

scalar : P, T
 vector : $\bar{v} = [0, -0.1, 0] \frac{m}{day}$
 $\bar{U} = [0, 1, 0] \text{ cm}$
 tensor : $\underline{\underline{\sigma}} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$

stress $\underline{\underline{\sigma}} = \begin{bmatrix} \sigma_{ij} & & \\ & \ddots & \\ & & \sigma_{ij} \end{bmatrix}$

$$\sigma_{ij} = \sigma_j i$$

σ_{ij}
 face direction
 symmetric

$\sigma_{ij} \in \mathbb{R}$
 eigenvalues $\in \mathbb{R}$

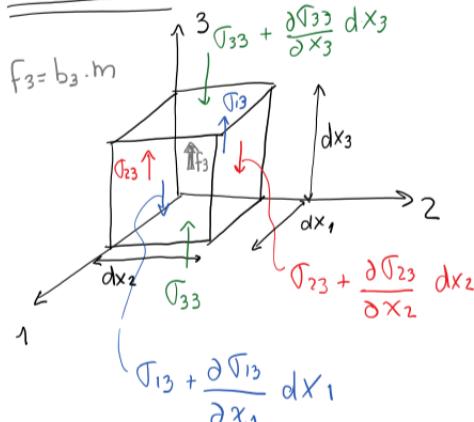
$$\underline{\underline{\sigma}} = \begin{bmatrix} 7000 & 0 & 0 \\ 0 & 6500 & 0 \\ 0 & 0 & 10000 \end{bmatrix} \text{ psi}$$

in coord system 1,2,3

principal stresses
 principal directions \perp $\rightarrow \underline{\underline{\sigma}}^P = \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix}$

$$\sigma_1 \neq \sigma_2 \neq \sigma_3$$

$$\sigma_1 \geq \sigma_2 \geq \sigma_3$$



$$V_{ol} = dx_1 dx_2 dx_3$$

$$\sum F_3 = m \cancel{a}_3^0 = 0$$

$$\cancel{T_{33}} dx_1 dx_2 - \left(\cancel{T_{33}} + \frac{\partial \cancel{T_{33}}}{\partial x_3} dx_3 \right) dx_1 dx_2 +$$

$$\cancel{T_{23}} dx_1 dx_3 - \left(\cancel{T_{23}} + \frac{\partial \cancel{T_{23}}}{\partial x_2} dx_2 \right) dx_1 dx_3 +$$

$$\cancel{T_{13}} dx_2 dx_3 - \left(\cancel{T_{13}} + \frac{\partial \cancel{T_{13}}}{\partial x_1} dx_1 \right) dx_2 dx_3 +$$

$$\underline{F_3} = 0$$

$$\frac{\partial \cancel{T_{33}}}{\partial x_3} dx_1 dx_2 dx_3 + \frac{\partial \cancel{T_{23}}}{\partial x_2} dx_1 dx_2 dx_3 +$$

$$\frac{\partial \cancel{T_{13}}}{\partial x_1} dx_1 dx_2 dx_3 + b_3 m = 0$$

$$\underline{\underline{\sum F_3}} \rightarrow \frac{\partial \cancel{T_{33}}}{\partial x_3} + \frac{\partial \cancel{T_{23}}}{\partial x_2} + \frac{\partial \cancel{T_{13}}}{\partial x_1} + b_3 \frac{m}{V_{ol}} = 0$$

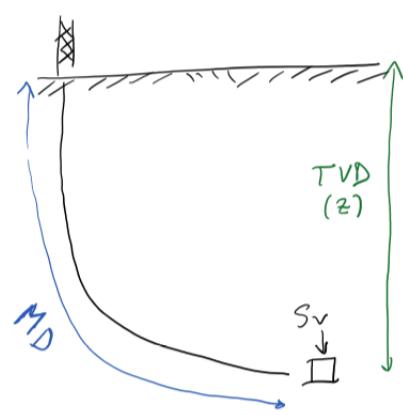
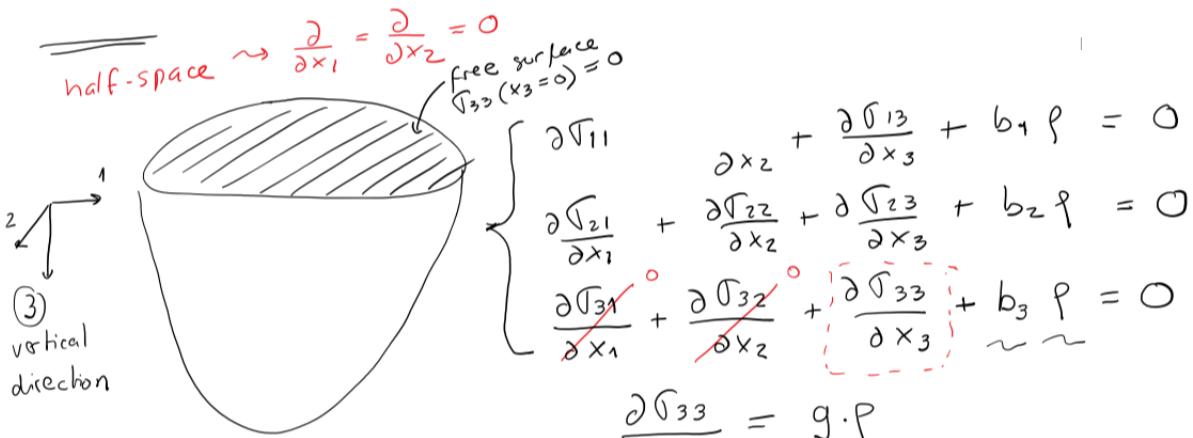
Cauchy's equilibrium equations

$$\bullet \frac{\partial \underline{\underline{T}}_{ij}}{\partial x_j} + b_i \rho = 0$$

$$\bullet \nabla \cdot \underline{\underline{T}} + b \rho = 0$$

$$\left\{ \begin{array}{l} \frac{\partial \underline{\underline{T}}_{11}}{\partial x_1} + \frac{\partial \underline{\underline{T}}_{12}}{\partial x_2} + \frac{\partial \underline{\underline{T}}_{13}}{\partial x_3} + b_1 \rho = 0 \\ \frac{\partial \underline{\underline{T}}_{21}}{\partial x_1} + \frac{\partial \underline{\underline{T}}_{22}}{\partial x_2} + \frac{\partial \underline{\underline{T}}_{23}}{\partial x_3} + b_2 \rho = 0 \\ \frac{\partial \underline{\underline{T}}_{31}}{\partial x_1} + \frac{\partial \underline{\underline{T}}_{32}}{\partial x_2} + \frac{\partial \underline{\underline{T}}_{33}}{\partial x_3} + b_3 \rho = 0 \end{array} \right.$$

gravity in 3 \downarrow \downarrow
 $b_3 = -g$ $\frac{m}{V_{ol}}$



$$\frac{\partial \sigma_{33}}{\partial x_3} = g \cdot \rho$$

$$\int_{\sigma_{33}(x_3=0)}^{\sigma_{33}(x_3)} d\sigma_{33} = \int_{x_3=0}^{x_3} g \cdot \rho \cdot dx_3$$

$$\sigma_{33}(x_3) = \int_0^{x_3} g \cdot \rho(x_3) dx_3$$

$$S_v(z) = \int_0^z g \cdot \rho_{bulk}(z) dz$$

vertical depth

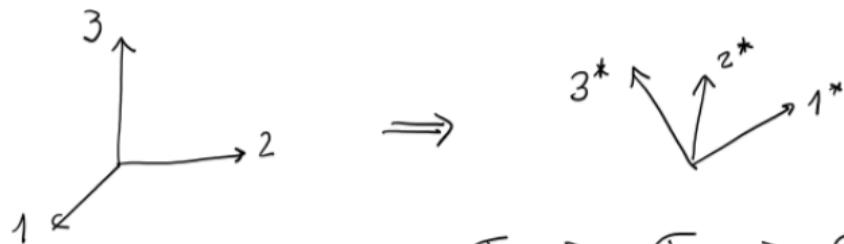
$$S_v(z) = \rho_{bulk} \cdot g \cdot z$$

$$\frac{dS_v}{dz} = \rho_{bulk} \cdot g$$

23 MPa/km
 1 psi/ft

$$2300 \frac{\text{kg}}{\text{m}^3} \cdot 9.8 \frac{\text{m}}{\text{s}^2}$$

$$\begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix} \Rightarrow \begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix}$$



$$\sigma_1 \geq \sigma_2 \geq \sigma_3$$

$$\sigma_1 \perp \sigma_2 \perp \sigma_3$$

σ_v is a principal stress:

$$\hookrightarrow \sigma_v \perp \sigma_{H\max} \perp \sigma_{h\min}$$

(*)

$$\hat{0} \equiv \begin{bmatrix} S_{11} & S_{12} & S_{13} \\ S_{21} & S_{22} & S_{23} \\ S_{31} & S_{32} & S_{33} \end{bmatrix} - \begin{bmatrix} P_p & & \\ & P_p & \\ & & P_p \end{bmatrix}$$

NORMAL FAULTING

$$\sigma_v \geq \sigma_{hmax} \geq \sigma_{hmin}$$

$$\begin{bmatrix} \sigma_v & 0 & 0 \\ 0 & \sigma_{hmax} & 0 \\ 0 & 0 & \sigma_{hmin} \end{bmatrix}$$

STRIKE-SLIP FAULTING

$$\sigma_{hmax} \geq \sigma_v \geq \sigma_{hmin}$$

$$\begin{bmatrix} \sigma_{hmax} & 0 & 0 \\ 0 & \sigma_v & 0 \\ 0 & 0 & \sigma_{hmin} \end{bmatrix}$$

REVERSE F.

$$\sigma_{hmax} \geq \sigma_{hmin} \geq \sigma_v$$

$$\begin{bmatrix} \sigma_{hmax} & 0 & 0 \\ 0 & \sigma_{hmin} & 0 \\ 0 & 0 & \sigma_v \end{bmatrix}$$

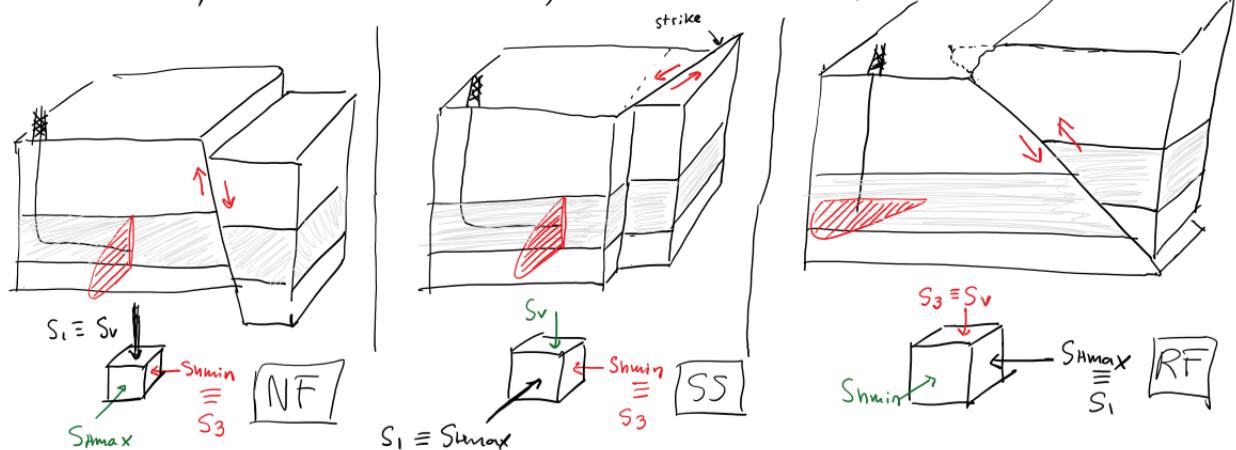
Effective stresses : $\underline{\sigma}$; Total stresses $\underline{S} = \underline{\sigma} + P_p \equiv$ (X)

$$\begin{bmatrix} S_v & 0 & 0 \\ 0 & S_{hmax} & 0 \\ 0 & 0 & S_{hmin} \end{bmatrix}$$

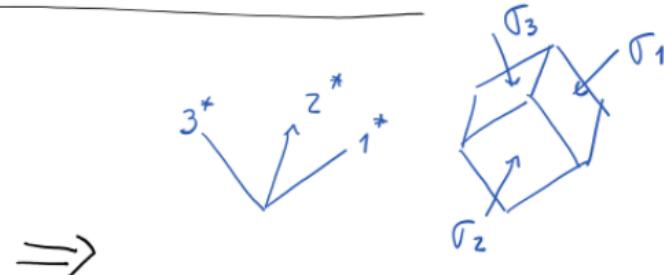
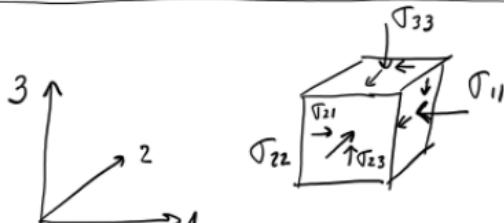
$$\begin{bmatrix} S_{hmax} & 0 & 0 \\ 0 & S_v & 0 \\ 0 & 0 & S_{hmin} \end{bmatrix}$$

$$\begin{bmatrix} S_{hmax} & 0 & 0 \\ 0 & S_{hmin} & 0 \\ 0 & 0 & S_v \end{bmatrix}$$

$$S_v = \sigma_v + P_p; S_{hmax} = \sigma_{hmax} + P_p; S_{hmin} = \sigma_{hmin} + P_p$$

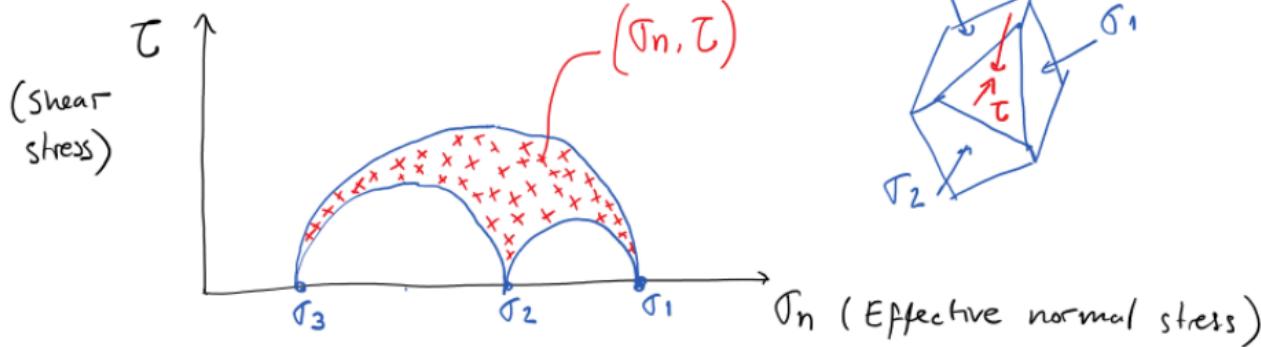


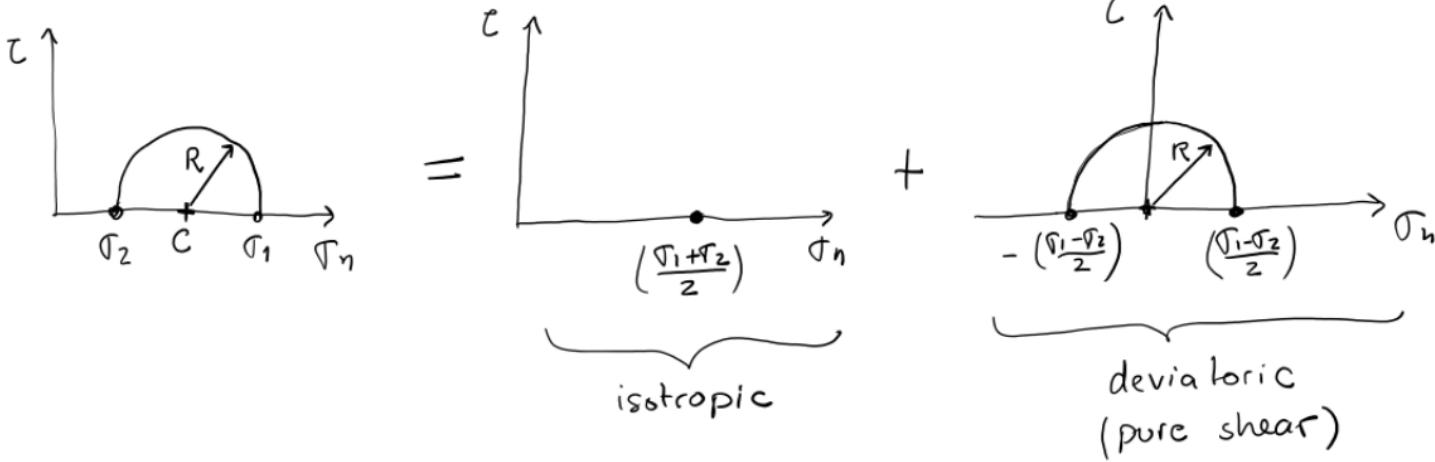
Stress Invariants and graphical representation



$$\begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix}$$

$$\begin{bmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{bmatrix}$$





$$\begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix} = \underbrace{\begin{bmatrix} \sigma_m & 0 & 0 \\ 0 & \sigma_m & 0 \\ 0 & 0 & \sigma_m \end{bmatrix}}_{\text{isotropic}} + \underbrace{\begin{bmatrix} \sigma_{11}-\sigma_m & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22}-\sigma_m & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33}-\sigma_m \end{bmatrix}}_{\text{deviatoric}}$$

$$\sigma_m = \frac{\sigma_{11} + \sigma_{22} + \sigma_{33}}{3}$$

$$\boxed{\underline{\sigma} = \sigma_m \underline{\mathbb{I}} + \underline{\underline{\sigma}}_d}$$

Invariants (do not change wrt coord system)

$$\Rightarrow J_1(\underline{\underline{\tau}}) = \tau_{11} + \tau_{22} + \tau_{33} = \tau_1 + \tau_2 + \tau_3 \quad \Rightarrow \tau_m = \frac{J_1(\underline{\underline{\tau}})}{3}$$

$$J_2(\underline{\underline{\tau}}) = \tau_{11}\tau_{22} + \tau_{11}\cdot\tau_{33} + \tau_{22}\tau_{33} - \tau_{12}^2 - \tau_{13}^2 - \tau_{23}^2$$

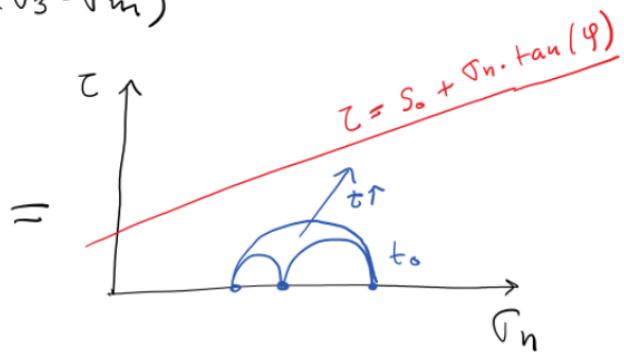
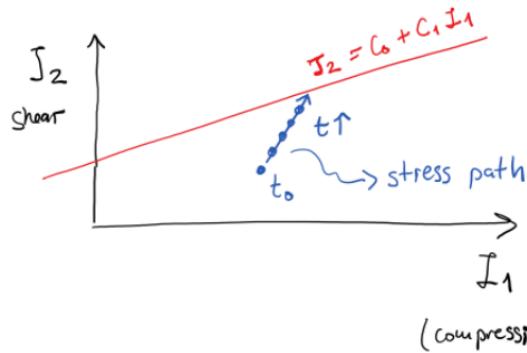
$$J_3(\underline{\underline{\tau}}) = \det(\underline{\underline{\tau}}) = \tau_1 \cdot \tau_2 \cdot \tau_3 \leftarrow$$

=

$$J_1(\underline{\underline{s}}_d) = 0$$

$$\Rightarrow J_2(\underline{\underline{s}}_d) = \frac{1}{6} \left[(\tau_1 - \tau_2)^2 + (\tau_1 - \tau_3)^2 + (\tau_2 - \tau_3)^2 \right]$$

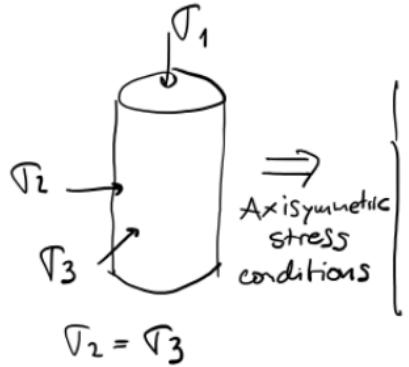
$$J_3(\underline{\underline{s}}_d) = (\tau_1 - \tau_m) \cdot (\tau_2 - \tau_m) \cdot (\tau_3 - \tau_m)$$



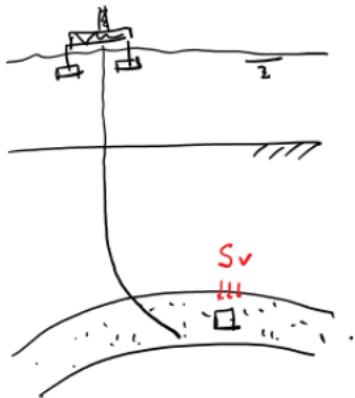
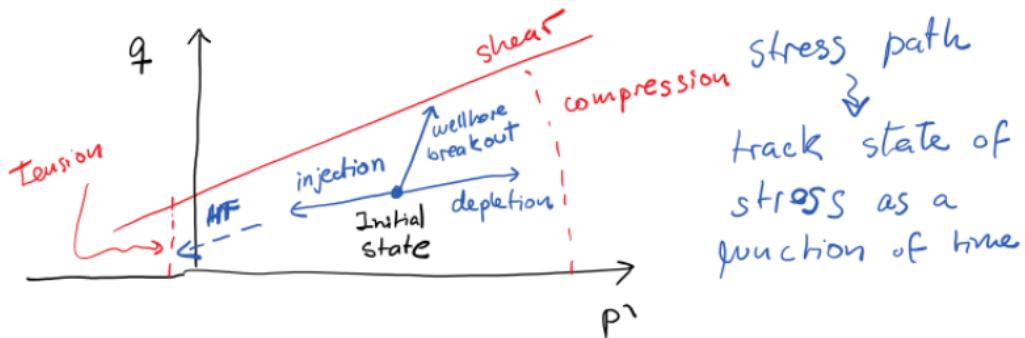
(compression)

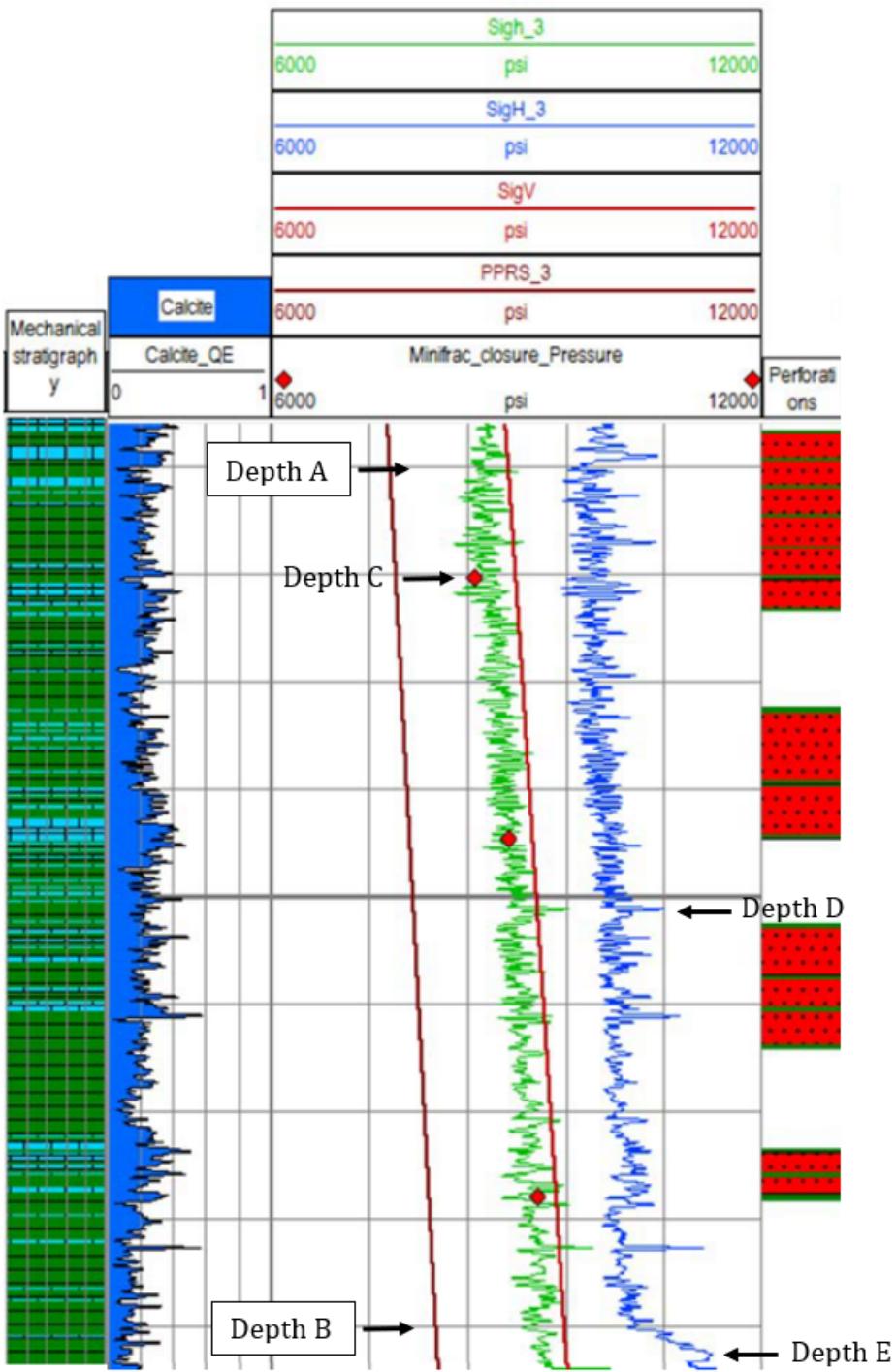
soft sediments
(soil mechanics)

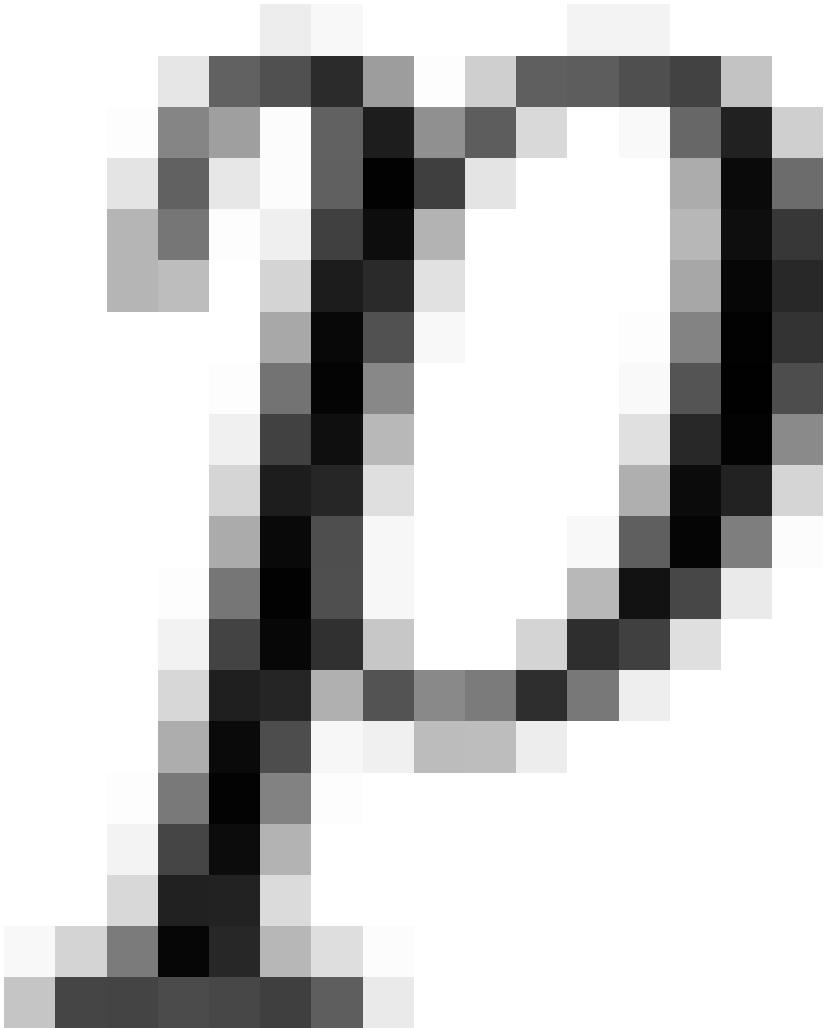
$$\left\{ \begin{array}{l} P' = \sigma_m^{\text{effective}} = J_1(\Sigma) / 3 \\ q = \sqrt{3 J_2} \end{array} \right.$$

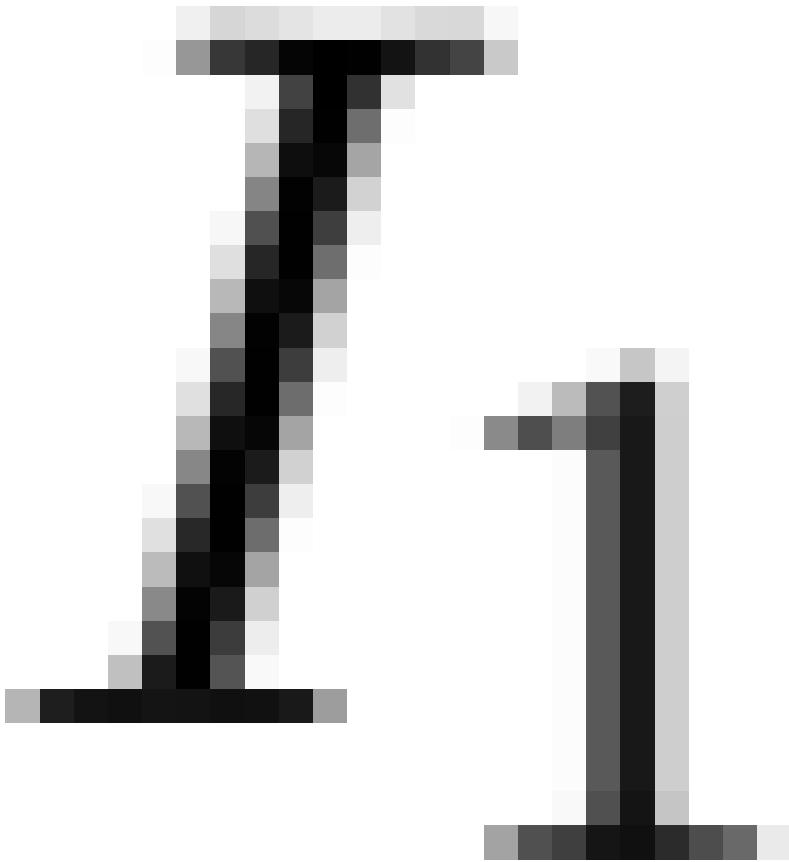


$$\left\{ \begin{array}{l} P' = \frac{\sigma_1 + \sigma_2 + \sigma_3}{3} = \frac{\sigma_1 + 2\sigma_3}{3} \\ q = \sqrt{3 \left\{ \frac{1}{8} \left[(\sigma_1 - \sigma_3)^2 + (\sigma_1 - \sigma_3)^2 \right] \right\}} = \sigma_1 - \sigma_3 \end{array} \right.$$





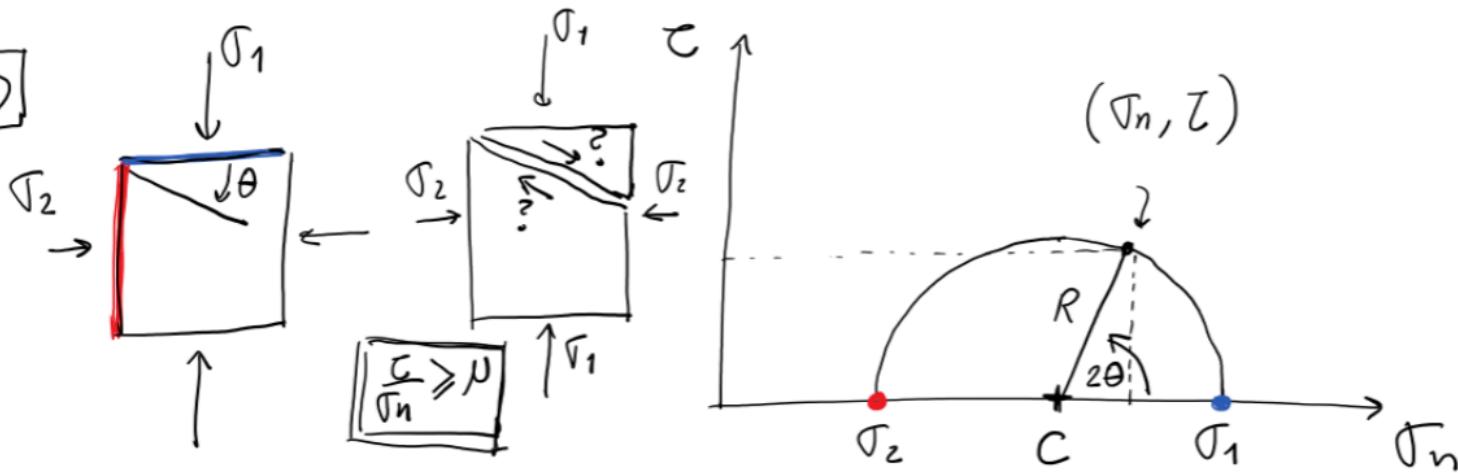




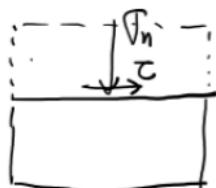


Stress projection on a plane

2D



$$\theta = 0$$

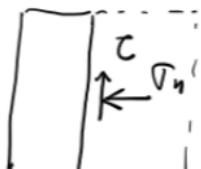


$$\sigma_n = \sigma_1; \tau = 0$$



$$\sigma_n, \tau$$

$$\theta = 90^\circ$$



$$\sigma_n = \sigma_2; \tau = 0$$

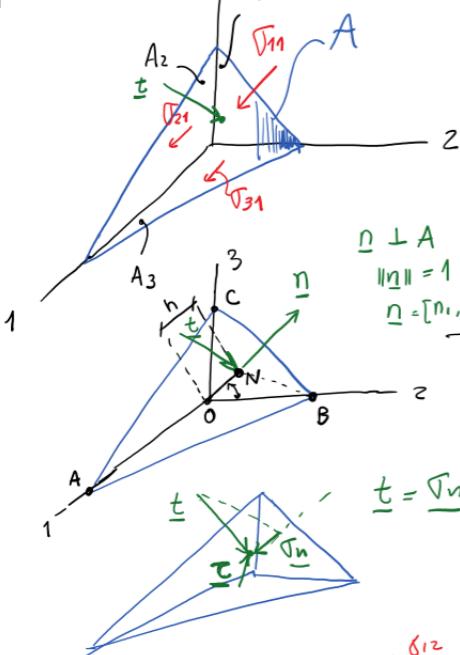
$$\begin{cases} \sigma_n = C + R \cdot \cos 2\theta \\ \tau = R \cdot \sin 2\theta \end{cases}$$

$$C = (\sigma_1 + \sigma_2)/2$$

$$R = (\sigma_1 - \sigma_2)/2$$

3D

$$\sum F_1 = 0$$



$\rightarrow \text{① + ②} \quad \tau_{11} n_1 A + \tau_{21} n_2 A + \tau_{31} n_3 A = t_1 A$

$\Downarrow \tau_{21} = \tau_{12}$ (angular momentum equil.)

$$\begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix} = \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

row \times column
cosine directors

$$\underline{t} = \underline{\tau} \cdot \underline{n}$$

$\Downarrow \left\{ \begin{array}{l} \tau_n = \underline{t} \cdot \underline{n} \\ C = \sqrt{\|\underline{t}\|^2 - \|\tau_n\|^2} \end{array} \right\} \begin{array}{l} \text{projection of} \\ \underline{\tau}_n \text{ on } \underline{n} \end{array}$

$$\textcircled{1} \quad \tau_{11} A_1 + \tau_{21} A_2 + \tau_{31} A_3 = t_1 A$$

$$\textcircled{2} \quad \text{Vol } \Delta = \frac{1}{3} A \cdot h$$

$$= \frac{1}{3} A_1 \cdot \overline{OA}$$

$$\frac{1}{3} Ah = \frac{1}{3} A_1 \overline{OA}$$

$$A_1 = \frac{h}{\overline{OA}} A$$

$$\begin{cases} A_1 = \cos A \hat{O} N \cdot A = n_1 A \\ A_2 = \cos B \hat{O} N \cdot A = n_2 A \\ A_3 = \cos C \hat{O} N \cdot A = n_3 A \end{cases}$$

cosine directors

$$| A_i = n_i A |$$

$$\rightarrow \text{① + ②} \quad \tau_{11} n_1 A + \tau_{21} n_2 A + \tau_{31} n_3 A = t_1 A$$

$\Downarrow \tau_{21} = \tau_{12}$ (angular momentum equil.)

$$\begin{bmatrix} t_1 \\ t_2 \\ t_3 \end{bmatrix} = \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix} \begin{bmatrix} n_1 \\ n_2 \\ n_3 \end{bmatrix}$$

row \times column
cosine directors

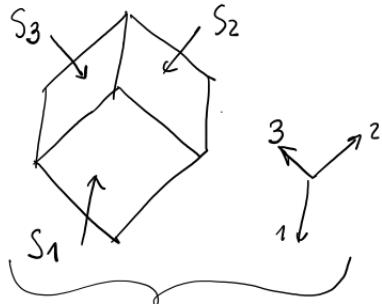
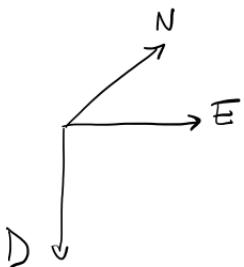
$$\underline{t} = \underline{\tau} \cdot \underline{n}$$

