

## 0.1 Proof of theorem 0.1

Our relaxed objective becomes:

$$\begin{aligned} & \underset{\mathbf{M}}{\text{minimize}} && f'_S := \text{Tr}(\mathbf{M}^T \mathbf{L} \mathbf{M}), \\ & \text{subject to} && \mathbf{M}^T \mathbf{D} \mathbf{M} = \mathbf{1}^{k \times k} \text{ and } \mathbf{M} \in \mathbb{R}^{n \times k}. \end{aligned}$$

The optimal solution to  $f'_S$  is more tractable to compute.

**Theorem 0.1.** *The optimal solution to  $f'_S$  is the matrix  $\mathbf{U}$  with the first  $k$  eigenvectors<sup>1</sup> of the generalized eigenvalue problem  $\mathbf{L}\mathbf{u} = \lambda\mathbf{D}\mathbf{u}$  as its columns.*

Originally stated without proof in [2], we construct a full proof of the theorem here. It requires finding a lower bound for  $\text{Tr}(\mathbf{M}^T \mathbf{L} \mathbf{M})$ , and showing that  $\mathbf{M} := \mathbf{U}$  achieves this bound. For a brief mathematical background, we again refer to appendix A.

**Lemma 0.2** (Courant-Fischer Min-Max Theorem). *Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be some symmetric matrix with eigenvalues*

$$\lambda_1 \leq \dots \leq \lambda_n.$$

*Then,*

$$\lambda_d = \min_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=d}} \max_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}_n}} R_{\mathbf{A}}(\mathbf{x}),$$

where  $R_{\mathbf{A}}(\mathbf{x})$  denotes the Rayleigh-Ritz quotient [1], defined as

$$\frac{\mathbf{x}^T \mathbf{A} \mathbf{x}}{\mathbf{x}^T \mathbf{x}},$$

for any  $1 \leq d \leq n$ .

*Proof.* Let  $\mathbf{u}_1, \dots, \mathbf{u}_n \in \mathbb{R}^n$  be an orthonormal set of eigenvectors of  $\mathbf{A}$  corresponding to eigenvalues  $\lambda_1, \dots, \lambda_n$ , implying  $\|\mathbf{u}_d\|^2 = 1$  for  $1 \leq d \leq n$ . Since  $\mathbf{A}$  is symmetric, this set exists (see appendix A.1.2).

Now let  $S_d := \text{span}(\mathbf{u}_d, \dots, \mathbf{u}_n)$  and let  $S \subseteq \mathbb{R}^n$  be an arbitrary set with  $\dim(S) = d$ . If  $S_d \cap S = \{\mathbf{0}^n\}$ , then by lemma A.4,  $S_d + S$  would be a subspace of  $\mathbb{R}^n$  of dimension  $d + (n - d + 1) = n + 1$ , which is impossible by lemma A.5. Therefore,  $S_d \cap S \neq \{\mathbf{0}^n\}$ . Now let  $\mathbf{s} \in S_d \cap S$  such that  $\mathbf{s} \neq \mathbf{0}^n$ . Since  $\mathbf{s} \in S_d$ , we can write  $\mathbf{s}$  as a linear combination  $\mathbf{s} = \sum_{j=d}^n \alpha_j \mathbf{u}_j$ , for scalars  $\alpha_j \in \mathbb{R}$ . Then, we see

$$R_{\mathbf{A}}(\mathbf{s}) = \frac{\mathbf{s}^T \mathbf{A} \mathbf{s}}{\mathbf{s}^T \mathbf{s}} = \frac{\sum_{j=d}^n \alpha_j^2 \lambda_j}{\sum_{j=d}^n \alpha_j^2} \geq \frac{\sum_{j=d}^n \alpha_j^2 \lambda_d}{\sum_{j=d}^n \alpha_j^2} = \lambda_d,$$

where the inequality follows from  $\lambda_d \leq \dots \leq \lambda_n$ . Therefore,

$$\max_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}^n}} R_{\mathbf{A}}(\mathbf{x}) \geq \lambda_d.$$

Since  $S$  was chosen as an arbitrary subspace of  $\mathbb{R}^n$  with dimension  $d$ , this statement holds for all such sets.

In particular, it holds for  $S_1 := \text{span}(\mathbf{u}_1, \dots, \mathbf{u}_d)$ . Again, using lemma A.4, we can pick  $\mathbf{0}^n \neq \mathbf{s} \in S_1 \cap S_d$ , and write  $\mathbf{s} = \sum_{j=1}^d \beta_j \mathbf{u}_j$ , for scalars  $\beta_j \in \mathbb{R}$ . Analogously, we get

$$R_{\mathbf{A}}(\mathbf{s}) = \frac{\mathbf{s}^T \mathbf{A} \mathbf{s}}{\mathbf{s}^T \mathbf{s}} = \frac{\sum_{j=1}^d \beta_j^2 \lambda_j}{\sum_{j=1}^d \beta_j^2} \leq \frac{\sum_{j=1}^d \beta_j^2 \lambda_d}{\sum_{j=1}^d \beta_j^2} = \lambda_d,$$

where the inequality follows from  $\lambda_1 \leq \dots \leq \lambda_d$ . Combining the two inequalities, we get

$$\min_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=d}} \max_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}^n}} R_{\mathbf{A}}(\mathbf{x}) = \lambda_d,$$

which is what we wanted to show. □

<sup>1</sup>By 'the first  $k$  eigenvectors' we mean eigenvectors corresponding to the  $k$  smallest eigenvalues.

