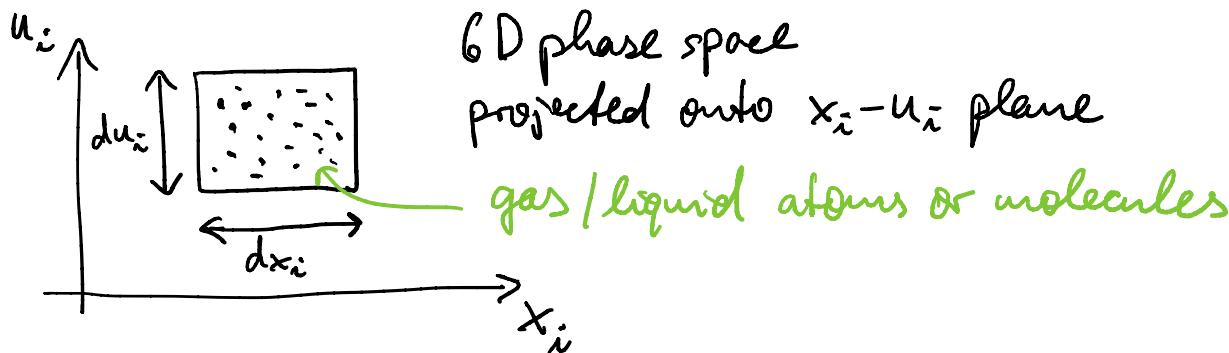


Chapter 2: Basic Equations

2.1 Continuous media: Boltzmann Eq



In principle evolution of system fully determined by Newtonian mechanics (N-body equations):

$$\frac{d\vec{x}_i}{dt} = \vec{u}_i \quad , \quad \frac{d\vec{u}_i}{dt} = \vec{F}_i(x_j, u_j, t) \quad \forall \text{ particles } i, j$$

\uparrow force on i

But: 1 mole $\hat{=} N = 6 \times 10^{23}$ particles \rightarrow computationally prohibitive

\rightarrow statistical approach (continuous media)
 \rightarrow hydrodynamics

$$dN = f(\vec{x}, \vec{u}, t) d\vec{x} d\vec{u}$$

\uparrow number of particles in phase-space control volume
 \nwarrow distribution function

- ignore internal degrees of freedom \rightarrow vibration, rotation
- identical particles of mass m
- ignore QM effects

Assume particles subject to external force per unit mass \vec{F} (\approx constant over typical inter-particle separation)

\Rightarrow particle number $f(\vec{x}, \vec{u}, t) d\vec{x} d\vec{u}$ conserved along their trajectories in phase space (Liouville's theorem) in absence of interactions:

(*)

$$\Delta f = f(\vec{x} + \underbrace{\vec{u} dt}_{\text{change in position}}, \vec{u} + \underbrace{\vec{F} dt}_{\text{change in velocity due to } \vec{F}}, t + dt) - f(\vec{x}, \vec{u}, t) = [\Delta f]_{\text{coll}}$$

change in position

change in velocity
due to \vec{F}

$$\begin{aligned} dt &\rightarrow 0 \\ \Delta f &\rightarrow \frac{df}{dt} \end{aligned}$$

↑ change in f in dt due to collisions

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + u_i \frac{\partial f}{\partial x_i} + F_i \frac{\partial f}{\partial u_i} = \left[\frac{\partial f}{\partial t} \right]_{\text{coll}}$$

Boltzmann's transport equation

→ evolution of distribution function in 6-D phase space (\vec{x}, \vec{u})

→ change dN in number of particles within a fixed volume $d\vec{x} d\vec{u}$ equals net number of particles entering or leaving this volume

(→ Liouville's theorem)

Some definitions:

$$n(\vec{x}, t) \equiv \int f(\vec{x}, \vec{u}, t) d\vec{u}$$

particles per unit volume in $\vec{u}, \vec{u} + d\vec{u}$

total number of particles per unit volume

- $\ell \equiv n^{1/3}$ mean particle separation

Note: any physical length scale $d\vec{x}$ we are interested in must be $\gg \ell$ for statistical approach to be valid

- $\rho(\vec{x}, t) = \int m f(\vec{x}, \vec{u}, t) d\vec{u}$ mass density
- $\vec{v}(\vec{x}, t) = \frac{1}{S} \int \vec{u} m f(\vec{x}, \vec{u}, t) d\vec{u}$ bulk velocity
- $\rho E(\vec{x}, t) = \frac{1}{2} \int m \vec{u}^2 f(\vec{x}, \vec{u}, t) d\vec{u}$ specific internal energy E
 $\uparrow \vec{u} = \vec{v} - \vec{v}$ peculiar velocity

Special case:

- elastic collisions (energy & momentum conserved)
- low density (collisions of 3 & more particles)
 (can be neglected)
- absence of external forces $\vec{F} \equiv 0$

unique solution \downarrow statistical mechanics

$$f(\vec{x}, \vec{u}, t) d\vec{u} = n(\vec{x}, t) \left[\frac{m}{2\pi k_B T(\vec{x}, t)} \right]^{3/2} \exp \left[-\frac{m(\vec{u} - \vec{v})^2}{2k_B T(\vec{x}, t)} \right] d\vec{u}$$

Maxwellian velocity

distribution
 (equilibrium state $t \rightarrow \infty$,
 $\frac{\partial f}{\partial t} = 0$)

2.2 From Boltzmann to Euler

Def: k-th moment of the Boltzmann equation

$$\int u_k \left[\frac{\partial f}{\partial t} + u_i \frac{\partial f}{\partial x_i} + f_i \frac{\partial f}{\partial u_i} \right] du = \int u_k \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} du,$$

where $u_k = \vec{u}^k$, i.e. $u_0 = 1$, $u_1 = \vec{u}$, $u_2 = u^2$ etc.

General properties of collision term:

If collisions are elastic and neither create nor destroy particles, then

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0 \quad \begin{matrix} \text{number of particles} \\ \text{conserved} \end{matrix}$$

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} u_i d\vec{u} = 0 \quad \begin{matrix} \text{total momentum} \\ \text{conserved} \end{matrix}$$

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} u^2 d\vec{u} = 0 \quad \begin{matrix} \text{total energy} \\ \text{conserved} \end{matrix}$$

$$\lim_{u \rightarrow \infty} u^k f = 0 \quad \begin{matrix} \text{total number, momentum} \\ \text{energy must be finite} \end{matrix}$$

$$\text{Also: } \left(\int_{\Omega} v \frac{\partial u}{\partial x_i} = \int_{\Omega} uv n_i d\Gamma - \int_{\Omega} u \frac{\partial v}{\partial x_i} \right)$$

$$\int \frac{\partial f}{\partial u_i} d\vec{u} \stackrel{P.i.}{=} \int f n_i d\Gamma - \int \underbrace{\frac{\partial(1)}{\partial u_i} f}_{=0} d\vec{u} = 0$$

$$\int u_j \frac{\partial f}{\partial u_i} d\vec{u} \stackrel{P.i.}{=} \underbrace{\int u_j f n_i d\Gamma}_{|u|= \pm \infty} - \int \underbrace{\frac{\partial u_j}{\partial u_i} f}_{=\delta_{ij}} d\vec{u}$$

$$= -\delta_{ij} \frac{g}{m}$$

$$\frac{1}{2} \int u^2 \frac{\partial f}{\partial u_i} d\vec{u} = \frac{1}{2} \int u^2 f n_i d\Gamma - \frac{1}{2} \int \underbrace{\frac{\partial u^2}{\partial u_i} f}_{|u|= \pm \infty} d\vec{u} \stackrel{\frac{\partial(\sum_j u_j^2)}{\partial u_i} = 2u_i}{=} 2u_i$$

$$= - \int u_i f d\vec{u} = - \frac{g}{m} v_i$$

① From θ -moment of Boltzmann eqn:

$$m \int \frac{\partial f}{\partial t} d\vec{u} + m \int u_i \frac{\partial f}{\partial x_i} d\vec{u} + m \overline{v}_i \underbrace{\int \frac{\partial f}{\partial u_i} d\vec{u}}_{=0} = \int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0$$

u_i, x_i independent

$$\Downarrow \Leftrightarrow \frac{\partial}{\partial t} \int m f d\vec{u} + \frac{\partial}{\partial x_i} \int u_i m f d\vec{u} = 0$$

