SHEET

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Sub-Nanometer Sca
OF A SERIES

Number Systems f

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dmparrishphd/projects/1

Sub-Nanometer Scale GIS:
Number Systems for GIS

DRAWN BY

D. Michael Parrish

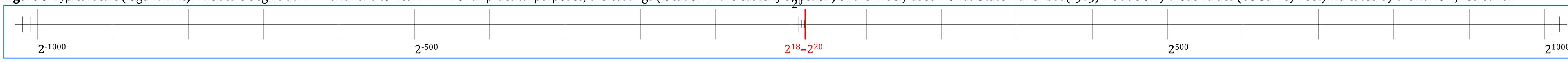
PRESENTED AT
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Sub-Nanometer Scale GIS Number Systems for GIS

THE PROGRAM FOR
UNIVERSAL
COMPUTATIONAL
FREEDOM

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Figure o. Typical scale (logarithmic). The scale begins at 2-1022 and runs to near 21024. For all practical purposes, the eastings (location in the easterly direction) of the widely-used Florida State Plane East (1983) include only those values (US Survey Feet) indicated by the narrow, red band.

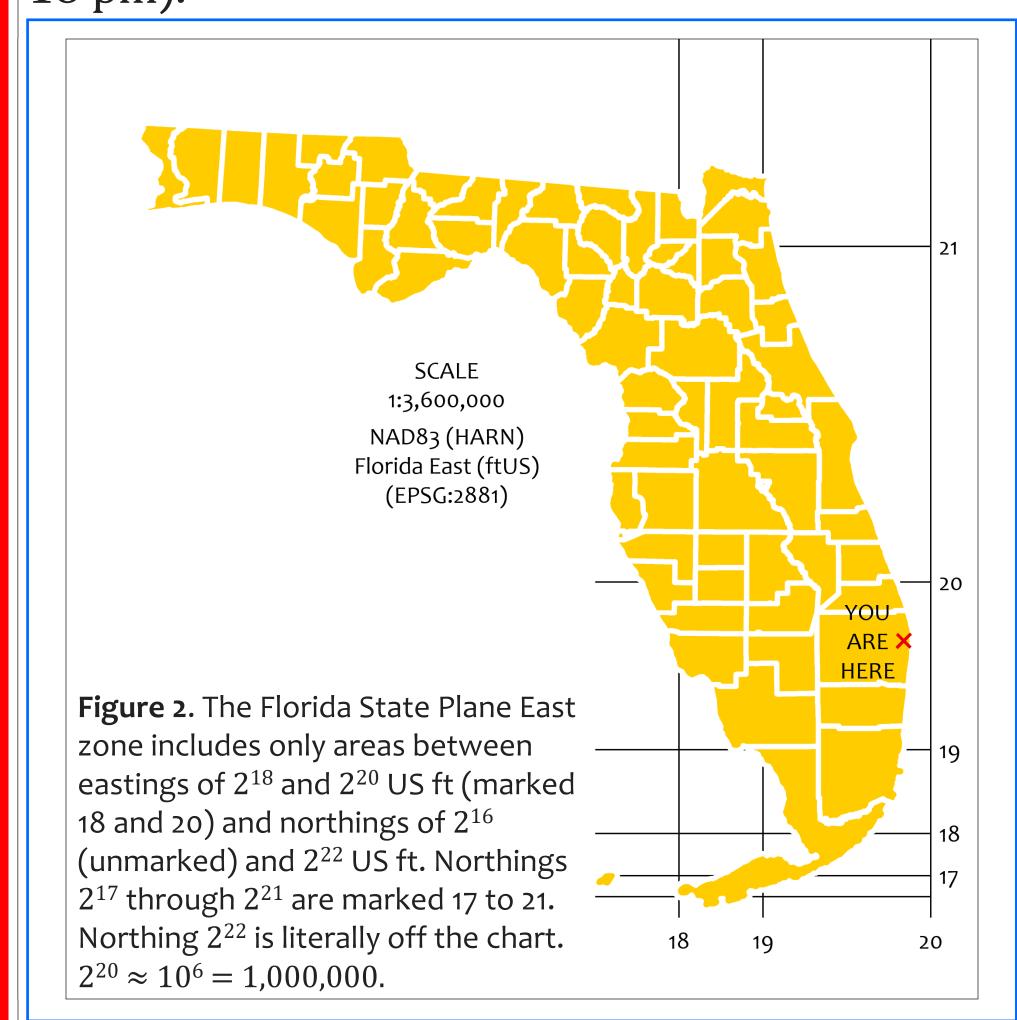


There is a disconnect, typically, between actual GIS problems and the representation of geographic locations in hardware addressing those problems. Locations are often stored as floating-point values: this wastes significant storage, time, and energy.

Figure 1. Typical **64-bit–word** representation of floating-point values uses 53 bits of precision (p, black), eleven bits of exponent (e, red), and one sign bit (s, blue) to represent values $(-1)^s(1+p/2^{53})\times 2^{e-1023}$.