**Corollary 0.3.** *We have*

$$\lambda_n = \max_{\substack{\mathbf{x} \in \mathbb{R}^n \\ \mathbf{x} \neq \mathbf{0}^n}} R_A(\mathbf{x})$$

*Proof.* Any subspace  $S$  of  $\mathbb{R}^n$  of dimension  $n$  is equal to  $\mathbb{R}^n$  itself. The statement now follows from lemma 0.2.  $\square$

**Corollary 0.4.** *Let  $\mathbf{A}$  as in lemma 0.2. Then*

$$\lambda_d = \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=n-d+1}} \min_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}^n}} R_A(\mathbf{x})$$

*Proof.* Analogous as in lemma 0.2, by swapping  $S_d$  and  $S_1$ .  $\square$

**Lemma 0.5** (Part of Cauchy's Interlacing Theorem). *Suppose that  $1 \leq k \leq n$ . Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be symmetric, partitioned as*

$$\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{C}^T & \mathbf{D} \end{bmatrix}, \text{ with } \mathbf{B} \in \mathbb{R}^{k \times k}, \mathbf{D} \in \mathbb{R}^{(n-k) \times (n-k)}, \mathbf{C} \in \mathbb{R}^{k \times (n-k)},$$

*and let the  $\lambda_1^A \leq \dots \leq \lambda_n^A$  and  $\lambda_1^B \leq \dots \leq \lambda_k^B$  be the eigenvalues of  $\mathbf{A}$  and  $\mathbf{B}$ . Then,  $\lambda_d^A \leq \lambda_d^B$  for  $1 \leq d \leq k$ .*

*Proof.* From corollary 0.4, we have

$$\lambda_d^A = \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=n-d+1}} \min_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}^n}} R_A(\mathbf{x}).$$

Similarly, we get

$$\lambda_d^B = \max_{\substack{S \subseteq \mathbb{R}^k \\ \dim(S)=(n-k)-d+1}} \min_{\substack{\mathbf{y} \in S \\ \mathbf{y} \neq \mathbf{0}^n}} R_B(\mathbf{y}).$$

Now for any  $\mathbf{y} \in \mathbb{R}^k$  define  $\tilde{\mathbf{y}} \in \mathbb{R}^n$  which has the same elements as  $\mathbf{y}$  for the first  $k$  dimensions, and zero for the last  $n-k$  dimensions. Then,  $\mathbf{y}^T \mathbf{B} \mathbf{y} = \tilde{\mathbf{y}}^T \mathbf{A} \tilde{\mathbf{y}}$  and also  $\mathbf{y}^T \mathbf{y} = \tilde{\mathbf{y}}^T \tilde{\mathbf{y}}$ , whence  $R_B(\mathbf{y}) = R_A(\tilde{\mathbf{y}})$ . We can now rewrite  $\lambda_d^B$  as

$$\lambda_d^B = \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=n-d+1}} \min_{\substack{\tilde{\mathbf{y}} \in S, \dagger \\ \tilde{\mathbf{y}} \neq \mathbf{0}^n}} R_A(\tilde{\mathbf{y}}),$$

where  $\dagger$  refers to the condition on  $\tilde{\mathbf{y}}$  that its last  $n-k$  elements have to equal zero. Clearly, this is the same statement as  $\lambda_d^A$ , but with the extra condition  $\dagger$ . If we substitute  $\mathbf{x} := \tilde{\mathbf{y}}$ , we thus get

$$\lambda_d^A = \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=n-d+1}} \min_{\substack{\mathbf{x} \in S \\ \mathbf{x} \neq \mathbf{0}^n}} R_A(\mathbf{x}) \leq \max_{\substack{S \subseteq \mathbb{R}^n \\ \dim(S)=n-d+1}} \min_{\substack{\mathbf{x} \in S, \dagger \\ \mathbf{x} \neq \mathbf{0}^n}} R_A(\mathbf{x}) = \lambda_d^B.$$

$\square$

**Corollary 0.6** (part of the Poincaré Separation Theorem). *Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be symmetric and suppose that  $1 \leq k \leq n$ . Let  $\mathbf{u}_1, \dots, \mathbf{u}_k \in \mathbb{R}^n$  be an orthonormal set of vectors and let  $\mathbf{V} \in \mathbb{R}^{n \times k}$  be the (orthogonal) matrix with  $\mathbf{u}_1, \dots, \mathbf{u}_k$  as its columns. Set  $\mathbf{B} := \mathbf{V}^T \mathbf{A} \mathbf{V} \in \mathbb{R}^{k \times k}$  and arrange the eigenvalues of  $\mathbf{A}$  and  $\mathbf{B}$  as above. Then,  $\lambda_d^A \leq \lambda_d^B$  for  $1 \leq d \leq k$ .*