\Leftrightarrow

$$\frac{\partial \mathbf{S}}{\partial t} + \nabla \cdot (\mathbf{S} \vec{v}) = 0$$

continuity
equation

Note: V large enough

$$\Rightarrow \int \frac{\partial \mathbf{S}}{\partial t} dV + \underbrace{\int \nabla \cdot (\mathbf{S} \vec{v}) dV}_{\text{Gauss}}$$

$$= \int_V \mathbf{S} v_i n_i d\Omega = 0 \quad \vec{v} = 0 \text{ on } \partial V$$

↑
unit normal

$$= \frac{\partial}{\partial t} \int_V \mathbf{S} dV = \frac{\partial M_V}{\partial t} = 0 \quad \text{mass conservation}$$

② From 1st-moment of Boltzmann eqn:

$$m \int u_i \frac{\partial f}{\partial t} d\vec{u} + m \int u_i u_j \frac{\partial f}{\partial x_i} d\vec{u} + m F_j \underbrace{\int u_i \frac{\partial f}{\partial u_j} d\vec{u}}_{= -\delta_{ij} \frac{f}{m}} = 0$$

$$= \int u_i \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0$$

$$\Leftrightarrow \frac{\partial}{\partial t} (S v_i) + \frac{\partial}{\partial x_i} \int m u_i u_j f d\vec{u} - S F_i = 0$$

$$\int m \tilde{u}_i \tilde{u}_j f d\vec{u} = \int m (\tilde{u}_i + v_i)(\tilde{u}_j + v_j) f d\vec{u}$$

$\xrightarrow{\text{cross terms vanish}}$

$$\int \tilde{u}_i f d\vec{u} = 0 \quad \xrightarrow{\text{peculiar velocities}} \quad \equiv s v_i v_j + P_{ij}$$

$$P_{ij} = \int m \tilde{u}_i \tilde{u}_j f d\vec{u} \quad \begin{matrix} \text{pressure} \\ \text{tensor} \end{matrix}$$

Most astrophysical cases:

$$\text{isotropic pressure} \Rightarrow P_{ij} = P \delta_{ij}$$

$$P = \frac{1}{3} \int m \tilde{u}^2 f d\vec{u}$$

$$(P = \frac{2}{3} s \epsilon)$$

$$\Leftrightarrow \frac{\partial}{\partial t} (s v_i) + \frac{\partial}{\partial x_j} (s v_i v_j) = - \frac{\partial P}{\partial x_i} + s \vec{F}_i$$

$$\Leftrightarrow \boxed{\frac{\partial}{\partial t} (s \vec{v}) + \nabla \cdot \Pi = s \vec{F}}$$

momentum
equation

$$\Pi = s v_i v_j + P \delta_{ij} \quad \begin{matrix} \text{momentum} \\ \text{flux tensor} \end{matrix}$$

Note: • pressure gradient and external forces act as source (or sink) terms

- force due to pressure gradient results from exchange of energy between bulk flow and peculiar motions

③ From 2nd-moment of Boltzmann eqn:
 (Exercise):

$$\frac{\partial}{\partial t} \left[S \left(\frac{v^2}{2} + \epsilon \right) \right] + \frac{\partial}{\partial x_i} \left[S v_i \left(\frac{v^2}{2} + \epsilon \right) \right] = - \frac{\partial h_i}{\partial x_i} - \frac{\partial}{\partial x_i} (P v_i) \\ + S v_i F_i$$

where $h_i = \int \frac{m}{2} \tilde{u}_i \tilde{u}^2 f d\tilde{u}$ conduction heat flux

If \vec{h} can be neglected (typical for astrophys. systems):

$$\rightsquigarrow \boxed{\frac{\partial E}{\partial t} + \frac{\partial}{\partial x_i} [(E+P)v_i] = S v_i F_i}$$

total
energy
equation

$$E \equiv \frac{1}{2} S v^2 + S \epsilon$$

total
energy
density

Remarks: 1) ①, ②, ③ are known as the Euler equations. They can be rewritten as a system of conservation laws:

$$\boxed{\begin{aligned} u_t + f^i(u)_{x_i} &= S \\ \partial_t u + \frac{\partial}{\partial x_i} f^i(u) &= S \end{aligned}}$$

where

$$u = \begin{pmatrix} s \\ s \vec{v} \\ E \end{pmatrix} \quad \text{"conserved variables"}$$

$$f^i = \begin{pmatrix} s v^i \\ s v^i v^j + \delta_{ij} p \\ v^i (E + p) \end{pmatrix} \quad \begin{array}{l} j = 1, 2, 3 \\ (\text{momentum components}) \end{array} \quad \text{"fluxes"}$$

$$S = \begin{pmatrix} 0 \\ s \vec{F} \\ s \vec{J} \cdot \vec{F} \end{pmatrix} \quad \begin{array}{l} i = 1, 2, 3 \\ (\text{flux directions}) \end{array} \quad \text{"sources"}$$

2) Equation of state: The Euler eqns. are five equations for six unknowns $s, \{v^i\}, P, e = sE$

and require relation $P = P(s, e)$ to close the system \rightarrow "equation of state"

Ideal gas: $p = (\gamma - 1)e = (\gamma - 1) \beta E$
 with $\gamma = \frac{c_p}{c_v}$ the ratio of specific heats
 (adiabatic constant)

In general: $p = p(S, e, X_i, \dots)$ can be very
 complicated (\rightarrow different chemical
 elements, ionization states, compl.
 reactions etc.)

Exercise: Show strict hyperbolicity of the Euler equations.

3) Validity of continuous medium approximation

require (see above):

$$(i) \quad \lambda \ll dx \ll l_{sys} \quad \begin{matrix} \text{mean free path of particle} \\ \uparrow \end{matrix} \quad \begin{matrix} \text{finite size element of medium} \\ \uparrow \end{matrix} \quad \begin{matrix} \text{characteristic size} \\ \text{of physical system} \end{matrix}$$

f should not vary over dx & dN
 should be large enough for averaging
 to be meaningful

(ii) interparticle forces must be short-range
 i.e. on distances $l_{force} \ll dx$, otherwise

energy & momentum exchanged with
fluid elements far away

example for long-range: external grav.
field
→ external force

Note: self-gravity cannot be obtained
from Boltzmann eqn due to
long-range nature
→ require additional Poisson eqn.

- (iii) peculiar motion close to boundary of
element $d\mathbf{x}$ carries particles into
adjacent elements with different $\mathbf{s}(\mathbf{z})$, $\mathbf{v}(\mathbf{z})$,
 $T(\mathbf{z})$ and "diffusion"
and friction forces appear \Rightarrow
microscopic exchange of
momentum & energy
neglected in Euler equation
→ need to take conduction heat flux
 \vec{h} and other terms into account
(see below)

2.3 Viscosity: Navier - Stokes equations

When interchange ("diffusion") of particles between adjacent fluid elements cannot be neglected
 → internal friction or viscosity

no Modify momentum flux density:

$$(\star) \quad \pi \rightarrow \bar{\pi} = \pi - \sigma, \quad \bar{\pi}_{ij} = \delta v_i v_j + \underbrace{p \delta_{ij}}_{\text{stress tensor}} - \underline{\sigma_{ij}}$$

viscous stress tensor

- friction requires differences in velocity between particles → σ should depend on $\frac{\partial v_i}{\partial x_j}$
 If velocity gradients small, 1st order derivatives OK, and σ is linear in $\frac{\partial v_i}{\partial x_j}$
- $\sigma = 0$ when fluid rotates rigidly or $v \equiv \text{const.}$

