# Lauritzen: Undergraduate Convexity

## Danny Nygård Hansen

## 20th December 2023

 $A \downarrow B$ 

## 2 • Affine subspaces

General notes

REMARK 2.1. Let  $f: \mathbb{R}^d \to \mathbb{R}^m$  be a map. Then the following properties are equivalent:

- (a) There exists a matrix A and a vector b such that f(x) = Ax + b for all  $x \in \mathbb{R}^d$ .
- (b) For all  $x, y \in \mathbb{R}^d$  and  $t \in \mathbb{R}$ , f((1-t)x + ty) = (1-t)f(x) + tf(y).
- (c) For all  $x_1, ..., x_k \in \mathbb{R}^d$  and  $t_1, ..., t_k \in \mathbb{R}$  with  $t_1 + \cdots + t_k = 1$ ,  $f(t_1 x_1 + \cdots + t_k x_k) = t_1 f(x_1) + \cdots + t_k f(x_k)$ .

Such a function is called *affine*. Note that if m = 1, then f is affine if and only if it is both convex and concave.

The first property clearly entails the third, which then entails the second, so assume that f has the second property. First assume that f(0) = 0. For  $\beta \in \mathbb{R}$  and  $x \in \mathbb{R}^d$  be thus have

$$f(\beta x) = f(\beta x + (1 - \beta)0) = \beta f(x) + (1 - \beta)f(0) = \beta f(x),$$

so f is homogeneous. If also  $y \in \mathbb{R}^d$ , then

$$\frac{1}{2}f(x+y) = f\left(\frac{1}{2}x + \frac{1}{2}y\right) = \frac{1}{2}f(x) + \frac{1}{2}f(y),$$

so f is also additive, hence linear. For general f, simply replace f with f - f(0).

REMARK 2.2. Let  $M \subseteq \mathbb{R}^d$  be nonempty. Then the following properties are equivalent:

- (a) For all  $x, y \in M$  and  $t \in \mathbb{R}$ ,  $(1 t)x + ty \in M$ .
- (b) For all  $x_1, ..., x_k \in \mathbb{R}^d$  and  $t_1, ..., t_k \in \mathbb{R}$  with  $t_1 + \cdots + t_k = 1$ ,  $t_1 x_1 + \cdots + t_k x_k \in M$ .
- (c) There is a linear subspace  $W \subseteq \mathbb{R}^d$  and an element  $x_0 \in M$  such that  $M = x_0 + W$ . In this case  $W = \{x y \mid x, y \in M\}$ , and the identity  $M = x_0 + W$  holds for all  $x_0 \in M$ .
- (d) There is an  $m \times d$  matrix A and a vector b such that  $M = \{x \in \mathbb{R}^d \mid Ax = b\}$ .
- (e) There is an affine map  $f: \mathbb{R}^d \to \mathbb{R}^m$  such that  $M = \{x \in \mathbb{R}^d \mid f(x) = 0\}$ .

If *M* has any of these properties, then *M* is called *affine*.

Clearly (b) implies (a), and the converse follows by noticing that when k > 1 at least one  $t_1$  must be different from 1, say  $t_k$ , so

$$t_1x_1 + \dots + t_kx_k = (1 - t_k)\left(\frac{t_1}{1 - t_k}x_1 + \dots + \frac{t_{k-1}}{1 - t_k}x_{k-1}\right) + t_kx_k.$$

Hence (b) follows by induction. Assuming (b), let  $W = \{x - y \mid x, y \in M\}$ , and consider  $x_1, x_2, y_1, y_2 \in M$  and  $\beta \in \mathbb{R}$ . Then

$$\beta(x_1 - y_1) + (x_2 - y_2) = (\beta x_1 + x_2 + (-\beta)y_1) - y_2 \in W$$
,

so W is a subspace. For any  $x_0, x, y \in M$  and we have  $x_0 + (x - y) \in M$ , and conversely  $x = x_0 + (x - x_0) \in x_0 + W$ , so  $M = x_0 + W$ . If W' is another subspace such that  $M = x_0 + W'$  for some  $x_0$ , then  $W' = M - x_0 = W$ .

If instead (c) holds, and  $x, y \in M$  and  $t \in \mathbb{R}$ , then  $x = x_0 + x'$  and  $y = x_0 + y'$  for some  $x', y' \in W$ , and so

$$(1-t)x + ty = x_0 + (1-t)x' + ty' \in x_0 + W$$

implying (a).

The equivalence between (c), (d) and (e) is obvious since W is the nullspace of some matrix, and we may choose any  $x_0$  such that  $Ax_0 = b$ . (Furthermore, (e) easily implies (b).)

