

**Digital Design and  
Computer Architecture LU**

# **IP Cores Manual**

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# 1 Mathematical Support Package

## 1.1 Description

The mathematical support package (*math\_pkg*) adds support for mathematical functions which are not available in VHDL.

## 1.2 Dependencies

- None

## 1.3 Required VHDL files

- `math_pkg.vhd`

## 1.4 Supported Functions

- `function log2c(constant value : in integer) return integer;`  
Calculates the logarithm dualis (base 2) of the integer operand and rounds it up to the next integer. Its main usage is to calculate the minimum required memory address width to store a certain amount of data words.
- `function log10c(constant value : in integer) return integer;`  
Calculates the logarithm base 10 of the integer operand and rounds it up to the next integer.
- `function max(constant value1, value2 : in integer) return integer;`  
`function max(constant value1, value2, value3 : in integer) return integer;`  
Determines the maximum of the integer operands. This function is available with two and three operands.

## 2 Synchronizer

### 2.1 Description

The synchronizer component is used to connect external signals (e.g., from push buttons or serial ports) to a design. As these input devices generate signals which not synchronous to internal FPGA clocks, using them without proper synchronization can lead to upsets and hence malfunction of a design.

### 2.2 Dependencies

- None

### 2.3 Required VHDL Files

- sync\_pkg.vhd
- sync.vhd

### 2.4 Component Declaration



#### VHDL Component Declaration:

```

1 component sync is
2   generic(
3     SYNC_STAGES : integer range 2 to integer'high; -- number of synchronizer stages (i.e
      ↳ ., flip flops)
4     RESET_VALUE : std_logic -- reset value of the output signal
5   );
6   port (
7     clk      : in std_logic;
8     res_n    : in std_logic;
9     data_in  : in std_logic;
10    data_out  : out std_logic
11  );
12 end component;
```



#### Generics Description:

Name	Functionality
SYNC_STAGES	Number of flip flop stages used for synchronization
RESET_VALUE	The value, the output signal should have directly after reset



#### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
res_n	in	1	Global reset signal (low active, not internally synchronized)
data_in	in	1	The signal which should be synchronized
data_out	out	1	The synchronized version of the input signal

In the special case that the synchronizer is used for an external global reset signal, the `res_n` port is set to constant one and the reset signal is connected to `data_in`. The processed reset signal can be accessed on port `data_out`.

## 2.5 Interface Protocol

The synchronizer has no special interface protocol. The input signal is sampled with the clock signal `clk`. Therefore an output signal generated which is aligned to the `clk` and has a delay of  $n$  clock cycles, where  $n$  is the number of synchronizer stages (i.e., `SYNC_STAGES`). Spikes or glitches not overlapping a rising clock edge (see example trace in Figure 2.1) will not show up at the synchronizer output.

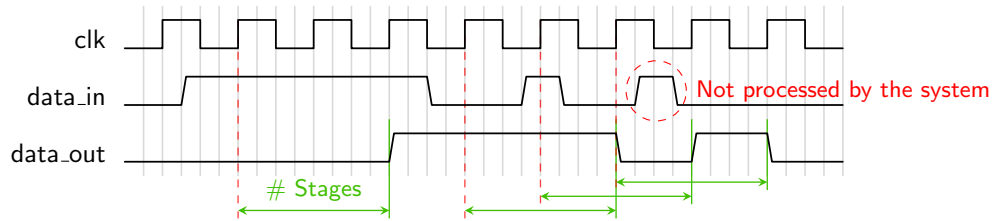


Figure 2.1: Synchronizer timing

## 2.6 Internal Structure

The synchronizer internally consists of a D flip-flop chain. Figure 2.2 shows an example of a three stage synchronizer.

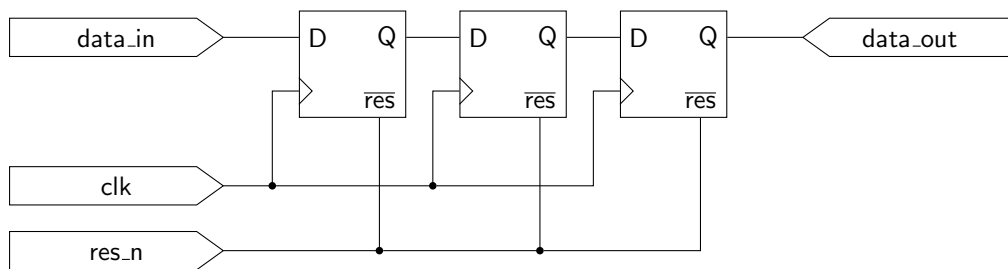


Figure 2.2: Synchronizer circuit

## 3 On-chip Memory Package

### 3.1 Description

Important components in nearly every integrated circuit are memories. If storage with full access speed is required, only on-chip memories are viable options. This package provides an easy way to instantiate on-chip memory, with different access strategies.

Currently there are three memories types available, a single clock dual-port RAM with one read and one write port and two single clock FIFOs with one read and one write port. The FIFO differ in how their read port is operated. While one has a classic read port controlled by a read flag, where the data is then available in the next clock cycle, the other one exhibits first word fall through (FWFT) behavior. For more information see Section 3.5.

### 3.2 Dependencies

- Mathematical support package (math\_pkg)

### 3.3 Required VHDL Files

- ram\_pkg.vhd
- dp\_ram\_1c1r1w.vhd
- fifo\_1c1r1w.vhd
- fifo\_1c1r1w\_fwft.vhd

### 3.4 Component Declarations

#### 3.4.1 Single clock dual-port RAM



#### VHDL Component Declaration:

```

1 component dp_ram_1c1r1w is
2   generic (
3     ADDR_WIDTH : integer;
4     DATA_WIDTH : integer
5   );
6   port (
7     clk : in std_logic;
8     -- read port
9     rd1_addr : in std_logic_vector(ADDR_WIDTH - 1 downto 0);
10    rd1_data : out std_logic_vector(DATA_WIDTH - 1 downto 0);
11    rd1 : in std_logic;
12    -- write port
13    wr2_addr : in std_logic_vector(ADDR_WIDTH - 1 downto 0);
14    wr2_data : in std_logic_vector(DATA_WIDTH - 1 downto 0);
15    wr2 : in std_logic
16  );
17 end component;
```



#### Generics Description:

Name	Functionality
ADDR_WIDTH	The number of address bits
DATA_WIDTH	The number of data bits



### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
rd1_addr	in	ADDR.WIDTH	Address signal of the read port
rd1_data	out	DATA.WIDTH	Data signal of the read port
rd1	in	1	If 1, a read operation is performed on the next rising edge of the clock signal
wr2_addr	in	ADDR.WIDTH	Address signal of the write port
wr2_data	in	DATA.WIDTH	Data signal of the write port
wr2	in	1	If 1, the data of wr2_data is written to address wr2_addr of the memory

### 3.4.2 Single clock FIFO



### VHDL Component Declaration:

```

1 component fifo_1c1r1w is
2   generic (
3     DEPTH : integer;
4     DATA_WIDTH : integer
5   );
6   port (
7     clk : in std_logic;
8     res_n : in std_logic;
9     -- read port
10    rd_data : out std_logic_vector(DATA_WIDTH - 1 downto 0);
11    rd : in std_logic;
12    -- write port
13    wr_data : in std_logic_vector(DATA_WIDTH - 1 downto 0);
14    wr : in std_logic;
15    -- status flags
16    empty : out std_logic;
17    full : out std_logic;
18    half_full : out std_logic
19  );
20 end component;
```



### Generics Description:

Name	Functionality
DEPTH	The depth of the FIFO. This generic must be set to a power of two.
DATA_WIDTH	The number of data bits



### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
res_n	in	1	Global reset signal, low active, not internally synchronized
rd_data	out	DATA.WIDTH	Output data
rd	in	1	If 1, a read operation is performed at the next rising edge of the clock signal. If the FIFO is empty, the result is undefined
wr_data	in	DATA.WIDTH	Data for the write operation
wr	in	1	If 1, the data of wr_data is written to the next free memory location. If the FIFO is full, the write request is ignored
empty	out	1	1, if the memory is empty
full	out	1	1, if the memory is full
half_full	out	1	1, if at least half of the memory of the FIFO contains data.



