

Struct-net-align

currently a very rough incoherent and partially incorrect sketch

Introduction

Using structure to improve a noisy PPI network.

Algorithm

Definitions

Let $G = (V, Int(G) \cup Hom(G))$ be a network whose vertices represent domains.

Let $Int(G)$ is a set of edges indicating interactions.

Let $Int(v)$ for any vertex $v \in Int(G)$ is the set of edges in $Int(G)$ that are incident to v . Also define $Hom(v)$ in the same way.

$Hom(G)$ is a set of edges indicating homology (similarity) between vertices.

An edge $e \in Int(G)$ is associated with a probability $Prob(e)$.

An edge $(a, b) \in Hom(G)$ is associated with a score denoted $s((a, b))$ ranging from 0 to ∞ . Any edge with score $s \geq 1$ is defined as significant.

Let $\rho(a, b)$ denote the score of the most specific homology relation r identified between nodes a and b . For example, if a and b are from the same SCOP fold but not the same SCOP superfamily, $\rho(a, b)$ will be given by this relation.

Let $\alpha(a, b)$ denote the weighted score of an alignment that has been performed between vertices a and b .

Let $\iota(v)$ denote the number of edges (v, v') in $Int(G)$, $\forall v \in V$, and let $\eta(v)$ denote the number of edges (v, v') in $Hom(G)$, $\forall v \in V$.

Let $\iota^* = \max_{v \in V} \{\iota(v)\}$, $\eta^* = \max_{v \in V} \{\eta(v)\}$.

Overview

The algorithm consists of three major steps.

Given an interaction network $G = (V, Int(G))$, build a network $G' = (V, Int(G') \cup Hom(G'))$ by using any available information (e.g. homology databases or alignment) to add edges to $Hom(G')$ and to increase the weights of those edges. At the end of this process, remove any edge from $Hom(G')$ with weight less than 1.

Second, generate a network $G'' = (V, Int(G''))$ by using edges in $Hom(G')$ to update edge weights (probabilities) in $Int(G)$.

Third, define an equivalence relation between vertices, H , such that $H(u) \equiv H(v)$ iff v is reachable from u by traversing $Hom(G')$. Generate a network $G''' = (V', Int(G''') \cup Hom(G'''))$ by merging nodes contained in cliques of $(V, Hom(G'))$ in which every vertex in the clique is associated with the same set of interaction edges in $(V, Int(G''))$, with respect to the equivalence relation H .

Algorithm

1. Parse network.
2. For every pair of vertices (a, b) , add an edge (a, b) to $Hom(G)$, with label $\rho(a, b)$.
3. For every pair of vertices (a, b) (optionally: not joined by an edge in $Hom(G)$), align a against b and add an edge to $Hom(G)$, with label $\alpha(a, b)$.
4. For every edge $e \in G$ such that $s(e) < 1$, remove e .
5. For every edge $(u, v) \in Int(G)$:
 - (a) Let $P = 0$ and $I = \emptyset$, and let $X_a = Y_a = 0 \forall a \in V$.

- (b) Run DFS on $(V, Hom(G))$ from u and v concurrently to generate vertex labellings X and Y , respectively. During traversal, when an already-traversed vertex o is encountered, visit o but don't traverse further.
- (c) For both $Q = X$ and $Q = Y$, when visiting a vertex b via edge e :
 - i. If $Q_b = 0$, let $Q_b := 1$.
 - ii. Let $P := P + \log S(e)$.
 - iii. Let $Q_b := Q_b - \exp(P)$.
- (d) For every edge $(x, y) \in Int(G)$ such that $X_x \neq 0$ and $Y_y \neq 0$, let $Prob((u, v)) := Prob((u, v)) + X_x Y_y Prob((x, y))$.
6. Discard every vertex v such that $\iota(v) = 0$ and remove every edge incident to v .
7. Run Bron–Kerbosch's algorithm on G_i to enumerate all maximal cliques $C = \{c_1 \dots c_x\}$, for clique sizes $\gamma(C_j) > 1 \forall j$.
8. Partition C into sets $D = d_1 \dots d_z$ such that $\forall v \in d_i, u \in d_j, Int(v) \neq Int(u), \forall i, j$, and $Int_H(v) = Int_H(u) \forall u, v \in d_i \forall i$.
9. For each $d \in D$, merge by edge contraction every vertex in d , modifying the reference graph G .
10. Output the network $(V, Int(G))$.

Defining homology by relations

Defining homology by alignment

Using homology to score interactions

$$\text{Define } R_{i,j}^{(u,v)} = \begin{cases} 0 & i = 0 \vee j = 0 \\ Q^{(u,v)}(v_i)Q^{(u,v)}(v_j)Prob(v_i, v_j) - \sum_{k < i \vee k < j} R_{i,j} & \text{otherwise} \end{cases}$$

$$\text{Define } Q_v(i)^{(u,v)} = \begin{cases} 0 & v = 0 \\ 1 - \prod_{j < i} Q_v^{(u,v)}(j) - S(\pi^{(i)}) & \exists \pi^{(i)} = u, e_1, v_1, e_2, v_2 \dots, e_k, v_k, v \\ 0 & \text{otherwise} \end{cases}$$

Then we update the probability of an interaction (u, v) with:

$$Prob((u, v))' = Prob((u, v)) + \sum_{i,j} R_{i,j}^{(u,v)}$$

Merging equivalent domains

To merge, we require:

1. Two subgraphs G_1, G_2 of G'' with edges in $Int(G')$
2. $\exists H \subseteq Hom(G)$ s.t. H defines an isomorphism between G_1 and G_2 (TODO: rigor).

Unfortunately, MAX-CLIQUE is NP-HARD. However, we can bound the time-complexity of a naive algorithm (such as Bron–Kerbosch) in terms of the maximum number of homology edges of any vertex in G . Let γ be the maximal clique size in $Hom(G)$. Then $\gamma^* \leq \eta^*$.

We can readily solve MAX-CLIQUE(G) in $\mathcal{O}(|V|^{\eta^*}(\eta^*)^3)$ time by enumerating all $|V|^\gamma$ subgraphs of size γ for every $\gamma = 1, 2, \dots, \eta^*$.

Note that a subset of $Hom(G'')$ nearly defines an isomorphism between two subgraphs of $(V', Int(G''))$. For a pair (u, v) where $(u, v) \in Hom(G')$, $Int(u)$ may not exactly equal $Int(v)$, but $Int(u)/H = Int(v)/H$, where $Int(u)/H$ is some kind of factor graph in the algebraic sense that I'll need to define (look up factor group or quotient ring).

Once we have a (maximal) clique C , we need to find which vertices in C share interactions. This results in a partitioning of C into disjoint subgraphs D . We can then merge every vertex in each D_i by edge contraction.

Extending to PPIs

Initial scoring of interactions

Implementation

Results

Overview

Accuracy

Speed

Appendix 1. Formal proofs