$\Downarrow \left\{ \begin{array}{l} \tau_n = \underline{t} \cdot \underline{n} \\ C = \sqrt{\|\underline{t}\|^2 - \|\tau_n\|^2} \end{array} \right\} \begin{array}{l} \text{projection of} \\ \underline{\tau}_n \text{ on } \underline{n} \end{array}$

$$\Leftrightarrow \|\underline{t}\|^2 = \|\tau_n\|^2 + \|C\|^2$$

Geographical coordinate system

N - E - D



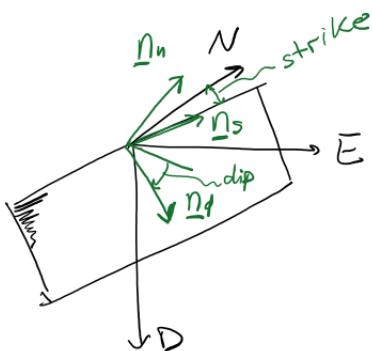
Principal
stresses
and
direction

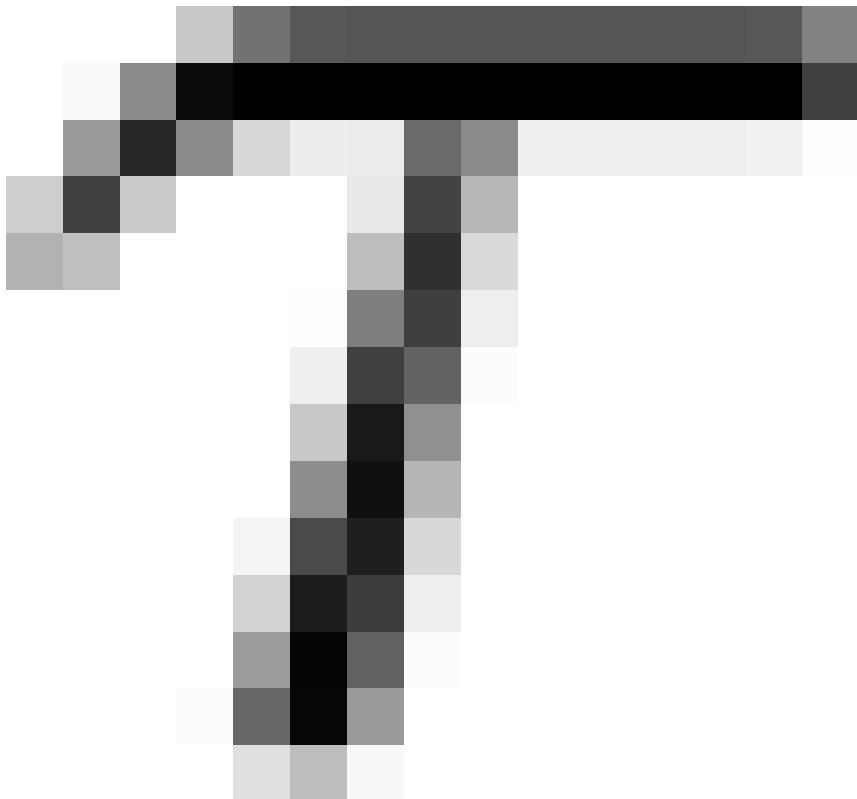
$$\underline{\underline{S}}_G = \begin{bmatrix} S_{NN} & S_{NE} & S_{ND} \\ S_{EN} & S_{EE} & S_{ED} \\ S_{DN} & S_{DE} & S_{DD} \end{bmatrix} \quad \underline{\underline{S}}_P = \begin{bmatrix} S_1 & 0 & 0 \\ 0 & S_2 & 0 \\ 0 & 0 & S_3 \end{bmatrix}$$

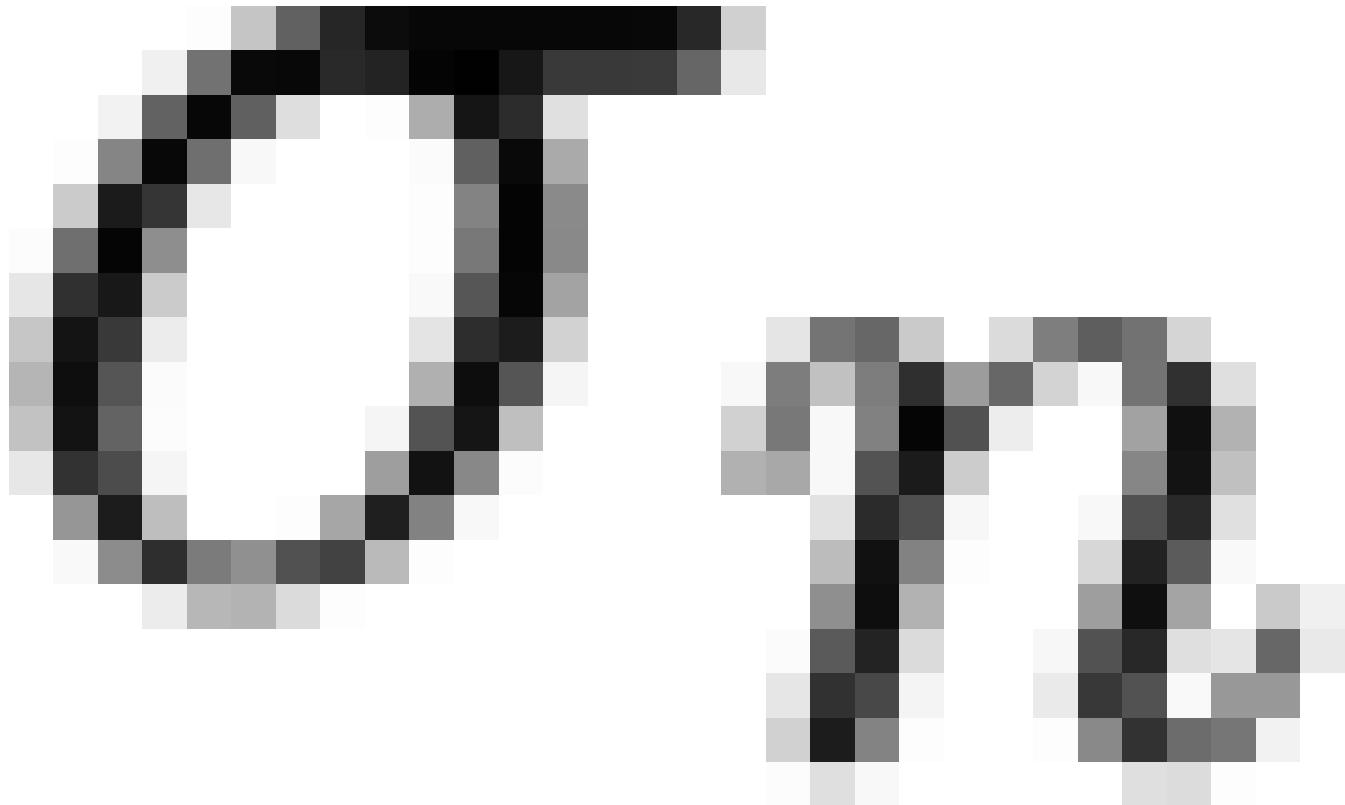
$$\underline{\underline{S}}_G = R_{PG}^T \underline{\underline{S}}_P R_{PG}$$

$$R_{PG} = \begin{bmatrix} - & - & - \\ - & - & - \\ - & - & - \end{bmatrix}$$

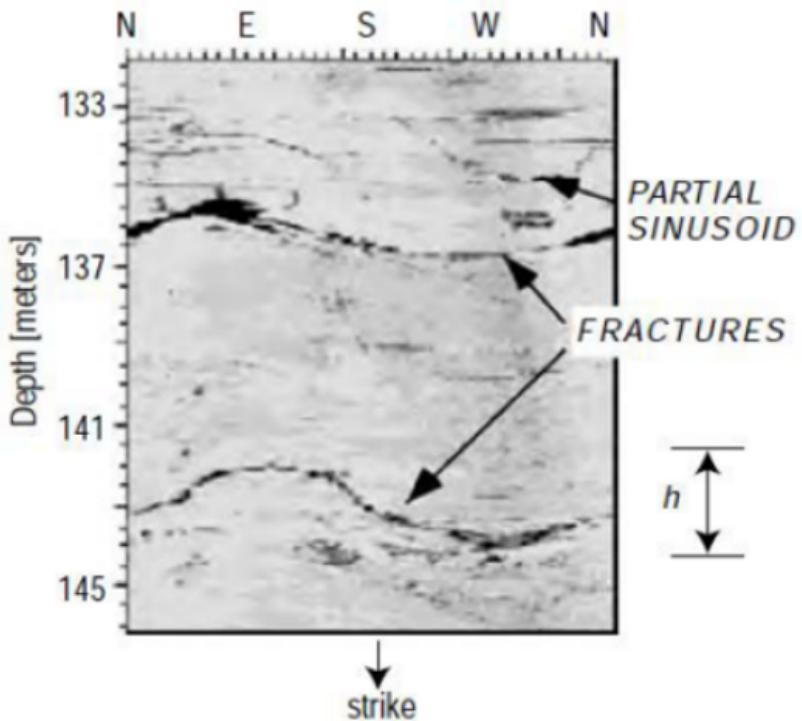
$$f(\alpha, \beta, \gamma)$$



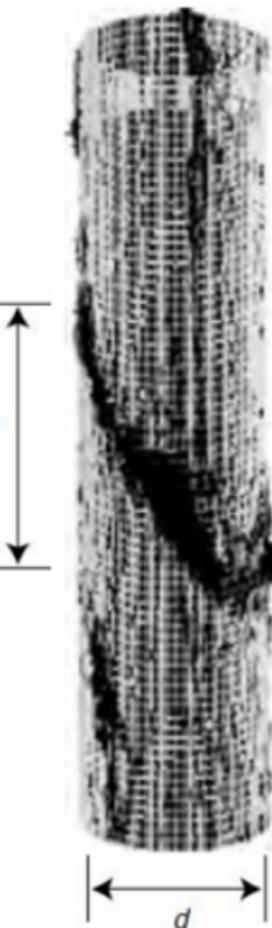




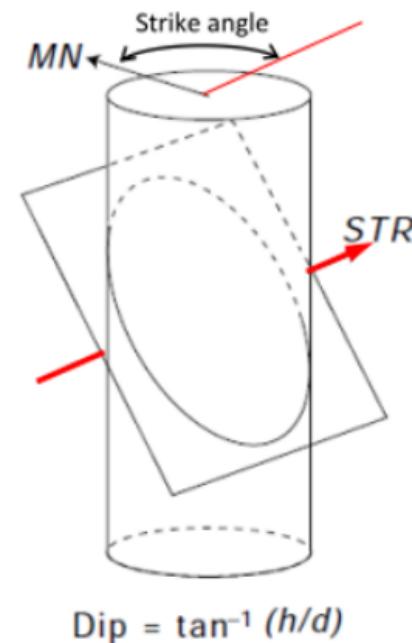
Un-wrapped image (ultrasonic)



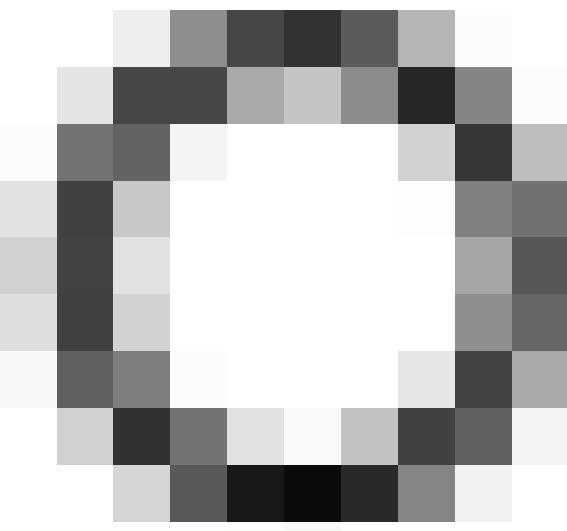
3D-representation

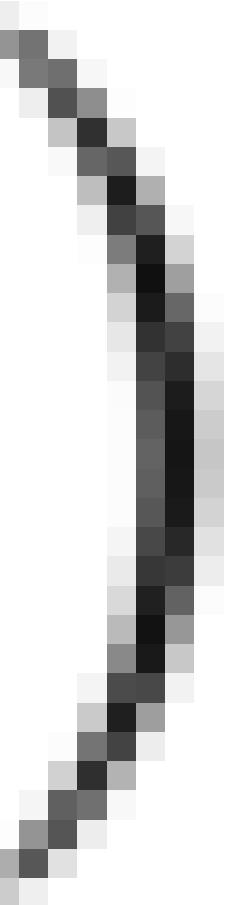
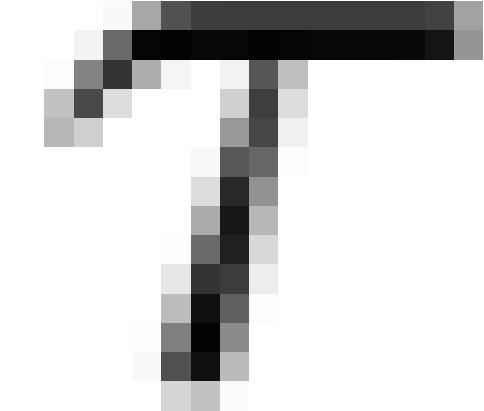
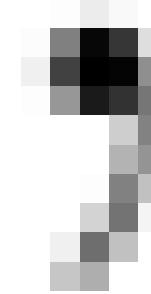
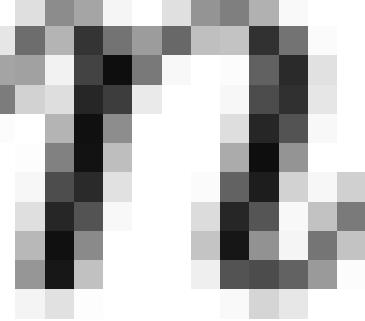
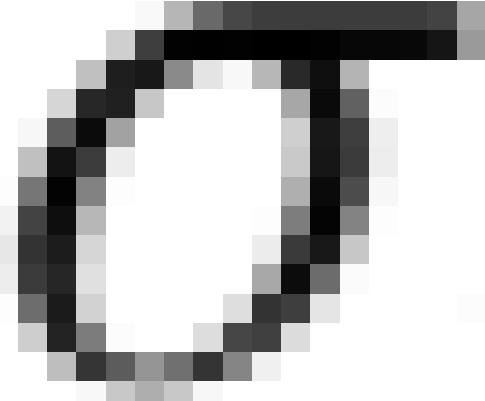
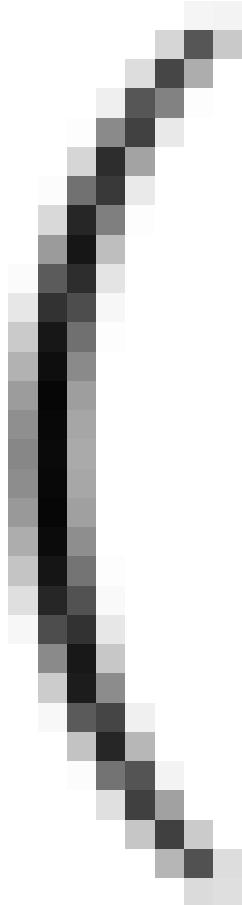


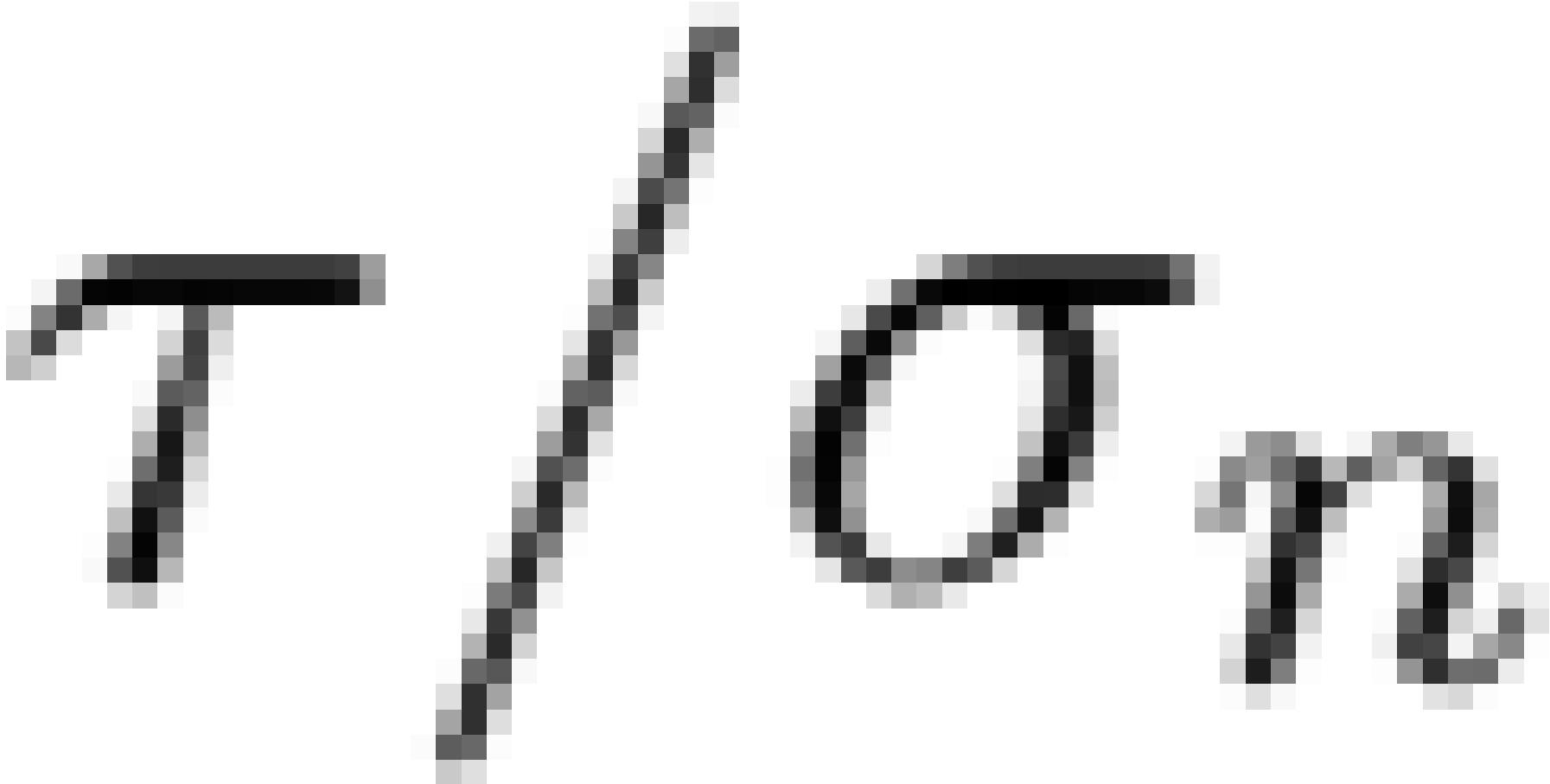
Interpretation

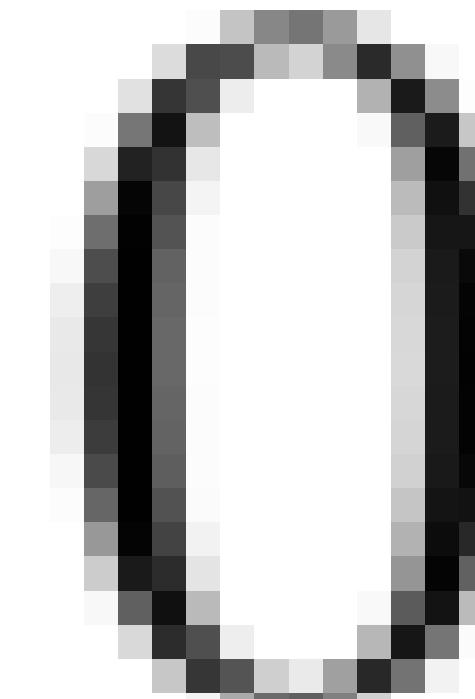
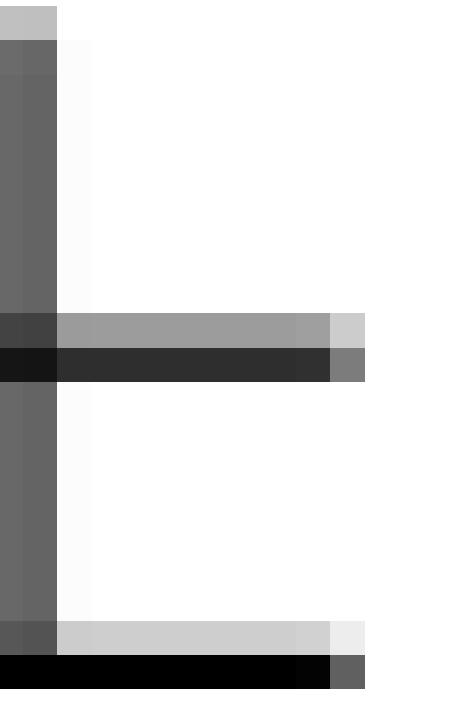
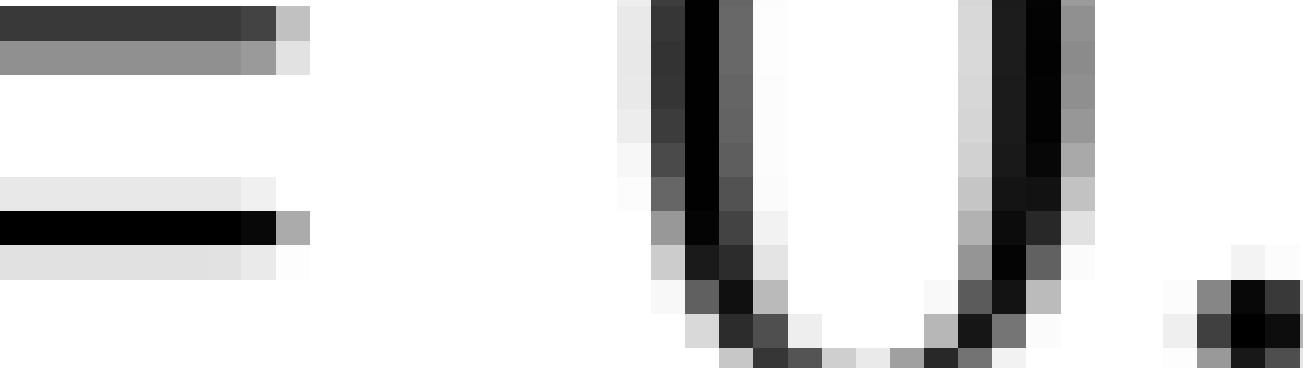
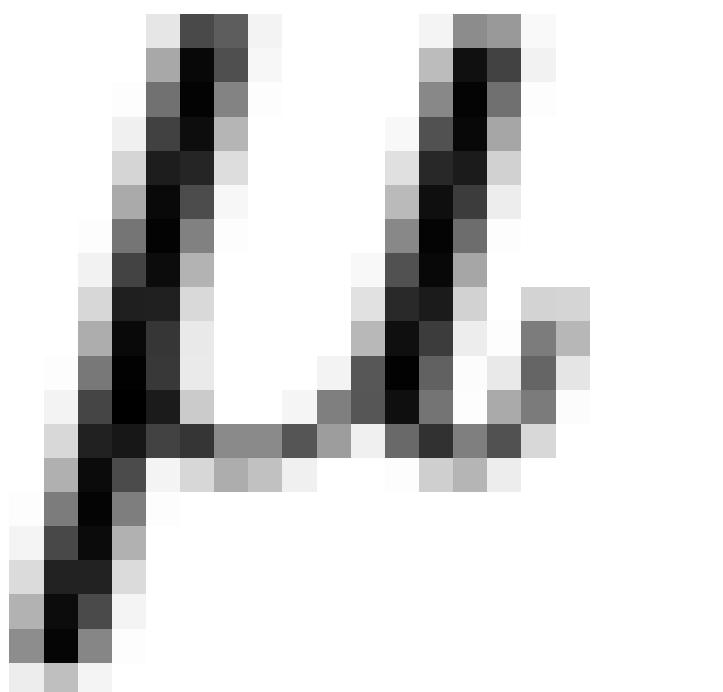


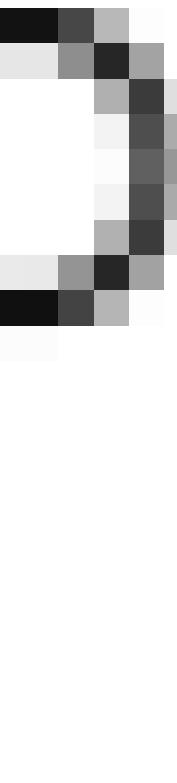
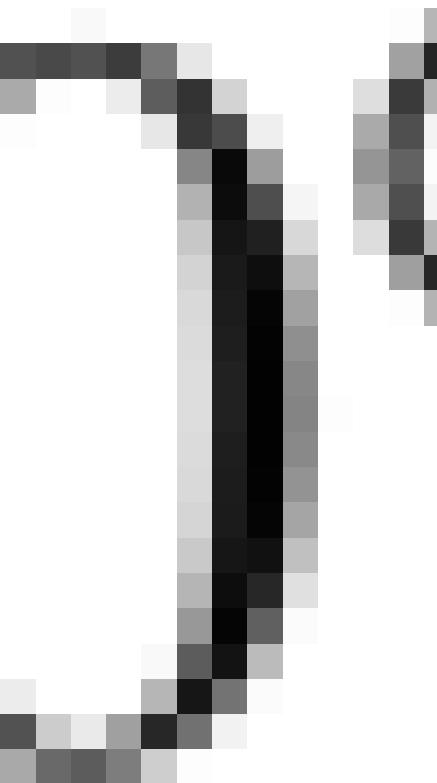
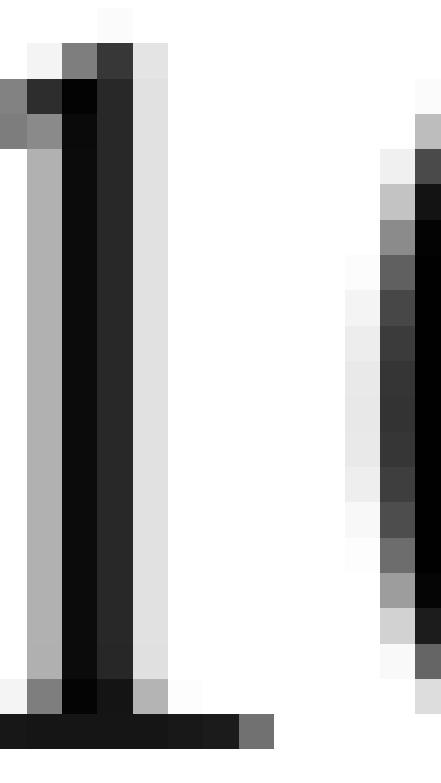
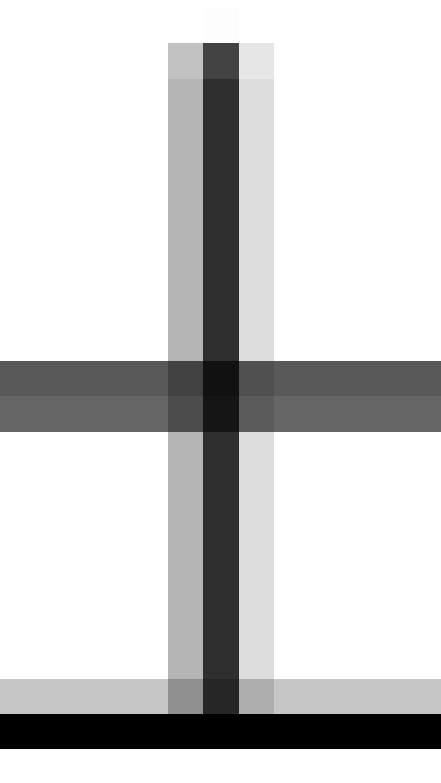
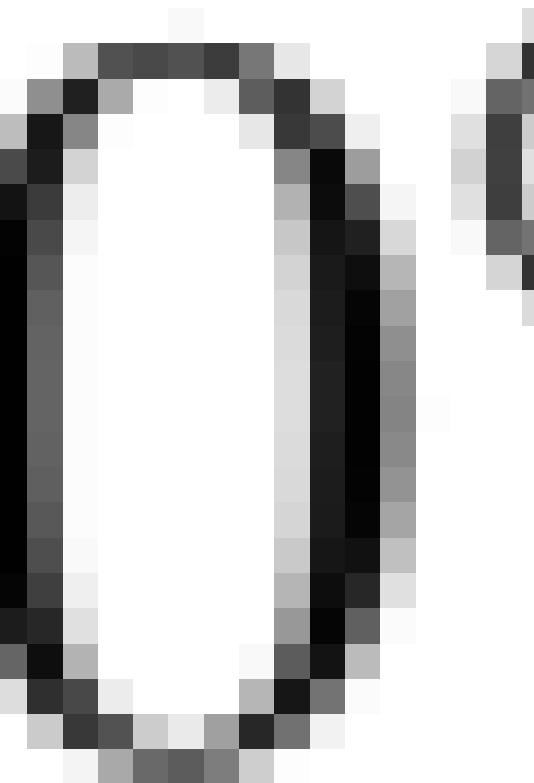
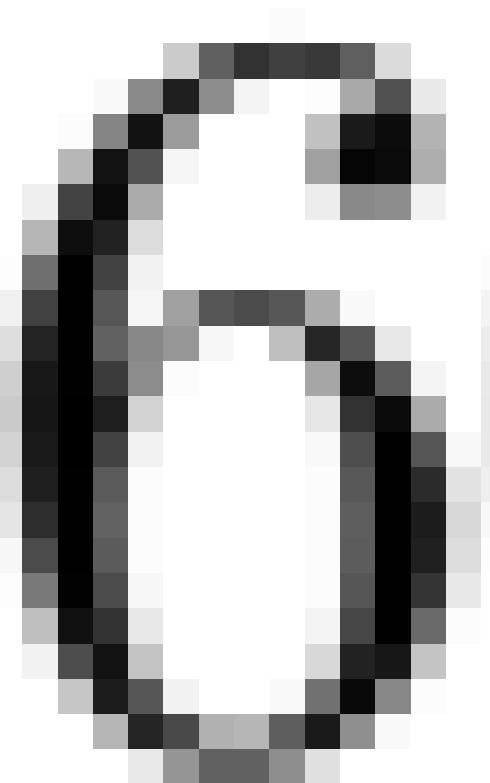
(Zoback 2013, RM, Ch 5.3)

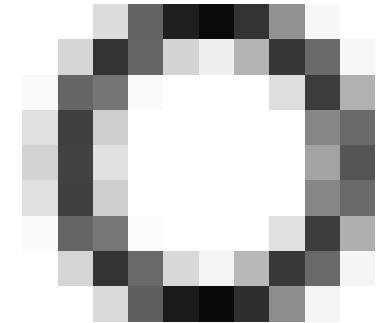
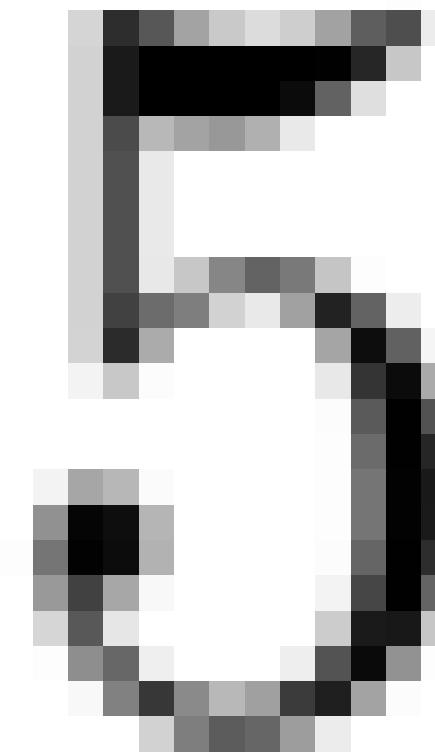
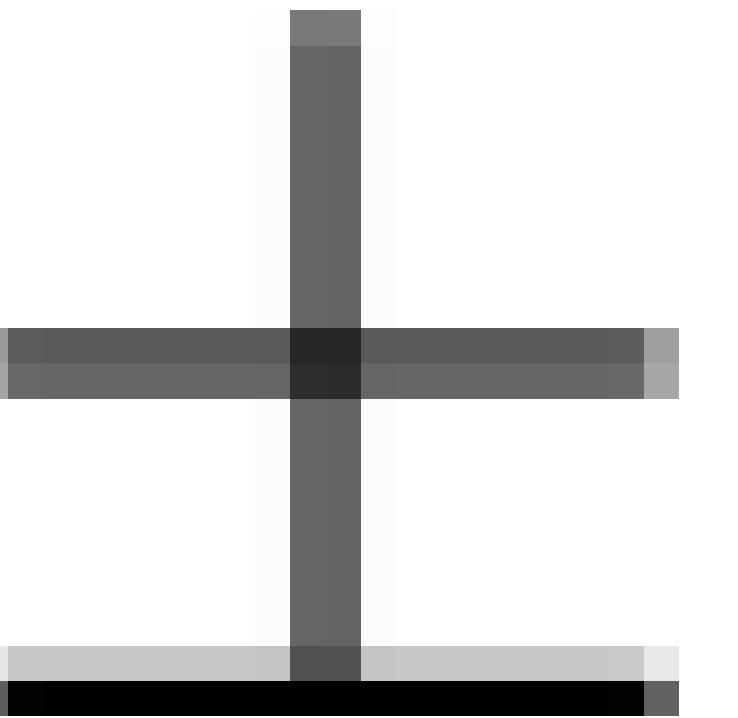
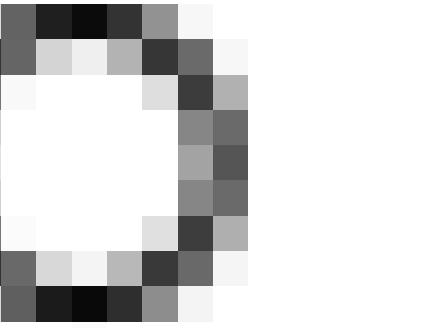
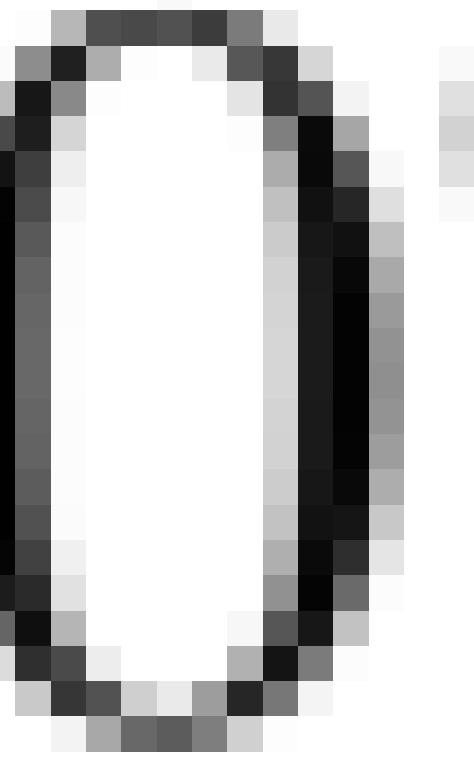
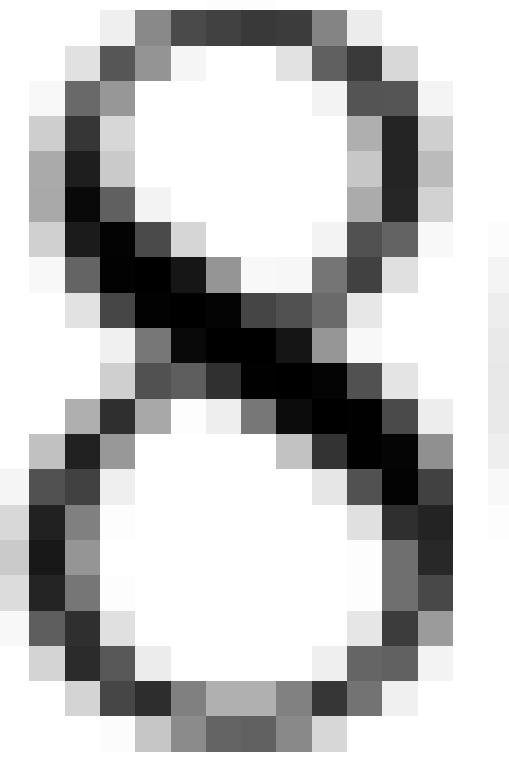


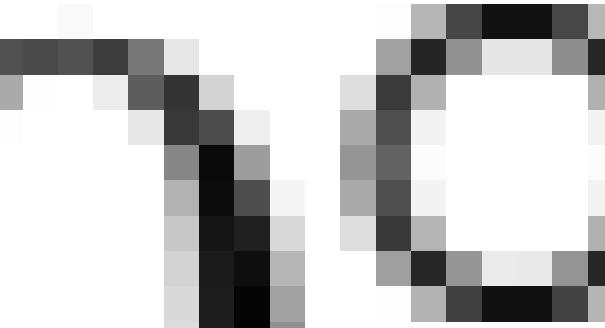
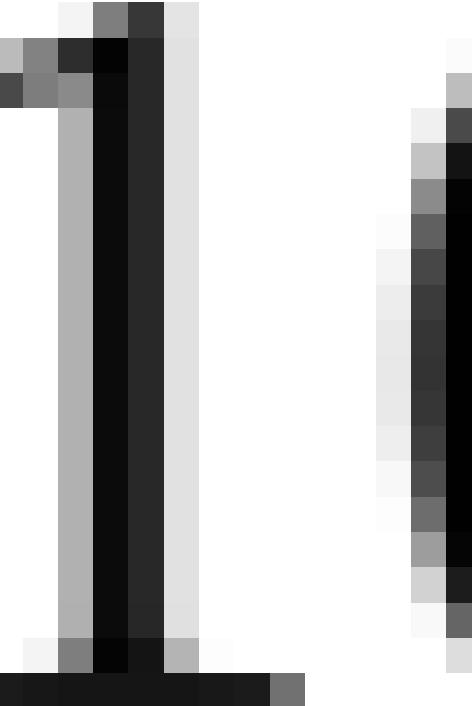
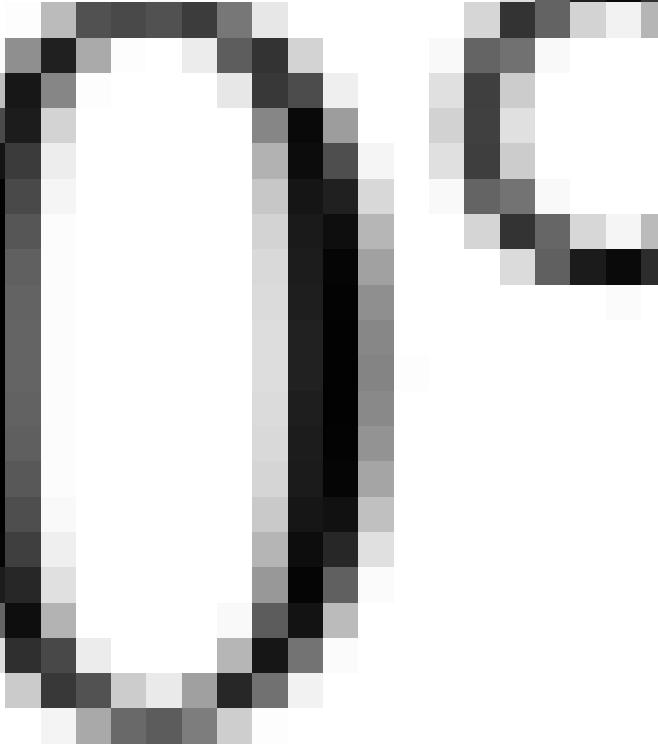
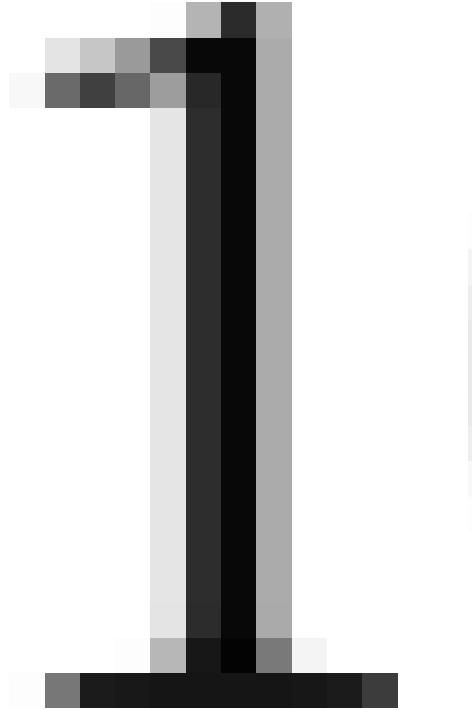