### 3.4.3 Single clock FIFO with FWFT behavior



#### VHDL Component Declaration:

```

1  component fifo_1c1r1w_fwft is
2    generic (
3      DEPTH : integer;
4      DATA_WIDTH : integer
5    );
6    port (
7      clk : in std_logic;
8      res_n : in std_logic;
9      -- read port
10     rd_data : out std_logic_vector(DATA_WIDTH - 1 downto 0);
11     rd_ack : in std_logic;
12     rd_valid : out std_logic;
13     -- write port
14     wr_data : in std_logic_vector(DATA_WIDTH - 1 downto 0);
15     wr : in std_logic;
16     -- status flags
17     full : out std_logic;
18     half_full : out std_logic
19   );
20 end component;
```



#### Generics Description:

Name	Functionality
DEPTH	The depth of the FIFO. This generic must be set to a power of two.
DATA_WIDTH	The number of data bits



#### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
res_n	in	1	Global reset signal, low active, not internally synchronized
rd_data	out	DATA_WIDTH	Output data
rd_valid	out	1	If 1, the data at <code>rd_data</code> is valid and can be used.
rd_ack	in	1	Indicated to the FIFO that the data at <code>rd_data</code> has been consumed and new data can be applied to <code>rd_data</code> . If no new data is available, because the FIFO is empty, the <code>rd_valid</code> signal, goes low in the next cycle.
wr_data	in	DATA_WIDTH	Data for the write operation
wr	in	1	If 1, the data of <code>wr_data</code> is written to the next free memory location. If the FIFO is full, the write request is ignored
full	out	1	1, if the memory is full
half_full	out	1	1, if at least half of the memory of the FIFO contains data.

## 3.5 Interface Protocol

### 3.5.1 Single clock dual-port RAM

A standard synchronous memory access protocol is used for accessing the RAM. At any rising edge of the `clk` signal, when the `rd1` signal is high, the data word stored at address `rd1_addr` is written to the `rd1_data` port (see Figure 3.1).

At any rising edge of the `clk` signal, when the `wr2` signal is high, the data word at `wr2_data` is written to address `wr2_addr` (see Figure 3.2).

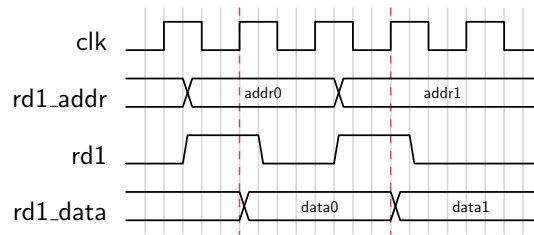


Figure 3.1: RAM read timing.

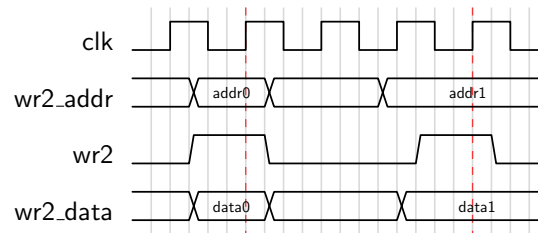


Figure 3.2: RAM write timing

### 3.5.2 Single clock FIFO

The FIFO memory uses a similar interface but does not require the address inputs. The read operation is again initiated by asserting the `rd` signal. If the FIFO is not empty the next data word is assigned to the output `rd_data` (see Figure 3.3). If the FIFO is empty, the result of the read operation is undefined.

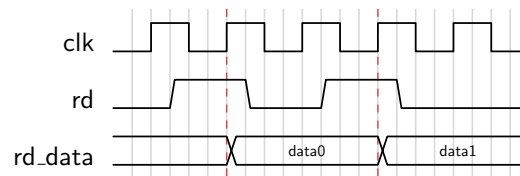


Figure 3.3: FIFO read timing

Asserting the input `wr` performs a write operation on the FIFO. The data word at `wr_data` is stored to the next free location of the internal memory (see Figure 3.4). While the FIFO is full, write operations are ignored.

If the first item is written to the FIFO, the `empty` signal becomes zero in parallel to the storage operation. If the last item is read from the FIFO, the `empty` signal becomes one at the same time the output data is set (see Figure 3.5).

If the FIFO becomes full by a write operation, parallel to the storing process the `full` signal becomes one. If afterwards a data word is read, the full signals becomes zero again at the same time as the output port is set (see Figure 3.6).

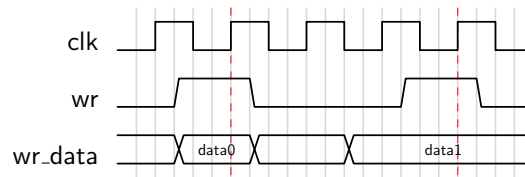


Figure 3.4: FIFO write timing

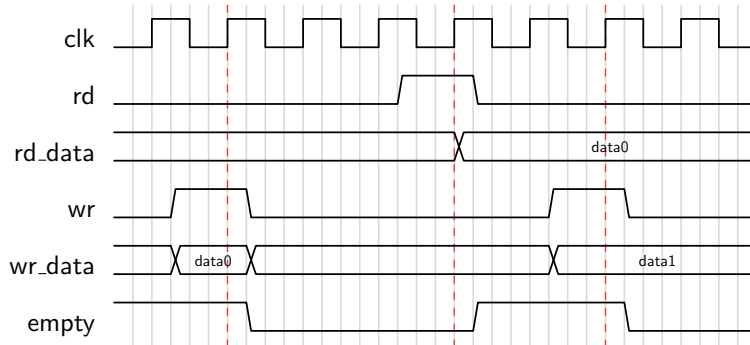


Figure 3.5: FIFO empty handling

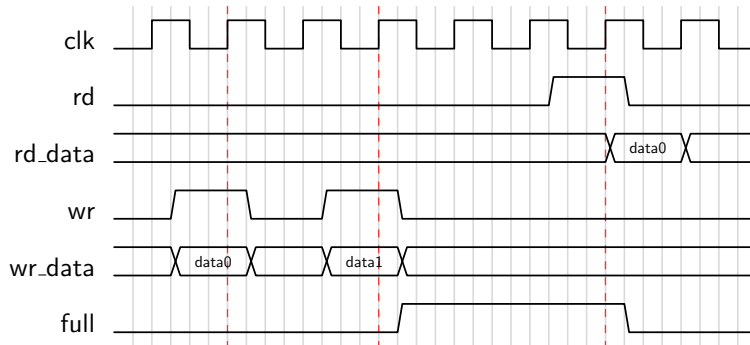


Figure 3.6: FIFO full handling

### 3.5.3 Single clock FIFO with FWFT behavior

The write port of the `fifo_1c1r1w_fwft` behaves exactly to same as for the other FIFO. Figure 3.7 demonstrates how the read port is operated. As soon as the FIFO contains data the `rd_valid` signal is asserted and the next data value can be retrieved at the `rd_data` output. This data value will be kept as long as it is not acknowledged by a high signal level at `rd_ack`. If `rd_ack` is asserted, the FIFO will either deassert `rd_valid` in the next clock cycle, indicating that the FIFO is now empty, or output the next data value at `rd_data`. Note that `rd_ack` must only be asserted if `rd_valid` is asserted. The role of the `empty` signal is now covered by the `rd_valid` signal.

The name for the read behavior of this FIFO comes from the fact, that no interaction is necessary to retrieve the first data value of the FIFO, i.e., it simply “falls through” the FIFO.

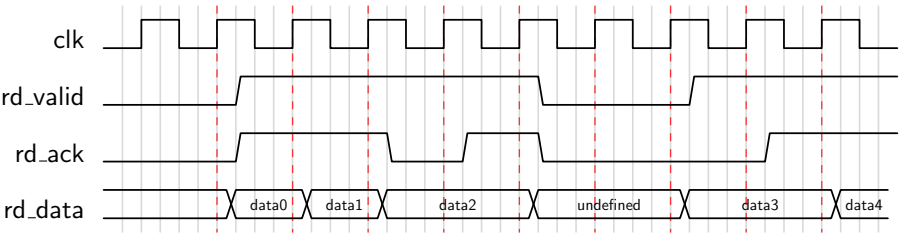


Figure 3.7: FIFO FWFT read timing

## 4 Audio Controller

The `audio_ctrl` module implements a simple synthetic sound generator that interfaces with the board's audio DAC (digital to analog converter) WM8731. This chip has two separate (serial) interfaces, one for configuration purposes (control interface) and another one to receive the actual audio samples (digital audio interface). The control interface is only required during start-up to configure the sampling rate and set up the digital audio interface. Figure 4.1 shows to the general structure of the audio controller.