*Proof.* If  $k < n$ , pick  $n-k$  additional orthonormal vectors  $\mathbf{u}_{k+1}, \dots, \mathbf{u}_n \in \mathbb{R}^n$ , and let  $\mathbf{U} \in \mathbb{R}^{n \times n}$  be an extension of  $\mathbf{V}$  by adding these last orthonormal vectors as columns. Then,  $\mathbf{U}$  is an orthogonal matrix, i.e.  $\mathbf{U}^T \mathbf{U} = \mathbf{I}_n$ . By lemma A.10, we see that  $\mathbf{A}$  and  $\mathbf{U}^T \mathbf{A} \mathbf{U}$  share the same eigenvalues.

To finish our argument, see that removing the last  $n-k$  rows and columns of  $\mathbf{U}^T \mathbf{A} \mathbf{U}$  gives us back  $\mathbf{B}$ . Hence, lemma 0.5 gives us

$$\lambda_d^A = \lambda_d^{\mathbf{U}^T \mathbf{A} \mathbf{U}} \leq \lambda_d^B,$$

which is what we wanted to show.  $\square$

**Corollary 0.7.** *Let  $\mathbf{A}$  and  $\mathbf{B}$  as above. Then,  $\text{Tr}(\mathbf{B}) \geq \sum_{d=1}^k \lambda_d^A$ .*

*Proof.* Combining corollary 0.6 and the definition of  $\text{Tr}$  yields

$$\text{Tr}(\mathbf{B}) = \sum_{d=1}^k \lambda_d^{\mathbf{B}} \geq \sum_{d=1}^k \lambda_d^{\mathbf{A}}.$$

□

For our proof of theorem 0.1, we will rewrite our original objective

$$\begin{aligned} & \underset{\mathbf{M}}{\text{minimize}} && \text{Tr}(\mathbf{M}^T \mathbf{L} \mathbf{M}), \\ & \text{subject to} && \mathbf{M}^T \mathbf{D} \mathbf{M} = \mathbf{1}^{k \times k} \text{ and } \mathbf{M} \in \mathbb{R}^{n \times k}. \end{aligned}$$

to suit the form of corollary 0.6. To do so, let  $\mathbf{L}_{\mathbf{N}} := \mathbf{D}^{-\frac{1}{2}} \mathbf{L} \mathbf{D}^{-\frac{1}{2}} \in \mathbb{R}^{n \times n}$  and  $\mathbf{H} := \mathbf{D}^{\frac{1}{2}} \mathbf{M}$ . The objective then becomes

$$\begin{aligned} & \underset{\mathbf{H}}{\text{minimize}} && \text{Tr}(\mathbf{H}^T \mathbf{L}_{\mathbf{N}} \mathbf{H}), \\ & \text{subject to} && \mathbf{H}^T \mathbf{H} = \mathbf{1}^{k \times k} \text{ and } \mathbf{H} \in \mathbb{R}^{n \times k}. \end{aligned}$$

To enhance the structure of the proof, we will show one property of  $\mathbf{L}_{\mathbf{N}}$  that we will use.

**Lemma 0.8.** *If  $\mathbf{v}$  is an eigenvector of  $\mathbf{L}_{\mathbf{N}}$  with eigenvalue  $\lambda$ , then  $\mathbf{u} := \mathbf{D}^{-\frac{1}{2}} \mathbf{v}$  is a solution to the generalized eigenvalue problem  $\mathbf{L} \mathbf{u} = \lambda \mathbf{D} \mathbf{u}$ .*

*Proof.*

$$\begin{aligned} \mathbf{L}_{\mathbf{N}} \mathbf{v} = \lambda \mathbf{v} &\iff \mathbf{D}^{-\frac{1}{2}} \mathbf{L} \mathbf{D}^{-\frac{1}{2}} \mathbf{v} = \lambda \mathbf{v} \\ &\iff \mathbf{L} \mathbf{D}^{-\frac{1}{2}} \mathbf{v} = \lambda \mathbf{D}^{\frac{1}{2}} \mathbf{v} && \text{(multiplying by } \mathbf{D}^{\frac{1}{2}} \text{ from the left)} \\ &\iff \mathbf{L}(\mathbf{D}^{-\frac{1}{2}} \mathbf{v}) = \lambda \mathbf{D}(\mathbf{D}^{-\frac{1}{2}} \mathbf{v}) && \text{(by rearranging)} \\ &\iff \mathbf{L} \mathbf{u} = \lambda \mathbf{D} \mathbf{u}. \end{aligned}$$

□

*Proof of theorem 0.1.* By definition,  $\mathbf{L}_{\mathbf{N}} \in \mathbb{R}^{n \times n}$  is a symmetric matrix. Hence, corollary 0.7 applies, so

$$\text{Tr}(\mathbf{H}^T \mathbf{L}_{\mathbf{N}} \mathbf{H}) \geq \sum_{d=1}^k \lambda_d^{\mathbf{L}_{\mathbf{N}}},$$

for all  $\mathbf{H} \in \mathbb{R}^{n \times k}$  with  $\mathbf{H}^T \mathbf{H} = \mathbf{1}^{k \times k}$ .