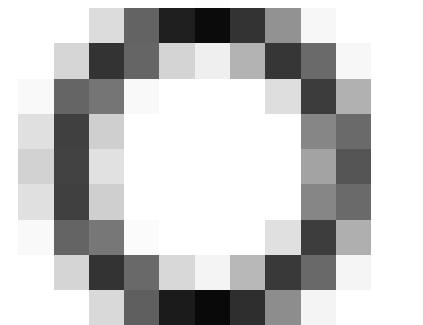
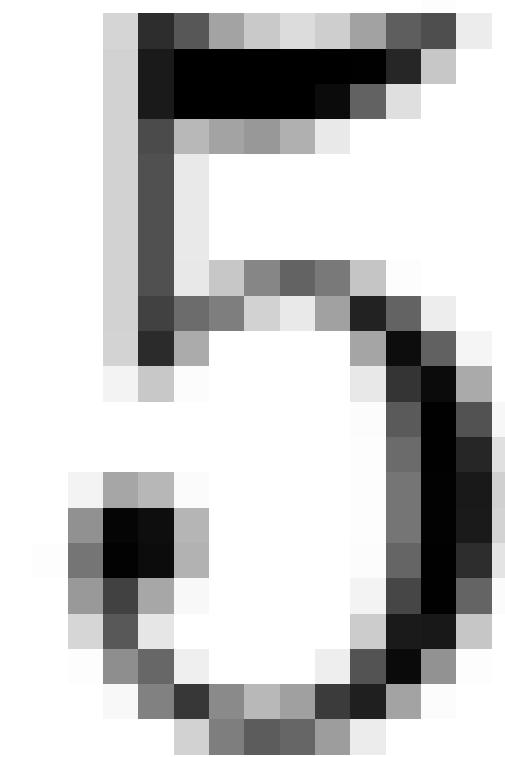
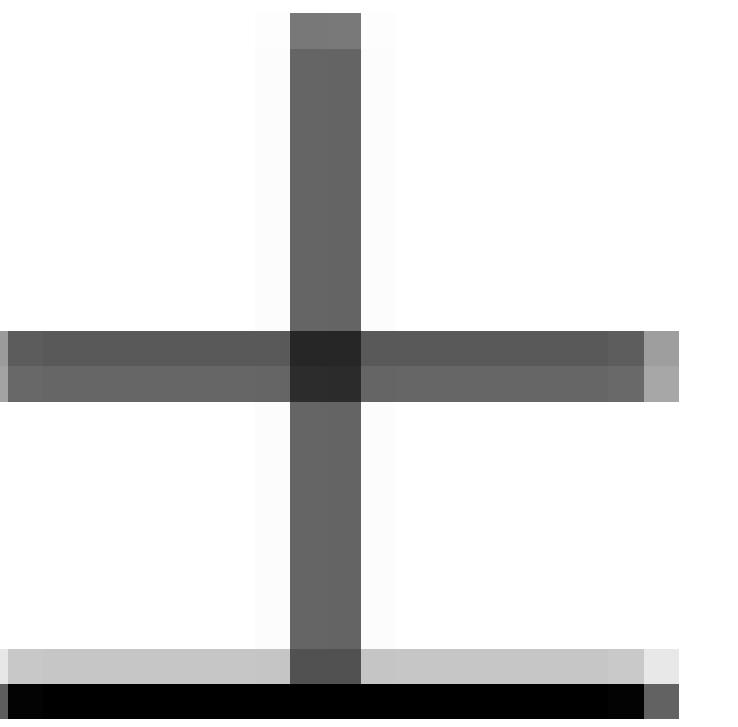
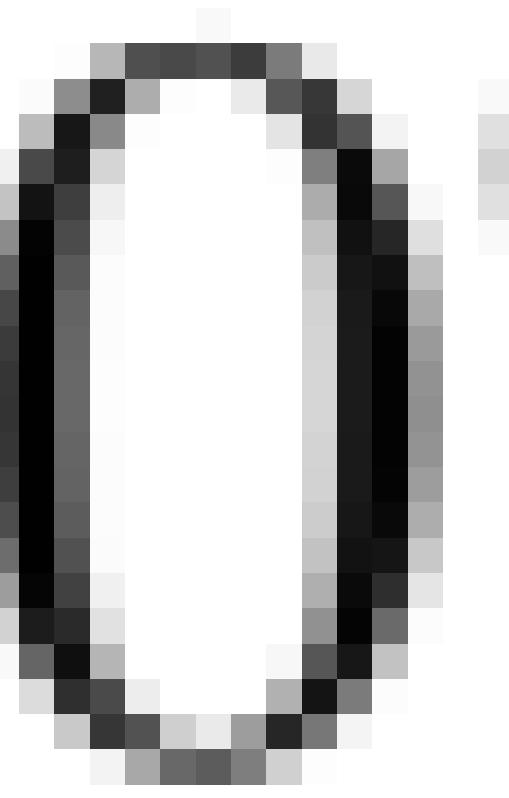
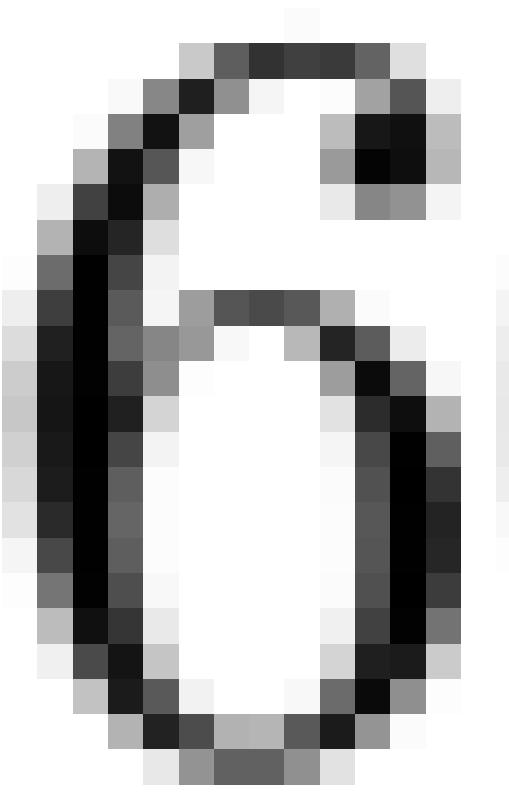






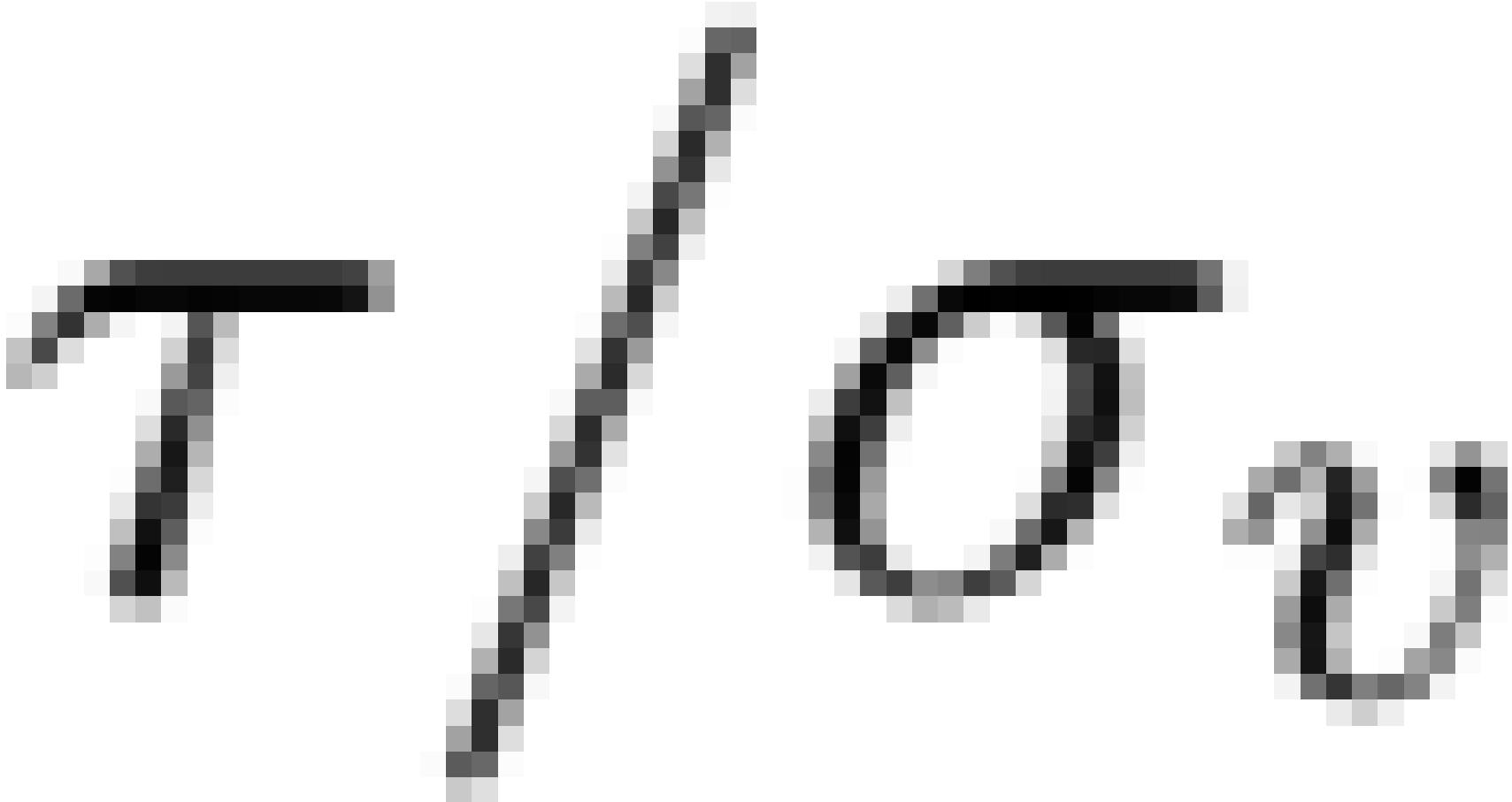




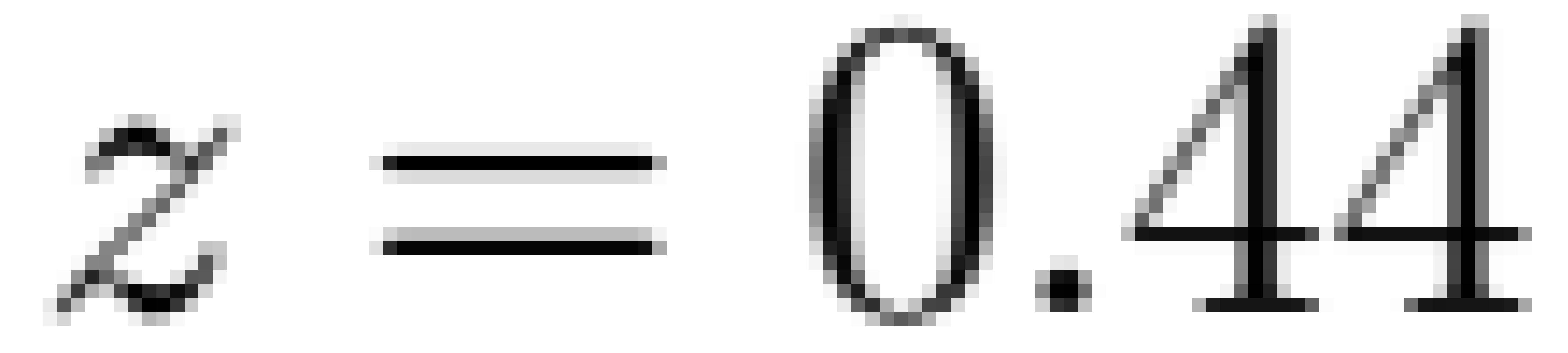


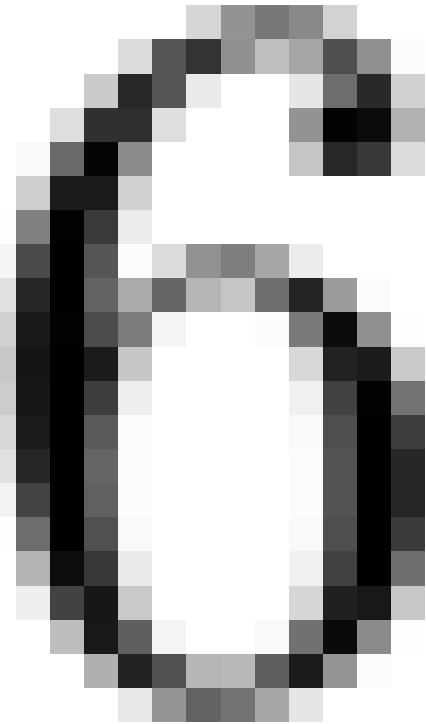
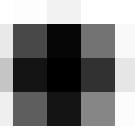
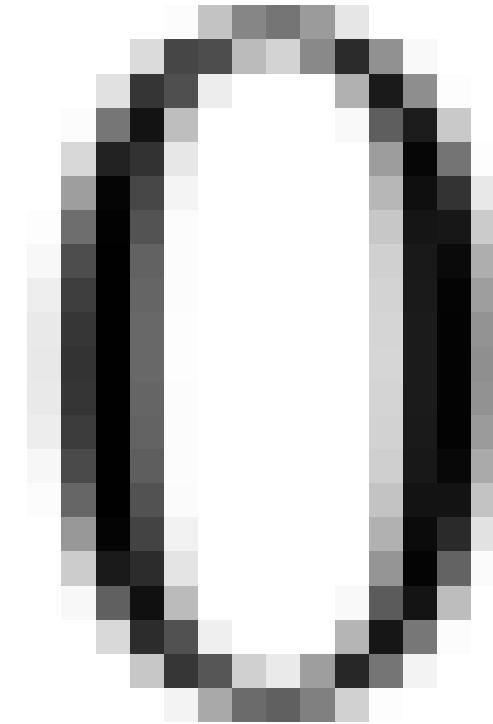
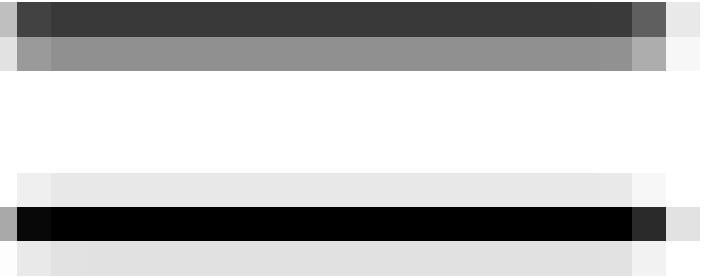
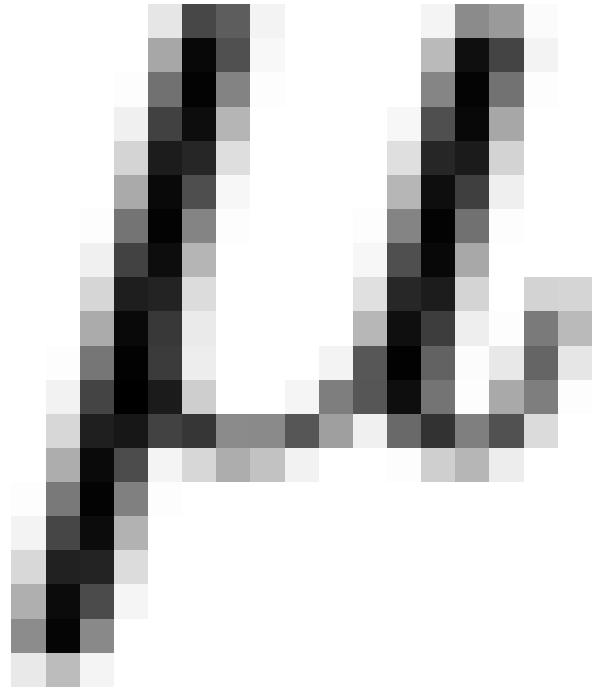




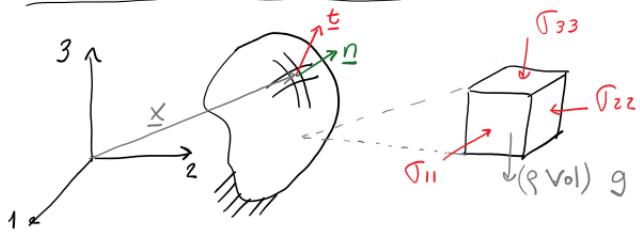








General solution to a continuum mechanics problem



$$\left\{ \begin{array}{l} \nabla \cdot \underline{\underline{\sigma}} + \underline{f} = \rho \underline{\underline{\alpha}} \\ \underline{\underline{\epsilon}} = F_1(\underline{u}) \\ \underline{\underline{\sigma}} = F_2(\underline{\underline{\epsilon}}) \end{array} \right.$$

→ Equilibrium (Cauchy's)
 → Kinematic eq
 { small strains
 { large strains
 → Constitutive equations

} linear isotropic elastic solid
 • TVI (VTE)
 • orthorhombic
 • visco-elasticity
 • plasticity

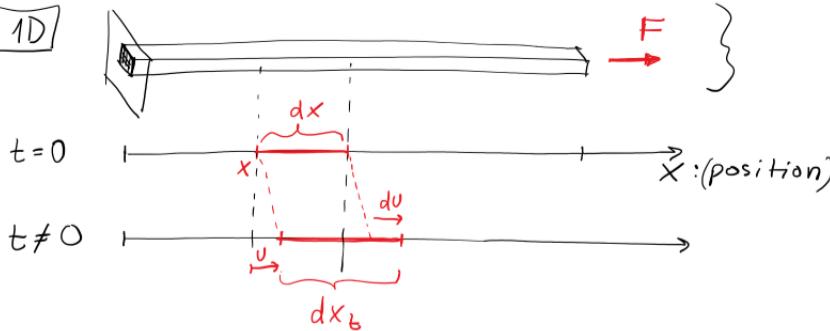
$$\nabla \cdot [F_2(\underline{\underline{\epsilon}})] + \underline{f} = \rho \underline{\underline{\alpha}}$$

$$\boxed{\nabla \cdot [F_2[F_1(\underline{u})]] + \underline{f} = \rho \underline{\underline{\alpha}}}$$

displacement $\underline{u} \rightarrow \underline{\underline{\epsilon}} \rightarrow \underline{\underline{\sigma}}$

Kinematic Equations (small strains) $\underline{\epsilon} = F_1(\underline{u})$

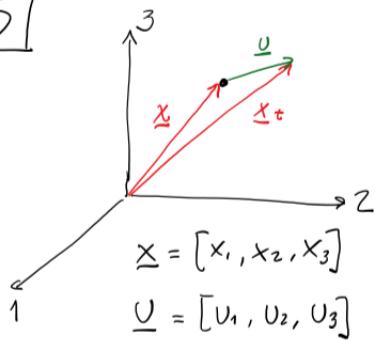
1D



$$\epsilon = \frac{dx_t - dx}{dx} = \frac{[x + u + dx + du - (x + u)] - [x + dx - x]}{[x + dx - x]}$$

$$\boxed{\epsilon = \frac{du}{dx}}$$

3D



Jacobian

\uparrow

\downarrow

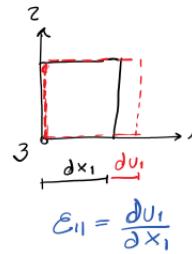
ϵ

$$\boxed{\begin{bmatrix} \frac{\partial u_1}{\partial x_1} & \frac{\partial u_1}{\partial x_2} & \frac{\partial u_1}{\partial x_3} \\ \frac{\partial u_2}{\partial x_1} & \frac{\partial u_2}{\partial x_2} & \frac{\partial u_2}{\partial x_3} \\ \frac{\partial u_3}{\partial x_1} & \frac{\partial u_3}{\partial x_2} & \frac{\partial u_3}{\partial x_3} \end{bmatrix}}$$

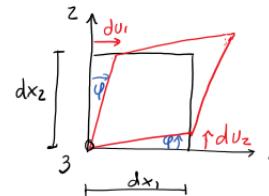
1

$$\underline{u} = [u_1, u_2, u_3]$$

$$\begin{bmatrix} \frac{\partial U_1}{\partial x_1} & \frac{\partial U_1}{\partial x_2} & \frac{\partial U_1}{\partial x_3} \\ \frac{\partial U_2}{\partial x_1} & \frac{\partial U_2}{\partial x_2} & \frac{\partial U_2}{\partial x_3} \\ \frac{\partial U_3}{\partial x_1} & \frac{\partial U_3}{\partial x_2} & \frac{\partial U_3}{\partial x_3} \end{bmatrix} = \begin{bmatrix} \frac{\partial U_1}{\partial x_1} & 0 & 0 \\ 0 & \frac{\partial U_2}{\partial x_2} & 0 \\ 0 & 0 & \frac{\partial U_3}{\partial x_3} \end{bmatrix}$$



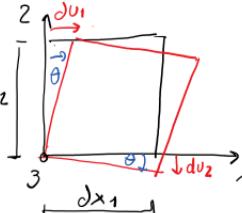
$$+ \begin{bmatrix} 0 & \underbrace{\frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right)}_{\tan \varphi} & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_3} + \frac{\partial U_3}{\partial x_1} \right) \\ \dots & 0 & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} + \frac{\partial U_3}{\partial x_2} \right) \\ \dots & \dots & 0 \end{bmatrix}$$



$$\tan \varphi = \frac{\partial U_1}{\partial x_2} = \frac{\partial U_2}{\partial x_1}$$

$$\mathcal{E}_{12} = \frac{1}{2} (\tan \varphi) = \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right)$$

$$+ \begin{bmatrix} 0 & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_1} \right) & \frac{1}{2} \left(\frac{\partial U_1}{\partial x_3} - \frac{\partial U_3}{\partial x_1} \right) \\ \frac{1}{2} \left(\frac{\partial U_2}{\partial x_1} - \frac{\partial U_1}{\partial x_2} \right) & 0 & \frac{1}{2} \left(\frac{\partial U_2}{\partial x_3} - \frac{\partial U_3}{\partial x_2} \right) \\ \dots & \dots & 0 \end{bmatrix}$$



$$\left(\frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right) = 0$$

$$\frac{1}{2} \left(\frac{\partial U_1}{\partial x_2} - \frac{\partial U_2}{\partial x_1} \right) = \omega_{12}$$

$$\underline{\underline{\epsilon}} = \begin{bmatrix} \frac{\partial u_1}{\partial x_1} & \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right) & \frac{1}{2} \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) \\ \frac{1}{2} \left(\frac{\partial u_2}{\partial x_1} + \frac{\partial u_1}{\partial x_2} \right) & \frac{\partial u_2}{\partial x_2} & \frac{1}{2} \left(\frac{\partial u_2}{\partial x_3} + \frac{\partial u_3}{\partial x_2} \right) \\ \frac{1}{2} \left(\frac{\partial u_3}{\partial x_1} + \frac{\partial u_1}{\partial x_3} \right) & \frac{1}{2} \left(\frac{\partial u_3}{\partial x_2} + \frac{\partial u_2}{\partial x_3} \right) & \frac{\partial u_3}{\partial x_3} \end{bmatrix} = \begin{bmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{bmatrix}$$

\rightarrow symmetric } eigen values \rightarrow principal strains
 \rightarrow real values } eigen vectors \rightarrow principal directions
 own

$$J_1(\underline{\epsilon}) = \epsilon_{11} + \epsilon_{22} + \epsilon_{33} = \epsilon_{vol}$$

$$\epsilon_{vol} = \frac{Vol(t) - Vol_0}{Vol_0}$$

$$\underline{\underline{\sigma}} = \underline{\underline{F}}_2 (\underline{\underline{\epsilon}})$$

\sim stress \sim strain

Superposition $\begin{cases} \text{space} \\ \text{time} \end{cases}$ } Green's functions

$$\left\{ \begin{array}{l} F_2(A + B) = F_2(A) + F_2(B) \\ F_2(c \cdot A) = c \cdot F_2(A) \end{array} \right.$$

linear relationships

$$\boxed{\underline{\underline{\sigma}} = \underline{\underline{C}} \cdot \underline{\underline{\epsilon}}}$$

$$\hookrightarrow \underline{y} = b \cdot \underline{x}$$

\sim
constant

9	81	9
6	36	6

Voigt Notation

$$\begin{matrix} \underline{\underline{\sigma}} \\ 3 \times 3 \end{matrix} \rightarrow \begin{matrix} \underline{\sigma} \\ 6 \times 1 \end{matrix}$$

$$\begin{bmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{bmatrix} \rightarrow \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix}$$

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & C_{14} & C_{15} & C_{16} \\ C_{21} & \ddots & \ddots & \ddots & \ddots & \ddots \\ \vdots & & & & & \vdots \\ \vdots & & & & & \vdots \\ C_{61} & C_{62} & \ddots & \ddots & \ddots & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2 \cdot \epsilon_{23} \\ 2 \cdot \epsilon_{13} \\ 2 \cdot \epsilon_{12} \end{bmatrix}$$

6×1

6×6

6×1

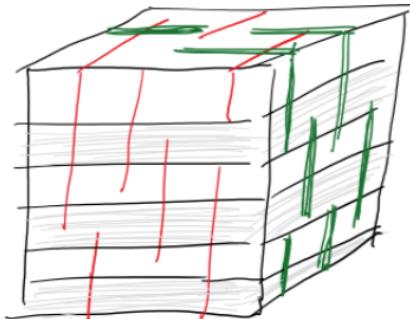
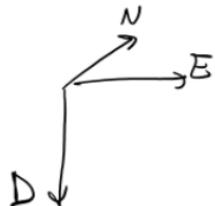
Stiffness Matrix

Shear decoupling < normal \leftrightarrow shear shear \leftrightarrow shear } does not apply
for plasticity

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} \\ C_{21} & C_{22} & C_{23} \\ C_{31} & C_{32} & C_{33} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ C_{44} & 0 & 0 \\ 0 & C_{55} & 0 \\ 0 & 0 & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2 \cdot \epsilon_{23} \\ 2 \cdot \epsilon_{13} \\ 2 \cdot \epsilon_{12} \end{bmatrix}$$

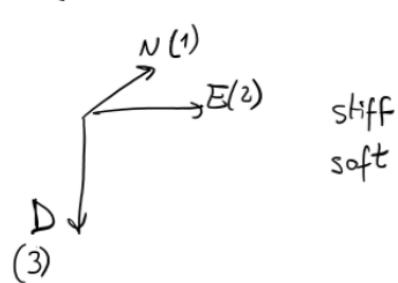


12 coeff \rightarrow 9 coeff \rightarrow Orthorhombic



$$E_v \neq E_{H(N-S)} \neq E_{H(E-W)}$$

Vertical Transverse Isotropy



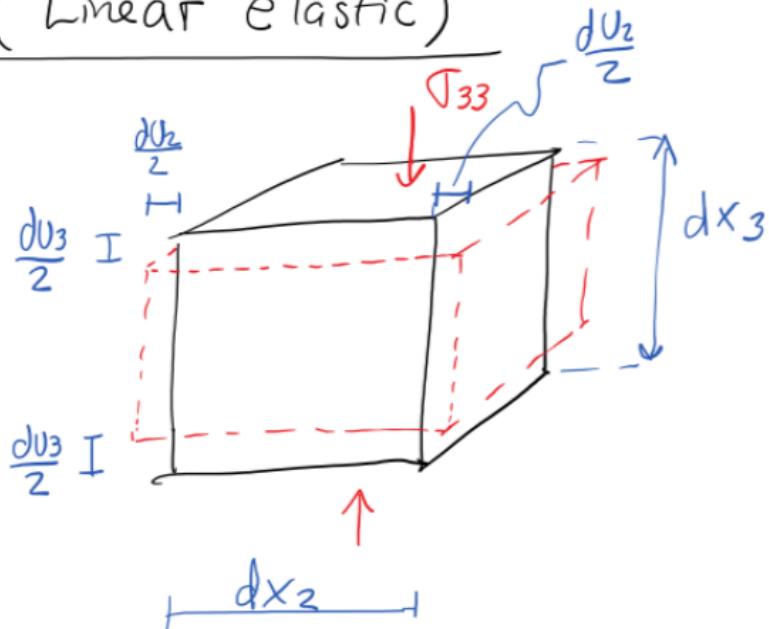
$$E_V < E_H$$

$$\rightarrow \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} \\ C_{12} & C_{11} & C_{13} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} \\ C_{13} & C_{13} & C_{33} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} \\ \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & C_{44} & \textcolor{green}{\bigcirc} & \textcolor{green}{\bigcirc} \\ \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{green}{\bigcirc} & C_{44} & \textcolor{green}{\bigcirc} \\ \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{red}{\bigcirc} & \textcolor{green}{\bigcirc} & \textcolor{green}{\bigcirc} & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix} \quad \left. \begin{array}{l} C_{11}, C_{33} \\ C_{12}, C_{13} \\ C_{44}, \cancel{C_{66}} \\ C_{66} = \frac{C_{11} - C_{12}}{z} \end{array} \right\}$$

S independent coefficients

Isotropy (Linear elastic)

$$\begin{array}{l} N(1) \\ \nearrow E(2) \\ \downarrow D(3) \end{array}$$



$$\epsilon_{33} = \frac{\partial u_3}{\partial x_3}$$

$$\epsilon_{22} = \frac{\partial u_2}{\partial x_2}$$

$$\epsilon_{11} = \frac{\partial u_1}{\partial x_1}$$

$$E \stackrel{\text{def}}{=} \frac{\sigma_{33}}{\epsilon_{33}}$$

Young's modulus

$$\nu \stackrel{\text{def}}{=} -\frac{\epsilon_{11}}{\epsilon_{33}} = -\frac{\epsilon_{22}}{\epsilon_{33}}$$

Poisson's ratio

$$\underline{\underline{\sigma}} = \begin{vmatrix} 0 \\ 0 \\ \sigma_{33} \\ 0 \\ 0 \\ 0 \end{vmatrix} \Rightarrow \underline{\underline{\epsilon}} = \begin{vmatrix} -(\nu/E)\sigma_{33} \\ -(\nu/E)\sigma_{33} \\ \sigma_{33}/E \\ 0 \\ 0 \\ 0 \end{vmatrix} \leftarrow \begin{matrix} \sigma_{33} \\ \sigma_{22} \\ \sigma_{11} \end{matrix}$$

$$\downarrow$$

$$\begin{vmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{vmatrix} = \begin{vmatrix} \frac{1}{E} & -\nu/E & -\nu/E \\ -\nu/E & \frac{1}{E} & -\nu/E \\ -\nu/E & -\nu/E & \frac{1}{E} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{vmatrix} \begin{vmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{vmatrix} \leftarrow G = \frac{E}{2(1+\nu)}$$

isotropic loading $\sigma_{11} = \sigma_{22} = \sigma_{33} = \sigma_m$

$$\rightarrow \epsilon_4 = \frac{1-2\nu}{E} \sigma_m$$

$$\epsilon_{vol} = \frac{3(1-2\nu)}{E} \sigma_m \Rightarrow K = \frac{E}{3(1-2\nu)}$$

$$\underline{\underline{\epsilon}} = \underline{\underline{D}} \cdot \underline{\underline{\sigma}}$$

E, ν
compliance matrix (2 indep. coeff)

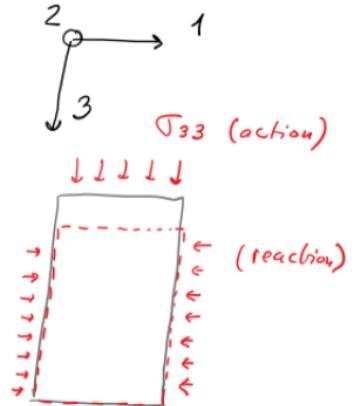
$$\underline{\underline{D}} \cdot \underline{\underline{\varepsilon}} = \underline{\underline{D}}^{-1} \cdot \underline{\underline{D}} \cdot \underline{\underline{\sigma}}$$

$\underline{\underline{\sigma}} = \underline{\underline{C}} \cdot \underline{\underline{\varepsilon}}$

$$\begin{bmatrix} \tau_{11} \\ \tau_{22} \\ \tau_{33} \\ \hline \tau_{23} \\ \tau_{13} \\ \tau_{12} \end{bmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & | & \varepsilon_1 \\ \nu & 1-\nu & \nu & | & \varepsilon_{22} \\ \nu & \nu & 1-\nu & | & \varepsilon_{33} \\ \hline 0 & & & | & 2\varepsilon_{23} \\ 0 & & & | & 2\varepsilon_{13} \\ 0 & & & | & 2\varepsilon_{12} \end{bmatrix}$$

Uniaxial-strain loading (stress path)

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \frac{E}{(1+v)(1-2v)} \begin{bmatrix} 1-v & v & v \\ v & 1-v & v \\ v & v & 1-v \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \epsilon_{23} \\ \epsilon_{13} \\ \epsilon_{12} \end{bmatrix}$$



$$\left\{ \begin{array}{l} \epsilon_{11} = \epsilon_{22} = 0; \epsilon_{33} \neq 0 \\ \epsilon_{12} = \epsilon_{13} = \epsilon_{23} = 0 \end{array} \right.$$

$$\sigma_{33} = \frac{(1-v) E}{(1+v)(1-2v)} \cdot \epsilon_{33}$$

M: constrained modulus
: oedometric modulus
: P-wave modulus

$$\left. \begin{array}{l} M \geq E \\ \text{for } v \geq 0 \end{array} \right\}$$

$$\sigma_{11} = \frac{v E}{(1+v)(1-2v)} \cdot \epsilon_{33} = \frac{v E}{(1+v)(1-2v)} \cdot \frac{(1+v)(1-2v)}{(1-v) E} \cdot \sigma_{33}$$

$$\sigma_{11} = \frac{v}{1-v} \sigma_{33}$$

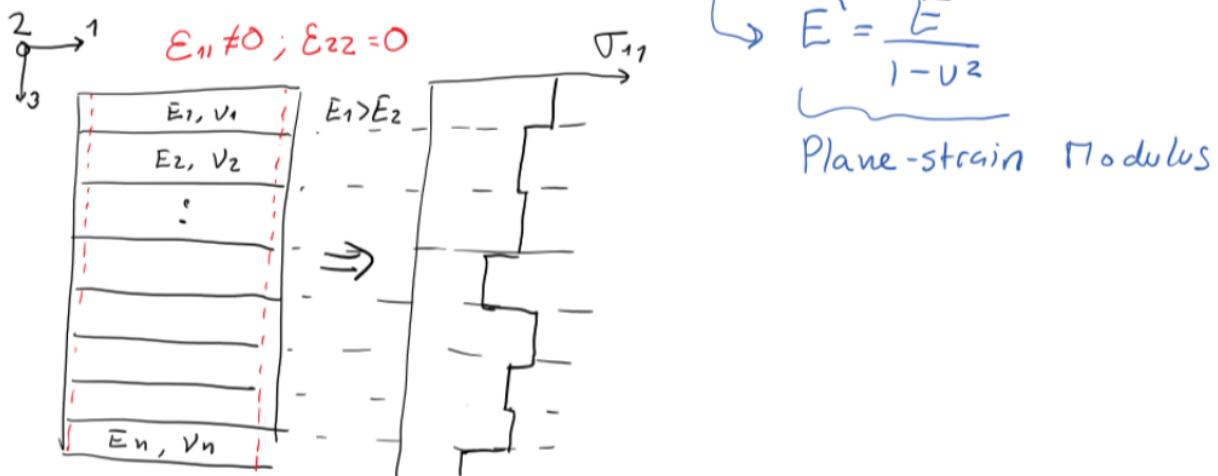
lateral effective stress coefficient
 K_o