↓ Landau & Lifshitz Fluid Mechanics §15

$$\sigma_{ij} = \eta \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \frac{\partial v_k}{\partial x_k} \delta_{ij} \right) + \eta \frac{\partial v_k}{\partial x_k} \delta_{ij}$$

↑ shear viscosity coefficient η , η independent of velocity, ≥ 0

↑ bulk viscosity coefficient

- bulk: energy transfer b/w translational and internal motions of fluid particles
- not possible for ideal mono-atomic gases for example → no internal DOF
 - not for incompressible fluids $\frac{\partial \rho}{\partial t} = 0$
 $(\nabla \cdot \mathbf{v} = 0 \Rightarrow \nabla \cdot \vec{v} = 0)$
 - if present frictional force opposing changes of the volume of fluid elements generated
 - usually not relevant in astrophysics

- shear: "dynamic viscosity coefficient"
- momentum diffusion through shear motion: faster fluid elements decelerate, slower elements accelerate

With the replacement (\star) we obtain the

Navier - Stokes equations:

Navier (1827)
Stokes (1845)

$$\frac{\partial \mathbf{s}}{\partial t} + \frac{\partial}{\partial x_i} (\mathbf{s} v_i) = 0$$

$$\frac{\partial}{\partial t} (\mathbf{s} v_i) + \frac{\partial}{\partial x_j} (\mathbf{s} v_i v_j - \sigma_{ij}) = - \frac{\partial P}{\partial x_i} + \mathbf{s} \vec{f}_i \quad (i=1,2,3)$$

$$\frac{\partial E}{\partial t} + \frac{\partial}{\partial x_j} [(E+P) v_j - \sigma_{jk} v_k] = \mathbf{s} v_j \vec{f}_j$$

Properties of viscous effects:

- Viscous timescale:

Assume that viscous effects dominate & consider incompressible fluid for simplicity ($\Rightarrow \sigma_{ij} = \eta \left(\frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right)$)

momentum eq.

$$\text{no } \frac{\partial}{\partial t} v_i \approx \frac{1}{\rho} \frac{\partial \sigma_{ij}}{\partial x_j} \Rightarrow \frac{|\vec{v}|}{t_v} \sim \sqrt{\frac{1}{l_{sys}} \frac{|\vec{\nabla}|}{l_{sys}}}$$

characteristic time & length scales

$$v = \frac{\eta}{\rho} \quad \text{kinematic viscosity coefficient}$$

$$t_v = \frac{l_{sys}^2}{v} \quad \text{viscous timescale}$$

- Magnitude of effects:

\rightarrow molecular viscosity (peculiar motions of particles) wrt to bulk motion

$$v_{mol} = \lambda \tilde{u}_{sys}$$

mean
free path

characteristic
velocity of peculiar motions

$$t_v = \frac{l_{sys}^2}{\lambda \tilde{u}_{sys}}$$

HII cloud
(interstellar)
 $\sim 3 \times 10^{12} \text{ yr}$

$$\begin{cases} l_{sys} \sim 10^{13} \text{ cm} \\ \lambda \sim 10^{14} \text{ cm} \\ \tilde{u}_{sys} \sim 10^4 \frac{\text{cm}}{\text{s}} \end{cases}$$

protostellar
disk (star formation)
 $\sim 3 \times 10^{14} \text{ yr}$

$$\begin{cases} l_{sys} \sim 10^{14} \text{ cm} \\ \lambda \sim 10^{10} \text{ cm} \\ \tilde{u}_{sys} \sim 10^5 \frac{\text{cm}}{\text{s}} \end{cases}$$

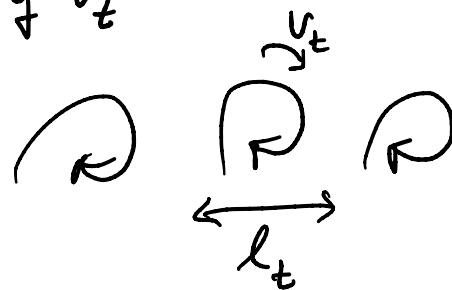
$> \sim 10^2 - 10^4 \times \text{age of universe!}$

\Rightarrow negligible for all practical purposes

\rightarrow turbulent viscosity (turbulent flows within)
a bulk flow

\rightsquigarrow random motions of eddies with characteristic size l_t and velocity v_t

$$v_t = l_t v_t$$



Consider accretion disk:



$$l_t \sim h$$

$$v_t \sim \propto c_s$$

$\in (0,1)$ \uparrow sound speed

(if $v_t > c_s \Rightarrow$ shock \Rightarrow dissipation
of turbulent motions until
 $v_t < c_s$)

$$\rightsquigarrow v_t = \propto c_s h$$

α : " α -viscosity" (Shakura & Sunyaev 1973)

\rightarrow source for such disk turbulence

is the magneto-rotational instability (MRI)

(Balbus & Hawley 1991)

2.4 Magneto hydrodynamics

Ionized medium (plasma) can conduct electric currents \Rightarrow interacts with EM fields
 \rightarrow complex interplay b/w plasma motions & fields

Simplest possible approximation of magnetized plasmas:
magnetohydrodynamics (MHD):

- (i) plasma treated as continuous medium, described by Navier-Stokes Eqns in absence of EM fields
- (ii) Positive & negative charges are locally and globally balanced at all times
(\rightarrow fluid elements are neutral)
- (iii) electrons are in statistical equilibrium with ions
(same temperature)
- (iv) interparticle collisions frequent enough for all effects of magnetic forces to be instantaneously transferred from e^- to ions and neutral particles (if present)

Note: for currents to flow, e^- & ions cannot move at the same velocity. However, the relative drift

velocity is so small that it can be neglected
(see below)

Vacuum Maxwell eqns:

$$\text{I} \quad \nabla \cdot \vec{E} = 4\pi q$$

$$\text{II} \quad \nabla \cdot \vec{B} = 0$$

$$\text{III} \quad \nabla \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}$$

$$\text{IV} \quad \nabla \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \simeq \frac{4\pi}{c} \vec{j}$$

Gauss (cgs)
units!

Plasma motion approximations:

$$1) \text{ III} \Rightarrow \frac{E_{\text{sys}}}{l_{\text{sys}}} \sim \frac{B_{\text{sys}}}{c t_{\text{sys}}}$$

$E_{\text{sys}}, B_{\text{sys}}$: characteristic field strengths

$l_{\text{sys}}, t_{\text{sys}}$: characteristic length & time scales

$v_{\text{sys}} = \frac{l_{\text{sys}}}{t_{\text{sys}}}$ characteristic plasma velocity

$$\text{IV} \quad \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \sim \frac{E_{\text{sys}}}{c t_{\text{sys}}} \sim \frac{B_{\text{sys}} l_{\text{sys}}}{c^2 t_{\text{sys}}} \sim \frac{v_{\text{sys}}^2}{c^2} |\nabla \times \vec{B}| \ll |\nabla \times \vec{B}|$$

assuming non-relativistic plasma

Drift velocity: consider e^- -p plasma (H-plasma)

different velocities of e^- , p cause current

$$\vec{j} = q_e (n_e \vec{v}_e - n_p \vec{v}_p) = q_e n_e (\vec{v}_e - \vec{v}_p) = q_e n_e \vec{v}_{\text{drift}}$$

number densities

$$|\nabla \times \vec{B}| \approx \frac{B_{\text{sys}}}{l_{\text{sys}}} \stackrel{\text{IV}}{\approx} \frac{4\pi}{c} q n_e |v_{\text{drift}}|$$

$$B_{\text{sys}} \sim 10^3 \text{ G}$$

$$n_e \sim 10^{23.1} \frac{1}{\text{cm}^3}$$

$$\Rightarrow v_{\text{drift}} \sim \begin{cases} 10^{-12} \frac{\text{cm}}{\text{s}} & \text{solar plasma} \\ & (\text{convection zone}) \quad l_{\text{sys}} \sim 10^{10} \text{ cm} \\ 10^{-2} \frac{\text{cm}}{\text{s}} & \text{interstellar medium} \\ (\text{compare turbulent}) \\ (\text{velocities} \sim 1 \frac{\text{km}}{\text{s}}) & l_{\text{sys}} \sim 1 \text{ pc} \\ & B_{\text{sys}} \sim 10^{-5} \text{ G} \\ & n_e \sim 10^{-3} \frac{1}{\text{cm}^3} \end{cases}$$

$$2) q|\vec{E}| \stackrel{\text{I}}{\sim} \frac{E_{\text{sys}}^2}{l_{\text{sys}}} \stackrel{\text{I)}}{\sim} \frac{v_{\text{sys}}^2}{c^2} \frac{B_{\text{sys}}^2}{l_{\text{sys}}} \stackrel{\text{IV}}{\sim} \frac{v_{\text{sys}}^2}{c^2} \frac{1}{c} |\vec{j} \times \vec{B}| \ll \frac{1}{c} |\vec{j} \times \vec{B}| \sim |\vec{J}_L|$$

