Please follow the steps below to update the cartographer\_ros package.

1. Clone or download the repository via the link.

<https://github.com/dmnaac/cartographer_ros/tree/switch_trajectory>

1. Find the location where cartographer\_ros is installed.
2. Copy the files listed in the left to the folders in the right and replace the files with the same name.

A screenshot of a computer

Description automatically generated

1. Rebuild the cartographer\_ros package.

Note: The ‘original’ folder contains the original copies of the modified codes.