Now set  $\mathbf{H}$  to be the matrix having the first  $k$  eigenvectors of  $\mathbf{L}_{\mathbf{N}}$ ,  $\mathbf{v}_1, \dots, \mathbf{v}_k \in \mathbb{R}^n$ , as its columns. It then follows that

$$\begin{aligned} \text{Tr}(\mathbf{H}^T \mathbf{L}_{\mathbf{N}} \mathbf{H}) &= \sum_{d=1}^k \mathbf{v}_d^T \mathbf{L}_{\mathbf{N}} \mathbf{v}_d \\ &= \sum_{d=1}^k \mathbf{v}_d^T \lambda_d^{\mathbf{L}_{\mathbf{N}}} \mathbf{v}_d \\ &= \sum_{d=1}^k (\mathbf{v}_d^T \mathbf{v}_d) \lambda_d^{\mathbf{L}_{\mathbf{N}}} \\ &= \sum_{d=1}^k \lambda_d^{\mathbf{L}_{\mathbf{N}}} && \text{(since } \mathbf{v}_d^T \mathbf{v}_d = 1) \end{aligned}$$

Combining everything, we get

$$\min_{\mathbf{H} \in \mathbb{R}^{n \times k}} \text{Tr}(\mathbf{H}^T \mathbf{L}_{\mathbf{N}} \mathbf{H}) = \sum_{d=1}^k \lambda_d^{\mathbf{L}_{\mathbf{N}}},$$

and this minimum is reached by the matrix  $\mathbf{H}$  having the first  $k$  eigenvectors of  $\mathbf{L}_{\mathbf{N}}$  as its columns. If we substitute back  $\mathbf{M} = \mathbf{D}^{-\frac{1}{2}} \mathbf{H}$ , we see by lemma 0.8 that the minimum for the original objective is reached by the matrix  $\mathbf{M}$  having the first  $k$  eigenvectors of the generalized eigenvalue problem  $\mathbf{L} \mathbf{u} = \lambda \mathbf{D} \mathbf{u}$ , which is what we wanted to show. □

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## Bibliography

- [1] Roger A Horn and Charles R Johnson. *Matrix analysis*. Cambridge university press, 2012.
- [2] Ahmed H Sameh and John A Wisniewski. A trace minimization algorithm for the generalized eigenvalue problem. *SIAM Journal on Numerical Analysis*, 19(6):1243–1259, 1982.

## A Mathematical prerequisites

### A.1 Linear algebra

#### A.1.1 Vector space

A vector space over  $\mathbb{R}$  is a non-empty set  $V$  equipped with an addition and a (scalar) multiplication operation, defined

$$\begin{aligned} + : V \times V &\rightarrow V \\ (\mathbf{x}, \mathbf{y}) &\mapsto \mathbf{x} + \mathbf{y} \end{aligned}$$

and

$$\begin{aligned} \cdot : \mathbb{R} \times V &\rightarrow V \\ (\lambda, \mathbf{y}) &\mapsto \lambda \cdot \mathbf{y} = \lambda \mathbf{y}, \end{aligned}$$

such that the following conditions hold:

- ▷ For all  $\mathbf{x}, \mathbf{y} \in V$  :  $\mathbf{x} + \mathbf{y} = \mathbf{y} + \mathbf{x}$
- ▷ For all  $\mathbf{x}, \mathbf{y}, \mathbf{z} \in V$  :  $(\mathbf{x} + \mathbf{y}) + \mathbf{z} = \mathbf{x} + (\mathbf{y} + \mathbf{z})$
- ▷ For all  $\mathbf{x}, \mathbf{y} \in V$  there exists a unique  $\mathbf{z} \in V$  such that  $\mathbf{x} + \mathbf{z} = \mathbf{y}$
- ▷ For all  $\mathbf{x} \in V$  and  $\lambda, \lambda' \in \mathbb{R}$  :  $(\lambda\lambda')\mathbf{x} = \lambda(\lambda'\mathbf{x})$
- ▷ For all  $\mathbf{x} \in V$  and  $\lambda, \lambda' \in \mathbb{R}$  :  $(\lambda + \lambda')\mathbf{x} = \lambda\mathbf{x} + \lambda'\mathbf{x}$
- ▷ For all  $\mathbf{x}, \mathbf{y} \in V$  and  $\lambda \in \mathbb{R}$  :  $\lambda(\mathbf{x} + \mathbf{y}) = \lambda\mathbf{x} + \lambda\mathbf{y}$
- ▷ For all  $\mathbf{x} \in V$  :  $1\mathbf{x} = \mathbf{x}$ .