$\frac{1}{c} |\vec{j}| \sim B_{\text{sys}}/l_{\text{sys}}$

↑ non-relativistic plasma

→ neglect effects of space charge → Gauss' law I can be dropped

MHD equations:

- Ohm's law: $\vec{j} = \sigma_e \vec{E}$ (plasma at rest)
 - non-relat. motion ↓
 - $\sigma_e = \frac{n_e e^2}{m_e f_c}$ electric conductivity
 - f_c collision frequency b/w ions and e^-
$$\text{V} \quad \vec{j} = \sigma_e \left(\vec{E} + \frac{1}{c} \vec{j} \times \vec{B} \right)$$
- Ohmic dissipation (current decay due to finite conductivity):

$$\frac{\partial e}{\partial t} = \frac{1}{\sigma_e} |\vec{j}|^2$$
 conversion of EM energy into internal energy

- reaction of B-field to motion of plasma:

$\text{IV} \text{ in } \text{IV}:$

$$\vec{E} = \frac{c}{4\pi\sigma_e} \vec{\nabla} \times \vec{B} - \frac{\vec{v}}{c} \times \vec{B}$$

electric field

in III:

$$\frac{\partial \vec{B}}{\partial t} = \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) - \vec{\nabla} \times (\gamma_e \vec{\nabla} \times \vec{B})$$

induction equation

$$\gamma_e = \frac{c^2}{4\pi\sigma_e} \quad \underline{\text{electric resistivity}}$$

at rest: $\frac{\partial \vec{B}}{\partial t} = -\vec{\nabla} \times (\gamma_e \vec{\nabla} \times \vec{B}) \Rightarrow \frac{B_{\text{sys}}}{t_{\text{res}}} \sim -\gamma_e \frac{B_{\text{sys}}}{l_{\text{sys}}^2}$

$$\Rightarrow t_{\text{res}} \sim \frac{l_{\text{sys}}^2}{\gamma_e} \quad \begin{array}{l} \text{decay timescale of} \\ \text{magnetic field due} \\ \text{to finite resistivity} \end{array}$$

Note: $[\gamma_e] = [\text{length}] \times [\text{velocity}]$

and γ_e also "magnetic diffusivity"

- EM fields affect motion of plasma:

Lorentz force $\vec{F}_L = \frac{1}{c} \vec{j} \times \vec{B} \stackrel{\text{IV}}{=} \frac{1}{4\pi} (\vec{\nabla} \times \vec{B}) \times \vec{B}$

$$= \underbrace{\frac{1}{4\pi} (\vec{B} \cdot \vec{\nabla}) \vec{B}}_{\text{magnetic tension}} - \underbrace{\frac{1}{8\pi} \vec{\nabla} (\vec{B}^2)}_{\text{magnetic pressure}}$$

magnetic tension

\rightarrow curvature of \vec{B} -field lines

magnetic pressure force $P_m = \frac{\vec{B}^2}{8\pi}$

(vanishes for \vec{B} const. on straight lines)

In principle: $\vec{F}_{EM} = \vec{F}_L + q\vec{E}$, but $q|\vec{E}| \ll |\vec{F}_L|$ (see above)

MP

$$\frac{\partial \vec{s}}{\partial t} + \nabla \cdot (\vec{s} \vec{v}) = 0$$

$$\frac{\partial}{\partial t}(\vec{s} \vec{v}) + \nabla \cdot \vec{\pi} = \frac{1}{4\pi} (\vec{B} \cdot \nabla) \vec{B} - \frac{1}{8\pi} \nabla \cdot (\vec{B}^2) + \vec{s} \vec{f}$$

$$\frac{\partial \vec{E}}{\partial t} + \nabla \cdot [(\vec{E} + \vec{P}) \vec{v}] = \frac{4\pi}{c^2} \gamma_e |\vec{j}|^2 + \vec{s} \vec{v} \cdot \vec{f}$$

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times (\gamma_e \nabla \times \vec{B}) + \nabla \times (\vec{v} \times \vec{B})$$

Ideal MHD approximation: assume $\boxed{\gamma_e = 0}$

Exercise: Show that the MHD equations can be written in conservation form:

$$\frac{\partial \vec{s}}{\partial t} + \nabla \cdot (\vec{s} \vec{v}) = 0$$

(conservation of mass)

$$\frac{\partial \vec{s}}{\partial t} + \nabla \cdot \vec{T} = 0$$

(conservation of momentum)

$$\frac{\partial \vec{e}}{\partial t} + \nabla \cdot \vec{u} = 0$$

(conservation of energy)

$$\frac{\partial \vec{B}}{\partial t} + \nabla \cdot \vec{y} = \vec{s}_{res}$$

((non) conservation of magnetic flux)

$$\text{or } \partial_t u + \partial_{x_i} f^i(u) = S$$

with $u = \begin{pmatrix} \rho \\ \vec{S} \\ \mathcal{T} \\ \vec{B} \end{pmatrix}$

- ρ ← conserved momentum
- \mathcal{T} ← conserved energy

$$f(u) = \begin{pmatrix} \rho \vec{v} \\ T \\ U \\ Y \end{pmatrix}, \quad S = \begin{pmatrix} 0 \\ 0 \\ 0 \\ \vec{S}_{\text{res}} \end{pmatrix}$$

where:

$$\vec{S} \equiv \rho \vec{v} \quad (\text{momentum density})$$

$$T_{ij} \equiv \underbrace{\rho v_i v_j}_{\text{Reynolds stress tensor}} + \delta_{ij} \left(P + \frac{B^2}{8\pi} \right) - \frac{1}{4\pi} B_i B_j \quad (\text{stress tensor})$$

↑
 isotropic pressure

magnetic part
 of Maxwell stress tensor

$$\begin{aligned} \mathcal{T} &\equiv \frac{1}{2} \rho v^2 + e + \frac{B^2}{8\pi} && (\text{total energy density}) \\ &= E + \frac{B^2}{8\pi} \end{aligned}$$

$$\vec{U} = (E + P) \vec{v} + \frac{1}{4\pi} \left(-\vec{v} \times \vec{B} + \frac{4\pi}{c} \gamma_e \vec{j} \right) \times \vec{B} \quad (\text{energy flow vector})$$

$$\gamma_{ij} \equiv v_i B_j - v_j B_i$$

$$\vec{S}_{\text{res}} = \gamma_e \nabla^2 \vec{B} + \frac{4\pi}{c} \vec{j} \times \nabla \gamma_e \quad (\text{resistive source term})$$

Limits of MHD approximation:

Collisionless regime:

Drift velocity only small as long as EM forces due to large-scale fields balanced by frictional forces due to interparticle collisions

→ breaks down at low density when e^- -ions decouple:

$$f_e^L = f_e^{\text{coll}} \quad \begin{matrix} \text{"Coulomb} \\ \text{"logarithm", weakly} \\ \text{dependent on } T, n_e \end{matrix}$$