For example, in data sets using the NAD83 HARN Florida East State Plane and units of US Survey Feet, eastings cover only two orders of magnitude, from roughly 2¹⁸ to less than 2²⁰. In other words, although only one bit is needed for the exponent (e.g., to select between 18 or 19), eleven bits are used. This **wastes** about 16% of space (10 out of 64 bits).

In the eastern half of the state plane, there are 34 bits to the right of the ones' place, corresponding to a precision of 2^{-34} ft (about 5.8×10^{-11} ft $\approx 1.8 \times 10^{-11}$ m = 1.8×10^{-2} nm = 18 pm).



What's the Alternative? There are many. For vector data we suggest the following.

Store location data using 64-bit scaled integers. Divide the area of interest into a regular grid of arbitrary grid size $\Delta x = \Delta y$.



Figure 3. Space may be organized into a regular grid with grid size $\Delta x = \Delta y$.

Figure 4. The separation between two points can be quantified using component vectors or by quadrance. Quadrance can be thought of as the square of distance; it can be computed exactly for any two points.

Points are represented by coordinates each ranging from 1 - N to N - 1 (one of 2N - 1 distinct values). If $N = 2^{60} \approx 10^{18}$ and grid size is $1 \text{ pm} = 10^{-12}$ m, then N represents over one million meters. Such choices would be suitable for many regional areas of interest, including the Florida East State Plane.

There are at least two ways in which to represent the **separation between two points**. One is by a **vector**, composed of directed distances along gridlines (e.g., east and north components). Another is by **quadrance**, which can be thought of as the *square* of distance.

Precise, though inexact, locations are summarized using parallelograms whose vertices are points. Such objects are termed p-parallelograms ("p-" for "point").

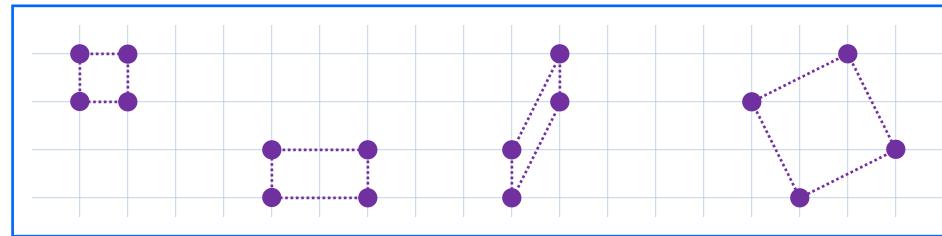


Figure 5. Certain collections of **points** form **p-parallelograms. P-parallelograms** need not be squares or rectangles (the skewed figure at center is a p-parallelogram). Neither do they need be aligned with the grid. The dotted "lines" are included for clarity; they are not part of any **p-parallelogram**.

Lines—not to be confused with line segments—are each represented by three integers. A point (x, y) is on the line (c, a, b) if and only if

$$c + a x + b y = 0$$

Furthermore—by design:

$$1 - 8N \le a \le 8N - 1, 1 - 8N \le b \le 8N - 1, \text{ and}$$

$$1 - 8N^2 \le c \le 8N^2 - 1$$

These constraints tolerate lines which pass through 1) any two points, 2) the centroids of any two p-parallelograms, or 3) any one point and the centroid of any one p-parallelogram.

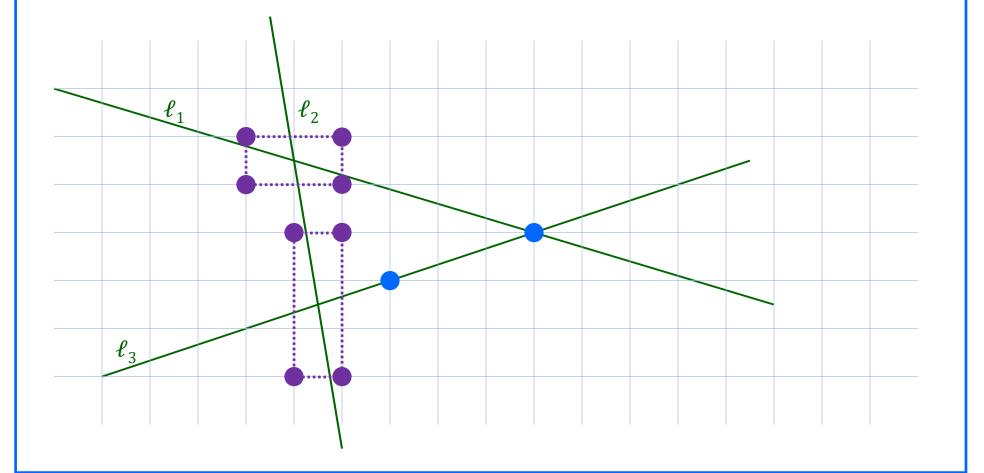


Figure 6. Lines extend indefinitely. **Line** ℓ_1 passes through a **point** and the centroid of a **p-parallelogram**. **Line** ℓ_2 passes through two **p-parallelograms**. **Line** ℓ_3 passes through two **points**.

