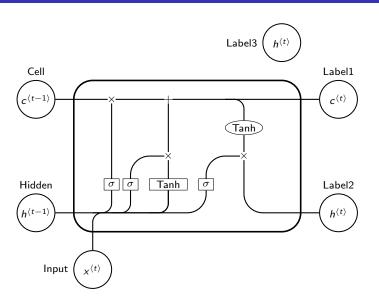
## LSTM-RNN Results for GPP

January 28, 2019

#### Overview

- Use Recurrent Neural Network
- Need a Gated Type Method
  - LSTM (long short term memory)
  - GRU (gated reccurent unit)
- No longer need to deal with vanishing/exploding gradients
- Can handle history of time sequences

#### **Bullet Points**



# LSTM Cell summary

$$f_{t} = \sigma(W_{f}x + U_{f}h_{t-1} + b_{f})$$

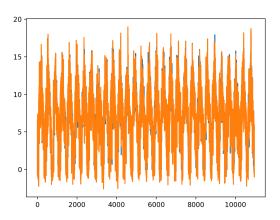
$$i_{t} = \sigma(W_{i}x + U_{i}h_{t-1} + b_{i})$$

$$o_{t} = \sigma(W_{o}x + U_{o}h_{t-1} + b_{o})$$

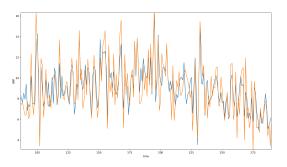
$$c_{t} = f_{t} \odot c_{t-1} + i_{t} \odot \sigma_{c}(W_{c}x_{t} + U_{c}c_{t-1} + b_{c})$$

$$h_{t} = o_{t} \odot \sigma_{b}(c_{t})$$
(1)

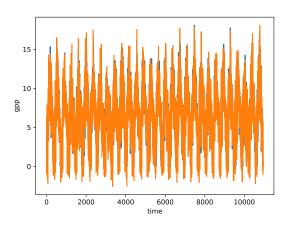
## Model 1



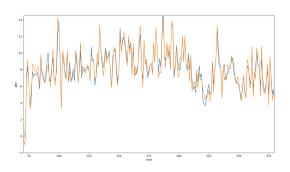
## Model 1 zoom



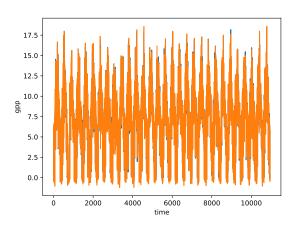
## Model 2



## Model 2 zoom



## Model 3



## Model 3 zoom