Elements of the vector space  $V$  are called vectors. In this thesis, we will only use Euclidean vector spaces  $\mathbb{R}^d$  with  $d > 1$  with commonly defined dot product and norms. That is, for  $\mathbf{x} := [x_1, \dots, x_d]^T, \mathbf{y} := [y_1, \dots, y_d]^T \in \mathbb{R}^d$ , we denote the dot product between  $\mathbf{x}$  and  $\mathbf{y}$  by

$$\mathbf{x}^T \mathbf{y} = [x_1 \quad \dots \quad x_d] \begin{bmatrix} y_1 \\ \vdots \\ y_d \end{bmatrix} = \sum_{i=1}^d x_i y_i,$$

and the (Euclidean) norm of  $\mathbf{x}$  by

$$\|\mathbf{x}\| = \sqrt{\mathbf{x}^T \mathbf{x}}.$$

**Lemma A.1.**

$$\|\mathbf{x} - \mathbf{y}\|^2 = \|\mathbf{x}\|^2 - 2\mathbf{x}^T \mathbf{y} + \|\mathbf{y}\|^2.$$

*Proof.* We have

$$\begin{aligned} \|\mathbf{x} - \mathbf{y}\|^2 &= (\mathbf{x} - \mathbf{y})^T (\mathbf{x} - \mathbf{y}) \\ &= \sum_{i=1}^d (x_i - y_i)^2 \\ &= \sum_{i=1}^d (x_i)^2 + \sum_{i=1}^d (y_i)^2 - 2 \sum_{i=1}^d x_i y_i \\ &= \|\mathbf{x}\|^2 - 2\mathbf{x}^T \mathbf{y} + \|\mathbf{y}\|^2. \end{aligned}$$

□

Two vectors  $\mathbf{x}$  and  $\mathbf{y}$  are called orthogonal if  $\mathbf{x}^T \mathbf{y} = 0$ , and orthonormal if they are orthogonal and additionally  $\|\mathbf{x}\| = \|\mathbf{y}\| = 1$ .

A linear combination of vectors  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$  is a vector  $\mathbf{x} \in \mathbb{R}^d$  such that

$$\mathbf{x} = \lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n$$

for some  $\lambda_1, \dots, \lambda_n \in \mathbb{R}$ . Vectors  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$  are said to be linearly independent if the linear combination such that

$$\lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n = \mathbf{0}^d$$

is achieved only with  $\lambda_1 = \dots = \lambda_n = 0$ . The span of vectors  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^d$ , denoted  $\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)$  is the set of all linear combinations of  $\mathbf{x}_1, \dots, \mathbf{x}_n$ .

**Lemma A.2.** *If  $\mathbf{x}_1, \dots, \mathbf{x}_n$  are orthonormal, they are linearly independent.*

*Proof.* Let  $\lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n = \mathbf{0}^d$ , and consider that for any  $1 \leq j \leq n$ , we have

$$\begin{aligned} \mathbf{x}_j^T \cdot (\lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n) &= (\lambda_1 \mathbf{x}_j^T \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_j^T \mathbf{x}_n) \\ &= \lambda_j \mathbf{x}_j^T \mathbf{x}_j. \end{aligned}$$

Since  $\mathbf{x}_j^T \mathbf{x}_j = \mathbf{0}^d$  implies  $\mathbf{x}_j^T$  (which contradicts orthonormality) it holds that  $\lambda_j = 0$ . Hence,  $\lambda_1 = \dots = \lambda_n = 0$ .  $\square$

A subspace  $W \subset V$  is a subset of  $V$  such that

- ▷  $\mathbf{0} \in W$
- ▷ For all  $\mathbf{x}, \mathbf{y} \in W$ :  $\mathbf{x} + \mathbf{y} \in W$ , and
- ▷ For all  $\mathbf{x} \in W$ ,  $\lambda \in \mathbb{R}$ :  $\lambda \mathbf{x} \in W$ .

Given two subspaces  $W, W' \subset V$ , the sets  $W \cap W'$  and  $W + W' := \{\mathbf{w} + \mathbf{w}' \mid \mathbf{w} \in W, \mathbf{w}' \in W'\}$  are also subspaces of  $V$ . The dimension of a subspace  $W$  – denoted  $\dim(W)$  – is the largest number  $k$  such that there exist  $k$  linearly independent vectors in  $W$ .

**Lemma A.3.** *Let  $\mathbf{x}_1, \dots, \mathbf{x}_n$  be orthonormal. Then it holds that  $\dim(\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)) = n$ .*

*Proof.* By lemma A.2 we know  $\dim(\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)) \geq n$ . By definition, all elements  $\mathbf{x}$  of  $\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)$  are linear combinations of  $\mathbf{x}_1, \dots, \mathbf{x}_n$ , and thus any  $\mathbf{x} \in \text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)$  can be written as  $\mathbf{x} = \lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n$ , or  $\mathbf{0}^d = \lambda_1 \mathbf{x}_1 + \dots + \lambda_n \mathbf{x}_n - \mathbf{x}$ . Since at least the last scalar is non-zero,  $\mathbf{x}$  is not linearly independent. Hence,  $\dim(\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)) = n$ .  $\square$