1D Mechanical Earth Model with tectonic strains

$$\varepsilon_{33} \neq 0; \quad \varepsilon_{11} \neq 0; \quad \varepsilon_{22} \neq 0; \quad \varepsilon_{ij} = 0 \text{ for } i \neq j$$

$$\left\{ \begin{array}{l} \sigma_{11} = \frac{\nu}{1-\nu} \sigma_{33} + \frac{E}{1-\nu^2} \varepsilon_{11} + \frac{\nu E}{1-\nu^2} \varepsilon_{22} \\ \sigma_{22} = \frac{\nu}{1-\nu} \sigma_{33} + \frac{\nu E}{1-\nu^2} \varepsilon_{11} + \frac{E}{1-\nu^2} \varepsilon_{22} \end{array} \right. \rightarrow \begin{array}{l} \text{tectonic} \\ \text{strains} \\ \varepsilon_{11}, \varepsilon_{22} \end{array}$$

$$\Gamma_{33} = S_{33} - P_p$$



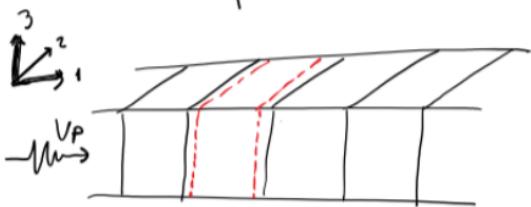
(E, V) from field and laboratory data

lab: static, dynamic

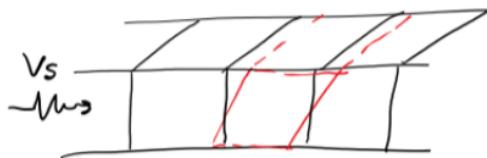
field: dynamic

$(E, V) \rightarrow$

$$V_p = \sqrt{\frac{M}{\rho_{bulk}}} \quad (\text{P-WAVE})$$

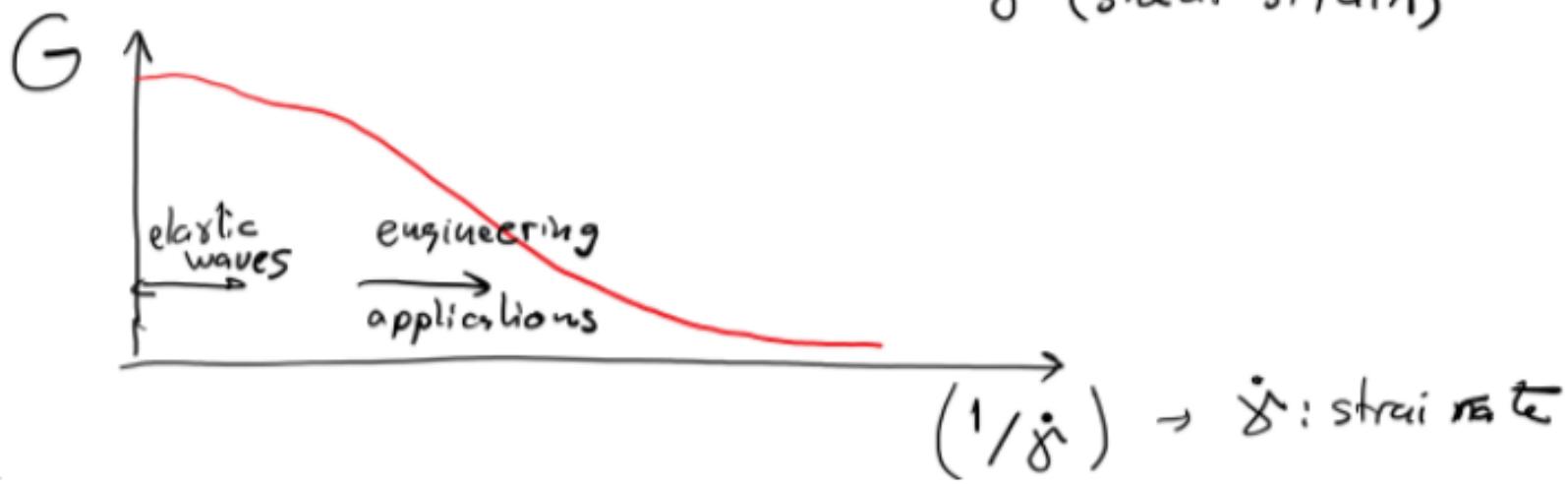
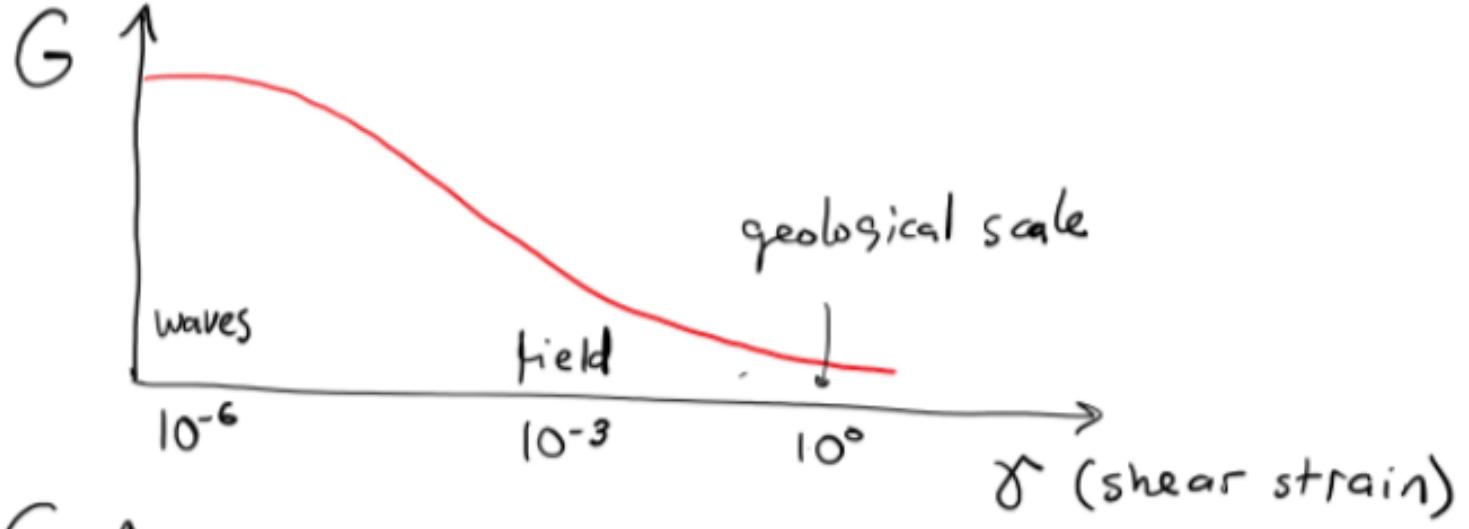


$$V_s = \sqrt{\frac{G}{\rho_{bulk}}} \quad (\text{S-WAVE})$$



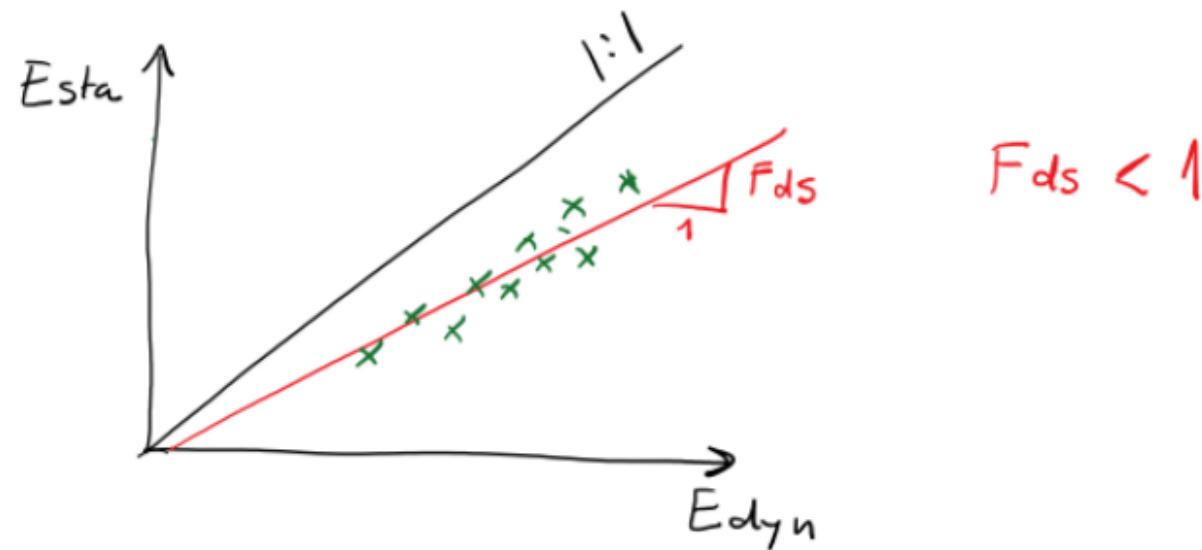
$$E_{dyn} = \rho_{bulk} V_s^2 \left(\frac{3V_p^2 - 4V_s^2}{V_p^2 - V_s^2} \right)$$

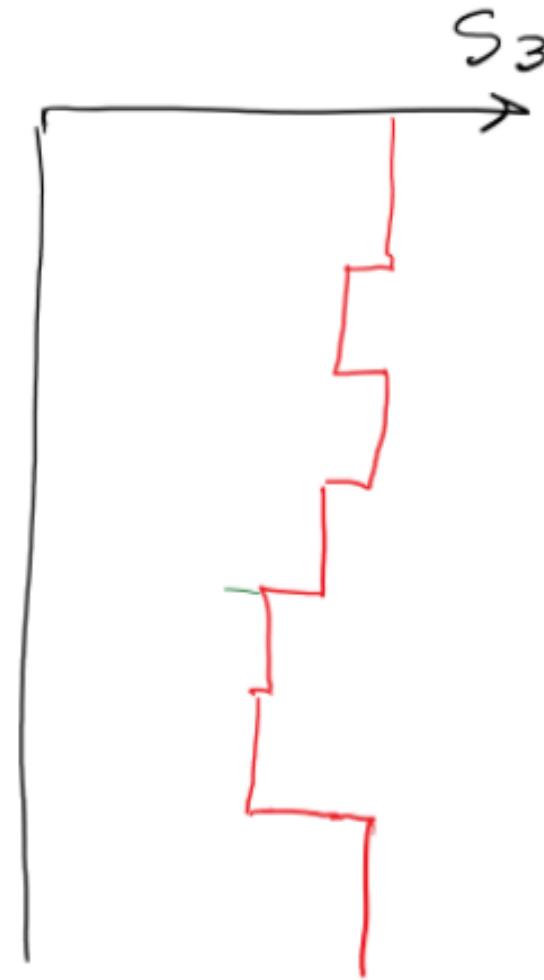
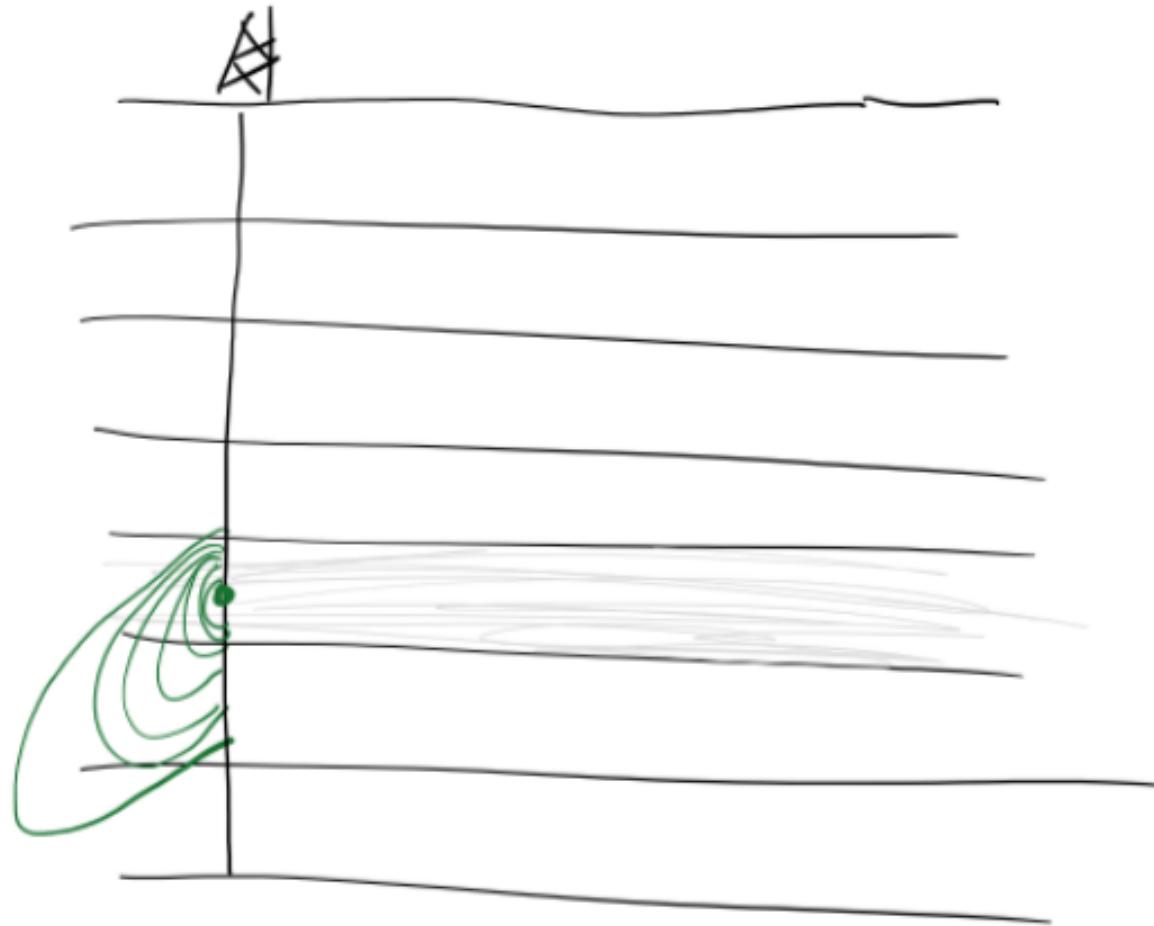
$$V_{dyn} = \frac{V_p^2 - 2V_s^2}{2(V_p^2 - V_s^2)}$$



$$E_{sta} = F_{ds} \cdot E_{dyn}$$

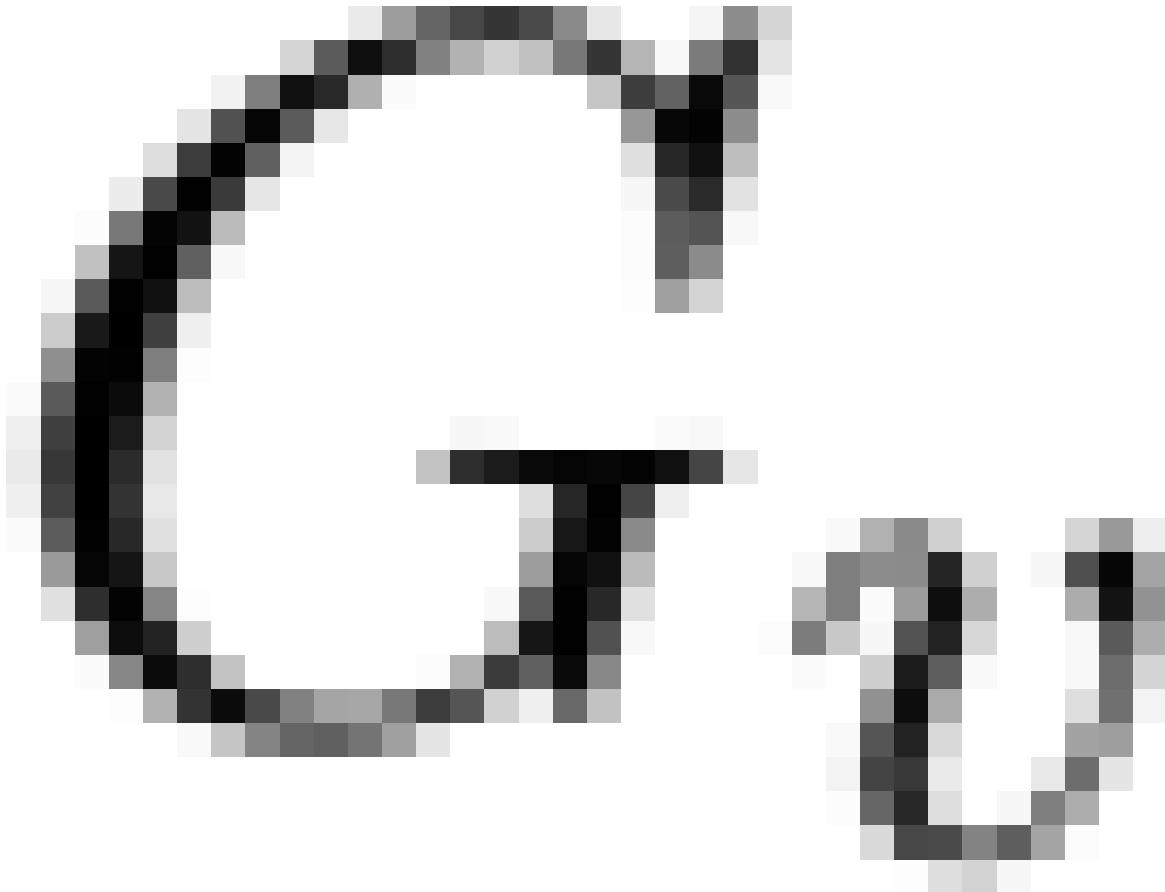
$$; V_{sta} \approx V_{dyn}$$





$$\begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ 2\varepsilon_{23} \\ 2\varepsilon_{13} \\ 2\varepsilon_{12} \end{bmatrix} = \begin{bmatrix} +\frac{1}{E_h} & -\frac{\nu_h}{E_h} & -\frac{\nu_v}{E_v} & 0 & 0 & 0 \\ -\frac{\nu_h}{E_h} & +\frac{1}{E_h} & -\frac{\nu_v}{E_v} & 0 & 0 & 0 \\ -\frac{\nu_v}{E_v} & -\frac{\nu_v}{E_v} & +\frac{1}{E_v} & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{G_v} & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{G_v} & 0 \\ 0 & 0 & 0 & 0 & 0 & \frac{1}{G_h} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix}$$

$$G_h = \frac{E_h}{2(1 + \nu_h)}$$



$$E_h = \frac{(C_{11} - C_{12}) [C_{33}(C_{11} + C_{12}) - 2C_{13}^2]}{C_{11}C_{33} - C_{13}^2}$$

E_0 $-$ C_{33} $-$ C_{11} $+$ C_{12} $2C_{13}$ $+C_{12}$

v_h $=$

$$\frac{c_{12}^1 c_{33} - c_{13}^2}{c_{11} c_{33} - c_{13}^2}$$

 $-$

$$v_0 = \frac{c_{13}}{c_{11} + c_{12}}$$



G_b

=

G₆₆

=

2

G₁₁

-

G₁₂

$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ C_{12} & C_{11} & C_{13} & 0 & 0 & 0 \\ C_{13} & C_{13} & C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{44} & 0 \\ 0 & 0 & 0 & 0 & 0 & C_{66} \end{bmatrix} \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix}$$

$$c_{11} = \frac{(E_h E_v - v^2 E_h^2) \left(\frac{1}{1 + \nu_h} E_v - 2 \nu_h E_h \right)}{\left[(1 - \nu_h) E_v - 1 \right]}$$

$$C_{33} = \frac{1}{(1 - \nu_h) E_v} \left(\frac{E_v^2 - \nu_h E_v}{E_v - 2\nu_h E_h} \right)$$

$$c_{12} = \frac{\left(\nu_v^2 E_h^2 + \nu_h E_h E_v \right)}{\left(1 - \nu_h \right) E_v - 2 \nu_v^2 E_h}$$

$$c_{13} = \frac{1}{(1 - \nu_h)E_u - 2\nu_u^2 E_h} \left(\nu_u E_h E_u \right)$$

$$\frac{G_{66}}{2} = \frac{C_{11} - C_{12}}{2} = G_h = \frac{E_h}{2(1 + \nu_b)}$$



VTI Static Elastic Properties

- Conventional Method

↳ Axisymmetric Triaxial Cell



↳ Deviatoric Loading Stress Path

$$\hookrightarrow \sigma_r = \text{cst}$$

$$\hookrightarrow \Delta(\sigma_a - \sigma_r) = \Delta\sigma_a, \quad \sigma_a \geq \sigma_r$$



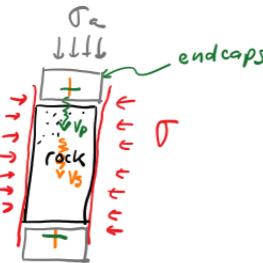
Sample	Quasi-static
Vertical 	Vertical Young modulus $E_v = \frac{\Delta\sigma_{33}}{\Delta\varepsilon_{33}} \Big _{\sigma_{11}, \sigma_{22}}$ Vertical Poisson ratio $\nu_v = -\frac{1}{2} \left(\frac{\Delta\varepsilon_{11}}{\Delta\varepsilon_{33}} + \frac{\Delta\varepsilon_{22}}{\Delta\varepsilon_{33}} \right) = -\frac{\underbrace{\Delta\varepsilon_4}_{\Delta\varepsilon_{33}}}{\underbrace{\Delta\varepsilon_{33}}} = -\frac{\Delta\varepsilon_{12}}{\Delta\varepsilon_{33}}$

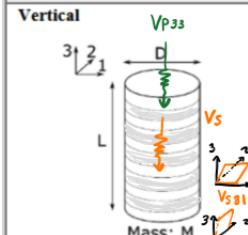
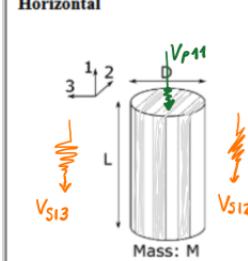
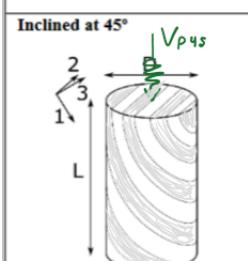
Horizontal	Quasi-static
	Horizontal Young modulus $E_h = \frac{\Delta\sigma_{11}}{\Delta\varepsilon_{11}}$ Vertical Poisson ratio $\nu_v = -\frac{\Delta\varepsilon_{33}}{\Delta\varepsilon_{11}} = \nu_{31} \quad \leftarrow = \nu_{13}$ Horizontal Poisson ratio $\nu_h = -\frac{\Delta\varepsilon_{22}}{\Delta\varepsilon_{11}} = \nu_{21} \Rightarrow = \nu_{12}$

} 4
 parameters

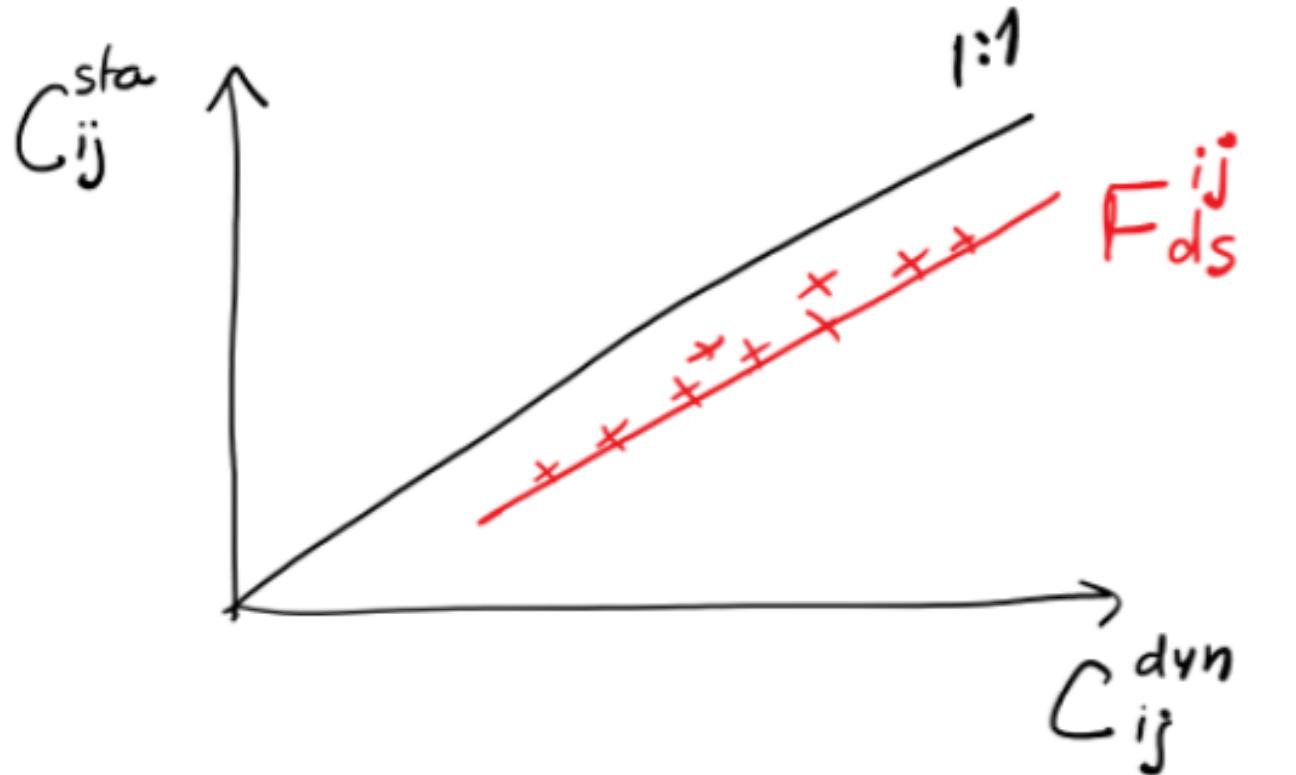
VTI Dynamic Elastic Properties

- Conventional Method



Sample	Dynamic
Vertical 	<p>P-wave stiffness perpendicular to bedding</p> $C_{33} = \rho(V_{p33})^2$ <p>S-wave stiffness perpendicular to bedding</p> $C_{44} = \frac{1}{2} [\rho(V_{s31})^2 + \rho(V_{s32})^2]$ $C_{44} = \rho(V_{s31})^2 = \rho(V_{s32})^2$
Horizontal 	<p>P-wave stiffness parallel to bedding</p> $C_{11} = \rho(V_{p11})^2$ <p>S-wave stiffness perpendicular to bedding</p> $C_{44} = \rho(V_{s13})^2$ <p>S-wave stiffness in the plane of bedding</p> $C_{66} = \rho(V_{s12})^2$
Inclined at 45° 	<p>Off-diagonal stiffness</p> $C_{13} = -C_{44} + [4\rho^2 V_{p45}^4 - 2\rho V_{p45}^2 (C_{11} + C_{33} + 2C_{44}) + (C_{11} + C_{44})(C_{33} + C_{44})]^{1/2}$

Dynamic to Static conversion



Quantification of anisotropy

Static

Young modulus anisotropy

$$\frac{E_h}{E_v} ; E_h > E_v$$

Poisson's ratio anisotropy

$$\frac{v_h}{1-v_h}$$
 } effective lateral stress coefficient

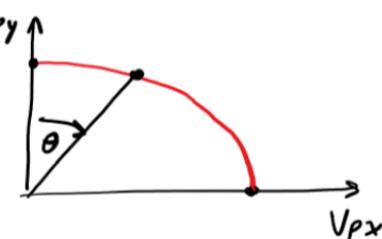
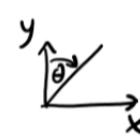
Dynamic

Thomson Parameters :

$$\epsilon = \frac{V_{p11}^2 - V_{p33}^2}{2 V_{p33}^2} = \frac{C_{11} - C_{33}}{2 C_{33}}$$

$$\gamma = \frac{C_{66} - C_{44}}{2 C_{44}}$$

$$\delta = \frac{(C_{13} + C_{44})^2 - (C_{33} - C_{44})^2}{2 C_{33} (C_{33} - C_{44})}$$



Weak anisotropy

$$V_p(\theta) = V_{p33} [1 + \delta \sin^2 \theta \cos^2 \theta + \epsilon \sin^4 \theta]$$

Iso-stress (Reuss Average)



$$\langle E_v \rangle = \frac{\sigma_v}{\langle \epsilon_v \rangle}$$

$$\hookrightarrow \langle \epsilon_v \rangle = \frac{\sigma_v}{\langle E_v \rangle} \quad (1)$$

L_{soft}, L_{stiff}

$$(2) \langle \epsilon_v \rangle = \left(\frac{\sigma_v}{E_{stiff}} \cdot L_{stiff} + \frac{\sigma_v}{E_{soft}} \cdot L_{soft} \right) \cdot \frac{1}{L_T}$$

$$= \frac{\sigma_v}{E_{stiff}} \cdot \underbrace{\frac{L_{stiff}}{L_T}}_{f_{stiff}} + \frac{\sigma_v}{E_{soft}} \cdot \underbrace{\frac{L_{soft}}{L_T}}_{f_{soft}}$$

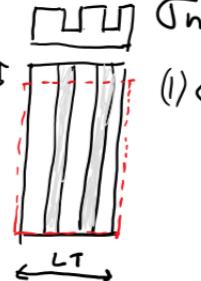
(1,2) \rightarrow

$$\frac{\sigma_v}{\langle E_v \rangle} = \frac{\sigma_v}{E_{stiff}} \cdot f_{stiff} + \frac{\sigma_v}{E_{soft}} \cdot f_{soft}$$

Iso-strain (Voigt Average)



ϵ_h



$$(2) \langle \sigma_h \rangle = \sigma_n^{soft} \cdot \underbrace{\frac{L_{soft}}{L_T}}_{f_{soft}} + \sigma_n^{stiff} \cdot \underbrace{\frac{L_{stiff}}{L_T}}_{f_{stiff}}$$

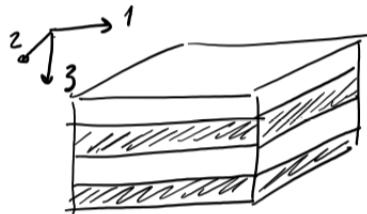
(1,2)

$$\epsilon_h \langle E_h \rangle = \epsilon_h E_{soft} \cdot f_{soft} + \epsilon_h \cdot E_{stiff} \cdot f_{stiff}$$

$$\boxed{\langle E_h \rangle = E_{soft} \cdot f_{soft} + E_{stiff} \cdot f_{stiff}}$$

$$\boxed{\langle E_v \rangle = \left(\frac{f_{stiff}}{E_{stiff}} + \frac{f_{soft}}{E_{soft}} \right)^{-1}}$$

VTI stiffness matrix



$$\begin{bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \end{bmatrix} = \begin{bmatrix} \frac{1}{E_h} & -\frac{v_h}{E_h} & -\frac{v_v}{E_v} \\ -\frac{v_h}{E_h} & \frac{1}{E_h} & -\frac{v_v}{E_v} \\ -\frac{v_v}{E_v} & -\frac{v_v}{E_v} & \frac{1}{E_v} \end{bmatrix} \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{bmatrix}$$

For isotropic loading $\sigma_{11} = \sigma_{22} = \sigma_{33} = \sigma_m$

$$\varepsilon_{11} = \varepsilon_{22} = \left(\frac{1-v_h}{E_h} - \frac{v_v}{E_v} \right) \sigma_m$$

$$\varepsilon_{33} = \left(-\frac{2v_v}{E_v} + \frac{1}{E_v} \right) \sigma_m$$

$$\varepsilon_{vol} = \left[2 \left(\frac{1-v_h}{E_h} - \frac{v_v}{E_v} \right) + \left(\frac{1-2v_v}{E_v} \right) \right] \sigma_m$$

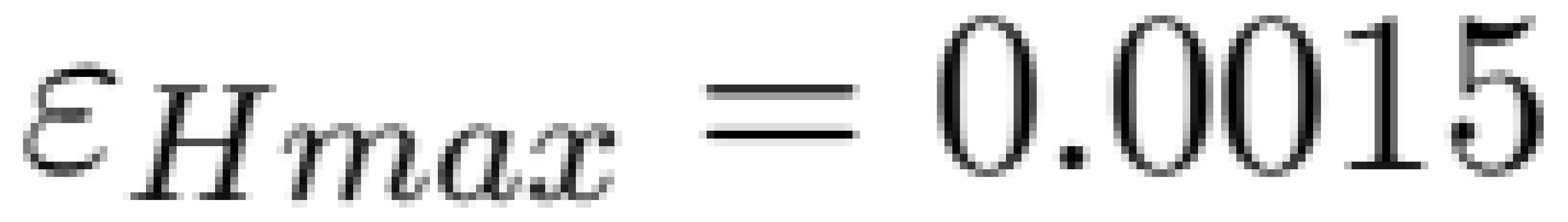
$$\rightarrow K_{VTI} = \left[\frac{2(1-v_h)}{E_h} + \frac{1-4v_v}{E_v} \right]^{-1}$$

if $v_h = v_v$; $E_h = E_v$

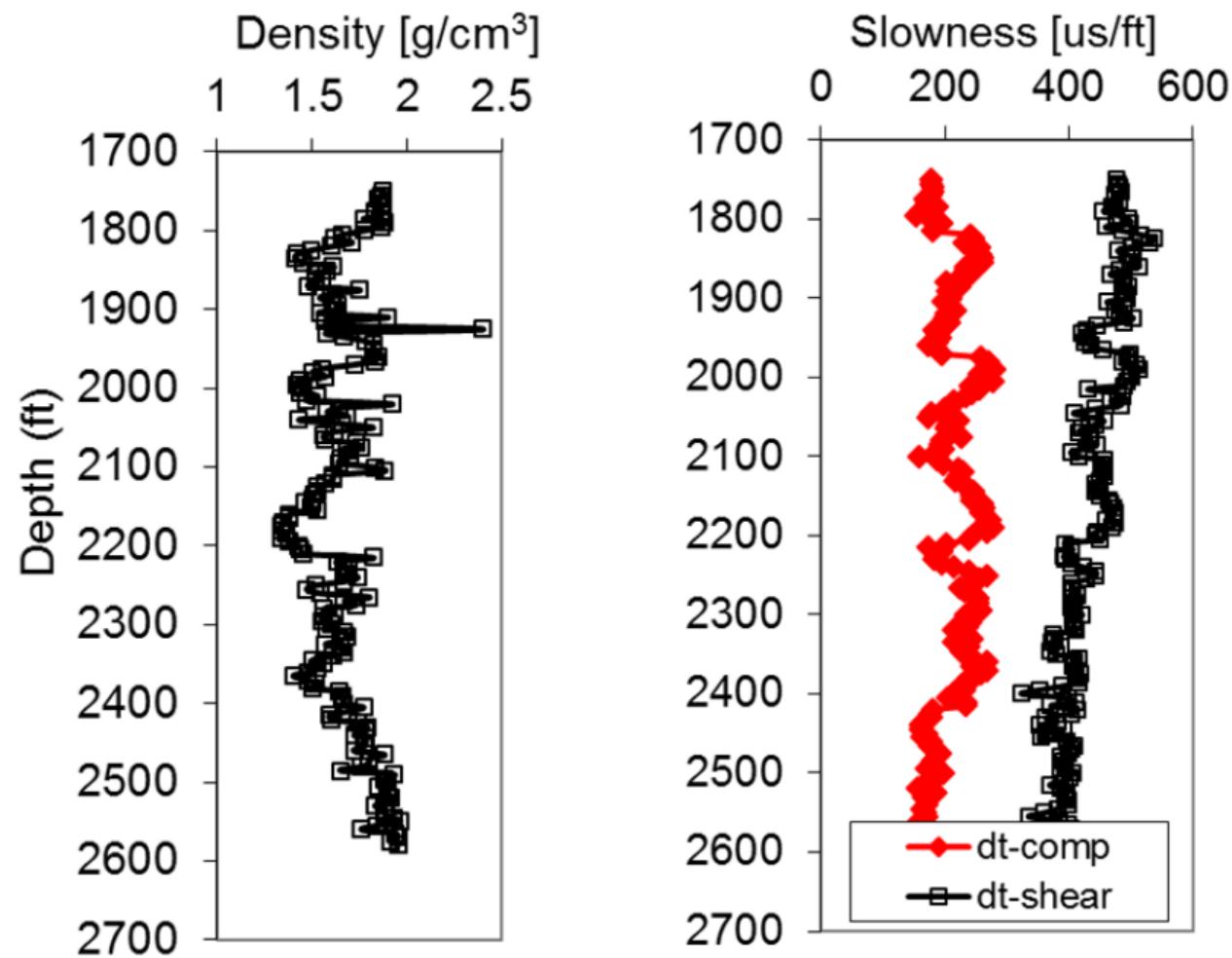
$$K = \left[\frac{2-2v+1-4v}{E} \right]^{-1} = \frac{E}{3(1-2v)} \quad \checkmark$$







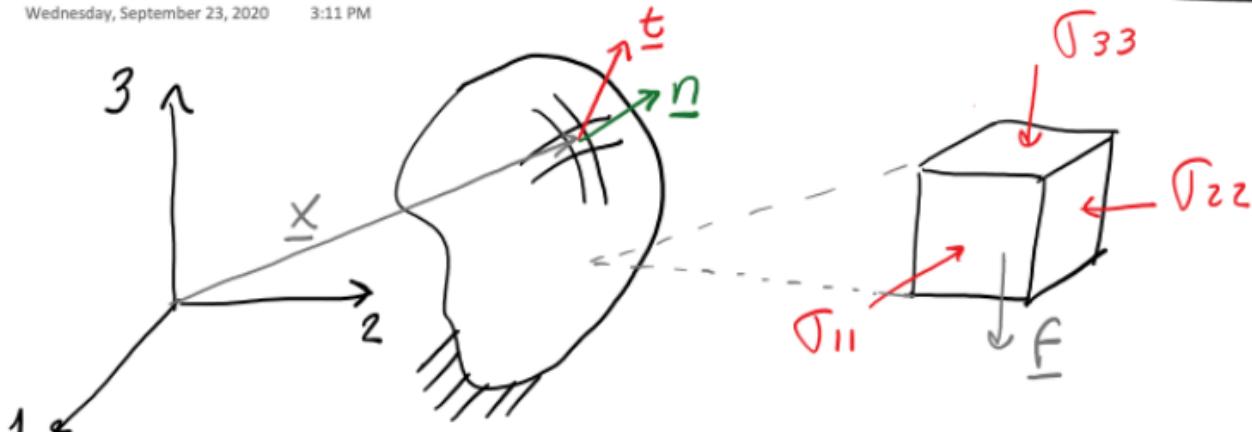




2- General solution for a continuum mechanics problem

Wednesday, September 23, 2020

3:11 PM



① Equilibrium : $\nabla \cdot \underline{\underline{\sigma}} + \underline{F} = 0$

② Kinematic : $\underline{\underline{\epsilon}} = \frac{1}{2} (\nabla \underline{u} + \nabla \underline{u}^\top) \rightarrow \text{small strains}$

③ Constitutive : $\underline{\underline{\sigma}} = \underline{\underline{C}} \cdot \underline{\underline{\epsilon}}$ \rightarrow linear elasticity

