Tether results comparison and debugging

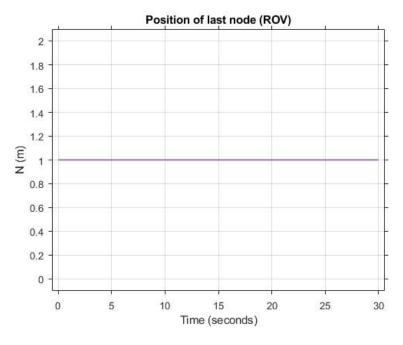


Fig1. Step Unit step input at t=0 s

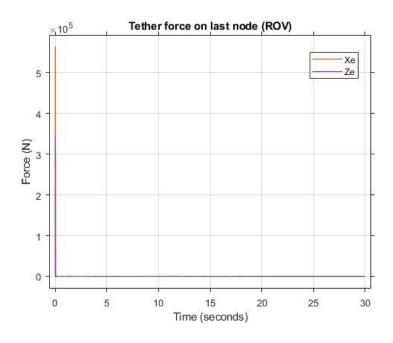


Fig2. Tether force results of benchmark model

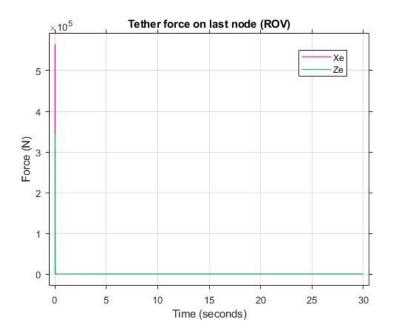


Fig2. Tether force results of my model

At t = 1e - 04 (The time at which the change in acceleration was observed)

The acceleration of 10th node

a) Benchmark

$$\dot{v_i} = \begin{bmatrix} 1.849777911961396 \\ 0 \\ 1.130686047143891 \end{bmatrix} \times 10^6$$

b) My

$$\dot{v_i} = \begin{bmatrix} 1.849777911961395 \\ 0 \\ 1.130686047143890 \end{bmatrix} \times 10^6$$

Difference between benchmark and my results in X direction is:- 9.313226e-10 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 9.313226e-10

The velocity of 10th node

a) Benchmark

$$v_i = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

b) *My*

$$v_i = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The position of 10th node

a) Benchmark

$$p_i = \begin{bmatrix} -2.680951323690902\\0\\22.75 \end{bmatrix}$$

b) *My*

$$p_i = \begin{bmatrix} -2.689051323690902\\0\\22.75 \end{bmatrix}$$

Difference between benchmark and my results in X direction is:- 0.000000e+00 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 0.000000e+00

$\underline{\mathsf{Tension}}\left(T_{i-1}-T_i\right)$

a) Benchmark

$$T_{\rm bm} = \begin{bmatrix} -5.644139726536330e + 05\\ 0\\ -3.450008779788236e + 05 \end{bmatrix}$$

b) My

$$T_{\rm bm} = \begin{bmatrix} -5.644139726536326e + 05\\ 0\\ -3.450008779788234e + 05 \end{bmatrix}$$

Difference between benchmark and my results in X direction is:- 3.492460e-10 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 2.328306e-10

$\underline{ \text{Hydrodynamic force }}(F_i)$

a) Benchmark

$$F_i = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

b) *My*

$$F_i = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

At t = 1.2e - 04 (The time at which the change in Hydrodynamic force was observed)

The acceleration of 10th node

a) Benchmark

$$\dot{v_i} = \begin{bmatrix} 1.762311212736936 \\ 0 \\ 1.098129265192919 \end{bmatrix} \times 10^6$$

b) *My*

$$\dot{v_i} = \begin{bmatrix} 1.762311212736935 \\ 0 \\ 1.098129265192918 \end{bmatrix} \times 10^6$$

Difference between benchmark and my results in X direction is:- 1.164153e-09
Difference between benchmark and my results in Y direction is:- 0.000000e+00
Difference between benchmark and my results in Z direction is:- 9.313226e-10

