considered approach, the structure of the multiagent system is based on the architecture of the OSTIS Ecosystem discussed above and is constantly refined taking into account the addition of new agents to the OSTIS Ecosystem. In terms of classification of agents of OSTIS Ecosystem at the current stage it is proposed to single out only corporate ostis-systems into a separate class due to the fact that they play a special role in the process of organizing collective problem solving. The principles of agents' communication via corporate ostis-systems are discussed in more detail at Step 4

- Step 3: Designing the internal structure of the agent and the principles of its operation. Since all OSTIS Ecosystem agents are ostis-systems (even users of the OSTIS Ecosystem interact with it through personal ostis-assistants, which are ostissystems [4], [8]), additional specification of the principles of their structure is not required, as it is discussed in detail in the works devoted to the OSTIS Technology [4], [16]. To ensure the possibility of interaction between ostissystems over the network, it is proposed to add an interface subsystem to each system, which is discussed in more detail in Step 5.
- Step 4: Develop the principles of agent **interaction.** As mentioned earlier, it is proposed to base the principles of agents' communication within OSTIS Ecosystem during collective problem solving on the principles of agents' communication in the memory of *ostis-systems* (sc-agents). In the work [7] an approach is proposed assuming that one of the *ostis-systems* included in the collective of ostis-systems will be used as a tool of communication for the participants of the collective of ostis-systems. If such collective is formed on a permanent basis (is a ostis-community or a part of it), it is proposed to use the corporate ostis-system of the specified ostis-community as such communicator system. If a collective of ostis-systems is formed temporarily for solving one or several complex problems, i.e. it is necessary to temporarily involve ostis-systems belonging to several ostis-communities, two variants of organizing communication of ostis-systems are possible:
- -One of the systems belonging to such a temporary collective of *ostis-systems* is selected as a communicator system. In this case, such an *ostis-system* becomes temporarily the corporate *ostis-system* of the temporary *ostis-community*.

Accordingly, in this case it is required to install in the ostis-system an interface subsystem for ostissystems and to load into its knowledge base the specifications of other ostis-systems participating in the problem solving process. Thus, the cost of preliminary preparation of a collective of ostis-systems for problem solving can be quite serious, and this approach may be ineffective for relatively simple problems solving. – The corporate ostis-system of the closest hierarchical ostiscommunity is chosen as the communicator system, such that all ostis-systems required for the solution belong either to this ostiscommunity or to more private ostis-communities (possibly on several hierarchical levels). In the example of the ostis-communities hierarchy fragment shown in Figure 2, assuming that the problem solving requires the participation of ostis-systems OS1, OS2, and OS3, then the corporate ostis-system of ostis-community OC1 will be selected as the communicator system.

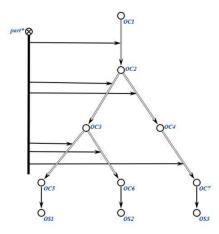


Figure 2. Example of communicator system selection

According to the above architecture of the OS-TIS Ecosystem such an ostis-community will always exist, in the extreme case the role of such a corporate system will be played by the OSTIS Metasystem. The disadvantage of this communication option is that sending messages between the participants of the problem solving process may generally take more time due to the increased path between the corporate ostis-system and the ostis-systems which are performers.

It is important to note that in the presence of such a communicator system, agents at the logical level do not exchange messages directly, but communicate by specifying their actions in the shared memory of the communicator system; nevertheless,