

Exercise sheet 3

Numerical Analysis 2022

1 PS.3 (triangular solver)

$Ly = b$ with L lower triangular with 1 in the diagonal.

$$\begin{aligned}y_1 &= b_1, \\y_2 &= b_2 - \ell_{2,1}y_1, \\&\vdots \\y_k &= b_k - \sum_{j=1}^{k-1} \ell_{k,j}y_j, \\&\vdots \\y_n &= b_n - \sum_{j=1}^{n-1} \ell_{n,j}y_j.\end{aligned}$$

a) Write a solver for $Ly = b$.

$Ux = y$ with U upper triangular and nonzero diagonal.

$$\begin{aligned}x_n &= \frac{y_n}{u_{n,n}} \\x_{n-1} &= \frac{1}{u_{n-1,n-1}} (y_{n-1} - u_{n-1,n}x_n) \\&\vdots \\x_k &= \frac{1}{u_{k,k}} \left(y_k - \sum_{j=k+1}^n u_{k,j}x_j \right) \\&\vdots \\x_1 &= \frac{1}{u_{1,1}} \left(y_1 - \sum_{j=2}^n u_{1,j}x_j \right).\end{aligned}$$

b) Write a solver for $Ux = y$.

2 PS.3 (lu-decomposition without pivoting)

For $A \in \mathbb{R}^{n \times n}$, set $A^{(1)} := B^{(1)} := A$ and

$$\ell^{(k)} = \frac{1}{a_{k,k}^{(k)}} \begin{pmatrix} a_{k+1,k}^{(k)} \\ \vdots \\ a_{n,k}^{(k)} \end{pmatrix} \in \mathbb{R}^{n-k}, \quad B^{(k+1)} = B^{(k)} - \ell^{(k)} \cdot \begin{pmatrix} a_{k,k+1}^{(k)}, \dots, a_{k,n}^{(k)} \end{pmatrix} \in \mathbb{R}^{(n-k) \times (n-k)} \quad (1)$$

$$A^{(k+1)} = L_k A^{(k)} = \begin{pmatrix} a_{1,1}^{(1)} & a_{1,2}^{(1)} & \cdots & \cdots & a_{1,n}^{(1)} \\ 0 & \ddots & & & \\ \vdots & \ddots & a_{k,k}^{(k)} & \cdots & a_{k,n}^{(k)} \\ 0 & & 0 & & \\ \vdots & & \vdots & B^{(k+1)} & \\ 0 & \cdots & 0 & & \end{pmatrix}, \quad L = \begin{pmatrix} 1 & 0 & \cdots & \cdots & \cdots & 0 \\ | & \ddots & \ddots & & & \vdots \\ | & & \ddots & \ddots & & \vdots \\ | & & & \ddots & 0 & \vdots \\ | & & & & 1 & 0 \\ \ell^{(1)} & \cdots & \ell^{(k)} & \cdots & \ell^{(n-1)} & 1 \end{pmatrix}, \quad U = A^{(n)} \quad (2)$$

We may store $\ell^{(1)}, \dots, \ell^{(k)}$ in $A^{(k+1)}$ to get rid of L , i.e.,

$$\tilde{A}^{(k+1)} = \begin{pmatrix} a_{1,1}^{(1)} & a_{1,2}^{(1)} & \cdots & \cdots & a_{1,n}^{(1)} \\ | & \ddots & & & \\ | & \ddots & a_{k,k}^{(k)} & \cdots & a_{k,n}^{(k)} \\ | & & | & & \\ \ell^{(1)} & \cdots & \ell^{(k)} & B^{(k+1)} & \end{pmatrix} \quad (3)$$

- Write a function with input A that returns L and U of the lu-decomposition.
- Solve the system of linear equations $Ax = b$ for

$$A = \begin{pmatrix} \varepsilon & 1 \\ 1 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 2 \end{pmatrix} \quad (4)$$

by using myLU and myU, myL for $\varepsilon = 2$ and for $\varepsilon = 2^{-55}$. Are the results correct?

3 PS.3 (lu-decomposition with partial pivoting)

$$PA = LU, \quad Ax = b \Leftrightarrow LUx = Pb \quad (5)$$

- Solve the system of linear equations $Ax = b$ for

$$A = \begin{pmatrix} -2 & 2 & -1 \\ 6 & -6 & 7 \\ 3 & -8 & 4 \end{pmatrix}, \quad b = \begin{pmatrix} -1 \\ 7 \\ -1 \end{pmatrix} \quad (6)$$

by using the lu-decomposition with partial pivoting by hand.

- b) The function `myLUPivot` is provided below. Write a function `myLinearSolver` that solves $Ax = b$ based on `myLUPivot`. Solve part a) with your implementation. Run testset and, if necessary, adjust the error bounds.

4 PS.3 (Cholesky factorization)

For symmetric, positive definite $A = LL^\top$, the matrix $L = (l_{i,j})$ is given by

$$l_{j,j} = \sqrt{a_{j,j} - \sum_{k=1}^{j-1} l_{j,k}^2}, \quad j = 1, \dots, n, \quad (7)$$

$$l_{i,j} = \frac{1}{l_{j,j}} \left(a_{i,j} - \sum_{k=1}^{j-1} l_{i,k} l_{j,k} \right), \quad i = j+1, \dots, n. \quad (8)$$

- a) Write a function with input A that returns L .
b) Complete the testset “myCholesky” and run the tests successfully.

5 PS.3 (lls via normal equations)

Given data $\alpha, b \in \mathbb{R}^m$, consider

$$\arg \min_{x \in \mathbb{R}^2} \sum_{k=1}^m |b_k - (x_1 + x_2 \alpha_k)|^2$$

The minimizer (x_1, x_2) defines an affine linear function $f(a) = x_1 + x_2 a$.

- a) Write a julia function that takes input α, b and returns f .
b) Generate several data sets with illustrative plots.

6 PS.3 (svd)

For $m \geq n$, let $A \in \mathbb{R}^{m \times n}$ with $\text{rank}(A) = p$.

- The matrix $A^\top A \in \mathbb{R}^{n \times n}$ has eigenvalues $\lambda_1 \geq \dots \geq \lambda_p > 0$ with pairwise orthonormal eigenvectors $v_1, \dots, v_p \in \mathbb{R}^n$ that are collected into

$$V := (v_1, \dots, v_p) \in \mathbb{R}^{n \times p}.$$

- The singular values $\sigma_k := \sqrt{\lambda_k}$, for $k = 1, \dots, p$, are collected into

$$\Sigma := \text{diag}(\sigma_1, \dots, \sigma_p) \in \mathbb{R}^{p \times p}.$$

- Define $u_k := \frac{1}{\sigma_k} A v_k$, for $k = 1, \dots, p$, and build

$$U := (u_1, \dots, u_p) \in \mathbb{R}^{m \times p}.$$

Then we obtain the decomposition

$$A = U \Sigma V^\top.$$

The pseudo inverse of A is $A^\# = V \Sigma^{-1} U^\top$.

- a) Write a julia function that takes input A and returns U , $\sigma_1, \dots, \sigma_p$, and V .
- b) Write a julia function that takes input A and returns $A^\#$. Eventually use $A^\#$ to compute f in part a) of PS.3 (lls via normal equations).