

## Determinant

Let  $A$  be an  $n \times n$  matrix ( $A = (a_{ij})_{ij}$ )

$$\text{Definition: } \det(A) = a_{11} \det A_{11} - a_{12} \det A_{12} + \dots + (-1)^{1+n} \det A_{1n}$$

$A_{ij}$  : obtained by deleting row  $i$  and column  $j$  of the matrix  $A$ .

Cofactors of  $A$  :

$$C_{ij} = \underbrace{(-1)^{i+j}} \det A_{ij}$$

Cofactor expansion across row  $i$

$$\det(A) = a_{11} C_{11} + a_{12} C_{12} + \dots + a_{1n} C_{1n}$$

Cofactor expansion down column  $j$

$$\det(A) = a_{1j} C_{1j} + a_{2j} C_{2j} + \dots + a_{nj} C_{nj}$$

$$\implies \det(A) = \det(A^T)$$

## Properties

• If  $A \xrightarrow{R_i \rightarrow R_i + cR_j} B$ ,  $\det(A) = \det(B)$

• If  $A \xrightarrow{R_i \leftrightarrow R_j} B$ ,  $-\det(A) = \det(B)$

• If  $A \xrightarrow{cR_i} B$ ,  $c \det(A) = \det(B)$

• If  $A \xrightarrow{\text{REF}} U$  : no use of row scaling

$$\det(A) = (-1)^r \det(U)$$

$r$ : # of row interchanging

$U$ : in REF (triangular matrix)  $\det(U) = \text{product of the main diagonal entries of } U$

•  $\det(AB) = \det(A) \det(B) = \det(B) \det(A) = \det(BA)$  ( $AB \neq BA$ )

•  $A^{-1}$  exists ( $\det(A) \neq 0$ )

$$\det(AA^{-1}) = \det(I_n) = 1$$

$$\det(A) \det(A^{-1}) = 1 \implies \det(A^{-1}) = \frac{1}{\det(A)}$$

Inverse formula:

If  $\det(A) \neq 0$

$$A^{-1} = \frac{1}{\det A} \text{Adj } A$$

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$$\text{Adj } A = \begin{bmatrix} C_{11} & C_{21} & \cdots & C_{n1} \\ C_{12} & C_{22} & \cdots & C_{n2} \\ \vdots & & & \\ C_{1n} & C_{2n} & \cdots & C_{nn} \end{bmatrix}$$

Vector spaces

$(V, +, \cdot)$  a vector space

- A subset  $H$  of  $V$  is a subspace of  $V$  if
  - $\vec{0}$  is in  $H$
  - If  $\vec{u}$  and  $\vec{v}$  are in  $H$ , then  $\vec{u} + \vec{v}$  is in  $H$
  - If  $\vec{u}$  is in  $H$  and  $c$  is in  $\mathbb{R}$ , then  $c\vec{u}$  is in  $H$
- Any subset  $W = \text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p)$  where  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are in  $V$ , is a subspace of  $V$ .
- Let  $A$  be an  $m \times n$  matrix. ( $A = [\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n]$ )
  $\text{Nul}(A) = \left\{ \vec{x} \text{ in } \mathbb{R}^n \mid A\vec{x} = \vec{0} \right\}$  is a subspace of  $\mathbb{R}^n$ .

$\text{Col}(A) = \text{Span}(\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n)$  is a subspace of  $\mathbb{R}^m$ .

$\text{Row}(A) = \text{Span}(\text{rows of } A)$  is a subspace of  $\mathbb{R}^n$ .

- $T: \mathbb{R}^n \longrightarrow \mathbb{R}^m$  a linear transformation with standard matrix  $A$ 

$$(T(\vec{x}) = A\vec{x})$$

$$\text{Ker}(T) = \left\{ \vec{x} \text{ in } \mathbb{R}^n \mid T(\vec{x}) = \vec{0} \right\}$$

$$T(\vec{x}) = A\vec{x}$$

$$= \left\{ \vec{x} \text{ in } \mathbb{R}^n \mid A\vec{x} = \vec{0} \right\} = \text{Nul}(A)$$

$$\text{Im}(T) = \left\{ T(\vec{x}) \mid \vec{x} \text{ in } \mathbb{R}^n \right\} = \text{Col}(A)$$

Bases

$V$  a vector space

- A basis for  $V$  is a **spanning set** of  $V$  which is **linearly independent**.

- If  $\vec{X} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_p \vec{v}_p$  is the parametric vector form of the solution of  $A\vec{x} = \vec{0}$

$\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$  is a basis for  $\text{Null}(A)$ .

- The pivot columns of  $A$  form a basis for  $\text{Col}(A)$
- The non-zero rows of ~~an~~ REF of  $A$  form a basis for  $\text{Row}(A)$

### Spanning set Theorem

$V$  is a vector space and  $H$  a subspace of  $V$

$$H = \text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p)$$

If  $\vec{v}_i = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_{i-1} \vec{v}_{i-1} + c_{i+1} \vec{v}_{i+1} + \dots + c_p \vec{v}_p$ , then

$$H = \text{Span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_p)$$

### Coordinate systems

Let  $B = \{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_n\}$  be a basis for  $V$ . For any  $\vec{u}$  in  $V$ , there exists a unique set of scalars  $c_1, c_2, \dots, c_n$  such that

$$\vec{u} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + \dots + c_n \vec{b}_n$$

$$[\vec{u}]_B = \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} \leftarrow B\text{-coordinate vector of } \vec{u}.$$

### Change of basis

Let  $G = \{\vec{g}_1, \vec{g}_2, \dots, \vec{g}_n\}$  be another basis for  $V$ .

The change-of-coordinates matrix from  $B$  to  $G$  is

$$P_{G \leftarrow B} = [\vec{b}_1]_G \quad [\vec{b}_2]_G \quad \dots \quad [\vec{b}_n]_G$$

$$[\vec{u}]_G = \underbrace{P_{G \leftarrow B}}_{\text{change-of-coordinates matrix}} [\vec{u}]_B$$

$$P_{B \leftarrow G} = [\vec{g}_1]_B \quad [\vec{g}_2]_B \quad \dots \quad [\vec{g}_n]_B$$

$$[\vec{u}]_B = P_{B \leftarrow G} [\vec{u}]_G$$

$$(P_{\mathcal{E} \hookrightarrow \mathcal{B}})^{-1} = P_{\mathcal{B} \hookrightarrow \mathcal{E}}$$

- $\dim(V) = \#$  vectors in a basis for  $V$ .

$$\dim(\text{Nul}(A)) = \# \text{ free variables in } A\vec{x} = \vec{0}$$

- (C)  $\dim(\text{Col}(A)) = \# \text{ pivot columns of } A$
- $\dim(\text{Row}(A)) = \# \text{ pivots in } A$

- Let  $A$  be an  $m \times n$  matrix

$$\text{rank}(A) = \dim(\text{Col}(A)) = \dim(\text{Row}(A))$$

$$\text{Row}(A) = \text{Col}(A^T)$$

$$\dim(\text{Col}(A^T)) = \dim(\text{Row}(A)) = \text{rank}(A)$$

$$\text{rank}(A^T) \quad (\text{rank}(A^T) = \text{rank}(A))$$

- $\text{rank}(A) + \dim(\text{Nul}(A)) = n = \# \text{ columns of } A$

- $\text{rank}(A) \leq \min(m, n)$ .