Team notebook

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1 Dynamic Programming

1.1 convex hull trick

```
struct line {
 long long m, b;
 line (long long a, long long c) : m(a), b(c) {}
 long long eval(long long x) {
   return m * x + b;
 }
};
long double inter(line a, line b) {
 long double den = a.m - b.m;
 long double num = b.b - a.b;
 return num / den;
}
 * min m_i * x_j + b_i, for all i.
      x_j \le x_{j+1}
      m_i >= m_{i} + 1
* */
struct ordered_cht {
```

```
vector<line> ch;
  int idx; // id of last "best" in query
  ordered_cht() {
   idx = 0;
  void insert_line(long long m, long long b) {
   line cur(m, b);
   // new line's slope is less than all the previous
   while (ch.size() > 1 &&
      (inter(cur, ch[ch.size() - 2]) >= inter(cur, ch[ch.size() - 1]))) {
       // f(x) is better in interval [inter(ch.back(), cur), inf)
       ch.pop_back();
   ch.push_back(cur);
  long long eval(long long x) { // minimum
   // current x is greater than all the previous x,
   // if that is not the case we can make binary search.
   idx = min<int>(idx, ch.size() - 1);
   while (idx + 1 < (int)ch.size() \&\& ch[idx + 1].eval(x) <=
        ch[idx].eval(x)
     idx++;
   return ch[idx].eval(x);
};
 * Dynammic convex hull trick
```

UTP

```
typedef long long int64;
typedef long double float128;
const int64 is_query = -(1LL<<62), inf = 1e18;</pre>
struct Line {
 int64 m. b:
 mutable function<const Line*()> succ;
 bool operator<(const Line& rhs) const {</pre>
   if (rhs.b != is_query) return m < rhs.m;</pre>
   const Line* s = succ();
   if (!s) return 0;
   int64 x = rhs.m:
   return b - s -> b < (s -> m - m) * x;
 }
};
struct HullDynamic : public multiset<Line> { // will maintain upper hull
    for maximum
 bool bad(iterator y) {
   auto z = next(y);
   if (y == begin()) {
     if (z == end()) return 0;
     return y->m == z->m && y->b <= z->b;
   auto x = prev(y);
   if (z == end()) return y->m == x->m && y->b <= x->b;
   return (float128)(x->b - y->b)*(z->m - y->m) >= (float128)(y->b - y->m)
        z->b)*(v->m - x->m);
 void insert_line(int64 m, int64 b) {
   auto y = insert({ m, b });
   y->succ = [=] { return next(y) == end() ? 0 : &*next(y); };
   if (bad(y)) { erase(y); return; }
   while (next(y) != end() && bad(next(y))) erase(next(y));
   while (y != begin() && bad(prev(y))) erase(prev(y));
 }
 int64 eval(int64 x) {
   auto 1 = *lower_bound((Line) { x, is_query });
   return 1.m * x + 1.b;
 }
};
```

2 Graphs

2.1 dinic

```
// taken from
    https://github.com/jaehyunp/stanfordacm/blob/master/code/MinCostMaxFlow.cc
typedef long long LL;
struct edge {
 int u, v;
 LL cap, flow;
 edge() {}
 edge(int u, int v, LL cap): u(u), v(v), cap(cap), flow(0) {}
struct dinic {
 int N:
 vector<edge> E;
 vector<vector<int>> g;
 vector<int> d, pt;
 dinic(int N): N(N), E(O), g(N), d(N), pt(N) {}
 void add_edge(int u, int v, LL cap) {
   if (u != v) {
     E.emplace_back(edge(u, v, cap));
     g[u].emplace_back(E.size() - 1);
     E.emplace_back(edge(v, u, 0));
     g[v].emplace_back(E.size() - 1);
   }
 }
 bool bfs(int S, int T) {
   queue<int> q({S});
   fill(d.begin(), d.end(), N + 1);
   d[S] = 0;
   while(!q.empty()) {
     int u = q.front(); q.pop();
     if (u == T) break;
     for (int k: g[u]) {
       edge &e = E[k];
       if (e.flow < e.cap && d[e.v] > d[e.u] + 1) {
        d[e.v] = d[e.u] + 1;
         q.emplace(e.v);
```

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```

```
}
     }
   }
   return d[T] != N + 1;
 LL dfs(int u, int T, LL flow = -1) {
   if (u == T || flow == 0) return flow;
   for (int &i = pt[u]; i < int(g[u].size()); ++i) {</pre>
     edge &e = E[g[u][i]];
     edge &oe = E[g[u][i]^1];
     if (d[e.v] == d[e.u] + 1) {
       LL amt = e.cap - e.flow;
       if (flow != -1 && amt > flow) amt = flow;
       if (LL pushed = dfs(e.v, T, amt)) {
         e.flow += pushed;
         oe.flow -= pushed;
         return pushed;
       }
     }
   }
   return 0;
 }
 LL max_flow(int S, int T) {
   LL total = 0;
   while (bfs(S, T)) {
     fill(pt.begin(), pt.end(), 0);
     while (LL flow = dfs(S, T))
       total += flow;
   }
   return total;
 }
};
```