REMARK 2.3. Let  $f: \mathbb{R}^d \to \mathbb{R}^m$  be affine, and let  $M \subseteq \mathbb{R}^d$  be affine. Then the image f[M] is also affine. Furthermore, for any  $S \subseteq \mathbb{R}^d$  we have f[aff S] = aff f[S] (just as linear maps commute with span).

If f(x) = Ax + b and  $M = x_0 + W$  is affine with W a subspace, then

$$f[M] = f[x_0 + W] = A[x_0 + W] + b = (Ax_0 + b) + A[W].$$

In particular, dim  $f[M] = \dim A[W]$ . If f (and hence A) is invertible, then we thus have dim  $f[M] = \dim W = \dim M$ .

2. Affine subspaces

3

REMARK 2.4. If  $S \subseteq \mathbb{R}^d$  and  $x_0 \in S$ , then we claim that aff  $S = x_0 + \operatorname{span}(S - x_0)$ . Consider the affine map  $f(x) = x - x_0$ . From the above remark we have

$$x_0 + \operatorname{aff} f[S] = x_0 + f[\operatorname{aff} S] = \operatorname{aff} S.$$

But f[S] contains 0, so aff f[S] is a subspace and hence equal to span f[S]. Furthermore, since f is invertible it preserves dimensions, so if |S| = m and is positive and finite, then dim S = m - 1 if and only if dim W = m - 1, where  $W = \operatorname{span}(S - x_0)$ . But W is also spanned by  $S \setminus \{x_0\} - x_0$  which has m - 1 elements, so S is affinely independent if and only if  $S \setminus \{x_0\} - x_0$  is linearly independent.

REMARK 2.5. If  $f: \mathbb{R}^d \to \mathbb{R}^d$  preserves the Euclidean metric, then it is affine. Replacing f with f - f(0) we may assume that f(0) = 0, and so that f also preserves the inner product. For all  $x, y, z \in \mathbb{R}^d$  and  $\beta \in \mathbb{R}$  we have

$$\langle f(\beta x + y), f(z) \rangle = \langle \beta x + y, z \rangle$$

$$= \beta \langle x, z \rangle + \langle y, z \rangle$$

$$= \beta \langle f(x), f(z) \rangle + \langle f(y), f(z) \rangle$$

$$= \langle \beta f(x) + f(y), f(z) \rangle.$$

Since *f* is surjective, the claim follows.

#### REMARK 2.6: The affine hull and dimension of the empty set.

By definition, the affine hull of the empty set is the empty set. This is the case by Definition 2.4, and this is also the standard definition. Hence the affine hull of the empty set is not an affine subspace! In particular, it cannot have a dimension in the sense of Definition 2.7.

Exercises

## EXERCISE 2.10

Prove that you can have no more than d+1 affinely independent vectors in  $\mathbb{R}^d$ .

SOLUTION. Let  $\{v_1, \dots, v_n\} \subseteq \mathbb{R}^d$  be affinely independent. By Proposition 2.9, the n-1 vectors  $v_2-v_1, \dots, v_n-v_1$  vectors are linearly independent. But then we must have  $n-1 \le d$ , i.e.  $n \le d+1$ .

#### EXERCISE 2.11

Let  $v_0, \ldots, v_d$  be affinely independent points in  $\mathbb{R}^d$ . Prove that

$$f(x) = (\lambda_0, \lambda_1, \dots, \lambda_d)$$

is a well defined affine map  $f: \mathbb{R}^d \to \mathbb{R}^{d+1}$ , where

$$x = \lambda_0 v_0 + \dots + \lambda_d v_d$$

with  $\lambda_0 + \cdots + \lambda_d = 1$ .

SOLUTION. If also  $x = \mu_0 v_0 + \cdots + \mu_d v_d$  with  $\mu_0 + \cdots + \mu_d = 1$ , then

$$(\lambda_0 - \mu_0)v_0 + \cdots + (\lambda_d - \mu_d)v_d = 0$$
,

so since the  $v_i$  are affinely independent we have  $\lambda_i = \mu_i$  by Proposition 2.9. Hence f is well-defined.

Next we show that f is affine. Let

$$x = \lambda_0 v_0 + \dots + \lambda_d v_d$$
 and  $y = \mu_0 v_0 + \dots + \mu_d v_d$ 

with  $\lambda_0 + \cdots + \lambda_d = 1$  and  $\mu_0 + \cdots + \mu_d = 1$ , and let  $t \in \mathbb{R}$ . Then

$$\sum_{i=0}^{d} \left( (1-t)\lambda_i + t\mu_i \right) = (1-t)\sum_{i=0}^{d} \lambda_i + t\sum_{i=0}^{d} \mu_i = (1-t) + t = 1.$$

Therefore, since

$$(1-t)x + ty = \sum_{i=0}^{d} ((1-t)\lambda_i + t\mu_i)v_i,$$

we have

$$f((1-t)x + ty) = ((1-t)\lambda_0 + t\mu_0, ..., (1-t)\lambda_d + t\mu_d)$$
  
=  $(1-t)(\lambda_0, ..., \lambda_d) + t(\mu_0, ..., \mu_d)$   
=  $(1-t)f(x) + tf(y),$ 

so *f* is affine.

