# FTC Control System & Programming

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#### What's New for 2017!

Rev Robotics Expansion Hub

OnBot Java Programming option



# FTC Hardware System Modern Robotics

- System provided by FIRST in the ResQ and Velocity Vortex Seasons
- No longer in FTC storefront
- Useable and supported by MR
- ► If purchased for ResQ (2015/16) and not sent in for Firmware update <u>Please see me</u>.



# FTC Hardware Systems Modern Robotics

- 5 Core Modules
- Core Power Distribution Module
  - Basically a 7-Port Powered USB Hub and Fused Power Distribution Block
- Core Motor Controller Module
  - Drives 2 DC Motors with or without encoders 5 Amps per motor Max
  - 3 operating modes
    - Run at Constant Power (no encoder required)
    - Run at Constant Speed (requires encoder)
      - Warning to Holonomic Drive users clocks are not consistent from module to module requiring compensation in software (it does work but "how to deal with it?" is left as an exercise for the student!)
    - Run to Position (requires encoder)

#### FTC Hardware Systems Modern Robotics

- Core Servo Controller Module
  - Runs six standard 6 Volt servos 5 Amps maximum total current
  - Runs 180 Degree or Continuous Rotation Servos
- Core Device Interface Module
  - ▶ PWM, Digital I/O, Analog I/O, I<sup>2</sup>C ports
- Core Device Legacy Module
  - Provides an Interface to allow use of older legacy FTC hardware
    - Lego NXT Sensors <u>But NOT Lego EV3 Sensors!</u>
    - ▶ Hi Technic Sensors
    - Matrix Controllers
    - ▶ Hi Technic Tetrix Motor & Servo Controllers

#### FTC Hardware Systems Rev Robotics

- NEW Provided in FTC storefront this season
  - Rookie teams will probably have these
- Much cheaper and more highly integrated
- Discount code in FIRST storefront to order an extra module
  - ▶ Buy the first one thru FIRST comes w/ more stuff!
- Requires 3.3V to 5V converters to use with 5V I<sup>2</sup>C sensors
  - MR, Lego, Hi-technic, AdaFruit, etc....
  - ▶ FIRST Storefront kit has 3 converters
- Includes powerful Bosch BNO055 9-axis IMU



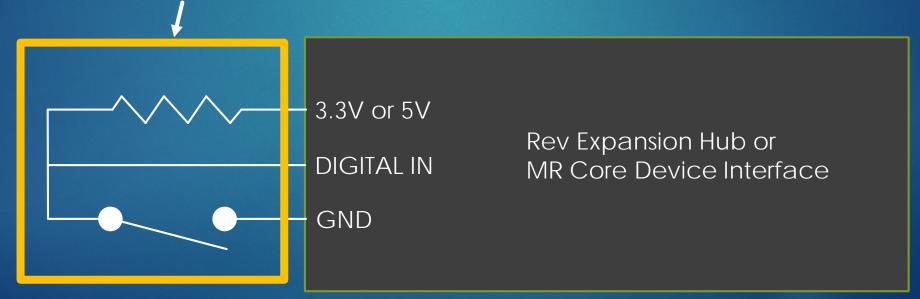


#### Sensors

- Wide variety available as allowed by <RE11>
- Be careful to use voltage converters where needed w/ Rev Exp. Hub
- 4 Common Interfaces Digital, Analog, I<sup>2</sup>C, Quadrature Encoder
- Legacy Sensors (NXT & HiTechnic) can be used w/ Core Legacy Module
  - ▶ Not clear if they can connect to I<sup>2</sup>C port of Rev Expansion Hub

### Sensor Interface - Digital

- Simple Digital Input
  - ▶ 0 Volts = Logic "0" = False
  - ▶ 5 Volts (MR) or 3.3V (REV) = Logic 1 = TRUE
- Used for Touch Sensor, Limit Switch, etc....