Plan : ① → ③ → ②

$$①, \text{Coordinate 1: } \frac{\partial \sigma_{11}}{\partial x_1} + \frac{\partial \sigma_{12}}{\partial x_2} + \frac{\partial \sigma_{13}}{\partial x_3} + f_1 = 0$$

$$\underline{\sigma} = \underline{C} \cdot \underline{\epsilon} \Rightarrow \begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{23} \\ \sigma_{13} \\ \sigma_{12} \end{bmatrix} = \left[\begin{array}{ccc|c} \lambda + 2\mu & \lambda & \lambda & 0 \\ \lambda & \lambda + 2\mu & \lambda & 0 \\ \lambda & \lambda & \lambda + 2\mu & 0 \\ \hline 0 & 0 & 0 & \nu \\ 0 & 0 & 0 & 2\nu \\ 0 & 0 & \nu & 2\nu \end{array} \right] \begin{bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ 2\epsilon_{23} \\ 2\epsilon_{13} \\ 2\epsilon_{12} \end{bmatrix}; \quad \begin{aligned} \lambda &= \frac{\nu E}{(1+\nu)(1-2\nu)} \\ \nu &= \frac{E}{2(1+\nu)} = G \end{aligned}$$

$$\frac{\partial}{\partial x_1} (\lambda(\epsilon_{11} + \epsilon_{22} + \epsilon_{33}) + 2\nu \epsilon_{11}) + \frac{\partial}{\partial x_2} (2\nu \epsilon_{12}) + \frac{\partial}{\partial x_3} (2\nu \epsilon_{13}) + f_1 = 0$$

$$\frac{\partial}{\partial x_1} \left(\lambda \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) + 2\nu \frac{\partial u_1}{\partial x_1} \right) + \frac{\partial}{\partial x_2} \left(2\nu \frac{1}{2} \left(\frac{\partial u_1}{\partial x_2} + \frac{\partial u_2}{\partial x_1} \right) \right) + \frac{\partial}{\partial x_3} \left(2\nu \frac{1}{2} \left(\frac{\partial u_1}{\partial x_3} + \frac{\partial u_3}{\partial x_1} \right) \right) + f_1 = 0$$

$$\lambda \left[\frac{\partial}{\partial x_1} \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) \right] + 2\nu \frac{\partial^2 u_1}{\partial x_1^2} + \nu \frac{\partial^2 u_1}{\partial x_2^2} + \nu \frac{\partial}{\partial x_2} \left(\frac{\partial u_2}{\partial x_1} \right) + \nu \frac{\partial^2 u_1}{\partial x_3^2} + \nu \frac{\partial^2 u_3}{\partial x_3 \partial x_1} + f_1 = 0 \quad \leftarrow \frac{\partial^2 f(x, y)}{\partial x \partial y} = \frac{\partial^2 f(x)}{\partial y \partial x}$$

$$\lambda \left[\frac{\partial}{\partial x_1} \left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right) \right] + \nu \underbrace{\left(\frac{\partial^2 u_1}{\partial x_1^2} + \frac{\partial^2 u_1}{\partial x_2^2} + \frac{\partial^2 u_1}{\partial x_3^2} \right)}_{\nabla^2 u_1} + \nu \frac{\partial}{\partial x_1} \underbrace{\left(\frac{\partial u_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \frac{\partial u_3}{\partial x_3} \right)}_{\nabla \cdot \underline{u}} + f_1 = 0$$

$$\lambda \frac{\partial}{\partial x_1} (\nabla \cdot \underline{u}) + \nu \frac{\partial}{\partial x_1} (\nabla \cdot \underline{u}) + \nu \nabla^2 \underline{u}_1 + f_1 = 0 \Rightarrow \text{Coord. 1}$$

$$\boxed{(\lambda + \nu) \nabla (\nabla \cdot \underline{u}) + \nu \nabla^2 \underline{u} + \underline{f} = \underline{0}} \quad \underline{u}: \text{unknown}$$

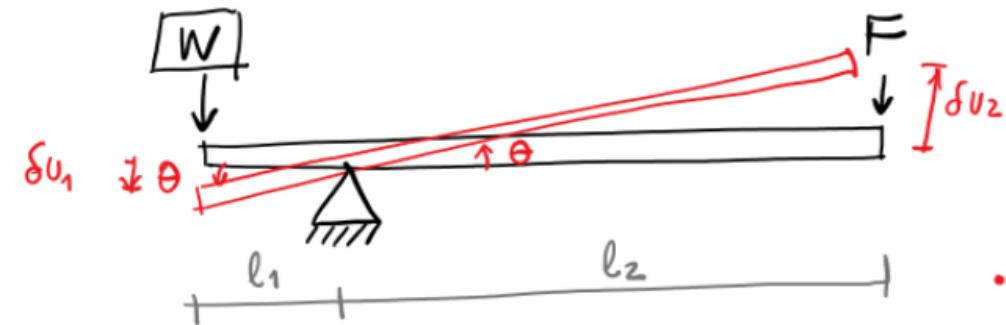
Navier's Equation

Solution

- Analytical
↓
simple boundary conditions
 - Beltrami-Mitchell (strain compatibility)
 - $\underline{U} \rightarrow \underline{\underline{\epsilon}}$ ✓
 - $\underline{\underline{\epsilon}} \rightarrow U$ ✗
 - Airy's functions
 - $\nabla^4 \varphi = 0 ; \left| \sigma_{ii} = \frac{\partial^2 \varphi}{\partial x_i^2} \right.$
 - Green functions (convolution): Boussinesq
 - Examples: Kirsch, Griffith, Sneddon
- Numerical
 - Finite differences; FLAC-Itasca
 - Finite Element Method (FEM): Abaqus
FreeFEM++
FEniCS
Comsol

Weak formulation of continuum mechanics equations

Analogy with virtual work



• Solution #1: Angular Momentum
 E_{ang}

$$W \cdot l_1 = F \cdot l_2$$

$$F = \frac{l_1}{l_2} \cdot W$$

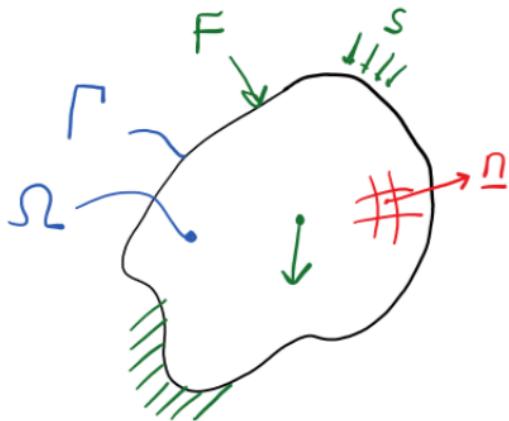
• Solution #2: Energy Conservation \leftrightarrow

Principle
of
Virtual
Work

$$W \cdot \underline{\delta u_1} = F \cdot \underline{\delta u_2}$$

$$W \cdot (l_1 \cdot \tan \theta) = F \cdot (l_2 \tan \theta)$$

$$F = \frac{l_1}{l_2} \cdot W$$



$$\text{Equil: } \nabla \cdot \underline{\underline{\Sigma}} + \underline{F} = \underline{0}$$

$$-\nabla \cdot \underline{\underline{\Sigma}} = \underline{F}$$

$$\int_{\Omega} (\delta \underline{U}) \cdot (-\nabla \cdot \underline{\underline{\Sigma}}) = \int_{\Omega} \delta \underline{U} \cdot \underline{F}$$

virtual displacement

Green's Theorem

$$\int_{\Omega} \nabla \delta \underline{U} \cdot \underline{\underline{\Sigma}} - \int_{\Gamma} \delta \underline{U} \cdot (\underline{\underline{\Sigma}} \cdot \underline{n}) = \int_{\Omega} \delta \underline{U} \cdot \underline{F}$$

- Variational form
- Weak form

$$\int_{\Omega} \underline{\epsilon}(\nabla \delta \underline{U}) : \underline{\underline{\Sigma}}(u) = \int_{\Gamma} \delta \underline{U} \cdot (\underline{\underline{\Sigma}}(u) \cdot \underline{n}) + \int_{\Omega} \delta \underline{U} \cdot \underline{F}$$

strain energy
stress boundary condition
body force

Unknowns: \underline{u} ; $\delta \underline{U}$
 actual virtual
 displacement displacement

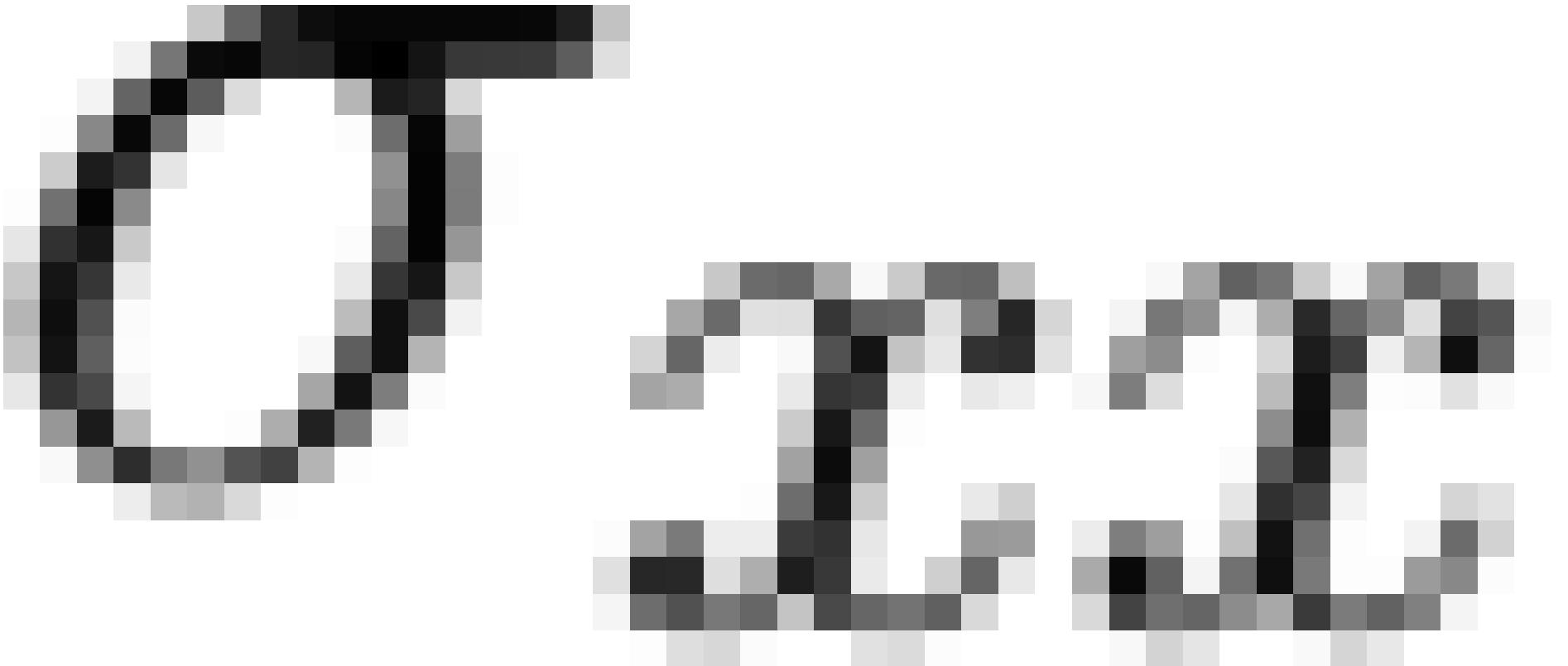
$$\mathcal{E}(\nabla \delta \mathbf{u}) : \underline{\underline{\Gamma}}(\underline{\underline{u}}) = \underline{\underline{\xi}}_{11} \cdot \underline{\underline{\Gamma}}_{11} + \underline{\underline{\xi}}_{22} \cdot \underline{\underline{\Gamma}}_{22} + \underline{\underline{\xi}}_{33} \cdot \underline{\underline{\Gamma}}_{33} + \underline{\underline{\xi}}_{12} \cdot \underline{\underline{\Gamma}}_{12} + \dots$$

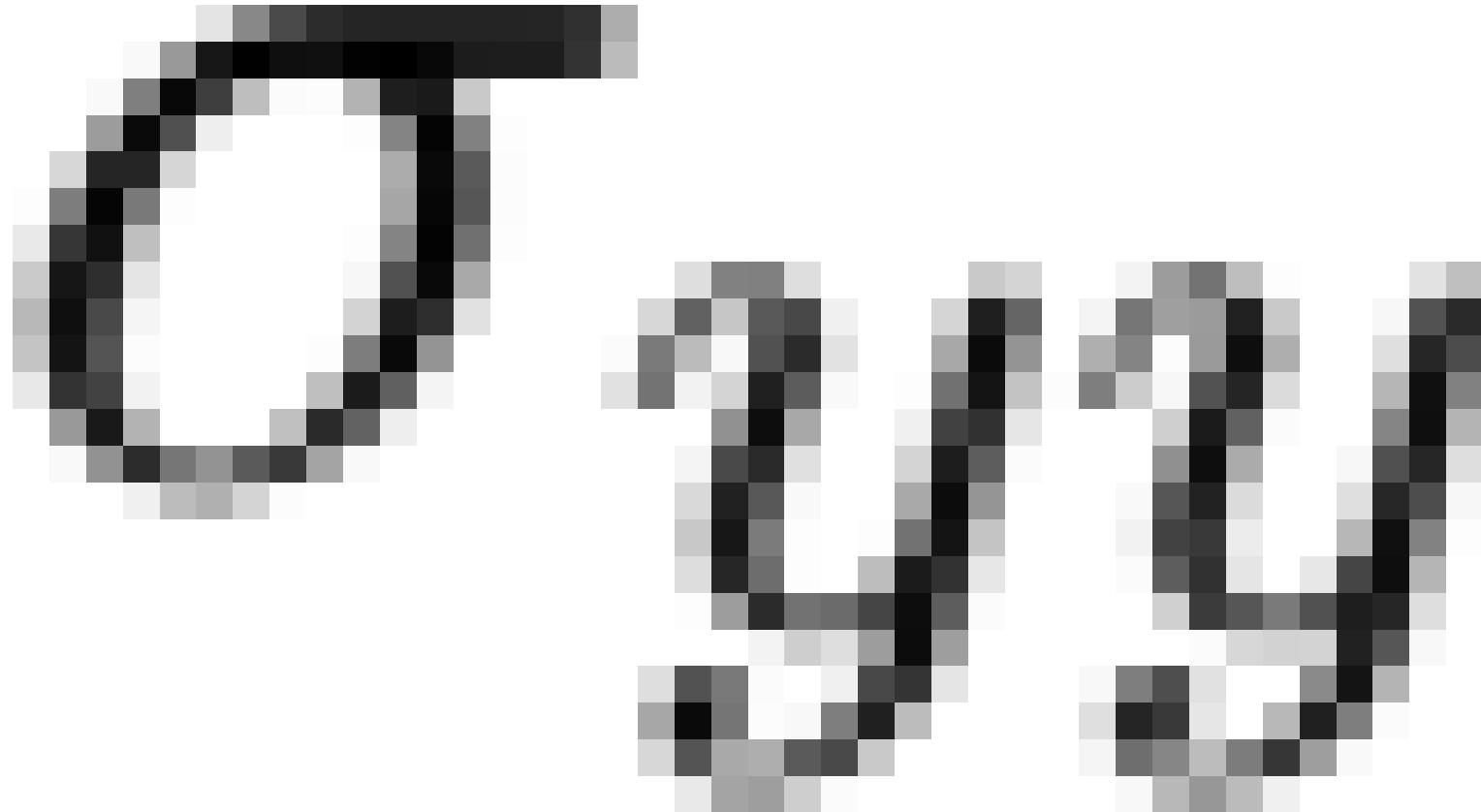
$$\rightarrow E = p \cdot V \quad (\text{Energy})$$

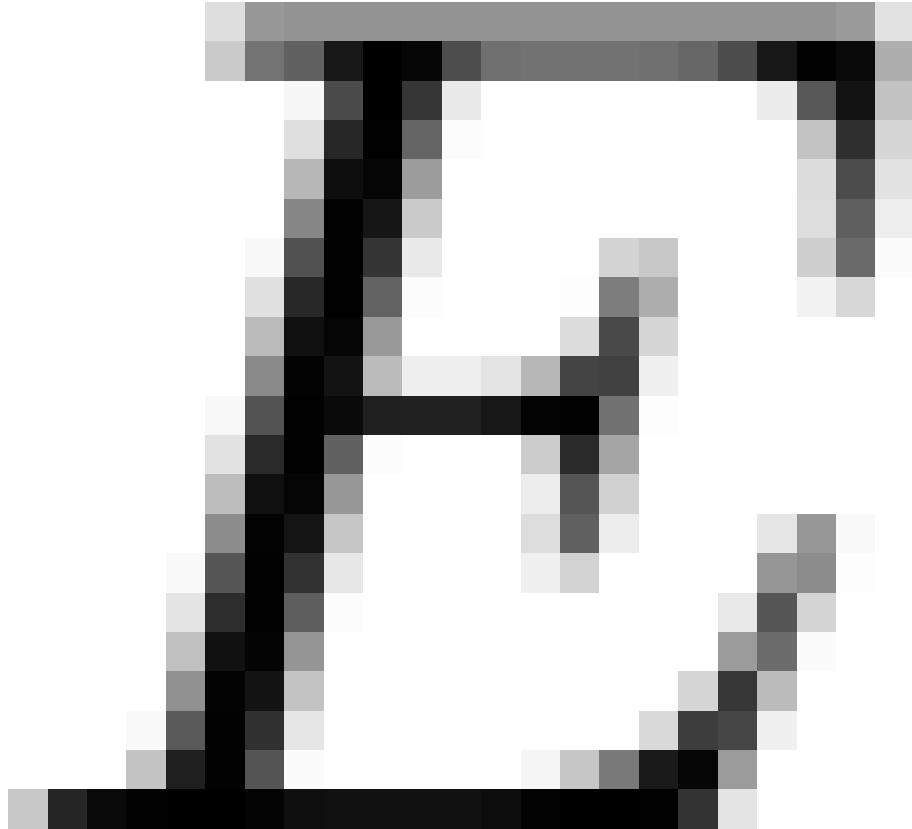
$$E = \sigma \cdot \underbrace{\frac{dV}{V}}_{\epsilon} \quad (\text{Energy per unit of volume})$$

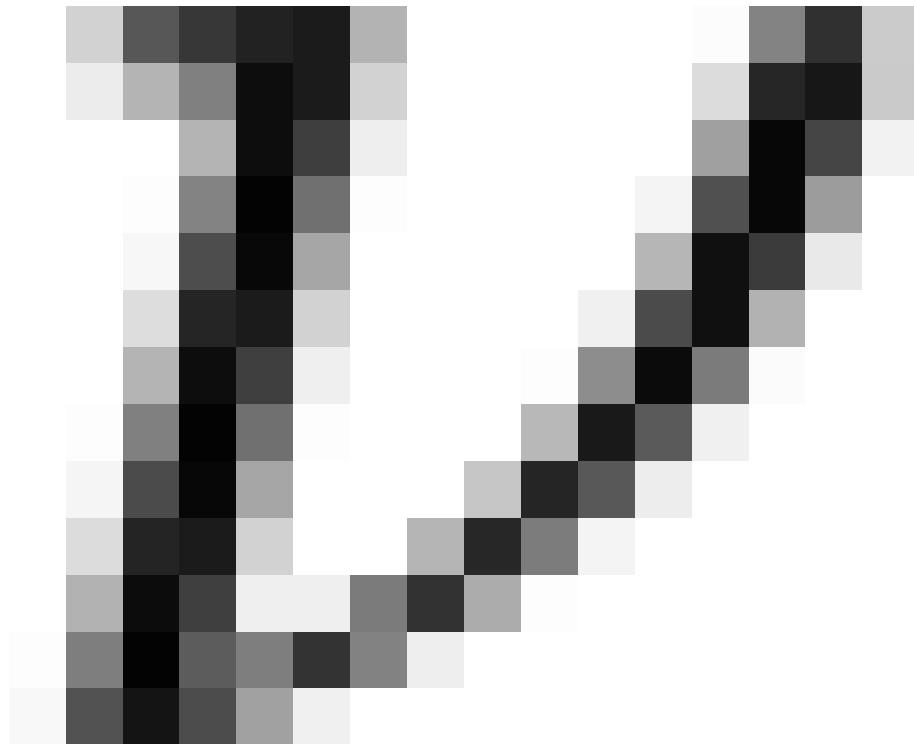
$$\int_{\Omega} \mathcal{E}(\nabla \delta \mathbf{u}) : \underline{\underline{\Gamma}}(\underline{\underline{u}}) = \int_{\Omega} \mathcal{E}(\nabla \delta \mathbf{u}) : [\underline{\underline{C}} \cdot \underline{\underline{e}}(\underline{\underline{u}})]$$

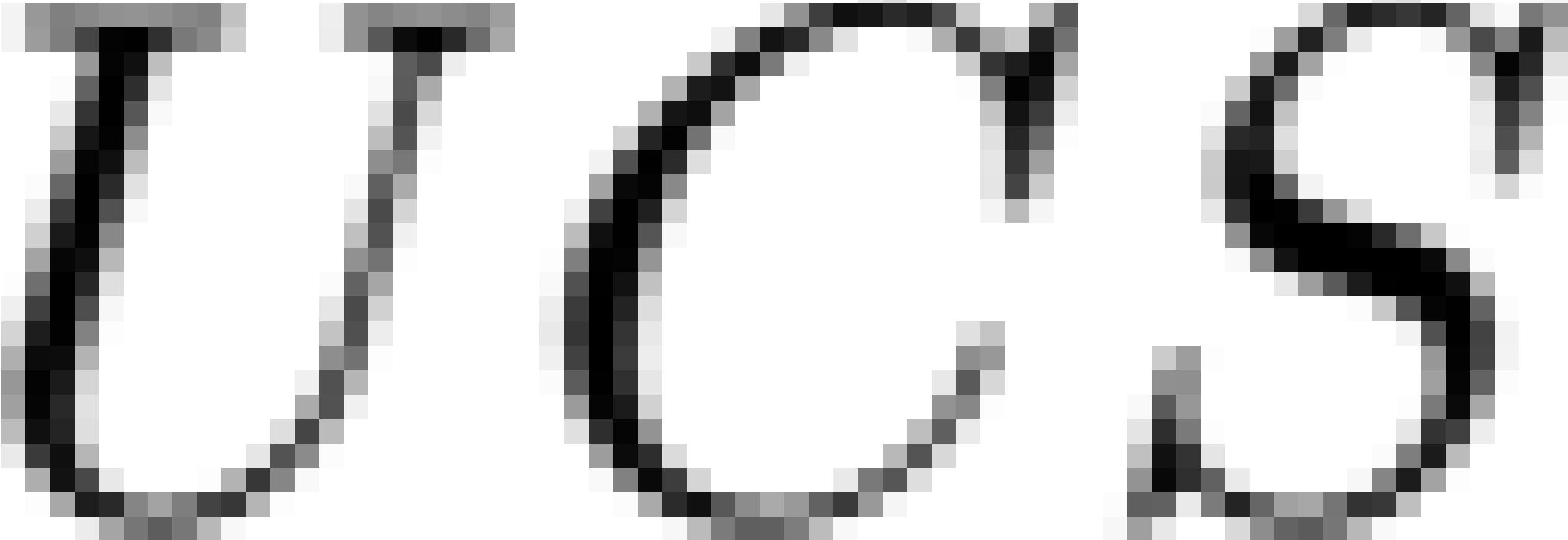
constitutive equation

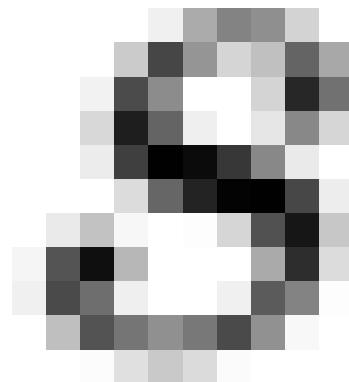
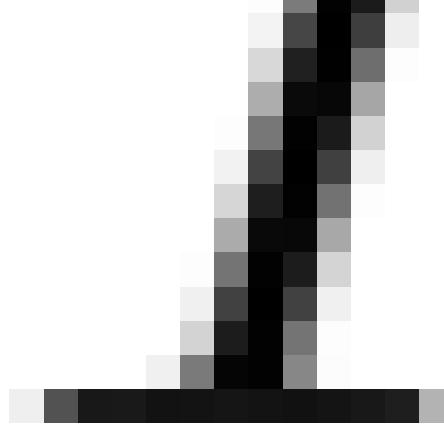
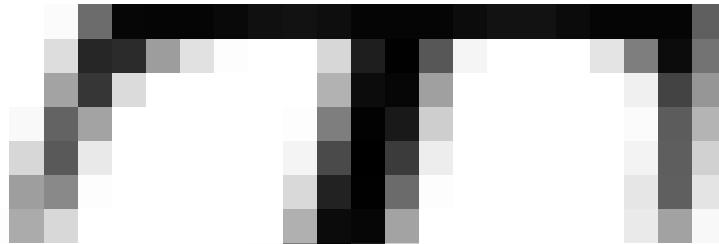


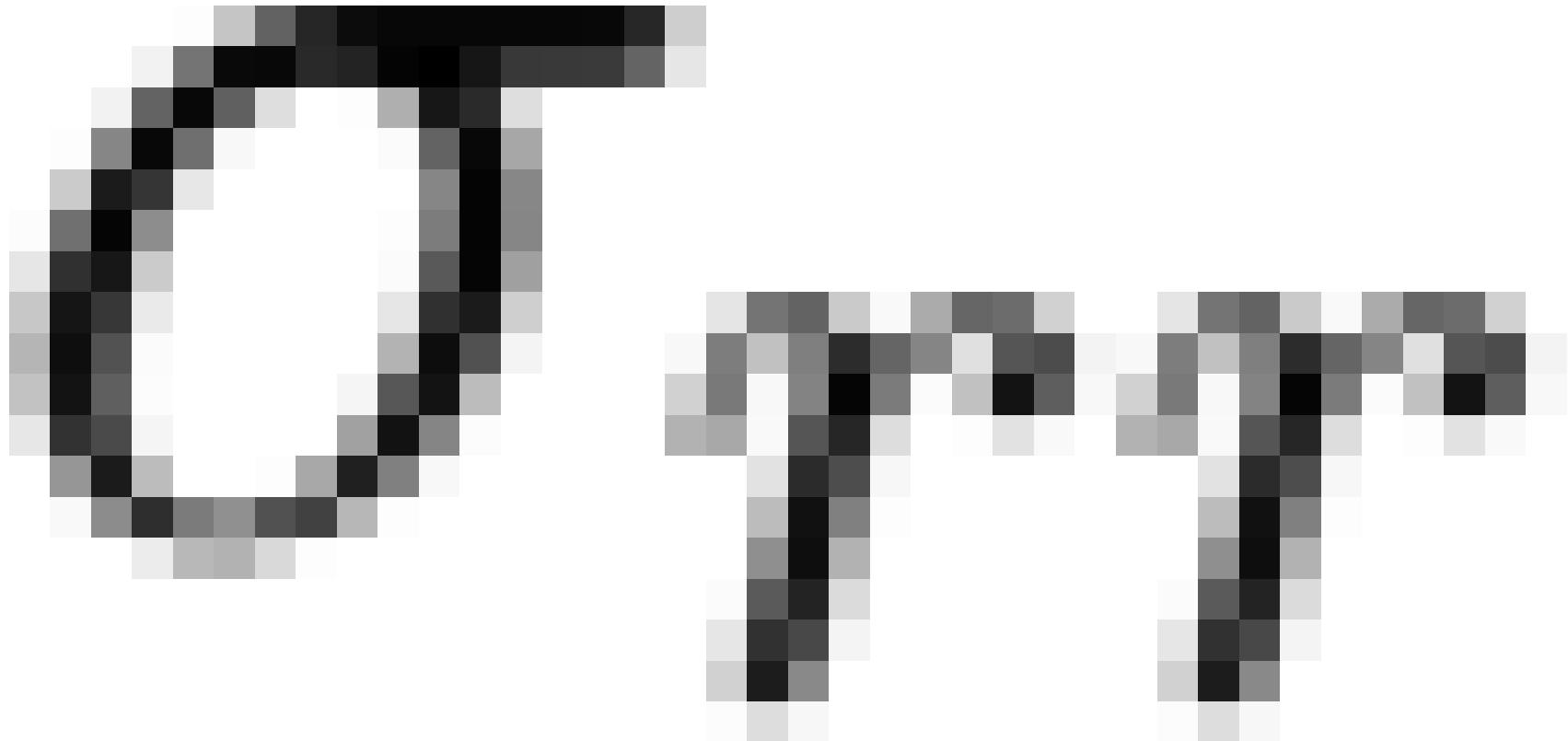


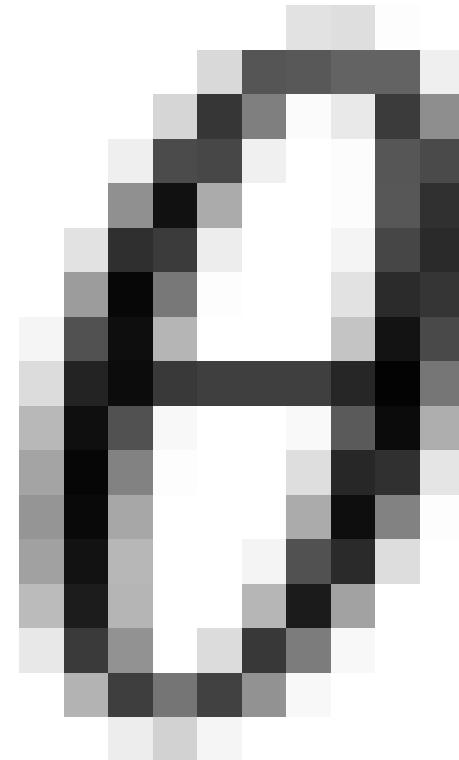
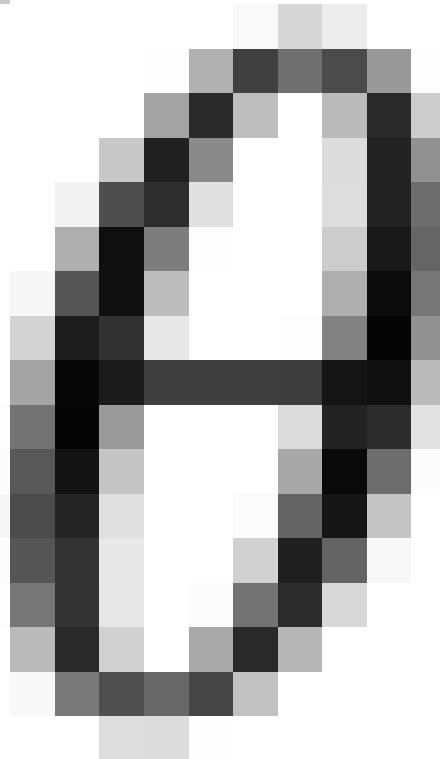
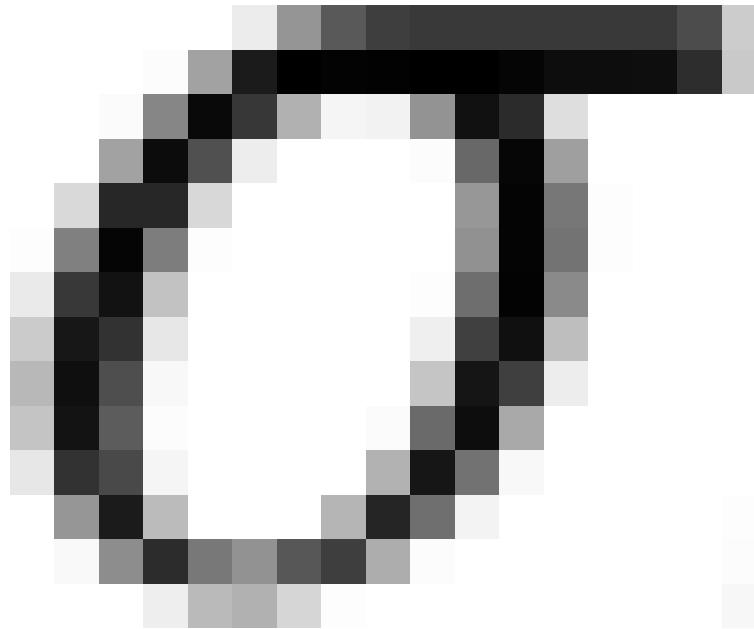


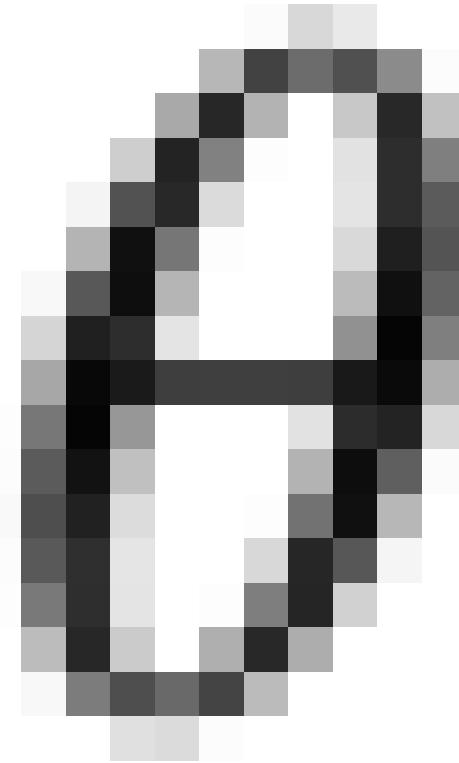
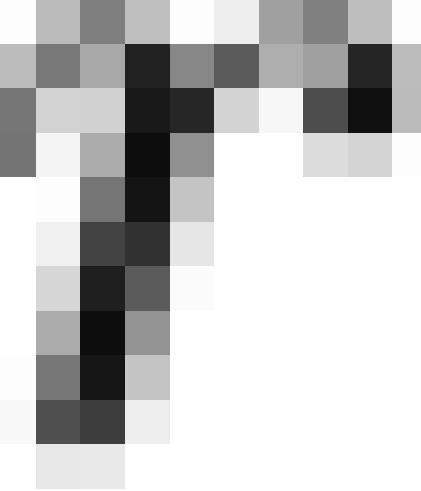
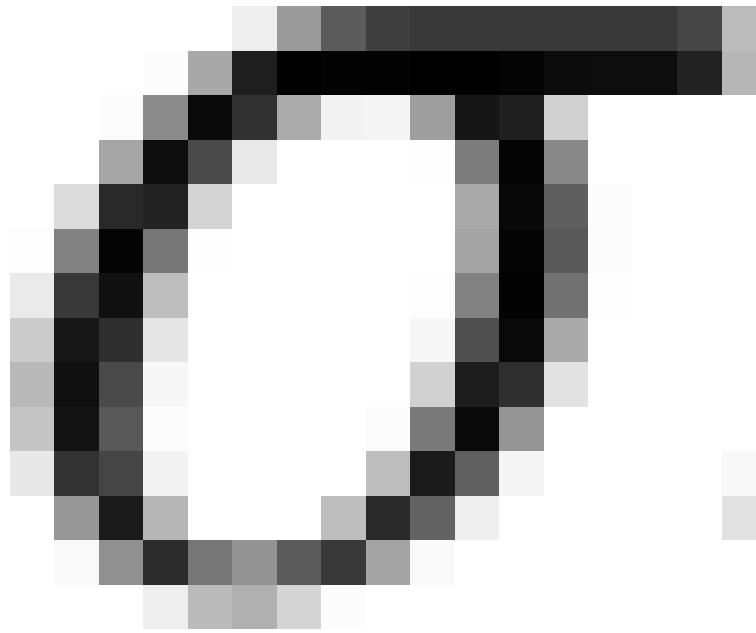


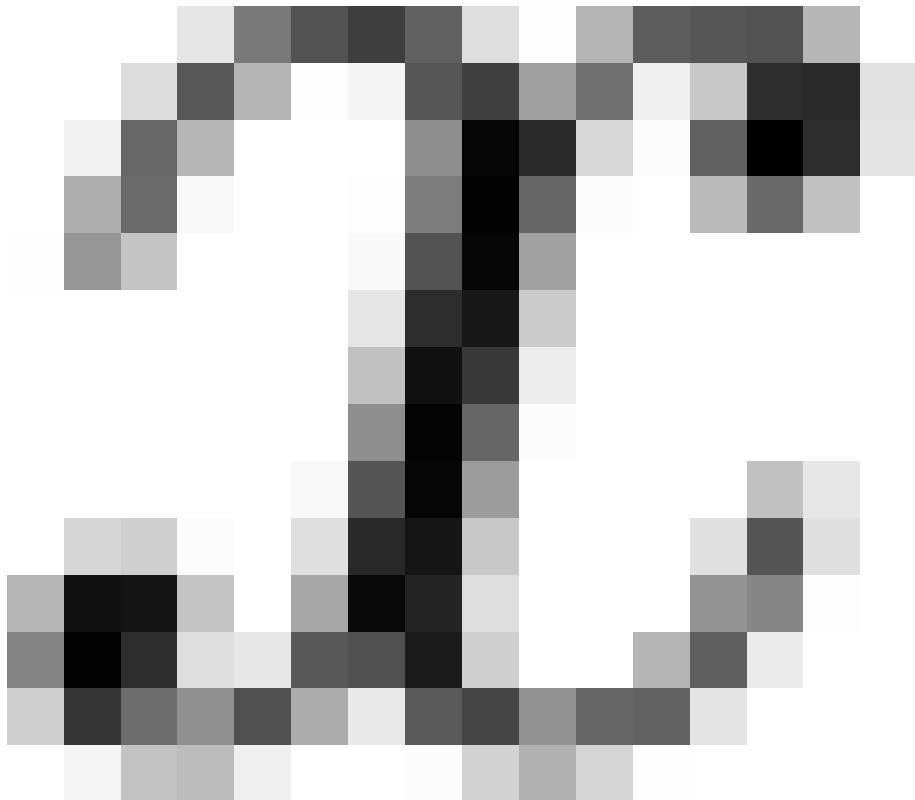


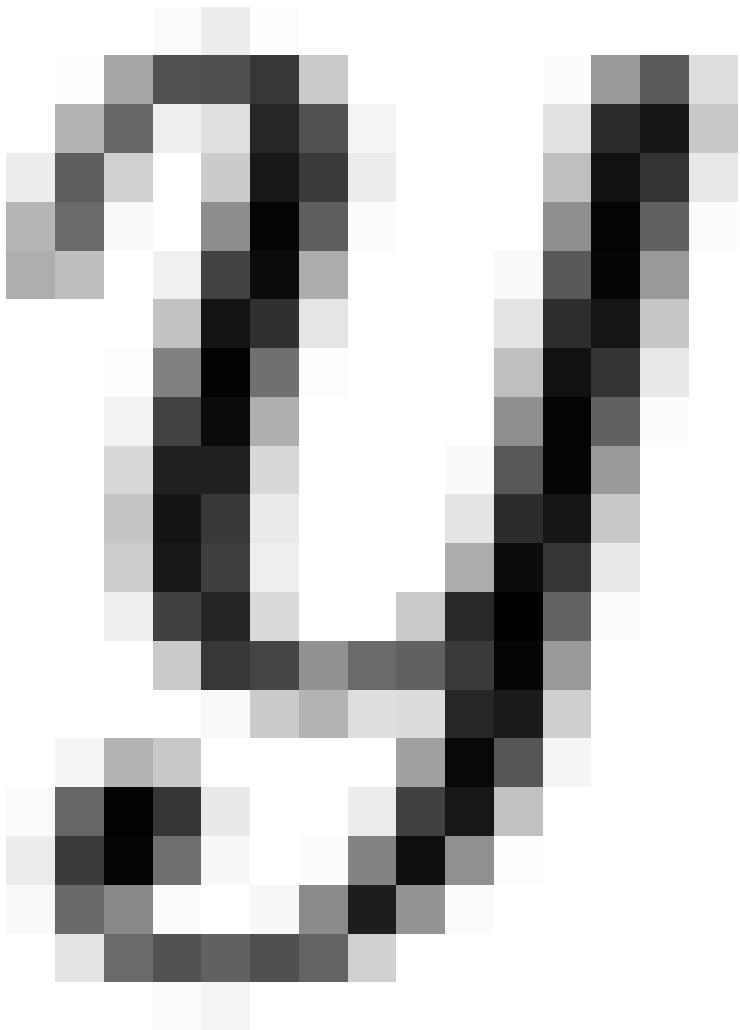


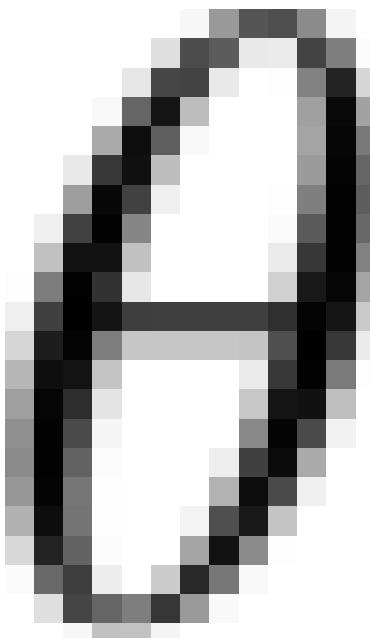
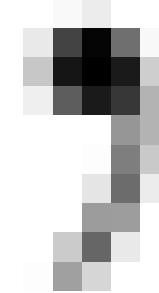
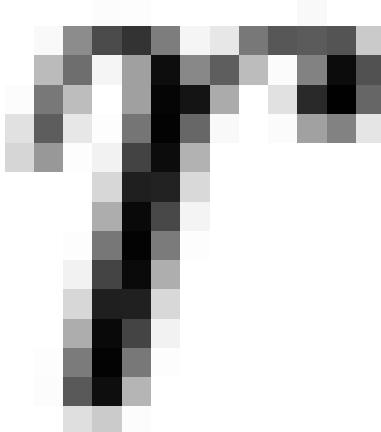
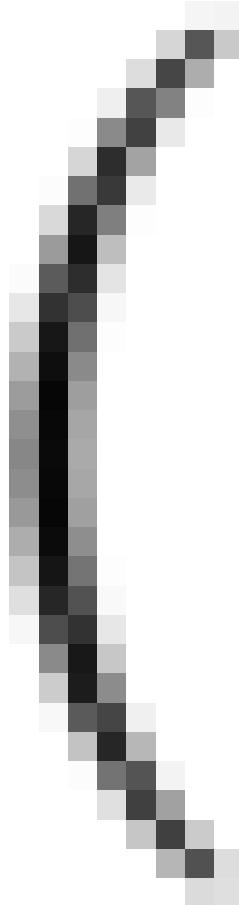






