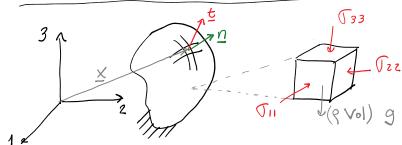
General Solution Cont Mech

General solution to a continuum mechanics problem



$$\begin{cases} \nabla \cdot \underline{\nabla} + \underline{f} = P \underline{\alpha} & \rightarrow \text{Equilibrium (Cauchy's)} \\ \underline{\mathcal{E}} = F_1(\underline{U}) & \rightarrow \text{Kinematic eq } \int_0^1 s mall st \\ \underline{\nabla} = F_2(\underline{\mathcal{E}}) & \rightarrow \text{Constitutive equations} \end{cases}$$

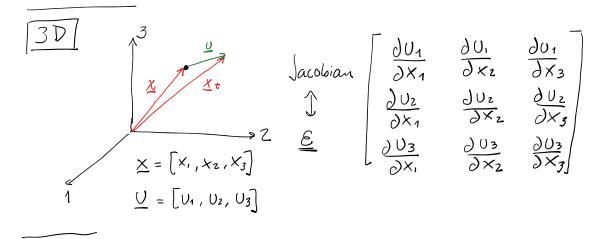
$$\nabla \cdot \left[F_{2}(\underline{\epsilon})\right] + \underline{f} = \underline{Q}$$

$$\nabla \cdot \left[F_{2}(\underline{\epsilon})\right] + \underline{f} = \underline{Q}$$

$$- \underline{displacement} \quad \underline{U} \rightarrow \underline{\varepsilon} \rightarrow \underline{C}$$

Kinematic Equations (small strains) [= F1 (U)

$$\mathcal{E} = \frac{dx_{\xi} - dx}{dx} = \frac{\left[x + y + dx + dy - (x + y)\right] - \left[x + dx - x\right]}{\left[x + dx - x\right]}$$



$$\begin{bmatrix}
\frac{\partial U_1}{\partial x_4} & \frac{\partial U_1}{\partial x_2} & \frac{\partial U_2}{\partial x_2} \\
\frac{\partial U_2}{\partial x_4} & \frac{\partial U_2}{\partial x_2} & \frac{\partial U_2}{\partial x_3} \\
\frac{\partial U_3}{\partial x_1} & \frac{\partial U_3}{\partial x_2} & \frac{\partial U_2}{\partial x_3}
\end{bmatrix} = \begin{bmatrix}
\frac{\partial U_1}{\partial x_1} & 0 & 0 \\
0 & \frac{\partial U_2}{\partial x_2} & 0 & 0
\end{bmatrix}$$

$$+ \begin{bmatrix}
0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial U_2}{\partial x_3}\right) \\
- & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_2} + \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right)
\end{bmatrix}$$

$$+ \begin{bmatrix}
0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right) \\
- & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right)
\end{bmatrix}$$

$$+ \begin{bmatrix}
0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right) \\
- & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right)
\end{bmatrix}$$

$$+ \begin{bmatrix}
0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right) \\
- & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right)
\end{bmatrix}$$

$$+ \begin{bmatrix}
0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right) \\
- & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_3}\right) & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_2}{\partial x_3}\right)
\end{bmatrix}$$

$$\underbrace{\mathcal{E}} = \begin{bmatrix}
\frac{\partial U_1}{\partial x_1} & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right) & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_3} + \frac{\partial U_3}{\partial x_1} \right) \\
\frac{1}{2} \left(\frac{\partial U_2}{\partial x_1} + \frac{\partial U_1}{\partial x_2} \right) & \frac{\partial U_2}{\partial x_2} & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} + \frac{\partial U_3}{\partial x_2} \right) \\
\frac{1}{2} \left(\frac{\partial U_3}{\partial x_1} + \frac{\partial U_1}{\partial x_3} \right) & \frac{1}{2} \left(\frac{\partial U_3}{\partial x_1} + \frac{\partial U_1}{\partial x_3} \right) & \frac{\partial U_3}{\partial x_3}
\end{bmatrix} = \underbrace{\mathcal{E}_{11}} \underbrace{\mathcal{E}_{12}} \underbrace{\mathcal{E}_{13}}$$

$$\underbrace{\mathcal{E}_{13}} \underbrace{\mathcal{E}_{13}} \underbrace{\mathcal{E}_{23}}$$

$$\underbrace{\mathcal{E}_{21}} \underbrace{\mathcal{E}_{23}} \underbrace{\mathcal{E}_{23}}$$

$$J_1(\underline{\varepsilon}) = \varepsilon_{11} + \varepsilon_{22} + \varepsilon_{33} = \varepsilon_{vo}$$