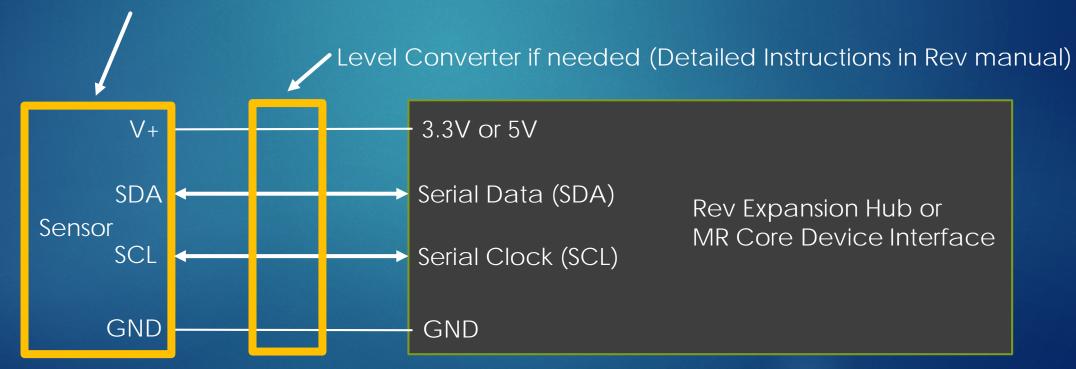
### Sensor Interface - Analog

- Simple Analog Input
  - ▶ 0 Volts to 3.3 or 5 Volts, 12 Bits of resolution (0 to 4095)
- Used for Potentiometer Position Sensor, Voltage Sensor....



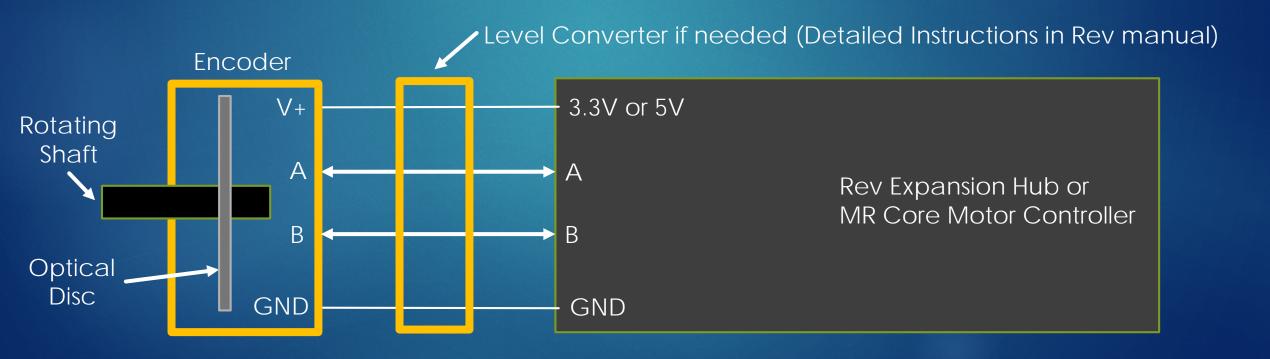
#### Sensor Interface – I<sup>2</sup>C

- ▶ Inter-Integrated Circuit (I²C) Serial Interface
  - ▶ Industry standard 2-wire serial interface developed in the 1970's
  - Used by many advanced sensors & IC's
- Used for Advanced Sensors w/ I2C Communication



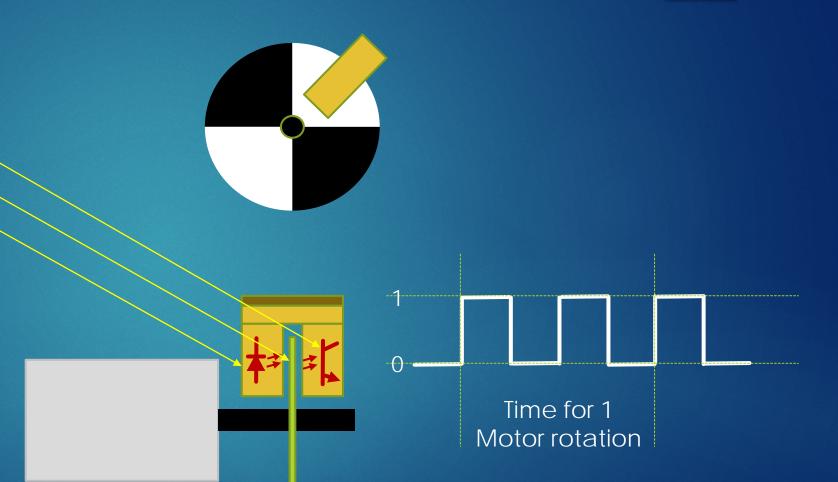
#### Sensor Interface – Encoders

- Specifically for Quadrature Encoders
  - Used on Motors for "Constant Speed" and "Run to Position"
  - Used on Moving Assemblies for precise measurement of motion
- 4 wire interface



