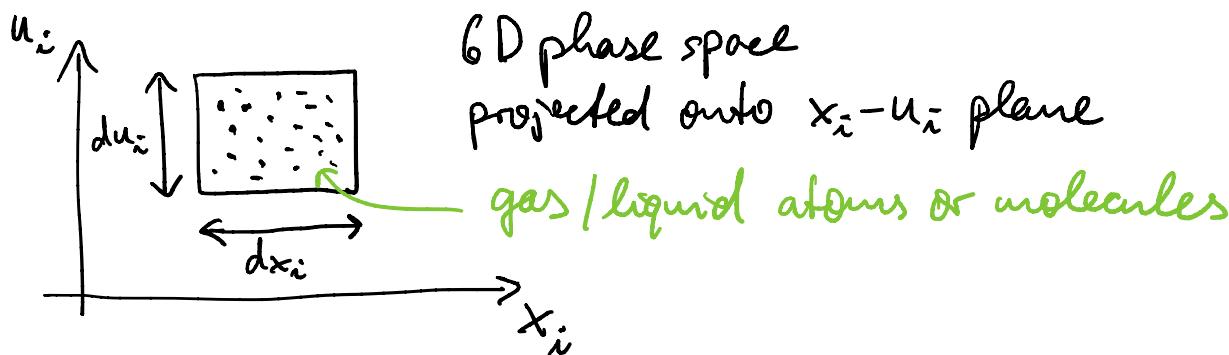


Chapter 2: Basic Equations

2.1 Continuous media: Boltzmann Eq



In principle evolution of system fully determined by Newtonian mechanics (N-body equations):

$$\frac{d\vec{x}_i}{dt} = \vec{u}_i \quad , \quad \frac{d\vec{u}_i}{dt} = \vec{F}_i(x_j, u_j, t) \quad \forall \text{ particles } i, j$$

\uparrow force on i

But: 1 mole $\hat{=} N = 6 \times 10^{23}$ particles \rightarrow computationally prohibitive

\rightarrow statistical approach (continuous media)
 \rightarrow hydrodynamics

$$dN = f(\vec{x}, \vec{u}, t) d\vec{x} d\vec{u}$$

\uparrow number of particles in phase-space control volume
 $d\vec{x} d\vec{u}$

\nwarrow distribution function

- ignore internal degrees of freedom \rightarrow vibration, rotation
- identical particles of mass m
- ignore QM effects

Assume particles subject to external force per unit mass \vec{F} (\approx constant over typical inter-particle separation)

\Rightarrow particle number $f(\vec{x}, \vec{u}, t) d\vec{x} d\vec{u}$ conserved along their trajectories in phase space (Liouville's theorem) in absence of interactions:

(*)

$$\Delta f = f(\vec{x} + \underbrace{\vec{u} dt}_{\text{change in position}}, \vec{u} + \underbrace{\vec{F} dt}_{\text{change in velocity due to } \vec{F}}, t + dt) - f(\vec{x}, \vec{u}, t) = [\Delta f]_{\text{coll}}$$

change in position

change in velocity
due to \vec{F}

$$\begin{aligned} dt &\rightarrow 0 \\ \Delta f &\rightarrow \frac{df}{dt} \end{aligned}$$

↑ change in f in dt due to collisions

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + u_i \frac{\partial f}{\partial x_i} + F_i \frac{\partial f}{\partial u_i} = \left[\frac{\partial f}{\partial t} \right]_{\text{coll}}$$

Boltzmann's transport equation

→ evolution of distribution function in 6-D phase space (\vec{x}, \vec{u})

→ change dN in number of particles within a fixed volume $d\vec{x} d\vec{u}$ equals net number of particles entering or leaving this volume

(→ Liouville's theorem)