\nearrow

$$\propto 3.7 \ln \Delta T^{-3/2} n_e$$

$\frac{q_e B}{\omega_{ce}}$ Larmor (cyclotron) frequency of collisions b/w free e^-

Zone C frequency of gyration

Example: star-forming cloud: $T \sim 10K$, $B \sim 10^{-5} G$

$$\Rightarrow n_e^{\text{crit}} \approx 10^4 \text{ cm}^{-3}$$

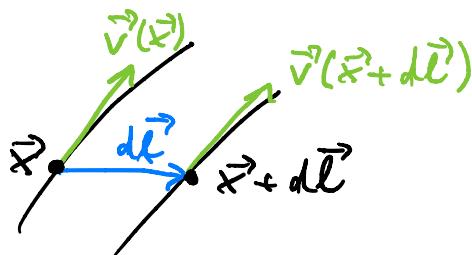
is rather high, especially bc of low ionization degree

But: often MHD approximation works well even in collisionless regime (e.g. solar wind past the Earth)

→ non-linear phenomena (not captured by MHD model) cause collisionless plasma to behave as continuous medium

Flux conservation & field freezing:

Assume ideal MHD: $\gamma_e \equiv 0$.

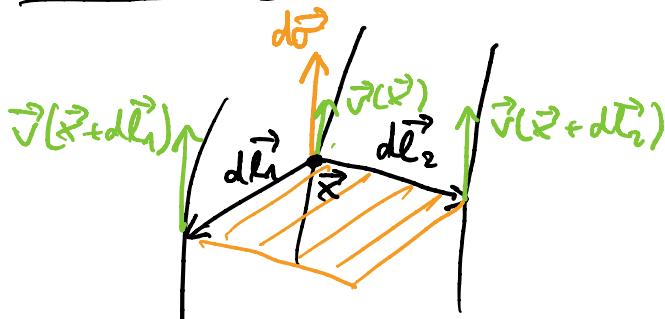


Co-moving line element (Lagrangian derivative):
Taylor

$$\frac{d}{dt}(d\vec{l}) = \frac{d(\vec{x} + d\vec{l})}{dt} - \frac{d\vec{x}}{dt} \stackrel{\text{def}}{=} \vec{v}(\vec{x} + d\vec{l}) - \vec{v}(\vec{x}) \stackrel{*}{=} (\nabla \vec{v}) \cdot d\vec{l}$$

(change of $d\vec{l}$ comoving with flow)

Co-moving surface element $d\vec{\sigma} = d\vec{l}_1 \times d\vec{l}_2$:



$$\frac{d(d\vec{\sigma})}{dt} = \frac{d(d\vec{l}_1)}{dt} \times d\vec{l}_2$$

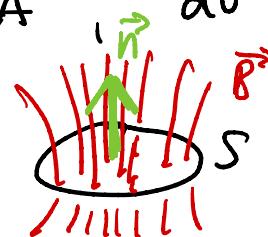
$$+ d\vec{l}_1 \times \frac{d(d\vec{l}_2)}{dt}$$

$$= d\vec{l}_1 \cdot \nabla \vec{v} \times d\vec{l}_2 - d\vec{l}_2 \cdot \nabla \vec{v} \times d\vec{l}_1$$

vector identity $\nabla \times (A \times B) = (A \cdot \nabla)B - (B \cdot \nabla)A - A \times (\nabla \times B) + B \times (\nabla \times A)$

$$= -(\vec{d\sigma} \times \nabla) \times \vec{v} = -\nabla \vec{v} \cdot \vec{d\sigma} + \nabla \cdot \vec{v} \vec{d\sigma}$$

Magnetic flux: $\Phi_m = \int_S \vec{B} \cdot \vec{n} dA$, $d\vec{\sigma} = \vec{n} dA$



$$\text{and } \frac{d}{dt}(\Phi_m) = \frac{d}{dt}(\vec{B} \cdot d\vec{\sigma}) = \frac{d\vec{B}}{dt} \cdot d\vec{\sigma} + \vec{B} \cdot \frac{d(d\vec{\sigma})}{dt}$$

Note: $\frac{\partial \vec{B}}{\partial t} \stackrel{\eta_c=0}{=} \nabla \times (\vec{v} \times \vec{B})$ vector identity $= \vec{B} \cdot \nabla \vec{v} - \vec{B} \nabla \cdot \vec{v} - \vec{v} \cdot \nabla \vec{B}$

$$\Rightarrow \frac{d\vec{B}}{dt} \stackrel{\text{def}}{=} \frac{\partial \vec{B}}{\partial t} + \vec{v} \cdot \nabla \vec{B} = \vec{B} \cdot \nabla \vec{v} - \vec{B} \nabla \cdot \vec{v}$$

Therefore:

$$\begin{aligned} \frac{d}{dt}(\Phi_m) &= (\vec{B} \cdot \nabla \vec{v} - \vec{B} \nabla \cdot \vec{v}) \cdot d\vec{\sigma} + \vec{B} \cdot (-\nabla \vec{v} \cdot d\vec{\sigma} + \nabla \cdot \vec{v} d\vec{\sigma}) \\ &= 0 \end{aligned}$$

co-moving surface element $d\vec{\sigma}$ arbitrary

\Rightarrow flux through any surface S moving with the fluid is conserved:

$$\Phi_m = \int_S \vec{B} \cdot \vec{n} dA = \text{const.}$$

field freezing (consider limit $d\vec{\sigma} \rightarrow 0$, i.e. "single field line". Since $\Phi_m \rightarrow 0$ divide by $\epsilon \rightarrow 0$)

$$\begin{aligned} \frac{d}{dt}\left(\frac{\vec{B}}{S}\right) &= \frac{1}{S}(\vec{B} \cdot \nabla \vec{v} - \vec{B} \nabla \cdot \vec{v}) + \frac{\vec{B}}{S} \nabla \cdot \vec{v} \\ &= \left(\frac{\vec{B}}{S}\right) \cdot \nabla \vec{v} \end{aligned}$$

\Rightarrow line element $d\vec{l} \parallel \vec{B}$ moves as $\frac{\vec{B}}{c}$ (see (1))
 i.e. plasma along $d\vec{l}$ and \vec{B} move together
 and \vec{B} -field is "frozen in" the fluid

Note: motion along the field lines is preserved
 however!

Limits of ideal MHD:

- $\eta_e = 6.5 \times 10^{12} \frac{\ln \Lambda}{T^{3/2}} [\text{cm}^2/\text{s}]$ (fully ionized hydrogen plasma)
 $\sim 10^8$ for HII region $\left(T \sim 10^4 \text{K}, \ln \Lambda \approx 20, n_e = 10 - 100 \frac{1}{\text{cm}^3}, l_{\text{sys}} \sim 1 \text{pc} \right)$
 \rightarrow diffusivity timescale $t_{\text{res}} \sim \frac{l_{\text{sys}}^2}{\eta_e} \sim 10^{21} \text{yr}$
 $\sim 10^{11}$ age of universe
 \rightarrow ideal MHD very good!
- But: η_e becomes large / t_{res} small if
 - 1) where field becomes very tangled or when oppositely directed fields come in close contact (small l_{sys})

2) plasma strongly turbulent

\Rightarrow turbulent magnetic diffusivity

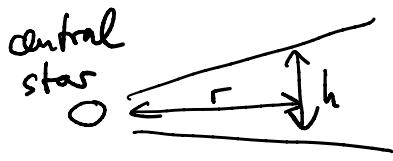
$$\eta_e^t \equiv v_t l_t = \underbrace{v_t}_{\text{Sec. 2.3}}$$

3) plasma weakly ionized

If $n_e \ll n_n$, n_n : number density of neutral particles

$$\eta_e = 300 \frac{n_n}{n_e} \sqrt{T} \left[\frac{\text{cm}^2}{\text{s}} \right] \quad \text{valid up to } T \approx 10^4 \text{ K}$$