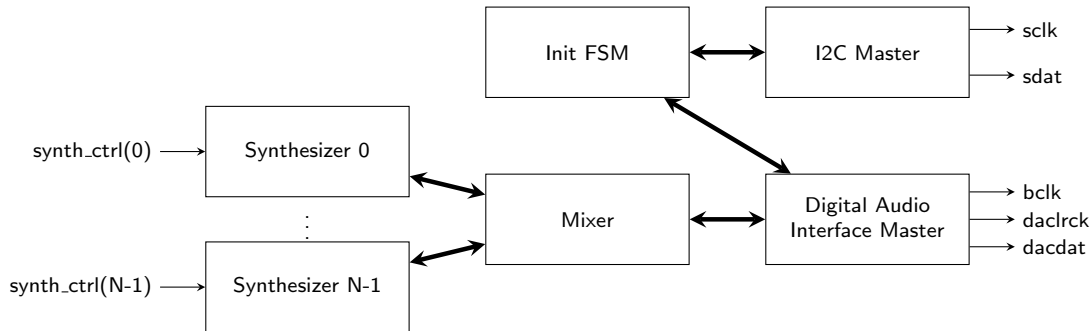


Figure 4.1: Audio controller internal structure

The audio controller must be clocked by a 12 MHz clock (which will internally be forwarded to the `xclk` output). The `synth_ctrl` signals can be written from any clock domain since the core uses synchronizers to bring the required signals into its (12 MHz) clock domain (see Section 4.4).

Note that the audio controller is provided as a precompiled module with two synthesizers (`SYNTH_COUNT = 2`).

### 4.1 Dependencies

Since the audio controller is provided as a precompiled module, there are no external dependencies.

### 4.2 Required Source Files

The audio controller is supplied as a precompiled module in the form of a Quartus II Exported Partition File (.qxp) for synthesis and a netlist file (.vho) for simulation. Additionally a wrapper module `audio_ctrl_s2` is required. The `audio_ctrl_pkg` package provides the component declaration as well as the required type declaration for the synthesizer interface.

- `audio_ctrl_pkg.vhd`
- `audio_ctrl_s2.vhd`
- `audio_ctrl_top.vho`
- `audio_ctrl_top.qxp`

Hence, if you want to simulate your design in Questa/Modelsim, use the files `audio_ctrl_s2.vhd` and `audio_ctrl_pkg.vhd` as well as the netlist file `audio_ctrl_top.vho`. For synthesis in Quartus use `audio_ctrl_s2.vhd` and `audio_ctrl_pkg.vhd` and the Exported Partition File `audio_ctrl_top.qxp`.

### 4.3 Component Declaration



#### VHDL Component Declaration:

```

1  component audio_ctrl_2s is
2  port (
3      clk      : in std_logic; --12 MHz input clock
4      res_n    : in std_logic;
5
6      --clock output signal for the wm8731
7      wm8731_xck      : out std_logic;
8
9      --cfg interface to wm8731: i2c configuration interface
10     wm8731_sdat : inout std_logic;
11     wm8731_sclk : inout std_logic;
12
13     --data interface to wm8731: digital audio interface
14     wm8731_dacdat : out std_logic;
15     wm8731_daclrck : out std_logic;
16     wm8731_bclk   : out std_logic;
17
18     --internal interface to the stynthesizers
19     synth_ctrl : in synth_ctrl_vec_t(0 to 1)
20 );
21 end component;
```



#### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	12 MHz clock signal
res_n	in	1	Reset signal (low active, not internally synchronized)
wm8731_xck	out	1	The 12 MHz clock signal from the clk input.
wm8731_sdat	inout	1	The data signal of the I2C bus of the WM8731's control interface
wm8731_sclk	inout	1	The clock signal of the I2C bus of the WM8731's control interface
wm8731_dacdat	out	1	DAC Digital Audio Data Input of the WM8731's digital audio interface
wm8731_daclrck	out	1	DAC Sample Rate Left/Right Clock of the WM8731's digital audio interface
wm8731_bclk	out	1	Digital Audio Bit Clock of the WM8731's digital audio interface
synth_ctrl	in	synth_ctrl_vec_t (0 to 1)	The synthesizer control signals

### 4.4 Interface Protocol

To interface with the audio controller, the `synth_ctrl` input is used, which allows to control the individual synthesizers. This signal is a 2-element vector of the record type `synth_ctrl_t` shown below.

```

1  type synth_ctrl_t is record
2      play : std_logic;
3      high_time : std_logic_vector(7 downto 0);
4      low_time : std_logic_vector(7 downto 0);
5  end record;
```

Every synthesizer produces a PWM signal which can be configured via the `high_time` and `low_time` entries of this record. These values have to be interpreted with respect to the sampling frequency of the DAC (in this case 8 KHz). If both values are 1, the maximum frequency output signal is generated. This means that in this case the actual samples that are sent to the DAC switch between the maximum and minimum value at every sampling period.

The high-active `play` signal controls the sound play-back, i.e., as long as this signal is high, the respective is played. When the `play` signal switches from low to high, the synthesizer reads the current values of `high_time` and `low_time` and uses those values to generate the PWM signal until `play` returns to zero again

(this means that changing those values while `play` is high has no effect). Hence, to change the PWM signal, the `play` signal must be low for at least one clock cycle (of the 12MHz input clock of the audio controller).

Since the audio controller can be controlled from any clock domain, care must be taken, to correctly handle the clock domain crossing. For that purpose, the core uses 3-stage synchronizers on the `play` signals. The `high_time` and `low_time` are not synchronized! This means that whenever these values are changed, it must be made sure that they are stable long enough such that the audio controller can sample them, without errors. Hence one has to take the synchronization delay into account.

## 5 VGA Graphics Controller

The VGA Graphics Controller performs graphical operations on bitmaps using a command-based interface. These operations include simple geometric operations (e.g., setting individual pixels, drawing lines, etc) as well as the ability to copy and transform (i.e., rotating) a section of one bitmap onto another one, an operation also referred to as bit blitting<sup>1</sup>. Bitmaps are stored in external SRAM, referred to as Video RAM (VRAM) throughout this document. The VGA Graphics Controller interfaces with the ADV7123 video DAC to produce an RGB analog component video signal that can be output through a VGA connector. It supports one fixed output resolution of 320x240 pixels and a color depth of 8 bit (RGB332).

### 5.1 Internal Structure

Figure 5.1 shows an overview of the internal structure of the core.

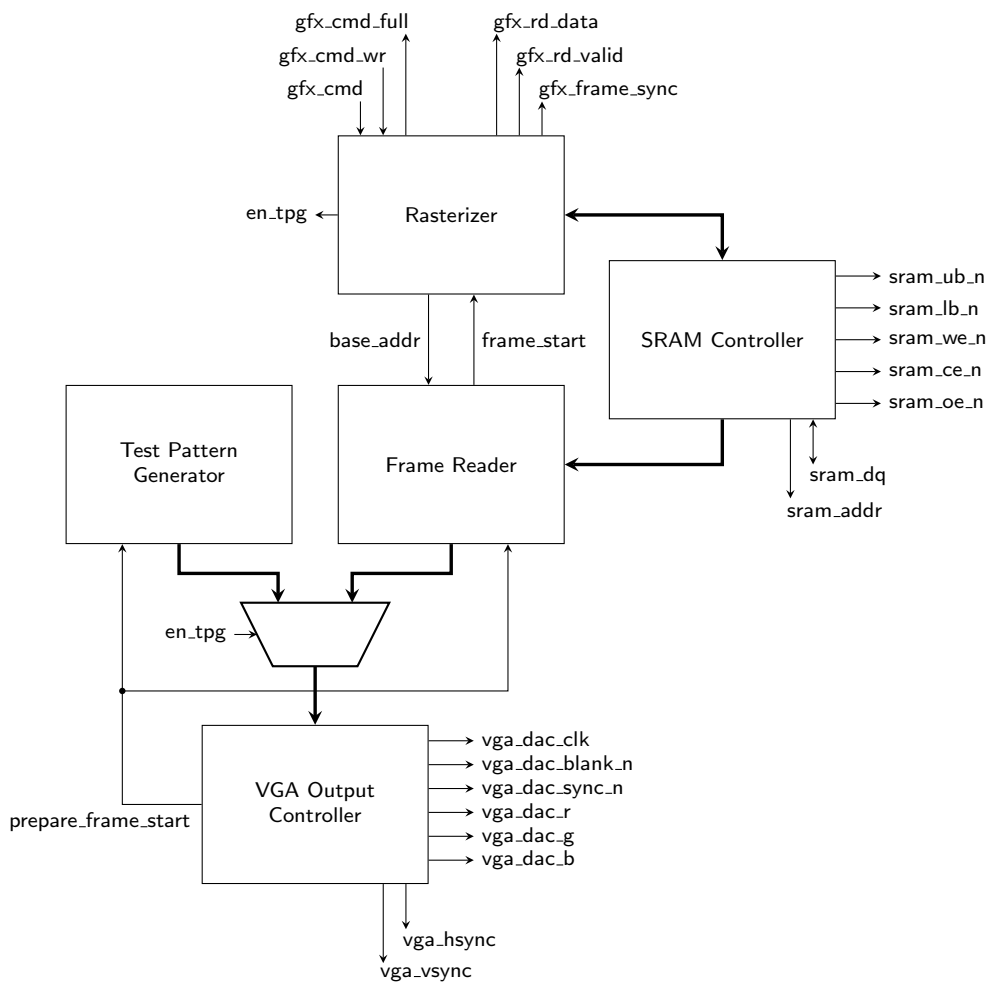


Figure 5.1: VGA Graphics Controller overview

The Rasterizer provides the internal interface to the core, i.e., the signals other IP cores have to connect to, in order to use the VGA Graphics Controller. It executes the actual graphics commands by reading and writing pixel data from and to bitmaps in VRAM. VRAM is byte-addressed, which means that every address corresponds to the 8-bit color value of a single pixel in the RGB332 format. Bitmaps in VRAM are identified by Bitmap Descriptors (BDs), which are stored internally in the Rasterizer. A BD contains 3 values:

