ROB 101 - Fall 2021 Vectors, Matrices, and

Determinants

September 1, 2021



Learning Objectives

- Begin to understand the vocabulary of mathematics and programming.
- An introduction to the most important tools of linear algebra: vectors and matrices.
- Find out an easy way to determine when a set of linear equations has a unique answer.

Outcomes

- Scalars vs. array
- Row vectors and column vectors
- Rectangular matrices and square matrices
- Learn new mathematical notation
- Using matrices and vectors to express systems of linear equations
- Determinant of a square matrix and its relation to uniqueness of solutions of systems of linear equations

Scalars

Scalars are simply numbers such as the ones you have been using for a long time: $25.77763, \sqrt{17}, 10, -4, \pi$.

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Let's define some scalars in Julia.

```
In [1]: # = assigns right hand side to the variable on the left.
a = 25.77763;
b = sqrt(17);
c = 10;
d = -4;
e = π;
println("Hello Scalars!")
print("a= ",a,", b=",b,", c=",c,", d=",d,", e=",e)

Hello Scalars!
a = 25.77763, b=4.123105625617661, c=10, d=-4, e=π
```

Arrays

- Arrays are scalars that have been organized somehow into lists.
- ➤ The lists could be rectangular or not, they could be made of columns of numbers, or rows of numbers.
- ► If you've ever used a spreadsheet, then you have seen an array of numbers.

Let's define some arrays in Julia.

```
In [2]: # we only define arrays of numbers.
         # a is a 1x5 array
         a = [1 -2 4 8.1 \pi]
Out[2]: 1x5 Array{Float64,2}:
         1.0 -2.0 4.0 8.1 3.14159
In [3]: # b is a 5x1 array
         b = [1, -2, 4, 8.1, \pi]
Out[3]: 5-element Array(Float64,1):
          1.0
          -2.0
           4.0
           8.1
           3.141592653589793
In [4]: # or
         c = [1; -2; 4; 8.1; \pi]
Out[4]: 5-element Array{Float64,1}:
          1.0
          -2.0
           4.0
           8.1
           3.141592653589793
```

b and c are equal. We used two different ways of defining a column array using comma and semicolon.

Let's check if Julia recognizes b and c are equal.

```
In [5]: # two arrays are equal if and only if their corresponding
         # entries (elements) are equal.
         # we can use == to check if b is equal c
         h == c
```

Out[5]: true

For us, a *vector* is a finite ordered list of numbers or variables.

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- A row vector has one row and multiple columns. For example, $v = \begin{bmatrix} 1.1 & -3 & 44.7 \end{bmatrix}$, is a row 3-vector (it has three elements in a row!).
- A column vector has multiple rows and one column. For example, $v = \begin{bmatrix} 1.1 \\ -3 \\ 44.7 \end{bmatrix}$, is a column 3-vector.

▶ We denote a general column *n*-vector

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix},$$

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$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix},$$

▶ and a general row *n*-vector

$$v = \begin{bmatrix} v_1 & \cdots & v_n \end{bmatrix}$$
.

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 \triangleright Here is a 3×2 matrix

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}.$$

 \blacktriangleright Here is a 2×3 matrix

$$A = \begin{bmatrix} 1.2 & -2.6 & 11.7 \\ 3.1 & \frac{11}{7} & 0 \end{bmatrix}.$$

ightharpoonup A general *rectangular* matrix of size $n \times m$ takes this form

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nm} \end{bmatrix}.$$

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▶ In matrix A, we denote the ij-element a_{ij} that lies on the intersection of the i-th row and j-th column.

The Matrix Diagonal

The diagonal of the square matrix A is

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \iff \operatorname{diag}(A) = \begin{bmatrix} a_{11} & a_{22} & \cdots & a_{nn} \end{bmatrix}.$$

The Matrix Diagonal

► The diagonal is sometimes called the *main diagonal* of a matrix. What about other elements?

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► The diagonal is sometimes called the *main diagonal* of a matrix. What about other elements?

Let's call them off-diagonal!

Linear Systems of Equations in Matrix Form, $\boldsymbol{A}\boldsymbol{x}=\boldsymbol{b}$

- ightharpoonup We will use the notation Ax = b.
- ightharpoonup A is an $n \times n$ matrix of the coefficients.
- \triangleright x is a column n-vector of the variables.
- \blacktriangleright b is a column n-vector of numbers on the right side of the equation.