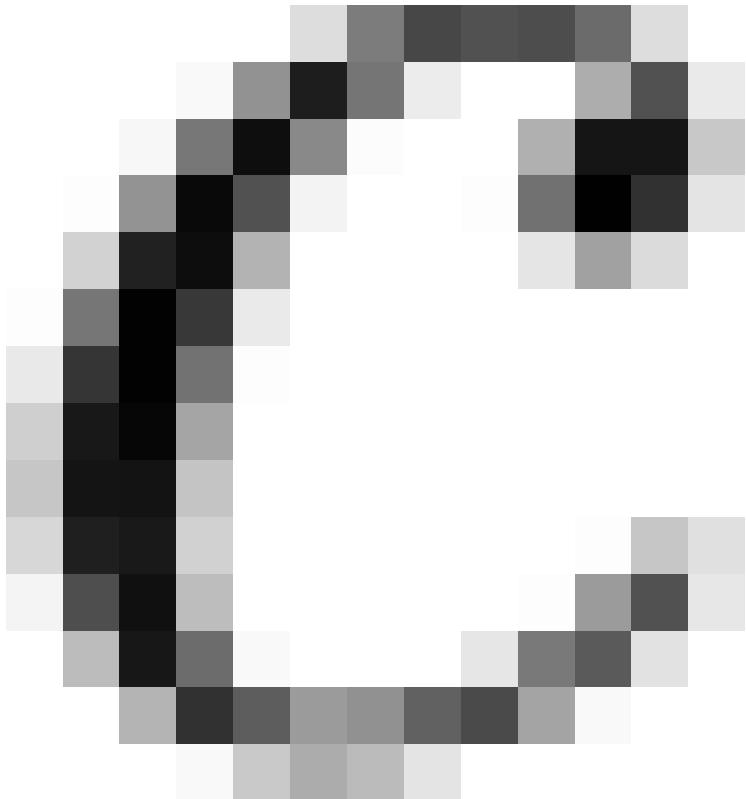


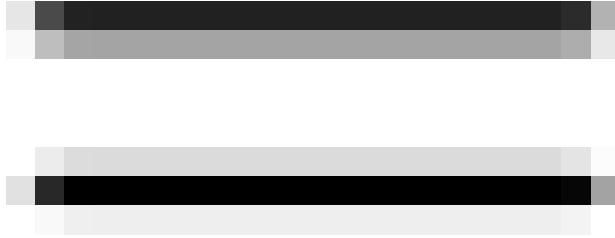
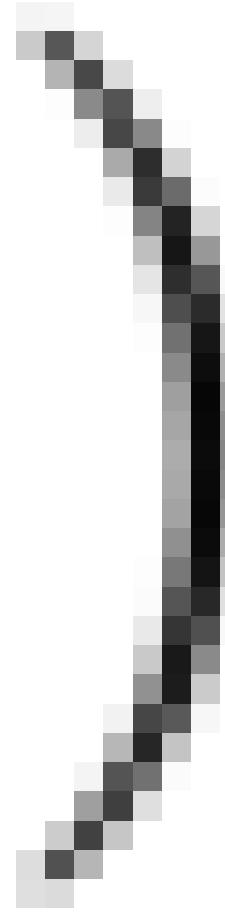
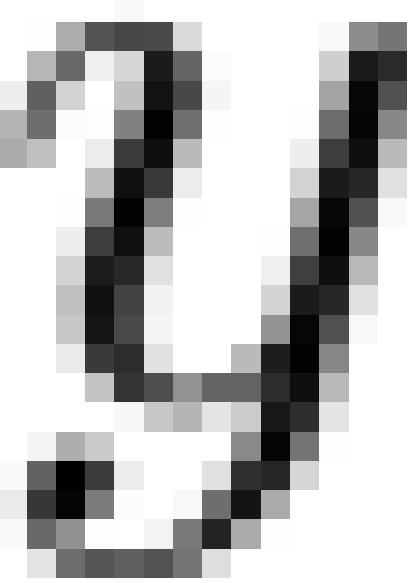
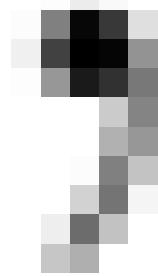
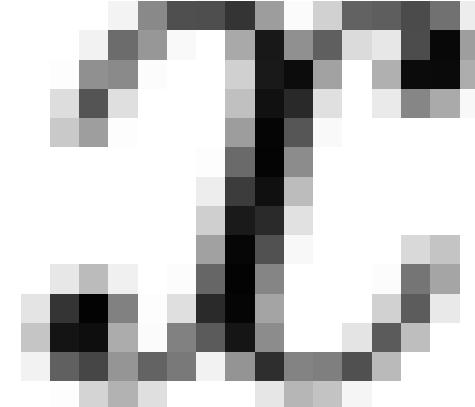
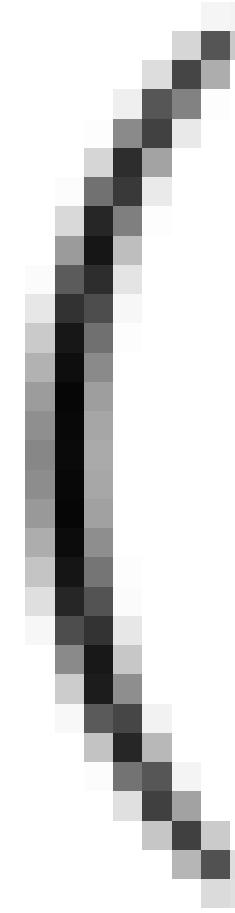




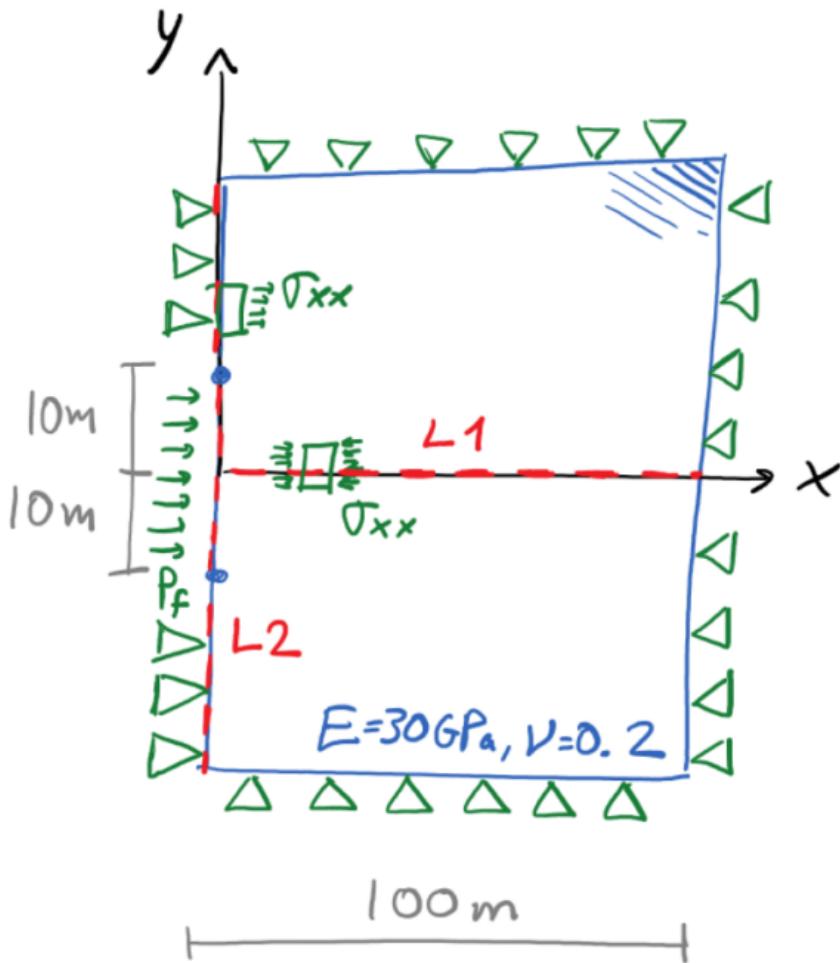
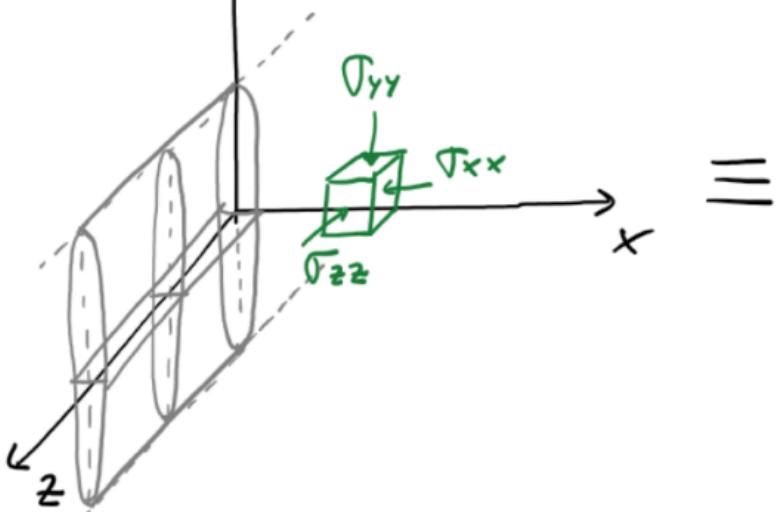


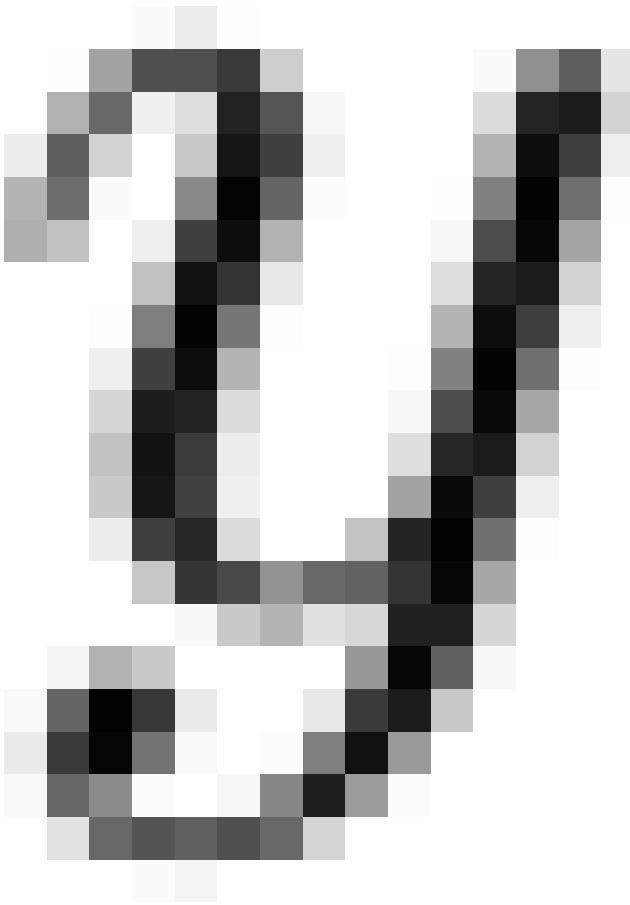






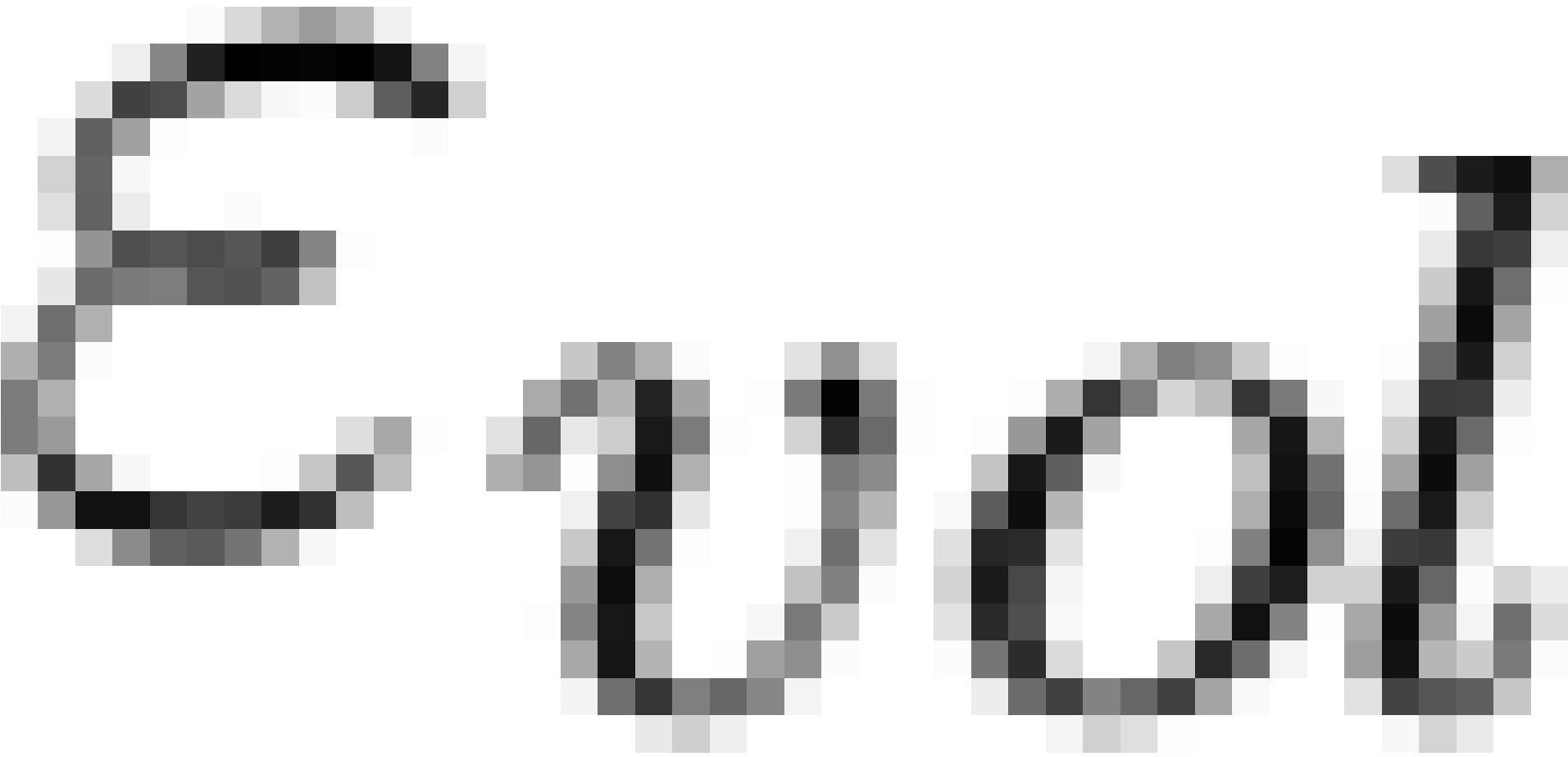
y
 Fracture length in z
 >> fracture length in y
 \Rightarrow Plane strain in (x, y)



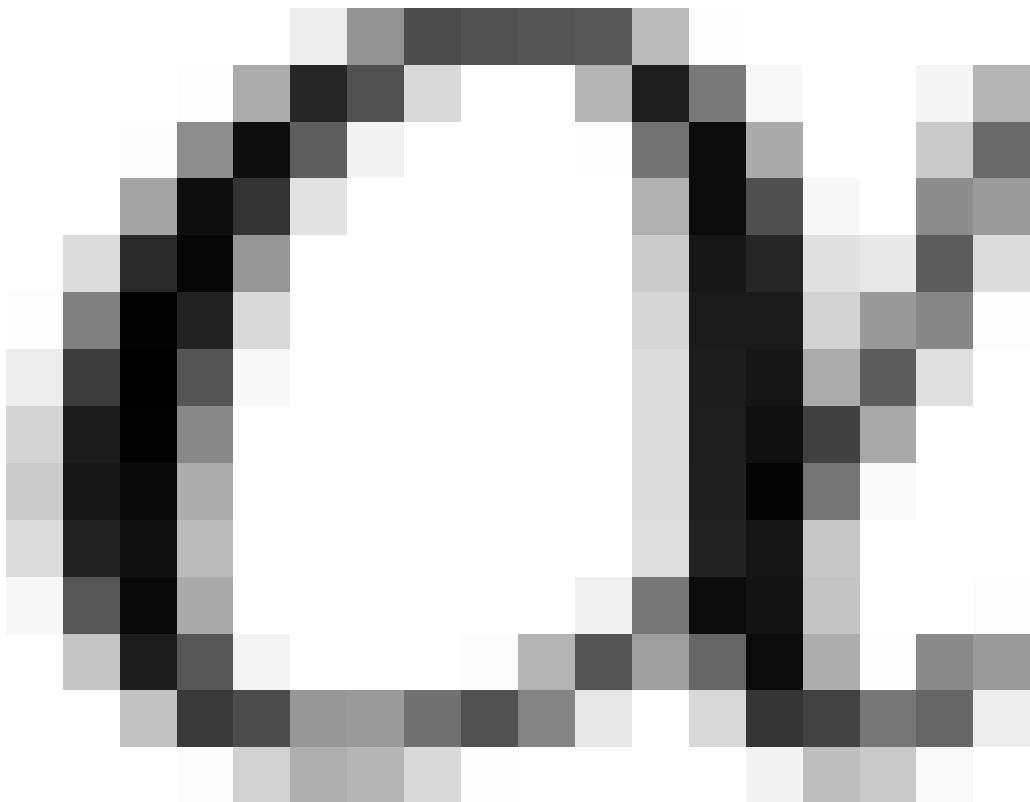




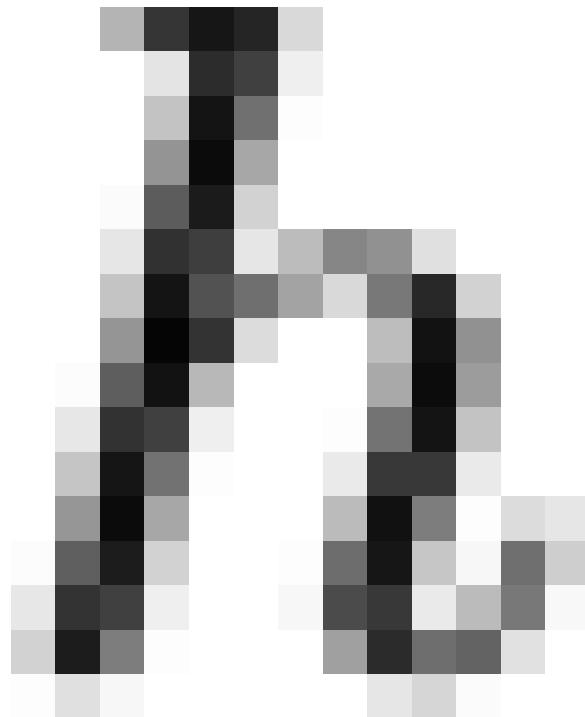
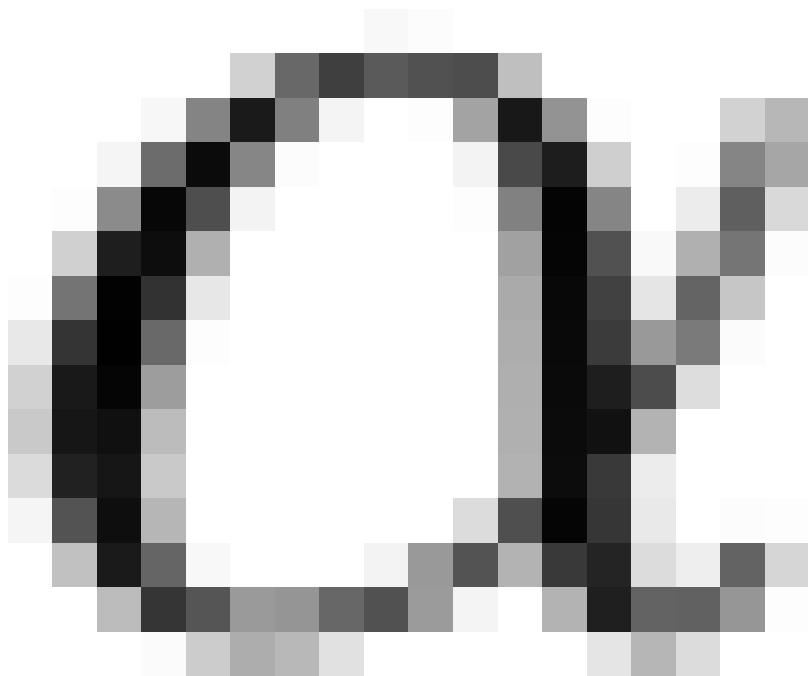


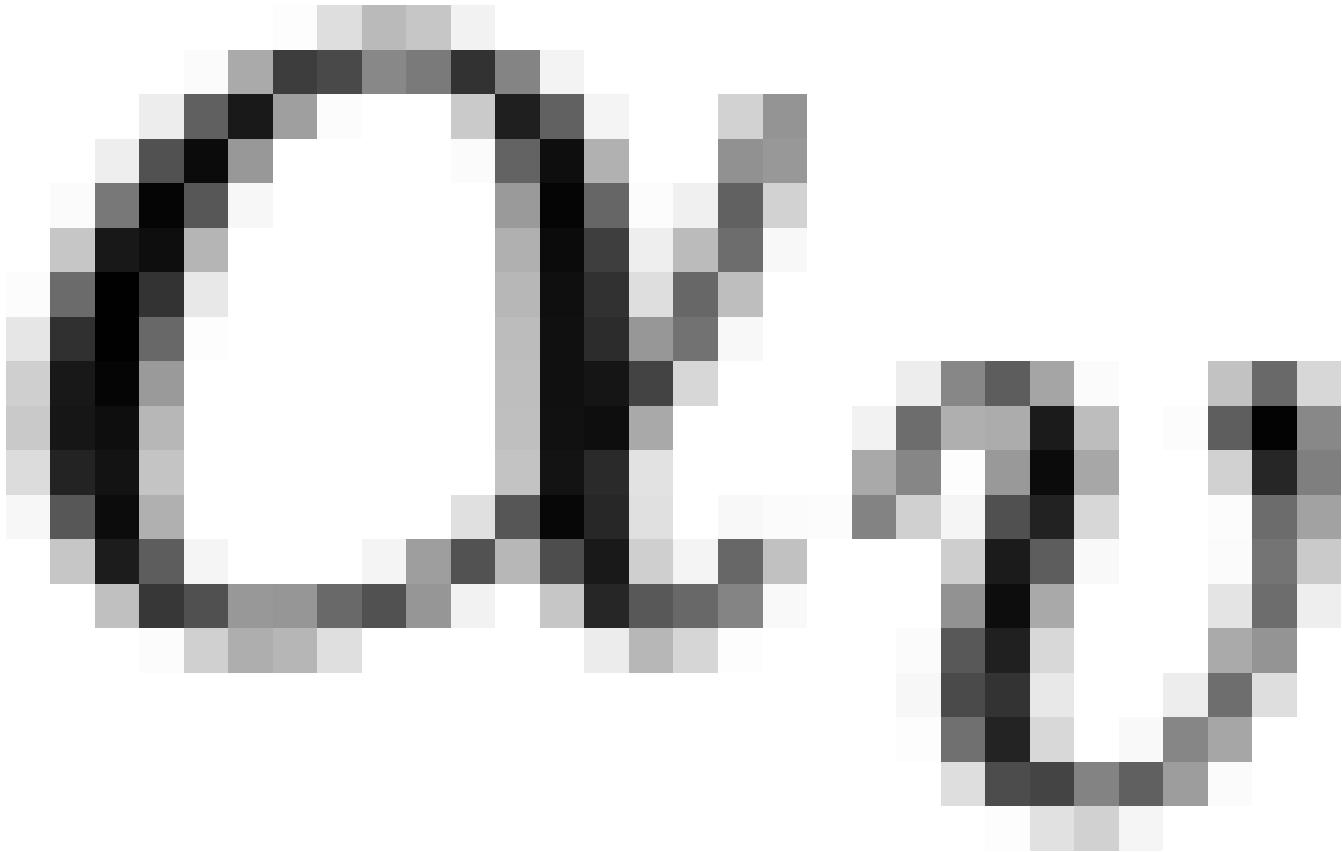


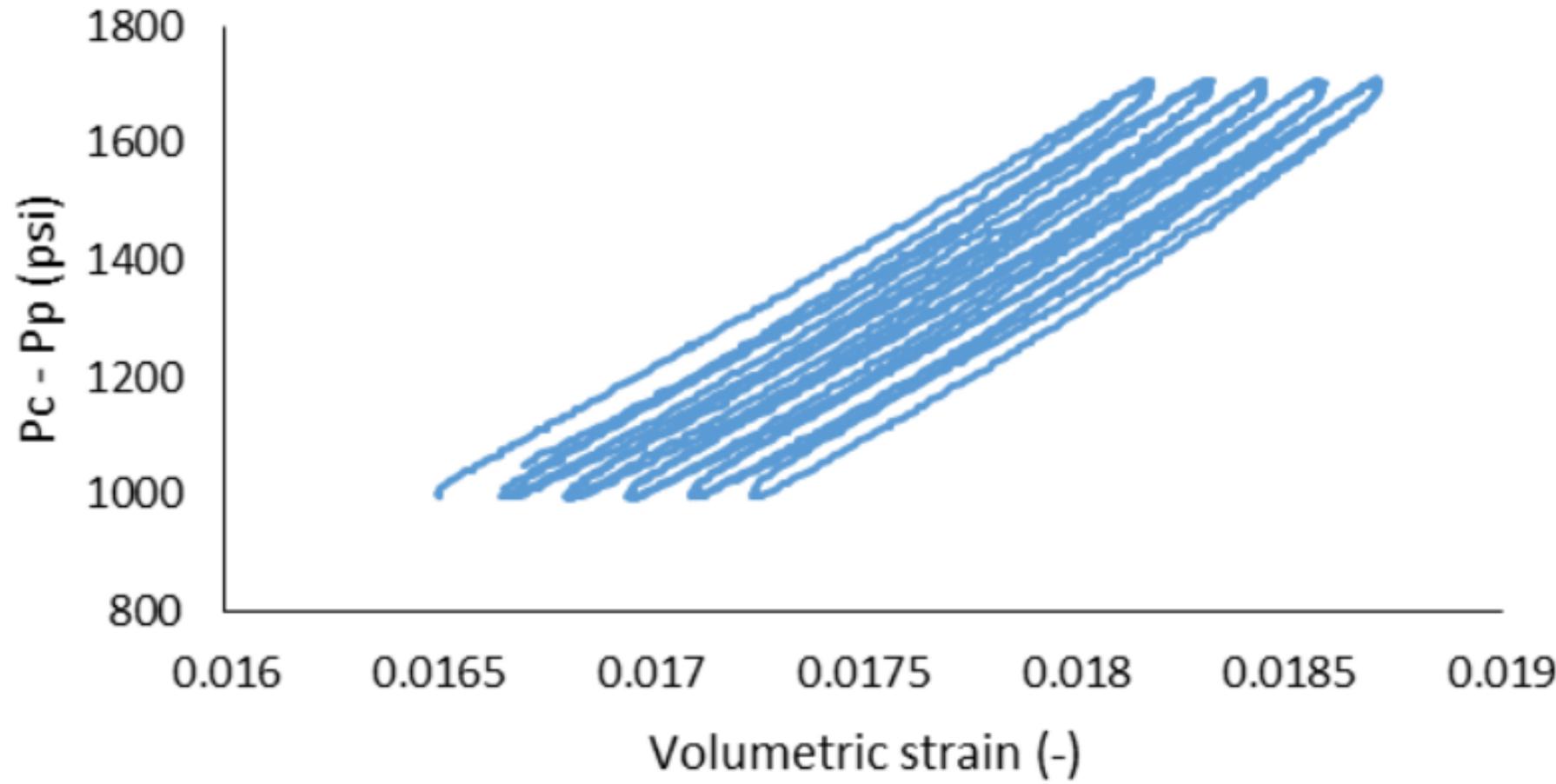












Production : 120 bbl/day
Min. BHP : 240 psi

1000 ft

$$S_v = 1200 \text{ psi}$$

Zero displacements
except for vertical
direction

Permeability : 50 mD
Porosity : 0.3
 P_{init} : 460 psi

100 ft

1000 ft

Q

(1) 22

1 - V

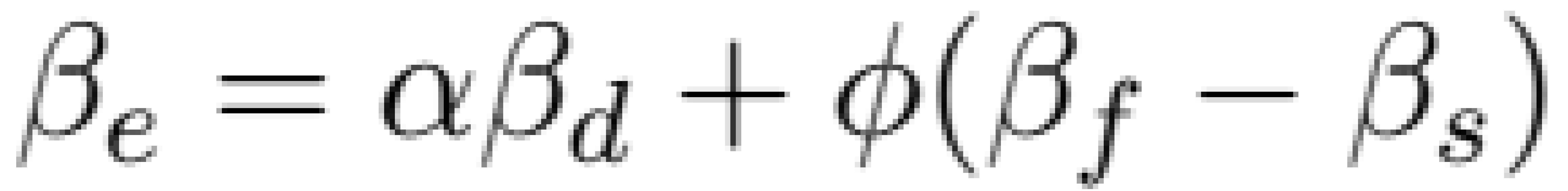


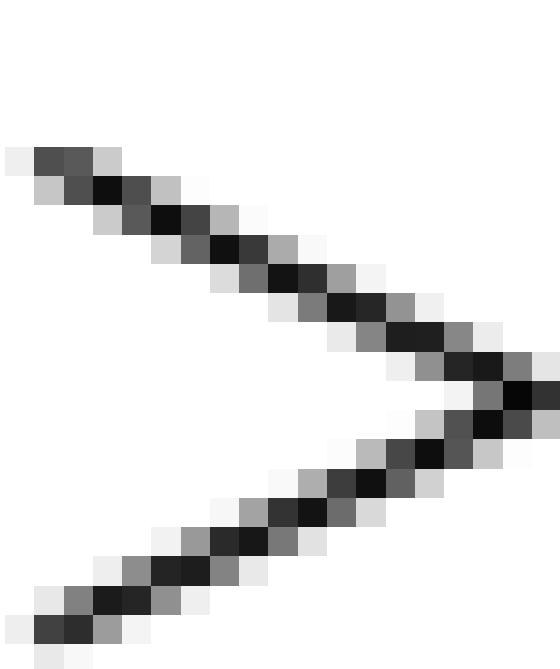
$$\left\{ \begin{array}{l} \nabla \underline{\underline{\sigma}} + \underline{\underline{f}} = \underline{\underline{0}} \\ \\ \underline{\underline{\varepsilon}} = \frac{1}{2}(\nabla \underline{u} + \nabla \underline{u}^T) \\ \underline{\underline{\sigma}} = \underline{\underline{C}} \cdot \underline{\underline{\varepsilon}} + 3\alpha_L K \theta \underline{\underline{I}}; \quad \theta = T - T_0 \\ \\ \frac{\partial \theta}{\partial t} = \frac{k_T}{\rho c_v} \nabla^2 \theta + \frac{3\beta K T_0 \partial \varepsilon_{vol}}{\rho c_v - \partial t} \end{array} \right. \begin{array}{l} \text{Equilibrium} \\ \\ \text{Kinematic} \\ \\ \text{Constitutive} \\ \\ \text{Diffusivity} \end{array}$$

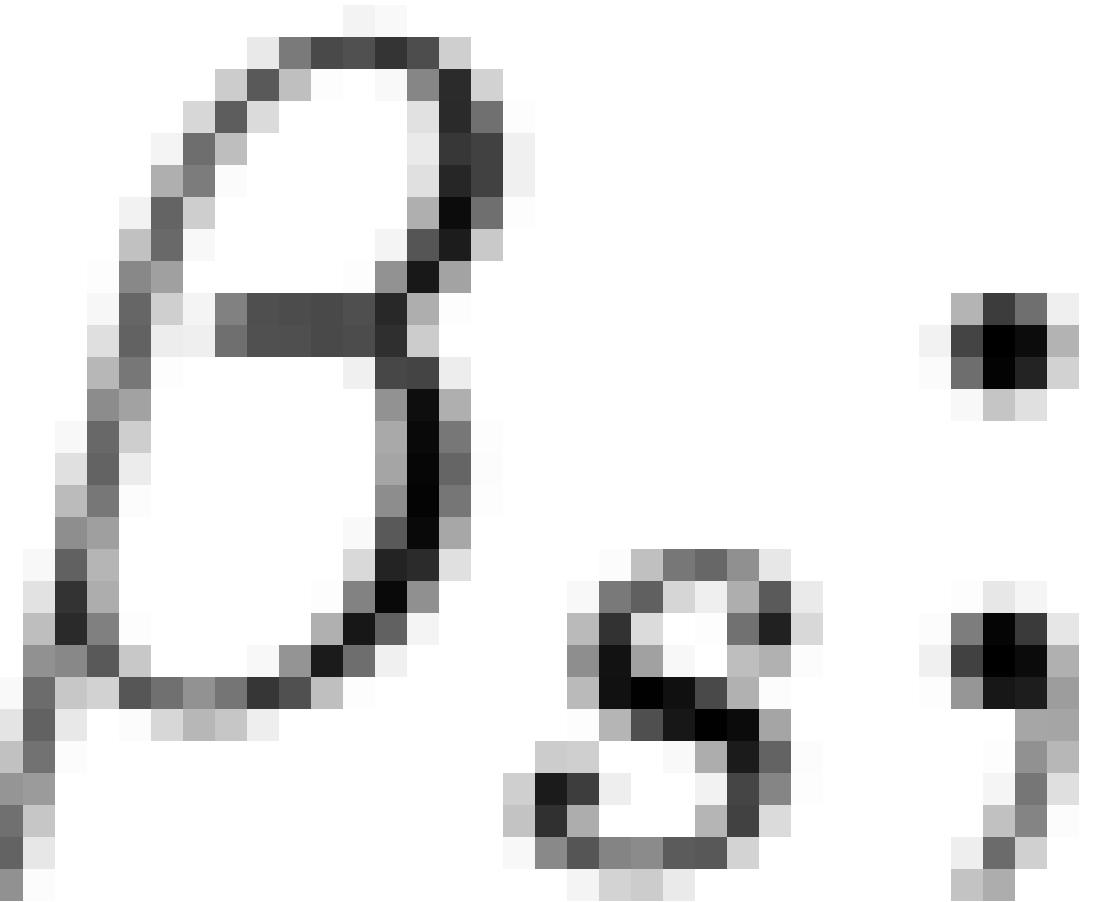
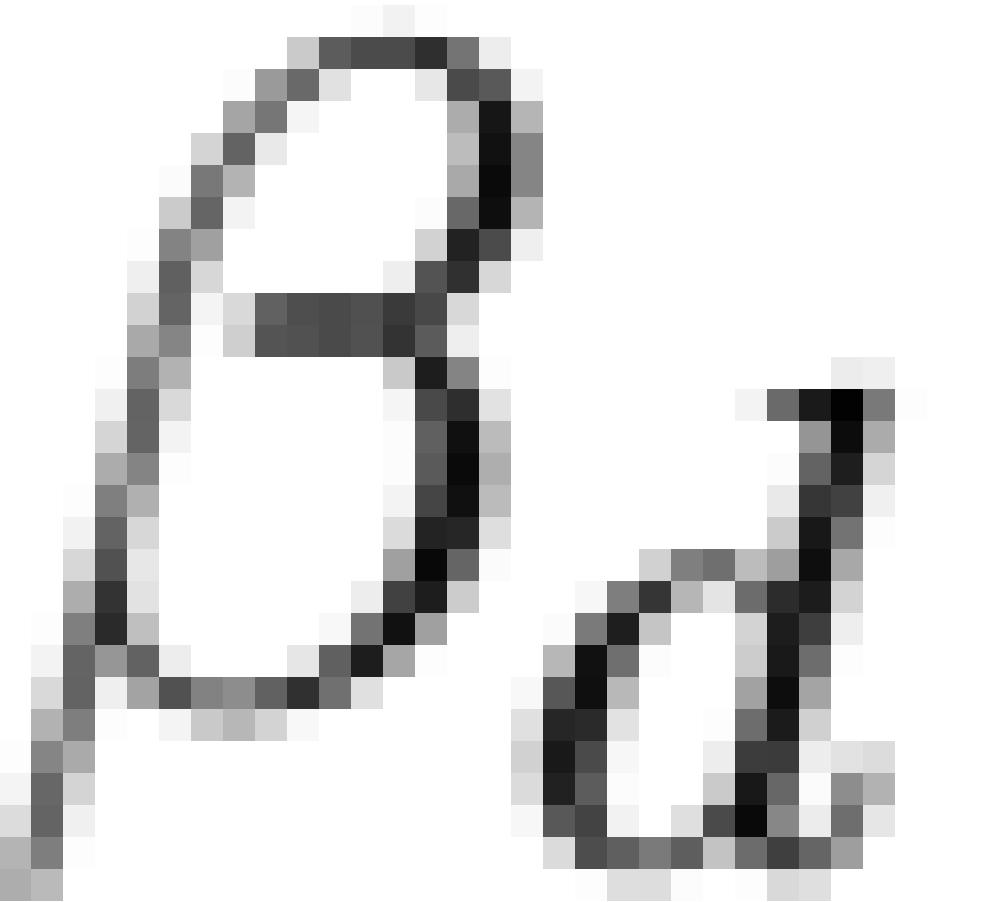
$$\left\{ \begin{array}{l} \frac{\partial p}{\partial t} - \frac{\kappa}{\mu} M \nabla^2 p = -\alpha M \frac{\partial \epsilon_{vol}}{\partial t} + \beta_e M \frac{\partial T}{\partial t} \\ \frac{\partial T}{\partial t} - \kappa_T \nabla^2 T = -\frac{\alpha_d}{m_d} \frac{\partial \epsilon_{vol}}{\partial t} + \frac{\beta_e}{m_d} \frac{\partial p}{\partial t} \end{array} \right.$$