<sup>1</sup>[https://en.wikipedia.org/wiki/Bit\\_blit](https://en.wikipedia.org/wiki/Bit_blit)



- base address (unsigned 21 bit)
- width (unsigned 15 bit)
- height (unsigned 15 bit)

BDs are used by the Rasterizer to calculate the effective addresses of pixels in VRAM. Given the pixel coordinates  $x$  and  $y$  for some pixel, its effective address in VRAM is given by

$$[\text{effective address}] = [\text{base address}] + y * [\text{width}] + x$$

The coordinate  $(x, y) = (0, 0)$  points to the pixel of the upper left corner of the bitmap, while  $(x, y) = ([\text{width}] - 1, [\text{height}] - 1)$  points to the lower right corner. Note that bitmaps must always start at even addresses in VRAM (i.e., the LSB of the base address must be zero).

To generate the actual video signal the VGA Output Controller (VOC) creates the appropriate signals for the video DAC (`vga_dac.*`) and the synchronization signals (`vga_hsync` and `vga_vsync`). The actual pixel data required by the VOC either comes from the Test Pattern Generator (TPG) or the Frame Reader. The `prepare_frame_start` signal is used to synchronize these modules. Although the supported resolution of the VGA Graphics Controller is only 320x240 pixels, the VOC outputs a resolution of 640x480. This is done for the sake of compatibility, since not all monitors support resolutions lower than 640x480.

Hence, the Frame Reader and the TPG have to supply image data with a higher resolution. Since the TPG only outputs a static image, this is not really an issue. However, the Frame Reader must perform an upscaling operation on the data read from VRAM. The Frame Reader uses the `frame_start` signal to synchronize the switching of the frame buffer with the Rasterizer, which is necessary in order to support double buffering.

## 5.2 Dependencies

Since the VGA Graphics Controller is provided as a precompiled module, there are no external dependencies.

## 5.3 Required VHDL Files

The VGA Graphics Controller is supplied as a precompiled module in the form of a Quartus II Exported Partition File (`.qxp`) for synthesis and a netlist file (`.vho`) for simulation.

- `vga_gfx_ctrl_pkg.vhd`
- `vga_gfx_ctrl.qxp`
- `vga_gfx_ctrl.vho`

Hence, if you want to perform a simulation on the module in Questa/Modelsim, use the package `vga_gfx_ctrl_pkg.vhd` and the netlist file `vga_gfx_ctrl.vho`. For synthesis in Quartus use `vga_gfx_ctrl_pkg.vhd` and the Exported Partition File `vga_gfx_ctrl.qxp`.

## 5.4 Component Declaration



### VHDL Component Declaration:

```

1 component vga_gfx_ctrl is
2   port (
3     clk      : in std_logic;
4     res_n    : in std_logic;
5     display_clk : in std_logic;
6     display_res_n : in std_logic;
7
8     -- command interface

```

```

9   gfx_cmd      : in std_logic_vector(15 downto 0);
10  gfx_cmd_wr   : in std_logic;
11  gfx_cmd_full : out std_logic;
12  gfx_rd_data  : out std_logic_vector(15 downto 0);
13  gfx_rd_valid : out std_logic;
14  gfx_frame_sync : out std_logic;
15
16  -- external interface to SRAM
17  sram_dq : inout std_logic_vector(15 downto 0);
18  sram_addr : out std_logic_vector(19 downto 0);
19  sram_ub_n : out std_logic;
20  sram_lb_n : out std_logic;
21  sram_we_n : out std_logic;
22  sram_ce_n : out std_logic;
23  sram_oe_n : out std_logic;
24
25  -- connection to VGA connector/DAC
26  vga_hsync : out std_logic;
27  vga_vsync : out std_logic;
28  vga_dac_clk : out std_logic;
29  vga_dac_blank_n : out std_logic;
30  vga_dac_sync_n : out std_logic;
31  vga_dac_r : out std_logic_vector(7 downto 0);
32  vga_dac_g : out std_logic_vector(7 downto 0);
33  vga_dac_b : out std_logic_vector(7 downto 0)
34  );
35  end component;

```



### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal (50 MHz)
res_n	in	1	Global reset signal, low active, not internally synchronized
display_clk	in	1	Clock signal for the actual video signal (25 MHz)
display_res_n	in	1	Reset signal for the display_clk clock domain, low active, not internally synchronized
gfx_cmd_wr	in	1	The write signal of the instruction FIFO
gfx_cmd_full	out	1	The full signal of the instruction FIFO
gfx_cmd	in	16	The actual commands and operands
gfx_rd_valid	out	1	Valid flag for the data returned by read commands. This signal is 1 of exactly one clock cycle.
gfx_rd_data	out	16	The actual data returned by a read command
gfx_frame_sync	out	1	The synchronization signal that allows other cores to synchronize to the start of a new frame
sram_dq	inout	20	SRAM data inputs/outputs
sram_addr	out	16	SRAM address
sram_lb_n	out	1	SRAM lower-byte control
sram_ub_n	out	1	SRAM upper-byte control
sram_we_n	out	1	SRAM write enable
sram_ce_n	out	1	SRAM chip enable
sram_oe_n	out	1	SRAM output enable
vga_hsync	out	1	The horizontal synchronization signal going directly to the VGA connector
vga_vsync	out	1	The vertical synchronization signal going directly to the VGA connector
vga_dac_clk	out	1	The clock signal for the video DAC (25 MHz)
vga_dac_blank_n	out	1	DAC control signal to set the analog output signals for the red, green and blue channels to the blank (black) level
vga_dac_sync_n	out	1	DAC control signal used to embed synchronization information in the green channel, unused, constant 1
vga_dac_r	out	8	DAC input data for the red output channel
vga_dac_g	out	8	DAC input data for the green output channel
vga_dac_b	out	8	DAC input data for the blue output channel

## 5.5 Interface

Graphics commands are fed into the core using the signals `gfx_cmd_wr` and `gfx_cmd`. Internally those signals directly feed a FIFO, referred to as the Command FIFO, whose full flag is in turn output at `gfx_cmd_full`. Hence, this port (i.e., the signals `gfx_cmd_wr`, `gfx_cmd` and `gfx_cmd_full`) behaves exactly like the write port of a FIFO, discussed in Section 3.

The `gfx_frame_sync` signal is only activated for a single clock cycle in response to the execution of a `DISPLAY_BMP` command and allows the synchronization of an interfacing IP core to the start of a new frame output by the VOC.

The signals `gfx_rd_data` and `gfx_rd_valid` are used by commands that read data from VRAM. Whenever the core writes new data to `gfx_rd_data`, `gfx_rd_valid` is asserted for exactly one clock cycle. The data on `gfx_rd_data` remains valid until `gfx_rd_valid` goes high again.

## 5.6 Graphics Commands

A graphics command always consists of a 16 bit instruction and a number of 16 bit operands associated with the instruction. Depending on the instruction the number of operands can range from 0 to 4, with one command having a variable number of upto  $2^{16+3}$  operands. This means that for most instructions multiple 16 bit words must be issued to the Command FIFO using the inputs `gfx_cmd_wr` and `gfx_cmd`.

