

Statistical models for large spatial datasets

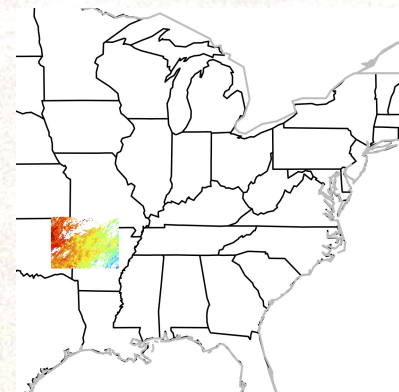
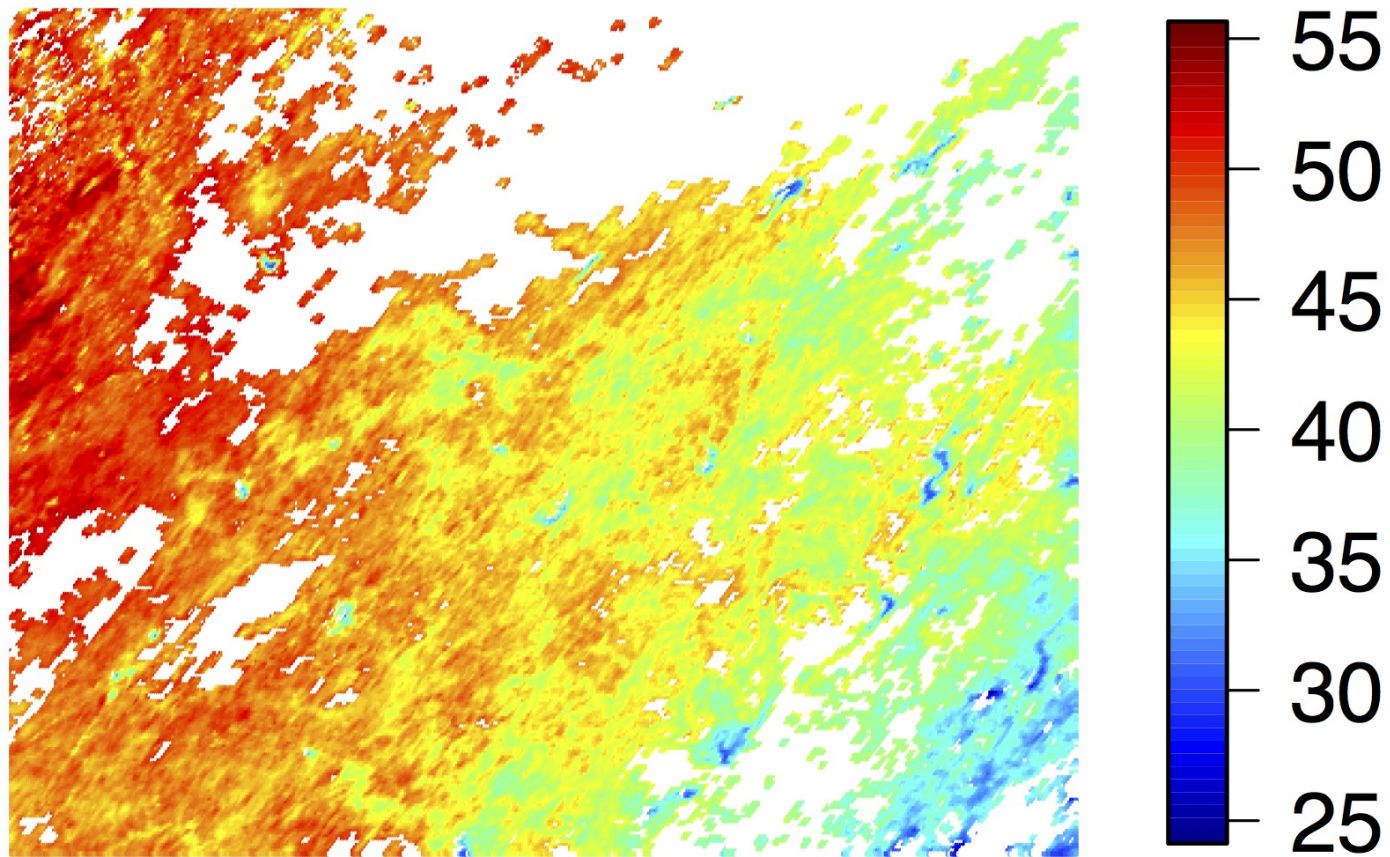
Douglas Nychka,
Colorado School of Mines



Introduction

- Examples of large spatial data and the problems
- Some cartoons and a spatial model
- Multi-resolution model
- LatticeKrig – properties
- LatticeKrig in action.

Remotely sensed temperatures



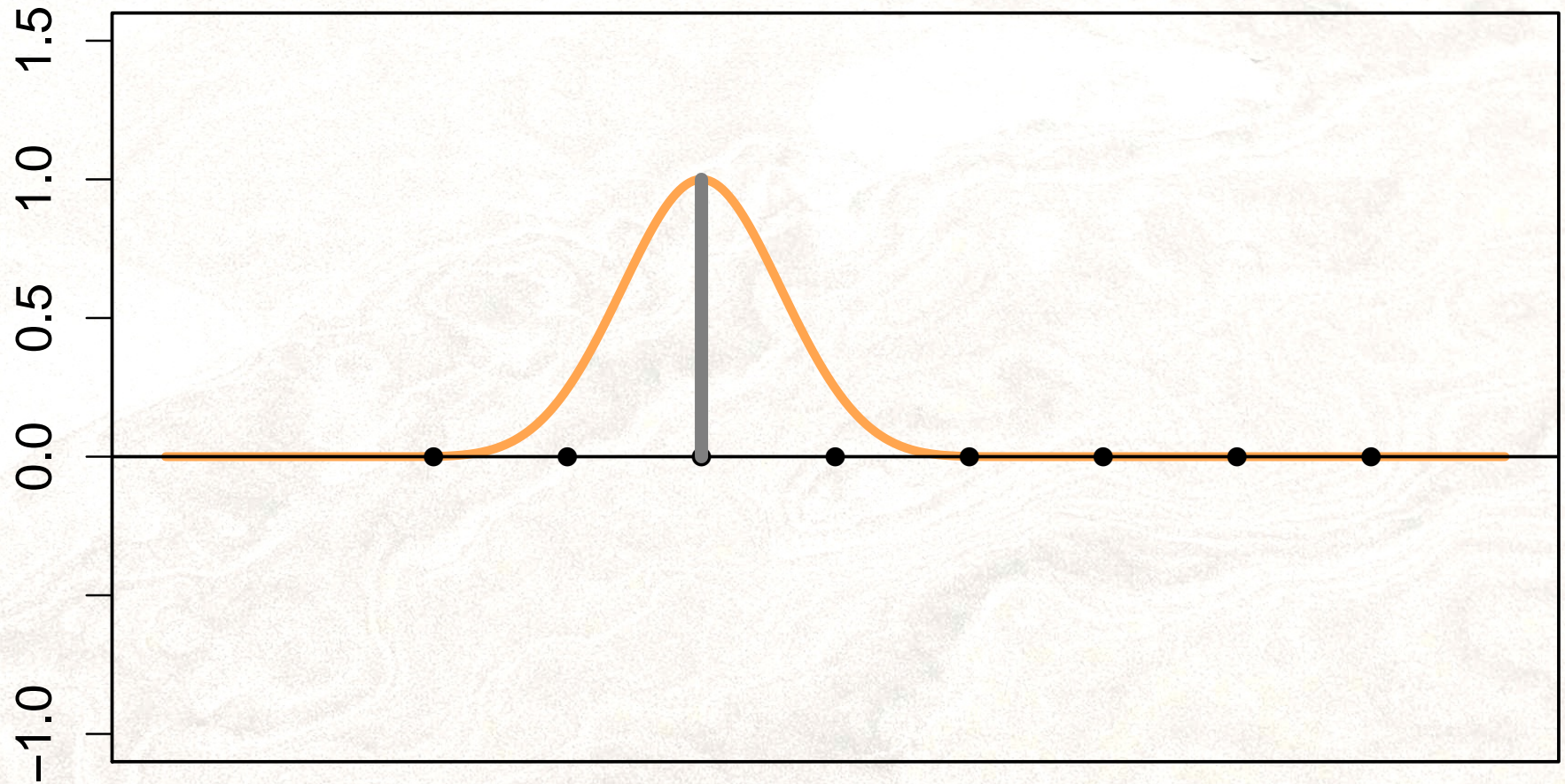
About 100K observations

Problems with large spatial data sets

- Storage: Covariance matrices are large – size of the number of observations
- Computation: Linear algebra for the usual Kriging estimator grows as the cube of the number of observations.
- Inference: Exact prediction standard errors are not computationally feasible.

