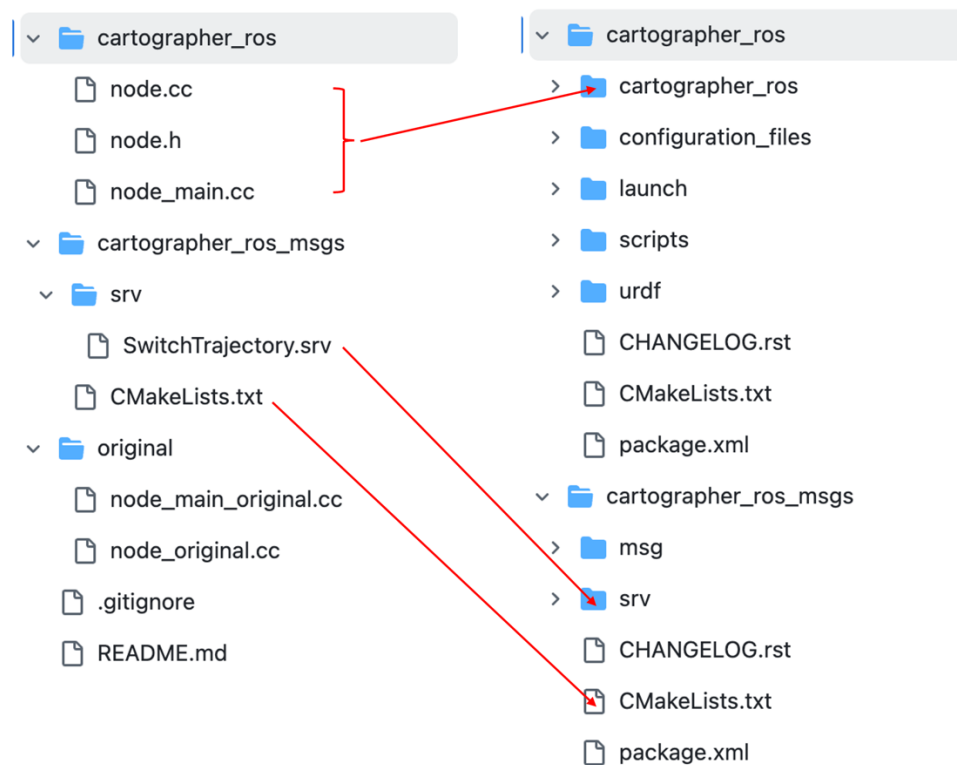


Please follow the steps below to update the cartographer_ros package.

1. Clone or download the repository via the link.

https://github.com/dmnaac/cartographer_ros/tree/switch_trajectory

2. Find the location where cartographer_ros is installed.
3. Copy the files listed in the left to the folders in the right and replace the files with the same name.



4. Rebuild the cartographer_ros package.

Note: The 'original' folder contains the original copies of the modified codes.