Some definitions:

$$n(\vec{x}, t) \equiv \int f(\vec{x}, \vec{u}, t) d\vec{u}$$

$\underbrace{\qquad\qquad\qquad}_{\text{# particles per unit volume in } \vec{u}, \vec{u}+d\vec{u}}$

total number of particles per unit volume

- $\ell \equiv n^{1/3}$ mean particle separation

Note: any physical length scale $d\vec{x}$ we are interested in must be $\gg \ell$ for statistical approach to be valid

- $\rho(\vec{x}, t) = \int m f(\vec{x}, \vec{u}, t) d\vec{u}$ mass density
- $\vec{v}(\vec{x}, t) = \frac{1}{S} \int \vec{u} m f(\vec{x}, \vec{u}, t) d\vec{u}$ bulk velocity
- $\rho E(\vec{x}, t) = \frac{1}{2} \int m \vec{u}^2 f(\vec{x}, \vec{u}, t) d\vec{u}$ specific internal energy E
 $\uparrow \vec{u} = \vec{v} - \vec{v}$ peculiar velocity

Special case:

- elastic collisions (energy & momentum conserved)
- low density (collisions of 3 & more particles)
 (can be neglected)
- absence of external forces $\vec{F} \equiv 0$

unique solution \downarrow statistical mechanics

$$f(\vec{x}, \vec{u}, t) d\vec{u} = n(\vec{x}, t) \left[\frac{m}{2\pi k_B T(\vec{x}, t)} \right]^{3/2} \exp \left[-\frac{m(\vec{u} - \vec{v})^2}{2k_B T(\vec{x}, t)} \right] d\vec{u}$$

Maxwellian velocity

distribution
 (equilibrium state $t \rightarrow \infty$,
 $\frac{\partial f}{\partial t} = 0$)

2.2 From Boltzmann to Euler

Def: k-th moment of the Boltzmann equation

$$\int u_k \left[\frac{\partial f}{\partial t} + u_i \frac{\partial f}{\partial x_i} + f_i \frac{\partial f}{\partial u_i} \right] du = \int u_k \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} du,$$

where $u_k = \vec{u}^k$, i.e. $u_0 = 1$, $u_1 = \vec{u}$, $u_2 = u^2$ etc.

General properties of collision term:

If collisions are elastic and neither create nor destroy particles, then

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0 \quad \begin{matrix} \text{number of particles} \\ \text{conserved} \end{matrix}$$

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} u_i d\vec{u} = 0 \quad \begin{matrix} \text{total momentum} \\ \text{conserved} \end{matrix}$$

$$\int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} u^2 d\vec{u} = 0 \quad \begin{matrix} \text{total energy} \\ \text{conserved} \end{matrix}$$

$$\lim_{u \rightarrow \infty} u^k f = 0 \quad \begin{matrix} \text{total number, momentum} \\ \text{energy must be finite} \end{matrix}$$

$$\text{Also: } \left(\int_{\Omega} v \frac{\partial u}{\partial x_i} = \int_{\Omega} uv n_i d\Gamma - \int_{\Omega} u \frac{\partial v}{\partial x_i} \right)$$

$$\int \frac{\partial f}{\partial u_i} d\vec{u} \stackrel{P.i.}{=} \int f n_i d\Gamma - \int \underbrace{\frac{\partial(1)}{\partial u_i} f}_{=0} d\vec{u} = 0$$

$$\int u_j \frac{\partial f}{\partial u_i} d\vec{u} \stackrel{P.i.}{=} \underbrace{\int u_j f n_i d\Gamma}_{|u|= \pm \infty} - \int \underbrace{\frac{\partial u_j}{\partial u_i} f}_{=\delta_{ij}} d\vec{u}$$

$$= -\delta_{ij} \frac{g}{m}$$

$$\frac{1}{2} \int u^2 \frac{\partial f}{\partial u_i} d\vec{u} = \frac{1}{2} \int u^2 f n_i d\Gamma - \frac{1}{2} \int \underbrace{\frac{\partial u^2}{\partial u_i} f}_{|u|= \pm \infty} d\vec{u} \stackrel{\frac{\partial(\sum_j u_j^2)}{\partial u_i} = 2u_i}{=} 2u_i$$