Exclusive and **inclusive half-planes**, are similar to **lines** in their representation. The *corresponding* relations (inequalities) are

c + a x + b y < 0 and $c + a x + b y \le 0$ A point (x, y) is in a **half-plane** if and only if the corresponding relation is satisfied.

Precise, inexact boundaries are represented with pairs of parallel **half-planes** called **swaths**.

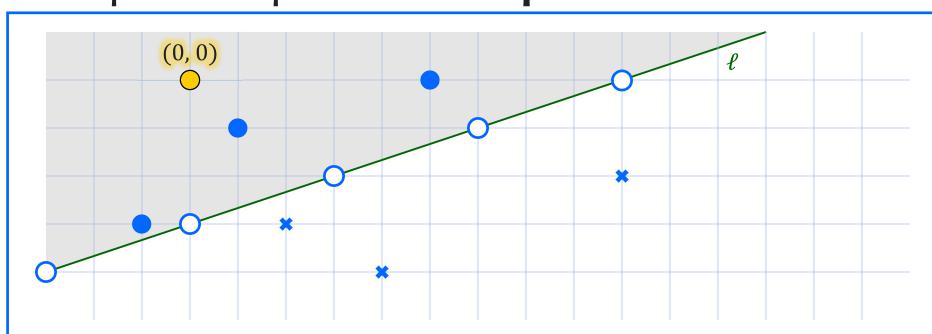
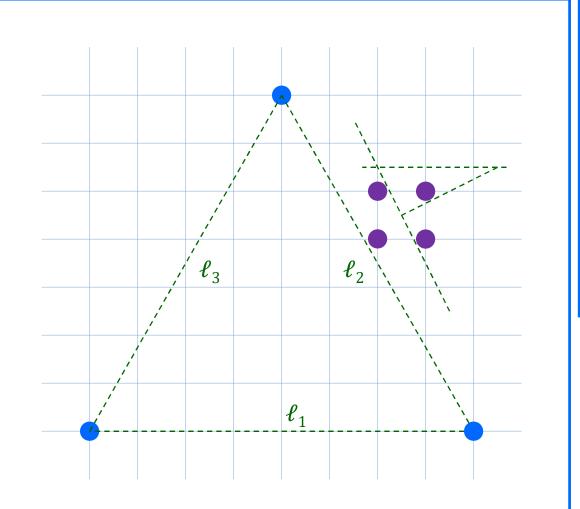


Figure 7. The **points** indicated by the solid dots (•) are among those in the exclusive half-plane with boundary **Line** ℓ . The corresponding inequality is $-9 + 1 \times + (-3) \times = 0$. The points indicated by the hollow dots (\odot) are not in the exclusive half-plane; neither are the points indicated by the exes (\times).

Triangles may be specified in at least two ways: as a triple of **points**—a **p-triangle**—or as a triple of **lines**—an *l*-triangle.



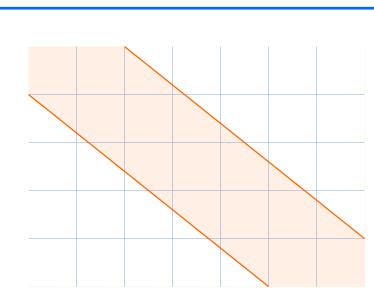


Figure 9 (above). A pair of parallel half-planes, forming a swath, represents a precise, though inexact linear feature.

Figure 8. A **triangle** can be represented by three **points** or by three **lines**. The vertices of an *ℓ*-**triangle** need not be (lattice) **points**.

The vertices of an *l*-triangle might not coincide with (lattice) points. Such vertices may still be located precisely, though not exactly. A square p-parallelogram spanning a single grid cell provides precision at the absolute limit.

A triangular region may be specified using three half-planes, where the interior of the triangular region is in all three half-planes.

DISCUSSION. By using—rather than wasting—memory, precision may be extended to the picometer scale. Normalizing for precision, integer arithmetic offers potential time and energy savings vs. floating-point arithmetic.

Feature	Requirement	Table 1. Storage requirements for select
Integer	1	sub-nanometer scale GIS objects. Units are 64-bit words, as in Figure 1. DISCLAIMER. The author / artist is solely responsible for the content of this draw ing. The views presented are not necessarily shared by the South Florida Water Management District or any other entity or person. SEE ALSO The accompany- ing white paper.
Point	2	
Vector	2	
Quadrance	2	
P-Paralleogra	am 8	
Line	4	
Half-Plane	4	
Swath	6	
P-Triangle	6	
L-Triangle	12	

ACKNOWLEDGEMENTS. Some material follows directly from Wildberger. His 2005 book Divine Proportions: Rational Trigonometry to Universal Geometry, Wild Egg Pty Ltd; Sydney, Australia; ISBN 097574920X; as well as his numerous recorded lectures on rational geometry (search: "wildtrig") are particularly relevant. Some inspiration and concepts come from a lecture delivered by John Gustafson entitled "Beyond Floating Point: Next Generation Computer Arithmetic" (2017-02-01; Stanford Center for Professional Development, Computer Systems Colloquium). This poster was developed using equipment at the South Florida Water Management District.