# Damian Sójka

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🏶 dmn-sjk.github.io 🔊 D. Sójka

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# **Professional Experience**

Dec 2022 - now

### PhD Student, IDEAS NCBR.

• I work on test-time adaptation and computer vision in Continual Machine Learning Group at IDEAS NCBR, a leading Polish R&D center that recently became a member of the ELLIS Society.

Sep 2024 - Nov 2024

## Research Internship, ENSTA Paris.

· I worked on improving the reliability of self-supervised monocular depth estimation through test-time adaptation with Prof. David Filliat and Prof. Antoine Manzanera.

Jul 2021 - Nov 2022

## **Embedded Software Developer, AETHER BIOMEDICAL.**

- Software development of bionic hand prosthesis and its accessories.
- · Responsible for the software used to log the activity and statistics of the prosthesis usage.
- Development of Qt PC app communicating with hand prosthesis.

Jul 2020 - Sep 2020

# Maintenance Department Employee, FARMUTIL HS.

• Inspection, repair and maintenance of production lines.

Aug 2019 - Sep 2019

## Apprentice, QUBIQA.

· Assembly of control cabinets and production line machines based on technical documentation.

# **Education**

Jan 2023 - now

## **PhD in Deep Learning,** Poznan University of Technology.

- My research is focused on test-time adaptation and machine perception.
- Supervisors: Prof. Piotr Skrzypczyński and Prof. Michał Nowicki.

Mar 2021 - Sep 2022

#### MSc in Automatic Control and Robotics, Poznan University of Technology.

- MSc thesis: Triplet Loss in Haptic Localization of a Walking Robot.
- Member of a student team building autonomous race car to compete in Formula Student events.
- Final grade: 4.88 / 5.
- Rector's Scholarship for high-achieving students.

Oct 2017 - Feb 2021

## **BSc in Mechatronics,** Poznan University of Technology.

- BSc thesis: Control of Logistics Tractor Using Artificial Intelligence Methods.
- Final grade: 4.75 / 5.
- Rector's Scholarship for high-achieving students.

# **Papers**

- D. Sójka, M. Masana, B. Twardowski, and S. Cygert, "Adaptive monocular depth estimation with masked image consistency", in Second Workshop on Test-Time Adaptation: Putting Updates to the Test! at ICML 2025, 2025.
- D. Sójka, M. Masana, B. Twardowski, and S. Cygert, "Intransigent teachers guide better test-time adaptation students", in Out-Of-Distribution Generalization in Computer Vision Workshop at European Conference on Computer Vision (ECCV), , 2024, 2024.
- D. Sójka, M. R. Nowicki, and P. Skrzypczyński, "Triplet loss-based metric learning for haptic-only robot localization", in *Progress in Polish Artificial Intelligence Research 5: Proceedings of the 5th Polish Conference on Artificial Intelligence (PP-RAI'2024), 18-20.04.2024, Warsaw, Poland, 2024*, pp. 338–345.
- D. Sójka, B. Twardowski, T. Trzcinski, and S. Cygert, "Ar-tta: A simple method for real-world continual test-time adaptation", in 35th British Machine Vision Conference 2024, BMVC 2024, Glasgow, UK, November 25-28, 2024, BMVA, 2024.
- D. Sójka, M. R. Nowicki, and P. Skrzypczyński, "Learning an efficient terrain representation for haptic localization of a legged robot", in 2023 IEEE International Conference on Robotics and Automation (ICRA), IEEE, 2023.

# Other Achievements

#### **Presentations**

- International Computer Vision Summer School (ICVSS). Presented a poster "AR-TTA: A Simple Method for Real-World Continual Test-Time Adaptation".
- ML in PL Conference. Presented a poster "AR-TTA: A Simple Method for Real-World Continual Test-Time Adaptation".

# **Awards and Grants**

- Polish National Science Centre PRELUDIUM grant for a research project "Reliable and Efficient Real-World Test-Time Adaptation".
- Innovation award and 3rd place in Continual Test Time Adaptation for Semantic Segmentation challenge organized within Visual Continual Learning workshop at ICCV 2023.

# Research interests

My research focuses on deep learning, machine perception, and robotics, with an emphasis on test-time adaptation. I aim to create intelligent, robust perception systems that continuously adapt and acquire new knowledge, possibly advancing lifelong learning in robotics.

# **Skills**

Research

Skilled in devising and executing scientific experiments. Knowledge of how to write scientific papers and publish at peer-reviewed conferences.

Teamwork

Most of my projects were done in small teams of researchers, and I also have history of effective collaborations within diverse international teams.

# **Skills (continued)**

**Programming** 

Proficiency in Python and C, with basic-level skills in C++. Expert-level at PyTorch. Expertise in embedded software development. I have experience working with tools such as Git, Docker, Wandb, ROS, and Linux operating system.

Languages

Fluency in English and Polish.