Example: protoplanetary disk (neglect turbulence)



$$\frac{h}{r} \approx 0.1, T \approx 10^3 \text{ K}$$

$$r_{\text{sys}} \approx 1.5 \times 10^{12} \text{ cm} \quad \begin{matrix} \text{(height at Earth's)} \\ \text{radius} \end{matrix}$$

$$t_{\text{disk}} \approx 10^7 \text{ yr} \quad (\text{lifetime of disk})$$

$$\frac{n_e}{n_n} \approx 10^{-6} \quad (t_{\text{disk}} \stackrel{!}{=} t_{\text{res}})$$

$$\text{For } t_{\text{res}} < t_{\text{disk}} \text{ one requires } \frac{n_e}{n_n} < 10^{-6}$$

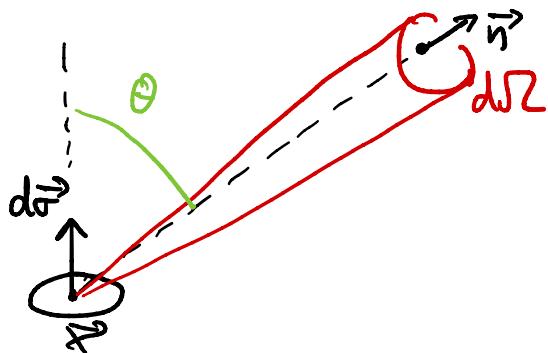
\Rightarrow even at these low ionization degrees
ideal MHD is still valid!

2.5 Radiation transfer

Def: radiation intensity

$$I_r(\vec{x}, \vec{n}, v, t) = \frac{dE_r}{\vec{n} \cdot d\vec{\sigma} d\Omega dv dt}$$

energy of photons that pass through an area $d\vec{\sigma}$ at point \vec{x} in direction \vec{n} , within a solid angle $d\Omega$ in the frequency interval $(v, v+dv)$ in time dt



Phase space for photons: use $\vec{u} \mapsto \vec{q}$ (momentum) as photons are massless and propagate with velocity c

$$\left. \begin{aligned} \text{total number} & \quad dN = f(\vec{x}, \vec{q}, t) d\vec{x} d\vec{q} \\ \text{total radiation energy} & \quad dE_r = h\nu f(\vec{x}, \vec{q}, t) d\vec{x} d\vec{q} \end{aligned} \right\} \begin{matrix} \downarrow \\ \text{within phase space volume } d\vec{x} d\vec{q} \end{matrix}$$

Note: consider a beam of photons as in previous definition.



$$\text{so } d\vec{x} = c dt (\vec{n} \cdot d\vec{\sigma})$$

spatial volume swept out by the beam in time dt

$$\begin{aligned} d\vec{q} &= q^2 dq d\Omega \\ &= \left(\frac{hv}{c}\right)^2 \frac{h}{c} dv d\Omega \end{aligned}$$

spherical polar coord.
in momentum space
 $q = |\vec{q}|$, $\vec{q} = \frac{hv}{c} \vec{n}$

$$\Rightarrow dE_v = \frac{h^4 v^3}{c^2} f(\vec{x}, v, \vec{n}, t) \vec{n} \cdot d\vec{\sigma} dv d\Omega dt$$

$$\Rightarrow I_v = \frac{h^4 v^3}{c^2} f$$

Boltzmann equation:

$$\vec{f} = 0 \text{ for photons}$$

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + cn_i \frac{\partial f}{\partial x_i} = \left[\frac{\partial f}{\partial t} \right]_{\text{coll}}$$

$u_i = cn_i$

$$\frac{1}{c} \frac{\partial I_v}{\partial t} + (\vec{n} \cdot \vec{\nabla}) I_v = \left[\frac{\partial I_v}{\partial t} \right]_{\text{coll}}$$

$$= \frac{\partial}{\partial s}$$

equation of radiation transfer
interaction of photons with matter
→ absorption, emission & scattering

For a time-independent problem:

$$\frac{dI_r}{ds} = \left[\frac{\partial I_r}{\partial t} \right]_{\text{coll}}$$

Computational challenge:

$$I_r(\vec{x}, v, \vec{n}, t) = I_r(r, \theta, \phi, v, \theta', \phi', t)$$

6+1 D function!

momentum space

take 100 grid points per variable

→ need to store $(10^2)^6 = 10^{12}$ values per time step!

→ direct numerical solution of radiation transfer equation computationally prohibitive, need additional simplifications (reduce number of spatial dimensions etc.)

or solve set of approximate equations (moment schemes etc.)

Exercise: M1 moment scheme

2.6 Relativistic Hydrodynamics

In special relativity the Euler equations can be written as

$$\partial_\mu (su^\mu) = 0$$

$$\partial_\mu T^{\mu\nu} = 0$$

For an ideal/perfect fluid (in local rest frame no energy fluxes & anisotropic stresses):

$$T^{\mu\nu} = \underbrace{(E + p)}_{\substack{\text{total energy} \\ \text{density}}} u^\mu u^\nu + p \gamma^{\mu\nu}$$

Minkowski metric

energy-momentum tensor

specific internal energy measured in local rest frame

\uparrow \uparrow \uparrow

isotropic pressure

specific enthalpy

$$E = sc^2 + e = s(1+\epsilon)$$

\uparrow henceforth set $c=1$

General relativity: invoke the equivalence principle and use the substitution rules

$$\partial_\mu (su^\mu) = 0$$

$$\partial_\mu T^{\mu\nu} = 0$$



equivalence
principle, substitution rules

$$g_{\mu\nu} \rightarrow g_{\mu\nu}$$

$$\partial_\mu \rightarrow \nabla_\mu$$

$$\nabla_\mu (s u^\mu) = 0$$

$$\nabla_\mu T^{\mu\nu} = 0$$

$$S_{SR}, X_{SR}^M T_{\mu\cdots\mu}^{i_1\cdots i_r} \xrightarrow{\text{in...jse}} S_{GR}, X_{GR}^M$$

$T_{\mu\cdots\mu}^{i_1\cdots i_r}$
in...jse
is GR

$$T^{\mu\nu} = (E + p) u^\mu u^\nu + p g^{\mu\nu}$$

(alternatively: Bianchi identities imply $\nabla_\mu T^{\mu\nu} = 0$)

Goal: want to rewrite these equations as an initial boundary value problem in conservation form so that one can use similar techniques as in the Newtonian case

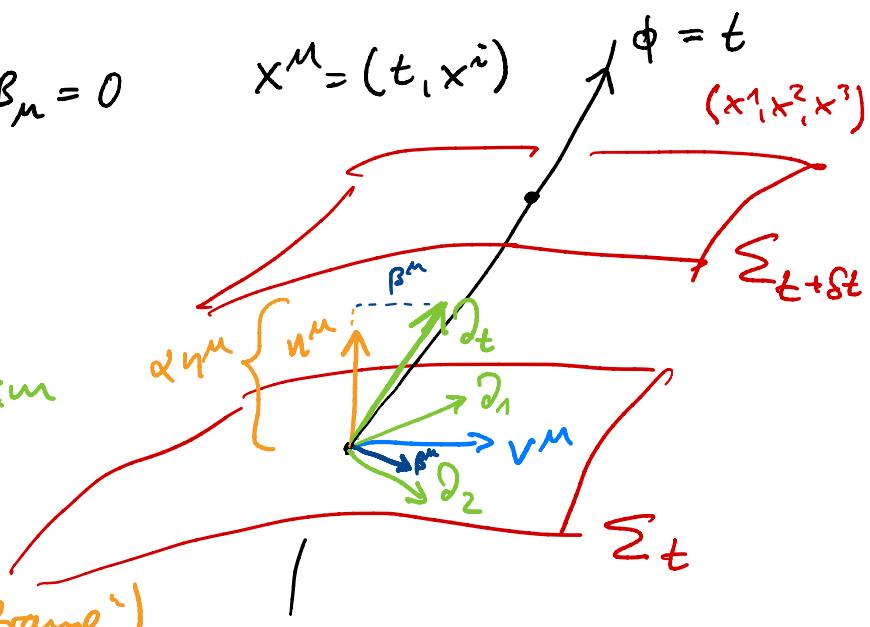
→ 3+1 decomposition of spacetime

$$(\partial_t)^M = \alpha u^M + \beta^M, \quad n^M \beta_M = 0$$

↑ "lapse" ↑ "shift"

represent 4 DOF to specify coordinates (diffeomorphism invariance of GR)