Internally the VGA Graphics Controller maintains a number of registers, which define its internal state are used by and modified through the execution of graphics commands:

- Active Bitmap Descriptor `abd` (51 bit)
  - `abd.base` (unsigned 21 bit)
  - `abd.width` (unsigned 15 bit)
  - `abd.height` (unsigned 15 bit)
- Graphics Pointer `gp` (2x16 bit)
  - `gp.x` (signed 16 bit)
  - `gp.y` (signed 16 bit)
- Primary Color (8 bit)
- Secondary Color (8 bit)
- Bitmap Descriptor Table `bdt` (8 descriptors, i.e., 8x51 bit)
  - `bdt[0]`
    - \* `bdt[0].base` (unsigned 21 bit)
    - \* `bdt[0].width` (unsigned 15 bit)
    - \* `bdt[0].height` (unsigned 15 bit)
  - ...
  - `bdt[7]`
    - \* `bdt[7].base` (unsigned 21 bit)
    - \* `bdt[7].width` (unsigned 15 bit)
    - \* `bdt[7].height` (unsigned 15 bit)
- Bit Blit Effect (10 bit)
  - `maskop` (2 bit)
  - `mask` (8 bit)
- Current Output Address (21 bit)

After reset all registers are initialized to 0.

The `abd` defines the bitmap that is the target of all subsequent drawing operations. The `gp` register represents a 2D coordinate on this bitmap (i.e., the current image in VRAM that the graphics instructions draw to) and is used by most drawing commands (e.g., `SET_PIXEL`, `DRAW_HLINE`, `BB_*`, etc.). The coordinate `gp.x = 0`, `gp.y = 0` points to the pixel of the upper left corner of the bitmap, while `gp.x = abd.width-1`, `gp.y = abd.height-1` points to the lower right corner. Since `gp.x` and `gp.y` are **signed 16 bit** values, it is possible that the `gp` points to a location outside of the bounds of the active bitmap. This is completely fine, as the Rasterizer ensures that a write access to a pixel outside of the bounds, will simply have no effect (i.e., it performs clipping). Hence, drawing a line from (0,0) to (10,0) will produce the exact same result as drawing a line from, e.g., (-10,0) to (10,0). The `gp` is changed explicitly using the `MOVE_GP` and `INC_GP` instructions. However, all drawing commands offer the possibility to automatically move the `gp` upon command completion.

The `bdt` holds 8 bitmap descriptors that are used (referenced) by certain commands (using the 3 bit instruction field `bmpidx` as an index to this table). The `BB_*` commands always read this table to get the descriptors of the source bitmap of the blitting operation. Data is written to the `bdt` using the `DEFINE_BMP` command. Furthermore, the commands `DISPLAY_BMP` and `ACTIVATE_BMP` read the `bdt`.

The core also contains two 8 bit color registers, the primary and the secondary color. An instruction can refer to one of these colors using its `cs` (color selector) field, where 0 (1) refers to the primary (secondary) color. The colors are set using the `SET_COLOR` instruction.

A few commands (`VRAM_*`, `DEFINE_BMP`) have to specify a VRAM address in their operands. Since operands are only 16 bits wide and a VRAM address requires 21 bits, two operands (`addrlo` and `addrhi`) are used for this purpose. The resulting VRAM (byte) address is obtained by concatenating the lower 16 bits (`addrlo`) with the upper 5 bits (`addrhi`), which we denote by `addrhi & addrlo`. The `VRAM_*` commands allow to access individual bytes and words<sup>2</sup> in VRAM. Accessing words is only permitted on even addresses, i.e., the LSB of the address must be zero. The byte order used is little-endian. Assume that 0x12 is stored in address 0x0 in VRAM and that address 0x1 stores 0x34. Reading a word from address 0x0, thus, returns 0x3412.

The `BB_CLIP` command is the most generic of the bit blit commands, but needs 4 separate arguments. For this reason the core also supports the simpler `BB_FULL` and `BB_CHAR` commands. The following (Python) listing demonstrates how the bit blit operations calculate the read address for a pixel in the source bitmap and the write address for the respective pixel destination bitmap.

```

1  #!/bin/env python3
2
3  from collections import namedtuple
4  from enum import Enum
5
6  BD = namedtuple("BD", ["base_address", "width", "height"])
7  BMPSection = namedtuple("BMPSection", ["x", "y", "width", "height"])
8  Point = namedtuple("Point", ["x", "y"])
9  Rotation = Enum("Rotation", "R0 R90 R180 R270")
10
11 def BitBlit(dst, dst_position, src, src_section, rotation):
12     for x in range(0, src_section.width):
13         for y in range(0, src_section.height):
14             dst_x_offset = src_section.width-1-x if rotation in [Rotation.R180, Rotation.R270]
15             ↪ else x
16             dst_y_offset = src_section.height-1-y if rotation in [Rotation.R90, Rotation.R180]
17             ↪ else y
18             if rotation in [Rotation.R90, Rotation.R270]:
19                 # swap coordinates
20                 dst_x_offset, dst_y_offset = dst_y_offset, dst_x_offset
21                 dst_x = dst_position.x + dst_x_offset
22                 dst_y = dst_position.y + dst_y_offset
23                 src_x = src_section.x + x
24                 src_y = src_section.y + y
25
26                 src_addr = src.base_address + src_y * src.width + src_x
27                 dst_addr = dst.base_address + dst_y * dst.width + dst_x

```

<sup>2</sup>In the context of this core a word is considered to be 16 bit (i.e., 2 byte) wide.

```

26     print(f"source pixel ({src_x},{src_y}) (addr={hex(src_addr)}) --> destination
    ↳ pixel ({dst_x},{dst_y}) (addr={hex(dst_addr)})")
27
28 BitBlit(
29     dst=BD(0,320,240),
30     dst_position=Point(10, 20),
31     src=BD(320*240,8,4),
32     src_section=BMPSection(0,0,4,4),
33     rotation=Rotation.R0
34 )

```

Now a detailed bit-level specification of each command supported by the VGA Graphics Controller follows. Note that the core does not check or prevent overflows in the `gp` or the execution of bit blit operations with illegal source image section dimensions. In such a scenario the behavior of the core becomes undefined.

---

### NOP

#### Format:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x0										0					

**Description:** Do nothing.

---

### MOVE\_GP

#### Format:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x1					0								rel	0	
								x							
								y							

**Description:** Sets the `gp` to (x,y). If the `relative` bit is set, `x` and `y` will instead be added to the current `gp` (i.e., `gp.x += x`, `gp.y += y`). The operands `x` and `y` are signed 16-bit values.

---

### INC\_GP

#### Format:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x2										dir		incvalue			

**Description:** Adds the signed 10 bit integer in `incvalue` to either `gp.y` (`dir=1`) or `gp.x` (`dir=0`). For that purpose `incvalue` is sign-extended.

---

### CLEAR

#### Format:

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x4										cs		0			

**Description:** Sets every pixel in active bitmap to the color specified by `cs`. Does not change the `gp`.

---

### SET\_PIXEL

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x5						cs	0			my	mx	0			

**Description:** Sets the pixel in the active bitmap the **gp** currently points at to the color specified by **cs**. If the **gp** is outside of the bounds of the active bitmap no pixel is set. After that **gp.x** (**gp.y**) is incremented by one if **mx** (**my**) is set.

---

### DRAW\_HLINE

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x6					cs	0				my	mx	0			
dx															

**Description:** Draws a horizontal line between the **gp** and the destination coordinate at (**gp.x** + **dx**, **gp.y**) using the color specified by **cs**. The operand **dx** is a signed 16-bit value. After the line has been drawn **gp.x** is set to the destination *x* coordinate of the line if **mx** is set. If **my** is set **gp.y** is incremented by one.

---

### DRAW\_VLINE

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x7					cs	0				my	mx	0			
dy															

**Description:** Draws a vertical line between the **gp** and the destination coordinate at (**gp.x**, **gp.y** + **dy**) using the color specified by **cs**. The operand **dy** is a signed 16-bit value. After the line has been drawn **gp.y** is set to the destination *y* coordinate of the line if **my** is set. If **mx** is set **gp.x** is incremented by one.

---

### DRAW\_CIRCLE

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x8					cs	0				my	mx	0			
0	radius														

**Description:** Draws a circle with a radius specified by the operand **radius** and its center at the **gp** using the color specified by **cs**. The operand **radius** is an unsigned 15 bit value. After the circle has been drawn **gp.x** (**gp.y**) is incremented by **radius** if **mx** (**my**) is set.