Constitutive Equations

$$\int = F_2(\underline{\varepsilon})$$
Superposition
$$\int F_2(A + B) = F_2(A) + F_2(B)$$
Stress
$$\int F_2(A + B) = F_2(A) + F_2(B)$$
Therefore the fourthing of the position of the p

$$\frac{\text{Voigt Notation}}{\text{Notation}} \left(\underbrace{\underline{\mathbb{S}}}_{3\times3} \rightarrow \underbrace{\underline{\mathbb{S}}}_{6\times1} \right) \rightarrow$$

$$\frac{9 \mid 81 \mid 9}{6 \mid 36 \mid 6}$$

$$\frac{\sqrt{\text{oigt Notation}}}{3 \times 3} \left(\frac{\square}{3} \right) \rightarrow \left(\frac{\square}{5 \times 1} \right) \rightarrow \left(\frac{\square}{5$$

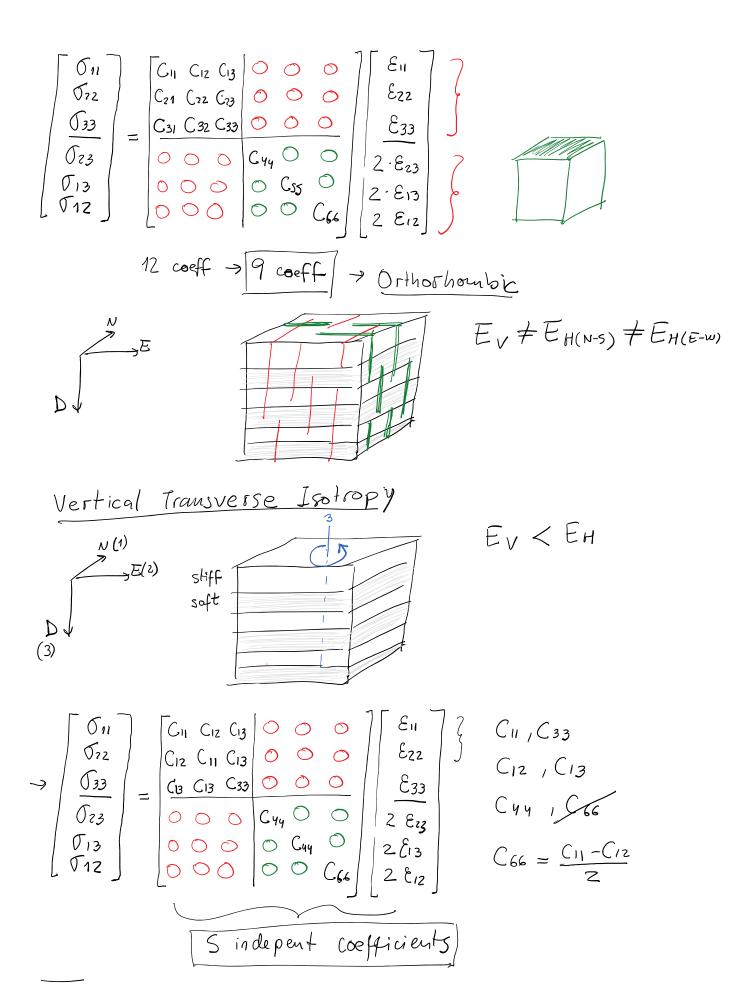
Superposition (Fine) Lunchons

$$\begin{bmatrix}
O_{11} \\
O_{72} \\
\frac{O_{33}}{O_{23}} \\
O_{13} \\
O_{12}
\end{bmatrix} = \begin{bmatrix}
C_{11} & C_{12} & C_{13} & C_{14} & C_{15} & C_{16} \\
C_{21} & \cdot & \cdot & \cdot \\
\vdots & \vdots & \ddots & \vdots \\
\vdots & \vdots & \ddots & \vdots \\
C_{61} & C_{62} & \cdot & \cdot & C_{64}
\end{bmatrix} \begin{bmatrix}
\mathcal{E}_{11} \\
\mathcal{E}_{22} \\
\mathcal{E}_{33} \\
\mathcal{E}_{23} \\
\mathcal{E}_{24} \\
\mathcal{E}_{25} \\
\mathcal$$

