David Matos Curriculum Vitae

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05/2015 - 09/2016 (PT)

Florida Institute of Technology Formula Team, United States

Suspension Team Lead

Matlab, Simulink, SolidWorks, ANSYS

Led a subteam of 5 people making sure deadlines, and all design requirements were met for the competition. Performed an finite element analysis of the suspension uprights using ANSYS workbench, along with its design in Solidworks. Contributed to development of the vehicle dynamics model using MATLAB and Simulink.

EDUCATION

09/2018 - 10/2020

M.Sc. Automotive Technology

Eindhoven University of Technology, Netherlands Department of electrical engineering, signal processing systems group.

Thesis title: "Analysis of multiple modality object detectors and 3D multiple object tracking"

09/2012 - 09/2016

B.Sc. Mechanical Engineering

MAGNA CUM LAUDE

Florida Institute of Technology, United States Senior Design Project: Design of a Formula Student car for FSAE Michigan Competition.

PROJECTS

02/202I - PRESENT

PyTorch - Flask X-Ray Disease detection

PyTorch, Python, JavaScript, Flask, Git

Trained EfficientDet network on the Chest-anomaly kaggle dataset. Evaluation was performed using COCO evaluation. Deployed as a web app using Flask to show predictions. Personal github project

12/2.02.0 - 01/2.02.1

Plant Instance Segmentation

PyTorch, Python, Git

Implemented instance segmentation network Mask-RCNN to count and segment plants on a private dataset. Evaluated model qualitatively and quantitatively using COCO metrics. Training was performed on Google Cloud Console.

02/2020 - 10/2020

Pointrenn detections with ROS

PyTorch, Python, ROS, Git

Implemented SoA object detector in KITTI with ROS. Detections are visualized in LiDAR and camera space using RVIZ. Personal github project

PERSONALIA

NAME, INITIALS FIRST NAME

STREET, HOUSE NUMBER ZIPCODE, CITY COUNTRY DATE OF BIRTH PLACE OF BIRTH

David De Lampendriessen 31 5612 AH, Eindhoven the Netherlands 06/12/1993 Panama, Panama Panamanian Male

Matos Rodriguez, D.E.

EXPERIENCE

NATIONALITY

GENDER

12/2019 - 09/2020 (PT)

Master Graduation Thesis, Netherlands

Analysis of multiple modality object detectors and 3D multiple-object tracking

Python, PyTorch, ROS, Git, Docker

Benchmarked different object detectors based on camera, LiDAR sensors and implemented multiple affinity measures for data association, and Kalman Filter for state estimation in a 3D object tracking algorithm for autonomous driving. The final algorithm was implemented in the TU/e autonomous vehicle and tested with a sample real driving scenario.

09/2019 - 12/2019 (FT)

ViNotion, Netherlands

Deep Learning Intern

PyTorch, Python

Implemented FasterRCNN and SSD object detector networks with PyTorch to analyze the effects of obfuscating license plates at different levels. Additionally, different datasets were used for training purposes and determine the robustness of using a particular object detector, which could also be implemented on the perception module of an autonomous vehicle

09/2018 - 09/2019 (PT)

University Racing Eindhoven, Netherlands Accumulator Engineer

Siemens NX10

TU Eindhoven's Formula Student team, the perfect environment to apply theoretical knowledge, where I designed some of the accumulator internals such as brackets, mounts or any other support for PCBs, which were then 3D printed. Additionally, performed Finite Element Analysis on components to make them up to spec. Furthermore, I had the final responsibility of the Engineering Design Judging team, which defends all technical design choices made at the competition.

07/2016 - 07/2017 (FT)

Fiat Chrysler Automobiles, United States

Catalyst Development Engineer

Responsible for resolving build issues related to powertrain to maintain build timing. Also responsible for reviewing with other powertrain engineers part requirements for each mule/proto build, to develop and publish Bill of Materials in database.

Kitti data to Bag tool

C++,ROS, Git

A tool to convert raw data from the automotive KITTI dataset to a ROS bag, using the ROS PointCloud Library to convert the point clouds. Personal github project

04/2019 - 07/2019

Kaggle Speech Recognition

TensorFlow, Python

Implemented network which consists of correctly predicting to different words from an audio file, which is converted to an spectrogram for input to CNN for training. Competition hosted by Kaggle. Team of 5 people

COMPUTER SKILLS

PROFICIENT WITH Python, PyTorch, TensorFlow, ROS,

Matlab, Git, OpenCV

FAMILIAR WITH Docker, C++, Flask

LANGUAGES

ENGLISH Advanced

DUTCH Intermediate

SPANISH Native

REFERENCES

Available upon request.

Robust Semantic Segmentation

TensorFlow, Python

Implemented network on which different data augmentation techniques were used to determine its effect on a network performance. Google Cloud was used for training given its vast resources. Results were tested on synthetic Synthia Dataset. Team of 2 people

01/2019 - 04/2019

CityScapes Semantic Segmentation

TensorFlow, Python

Implemented network on which different experiments were done such as changing the optimizer, adding regularization and using full input size images to determine effect on the network with training on Google Cloud Console.