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Team 19 Robot Control Specification

Verification

Laboratory # 2: Requirements and Specification Morgan, Laura Miaw, Jireh Hauser, Steven **Dworak, Catherine** Bertoglio, David **Work Product** Verification of robot control specification document. Includes documentation of inspection, including mistakes and revisions. **Document Revision Information Document Revision Information** 2/24/13 - created

Approval Sheet All group members whose names are listed below approve of the document and contributed fairly. **Member Names** Morgan, Laura Miaw, Jireh **Dworak, Catherine** Bertoglio, David **Pledge** On my honor, as a student, I have neither given nor received unauthorized aid on this assignment. Names Morgan, Laura Miaw, Jireh **Dworak, Catherine** Bertoglio, David

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91	Inspection of Document
92 93 94 95 96 97	Glossary Are all text macros and symbolic constants used in specification included in glossary? Yes. Are all symbolic constants unchanging? Yes. Are they all defined? Yes.
98 99 100 101	Definition of Modes Are all modes defined? Yes. Is there anything the base computer can do that is not included in the modes? No.
102 103	Mode Transition Table Are all modes correctly connected? Yes.
104 105 106 107	User Interface Are all buttons defined as events/input? No. New mock up of GUI must be created Are all displays defined as outputs? Yes.
108 109 110 111	Inputs and Outputs Are all user inputs represented? Verify with use cases Are all outputs to robot represented? Yes.
112 113 114 115	Events All events from user inputs? Yes. All events from output? Yes.
116 117 118 119 120 121	Mistakes \$max_speed\$ and \$arc_radius\$ undefined Table of Contents not updated New mock up image of GUI needed with new changes to inputs and outputs accounted for.
122 123 124 125	Revisions \$max_speed\$ and \$arc_radius\$ to be determined after testing. Table of Contents edited. New mock up to be added by group member absent from meeting.