9637	0.9601	426M
SPADE (Hwang et al., 2020)	-	-	0.9150	-
BROS (Anonymous, 2021)	0.9558	0.9514	0.9536	-

Table 2: Model accuracy (entity-level Precision, Recall, F1) on the CORD dataset

Model	Precision	Recall	F1	#Parameters
BERT _{BASE}	0.9099	0.9099	0.9099	110M
UniLMv2 _{BASE}	0.9459	0.9459	0.9459	125M
BERT _{LARGE}	0.9200	0.9200	0.9200	340M
UniLMv2 _{LARGE}	0.9488	0.9488	0.9488	355M
LayoutLM _{BASE}	0.9438	0.9438	0.9438	113M
LayoutLM _{LARGE}	0.9524	0.9524	0.9524	343M
LayoutLMv2 _{BASE}	0.9625	0.9625	0.9625	200M
LayoutLMv2 _{LARGE}	0.9661	0.9661	0.9661	426M
LayoutLMv2 _{LARGE} (Excluding OCR mismatch)	0.9904	0.9661	0.9781	426M
BROS (Anonymous, 2021)	0.9493	0.9603	0.9548	-
PICK (Yu et al., 2020)	0.9679	0.9546	0.9612	-
TRIE (Zhang et al., 2020)	-	-	0.9618	-
Top-1 on SROIE Leaderboard (Excluding OCR mismatch)	0.9889	0.9647	0.9767	-

Table 3: Model accuracy (entity-level Precision, Recall, F1) on the SROIE dataset (until 2020-12-24)

Model	Fine-tuning set	ANLS	#Parameters
BERT _{BASE}	train	0.6354	110M
UniLMv2 _{BASE}	train	0.7134	125M
BERT _{LARGE}	train	0.6768	340M
UniLMv2 _{LARGE}	train	0.7709	355M
LayoutLM _{BASE}	train	0.6979	113M
LayoutLM _{LARGE}	train	0.7259	343M
LayoutLMv2 _{BASE}	train	0.7808	200M
LayoutLMv2 _{LARGE}	train	0.8348	426M
LayoutLMv2 _{LARGE} + QG	train + dev	0.8529	426M
LayoutLMv2 _{LARGE} + QG	train + dev	0.8672	426M
Top-1 on DocVQA Leaderboard (30 models ensemble)	-	0.8506	-

Table 6: Average Normalized Levenshtein Similarity (ANLS) score on the DocVQA dataset (until 2020-12-24), “QG” denotes the data augmentation with the question generation dataset.

Thanks