$u^M = n^M$: Eulerian observer ("lab frame")



no motion wrt spatial coordinates

$$\|\partial_t\|^2 = (\partial_t)^\mu (\partial_t)_\mu = -\alpha^2 + \beta_\mu \beta^\mu = -\alpha^2 + \beta^2$$

so $(\partial_t)^\mu$ timelike $\Leftrightarrow \beta^2 < \alpha^2$

$(\partial_t)^\mu$ null $\Leftrightarrow \beta^2 = \alpha^2$

$(\partial_t)^\mu$ spacelike $\Leftrightarrow \beta^2 > \alpha^2$

Adapted coordinates:

$$(\partial_t)^\mu = (1, 0, 0, 0)$$

$$\beta^\mu = (0, \beta^i)$$

$$\text{so } n^\mu = \frac{1}{\alpha} (\partial_t)^\mu - \frac{1}{\alpha} \beta^\mu = \left(\frac{1}{\alpha}, -\frac{1}{\alpha} \beta^i \right)$$

$$n_\mu = (-\alpha, 0, 0, 0)$$

$$g_{00} = g(\partial_t, \partial_t) = -\alpha^2 - \beta^2$$

$$g_{0i} = g(\partial_t, \partial_i) = (\alpha n^\mu + \beta^\mu)(\partial_i)_\mu$$

$$= \underbrace{\alpha n^\mu (\partial_i)_\mu}_= 0 + \beta^\mu (\partial_i)_\mu = \beta_i$$

$$g_{ij} = g(\partial_i, \partial_j) \equiv \delta_{ij}$$

$$g_{\mu\nu} = \begin{pmatrix} -\alpha^2 - \beta^2 & \beta_i \\ \beta_i & \delta_{ij} \end{pmatrix}$$

$$\text{or: } ds^2 = -\alpha^2 dt^2 + \gamma_{ij} (dx^i + \beta^i dt)(dx^j + \beta^j dt)$$

↳ measures proper time that elapses going from one time slice to the next along ds no "lapse"

Note: a specific choice of α & β^i represents a specific choice of coordinates (gauge)

Example: $\alpha \equiv 1$ (Geodesic gauge)
 $\beta^i \equiv 0$

• $ds^2 = \alpha dt^2 = dt^2$ for Eulerian observers

$\Rightarrow t = \tau$ represents proper time of Eulerian observers

- curves c of $\{x^i\} = \text{const.}$ are orthogonal to Σ_t , i.e. Eulerian observers move on geodesics:

$$a_\mu = \nabla_c \dot{c} = \nabla_\mu u = n^\nu \nabla_\nu n_\mu$$

$$\begin{cases} n^\nu \nabla_\nu \alpha = 0 & \mu = 0 \\ 0 & \mu = 1, 2, 3 \end{cases}$$

"Gaussian normal coordinates"

Adapted equations of hydrodynamics:

Split fluid velocity

$$u^\mu = W(n^\mu + v^\mu)$$

$$\text{and } v^i = \frac{ds^i}{d\tau_{\text{Eul}}} = \frac{u^i}{W} + \frac{1}{\alpha} \beta^i \quad \begin{array}{l} \text{fluid velocity} \\ \text{relative to Eulerian obs.} \end{array}$$

$$W = -u^\mu n_\mu \quad \begin{array}{l} \text{Lorentz factor b/w Eulerian} \\ \text{\& comoving (fluid) frame} \end{array}$$

and define

$$E_E \equiv n^\mu n^\nu T_{\mu\nu} = (E+p)W^2 - p = hsW^2 - p$$

$$S_i \equiv -g_i{}^\mu n^\nu T_{\mu\nu} = (E+p)W^2 v_i = hsW^2 v_i$$

$$S_{ij} \equiv g_i{}^\mu g_j{}^\nu T_{\mu\nu} = hsW^2 v_i v_j + p \delta_{ij}$$

$$(h \equiv 1 + \epsilon + p \quad \text{specific enthalpy})$$

(total energy density, momentum density,
stress-energy as measured by Eulerian observer)

then one obtains:

$$\bullet \partial_\mu (\gamma u^\mu) \rightarrow \boxed{\partial_t (\sqrt{g} D) + \partial_i (\sqrt{g} D \tilde{v}^i) = 0}$$

$D = \gamma W$ rest mass measured by Eulerian obs.

$$\tilde{v}^i = \alpha v^i - \beta^i$$

- $\partial = n_\mu \nabla_\nu T^{\mu\nu}$ (projection of conservation law)
(along Eulerian observer)

$$\rightarrow \partial_t (\sqrt{g} E_E) + \partial_j [\sqrt{g} (\alpha S^j - E_E \beta^j)] = \alpha \sqrt{g} (K_{ij} S^{ij} - S^k \partial_k \ln \alpha)$$

extrinsic curvature
of Σ_t

- $\partial = \gamma_i{}^\mu \nabla_\mu T^\nu{}_\nu$ (spatial projection)

$$\rightarrow \partial_t (\sqrt{g} S_i) + \partial_j [\sqrt{g} (S_j \tilde{v}^i + \rho \delta^i{}_j)] = \sqrt{g} \left[\frac{\alpha}{2} S^{kl} \partial_i \delta_{kl} \right. \\ \left. + S_\ell \partial_i \beta^\ell - S \partial_i \alpha \right]$$

no conservative formulation: $\partial_t u + \partial_i f^i(u) = S(u)$

$$u = \sqrt{g} (D, S_i, \tilde{v})$$

$$f^i = \sqrt{g} (D \tilde{v}^i, S_j \tilde{v}^i + \rho \delta^i{}_j, \tilde{v} \tilde{v}^i + \rho v^i)$$

$$S(u) = (0, \alpha \sqrt{g} (K_{ij} S^{ij} - S^k \partial_k \ln \alpha), \sqrt{g} (\frac{\alpha}{2} S^{kl} \partial_i \delta_{kl} + S_\ell \partial_i \beta^\ell - S \partial_i \alpha))$$

$$(T = E_E - D)$$

Remarks: 1) The energy equation is written in terms of $\tau = E_E - D$, in order to obtain the "correct" Newtonian limit:

$$\tau = E_E - D = \gamma h w^2 - p - \gamma w$$

$$\frac{p}{\gamma c^2} \stackrel{\ll 1}{=} \underbrace{\gamma w(w-1)}_{\approx 1 + \left(\frac{w}{c}\right)^2} + \gamma \varepsilon w^2 \approx \frac{1}{2} \gamma v^2 + \gamma \varepsilon$$

$$\approx \left[1 + \frac{1}{2} \left(\frac{w}{c}\right)^2\right] \left[\frac{1}{2} \left(\frac{w}{c}\right)^2 + \dots\right]$$

2) $s(u)$: "geometric source terms"

Note: do not depend on time derivatives of space-time quantities!

