

ROB 101 - Computational Linear Algebra

Recitation #6

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1 Null Space and Range of a Matrix

For any Matrix $A \in_{m \times n}$, then the following sets (are actually Subspaces!) can be defined:

Def. $\text{null}(A) := \{x \in^m \mid Ax = 0_{n \times 1}\}$ is the **null space** of A .

Def. $\text{range}(A) := \{y \in^n \mid y = Ax \text{ for some } x \in^m\}$ is the **range** of A .

Question? What is a null space of a matrix and why is it important?

Source: FAQ Questions <https://umich.instructure.com/courses/475066/files/folder/HW/HW%2006>

2 Basis Vectors

Definition: Suppose that V is a subspace of \mathbb{R}^n . Then $\{v_1, v_2, \dots, v_k\}$ is a basis for V if

- the set $\{v_1, v_2, \dots, v_k\}$ is linearly independent
- $\text{span}\{v_1, v_2, \dots, v_k\} = V$

The dimension of V is k , the number of basis vectors.

Remark: Basis vectors provide a simple means to generate all vectors in a vector space or a subspace by forming linear combinations from a finite list of vectors. The three vectors commonly seen in vector calculus and physics $\hat{i}, \hat{j}, \hat{k}$ are orthonormal basis vectors!

3 Span of a Set of Vectors

Definition: The span of a set of vectors $S \in \mathbb{R}^n$ is:

$$\text{span}(S) := \{\text{all possible linear combinations of elements in } S\}$$

The span operation is useful for generating a subspace from an arbitrary set vectors in \mathbb{R}^n by the definition of the span (contains zero vector and is closed under linear combination). That is, the result of $\text{span}(S)$ is a subspace of \mathbb{R}^n .

4 Column Span of a Matrix

Definition: The column span of an $n \times m$ matrix A is:

$$\text{col}(A) := \text{span}(\{a_1^{\text{col}}, a_2^{\text{col}}, \dots, a_m^{\text{col}}\})$$

i.e., take the columns of matrix A and form a set S containing m vectors in \mathbb{R}^n ($\{a_1^{\text{col}}, a_2^{\text{col}}, \dots, a_m^{\text{col}}\}$) to perform the $\text{span}(S)$ operation.

Remark: $Ax = b$ has a solution if, and only if, b is a linear combination of the columns of A . A more elegant way to write this is $Ax = b$ has a solution if, and only if,

$$b \in \text{col}(A)$$

We can also discuss, rank and nullity of A here as:

Def. $\text{rank}(A) := \dim \text{col span}\{A\}$.

Def. $\text{nullity}(A) := \dim \text{null}(A)$.

5 Eigen values and Eigen Vectors

Let A be an $n \times n$ matrix. A scalar $\lambda \in \mathbb{R}$ is an **eigenvalue** (e-value) of A , if there exists a non-zero vector $v \in \mathbb{R}^n$ such that $Av = \lambda v$. Any such vector v is called an **eigenvector** (e-vector) associated with λ .

Eigenvectors are not unique.

- To find e-values, we solve $\det(\lambda I - A) = 0$ because

$$A \cdot v = \lambda v \iff (\lambda I - A) \cdot v = 0 \xLeftrightarrow{v \neq 0} \det(\lambda I - A) = 0. \quad (1)$$

- To find e-vectors, we find any non-zero $v \in \mathbb{R}^n$ such that

$$(\lambda I - A) \cdot v = 0. \quad (2)$$

Of course, if you prefer, you can solve $(A - \lambda I)v = 0$ when seeking e-vectors.