**Lemma A.4.** *For two subspaces  $W, W' \subseteq V$  of a vector space  $V$ , we have  $\dim(W) + \dim(W') = \dim(W + W')$  if  $W \cap W' = \{\mathbf{0}^d\}$ .*

*Proof.* Let  $\dim(W) := r$  and  $\dim(W') := s$ , and let  $\mathbf{u}_1, \dots, \mathbf{u}_r \in W$ ,  $\mathbf{v}_1, \dots, \mathbf{v}_s \in W'$  be two linearly independent sets of vectors. We will show that  $\mathbf{u}_1, \dots, \mathbf{u}_r, \mathbf{v}_1, \dots, \mathbf{v}_s$  are all linear independent from each other. To do so, let

$$\mathbf{0}^d = \sum_{i=1}^r \lambda_i \mathbf{u}_i + \sum_{j=1}^s \lambda'_j \mathbf{v}_j,$$

or

$$\sum_{i=1}^r \lambda_i \mathbf{u}_i = - \sum_{j=1}^s \lambda'_j \mathbf{v}_j.$$

Let  $\mathbf{x} := \sum_{i=1}^r \lambda_i \mathbf{u}_i = - \sum_{j=1}^s \lambda'_j \mathbf{v}_j$ . By definition of subspaces,  $\mathbf{x} \in W$  and also  $\mathbf{x} \in W'$ , so  $\mathbf{x} \in W \cap W'$ . Since  $W \cap W' = \{\mathbf{0}^d\}$  however, we know,  $\sum_{i=1}^r \lambda_i \mathbf{u}_i = - \sum_{j=1}^s \lambda'_j \mathbf{v}_j = \mathbf{0}^d$ . Since  $\mathbf{u}_1, \dots, \mathbf{u}_r$  and  $\mathbf{v}_1, \dots, \mathbf{v}_s$  are linearly independent, this means  $\lambda_1 = \dots = \lambda_r = \lambda'_1 = \dots = \lambda'_s = 0$ , which in turn means  $\mathbf{u}_1, \dots, \mathbf{u}_r, \mathbf{v}_1, \dots, \mathbf{v}_s$  are linearly independent.

Now let  $\mathbf{x} \in W + W'$ , such that it can be written as  $\mathbf{x} = \sum_{i=1}^r \lambda_i \mathbf{u}_i + \sum_{j=1}^s \lambda'_j \mathbf{v}_j$ . By the same argument as lemma A.3 we see  $\mathbf{x}$  is not linearly independent from  $\mathbf{u}_1, \dots, \mathbf{u}_r, \mathbf{v}_1, \dots, \mathbf{v}_s$ . Since  $\mathbf{x}$  was chosen arbitrarily, there

exist at most  $r + s$  linearly independent vectors in  $W + W'$ , i.e.  $\dim(W + W') = r + s = \dim(W) + \dim(W')$ , which is what we wanted to show.  $\square$

**Lemma A.5.**  $\dim(\mathbb{R}^d) = d$ .

*Proof.* Clearly, vectors  $[1, 0 \cdots 0]^T, [0, 1 \cdots 0]^T, \dots, [0, 0 \cdots 1]^T \in \mathbb{R}^d$  are linearly independent. Therefore,  $\dim(\mathbb{R}^d) \geq d$ . Now let  $\mathbf{x} = [x_1 \cdots x_d]^T$  be some other element of  $\mathbb{R}^d$ . Then,  $\mathbf{x}$  can be written as

$$\mathbf{x} = x_1 \cdot [10 \cdots 0]^T + \cdots + x_d \cdot [00 \cdots 1]^T,$$

which means  $\mathbf{x}$  is not linearly independent from  $[10 \cdots 0]^T, [01 \cdots 0]^T, \dots, [00 \cdots 1]^T$ . Since  $\mathbf{x}$  was chosen arbitrarily,  $\dim(\mathbb{R}^d) = d$ .  $\square$

### A.1.2 Matrices

A matrix is a rectangular array of objects – which, in the context of this thesis, are all real numbers – called entries. A matrix with  $n$  rows and  $k$  columns is a  $n \times k$  matrix, and the set of all such matrices is denoted  $\mathbb{R}^{n \times k}$  ( $n$  and  $k$  are also called the dimensions). The entry in the  $i$ -th row and  $j$ -th column of a matrix  $\mathbf{M} \in \mathbb{R}^{n \times k}$  is denoted  $(\mathbf{M})_{ij}$ , such that the matrix can be portrayed visually as

$$\mathbf{M} = \begin{bmatrix} (\mathbf{M})_{11} & (\mathbf{M})_{12} & \dots & (\mathbf{M})_{1k} \\ (\mathbf{M})_{21} & (\mathbf{M})_{22} & \dots & (\mathbf{M})_{2k} \\ \vdots & \vdots & \ddots & \vdots \\ (\mathbf{M})_{n1} & (\mathbf{M})_{n2} & \dots & (\mathbf{M})_{nk} \end{bmatrix}.$$