3) EOS: As in Newtonian hydrodynamics, the system is closed by an equation of state
 $p = p(\gamma, \varepsilon, \dots)$

4) Conservatives & primitives:

$$u \equiv \sqrt{f}(D, S_i, \tau) \quad \text{"conservatives"}$$

$$w \equiv (\gamma, v^i, \varepsilon) \quad \text{"primitives"}$$

In order to compute flux terms during evolution, one must compute w from u numerically (no need $p = p(\gamma, \varepsilon)$)

typically: obtain these via non-linear
root-finding in some variable z

$$f(z) = z(\xi, \epsilon, v^i) - z$$

where $z(\xi, \epsilon, v^i)$ is computed from
 ξ, ϵ, v^i obtained from conservatives

Example: $z=p$

$$\text{and } v^i = \frac{\xi^i}{z+p}, \quad w = \sqrt{1-v_i v^i}$$

$$\epsilon = \frac{D}{W}$$

$$\epsilon = \frac{z - DW + p(1-w^2)}{DW}$$

See Siegel et al. ApJ 859, 71 (2018) for a discussion of recovery schemes.

5) Hyperbolicity: the eqns in conservative form are strongly hyperbolic if the EOS is causal,

$$c_s^2 = \frac{\partial P}{\partial e} < 1 \quad (\text{sound speed} < \text{speed of light})$$

see Ante 1990, Anton et al. 2006 ApJ 637, 296 for hydrodynamic & magnetohydrodynamic case

6) Special-relativistic limit:

$$\alpha \rightarrow 1, \beta^i \rightarrow 0, \gamma_{ij} \rightarrow \eta_{ij}$$

$$(\Rightarrow v^i \rightarrow v^i)$$

and $u = (1, S_i, \varepsilon)$

$$f^\lambda(u) = (Dv^i, S_j v^i + p \delta^i_j, \varepsilon v^i + p v^i)$$

$$S(u) = 0$$

7) Newtonian limit: SR limit plus

$$\frac{v}{c} \ll 1, \omega \rightarrow 1 + \frac{1}{2} \left(\frac{v}{c} \right)^2$$

$$\frac{p}{sc^2} \ll 1, h \rightarrow 1, \varepsilon \rightarrow E = s\varepsilon + \frac{1}{2} sv^2$$

and $u = (s, sv_j, E)$

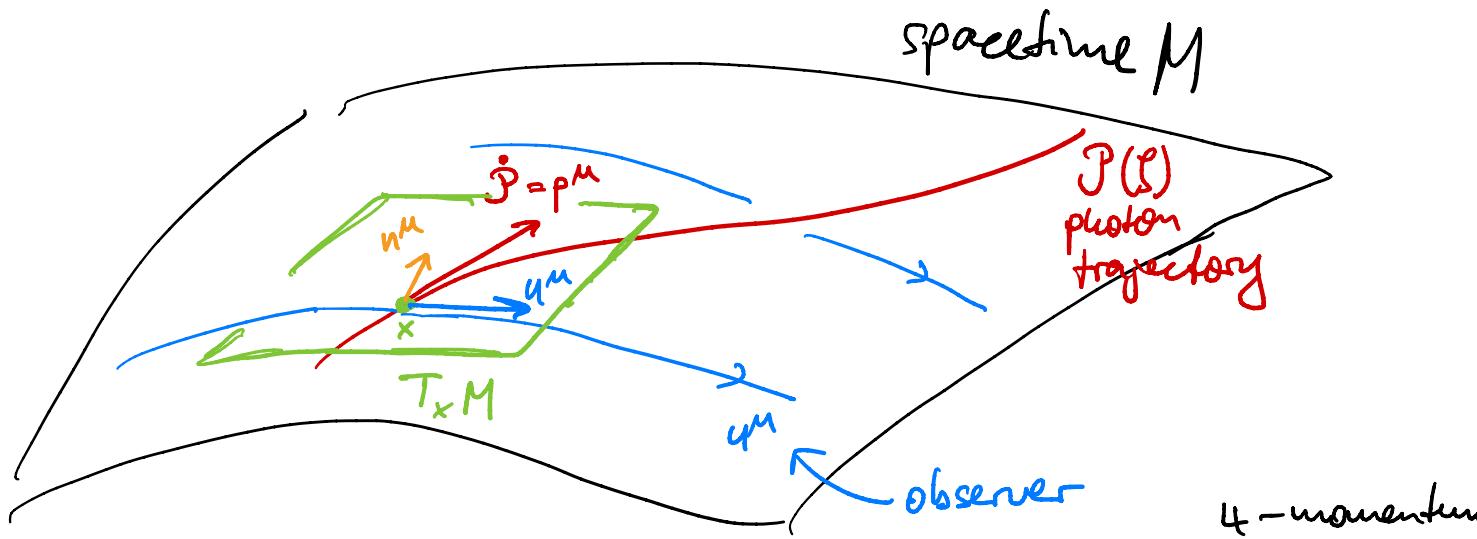
$$f^\lambda(u) = (Dv^i, sv^i v_j + p \delta^i_j, (E+p)v^i)$$

$$S(u) = 0$$

(cf. Sec. 2.2)

2.7 Relativistic radiation transfer

Reading: Thorne 1981, MNRAS 194, 439
 Straumann Chap. 3.11



- Consider light-like (massless) particle $p_\mu p^\mu = 0$ moving along trajectory $P(s)$, parametrized such that $\dot{P}(s) = p^\mu$

Decompose: $p^\mu = -p^\nu u_\nu$ ($u^\mu + n^\mu$)

\nwarrow unit normal
 \nwarrow in orthogonal space to u^μ

$$n^\mu u_\mu = 1, \quad n^\mu u_\mu = 0$$

- Reparametrize by proper spatial distance l travelled by photon as seen by observer u^μ :

$$l \equiv \int (-p_\mu u^\mu) ds, \quad dl = (-p_\mu u^\mu) ds$$

$$\text{as } P = P(l), \quad \dot{P}_l = \frac{dP}{dl} = \frac{dP}{ds} \frac{ds}{dl} \\ = (-\rho^{\mu} u_{\mu})(u^{\mu} + n^{\mu}) \frac{1}{(-\rho u n^{\mu})} = u^{\mu} + n^{\mu}$$

- Consider particle distribution function

$$f(x^{\mu}, p^{\mu}) \quad (\text{number density of light-like particles in phase space})$$

↓ ↓
 point in spacetime 4-momentum
 P on light cone in
 $T_p M$

actually: $f = f(t, x^i, p^i)$ as p^0 determined by

$$p_{\mu} p^{\mu} = 0 \quad (\text{light cone particles})$$

- Note: along each photon trajectory the number density is conserved (in absence of interactions with medium)

(Liouville's theorem): $\frac{df}{dl} = 0$

$$\text{as } \boxed{\frac{df}{dl} = \frac{\partial f}{\partial x^{\mu}} \frac{dx^{\mu}}{dl} + \frac{\partial f}{\partial p^i} \frac{dp^i}{dl} = S(x^{\mu}, p^{\mu}, f)}$$

GR radiation transfer equation

(Boltzmann equation in GR)

S : source term ("collision terms") that accounts for emission, absorption & scattering

Note: $\frac{dx^\mu}{dt} = \dot{\mathcal{P}}_L = n^\mu + u^\mu$ (see above)

$$\frac{dp^i}{dt} = \dot{p}^i = (\dot{\mathcal{P}}_L)^i = -\Gamma_{\mu\nu}^{i\mu} p^\nu \dot{x}^\nu$$

$$= -\Gamma_{\mu\nu}^{i\mu} p^\nu (n^\nu + u^\nu) \quad (\text{null geodesic!})$$

Moment formalism: (analogous to Newtonian case)

Thorne 1981, MNRAS 194, 439

Define k -th moment

of distribution function

restrict integration to light cone

$$M_v^{\alpha_1 \dots \alpha_k} = \int \frac{f(x^\mu, p^\mu) \delta(p^\mu u_\mu + v)}{(-p^\mu u_\mu)^{k-2}} p^{\alpha_1} \dots p^{\alpha_k} dV_p$$

↑ frequency
 $v = -p^\mu u_\mu$

→ can derive evolution equations for

the moments in conservation form,
analogous to the Newtonian case,
closed by Eddington factors
(→ "M1 scheme")

see Thorne 1981 & Shibata et al. Prog. Theo. Phys.
125, 1255 (2011)