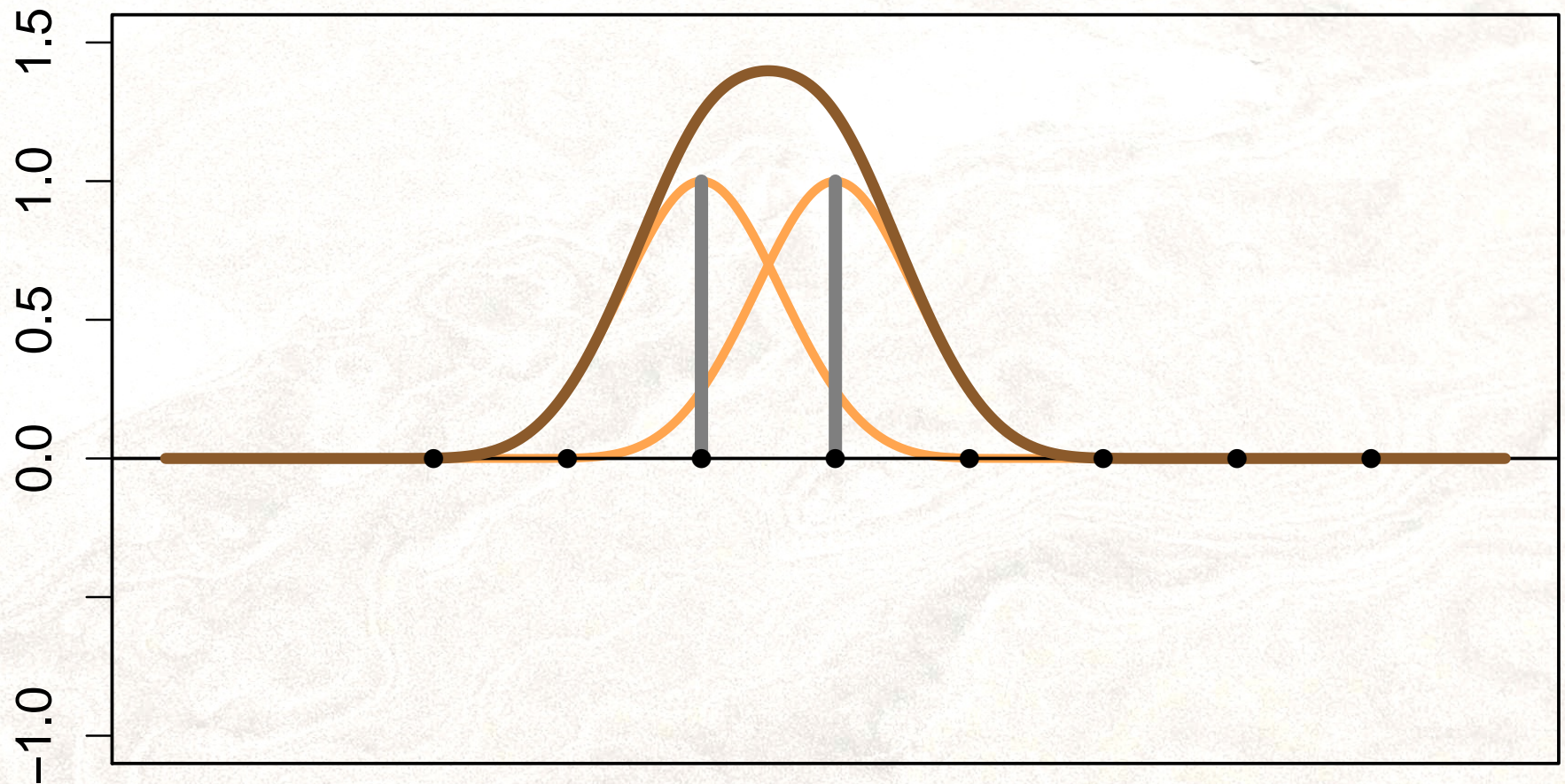
Cartoons

Building a curve from bumps



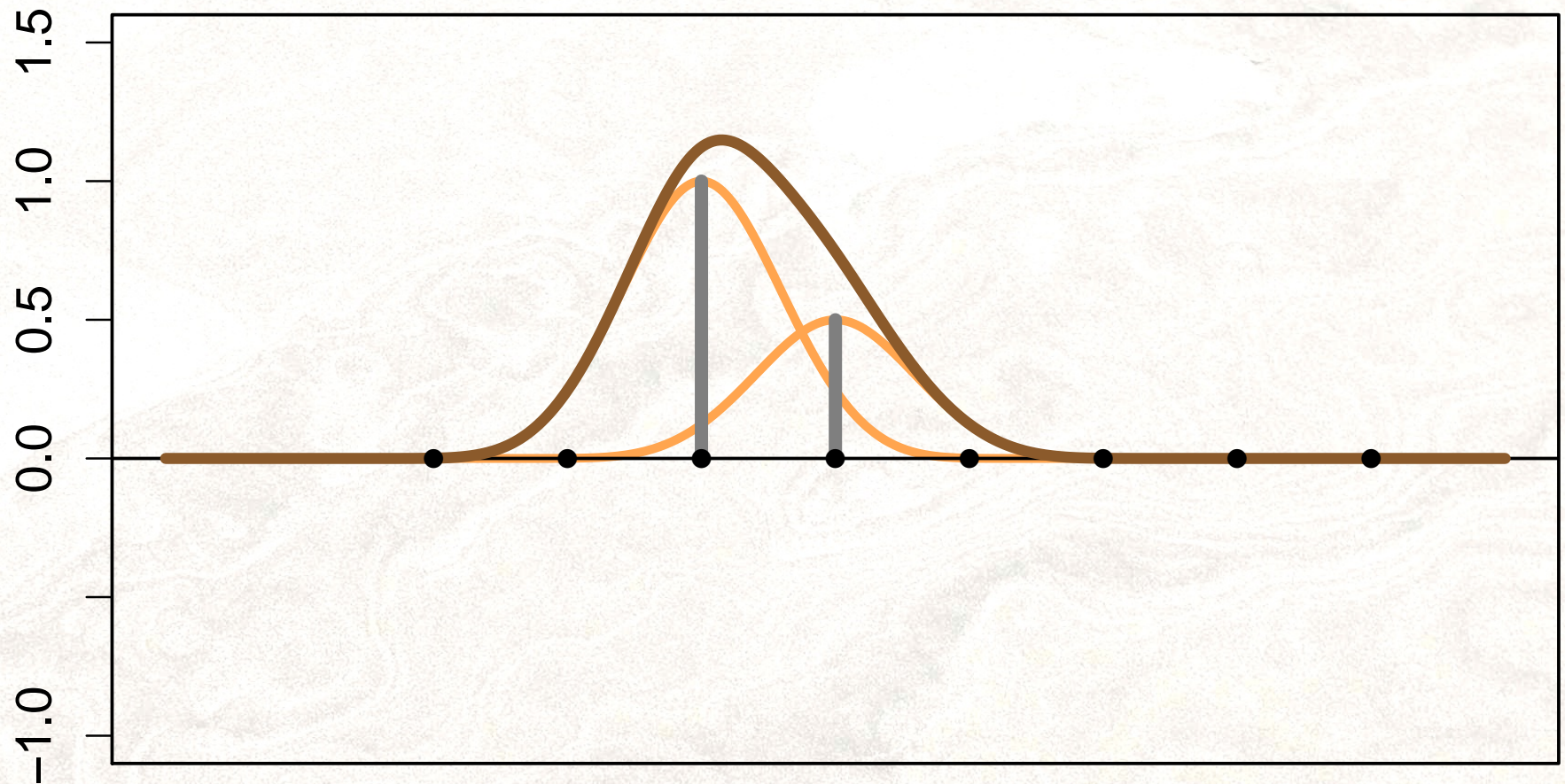
Single bump

Building a curve from bumps



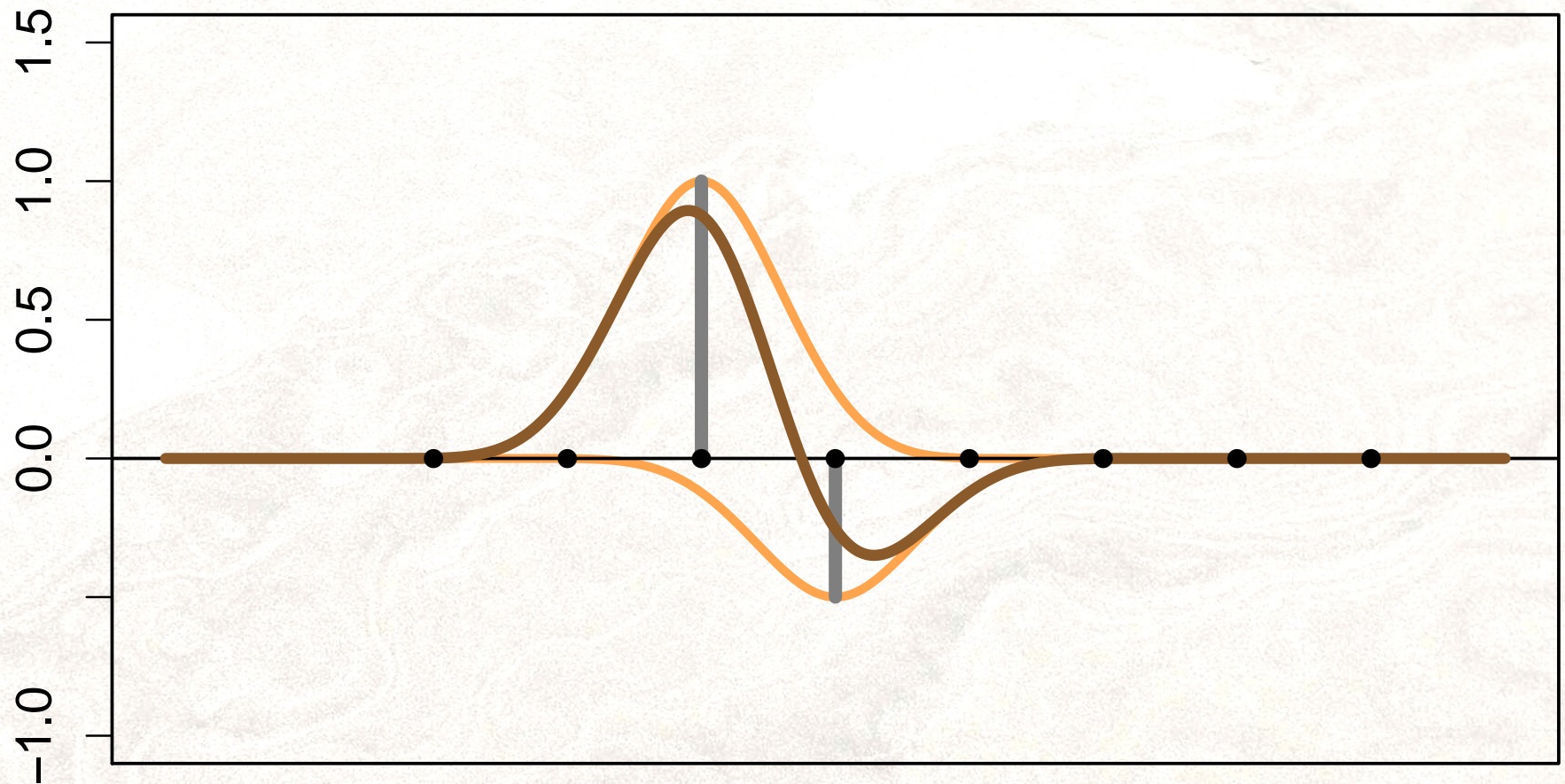
Two bumps same height

Building a curve from bumps



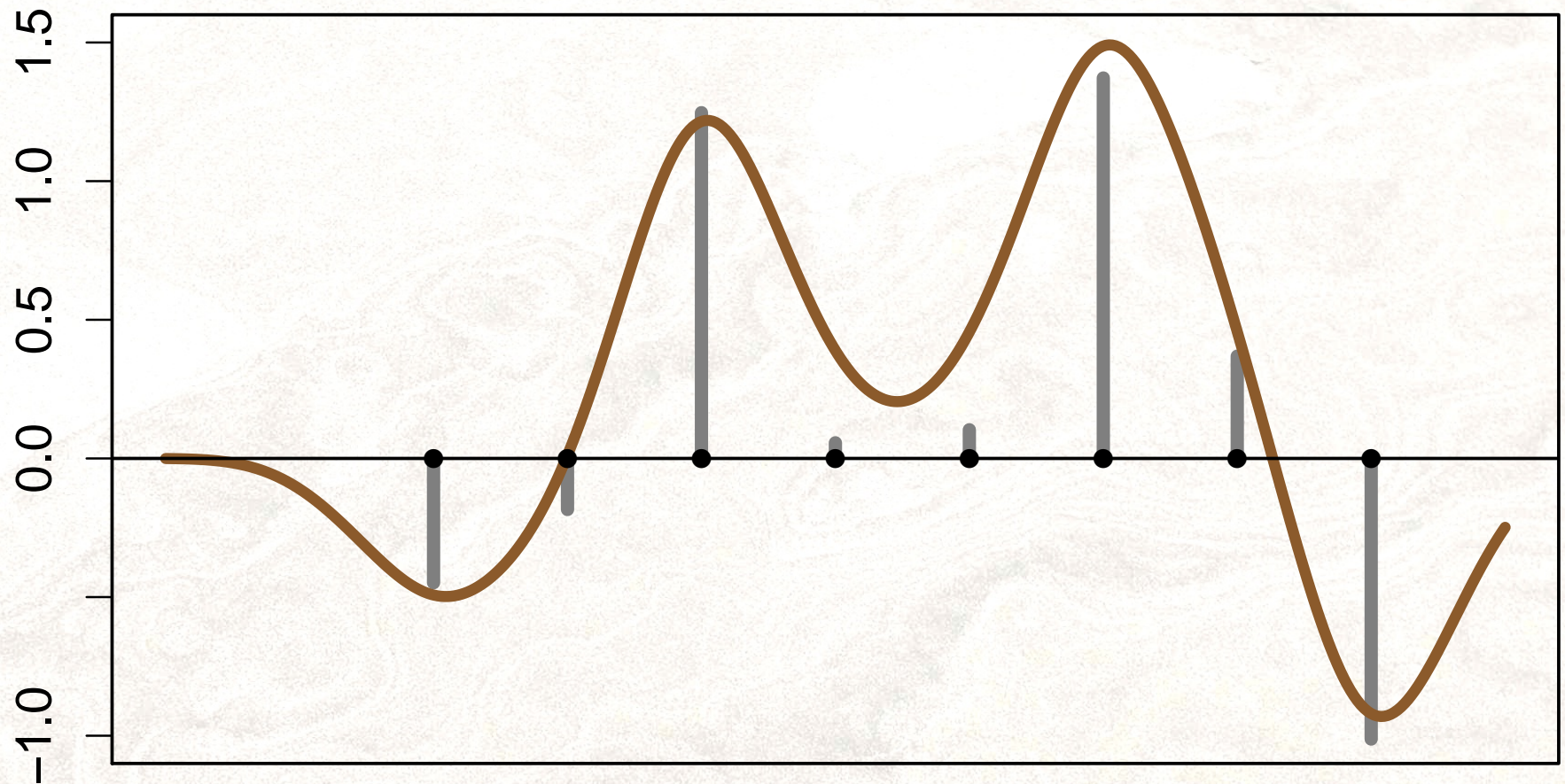
Two bumps different heights

Building a curve from bumps



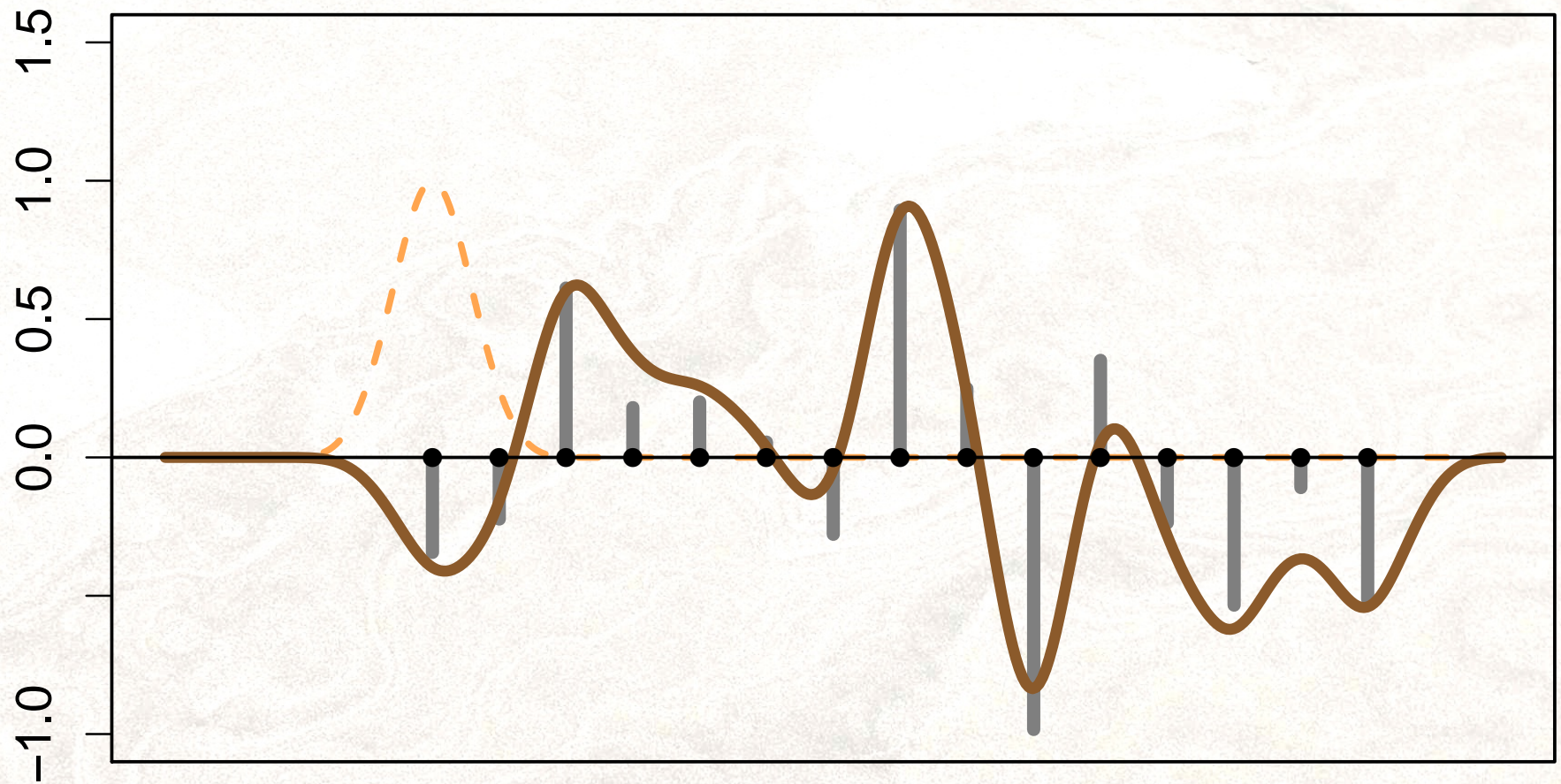
Two bumps different heights

Building a curve from bumps



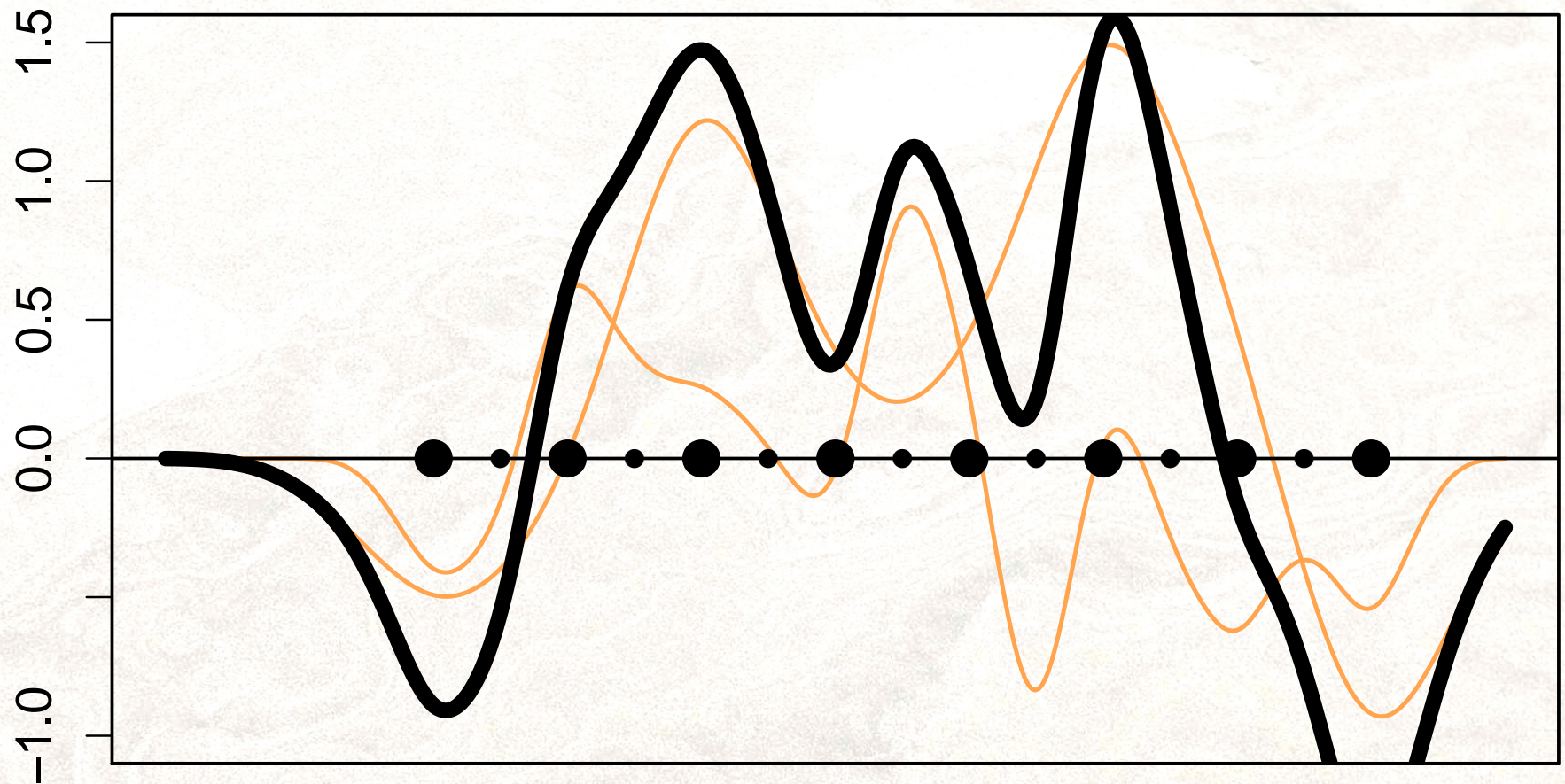
Eight bumps – all different heights

Building a curve from bumps



16 bumps – all different heights

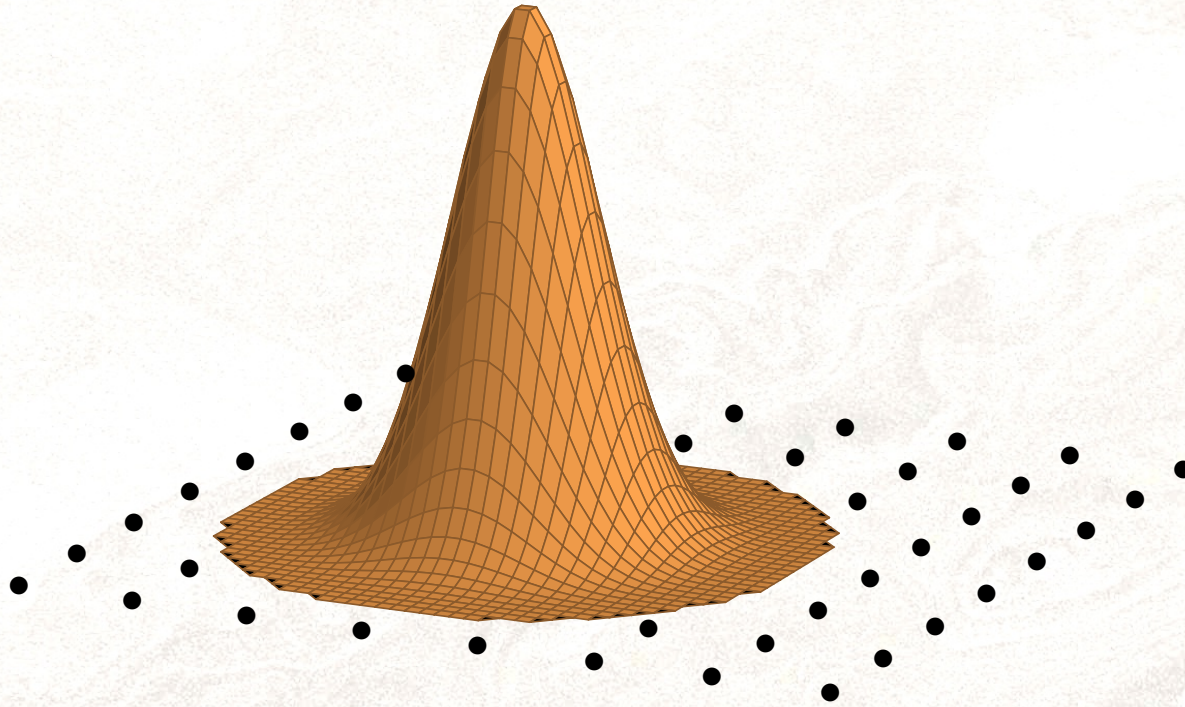
Building a curve from bumps



Adding them together

bumps = basis functions, bump heights = coefficients