$$= - \int u_i f d\vec{u} = - \frac{g}{m} v_i$$

① From θ -moment of Boltzmann eqn:

$$m \int \frac{\partial f}{\partial t} d\vec{u} + m \int u_i \frac{\partial f}{\partial x_i} d\vec{u} + m \overline{v}_i \underbrace{\int \frac{\partial f}{\partial u_i} d\vec{u}}_{=0} = \int \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0$$

u_i, x_i independent

$$\Downarrow \Leftrightarrow \frac{\partial}{\partial t} \int m f d\vec{u} + \frac{\partial}{\partial x_i} \int u_i m f d\vec{u} = 0$$

\Leftrightarrow

$$\frac{\partial \mathbf{S}}{\partial t} + \nabla \cdot (\mathbf{S} \vec{v}) = 0$$

continuity
equation

Note: V large enough

$$\Rightarrow \int \frac{\partial \mathbf{S}}{\partial t} dV + \underbrace{\int \nabla \cdot (\mathbf{S} \vec{v}) dV}_{\text{Gauss}}$$

$$= \int_V \mathbf{S} v_i n_i d\Omega = 0 \quad \vec{v} = 0 \text{ on } \partial V$$

↑
unit
normal

$$= \frac{\partial}{\partial t} \int_V \mathbf{S} dV = \frac{\partial M_V}{\partial t} = 0 \quad \text{mass conservation}$$

② From 1st-moment of Boltzmann eqn:

$$m \int u_i \frac{\partial f}{\partial t} d\vec{u} + m \int u_i u_j \frac{\partial f}{\partial x_i} d\vec{u} + m F_j \underbrace{\int u_i \frac{\partial f}{\partial u_j} d\vec{u}}_{= -\delta_{ij} \frac{f}{m}} = 0$$

$$= \int u_i \left[\frac{\partial f}{\partial t} \right]_{\text{coll}} d\vec{u} = 0$$

$$\Leftrightarrow \frac{\partial}{\partial t} (S v_i) + \frac{\partial}{\partial x_i} \int m u_i u_j f d\vec{u} - S F_i = 0$$

$$\int m \tilde{u}_i \tilde{u}_j f d\vec{u} = \int m (\tilde{u}_i + v_i)(\tilde{u}_j + v_j) f d\vec{u}$$

$\xrightarrow{\text{cross terms vanish}}$

$$\int \tilde{u}_i f d\vec{u} = 0 \quad \xrightarrow{\text{peculiar velocities}} \quad \equiv s v_i v_j + P_{ij}$$

$$P_{ij} = \int m \tilde{u}_i \tilde{u}_j f d\vec{u} \quad \begin{matrix} \text{pressure} \\ \text{tensor} \end{matrix}$$

Most astrophysical cases:

$$\text{isotropic pressure} \Rightarrow P_{ij} = P \delta_{ij}$$

$$P = \frac{1}{3} \int m \tilde{u}^2 f d\vec{u}$$

$$(P = \frac{2}{3} s \epsilon)$$

$$\Leftrightarrow \frac{\partial}{\partial t} (s v_i) + \frac{\partial}{\partial x_j} (s v_i v_j) = - \frac{\partial P}{\partial x_i} + s \vec{F}_i$$

$$\Leftrightarrow \boxed{\frac{\partial}{\partial t} (s \vec{v}) + \nabla \cdot \Pi = s \vec{F}}$$

momentum
equation

$$\Pi = s v_i v_j + P \delta_{ij} \quad \begin{matrix} \text{momentum} \\ \text{flux tensor} \end{matrix}$$

Note: • pressure gradient and external forces act as source (or sink) terms

- force due to pressure gradient results from exchange of energy between bulk flow and peculiar motions