A  $d$ -dimensional (row) vector is also a  $1 \times d$ -dimensional matrix. There are a couple basic operations defined on matrices: addition, (scalar) multiplication and transposition. Addition and scalar multiplication function entrywise, i.e. for  $\mathbf{M}, \mathbf{M}' \in \mathbb{R}^{n \times k}$ ,  $\lambda \in \mathbb{R}$ :

$$\begin{aligned} (\mathbf{M} + \mathbf{M}')_{ij} &= (\mathbf{M})_{ij} + (\mathbf{M}')_{ij}, \\ (\lambda \mathbf{M})_{ij} &= \lambda (\mathbf{M})_{ij}. \end{aligned}$$

Switching rows and columns, we get the transpose of  $\mathbf{M}$ , denoted  $\mathbf{M}^T$ , defined as

$$(\mathbf{M}^T)_{ij} = (\mathbf{M})_{ji}.$$

Multiplication of two matrices is defined for matrices  $\mathbf{M} \in \mathbb{R}^{n \times k}$  and  $\mathbf{M}' \in \mathbb{R}^{k \times n'}$  – such that the number of columns in  $\mathbf{M}$  equals the number of rows in  $\mathbf{M}'$  – and returns a matrix  $\mathbf{M}\mathbf{M}' \in \mathbb{R}^{n \times n'}$  such that

$$(\mathbf{M}\mathbf{M}')_{ij} = \sum_{r=1}^k (\mathbf{M})_{ir} (\mathbf{M}')_{rj} = \mathbf{m}_i^T \mathbf{m}'_j,$$

where  $\mathbf{m}_i$  and  $\mathbf{m}'_j$  refer to the  $i$ -th row of  $\mathbf{M}$  and  $j$ -th column of  $\mathbf{M}'$  respectively. A few properties using and connecting the operations include:

- ▷  $\mathbf{M}(\mathbf{M}' + \mathbf{M}'') = \mathbf{M}\mathbf{M}' + \mathbf{M}\mathbf{M}''$
- ▷  $\mathbf{M}(\mathbf{M}'\mathbf{M}'') = (\mathbf{M}\mathbf{M}')\mathbf{M}''$
- ▷  $(\mathbf{M}^T)^T = \mathbf{M}$
- ▷  $(\mathbf{M} + \mathbf{M}')^T = \mathbf{M}^T + \mathbf{M}'^T$

If  $\mathbf{M}^T = \mathbf{M}$  we call  $\mathbf{M}$  symmetric. A matrix  $\mathbf{M} \in \mathbb{R}^{n \times n}$  is called orthogonal if the columns of  $\mathbf{M}$  form a set of orthonormal vectors, such that  $\mathbf{M}^T \mathbf{M} = \mathbf{1}^{n \times n}$ . Here,  $\mathbf{1}^{n \times n}$  is the identity matrix defined as  $(\mathbf{1})_{ij} = \delta_{ij}$  where  $\delta_{ij}$  is the Kronecker delta. The  $n \times k$  matrix with only zero entries is denoted  $\mathbf{0}^{n \times k}$ .

Multiplication of a matrix with a vectors induces another important notion we will use: eigenvectors. For any square matrix  $\mathbf{M} \in \mathbb{R}^{n \times n}$ ,  $\mathbf{x} \in \mathbb{R}^n$ , we call  $\mathbf{x}$  an eigenvector of  $\mathbf{M}$  if

$$\mathbf{M}\mathbf{x} = \lambda \mathbf{x}$$

for some  $\lambda \in \mathbb{R}$ , and call  $\lambda$  a eigenvalue of  $\mathbf{M}$ .

**Lemma A.6.** *If  $\mathbf{v}$  is an eigenvector of  $\mathbf{M}$  with eigenvalue  $\lambda$  then  $\alpha\mathbf{v}$  is also an eigenvector  $\mathbf{M}$  with eigenvalue  $\lambda$  for any  $0 \neq \alpha \in \mathbb{R}$ .*

*Proof.* Let  $\lambda$  be the eigenvalue corresponding to  $\mathbf{v}$ . Then, we have

$$\mathbf{M}(\alpha\mathbf{v}) = \alpha(\mathbf{M}\mathbf{v}) = \alpha\lambda\mathbf{v} = \lambda(\alpha\mathbf{v}).$$

□

Lemma A.6 tells us it is silly to speak of *the* eigenvectors of  $\mathbf{M}$ , when in fact there are an infinite amount of them corresponding to every distinct eigenvalue. In particular, for every  $\lambda$  we can construct an eigenvector of unit length by picking some eigenvector  $\mathbf{v}$  and determining

$$\frac{1}{\|\mathbf{v}\|}\mathbf{v}.$$

**Lemma A.7.** *Let  $\mathbf{M}$  be symmetric. Then, any two eigenvectors of  $\mathbf{M}$  with distinct eigenvalues are orthogonal.*

*Proof.* Let  $\mathbf{x}, \mathbf{y}$  be distinct eigenvectors with eigenvalues  $\lambda$  and  $\lambda'$ ,  $\lambda \neq \lambda'$ . Then by definition the following holds:

$$\begin{aligned}\mathbf{M}\mathbf{x} &= \lambda\mathbf{x} \\ \mathbf{M}\mathbf{y} &= \lambda'\mathbf{y}.\end{aligned}$$