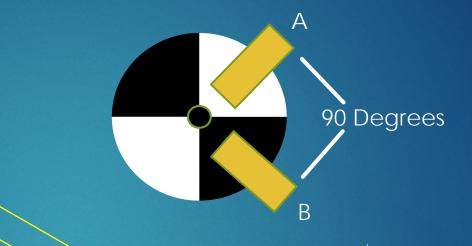
#### How Encoders Work

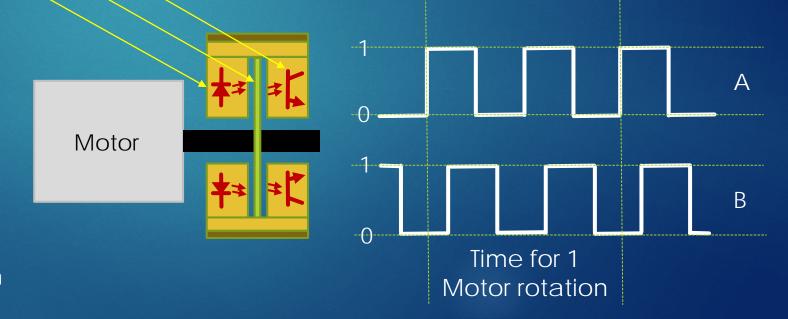
- Layered Optical Sensor
  - ► Photo-Transistor
  - ▶ Glass Disk
  - ▶ LED Light Source
- 2 pulses per rotation of the motor
- 4 edges per rotation of the motor



#### How Encoders Work

- Quadrature Encoders
- 2x Layered Optical Sensors
  - Spaced to create 2 waveforms 90° apart
  - Photo-Transistor
  - Glass Disk
  - ▶ LED Light Source
- 2 pulses per rotation of the motor per sensor
- 4 edges per rotation of the motor per sensor (8 total)
- Can now sense direction
  - CW A leads B
  - CCW B leads A
- Can be 1 to 10000's lines around the glass disc
  - more lines = more resolution



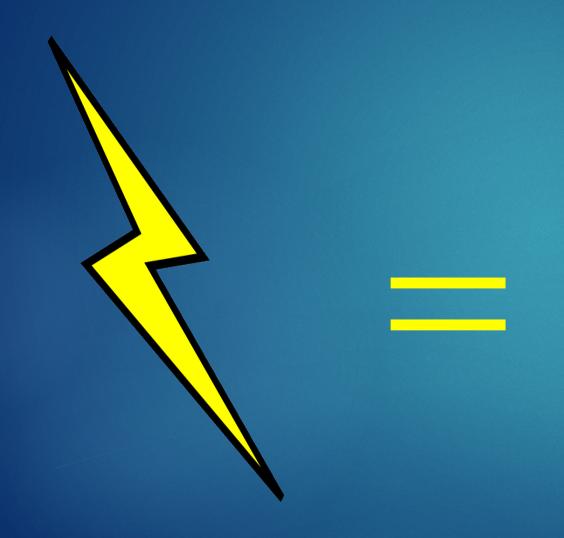


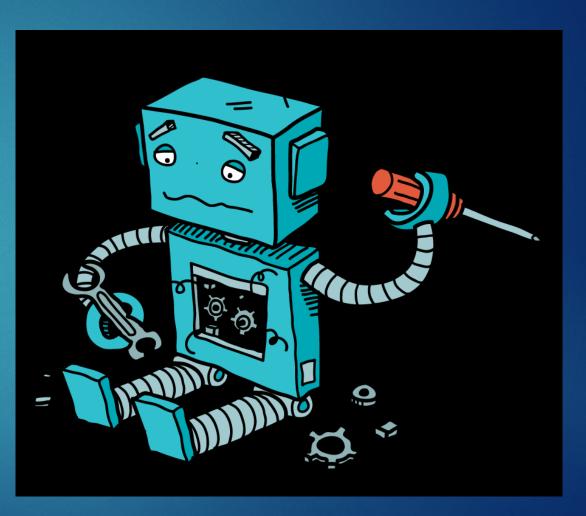
#### Vuforia Augmented Reality

- Uses Phone Camera
- Image recognition and alignment
- Software built into FTC SDK
- 4 Images on field randomly selected
- Tutorials & discussions on line google FTC Vuforia