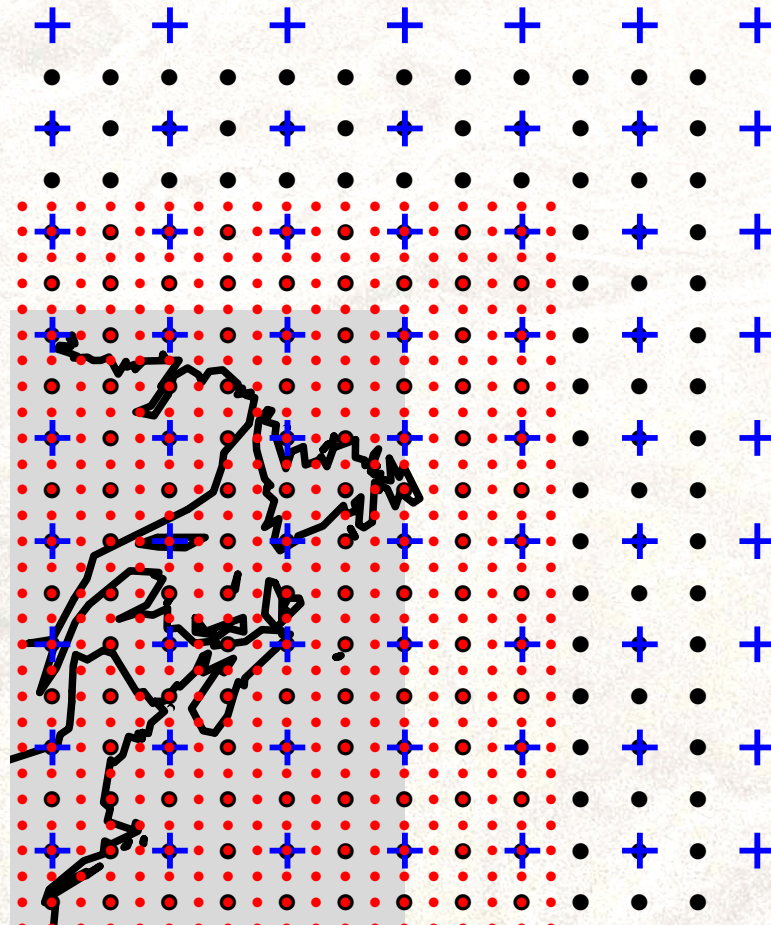
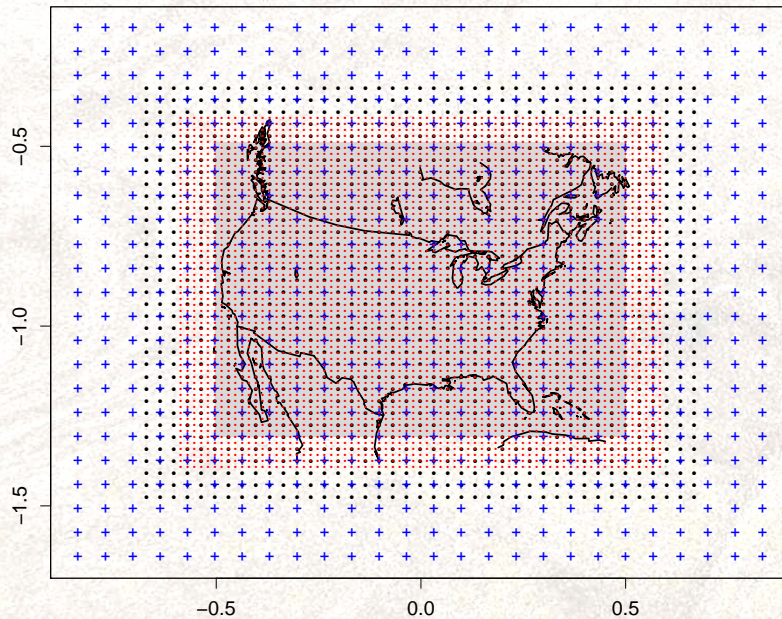
A (Wendland Basis function



Example of a 2-d bump

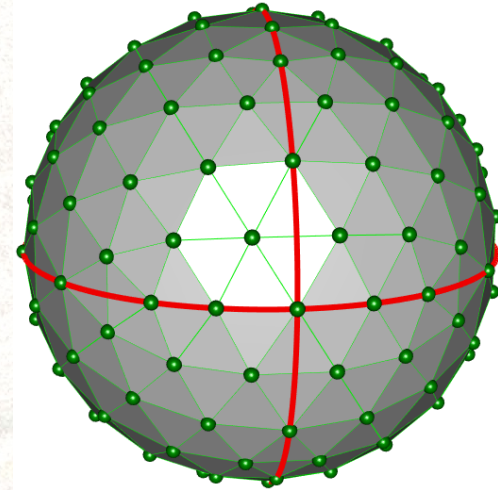
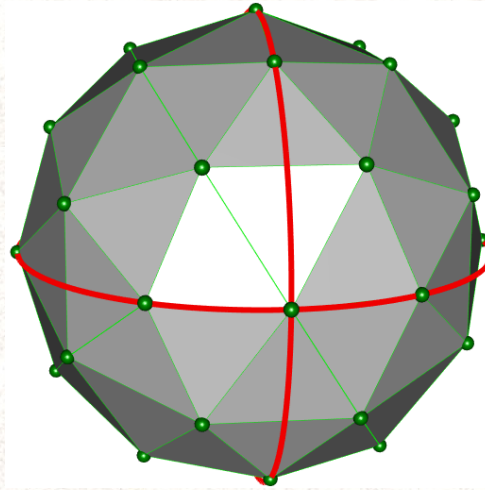
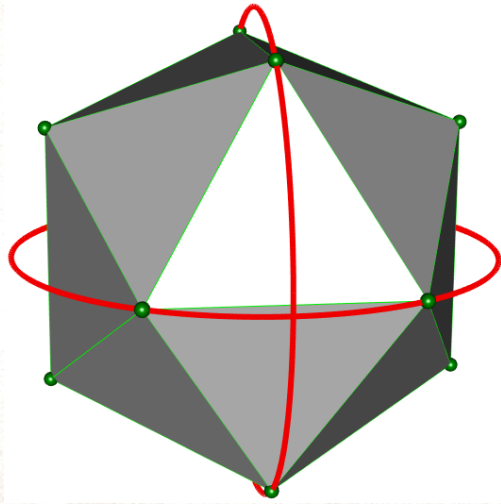
A lattice example

- Three levels
- Extra points on margins to minimize edges effects
- About 4000 total lattice points



Another lattice

Icosohedra grids for the sphere.



Spatial model

A linear (random effects) model

- X a regression matrix with $X_{i,j} = \phi_j(\mathbf{x}_i)$

Observations:

$$\mathbf{y} = X\mathbf{c} + \mathbf{e} \quad \mathbf{e} \sim MN(0, \tau^2 I)$$

Process:

$$g(x) = \sum_j \phi_j(x) c_j, \quad \mathbf{c} \sim MN(0, \sigma^2 Q^{-1})$$