It now follows that

$$\begin{aligned}\lambda(\mathbf{x}^T \mathbf{y}) &= (\lambda\mathbf{x})^T \mathbf{y} \\ &= (\mathbf{M}\mathbf{x})^T \mathbf{y} \\ &= \mathbf{x}^T \mathbf{M}^T \mathbf{y} \\ &= \mathbf{x}^T \mathbf{M} \mathbf{y} \\ &= \mathbf{x}^T \lambda' \mathbf{y} \\ &= \lambda'(\mathbf{x}^T \mathbf{y}),\end{aligned}$$

meaning  $0 = (\lambda - \lambda')(\mathbf{x}^T \mathbf{y})$ . Since  $\lambda \neq \lambda'$ , we have  $\mathbf{x}^T \mathbf{y} = 0$ , which means  $\mathbf{x}$  and  $\mathbf{y}$  are orthogonal. □

A  $n \times n$  symmetric matrix  $\mathbf{M}$  is called positive semi-definite if and only if  $\mathbf{x}^T \mathbf{M} \mathbf{x} \geq 0$  for all  $\mathbf{x} \in \mathbb{R}^n$ .

**Lemma A.8.** *If  $\mathbf{M}$  is positive semi-definite, it has only non-negative eigenvalues.*

*Proof.* Let  $\lambda$  be some eigenvalue of  $\mathbf{M}$  and let  $\mathbf{v}$  be some corresponding eigenvector. Then it holds that  $0 \leq \mathbf{v}^T \mathbf{M} \mathbf{v} = \mathbf{v}^T (\lambda \mathbf{v}) = (\mathbf{v}^T \mathbf{v}) \lambda$ . Since  $\mathbf{v}^T \mathbf{v} \geq 0$  (easily checked) it must be the case that  $\lambda \geq 0$ . □

Combining lemma A.6, A.7 and A.8, we see that for any positive semi-definite matrix  $\mathbf{M}$ , we know  $\mathbf{M}$  has eigenvalues  $0 \leq \lambda_1 \leq \dots \leq \lambda_k$  (for some  $k > 0$ ), such that there exists an orthonormal set of eigenvectors  $\mathbf{v}_1, \dots, \mathbf{v}_k$  corresponding to those eigenvalues.

For any eigenvalue  $\lambda$ , we define its eigenspace  $E_{\mathbf{M}}(\lambda)$  as the set of all eigenvectors corresponding to this eigenvalue, i.e. for some  $\mathbf{M} \in \text{mathbb{R}}^{n \times n}$  it is defined as

$$\{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{M}\mathbf{x} = \lambda\mathbf{x}\}.$$

**Lemma A.9.** *For any  $\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{y} \in \mathbb{R}^d$ , with  $\mathbf{x}_i := [x_i^1, \dots, x_i^d]^T$  for  $1 \leq i \leq n$ , we have*

$$\sum_{i=1}^n \mathbf{x}_i^T \mathbf{y} = \left( \sum_{i=1}^n \mathbf{x}_i \right)^T \mathbf{y}$$



*Proof.*

$$\begin{aligned}\sum_{i=1}^n \mathbf{x}_i^T \mathbf{y} &= \left( \sum_{i=1}^n \mathbf{x}_i^T \right) \cdot \mathbf{y} \\ &= \left( \sum_{i=1}^n \mathbf{x}_i \right)^T \cdot \mathbf{y}. \quad (\text{since } (\mathbf{M} + \mathbf{M}')^T = \mathbf{M}^T + \mathbf{M}'^T)\end{aligned}$$

□

**Lemma A.10.** *Let  $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ . Then  $\lambda \neq 0$  is an eigenvalue of  $\mathbf{AB}$  iff  $\lambda$  is an eigenvalue of  $\mathbf{BA}$ .*

*Proof.* Let  $\mathbf{u}$  be an eigenvector of  $\mathbf{AB}$  associated with eigenvalue  $\lambda$ , i.e.  $\mathbf{ABu} = \lambda \mathbf{u}$ . Let  $\mathbf{v} := \mathbf{Bu}$ . Then,

$$\begin{aligned}\mathbf{BAv} &= \mathbf{BABu} \\ &= \mathbf{B}(\mathbf{ABu}) \\ &= \mathbf{B}\lambda \mathbf{u} \\ &= \lambda(\mathbf{Bu}) \\ &= \lambda \mathbf{v}.\end{aligned}$$

Hence,  $\lambda$  is an eigenvalue of  $\mathbf{BA}$  too. The other implication follows analogously, mutatis mutandis. □

Lastly, the trace of a square matrix  $\mathbf{M}$ , denoted  $\text{Tr}(\mathbf{M})$  is the sum of its diagonal elements, i.e.

$$\text{Tr}(\mathbf{M}) = \sum_{i=1}^n (\mathbf{M})_{ii}.$$

It can be shown that the trace is equal to the sum of the eigenvalues of  $\mathbf{M}$ .