

Electricity & Magnetism

practice session

§1 - Lorentz law

§2 - Biot-Savart law: \vec{B}

§3 - Ampere's law

§4 - Magnetization: \vec{m} , \vec{M} , \vec{A} , \vec{H}

§5 - Linear magnetics: \vec{B}_m

§1 $\vec{F} = q \vec{v} \times \vec{B}$

\vec{B} uniform $\vec{v} \perp \vec{B}$

$F = qvB$

$\frac{mv^2}{R} = qvB$

$mv = qBR$

$F = ma_c = m \frac{v^2}{R}$

generalizing to current $\vec{I} = \vec{v} \lambda$

wire: $\vec{F} = \int_{\text{wire}} I d\vec{l} \times \vec{B}$

surface current \vec{K} : $\vec{F} = \int_{\text{surface of wire}} (\vec{K} \times \vec{B}) da$

volume current: $\vec{F} = \int_{\text{volume of wire}} (\vec{J} \times \vec{B}) dv$

§2 magnetic field from wire of time-independent current is given by

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} \times \hat{r}}{r^2} dl'$$

$$= \frac{\mu_0}{4\pi} I \int \frac{d\vec{l}' \times \hat{r}}{r^2}$$

const

$$d\vec{l}' \times \hat{r} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ dx & 0 & 0 \\ -x & 0 & s \end{vmatrix} = -\hat{y} \frac{s dx}{r^2}$$

$$\vec{B} = \frac{\mu_0}{4\pi} I \hat{y} \int \frac{dx}{s^2}$$

$$= (-\hat{y}) \frac{\mu_0 I}{4\pi} \int \frac{dx}{(x^2 + s^2)^{3/2}}$$

$x = s \tan \theta$ sub

§3 Ampere's law

wire (infinite wire) \vec{I} loop around wire

$$\oint \vec{B} \cdot d\vec{l} = \oint \frac{\mu_0 I}{2\pi s} dl$$

$$= \frac{\mu_0 I}{2\pi s} \oint dl$$

$$= \mu_0 I$$

By principle of superposition,

$$\oint_{\text{any smooth loop}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}}$$

$$\Leftrightarrow \nabla \times \vec{B} = \mu_0 \vec{J}$$

Ex: wire 

$\oint \vec{B} \cdot d\vec{l} =$ by symmetry $\left\{ \begin{array}{l} \vec{B} = \text{const} \\ \text{direction along loop} \end{array} \right.$ on the loop

$= B \cdot 2\pi S$ length of loop

By Ampere's law: $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} = I$

$\Rightarrow B 2\pi S = \mu_0 I$

$B = \frac{\mu_0 I}{2\pi S}$

Thm (Helmholtz) any vector field \vec{B}

as $\vec{B} = -\vec{\nabla} \mathcal{U} + \vec{\nabla} \times \vec{A}$

$\mathcal{U}(\vec{r}) = \frac{1}{4\pi} \int \frac{\vec{\nabla} \cdot \vec{B}}{r} d\vec{r}'$ scalar $\mathbb{R}^3 \rightarrow \mathbb{R}$

$\vec{A}(\vec{r}) = \frac{1}{4\pi} \int \frac{\vec{\nabla} \times \vec{B}}{r} d\vec{r}'$ vector field $\mathbb{R}^3 \rightarrow \mathbb{R}^3$

\Rightarrow (Helmholtz \mathcal{U}^m): \mathcal{U} of magnetic field \vec{B} is zero $\Rightarrow \vec{B} = \vec{\nabla} \times \vec{A}$

$\vec{A} = \frac{1}{4\pi} \int \frac{\vec{\nabla} \times \vec{B}}{r} d\vec{r}' = \frac{1}{4\pi} \int \frac{\mu_0 \vec{J}(\vec{r}')}{r} d\vec{r}'$

$= \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{r} d\vec{r}'$

Typically easier to compute than \vec{B} .

$\vec{B}_f = \vec{M} \times \hat{n}$

$\vec{J}_f = \vec{\nabla} \times \vec{M}$

given \vec{M} , find \vec{B}_f

\Rightarrow compute $\vec{A} \Rightarrow \vec{B}$

(S4) Magnetization

expand \vec{A} in $\frac{1}{r}$ with fixed \vec{r}

$\Rightarrow \vec{A}_{\text{dip}}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^2}$, $\vec{m} = I \int d\vec{a}$ surface enclosing I

\Rightarrow for a $\vec{N} = \vec{m} \times \vec{B}$

force $\vec{F} = \vec{\nabla}(\vec{m} \cdot \vec{B})$

By principle of superposition, volume \mathcal{V} of \vec{m} per volume we call $\vec{M} \leftarrow$ magnetization

$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{M}(\vec{r}') \times \vec{r}}{r^2} d\vec{r}'$

$= \frac{\mu_0}{4\pi} \int \frac{1}{r^2} \vec{\nabla} \times \vec{M}(\vec{r}') d\vec{r}'$

$+ \frac{\mu_0}{4\pi} \oint \frac{1}{r} \vec{M} \times \hat{n} da'$

$= \frac{\mu_0}{4\pi} \int \vec{J}_f d\vec{r}' + \frac{\mu_0}{4\pi} \oint \vec{J}_s d\vec{a}'$

(S5) special case of \vec{B}_{free} causing \vec{M}

$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_{\text{total}} = \mu_0 (\vec{J}_f + \vec{J}_b)$

$\frac{1}{\mu_0} \vec{\nabla} \times \vec{B} = \vec{J}_f + \vec{\nabla} \times \vec{M}$

$\vec{\nabla} \times (\frac{1}{\mu_0} \vec{B} - \vec{M}) = \vec{J}_f$

$= \vec{H}$ auxiliary field

$\vec{\nabla} \times \vec{H} = \vec{J}_f$

$\Leftrightarrow \oint \vec{H} \cdot d\vec{l} = I_f^{\text{enc}}$

if we know config of wires & currents we can find \vec{H}

Special case: $\vec{M} \propto \vec{H}$, $\vec{M} = \chi_m \vec{H}$

$\frac{1}{\mu_0} \vec{B} - \vec{M} = \vec{H}$

$\vec{B} = \mu_0 (\vec{H} + \vec{M}) = \mu_0 (\vec{H} + \chi_m \vec{H}) = \mu_0 (1 + \chi_m) \vec{H}$

$\vec{B} = \mu \vec{H}$ linear

Problem (linear)

1. given wire/current distrib \Rightarrow compute \vec{H}

2. $\vec{B} = \mu \vec{H}$

Problem: given $\vec{M} \Rightarrow$ compute \vec{J}_f, \vec{B}

$\Rightarrow \vec{A} \Rightarrow \vec{B}$