The velocity of 10th node

a) Benchmark

$$v_i = \begin{bmatrix} 36.995558239227911\\0\\22.613720942877823 \end{bmatrix}$$

b) *My*

$$v_i = \begin{bmatrix} 36.995558239227897 \\ 0 \\ 22.613720942877812 \end{bmatrix}$$

Difference between benchmark and my results in X direction is:- 1.164153e-09
Difference between benchmark and my results in Y direction is:- 0.000000e+00
Difference between benchmark and my results in Z direction is:- 9.313226e-10

The position of 10th node

a) Benchmark

$$p_i = \begin{bmatrix} -2.680951323690902\\0\\22.75 \end{bmatrix}$$

b) *My*

$$p_i = \begin{bmatrix} -2.689051323690902\\0\\22.75 \end{bmatrix}$$

Difference between benchmark and my results in X direction is:- 0.000000e+00 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 0.000000e+00

Tension $(T_{i-1} - T_i)$

a) Benchmark

$$T_{bm} = \begin{bmatrix} -5.644139726536330e + 05\\ 0\\ -3.450008779788236e + 05 \end{bmatrix}$$

b) My

$$T_{my} = \begin{bmatrix} -5.644139726536326e + 05\\ 0\\ -3.450008779788234e + 05 \end{bmatrix}$$

Difference between benchmark and my results in X direction is:- 3.492460e-10 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 2.328306e-10

Hydrodynamic force (F_i)

a) Benchmark

$$F_i = \begin{bmatrix} 2.668829964124261\\0\\0.9933896668861222 \end{bmatrix} \times 10^4$$

b) *My*

$$F_i = \begin{bmatrix} 2.668829964124259\\0\\0.993389666886121 \end{bmatrix} \times 10^4$$

Difference between benchmark and my results in X direction is:- 2.182787e-11 Difference between benchmark and my results in Y direction is:- 0.000000e+00 Difference between benchmark and my results in Z direction is:- 1.091394e-11

Another thing observed is that:

For tension the stiffness term is defined as $K=\dfrac{\left(E imes\left(\dfrac{\pi}{4}\right) imes d^2\right)}{l_0}$ in the paper

However, symbolically generated function simplifies this term and makes it

 $K=E\times d^2\times \left(\frac{1}{l}\right)\times \pi\times \left(\frac{5}{2}\right)$, but I used the above formula as it is and this gives different value of K

 $K_{bm} = 8.125084250018639e + 05$

 $K_{my} = 8.125084250018637e + 05$

After altering the formula of K and keeping it consistent with the benchmark one the results are as follows:

 $K_{bm} = 8.125084250018639e + 05$

 $K_{my} = 8.125084250018639e + 05$

However, still the value of tension is not equal and to further debug it I isolated the components of formula and check individual components for any existing difference.

Fomrula of tension is:

$$T_i = K \times (r_i - r_{i+1}) \times \left(\frac{l \times \left(\frac{1}{||r_i - r_{i+1}||}\right)}{10} - 1\right)$$

Firstly, the comparison of K was done,

$$K_{bm} = 8.125084250018639e + 05$$

$$K_{my} = 8.125084250018639e + 05$$

Secondly, comparison of length of last segment was done,

$$(r_i - r_{i+1})_{bm} = \begin{bmatrix} -3.680951323690902\\ 0\\ -2.25 \end{bmatrix}$$

$$(r_i - r_{i+1})_{my} = \begin{bmatrix} -3.680951323690902\\ 0\\ -2.25 \end{bmatrix}$$

Lastly, the comparison of strain was done,

$$\left(\frac{l \times \left(\frac{1}{||r_i - r_{i+1}||}\right)}{10} - 1\right)_{bm} = -0.188716472134787 \qquad \left(\frac{l \times \left(\frac{1}{||r_i - r_{i+1}||}\right)}{10} - 1\right)_{my} = -0.188716472134787$$

$$T_{bm} = \begin{bmatrix} -5.644139726536330e + 05 \\ 0 \\ -3.450008779788236e + 05 \end{bmatrix} \qquad T_{my} = \begin{bmatrix} -5.644139726536327e + 05 \\ 0 \\ -3.450008779788234e + 05 \end{bmatrix}$$

Therefore, it can be seen that despite of similar values of all the components of tension formula there is difference in the value of tension.

