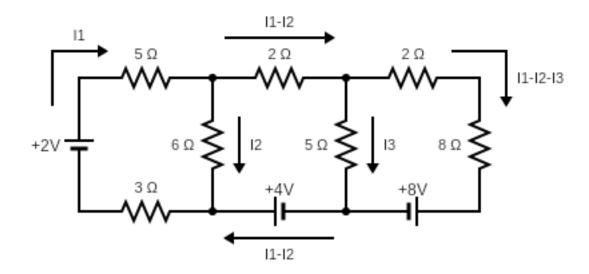
ROB 101 - Computational Linear Algebra Recitation #2

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1 Solving Ax = b using LU Decomposition

- 1. Convert the system of equations into Ax = b
- 2. Decompose the A matrix as A = LU.
- 3. Finally, solve using, Forward Substitution for Ly = b and Backward substitution for Ux = y



In order to find the values of currents I_1 through I_3 in the above circuit diagram, we can use Kirchhoff's rules to represent this circuit as the following system of equations:

$$-5I_1 - 6I_2 - 3I_1 + 2 = 0$$
$$-2(I_1 - I_2) - 5I_3 + 4 + 6I_2 = 0$$
$$-10(I_1 - I_2 - I_3) - 8 + 5I_3 = 0$$

$$-5I_1 - 6I_2 - 3I_1 + 2 = 0$$

$$-2(I_1 - I_2) - 5I_3 + 4 + 6I_2 = 0$$

$$-10(I_1 - I_2 - I_3) - 8 + 5I_3 = 0$$

Solution: First, rearrange the above system of equations to make it easier to represent in matrix form.

$$8I_1 + 6I_2 + 0I_3 = 2$$
$$2I_1 - 8I_2 + 5I_3 = 4$$
$$-10I_1 + 10I_2 + 15I_3 = 8$$

$$A = \begin{bmatrix} 8 & 6 & 0 \\ 2 & -8 & 5 \\ -10 & 10 & 15 \end{bmatrix} \quad x = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}$$

Now, we perform LU decomposition on matrix A

$$A = \begin{bmatrix} 8 & 6 & 0 \\ 2 & -8 & 5 \\ -10 & 10 & 15 \end{bmatrix}$$

Find a column vector C_1 and a row vector R_1 such that $C_1 \cdot R_1 = \begin{bmatrix} 8 & 6 & 0 \\ 2 & * & * \\ -10 & * & * \end{bmatrix}$

$$R_{1} = \begin{bmatrix} 8 & 6 & 0 \end{bmatrix}$$

$$C_{1} = \begin{bmatrix} 1 \\ 1/4 \\ -5/4 \end{bmatrix}$$

$$C_{1} \cdot R_{1} = \begin{bmatrix} 8 & 6 & 0 \\ 2 & 3/2 & 0 \\ -10 & -15/2 & 0 \end{bmatrix}$$

$$A - C_{1} \cdot R_{1} = \begin{bmatrix} 8 & 6 & 0 \\ 2 & -8 & 5 \\ -10 & 10 & 15 \end{bmatrix} - \begin{bmatrix} 8 & 6 & 0 \\ 2 & 3/2 & 0 \\ -10 & -15/2 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -19/2 & 5 \\ 0 & -35/2 & 15 \end{bmatrix}$$

Now find a column vector C_2 and a row vector R_2 such that $C_2 \cdot R_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -19/2 & 5 \\ 0 & -35/2 & * \end{bmatrix}$

$$R_2 = \begin{bmatrix} 0 & -19/2 & 5 \end{bmatrix}$$

$$C_2 = \begin{bmatrix} 0 \\ 1 \\ -35/19 \end{bmatrix}$$

$$C_2 \cdot R_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -19/2 & 5 \\ 0 & -35/2 & -175/19 \end{bmatrix}$$

$$(A - C_1 \cdot R_1) - (C_2 \cdot R_2) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -19/2 & 5 \\ 0 & -35/2 & 15 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & -19/2 & 5 \\ 0 & -35/2 & -175/19 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 460/19 \end{bmatrix}$$

Then the final column vector C_3 and row vector R_3 is just

$$R_3 = \begin{bmatrix} 0 & 0 & 460/19 \end{bmatrix}$$

$$C_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

We combine the row vectors to form our U matrix and the column vectors to form our L matrix:

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 1/4 & 1 & 0 \\ -5/4 & -35/19 & 1 \end{bmatrix}$$

$$U = \begin{bmatrix} 8 & 6 & 0 \\ 0 & -19/2 & 5 \\ 0 & 0 & 460/19 \end{bmatrix}$$

