Learning relational meanings from situated caregiver-child interaction

A computational approach

Barend Beekhuizen¹, Afsaneh Fazly², Aida Nematzadeh² & Suzanne Stevenston²

¹Leiden University ²University of Toronto

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Introduction

Topic

Cognitive models of acquiring word-meaning mappings

Goals

- methodological issues: Discuss sources of semantic data for models and present a new one
- Providing a baseline: Explore the behavior of a basic word-learning model on this data
- extending the model: Show how we can add 'modules' to the model

- $\bullet \ \mathsf{Cross\text{-}situational} \ \mathsf{learning} \to \mathsf{computational} \ \mathsf{models} \\$
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- 32 dyads (child 16mo, \pm 5 min. each) playing game.
- 175 minutes of material, 7842 word tokens, 2492 utterances.
- Situational coding. For every interval of 3 seconds, code:
 - simple behavior (grab, move, position, letgo),
 - changes in spatial relations (in,on,out,off,match),
 - objects (block, bucket, mother, table)
 - properties (triangular, square, red, blue)



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 - properties (triangular, square, red, blue)
- Structured: grab(mother, (red, square, block))
- High intra- & interannotator agreement (almost all $\kappa > 0.8$)

Example

time type	coding/transcription
0m0s situation	
language	een. nou jij een.
translation	"One. Now you try one."
0m3s situation	position(mother, toy, on(toy, floor)) grab(child, b-ye-
	tr) move(child, b-ye-tr, on(b-ye-tr, floor), near(b-ye-tr,
	ho-ro)), mismatch(b-ye-tr, ho-ro)
language	nee daar.
translation	"No, there."
Om6s situation	point(mother, ho-tr, child) position(child, b-ye-tr,
	near(b-ye-tr, ho-ro)) mismatch(b-ye-tr, ho-ro)
language	nee lieverd hier past ie niet.
translation	"No sweetie, it won't fit in here."

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- FAS10: incremental model of aligning words in utterance $U = \{w_1, \dots, w_n\}$ with features in situation $S = \{f_1, \dots, f_n\}$
- Data preparation
 - Representations are structured, so flatten them: grab(mother,(red,square,block)) → {grab,mother,red,square,block}
 - Take the set of all flattened representations of the situations occurring in the interval in which the utterance was produced.
 - We used lemma representations for the words



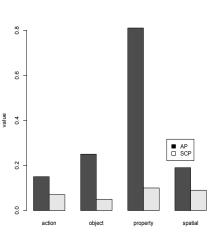
Baseline experiment: evaluation

- No golden lexicon, so hand-built one for 'meaningful' words (n = 41):
 - Object labels: blok meaning block
 - Properties: rood meaning red
 - Spatial relations: op meaning on
 - Actions: passen meaning match, stoppen meaning {move,in}

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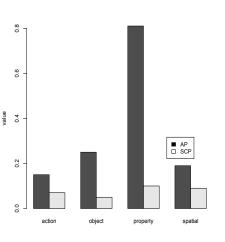
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- Two (partially complementary) measures:
 - Summed Conditional Probability (SCP): how much probability mass is assigned to the true meanings given a word?
 - Average Precision (AP): how are the true meanings ranked (on conditional probability) w.r.t. the other meanings.

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- AP (ranking): good for properties, rather bad for other classes.
- No model dependence.
- Relational meanings hard to glean from situation alone. Why?
 - True meaning absent from S
 - Poil features structurally present in
 - **3** True meaning also present in many other *S*s
- In general: situations look a lot like each other, unlike 'synthesized' semantics (cf. Matusevych et al. 2013)

Exploring known biases/mechanisms

added bias/mechanism	prop.	object	spatial	actions
INTENTION				
increasing temporal scope	=	\uparrow	↑	\uparrow
attention to own behavior	=	\downarrow	\downarrow	\uparrow
attention to mother's behavior	\uparrow	\downarrow	\downarrow	=
ATTENTION				
only take novel features	\downarrow	\downarrow	\downarrow	\uparrow
more weight to novel features	\downarrow	\downarrow	\uparrow	\uparrow
more weight to rarer features	\uparrow	\uparrow	\uparrow	\uparrow
more weight to expected features	\uparrow	$\uparrow\downarrow$	$\uparrow\downarrow$	=
LINGUISTIC STRUCTURE				
using parts of speech	=	\downarrow	=	=
Mintz' frequent frames	\downarrow	\downarrow	=	<u> </u>



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- Exploring other mechanisms
 - method to evaluate their contribution
 - what works:
 - attention to rare events,
 - increasing temporal scope,
 - adding words from previous utterances
 - other mechanisms are mixed: e.g. good for verbs, bad for rest



FAS10

• Calculating alignment on the basis of conditional probabilities:

$$a(w|f, U^{(t)}, S^{(t)}) = \frac{p^{(t-1)}(f|w)}{\sum\limits_{w' \in U^{(t)}} p^{(t-1)}(f|w')}$$
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Recalculating the conditional probabilities:

$$p^{(t)}(f|w) = \frac{\mathsf{assoc}^{(t)}(w,f) + \lambda}{\sum\limits_{f' \in F} \mathsf{assoc}^{(t)}(w,f') + \beta \times \lambda} \tag{3}$$