---

### GET\_PIXEL

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0xb						0				my	mx	0			

**Description:** Reads the color of the pixel in the active bitmap the **gp** currently points to and outputs it using **gfx\_rd\_data**/**gfx\_rd\_valid**. Since pixels are 8 bits wide only the lower 8 bits (i.e., 7 downto 0) of **gfx\_rd\_data** are used. The upper bits are set to zero. If the **gp** is outside of the bound of the active bitmap all bits in **gfx\_rd\_data** are set. After that **gp.x** (**gp.y**) is incremented by one if **mx** (**my**) is set.

---

### VRAM\_READ

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0xc					0										m
addrlo															
0											addrhi				

**Description:** Performs a read operation on the VRAM address **addrhi** & **addrlo** and outputs the result using **gfx\_rd\_data/gfx\_rd\_valid**. If **m** is 0, a byte access is performed. In this case the upper byte (15 downto 8) in **gfx\_rd\_data** is set to zero and the read byte is placed in the lower byte (7 downto 0). If **m** is 1, a word access is performed. For a word access the LSB of the address must be zero.

---

### VRAM\_WRITE

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0xd					0										m
addrlo															
0										addrhi					
data															

**Description:** Writes a single byte (**m**=0) or word (**m**=1) to VRAM. If a byte access is performed only the lower 8 bits of the **data** operand are used, the upper 8 bits are ignored. For a word access the LSB of the address must be zero.

---

### VRAM\_WRITE\_SEQ

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0xe					0										m
n															
addrlo															
0										addrhi					
data[0]															
...															
data[n-1]															

**Description:** Writes a sequence of bytes (**m**=0) or words (**m**=1) to VRAM starting at the address **addrhi** & **addrlo**. In byte mode (**m**=0) only the lower 8 bits of each of the operands **data[0]** to **data[n-1]** are used. The last address written is (**addrhi** & **addrlo**) + **n** - 1. In word mode (**m**=1) the last address written is (**addrhi** & **addrlo**) + 2\*(**n** - 1).

---

### VRAM\_WRITE\_INIT

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0xf					0										m
n															
addrlo															
0										addrhi					
data															

**Description:** Initializes a range of memory addresses starting at **addrhi** & **addrlo** to **data**. In byte mode (**m**=0) only the lower 8 bits of the operand **data** are used. The last address written is (**addrhi** & **addrlo**) + **n** - 1. In word mode (**m**=1) the last address written is (**addrhi** & **addrlo**) + 2\*(**n** - 1).

---

### SET\_COLOR

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x10						cs	0	color							

**Description:** Sets the primary (secondary) color to `color` if `cs` is 0 (1). For the actual color value in `color` the RGB332 format is used.

---

### SET\_BB\_EFFECT

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x11						0	maskop	mask							

**Description:** Sets the current BB Effect (i.e., the registers `maskop` and `mask`) used by all subsequent `BB_*` commands. See the entry for `BB_CLIP` for the purpose of these registers.

---

### DEFINE\_BMP

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x12					0								bmpidx		
addrlo															
0											addrhi				
0	width														
0	height														

**Description:** Writes a Bitmap Descriptor to `bdt[bmpidx]`. Bitmaps always start at even addresses. This means that the LSB of the low address is assumed to be zero.

---

### ACTIVATE\_BMP

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x13						0						bmpidx			

**Description:** Sets the Active Bitmap Descriptor by copying `bdt[bmpidx]` to `abd`. All subsequent drawing commands will use this bitmap as their target. Changing `bdt[bmpidx]` with a subsequent `DEFINE_BMP` command does not affect the `abd`.

---

### DISPLAY\_BMP

**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x14						fs	0						bmpidx		

**Description:** Sets the Current Output Address for the Frame Reader to `bdt[bmpidx].base`. If the frame synchronization flag `fs` is 1, the command blocks the execution of the following graphics commands until the Frame Reader starts to fetch a new frame. This feature makes it possible to implement double buffering. If `fs=1` the `gfx.frame_sync` signal is asserted for exactly one clock cycle to indicate that the command has been executed. The dimension of the bitmap referenced by `bmpidx` must be 320x240 pixels, `bdt[bmpidx].width` and `bdt[bmpidx].height` are ignored.



---

**BB\_FULL**
**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x19						am	rot	0	my	mx	0	bmpidx			

**Description:** This command is equivalent to calling BB\_CLIP with the operands (0, 0, bdt[bmpidx].width, bdt[bmpidx].height).

---

**BB\_CHAR**
**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x1a					am	rot		0		my	mx	0	bmpidx		
xoffset										charwidth					

**Description:** This command is equivalent to calling BB\_CLIP with the operands (xoffset, 0, charwidth, bdt[bmpidx].height).

---

**BB\_CLIP**
**Format:**

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
opcode: 0x18					am	rot		0		my	mx	0	bmpidx		
0	x														
0	y														
0	width														
0	height														

**Description:** Performs a bit blit operation by copying (and transforming) the bitmap section defined by **x**, **y**, **width** and **height** of the source bitmap identified by **bmpidx** to the Active Bitmap to the position of the **gp**. If the rectangle defined by unsigned 15-bit operands **x**, **y**, **width** and **height** lies (even only partially) outside of the bound of the source bitmap the behavior of the command is undefined. If the bounds of the drawn image section are outside of the bounds of the destination bitmaps (i.e., the Active Bitmap) clipping is performed. The **rot** field is used to control the rotation of the copied image section and can take the following values:

- 00: no rotation
- 01: 90°clockwise rotation
- 10: 180°clockwise rotation
- 11: 270°clockwise rotation

After the execution of the command **gp.x** (**gp.y**) is incremented by  $dx$  ( $dy$ ) if **mx** (**my**) is 1:

$$dx = \begin{cases} \text{width} & \text{if } \text{rot}=00 \text{ or } \text{rot}=10 \\ \text{height} & \text{otherwise} \end{cases}, \quad dy = \begin{cases} \text{height} & \text{if } \text{rot}=00 \text{ or } \text{rot}=10 \\ \text{width} & \text{otherwise} \end{cases}$$

If the alpha mode (**am**) flag is 1, pixels in the source image that match the secondary color are not copied to the active bitmap. The behavior of this command is changed by the registers **mask** and **maskop**. Depending on the value of **maskop** the pixels read from the source bitmap are transformed by performing a bitwise Boolean operation with the **mask** register before writing them to the Active Bitmap. Let  $c$  be the pixel color read for some pixel of the source bitmap, then  $c'$  will be written to the Active Bitmap:

$$c' = \begin{cases} c & \text{if } \text{maskop} = 00 \\ c \text{ and } \text{mask} & \text{if } \text{maskop} = 01 \\ c \text{ or } \text{mask} & \text{if } \text{maskop} = 10 \\ c \text{ xor } \text{mask} & \text{if } \text{maskop} = 11 \end{cases}$$

When the alpha mode is active (i.e., if **am** is 1) the same transformation is also applied to the secondary color. This is done such that the “transparency” of pixels is preserved. However, the actual register where the secondary color is stored is not changed.

## 6 Game Utility Package

The `game_util_pkg` package contains some utility functions and modules that deal with drawing and colliding shots and space invaders.

### 6.1 Shot Controller

The Shot Controller (`shot_ctrl`) can be used to draw shots and check them for collisions with other objects on the screen. For that purpose it has to communicate directly with the `vga_gfx_ctrl`. The `shot_t` record type is used to hold all information associated with a shot and is fed into the core using its `shot` input.

```
constant SHOT_COORDINATE_WIDTH : integer := 10;
constant SHOT_LENGTH : integer := 4;
constant DOWNWARDS : std_logic := '0';
constant UPWARDS : std_logic := '1';

type shot_t is record
  x : std_logic_vector(SHOT_COORDINATE_WIDTH-1 downto 0);
  y : std_logic_vector(SHOT_COORDINATE_WIDTH-1 downto 0);
  movement_direction : std_logic;
  active : std_logic;
end record;
```

In the context of this package a shot is considered to be a vertical line, one pixel wide and `SHOT_LENGTH` pixels long. The fields `x` and `y` are **signed** values and point to the topmost pixel of this line on the screen. Note that this value range allows for shots to be outside of the visible area of the screen. The field `movement_direction` specifies whether the shot moves up or down. The core itself is not responsible nor capable to actually move shots, but this information is important to calculate exact collision points. The `active` field can be used to deactivate shots. A deactivated shot will neither be drawn nor checked for collisions.

To check a shot for collision with other objects on the screen the core uses `GET_PIXEL` commands to examine whether the pixels occupied by the line representing the shot have a color that is different from black (i.e, pixels with a color value of 0). A color value other than black constitutes a collision. Note that for this to work, the shot must not already have been drawn! The result of the collision check is output using the record type `collision_info_t` on the output `check_result`.

```
type collision_info_t is record
  oob : std_logic;
  color : std_logic_vector(7 downto 0);
end record;
```

The field `color` holds the 8-bit color value of the pixel position for which a collision has been detected. If `color` is equal to the all-zero vector, no collision occurred. If `oob` is asserted the shot is out-of-bounds of the visible display area. In the case of a collision the Graphics Pointer of the `vga_gfx_ctrl` is set to the exact position of the collision!