Now we use the equations

$$Ly = b$$
$$Ux = y$$

Forward Substitution:

$$L = \begin{bmatrix} 1 & 0 & 0 \\ 1/4 & 1 & 0 \\ -5/4 & -35/19 & 1 \end{bmatrix} y = \begin{bmatrix} x \\ y \\ z \end{bmatrix} b = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 1/4 & 1 & 0 \\ -5/4 & -35/19 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}$$

$$x = 2$$

$$\frac{x}{4} + y = 4$$

$$\frac{-5x}{4} - \frac{35y}{19} + z = 8$$

$$x = 2$$

$$\frac{x}{4} + y = 4 \rightarrow y = 4 - \frac{2}{4} = \frac{7}{2}$$

$$\frac{-5x}{4} - \frac{35y}{19} + z = 8 \rightarrow z = 8 + \frac{5(2)}{4} + \frac{35(7/2)}{19} = \frac{322}{19}$$

$$x = 2$$

$$y = \frac{7}{2}$$

$$z = \frac{322}{19}$$

Backward Substitution:

$$U = \begin{bmatrix} 8 & 6 & 0 \\ 0 & -19/2 & 5 \\ 0 & 0 & 460/19 \end{bmatrix} x = \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} y = \begin{bmatrix} 2 \\ 7/2 \\ 322/19 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 6 & 0 \\ 0 & -19/2 & 5 \\ 0 & 0 & 460/19 \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 7/2 \\ 322/19 \end{bmatrix}$$

$$8I_1 + 6I_2 = 2$$

$$\frac{-19I_2}{2} + 5I_3 = \frac{7}{2}$$

$$\frac{460I_3}{19} = \frac{322}{19}$$

$$\begin{split} \frac{460I_3}{19} &= \frac{322}{19} \to I_3 = \frac{322}{460} = 7/10 \text{ A} \\ \frac{-19I_2}{2} + 5I_3 &= \frac{7}{2} \to I_2 = (7/2 - 7/2) \cdot -2/19 = 0 \text{ A} \\ 8I_1 + 6I_2 &= 2 \to I_1 = (2 - 6(0))/8 = 1/4 \text{ A} \end{split}$$

$$I_1 = 1/4 \mathbf{A}$$

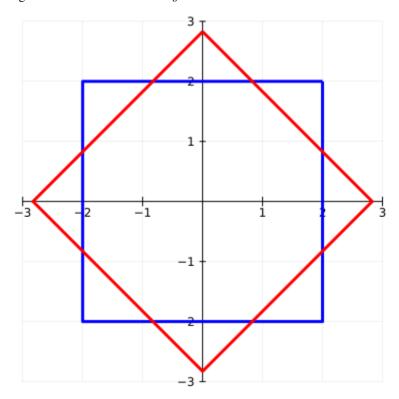
 $I_2 = 0 \mathbf{A}$
 $I_3 = 7/10 \mathbf{A}$

$$A = \begin{bmatrix} 8 & 6 & 0 \\ 2 & -8 & 5 \\ -10 & 10 & 15 \end{bmatrix} \quad x = \begin{bmatrix} 1/4 \\ 0 \\ 7/10 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 6 & 0 \\ 2 & -8 & 5 \\ -10 & 10 & 15 \end{bmatrix} \quad \begin{bmatrix} 1/4 \\ 0 \\ 7/10 \end{bmatrix} \quad = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}$$

2 LU Decomposition with Permutations

- 1. Convert the system of equations into PAx = Pb
- 2. Decompose the A matrix as PA = LU.
- 3. Finally, solve using Forward Substitution for Ly = Pb and Backward substitution for Ux = y



In linear algebra, a rotation matrix is a transformation matrix that is used to perform a rotation on a set of points in Euclidean space about the origin. We will construct the transformation matrix required to rotate the 2-dimensional blue square 45 degrees counter-clockwise so that the result is the red square.

Transforms in 2 dimensions using 2x2 transformation matrices come in the form of

$$Ax = b$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad x = \begin{bmatrix} x \\ y \end{bmatrix} \quad b = \begin{bmatrix} x_{new} \\ y_{new} \end{bmatrix}$$

Pick two coordinates (x_1, y_1) and (x_2, y_2) on the blue square, and then pick (x_{1new}, y_{1new}) and (x_{2new}, y_{2new}) on the red square such that they correspond with a 45° rotation CCW. We can then write out the system of linear equations:

$$ax_1 + by_1 = x_{1new}$$

$$cx_1 + dy_1 = y_{1new}$$

$$ax_2 + by_2 = x_{2new}$$

$$cx_2 + dy_2 = y_{2new}$$

By examining the system of linear equations, we can form a more familiar x as a column vector with terms a, b, c, d. In order to motivate LU factorization, we will continue with this form for the rest of the solution.

$$A = \begin{bmatrix} x_1 & y_1 & 0 & 0 \\ 0 & 0 & x_1 & y_1 \\ x_2 & y_2 & 0 & 0 \\ 0 & 0 & x_2 & y_2 \end{bmatrix} \quad x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \quad b = \begin{bmatrix} x_{1new} \\ y_{1new} \\ x_{2new} \\ y_{2new} \end{bmatrix}$$

