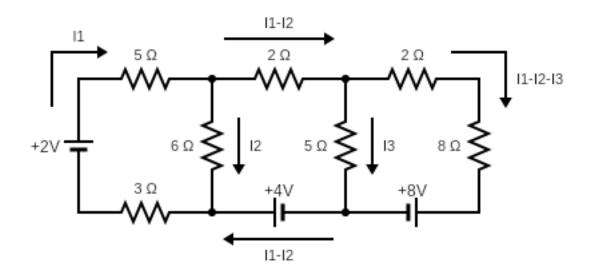
## ROB 101 - Computational Linear Algebra Recitation #2

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## 1 Solving Ax = b using LU Decomposition

- 1. Convert the system of equations into Ax = b
- 2. Decompose the A matrix as A = LU.
- 3. Finally, solve using, Forward Substitution for Ly = b and Backward substitution for Ux = y



In order to find the values of currents  $I_1$  through  $I_3$  in the above circuit diagram, we can use Kirchhoff's rules to represent this circuit as the following system of equations:

$$-5I_1 - 6I_2 - 3I_1 + 2 = 0$$
  

$$-2(I_1 - I_2) - 5I_3 + 4 + 6I_2 = 0$$
  

$$-10(I_1 - I_2 - I_3) - 8 + 5I_3 = 0$$

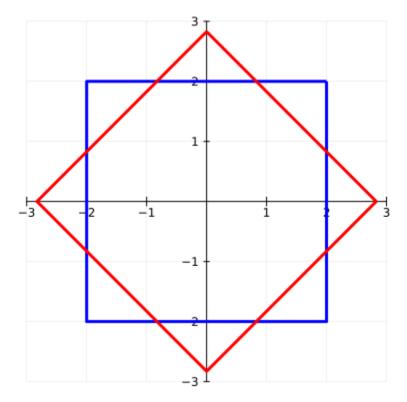
$$-5I_1 - 6I_2 - 3I_1 + 2 = 0$$
  

$$-2(I_1 - I_2) - 5I_3 + 4 + 6I_2 = 0$$
  

$$-10(I_1 - I_2 - I_3) - 8 + 5I_3 = 0$$

## 2 LU Decomposition with Permutations

- 1. Convert the system of equations into PAx = Pb
- 2. Decompose the A matrix as PA = LU.
- 3. Finally, solve using, Forward Substitution for Ly = Pb and Backward substitution for Ux = y



In linear algebra, a rotation matrix is a transformation matrix that is used to perform a rotation in Euclidean space. We will construct the transformation matrix required to rotate the blue square 45 degrees counterclockwise so that the result is the red square.