Stiffness Matrix

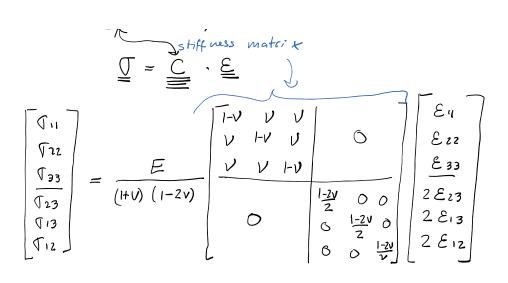
Shear de coupling (normal as shear) for plusticity

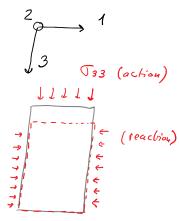
Shear de coupling (shear as shear)



John py (Linear elastic)

$$V = E(z)$$
 $V = E(z)$
 V





$$\begin{array}{c}
(1-V) \ E \\
\hline
(1+V) (1-2V)
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\hline
(1+V) (1-2V)
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\hline
(1+V) (1-2V)
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\vdots \ Oedometric \ modulus
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\vdots \ Oedometric \ modulus
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\vdots \ Oedometric \ modulus
\end{array}$$

$$\begin{array}{c}
(1-V) \ E \\
\vdots \ Oedometric \ modulus
\end{array}$$

$$\sqrt{11} = \frac{\sqrt{E}}{(1+V)(1-2V)} \cdot \mathcal{E}_{33} = \frac{\sqrt{E}}{(1+V)(1-2V)} \cdot \frac{(1+V)(1-2V)}{(1-V)E} \cdot \sqrt{33}$$

$$\int_{11} = \frac{v}{1-v} \int_{33}$$

 $\sqrt{11} = \frac{V}{1-V}$ | lateral effective stress coefficient

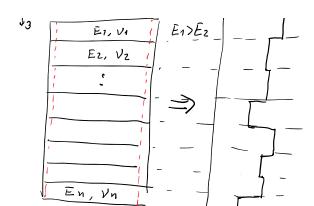
1D Mechanical Earth Model with techomic strains

$$\begin{cases} \sigma_{11} = \sqrt{\frac{\nu}{1-\nu}}\sigma_{33} + \frac{E}{1-\nu^2}\varepsilon_{11} + \frac{\nu E}{1-\nu^2}\varepsilon_{22} \end{cases} \rightarrow \begin{cases} \text{lec bonic} \\ \sigma_{22} = \frac{\nu}{1-\nu}\sigma_{33} + \frac{\nu E}{1-\nu^2}\varepsilon_{11} + \frac{E}{1-\nu^2}\varepsilon_{22} \end{cases} \end{cases}$$

$$E_{11} \neq 0; E_{22} = 0$$

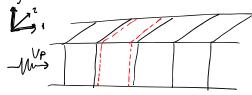
$$E_{11} \neq 0; E_{22} \neq 0; E_{22} = 0$$

$$E_{11} \neq 0; E_{22} \neq 0; E_{$$



Plane-strain Modulus

$$(E, V) = \sqrt{\frac{M}{P_{bulk}}} (P-WAVE) | V_S = \sqrt{\frac{6}{P_{bulk}}} (S-WAVE)$$





$$\int E \, dy \, n = \int L \, |V_s|^2 \left(\frac{3 \, V_\rho^2 - 4 \, V_s^2}{V_\rho^2 - V_s^2} \right)$$

$$\int V \, dy \, n = \frac{V_\rho^2 - 2 \, V_s^2}{Z \left(V_\rho^2 - V_s^2 \right)}$$