Verify for yourself that this Ax = b form results in the above system of equations and continue with the problem

Solution: We will take points

$$(x_1, y_1) = (2, 2)$$

 $(x_2, y_2) = (2, -2)$

from the blue square, giving us an ${\cal A}$ matrix

$$A = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 2 & -2 & 0 & 0 \\ 0 & 0 & 2 & -2 \end{bmatrix}$$

Additionally, we will take points

$$(x_{1new}, y_{1new}) = (0, 2\sqrt{2})$$

 $(x_{2new}, y_{2new}) = (2\sqrt{2}, 0)$

from the red square, giving us the b matrix

$$b = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ 0 \end{bmatrix}$$

By permuting rows to ensure there are no zeros along the diagonal, we get

$$A = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 2 & -2 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 2 & -2 \end{bmatrix} x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} b = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ 0 \end{bmatrix} P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Now, we continue with the LU decomposition process.

Find a column vector
$$C_1$$
 and a row vector R_1 such that $C_1 \cdot R_1 = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 2 & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{bmatrix}$

$$R_4 = \begin{bmatrix} 0 & 0 & 0 & -4 \end{bmatrix}$$

giving us

$$C_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

and finally our LU matrices can be constructed,

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

$$U = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & -4 \end{bmatrix}$$
Now we use the equation

Now we use the equations

$$Ly = P \cdot b$$
$$Ux = y$$

Forward Substitution:

$$L = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} y = \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} b = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ 0 \end{bmatrix}$$

$$w = 0$$

$$w + x = 2\sqrt{2}$$

$$y = 2\sqrt{2}$$

$$y + z = 0$$

$$w = 0$$
$$x = 2\sqrt{2}$$
$$y = 2\sqrt{2}$$

$$z = -2\sqrt{2}$$

Backward Substitution:

$$U = \begin{bmatrix} 2 & 2 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & -4 \end{bmatrix} x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} y = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ -2\sqrt{2} \end{bmatrix}$$

$$\begin{bmatrix} 2 & 2 & 0 & 0 \\ 0 & -4 & 0 & 0 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & -4 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 2\sqrt{2} \\ 2\sqrt{2} \\ -2\sqrt{2} \end{bmatrix}$$

$$2a + 2b = 0$$
$$-4b = 2\sqrt{2}$$
$$2c + 2d = 2\sqrt{2}$$
$$-4d = -2\sqrt{2}$$

$$-4b = 2\sqrt{2} \to b = \frac{2\sqrt{2}}{-4} = -\frac{1}{\sqrt{2}}$$

$$2a + 2b = 0 \to a = -b = \frac{1}{\sqrt{2}}$$

$$-4d = -2\sqrt{2} \to d = \frac{-2\sqrt{2}}{-4} = \frac{1}{\sqrt{2}}$$

$$2c + 2d = 2\sqrt{2} \to c = \sqrt{2} - d = \sqrt{2} - \frac{1}{\sqrt{2}} = \frac{1}{\sqrt{2}}$$

$$a = 1/\sqrt{2}$$

$$b = -1/\sqrt{2}$$

$$c = 1/\sqrt{2}$$

$$d = 1/\sqrt{2}$$

Our final transformation matrix in the 2x2 form is then

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

Remark 1: The general transform matrix for a clockwise rotation by angle θ about the origin is given by

$$T = \begin{bmatrix} cos(\theta) & sin(\theta) \\ -sin(\theta) & cos(\theta) \end{bmatrix}$$

Verify that

$$\begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

for $\theta = -45^{\circ}$ is true!

Remark 2: We aren't limited to transforming 2 ordered pairs as we did in the problem. Nor do we have to rearrange the system of equations every time to result in a column vector x. Recall that the number of columns in matrix A has to equal the number of rows in matrix x. With more coordinates we would simply continue stacking columns of (x_n, y_n) to the right of matrix x and b.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad x = \begin{bmatrix} x_1 & x_2 & \dots & x_n \\ y_1 & y_2 & \dots & y_n \end{bmatrix} \quad b = \begin{bmatrix} x_{1new} & x_{2new} & \dots & x_{nnew} \\ y_{1new} & x_{2new} & \dots & y_{nnew} \end{bmatrix}$$

You can now verify that

$$\begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \quad \begin{bmatrix} 2 & 2 & -2 & -2 \\ 2 & -2 & -2 & 2 \end{bmatrix} \quad = \begin{bmatrix} 0 & 2\sqrt{2} & 0 & -2\sqrt{2} \\ 2\sqrt{2} & 0 & -2\sqrt{2} & 0 \end{bmatrix}$$

is true!

Remark 3: Try using Julia to rotate your own matrix of ordered pairs, multiplied by the general rotation transform matrix with your own option of θ and plot it!