## EXERCISE 2.12

Prove that a non-empty open subset  $U \subseteq \mathbb{R}^d$  has dimension dim U = d. Show that a subset  $S \subseteq \mathbb{R}^d$  with dim S = d contains a non-empty open subset.

SOLUTION. Let  $x \in U$ , and let  $(e_1, ..., e_d)$  be the standard basis for  $\mathbb{R}^d$ . Since U is open there is some  $\delta > 0$  such that  $x + \delta e_i \in U$  for all i. The linear subspace  $-x + \operatorname{aff} U$  has dimension d, so U has dimension d.

The latter claim is in fact false, since if S is e.g. the collection of points  $\delta e_i$  along with the origin, then S has dimension d (since aff S contains each of the coordinate axes, hence the entire  $\mathbb{R}^d$ ) but clearly contains no non-empty open subset.

3. Convex subsets 5

## 3 • Convex subsets

**Exercises** 

#### EXERCISE 3.7

We state and prove a more general result that the one given in the exercise. For any subsets  $A, B \subseteq \mathbb{R}^d$  we have

$$conv(A + B) = conv A + conv B$$
.

SOLUTION. The inclusion ' $\subseteq$ ' is clear since the sum of convex sets is convex. For the converse direction, let  $v \in \text{conv} A$  and  $w \in \text{conv} B$ , and write  $v = \sum_{i=1}^{n} \lambda_i v_i$  and  $w = \sum_{j=1}^{m} \mu_j w_j$  as convex combinations of elements in A and B respectively. Then

$$v + w_j = v + (\lambda_1 + \dots + \lambda_n)w_j = \sum_{i=1}^n \lambda_i(v_i + w_j) \in \text{conv}(A + B),$$

and

$$v + w = (\mu_1 + \dots + \mu_n)v + w = \sum_{j=1}^{m} \mu_j(v + w_j) \in \text{conv} \operatorname{conv}(A + B) = \operatorname{conv}(A + B),$$

as desired.

#### EXERCISE 3.9

We state and prove a more general result that the one given in the exercise. For  $S \subseteq \mathbb{R}^d$ , prove that  $(\operatorname{conv} S)^\circ = S^\circ$ . If  $S = \{v_1, \dots, v_n\}$  is finite, then

$$(\operatorname{conv} S)^{\circ} = \{ \alpha \in \mathbb{R}^d \mid \alpha^{\top} v_1 \le 1, \dots, \alpha^{\top} v_n \le 1 \} = \{ \alpha \in \mathbb{R}^d \mid A\alpha \le 1 \},$$

where *A* is the  $n \times d$  matrix with rows  $v_1^\top, \dots, v_n^\top$ . In particular, polytopes are polyhedra.

SOLUTION. Since  $S \subseteq \text{conv } S$ , we clearly have  $(\text{conv } S)^{\circ} \subseteq S^{\circ}$ . For the opposite inclusion, let  $\alpha \in S^{\circ}$  and let  $\lambda_1 v_1 + \cdots + \lambda_n v_n$  be a convex combination of elements in S. Then

$$\alpha^\top (\lambda_1 v_1 + \dots + \lambda_n v_n) = \lambda_1 \alpha^\top v_1 + \dots + \lambda_n \alpha^\top v_n \leq \lambda_1 + \dots + \lambda_n = 1,$$

so  $\alpha \in (\text{conv } S)^{\circ}$ . The rest of the claims follow easily.

3. Convex subsets 6

#### EXERCISE 3.10

If  $F \subseteq G \subseteq C$  are convex subsets of  $\mathbb{R}^d$ , prove that F is a face of C if F is a face of G and G is a face of C.

SOLUTION. Let  $x, y \in C$  such that the open line segment (x, y) intersects F. Then it intersects G, so since G is a face of C we have  $x, y \in G$ . Similarly, since F is a face of G we then have  $x, y \in F$ . Hence F is a face of G.

## EXERCISE 3.12

Prove that  $C \setminus F$  is a convex subset if F is a face of a convex subset C. Is it true that  $F \subseteq C$  is a face if  $C \setminus F$  is a convex subset?

SOLUTION. Let  $x, y \in C \setminus F$ . If the open line segment (x, y) intersected F, then we would have  $x, y \in F$  since F is a face of C. Thus  $(x, y) \subseteq C \setminus F$ , so in total  $[x, y] \subseteq C \setminus F$ . Hence  $C \setminus F$  is convex.

The converse is false. For instance, remove (at least) two extreme points from a disk.  $\Box$