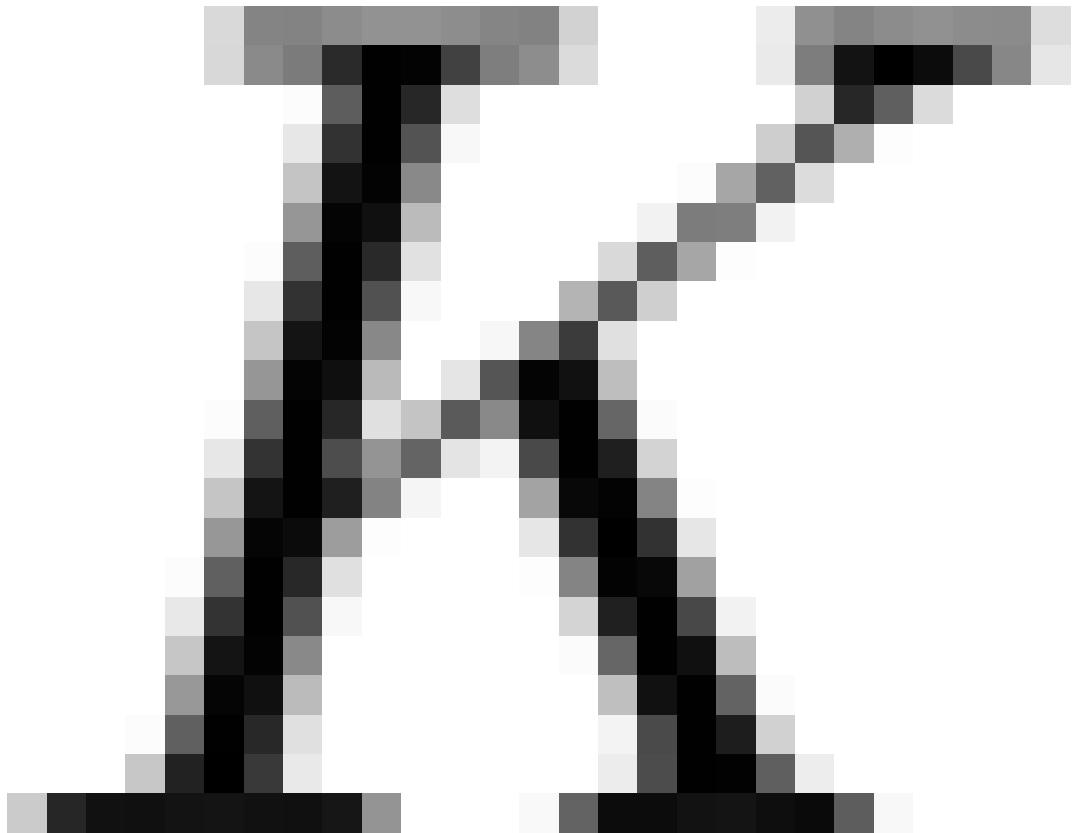
Pore pressure diffusivity

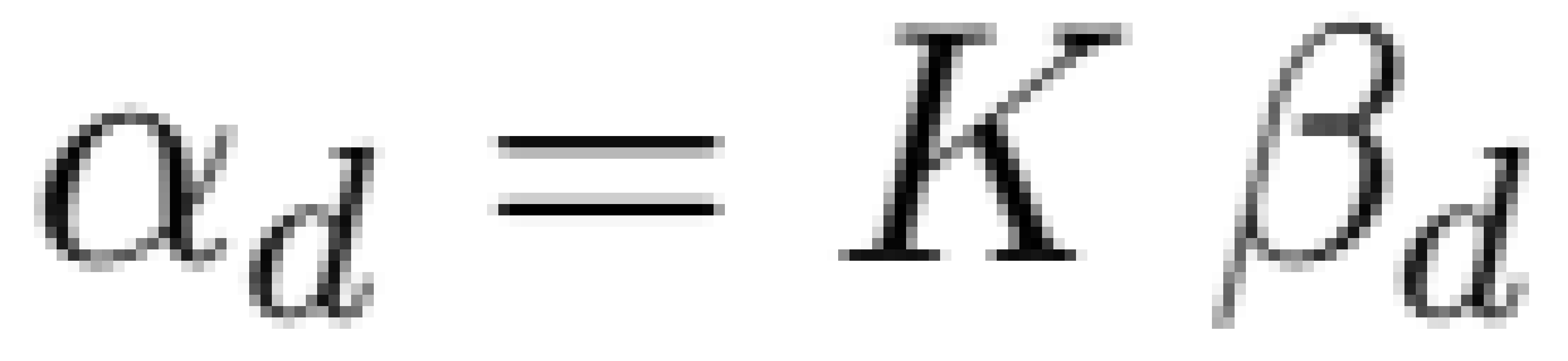
Temperature diffusivity











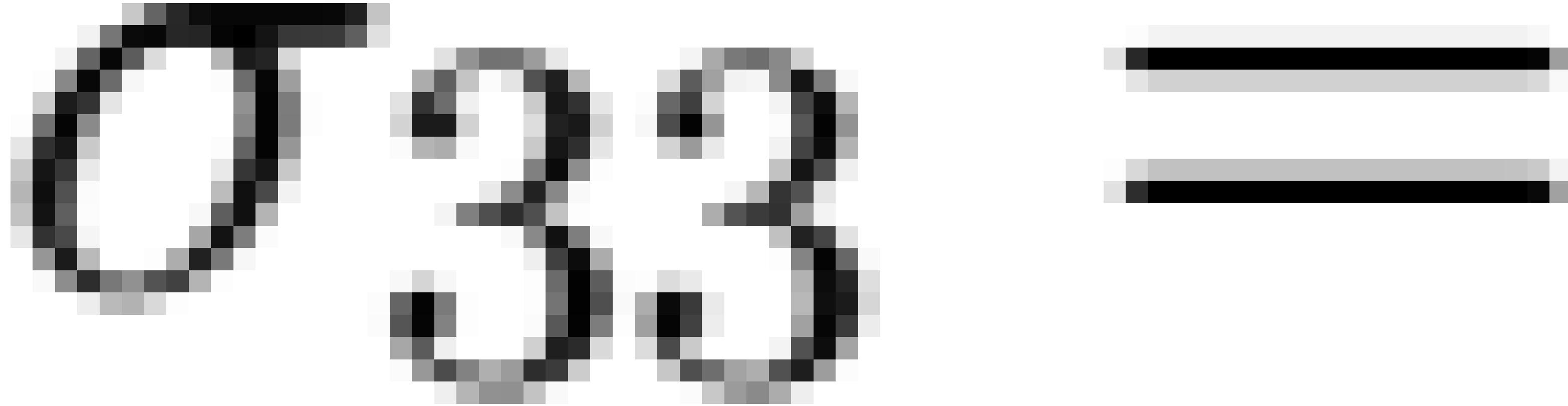
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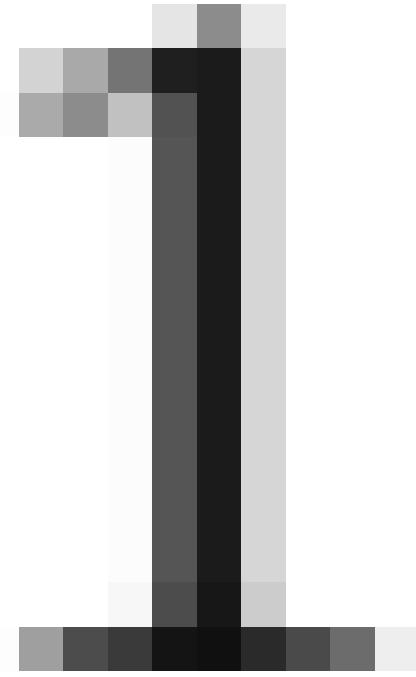
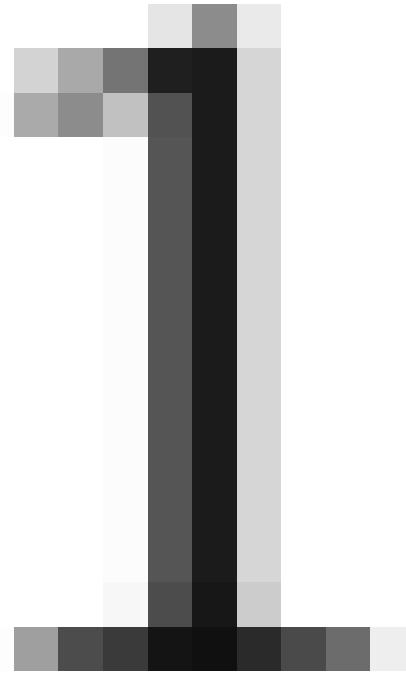
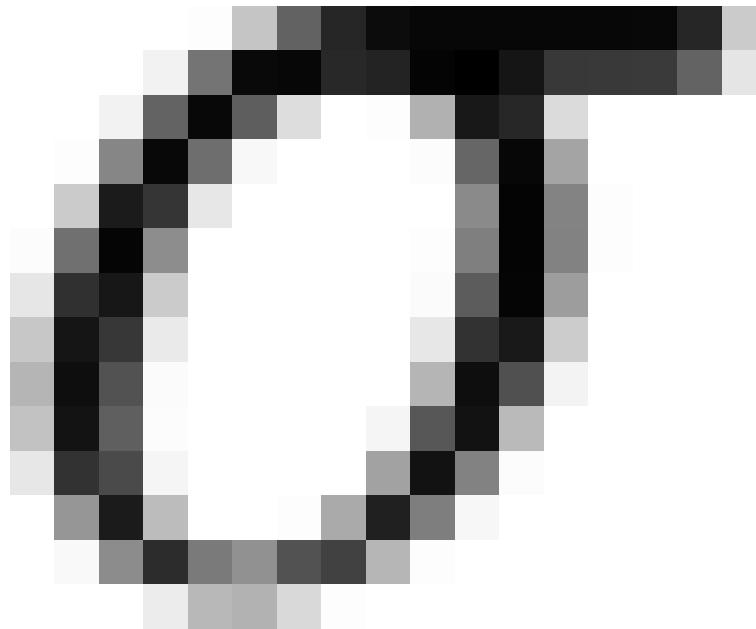
cd
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70

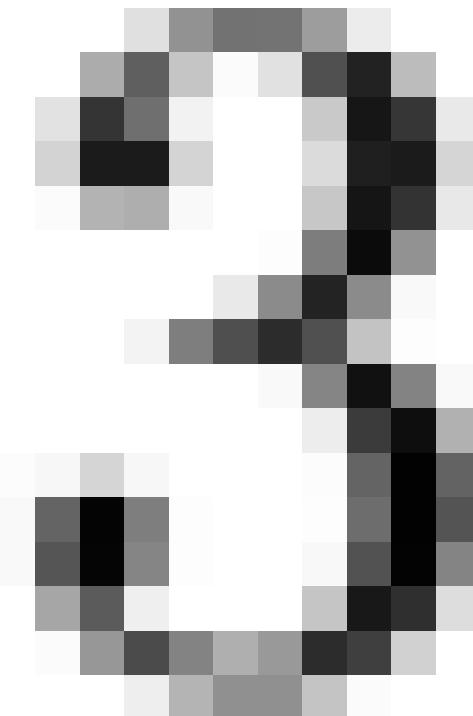
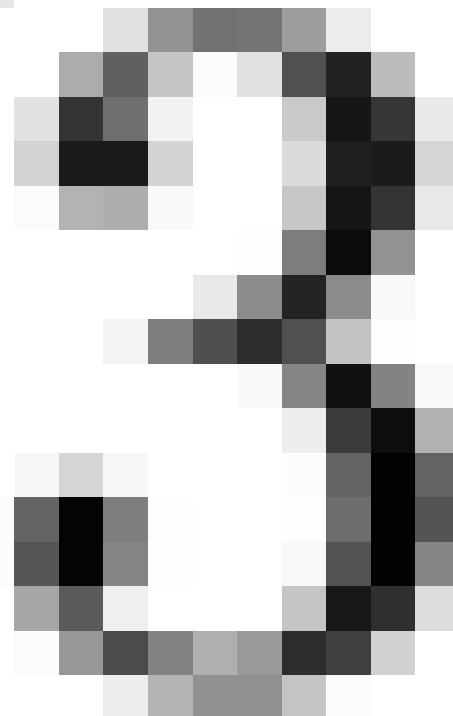
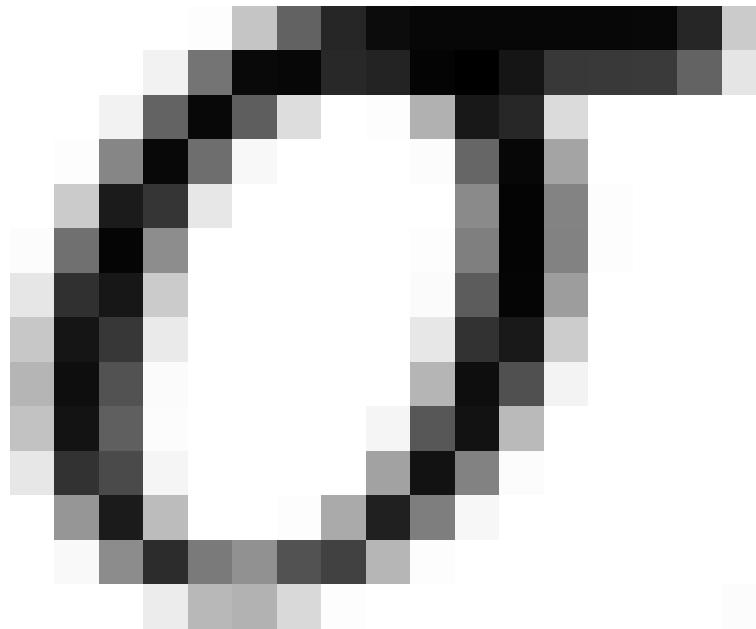




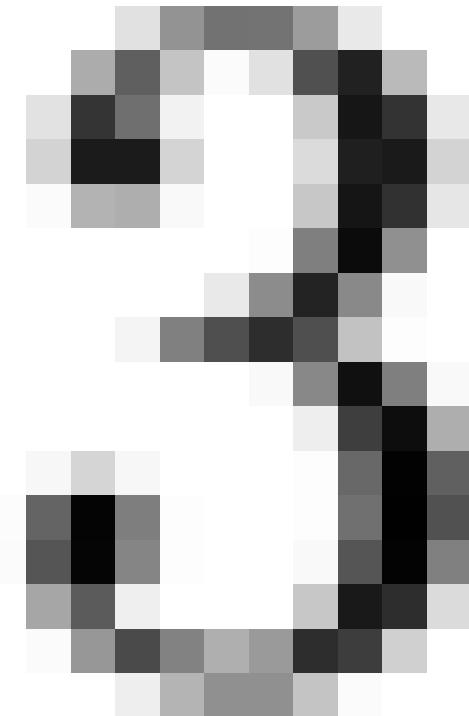
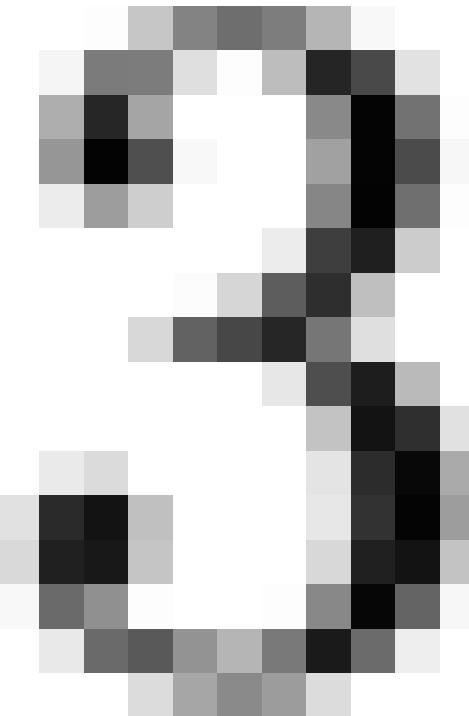
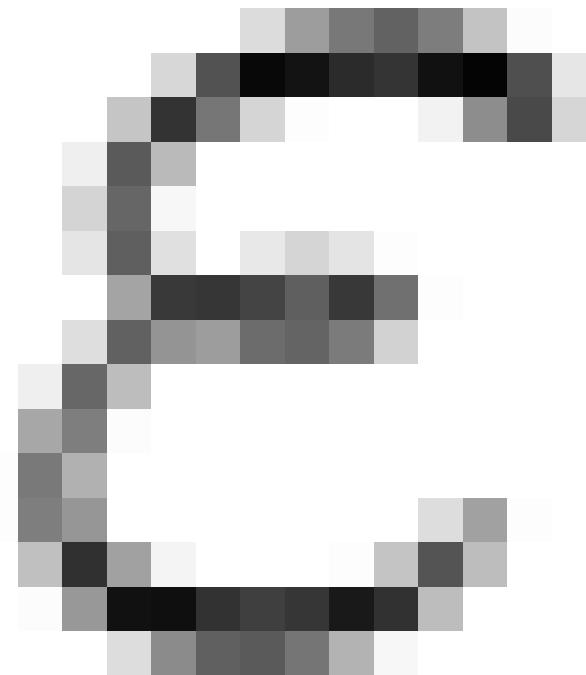


$$\begin{bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{bmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu \\ \nu & 1-\nu & \nu \\ \nu & \nu & 1-\nu \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ \varepsilon_{33} \end{bmatrix} + \begin{bmatrix} 3\alpha_L K \theta \\ 3\alpha_L K \theta \\ 3\alpha_L K \theta \end{bmatrix}$$

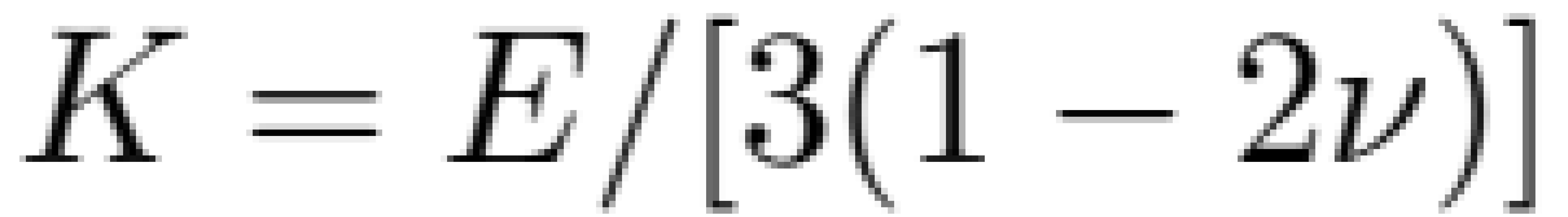




$$\left\{ \begin{array}{l} \sigma_{11} = \frac{\nu E}{(1+\nu)(1-2\nu)} \epsilon_{33} + 3\alpha_L K \theta \\ \sigma_{33} = \frac{(1-\nu)E}{(1+\nu)(1-2\nu)} \epsilon_{33} + 3\alpha_L K \theta \end{array} \right.$$



$$\sigma_{11} = \left(\frac{v}{1-v} \right) \sigma_{33} + \left(\frac{1-v}{1+v} \right) 3\alpha_L K_0$$



$$\sigma_{11} = \left(\frac{1 - \nu}{1 + \nu} \right) \sigma_{33} + \frac{\alpha E}{1 - \nu}$$

$\hat{\sigma}_{11}$

$\hat{\sigma}_{11}$

$\hat{\sigma}_0$

$\hat{\sigma}_0$

$\hat{\sigma}_0$

$\hat{\sigma}_1$

$\hat{\sigma}_1$

$\hat{\sigma}_2$

$\hat{\sigma}_{DE}$

$\hat{\sigma}_{11}$

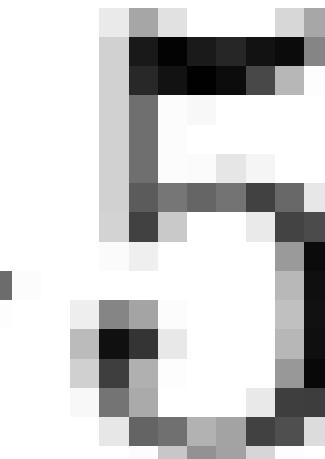
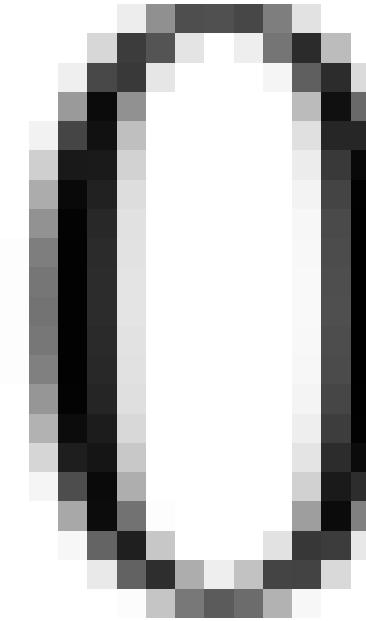
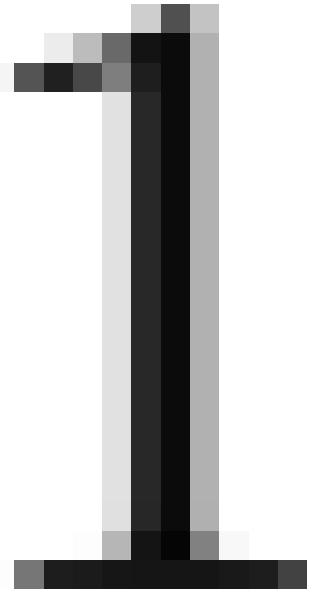
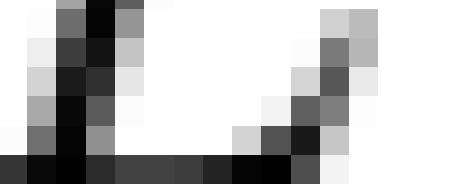
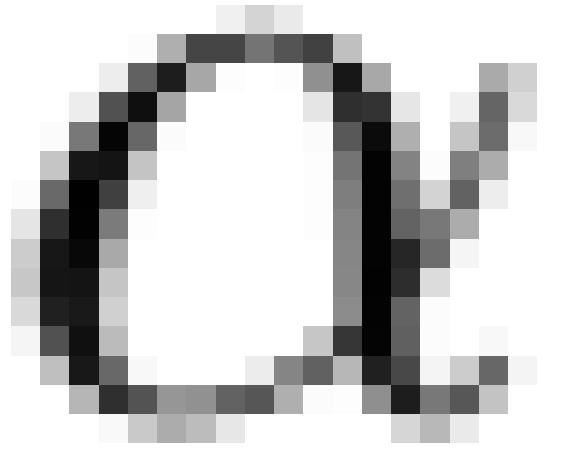
$\hat{\theta}$

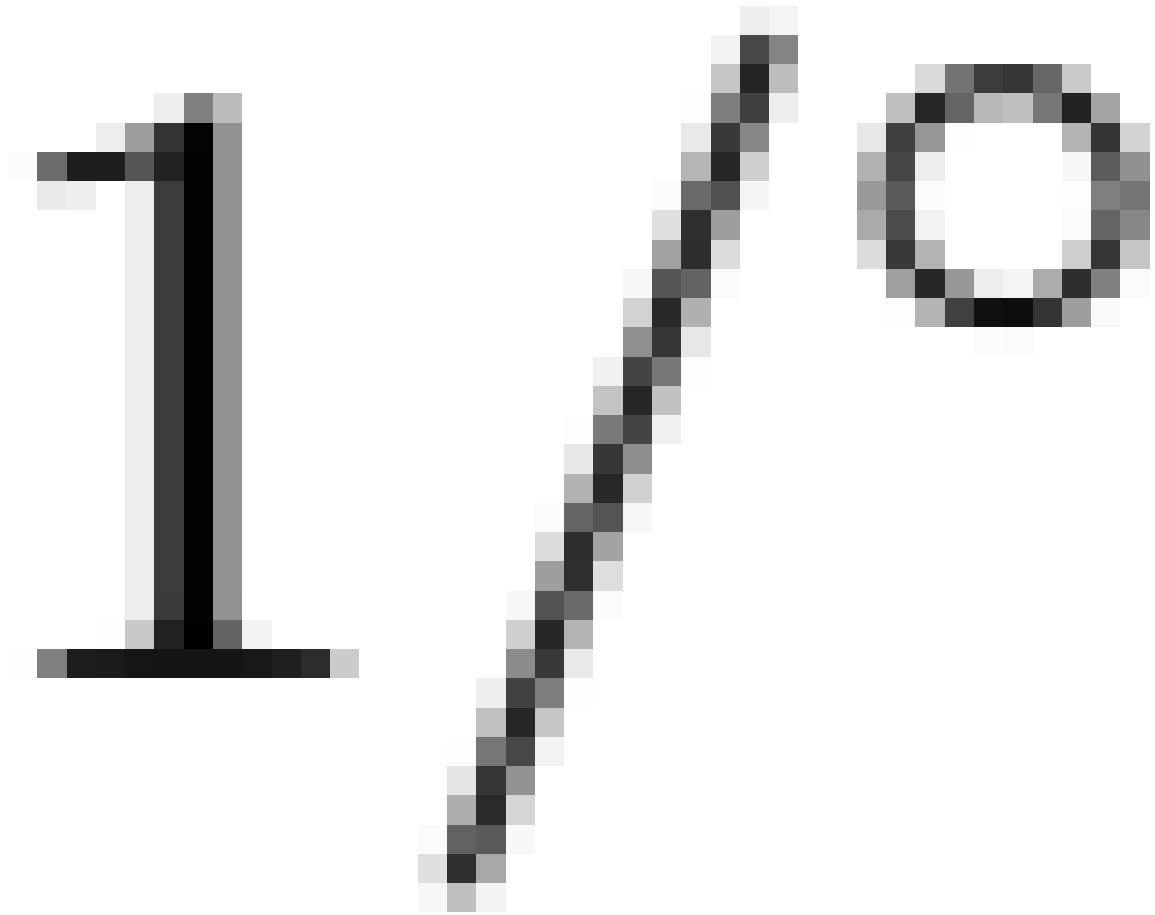


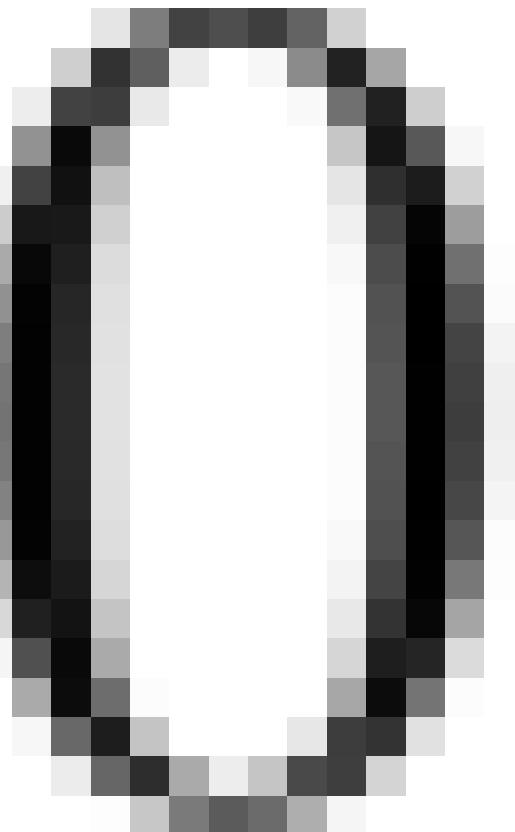
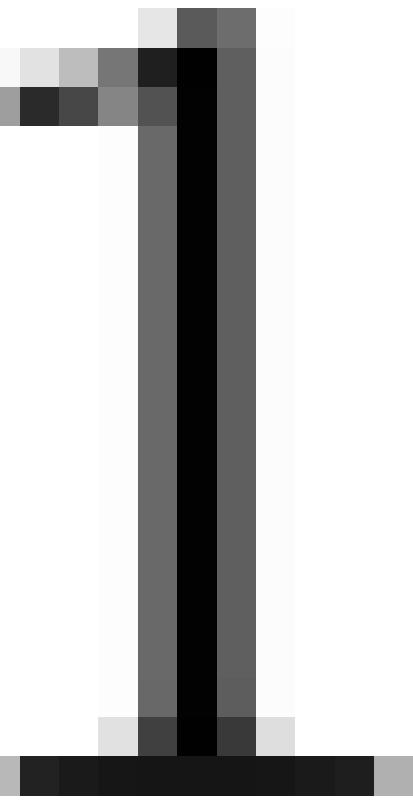
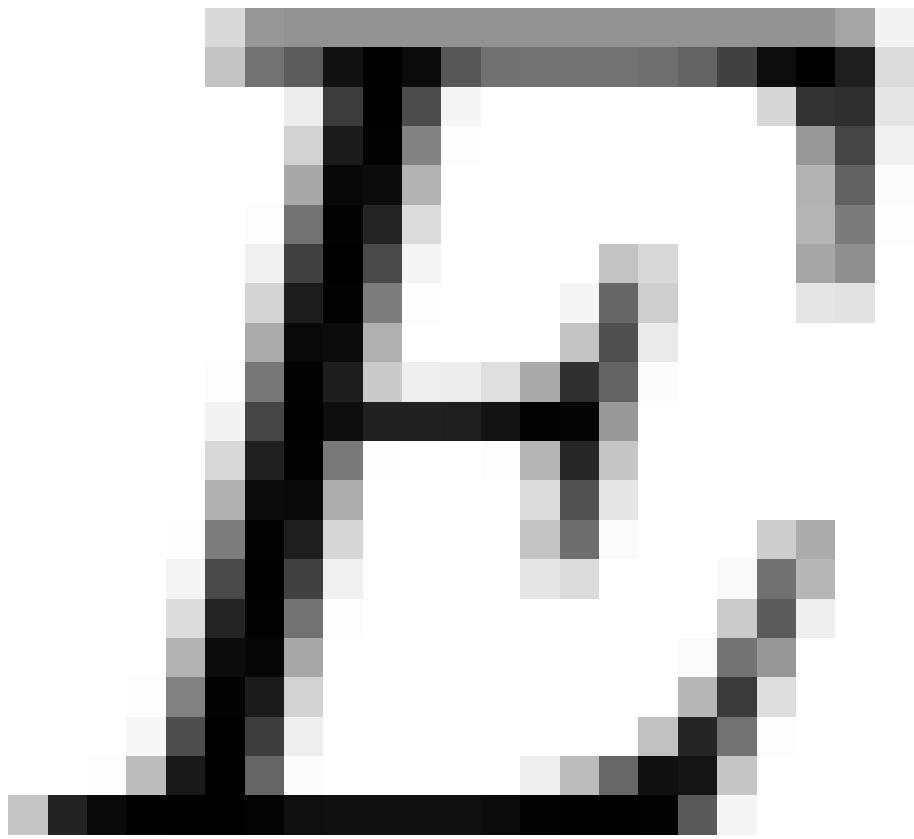
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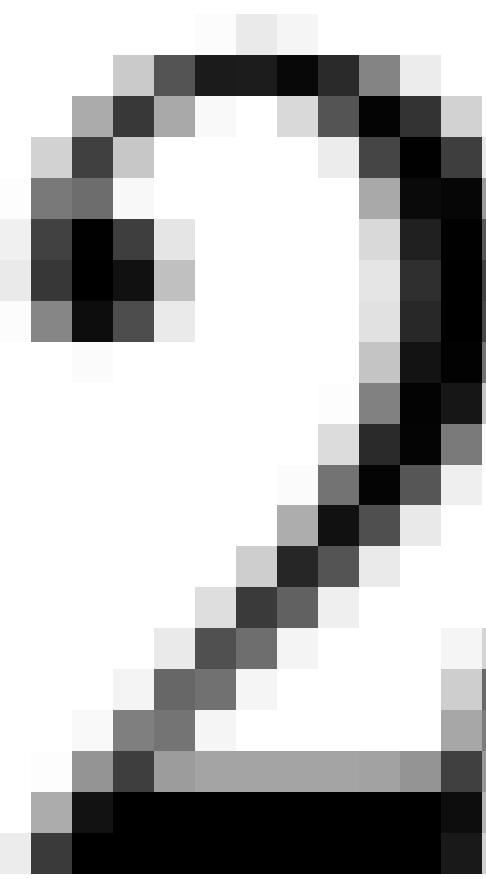
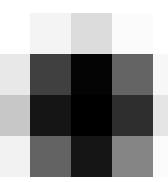
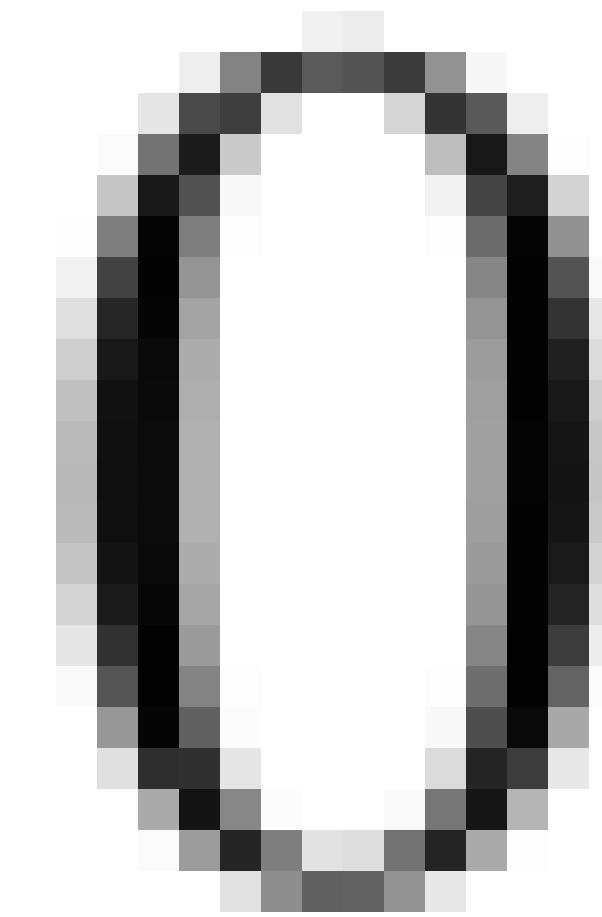
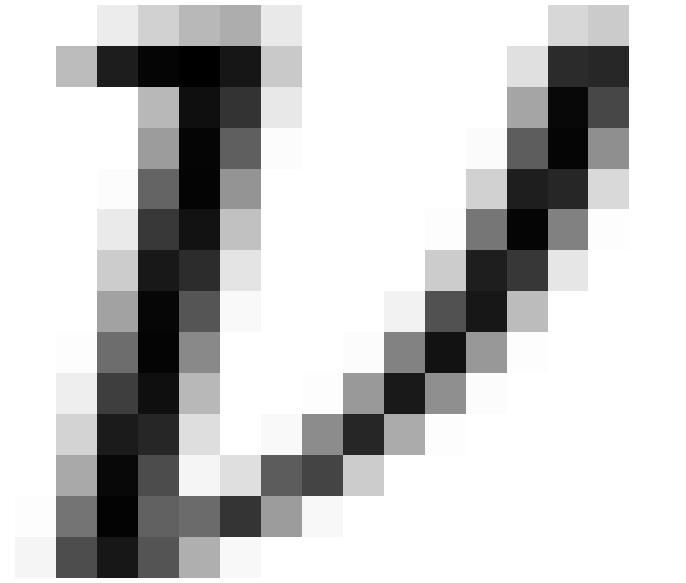
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MPa