- Recipe for static electricity build-up:
  - Drive robots with plastic & rubber wheels on foam mats, surrounded by acrylic walls in a low humidity, southwest climate
- Discharge occurs when robots contact walls, field elements, or each other
  - When it gets into the electronics BAD THINGS HAPPEN!
- Keep wiring neat & organized!
- Use ESD plastics to protect parts (particularly sensors)
- Use insulated connectors, splice blocks or electrical tape
- During practice, occasionally spray <u>light</u> mist of water on field tiles

- Keep Wiring Neat & organized!
  - More Reliable!
  - Won't get tangled in other robots or field elements
  - Messy wiring is common cause of Robot Inspection Failure!
  - Use Anderson Powerpole connectors
  - Make sure to use some kind of retention on motor cables
    - ► Tape, Ty-wraps, 3D printed retainer
    - Or solder the wires on but be careful and quick, you can damage the motor!
- 3D Printable Components on <a href="https://www.thingiverse.com/">https://www.thingiverse.com/</a>
  - Cable Strain reliefs
  - Phone / Electronics/ Sensor Mounts
  - Many Mechanical Components
  - If you don't find it design & build it yourself then share on Thingiverse!
    - Good Core Values!

- Pay attention to the specs of your components!
  - Exceeding rated power supply & input voltages:
    - Causes unpredictable behavior
    - Damages modules
  - Exceeding maximum currents on modules, wiring, motors & servos:
    - Causes unpredictable behavior
    - ▶ Let's out the "Magic Smoke" that makes it work!
    - Damages modules, Weakens or burns out motors & servos.
    - ▶ Can cause fires! (NO FLAMING ROBOTS PLEASE!)
  - Exceeding specs of mechanical parts:
    - Causes unpredictable behavior
    - Breaks stuff!
    - CREATES SAFETY HAZARDS!
- If you have unexplainable behavior occurring THINK ABOUT THIS SLIDE!

#### Allowed Android Phones < RS03>

- Very specific (and somewhat outdated!) models
  - ZTE Speed
  - Motorola Moto G 2<sup>nd</sup> Generation
  - Motorola Moto G 3<sup>rd</sup> Generation
    - ▶ If you have these <a href="Please See Me!">Please See Me!</a>
  - Motorola Moto G4 Play
  - Google Nexus 5
  - Samsung Galaxy \$5
- Keep an eye on revisions to Game Manual 1 for possible additions
- Android OS as specified in <RS03>
- Other phones / tablets may work but are not legal for competition

# Driver Station Setup





Mount Phones to something Non-metallic for best WiFi



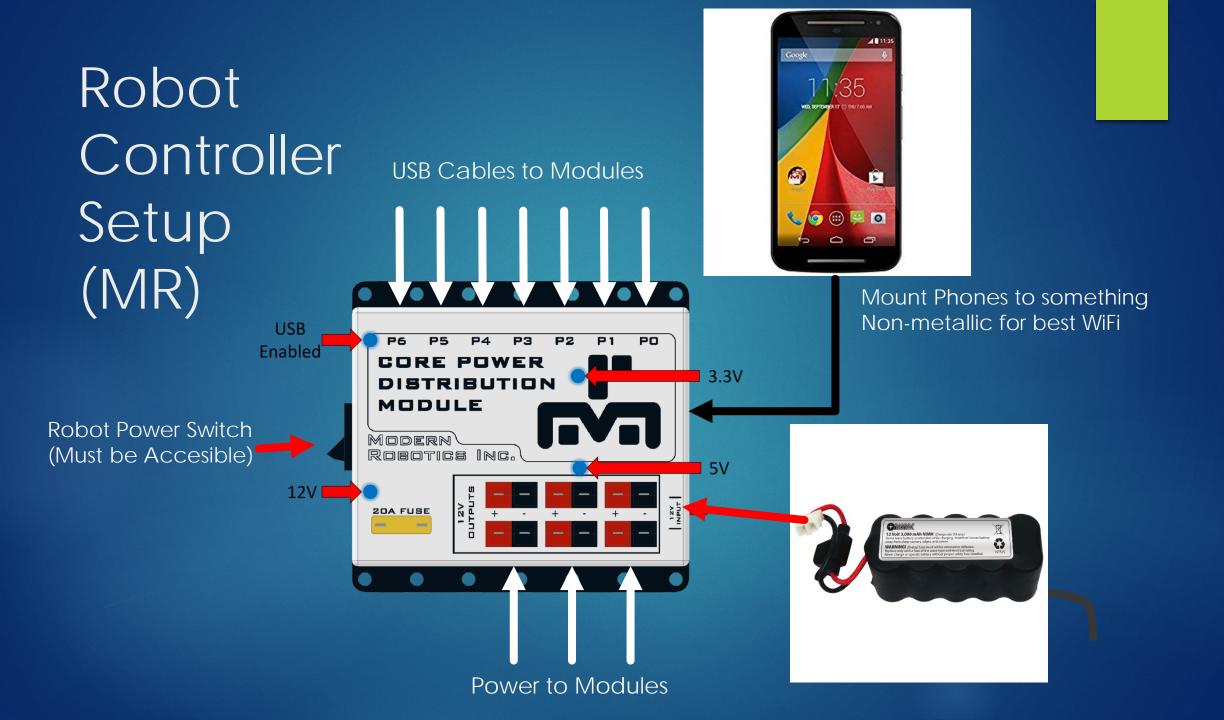
Optional USB Battery (required for Moto G 3<sup>rd</sup> gen phones)





