

$$a.) d(x_1, x_2) = \bar{P}_{x_1} - x_2 = \lim_{T \rightarrow \infty} \frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt$$

$$x_1(t) = A e^{j\omega_0 t}$$

$$x_2(t) = B e^{j5\omega_0 t} \quad \omega_0 = \frac{2\pi}{T}$$

$$\frac{1}{T} \int_T |x_1(t) - x_2(t)|^2 dt = \frac{1}{T} \left[\int_T |x_1(t)|^2 dt - 2 \int_T x_1(t) x_2(t) dt + \int_T |x_2(t)|^2 dt \right]$$

$$|x_1(t)|^2 = x_1(t) x_1^*(t)$$

$$= \bar{P}_{x_1} - \frac{2}{T} \int_T x_1(t) x_2(t) dt + \bar{P}_{x_2}$$

$$\bar{P}_{x_1} = \frac{1}{T} \int_0^T A e^{j\omega_0 t} \cdot A e^{-j\omega_0 t} dt$$

$$\bar{P}_{x_1} = \frac{1}{T} \int_0^T A^2 e^{j\omega_0 t - j\omega_0 t} dt$$

$$\bar{P}_{x_1} = \frac{1}{T} A^2 \int_0^T 1 dt = \frac{1}{T} [t]_0^T = \frac{A^2}{T} [T - 0]$$

$$\bar{P}_{x_1} = \frac{A^2}{T} \quad \boxed{\bar{P}_{x_1} = A^2}$$

$$\bar{P}_{x_2} = \frac{1}{T} \int_0^T B e^{j5\omega_0 t} \cdot B e^{-j5\omega_0 t} dt$$

$$\bar{P}_{x_2} = \frac{1}{T} \int_0^T B^2 e^{j5\omega_0 t - j5\omega_0 t} dt$$

$$\bar{P}_{x_2} = \frac{B^2}{T} \int_0^T 1 dt = \bar{P}_{x_2} = \frac{B^2}{T} [t]_0^T =$$

$$\bar{P}_{x_2} = \frac{B^2}{T} [T - 0] = \frac{B^2}{T} \rightarrow \boxed{\bar{P}_{x_2} = B^2}$$

$$-\frac{2}{T} \int_0^T A e^{j\omega_0 t} B e^{j5\omega_0 t} dt = -\frac{2}{T} \int_0^T AB e^{j\omega_0 t + j5\omega_0 t} dt$$

$$= -\frac{2}{T} AB \int_0^T e^{j6\omega_0 t} dt$$

$$= -\frac{2}{T} AB \left[\frac{e^{j6\omega_0 t}}{j6\omega_0} \right]_0^T$$

$$= -\frac{2}{T} AB \left[\frac{e^{j6 \frac{2\pi}{T} T}}{j6 \frac{2\pi}{T}} - \frac{e^{j6 \frac{2\pi}{T} 0}}{j6 \frac{2\pi}{T}} \right]$$

$$e^{j12\pi} = \cos(12\pi) + j\sin(12\pi)$$

$$= -\frac{2}{T} AB \left[\frac{1}{j12\pi} - \frac{1}{j12\pi} \right] = 0$$

$$-\frac{2}{T} \int_T x_1(t) x_2(t) dt = 0$$

$$\bar{P}_{x_1} = \frac{2}{T} \int_T x_1(t) x_2(t) dt + P_{x_2} = A^2 - 0 + B^2$$

$$d(x_1, x_2) = \lim_{T \rightarrow \infty} A^2 + B^2 = d(x_1, x_2) = A^2 + B^2$$

$$b) F_s = 5 \text{ kHz}$$

$$x(t) = 3 \cos(1000 \pi t) + 5 \sin(2000 \pi t) + 10 \cos(11000 \pi t)$$

$$x[t = nT_s] = 3 \cos(1000 \pi nT_s) + 5 \sin[2000 \pi nT_s] + 10 \cos[11000 \pi nT_s]$$

$$T_s = \frac{1}{F_s} = \frac{1}{5 \text{ K}} \text{ [s]}$$

$$x[n] = 3 \cos\left[\frac{1000 \pi n}{5 \text{ K}}\right] + 5 \sin\left[\frac{2000 \pi n}{5 \text{ K}}\right] + 10 \cos\left[\frac{11000 \pi n}{5 \text{ K}}\right]$$

$$x[n] = 3 \cos\left[\frac{\pi}{5} n\right] + 5 \sin\left[\frac{2 \pi}{5} n\right] + 10 \cos\left[\frac{11 \pi}{5} n\right]$$

$$\Omega_1 = \frac{\pi}{5}; \quad \Omega_2 = \frac{2 \pi}{5}; \quad \Omega_3 = \frac{11 \pi}{5}$$

Ω_3 es una copia

$$\frac{11 \pi}{5} > \pi; \quad -\pi \leq \Omega \leq \pi$$

$$\Omega_{3_{\text{copy}}} = \frac{11 \pi}{5} - 2 \pi = \frac{\pi}{5}$$

$$x[n] = 3 \cos\left[\frac{\pi}{5} n\right] + 5 \sin\left[\frac{2 \pi}{5} n\right] + 10 \cos\left[\frac{\pi}{5} n\right]$$

$$x[n] = 13 \cos\left[\frac{\pi}{5} n\right] + 5 \sin\left[\frac{2 \pi}{5} n\right]$$

$$\omega_1 = 1000 \pi; \quad \omega_2 = 2000 \pi; \quad \omega_3 = 11000 \pi$$

$$F_1 = \frac{1000 \pi}{2 \pi}; \quad F_2 = \frac{2000 \pi}{2 \pi}; \quad F_3 = \frac{11000 \pi}{2 \pi}$$

$$F_1 = 500 \text{ [Hz]}; \quad F_2 = 1000 \text{ [Hz]}; \quad F_3 = 5500 \text{ [Hz]}$$

$$[F_s = 5 \text{ kHz}] \rightarrow \text{No apropiada} \quad F_s \geq 2 F_{\text{max}}$$

F_s apropiada

$$F_s = 2 [5500] \text{ Hz}$$

$$F_s = 11 \text{ kHz}$$

$$c.) \quad h_e[n] = \{2, 4, 1, 5, 0, 10\} \quad n \in \mathbb{Z}$$

$$x(t) = 20 \cos(t/3) + \cos(t/4) \quad [A]$$

$$\omega_1 = \frac{1}{3} \quad \omega_2 = \frac{1}{4}$$

$$\frac{\omega_1}{\omega_2} = \frac{\frac{1}{3}}{\frac{1}{4}} = \frac{4}{3} \in \mathbb{Q}$$

Señal cuasiperiódica

$$T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{\frac{1}{3}} = 6\pi$$

$$T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{\frac{1}{4}} = 8\pi$$

$$T = T_1 L = T_2 K \quad L, K \in \mathbb{Z}$$

$$\frac{T}{\pi} = \frac{6\pi}{\pi} L = \frac{8\pi}{\pi} K =$$

$$\frac{T}{\pi} = 6L = 8K$$

$$MCM(6, 8) = 24$$

$$24\pi = T$$