③ From 2nd-moment of Boltzmann eqn:
 (Exercise):

$$\frac{\partial}{\partial t} \left[S \left(\frac{v^2}{2} + \epsilon \right) \right] + \frac{\partial}{\partial x_i} \left[S v_i \left(\frac{v^2}{2} + \epsilon \right) \right] = - \frac{\partial h_i}{\partial x_i} - \frac{\partial}{\partial x_i} (P v_i) \\ + S v_i F_i$$

where $h_i = \int \frac{m}{2} \tilde{u}_i \tilde{u}^2 f d\tilde{u}$ conduction heat flux

If \vec{h} can be neglected (typical for astrophys. systems):

$$\rightsquigarrow \boxed{\frac{\partial E}{\partial t} + \frac{\partial}{\partial x_i} [(E+P)v_i] = S v_i F_i}$$

total
energy
equation

$$E \equiv \frac{1}{2} S v^2 + S \epsilon$$

total
energy
density

Remarks: 1) ①, ②, ③ are known as the Euler equations. They can be rewritten as a system of conservation laws:

$$\boxed{\begin{aligned} u_t + f^i(u)_{x_i} &= S \\ \partial_t u + \frac{\partial}{\partial x_i} f^i(u) &= S \end{aligned}}$$

where

$$u = \begin{pmatrix} s \\ s \vec{v} \\ E \end{pmatrix} \quad \text{"conserved variables"}$$

$$f^i = \begin{pmatrix} s v^i \\ s v^i v^j + \delta_{ij} p \\ v^i (E + p) \end{pmatrix} \quad \begin{array}{l} j = 1, 2, 3 \\ (\text{momentum components}) \end{array} \quad \text{"fluxes"}$$

$$S = \begin{pmatrix} 0 \\ s \vec{F} \\ s \vec{J} \cdot \vec{F} \end{pmatrix} \quad \begin{array}{l} i = 1, 2, 3 \\ (\text{flux directions}) \end{array} \quad \text{"sources"}$$

2) Equation of state: The Euler eqns. are five equations for six unknowns $s, \{v^i\}, P, e = sE$

and require relation $P = P(s, e)$ to close the system \rightarrow "equation of state"

Ideal gas: $p = (\gamma - 1)e = (\gamma - 1) \beta E$
 with $\gamma = \frac{c_p}{c_v}$ the ratio of specific heats
 (adiabatic constant)

In general: $p = p(S, e, X_i, \dots)$ can be very
 complicated (\rightarrow different chemical
 elements, ionization states, compl.
 reactions etc.)

Exercise: Show strict hyperbolicity of the Euler equations.

3) Validity of continuous medium approximation
 require (see above):

$$(i) \quad \lambda \ll dx \ll l_{sys} \quad \begin{matrix} \text{mean free path of particle} \\ \uparrow \end{matrix} \quad \begin{matrix} \text{finite size element of medium} \\ \uparrow \end{matrix} \quad \begin{matrix} \text{characteristic size} \\ \text{of physical system} \end{matrix}$$

f should not vary over dx & dN
 should be large enough for averaging
 to be meaningful

(ii) interparticle forces must be short-range
 i.e. on distances $l_{force} \ll dx$, otherwise

energy & momentum exchanged with
fluid elements far away

example for long-range: external grav.
field
→ external force

Note: self-gravity cannot be obtained
from Boltzmann eqn due to
long-range nature
→ require additional Poisson eqn.

- (iii) peculiar motion close to boundary of
element $d\mathbf{x}$ carries particles into
adjacent elements with different $s(\vec{r})$, $\mathbf{v}(\vec{r})$,
 $T(\vec{r})$ and "diffusion"
and friction forces appear \Rightarrow
microscopic exchange of
momentum & energy
neglected in Euler equation
→ need to take conduction heat flux
 \vec{h} and other terms into account
(see below)