#### Driver Station App

- Two Install Options:
  - Free download from Google Play Store
    - will be latest official release version
  - Install APK included with FTC SDK
    - Will be the version that goes with that SDK (including beta releases)
- Be certain Installed version is same as the Robot Controller Version
- Make sure no stray Robot Controller App on Driver Station Phone
  - Causes unpredictable results & phone crashes
- Phone WiFi Name should be #####-DS (##### = team number)



# Robot Controller Setup (Rev)

Robot Power Switch (Must be Accessible)



be Accessible)
USB Cable



FTC Legal

Mount Phones to something Non-metallic for best WiFi

Second Hub (if used)



Sensors (w/ Level Shifters as needed)



#### Robot ControllerApp

- This is the app you are putting your team's Robot Code in!
- Two initial install options:
  - ► Free download from Google Play Store
    - ▶ Will be latest official release version
  - Build and Install using Android Studio from FTC SDK
    - Will be whatever version you choose (including beta releases)
- Be certain installed version is same as the Driver Station app version
- Make sure no stray Driver Station app is on Robot Controller phone
  - Causes unpredictable results & phone crashes
- Must be only one Robot Controller app on the phone
  - Causes unpredictable results (even if they have different names!)
- Phone WiFi name should be #####-RC (##### = team number)

#### Programming Environments < RS02>

- Google Android Studio, Oracle Java Development Kit, FTC SDK
  - Text based Java programming environment
  - Most powerful but also the most complicated
- Brand new "OnBot" Java Programming development tool
  - Text based Java Programming built into the Robot Controller app
  - Only exists in FTC SDK 3.4 release
  - Doesn't currently show in <RS02> but presumably being added
- FTC Blocks Programming development tool
  - Visual Blocks Based Programming built into the Robot Controller app
  - Based on Google's Blockly language but similar to FTC/MIT App Inventor
- FTC/MIT App Inventor
  - Visual Blocks based Programming Tool using a Virtual Box based server
  - According to Tom Eng at FIRST going away after this season
  - ▶ 2017 legal minimum 3.1 version not released yet not a good sign for support

# Programming Key Web Links

- FTC Control System Wiki
  - https://github.com/ftctechnh/ftc\_app/wiki
- FTC Software Development Kit Current Release (now v3.4)
  - Just released Wed, Sept 6
  - https://github.com/ftctechnh/ftc\_app
- ▶ FTC Software Development Kit Beta Release
  - https://github.com/ftctechnh/ftc\_app/tree/beta/doc/apk
  - Not currently a beta version available (3.4 just released Wednesday)
  - Experimental beta versions allowed for use, but AT YOUR OWN RISK!
- FTC App Inventor Current Release (now v2.4 not legal for use)
  - https://frc-events.firstinspires.org/ftcimages/2017

#### Blocks and OnBot Quick Demo

- Can be used on the Robot Controller phone screen
  - Small but useable in a pinch
- Typically used in a Java enabled browser on a PC
  - Chrome seems to be the recommended browser
- Steps:
  - Ensure WiFi direct is configured on the phone (named #####-RC)
  - Start Robot Controller App on phone, select "Program & Manage"
  - ▶ The phone will display a screen with the WiFi name, password & http address
  - Connect your PC to the phone using the WiFi name & Password
  - Start Chrome and open the displayed http address
  - You will be in the environment for Blocks and OnBot