Potential Priors:

$$[\sigma^2, \tau^2, Q]$$

Derived Covariance

$$\text{Cov}(g(\mathbf{x}), g(\mathbf{x}')) = \sigma^2 \sum_{j,k} \phi_j(\mathbf{x}) [Q^{-1}]_{j,k} \phi_k(\mathbf{x}')$$

- The model is written so that the covariance never needs to be explicitly found.

Computing the estimate

Integrating out \mathbf{c} :

$$[\mathbf{y}|\sigma^2, \tau^2, Q] \sim MN(0, (\sigma^2 \mathbf{X} Q^{-1} \mathbf{X}^T + \tau^2 I))$$

Likelihood/posterior computation for σ^2, τ^2, Q

dominated by

$$|\sigma^2 \mathbf{X}^T Q^{-1} \mathbf{X} + \tau^2 I| \text{ or equivalently } |(\tau^2 \mathbf{X}^T \mathbf{X} + (1/\sigma^2)Q)|$$

Kriging estimate of \mathbf{c} :

$$\hat{\mathbf{c}} = (\mathbf{X}^T \mathbf{X} + (\tau^2/\sigma^2)Q)^{-1} \mathbf{X}^T \mathbf{y}$$

Conditional simulation

Based on *unconditional* simulation of \mathbf{c} and Kriging estimate.

- Fast computation hinges on sparsity of Q and X .

Details and engineering

More about Q

At a single level

Some coefficients:

$$\begin{bmatrix} \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & c_1 & \cdot & \cdot \\ \cdot & c_2 & \textcolor{red}{c_*} & c_3 & \cdot \\ \cdot & \cdot & c_4 & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$

Some weights:

$$\begin{bmatrix} \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & -1 & \cdot & \cdot \\ \cdot & -1 & \textcolor{red}{a} & -1 & \cdot \\ \cdot & \cdot & -1 & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \end{bmatrix}$$

The filter:

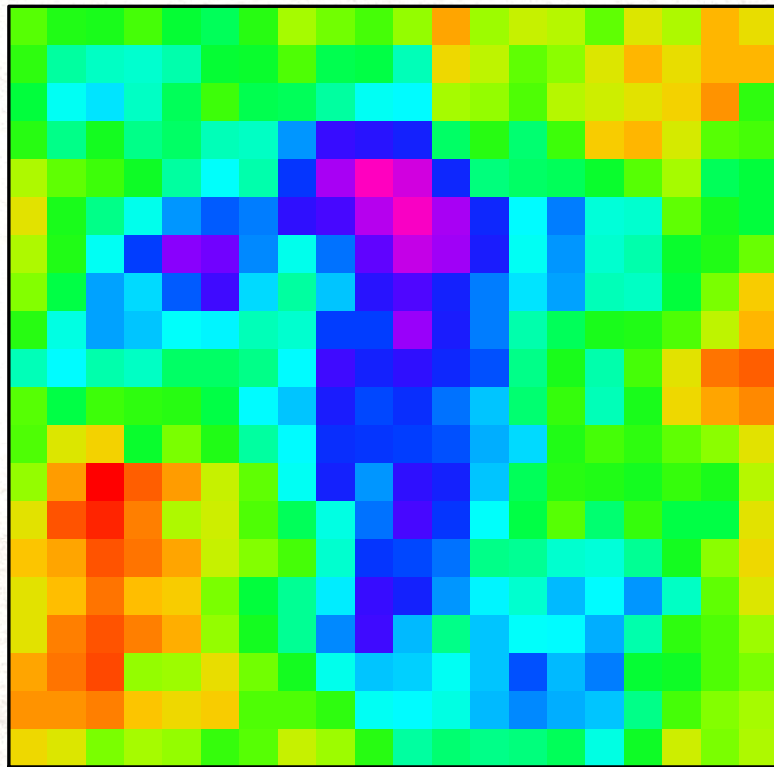
$$\textcolor{red}{a}c_* - (c_1 + c_2 + c_3 + c_4) = \text{white noise}$$

$$\text{If } B\mathbf{c} = \text{iid } N(0, 1), \quad Q = BB^T$$

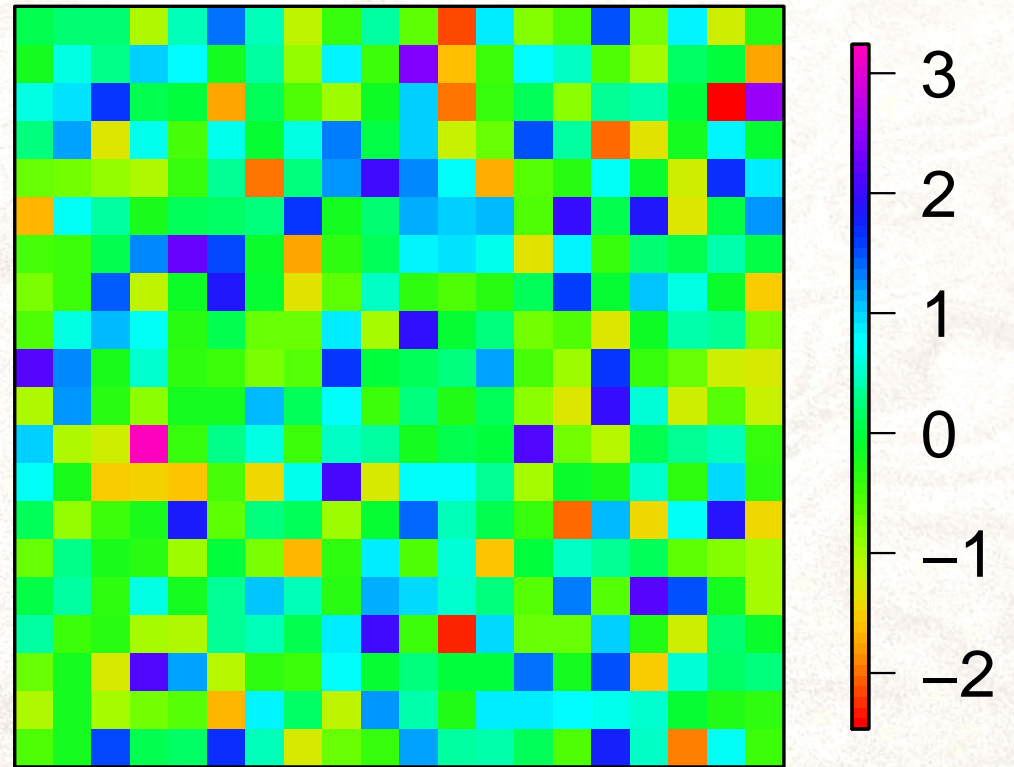
- $\textcolor{red}{a}$ needs to be greater than 4.
- A simple discretization of the Laplacian. $\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}$

Filtering coefficients

Coefficients on the lattice



Applying the filter

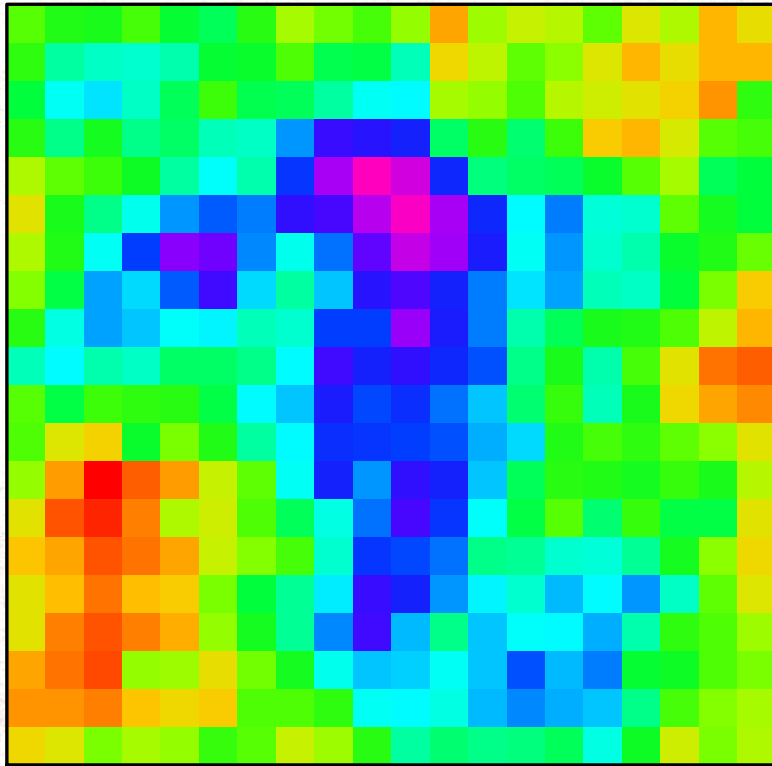


$$c_* \rightarrow ac_* - (c_1 + c_2 + c_3 + c_4)$$

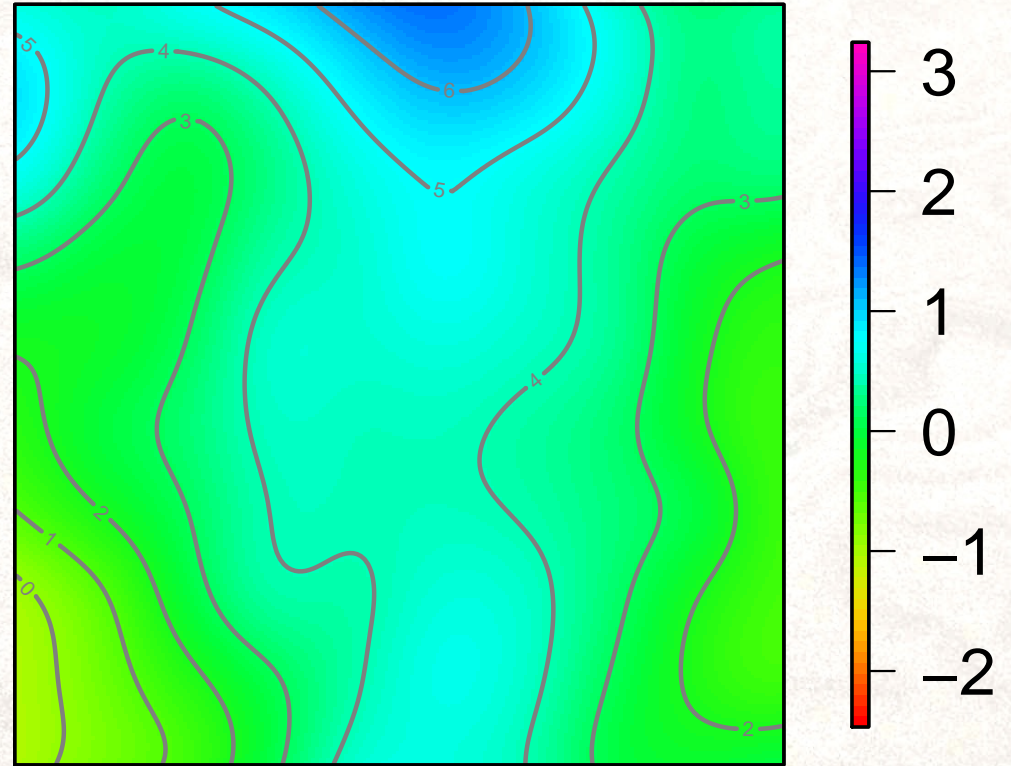
$$a = 4.01$$

Applying the basis functions

Coefficients on the lattice



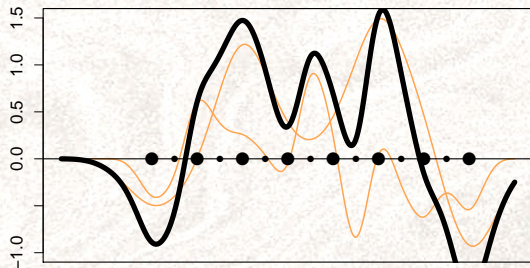
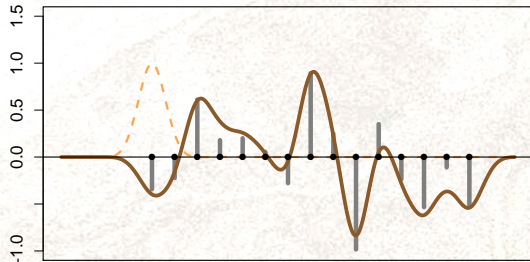
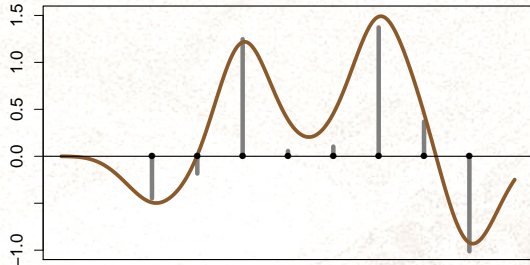
Expanding with basis functions



$$c_k \rightarrow \sum \phi_k(x) c_k = g(x)$$

More than one level:

Adding different resolutions together:



$$g(x) = \sigma^2(\alpha_1 g_1(x) + \alpha_2 g_2(x) + \alpha_3 g_3(x) + \dots)$$

$$Q = (1/\sigma^2) \begin{bmatrix} \alpha_1 B_1^T B_1 & 0 & 0 \\ 0 & \alpha_2 B_2^T B_2 & 0 \\ 0 & 0 & \alpha_3 B_3^T B_3 \end{bmatrix}$$

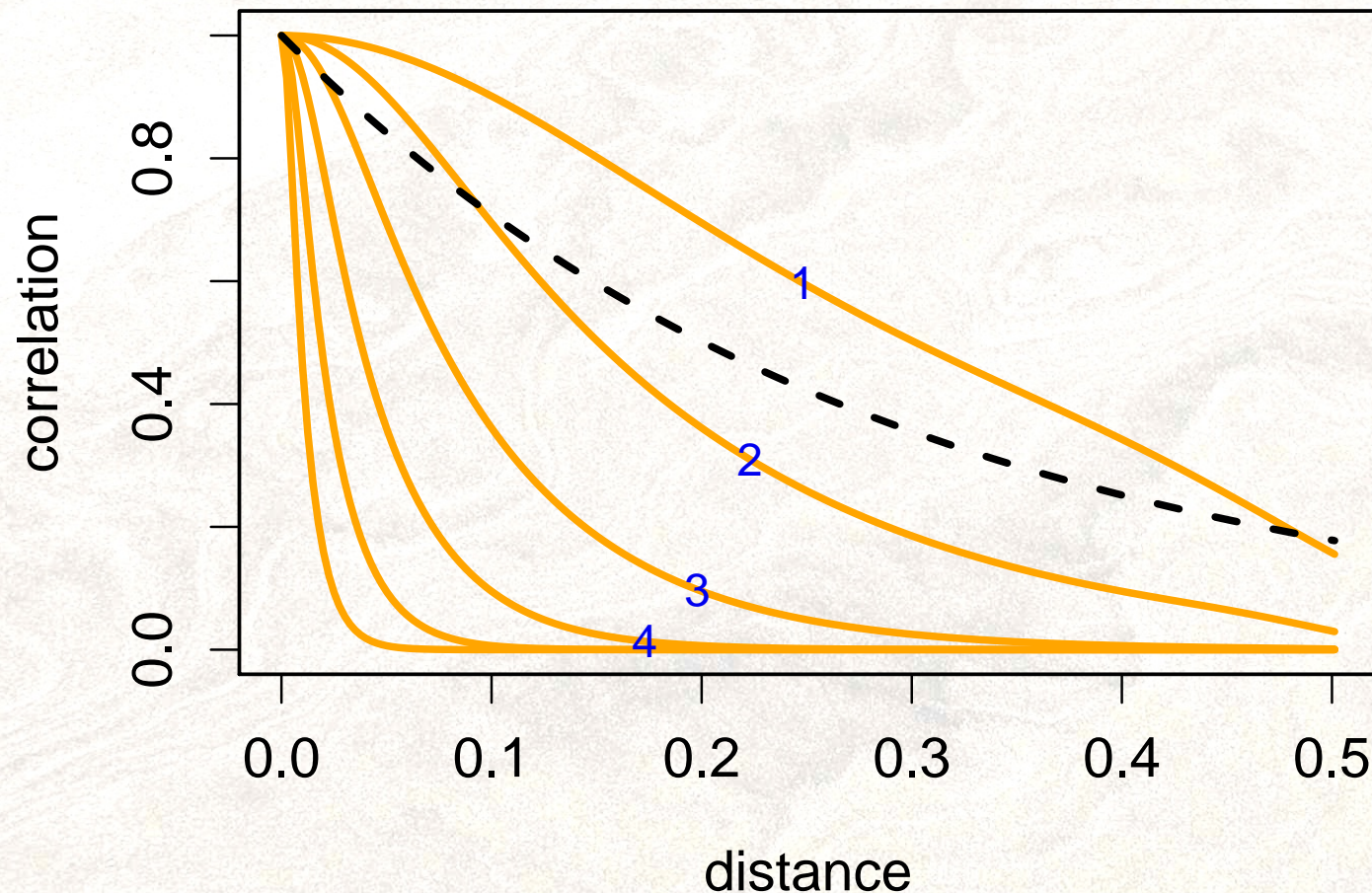
- σ^2 marginal variance of the process
- $\alpha_1, \alpha_2, \alpha_3$ relative weight for each level – all nonnegative and add to 1.

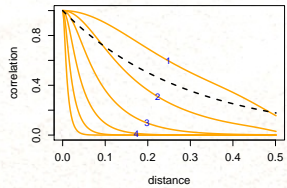
Benefits of a multi-resolution

Approximating standard covariances

Approximating an exponential covariance

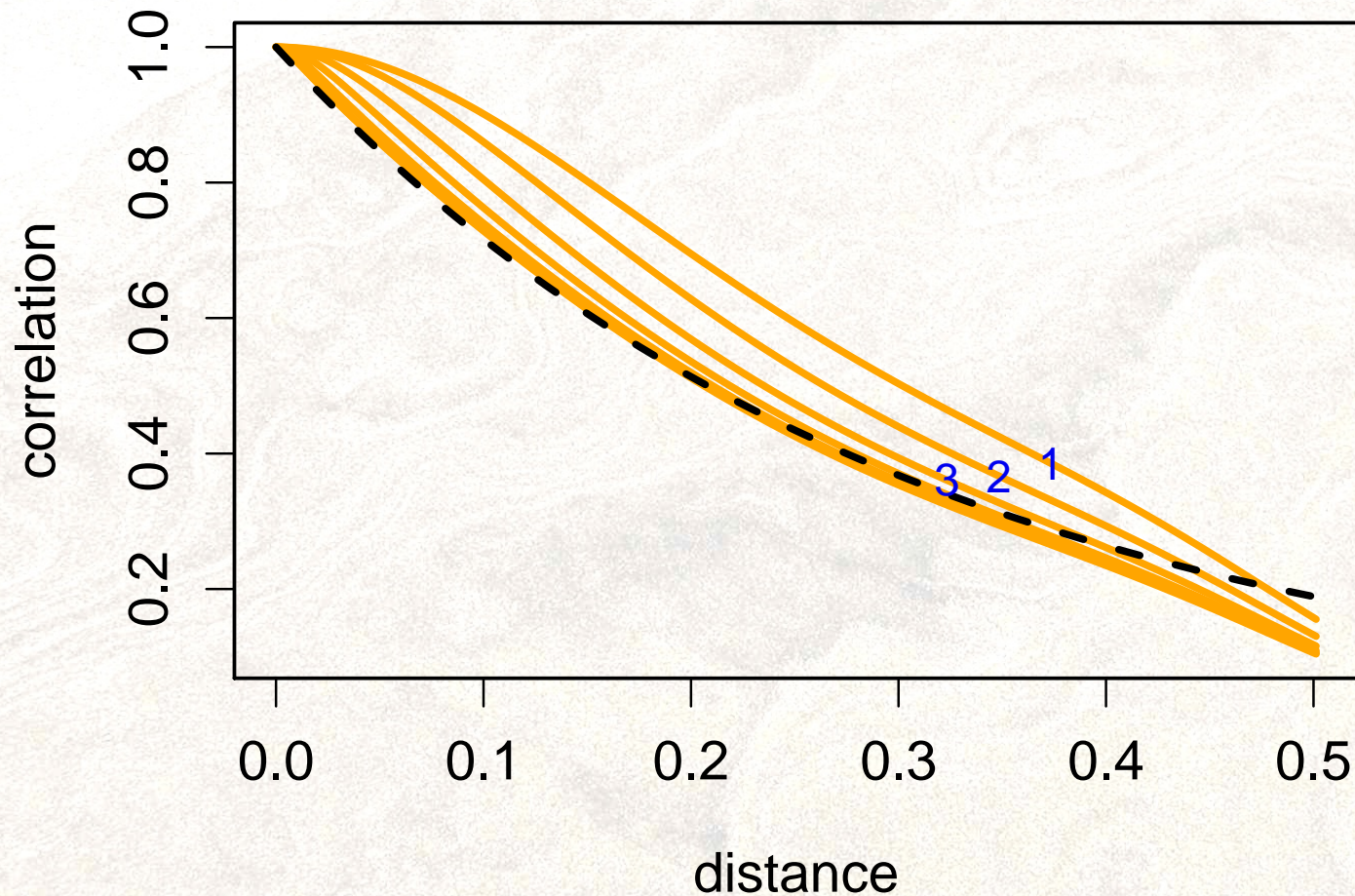
Correlation functions for 6 levels and a target exponential