Linear Systems of Equations in Matrix Form, $\boldsymbol{A}\boldsymbol{x}=\boldsymbol{b}$

Consider the following system of linear equations with two unknowns.

$$a_{11}x_1 + a_{12}x_2 = b_1$$
$$a_{21}x_1 + a_{22}x_2 = b_2$$

Linear Systems of Equations in Matrix Form, Ax = b

We can also write it as:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix},$$

where:

$$A := \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}, x := \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, b := \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}.$$

Generalization to *n* **Unknowns**

We now write a general system of linear equations as

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

$$\vdots = \vdots$$

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$$

Generalization to *n* **Unknowns**

We can write this system as:

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix},$$

where:

$$A := \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}, x := \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, b := \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}.$$

Express the system of linear equations in matrix form:

$$x_1 + 5x_2 = 4$$
$$3x_1 - x_2 + 7x_3 = 2$$
$$-x_1 + 2x_3 = -5$$

Remark

When one of the x variables is missing from a row, the coefficient is zero, which we have to include in the matrix.

$$x_1 + 5x_2 + 0x_3 = 4$$
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$$\begin{bmatrix} 1 & 5 & 0 \\ 3 & -1 & 7 \\ -1 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ -5 \end{bmatrix}$$

Let's define A and b in Julia.

Look at the systems and declare matrix A and vector b such that Ax=b.

Problem (1)

$$x_1 + 6x_3 - x_4 = 2$$

$$2x_1 - x_2 + 3x_3 + 6x_4 = -9$$

$$-x_1 + 2x_3 = 0$$

$$x_2 + 4x_3 - 2x_4 = 12$$

Problem (2)

Note: These variables are not in a "nice" order. Pay attention to the coefficients, and make sure they are in the correct order.

$$x_4 - 3x_2 + 6x_5 = 7$$

$$2x_3 - x_1 = -5$$

$$x_1 + 4x_5 - 3x_2 + x_4 - 3x_3 = 17$$

$$9x_2 - 3x_1 = 8$$

$$4x_5 + 2x_1 - 7x_3 = -12$$

We take an operational approach to define the determinant (a tricky topic in linear algebra).

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► The determinant is a function that maps a square matrix to a real number.

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- ► The determinant is a function that maps a square matrix to a real number.
- ▶ The determinant of a 1×1 matrix is the scalar value that defines the matrix.

The determinant of a 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is $\det(A) := ad - bc$

▶ The determinant of a 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is $\det(A) := ad - bc$

▶ This notation is another way to express the determinant

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix} = \det \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = ad - bc$$

A formula for the determinant of a 3×3 matrix is

$$\det\left(\begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}\right) := a \begin{vmatrix} e & f \\ h & i \end{vmatrix} - b \begin{vmatrix} d & f \\ g & i \end{vmatrix} + c \begin{vmatrix} d & e \\ g & h \end{vmatrix}$$

Q. Is there a way to compute determinant of any square matrix painlessly?

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```
# Run this block to enable the determinant function
using Pkg
Pkg.add("LinearAlgebra")
using LinearAlgebra
A = [1 2 3; 4 5 6; 7 8 9];
det(A)
```

Why does the determinant matter?

- A square system of linear equations Ax = b will have a unique solution x when $det(A) \neq 0$.
- If det(A) = 0, the system either has no possible solutions or infinite possible solutions.
- ▶ The determinant is only defined for square matrices.

For the following problems, convert the system of equations to the matrix form Ax=b, then find the determinant to see if x has a unique solution. Do not solve for x! We haven't learned that yet.

```
# Declare your matrix for A
A =
# take the determinant of A
det(A)
```

Problem (1)

$$x_1 + x_2 + 2x_3 = 7$$

$$2x_1 - x_2 + x_3 = 0.5$$

$$x_1 + 4x_3 = 7$$

$$x_4 + 2x_3 - 5x_5 = 11$$

$$-4x_2 + 12x_4 = 0$$

Problem (2)

$$x_2 + 2x_5 = 7$$

$$-14x_5 + -7x_2 = 0.5$$

$$-5x_1 + 4x_3 = 7$$

$$x_1 + 2x_2 + 3x_3 + 4x_5 + 5x_5 = 11$$

$$-4x_2 + 12x_4 = 0$$

Next Time

- ► Triangular Systems of Equations
- Forward and Back Substitution
- ▶ Read Chapter 3 of ROB 101 Book