Drawing a shot involves moving the Graphics Pointer to the position specified by the `shot` input and issuing a `DRAW_VLINE` command.

### 6.2 Space Invader Field

The intended use case for the Space Invader Field (`sifield`) is to initialize, manage and draw a field of space invaders. The dimensions of this field are specified in the package using the constants `SIFIELD_WIDTH` and `SIFIELD_HEIGHT`:

```
constant SIFIELD_WIDTH : integer := 16;
constant SIFIELD_HEIGHT : integer := 5;
constant SIFIELD_DATA_WIDTH : integer := 2;
```

Internally the core uses a RAM block from the `mem_pkg` to hold the required data. Each position in the field is associated with a memory address, which stores 2-bit of data (`SIFIELD_DATA_WIDTH`). The core supports three types of space invaders (which are drawn in different colors). The data word 11 is reserved to represent empty places in the field.



Figure 6.1: Example space invader bitmap with  $8 \times 8$  pixels grid-overlay

The internal memory can be accessed directly using dedicated signals of the core. For reading data the signals `rd`, `rd_location` and `rd_data` are used, while writing involves accessing the inputs `wr`, `wr_location` and `wr_data`. The inputs `rd_location` and `wr_location` are record types that combine the `x` and `y` coordinates of a field location (the position (0,0) corresponds to the upper left location in the field).

```
type sifield_location_t is record
  x : std_logic_vector(log2c(SIFIELD_WIDTH)-1 downto 0);
  y : std_logic_vector(log2c(SIFIELD_HEIGHT)-1 downto 0);
end record;
```

The core can perform three types of operations on/with the field of space invaders.

- Initialization

This operation initializes the field of space invaders to a default pattern. The addresses of each row are set to a particular value (i.e., space invader type).

Row	Value
0	01
1-2	10
3-4	00

- Drawing

Drawing assumes that each space invader has a size of  $16 \times 8$  pixels. The core expects the bitmap specified by the `draw_bmpidx` input to have a height of exactly 8 pixels and a width of at least  $16 \times 3 = 48$  pixels (it can, however, be wider). Figure 6.1 shows how such a bitmap can look like.

Note that the `draw_bmpidx` can be used to change the actual bitmap between drawing operations to animate the space invaders.

The field is drawn with an offset specified by the inputs `draw_offset_x` and `draw_offset_y`.

- Checking

This feature can be used to gather information about the remaining space invaders in the field. Recall that a location in the field is considered empty if the internal memory stores 11 for the address associated with it. When the check concludes, the `check_result` output is updated. For this output the record type `sifield_info_t` is used.

```
type sifield_info_t is record
  l : std_logic_vector(log2c(SIFIELD_WIDTH)-1 downto 0);
  r : std_logic_vector(log2c(SIFIELD_WIDTH)-1 downto 0);
  b : std_logic_vector(log2c(SIFIELD_HEIGHT)-1 downto 0);
  count : std_logic_vector(log2c(SIFIELD_WIDTH*SIFIELD_HEIGHT+1)-1 downto 0);
end record;
```

The entries have the following meaning:

- `l`: The `x` position of the left-most space invader
- `r`: The `x` position of the right-most space invader
- `b`: The `y` position of the bottom-most space invader
- `count`: The total number of space invaders remaining

Consequently, performing a check right after initialization yields:

- `l`: 0
- `r`: `SIFIELD_WIDTH-1`
- `b`: `SIFIELD_HEIGHT-1`
- `count`: `SIFIELD_WIDTH*SIFIELD_HEIGHT`

### 6.3 Dependencies

- Mathematical support package (`math_pkg`)
- GFX Command package (`gfx_cmd_pkg`)
- Memory package (`mem_pkg`)

### 6.4 Required VHDL Files

- `game_util_pkg.vhd`
- `sifield.vhd`
- `shot_ctrl.vhd`

## 6.5 Component Declarations

### 6.5.1 Shot Controller



#### VHDL Component Declaration:

```

1 component shot_ctrl is
2   port (
3     clk : in std_logic;
4     res_n : in std_logic;
5
6     -- GFX command port
7     gfx_cmd : out std_logic_vector(15 downto 0);
8     gfx_cmd_wr : out std_logic;
9     gfx_cmd_full : in std_logic;
10    gfx_rd_data : in std_logic_vector(15 downto 0);
11    gfx_rd_valid : in std_logic;
12
13    -- control signals
14    shot : in shot_t;
15    draw : in std_logic;
16    check : in std_logic;
17    busy : out std_logic;
18    check_result : out collision_info_t
19  );
20 end component;
```



#### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
res_n	in	1	Low active reset signal
gfx_cmd	out	16	GFX command port, actual instructions/operands
gfx_cmd_wr	out	1	GFX command port, write signal
gfx_cmd_full	in	1	GFX command port, full flag
gfx_rd_data	in	16	GFX command port, read data
gfx_rd_valid	in	1	GFX command port, read valid signal
shot	in	shot_t	The shot that should be drawn or checked for collisions.
draw	in	1	This signal is used to initiate a drawing operation. It must be asserted for exactly one clock cycle. The core will react to this event by asserting the busy signal. The shot input must be valid when draw is asserted and must remain valid (and unchanged) until the busy signal goes low. Note that draw and check must never be asserted simultaneously.
check	in	1	This signal is used to initiate the collision check. It is operated exactly as the draw input. When busy goes low (to indicate the completion), check_result is updated.
busy	out	1	The core asserts this signal to indicate that it is currently performing an operation. As soon as it is done, busy goes low again, which allows for a new operation to be started using either the draw or check input. While busy is high draw and check and must remain low.
check_result	out	collision_info_t	The result of the collision check run. This signal is invalid while busy is asserted and is updated with new data when the busy signal goes to low.

### 6.5.2 Space Invader Field



#### VHDL Component Declaration:

```

1 component sifield is
2   port (
3     clk : in std_logic;
4     res_n : in std_logic;
5
6     -- GFX command port
```

```

7   gfx_cmd : out std_logic_vector(15 downto 0);
8   gfx_cmd_wr : out std_logic;
9   gfx_cmd_full : in std_logic;
10
11  -- control signals
12  init : in std_logic;
13  draw : in std_logic;
14  check : in std_logic;
15  busy : out std_logic;
16  check_result : out sifield_info_t;
17  draw_offset_x : in std_logic_vector(GFX_CMD_WIDTH-1 downto 0);
18  draw_offset_y : in std_logic_vector(GFX_CMD_WIDTH-1 downto 0);
19  draw_bmpidx : in std_logic_vector(WIDTH_BMPIDX-1 downto 0);
20
21  -- direct access to internal memory
22  rd : in std_logic;
23  rd_location : in sifield_location_t;
24  rd_data : out std_logic_vector(SIFIELD_DATA_WIDTH-1 downto 0);
25  wr : in std_logic;
26  wr_location : in sifield_location_t;
27  wr_data : in std_logic_vector(SIFIELD_DATA_WIDTH-1 downto 0)
28 );
29 end component;

```



### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	Global clock signal
res_n	in	1	Low active reset signal
gfx_cmd	out	16	GFX command port, actual instructions/operands
gfx_cmd_wr	out	1	GFX command port, write signal
gfx_cmd_full	in	1	GFX command port, full flag
init	in	1	This signal is used to initialize the internal memory to the default pattern of space invaders. It must be asserted for exactly one clock cycle. The core will react to this event by asserting the busy signal. The signals init, draw and check must never be asserted simultaneously.
draw	in	1	This signal is used to draw the field of space invaders. It is operated exactly as the init input. The signals draw_offset_x, draw_offset_y and draw_bmpidx must be valid when draw is asserted and remain valid while busy is high.
check	in	1	This signal is used to perform a check on the field of space invaders regarding the distribution and number of the remaining space invaders. It is operated exactly as the init input. When busy goes low (to indicate the completion), check_result is updated.
busy	out	1	The core asserts this signal to indicate that it is currently performing an operation. As soon as it is done, busy goes low again, which allows for a new operations to be started using either the init, draw and check inputs. While busy is high init, draw, check, rd and wr must remain low.
check_result	out	sifield_info_t	The result of the field check. This signal is invalid while busy is asserted and is updated with new data when the busy signal goes to low.
draw_offset_x	in	GFX_CMD_WIDTH	X drawing offset.
draw_offset_y	in	GFX_CMD_WIDTH	Y drawing offset.
draw_bmpidx	in	WIDTH_BMPIDX	The index of the bitmap used to draw the space invaders.
rd	in	1	Read Port: The read signal of the internal memory. If 1, a read operation is performed on the next rising edge of the clock. signal.
rd_location	in	sifield_location_t	Read Port: The location in the field that should be read. Internally this input is used to calculate the read address of the internal RAM.
rd_data	out	SIFIELD_DATA_WIDTH	Read Port: Data signal
wr	in	1	Write Port: The write signal of the internal memory. If 1, the data of wr_data is written to memory address specified by wr_location.
wr_location	in	sifield_location_t	Write Port: The location in the field that should be written.
wr_data	in	SIFIELD_DATA_WIDTH	Write Port: Data signal

## 6.6 Interface Protocol

The interfaces of both the `sifield` and the `shot_ctrl` are quite similar.

