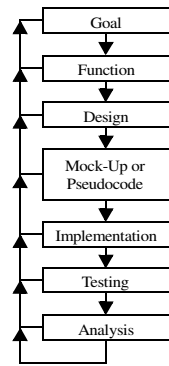


Griffin Robotics Engineering Worksheet



Subsystem Name

My name for this subsystem is _____ .

Goal

My goal(s) for this subsystem is (are):

1. _____

2. _____

3. _____

4. _____

Function

The function(s) and constant(s) (external interface) that will be in my abstract superclass are:

1. _____

2. _____

3. _____

4. _____

5. _____

6. _____

7. _____

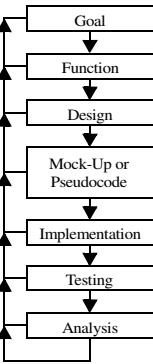
8. _____

Design

The motors, servos and sensors am I using are:

Hub	Device Type	Port	Name

My notes and sketches that describe how it works:



Pseudocode And Implementation

My pseudocode and implementation is in Android Studio; the name of the class is:

_____.

Testing

My plan for testing my subsystem is:

1. _____

2. _____

3. _____

4. _____

5. _____

6. _____

Analysis

The results from my tests and whether my tests worked:

1. _____

2. _____

3. _____

4. _____

5. _____

6. _____
