## Offline

- 1. Plan in Reduced Space (B)
  - No Classifier
- 2. Execute on Robot  $(\Gamma)$

Transition Data

- 3. Label Reliable/Unreliable (l)
- 4. Train Classifier

Classify function

## **Online**

- 5. Plan in Reduced Space (B)
- Use Classify Function
- 6. Execute on Robot (Γ)