### 6.6.1 Shot Controller

To start an operation of the shot controller, either `draw` or `check` must be asserted for exactly one clock cycle. The core will then assert the `busy` signal and keep it high as long as it is processing and/or generating graphics commands. During this time the `shot` input must not be changed and `draw` and `check` must remain low.

The `shot_ctrl` is designed to communicate (directly) with the `vga_gfx_ctrl`. It, hence, obeys its interface protocol with respect to the `gfx_*` signals.

Figure 6.2 shows an example timing diagram for the `shot_ctrl` where a check operation is performed. The `busy` output can be high for an arbitrary number of clock cycles. This of course depends on how fast the `vga_gfx_ctrl` executes the commands issued by the core. As soon as the `busy` signal is deasserted, a new collision check or drawing operation can be started. The `check_result` output is also updated when `busy` returns to low. It is valid until a new check operation is started.

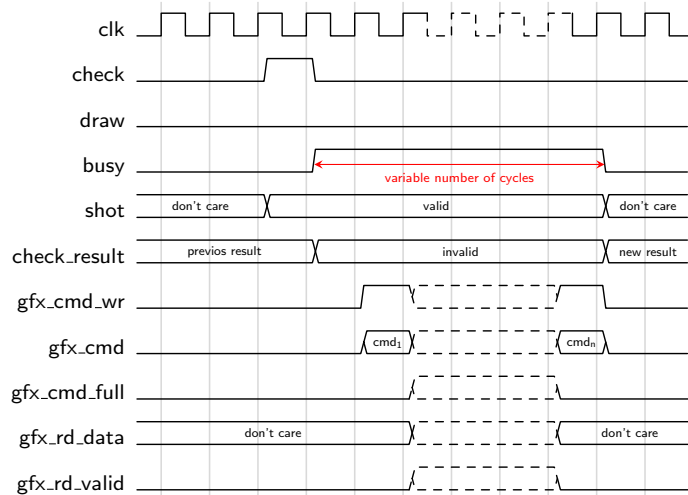


Figure 6.2: Shot Controller example timing diagram

### 6.6.2 Space Invader Field

The `sifield` operates similarly to the `shot_ctrl` with respect to the signals `init`, `check`, `draw` and `busy`.

The read and write ports operate like the ports of a `dp_ram_1c1r1w` (see 3), with the only difference that instead of applying an address `wr_location` or `rd_location` is used.



## 7 Decimal Printer

The `decimal_printer` can be used to print unsigned 16-bit numbers in their 5-digit decimal representation using the `vga_gfx_ctrl`. It always prints leading zeros. The core requires a bitmap index which refers to a bitmap containing the numbers 0-9 (in that order) as 8 pixel wide characters. Figure 7.1 shows how such a bitmap can look like.



Figure 7.1: Example bitmap with 8×8 pixels grid-overlay

It is fine if the bitmap contains further characters, but the first 10 must be the numbers 0-9 as shown in the figure.

The number is printed at the current location of the Graphics Pointer of the `vga_gfx_ctrl`. Afterwards the x coordinate of Graphics Pointer is incremented by  $5 * 8$ .

### 7.1 Dependencies

Since the `decimal_printer` is provided as a precompiled module, there are no external dependencies.

### 7.2 Required VHDL Files

The `decimal_printer` is supplied as a precompiled module in the form of a Quartus II Exported Partition File (.qxp) for synthesis and a netlist file (.vho) for simulation.

- `decimal_printer.vhd`
- `decimal_printer.qxp`
- `decimal_printer.vho`

Hence, if you want to perform a simulation on the module in Questa/Modelsim, use the package `decimal_printer_pkg.vhd` and the netlist file `decimal_printer.vho`. For synthesis in Quartus use `decimal_printer_pkg.vhd` and the Exported Partition File `decimal_printer.qxp`.

### 7.3 Component Declaration



#### VHDL Component Declaration:

```

1 component decimal_printer is
2   port (
3     clk : in std_logic;
4     res_n : in std_logic;
5     gfx_cmd : out std_logic_vector(15 downto 0);
6     gfx_cmd_wr : out std_logic;
7     gfx_cmd_full : in std_logic;
8     start : in std_logic;
9     busy : out std_logic;
10    number : in std_logic_vector(15 downto 0);
11    bmpidx : in std_logic_vector(2 downto 0)
12  );
13 end component;
```



### Port Signals Description:

Name	Dir.	Width/Type	Functionality
clk	in	1	clock signal (50 MHz)
res_n	in	1	reset signal, low active, not internally synchronized
gfx_cmd	out	16	GFX command port, actual instructions/operands
gfx_cmd_wr	out	1	GFX command port, write signal
gfx_cmd_full	in	1	GFX command port, full flag
start	in	1	This signal is used to start a drawing operation. It must be asserted for exactly one clock cycle. The core will react to this event by asserting the busy signal. The inputs <code>bmpidx</code> and <code>number</code> must be valid when <code>start</code> is asserted and must remain valid (and unchanged) until the <code>busy</code> signal goes low.
busy	out	1	The core asserts this signal to indicate that it is currently performing an operation. As soon as it is done, <code>busy</code> goes low again, which allows for a new operation to be started using the <code>start</code> input. While <code>busy</code> is high <code>start</code> must remain low.
number	in	16	The actual number that shall be printed in its decimal form
bmpidx	in	3	The bitmap index containing (8 pixel wide) characters for the numbers 0 to 9

## 7.4 Interface

Figure 7.2 shows an example timing diagram for the `decimal_printer`. After the `start` signal is asserted, the core starts with the conversion process. When its done converting the `number` to its decimal representation it outputs exactly 5 BB\_CHAR commands. As soon as the `busy` signal goes low a new drawing operation can be started.

The `decimal_printer` is designed to communicate (directly) with the `vga_gfx_ctrl`. It, hence, obeys its interface protocol with respect to the `gfx_*` signals.

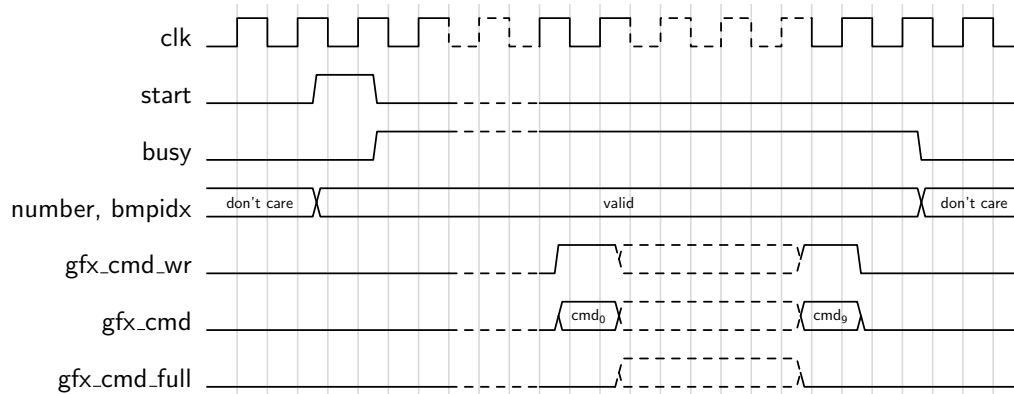


Figure 7.2: Example timing diagram for the `decimal_printer`

## Revision History

Revision	Date	Author(s)	Description
2.0	07.04.2023	FH	Added <code>game_util.pkg</code> and <code>decimal_printer</code>
1.0	09.03.2023	FH	Initial version

### Author Abbreviations:

FH Florian Huemer  
FK Florian Kriebel