

## **Workshop 3: Real Time Automated Systems**

### **Definition**

Provides time/frequency to user specification in real time

- May have historical calibration

Do not require frequent operator action

- No full time operator
- May be fully unattended or remotely controlled

Typical applications include

- National time scales
- Remote time stations
- Imbedded part in Military systems and Telecommunications systems

### **Performance**

- Time Accuracy – typically 100 nsec or better
- Frequency accuracy –  $10^{-11}$  or better
- Frequency Stability – as good as  $10^{-13}$  at 1 second to  $10^{-13}$  at 1 day
- Usually require synchronization to national standard via GPS or 2 Way

## **Measurements**

- Accurate time tagging of measurements very important
  - Use telephone or network time sync for control computer time
- Measurement system must produce quiet, unambiguous measurements
  - RF (5 MHz) measurements preferred over tick measurements
  - 1PPS measurements problems are rise time, triggering, cable length

## **Distribution Systems**

- Environmental effects, temperature & humidity
- Use of high quality cable and connectors
- Greater than 100 db isolation between ports including output to input
- Widely distributed systems such as communication networks have special problems

## **Robustness**

- Small errors should only cause small problems
  - e.g. loss of 1 device shouldn't kill the system
- Computer needs stable operating system and user software
- There is a trade-off between single point failures and problems caused trying to avoid single point failures.
- User equipment driven from real time systems should be tolerant of small output glitches
- Robustness is difficult to specify
  - Depends on user environment
  - Hard to think of everything

## **Maintenance and testing**

- Box level field maintenance
  - Hardware is too complex to fix in the field
- Built-in test
- Remote diagnostic capability