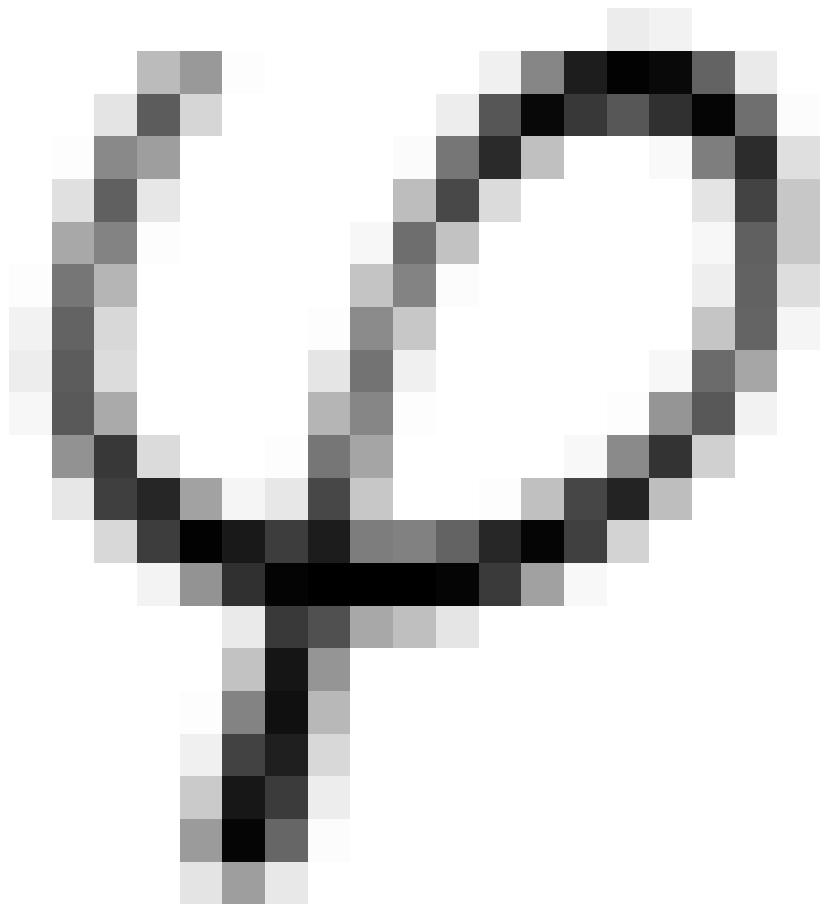


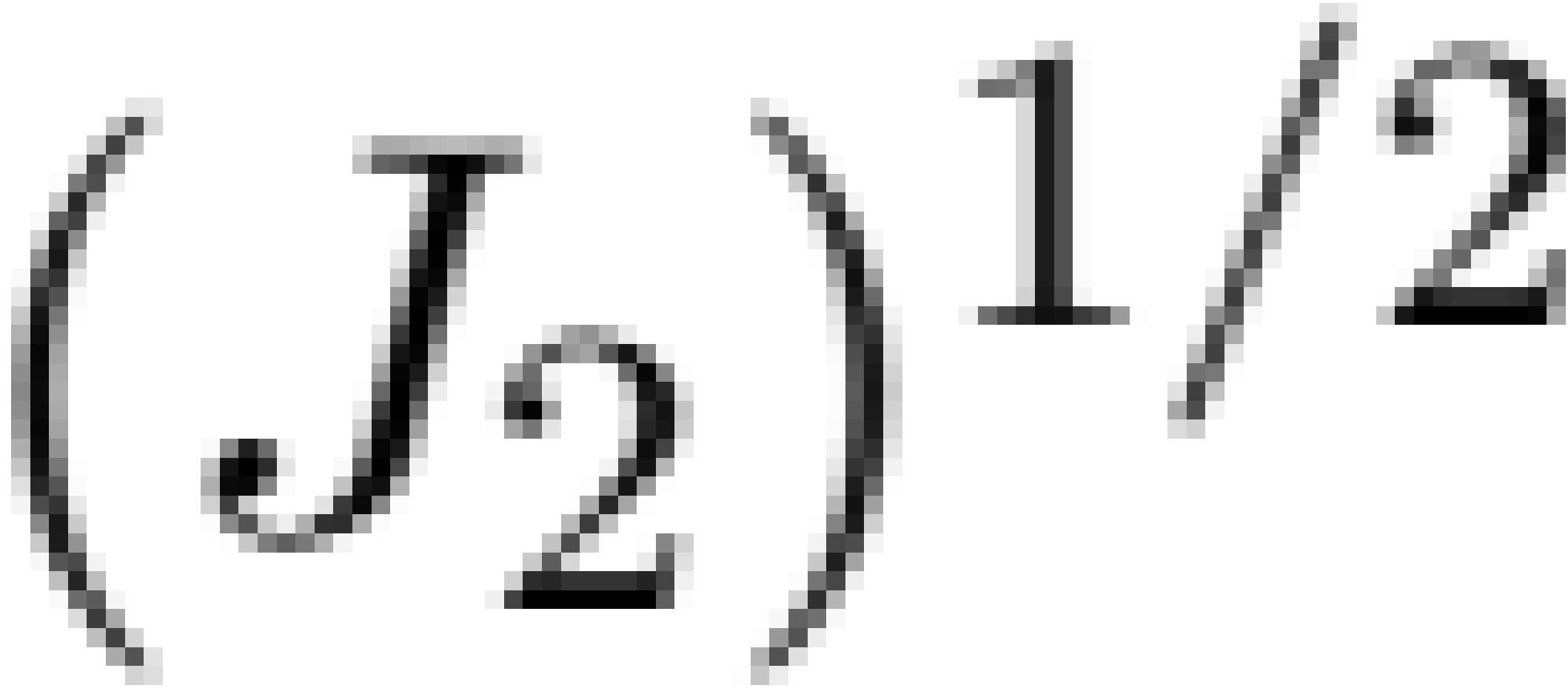




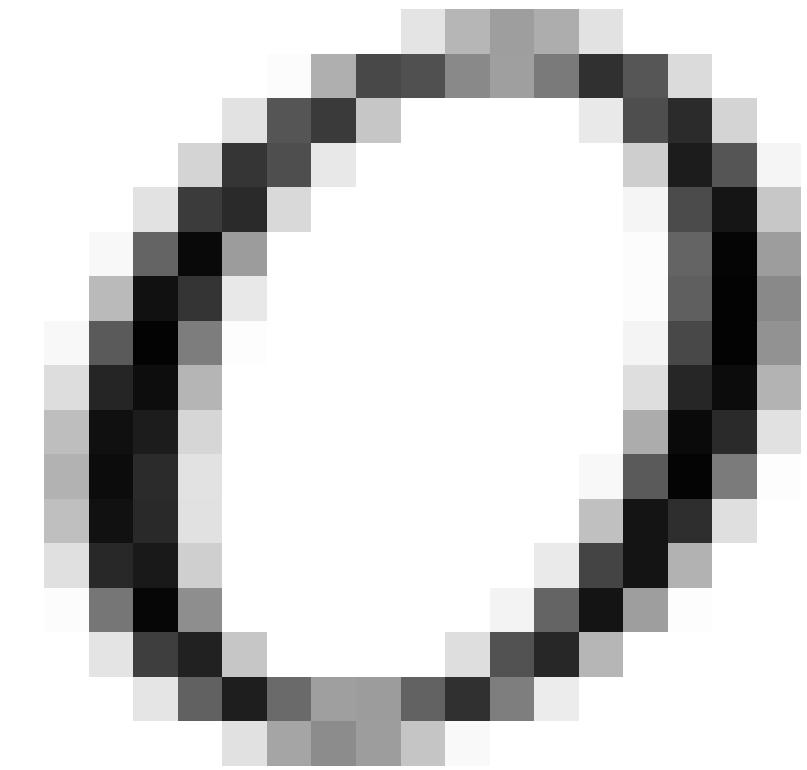
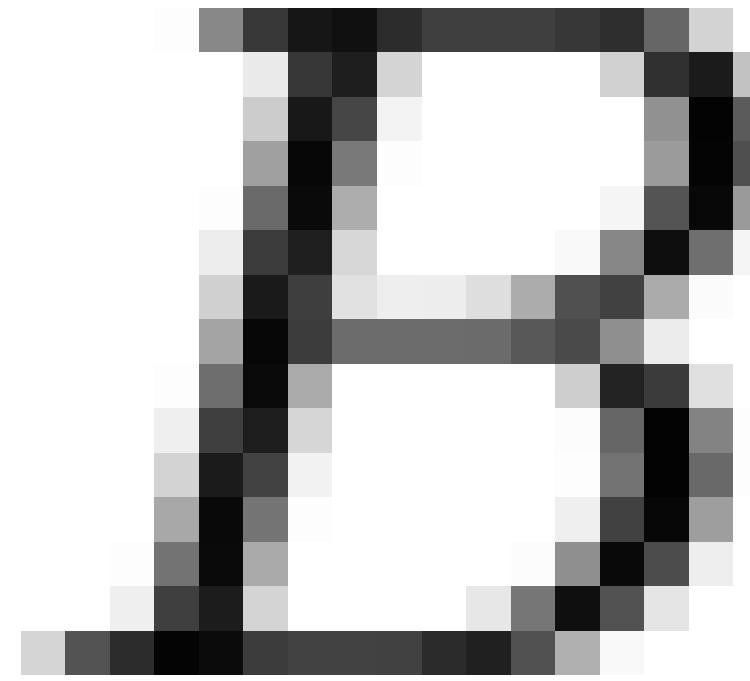
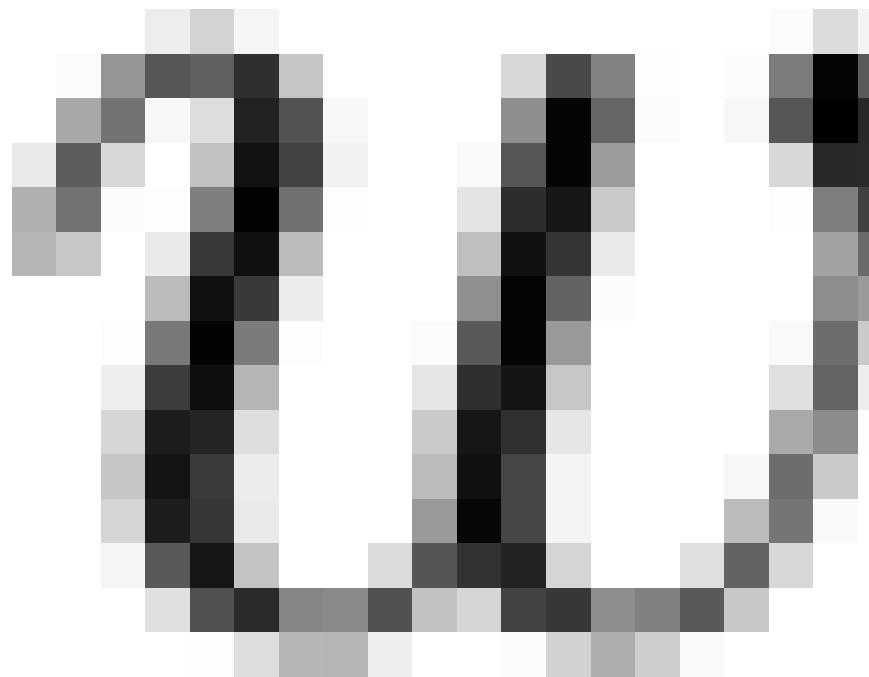




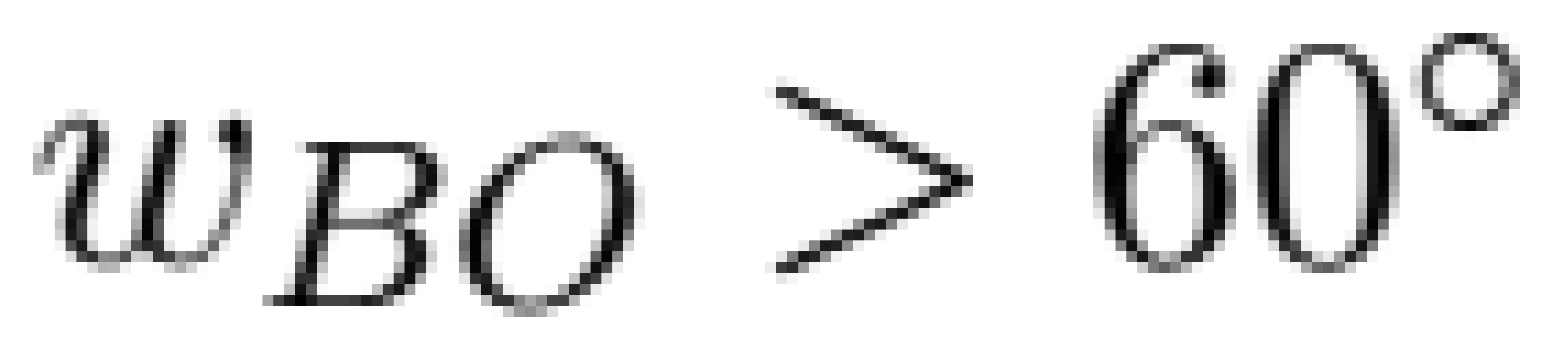


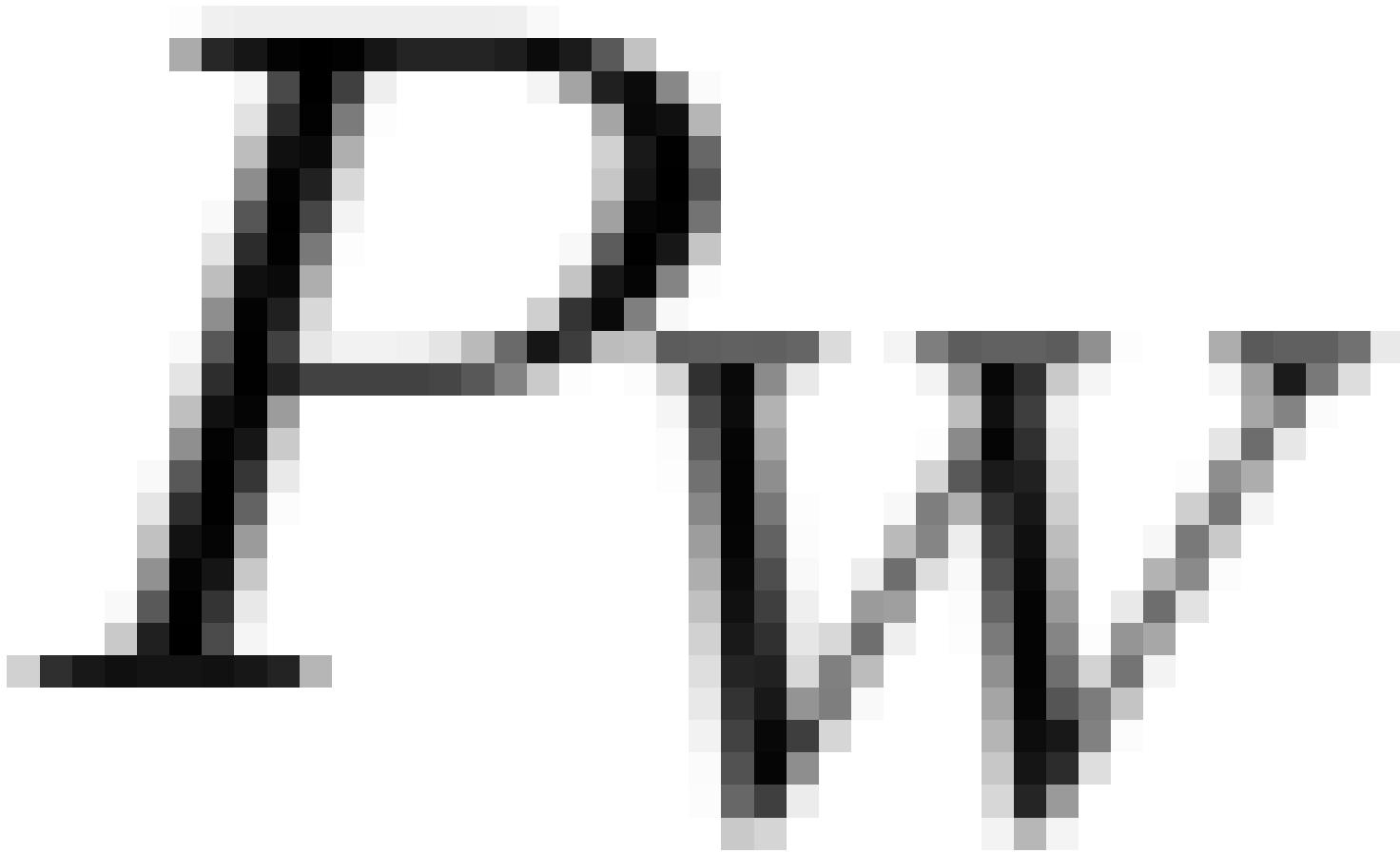








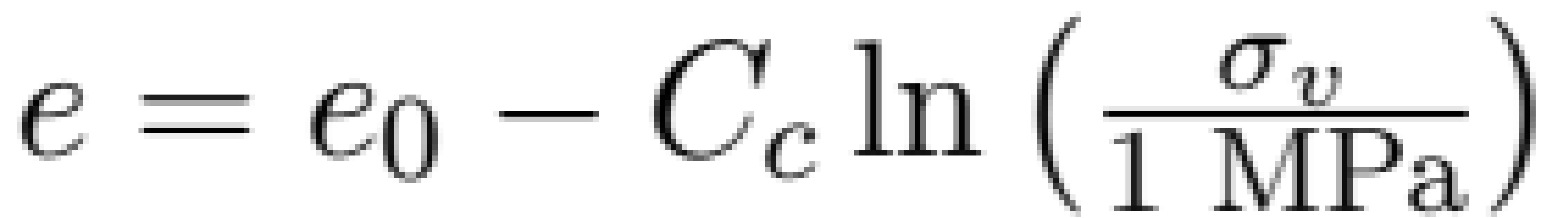






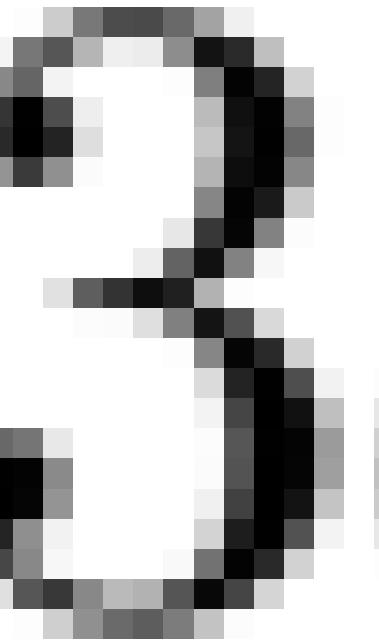


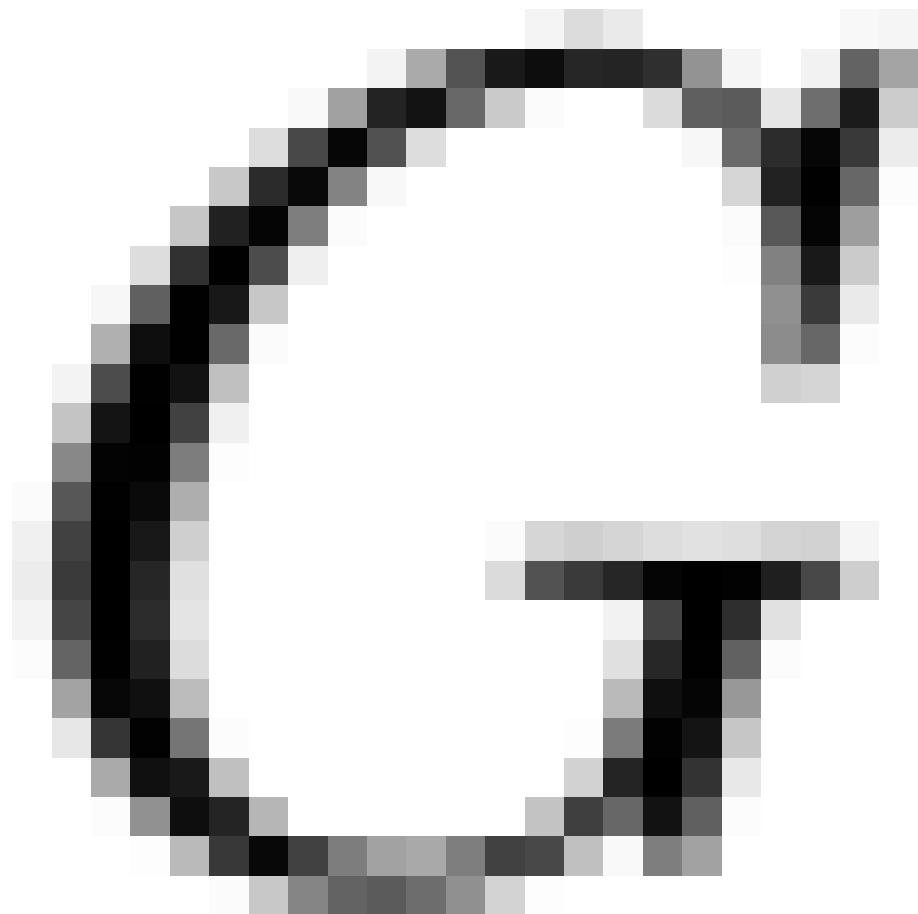




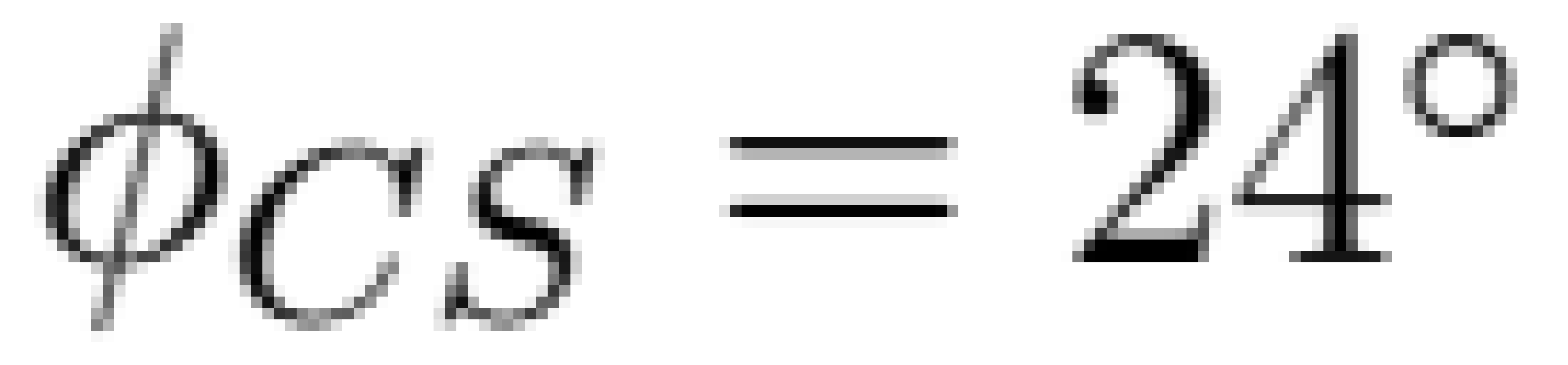


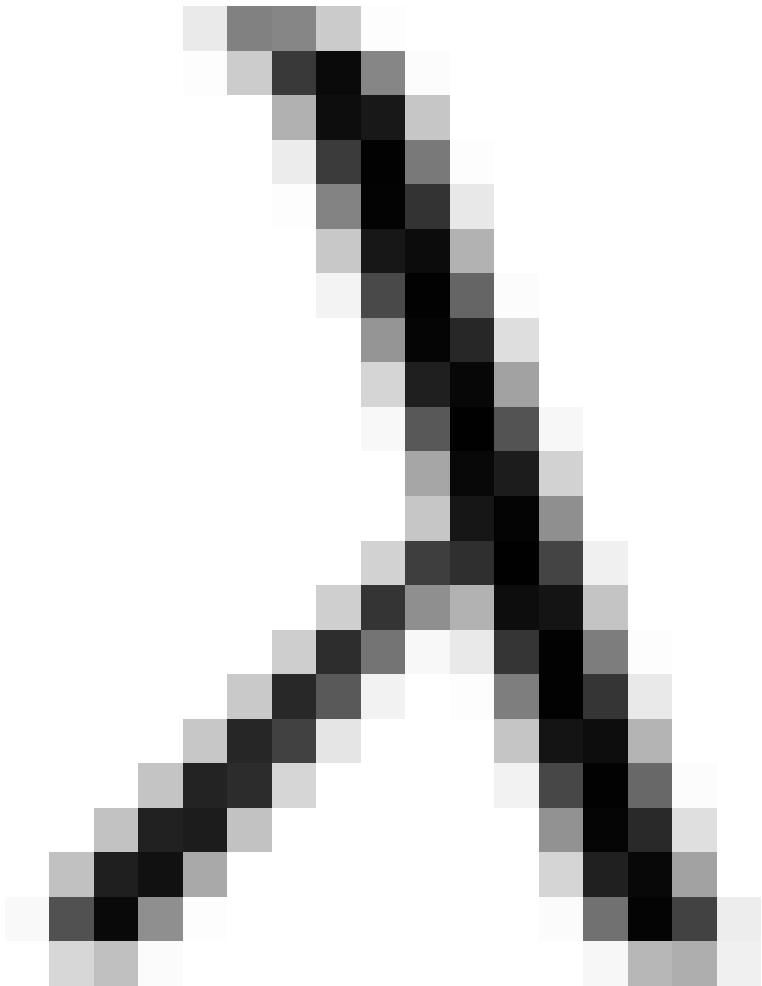


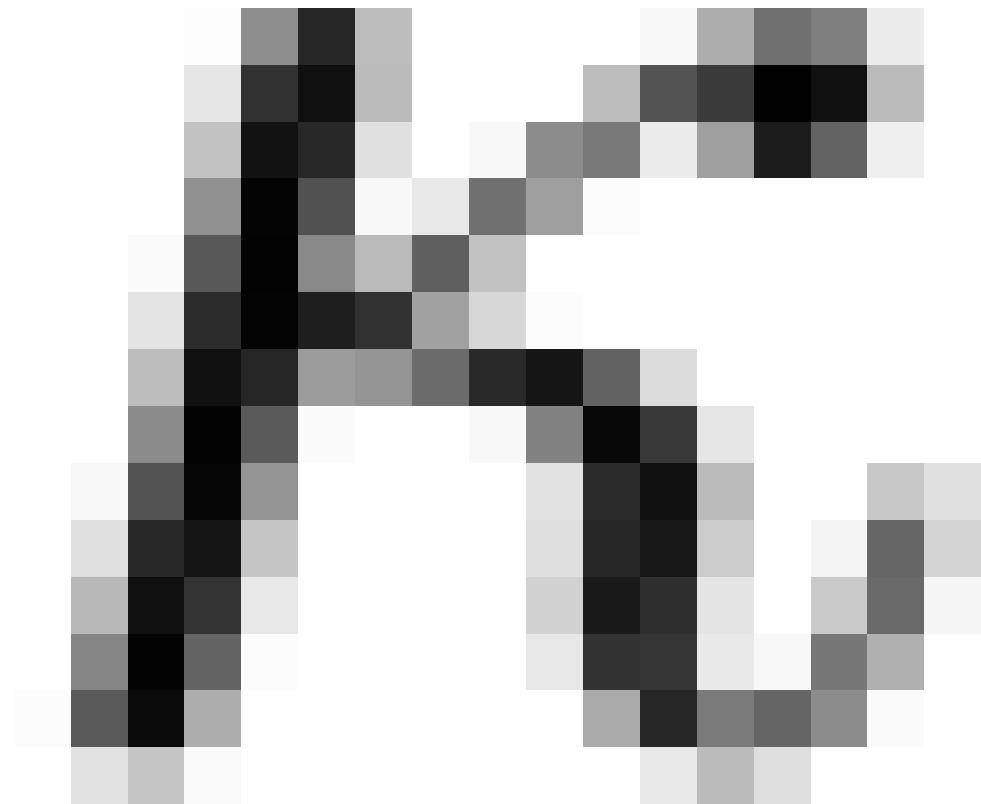


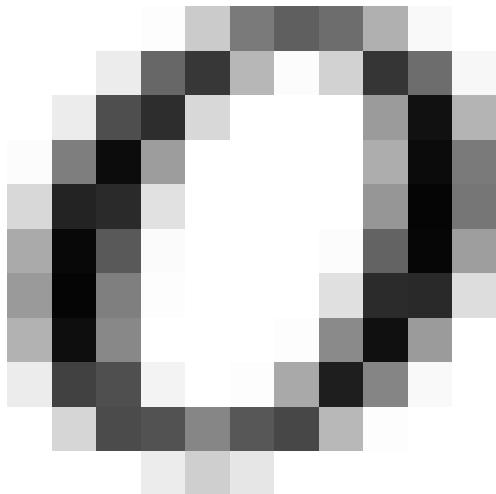
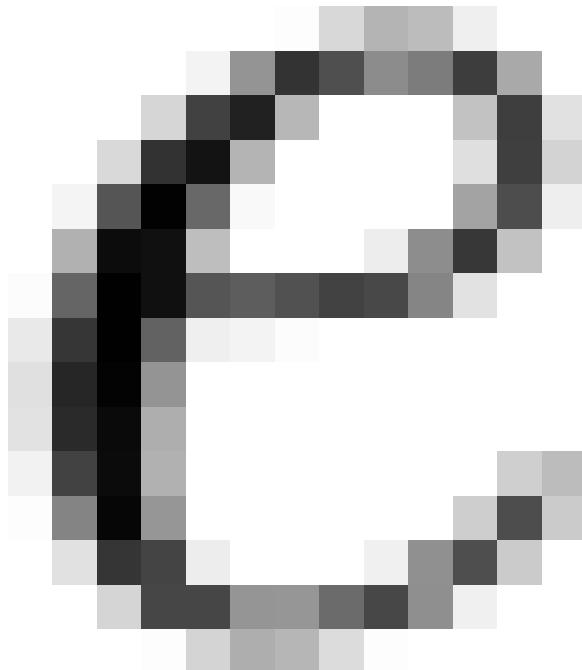


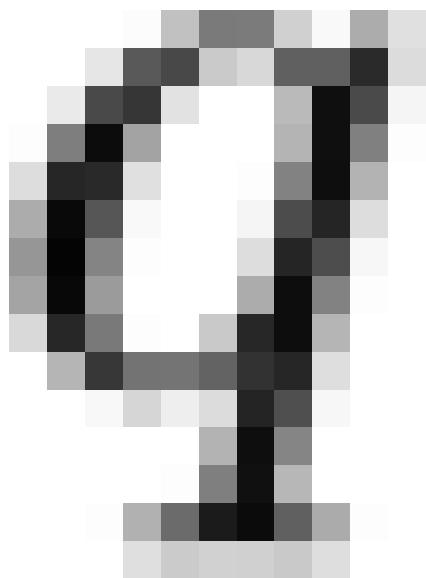
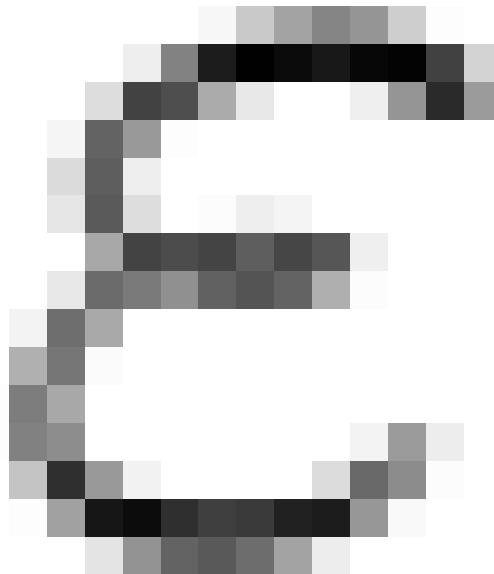


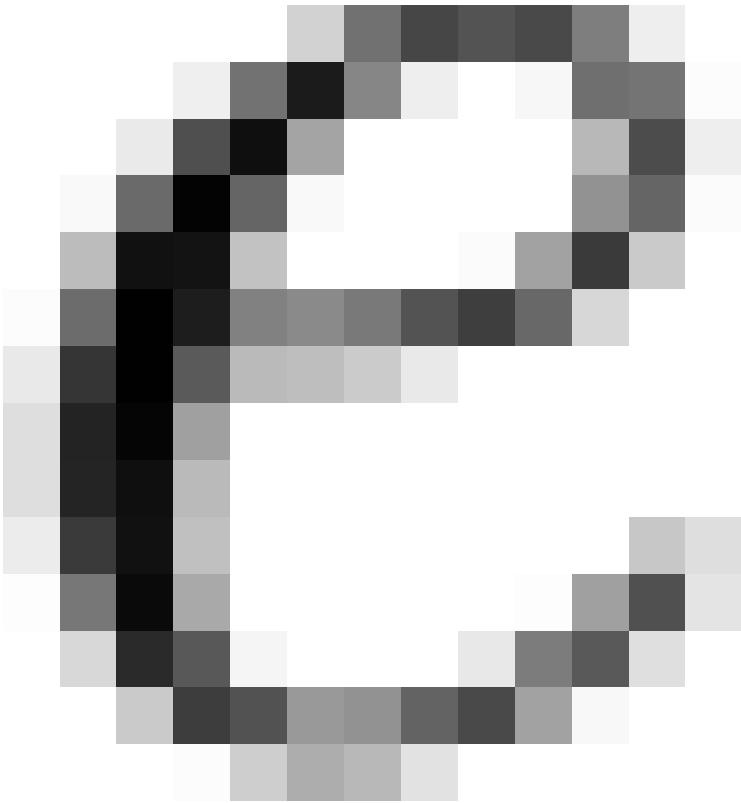


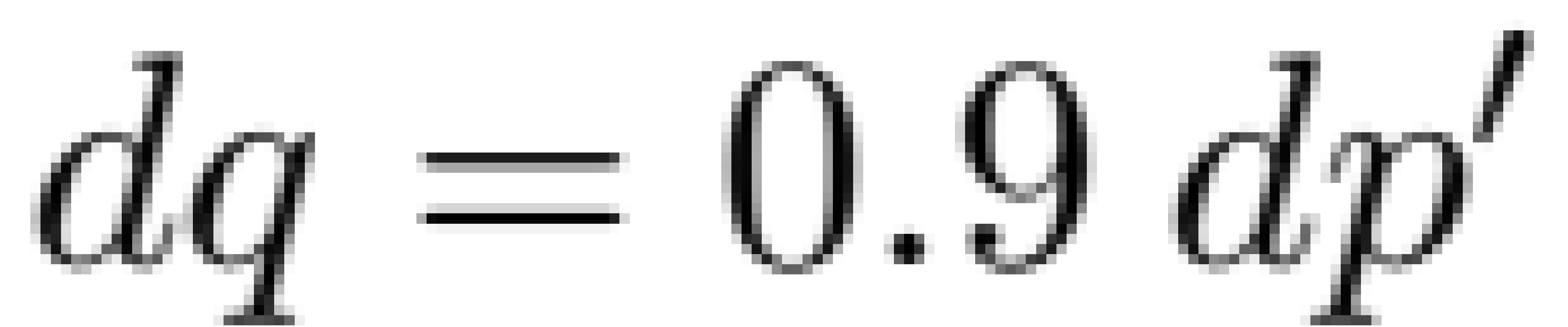


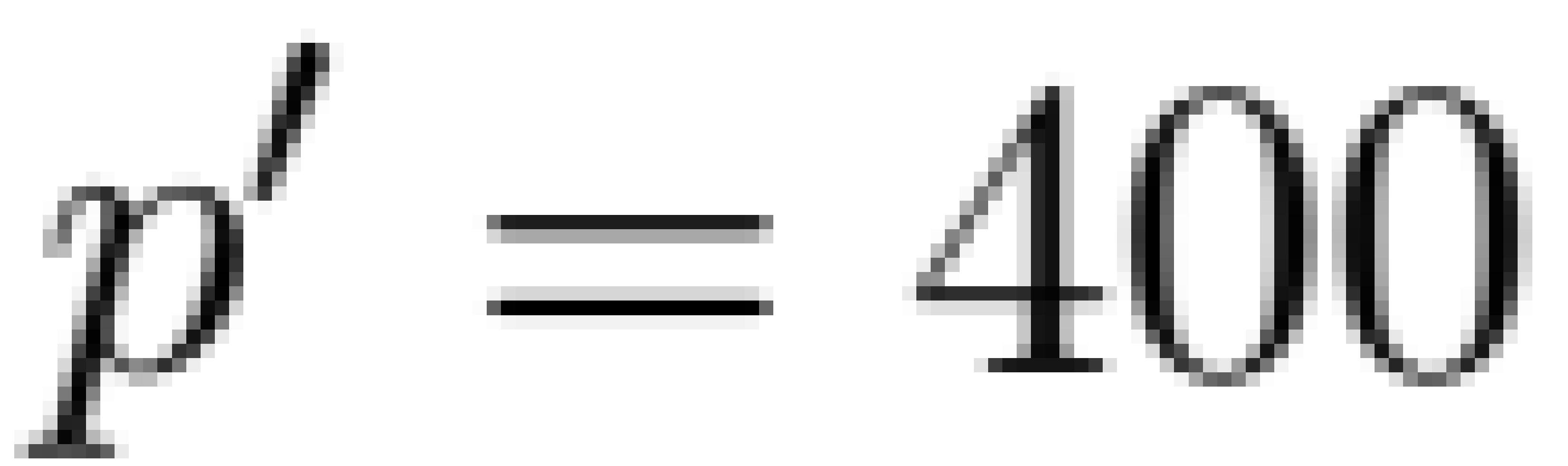


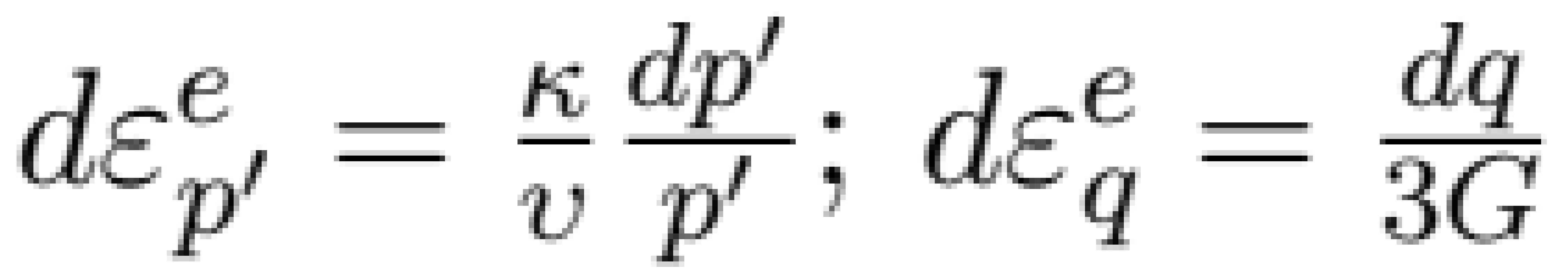












$$\begin{bmatrix} d\epsilon_p^p \\ d\epsilon_q^p \end{bmatrix} = \frac{\lambda - \kappa}{vp(M^2 + \eta^2)} \begin{bmatrix} M^2 - \eta^2 \\ 2\eta \\ 4\eta^2 \\ M^2 - \eta^2 \end{bmatrix}$$