Weighting by $2^{-\text{level}/2}$

Correlation functions adding levels and the target exponential



Timing

On my mac laptop and in R

— i.e. a single core and LatticeKrig package

Computation may be dominated by :

- matrix setup
- normalization to stationarity
- *Cholesky decomposition*

For 20,000 observations, single likelihood evaluation:

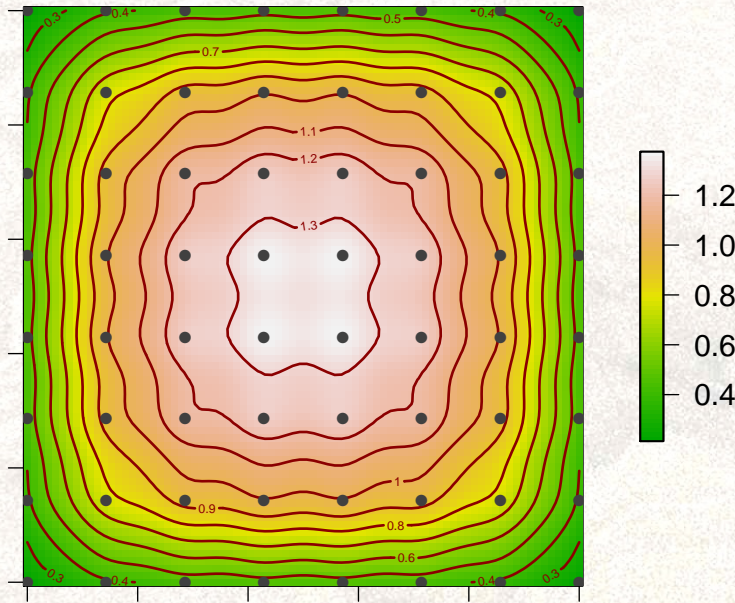
- standard Kriging (dense Cholesky) is ≈ 20 minutes
- LatticeKrig (sparse Cholesky) is ≈ 10 seconds.

Stationarity?

Recall $\text{Cov}(g(\mathbf{x}), g(\mathbf{x}') = \sigma^2 \sum_{j,k} \phi_j(\mathbf{x}) [Q^{-1}]_{j,k} \phi_k(\mathbf{x}')$

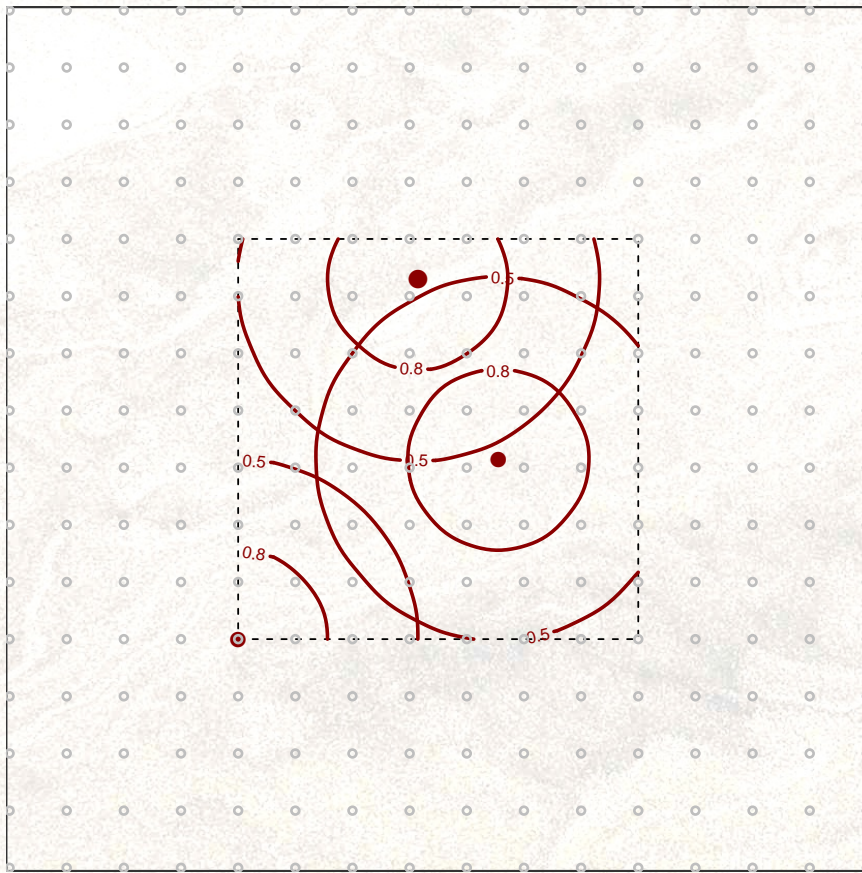
Correlation function for a single level $a = 4.2$

Marginal variance $\text{VAR}(g(x))$ from a 8×8 grid

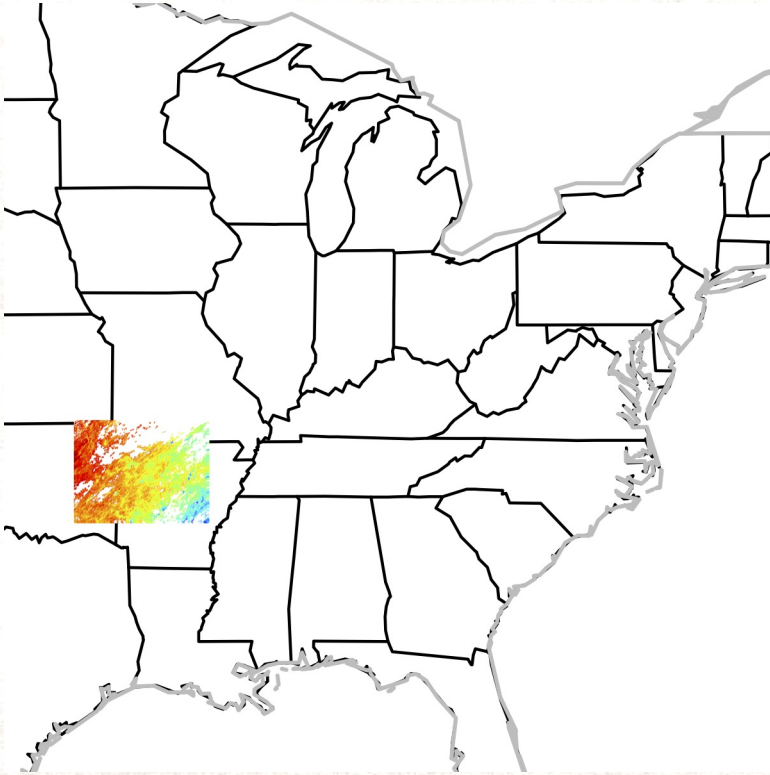


Adding buffer and normalizing

8× 8 grid with 4 grid points of buffer and normalized
Correlation function for a single level, $a = 4.2$

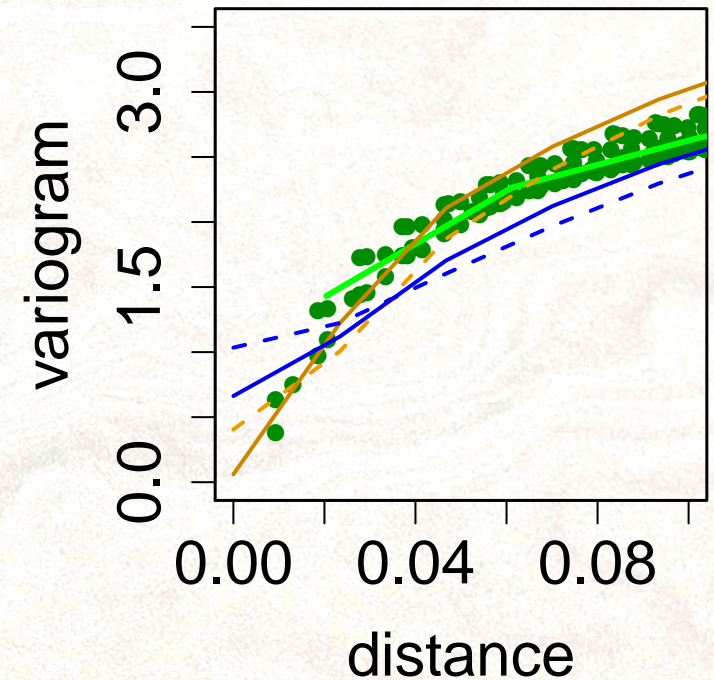
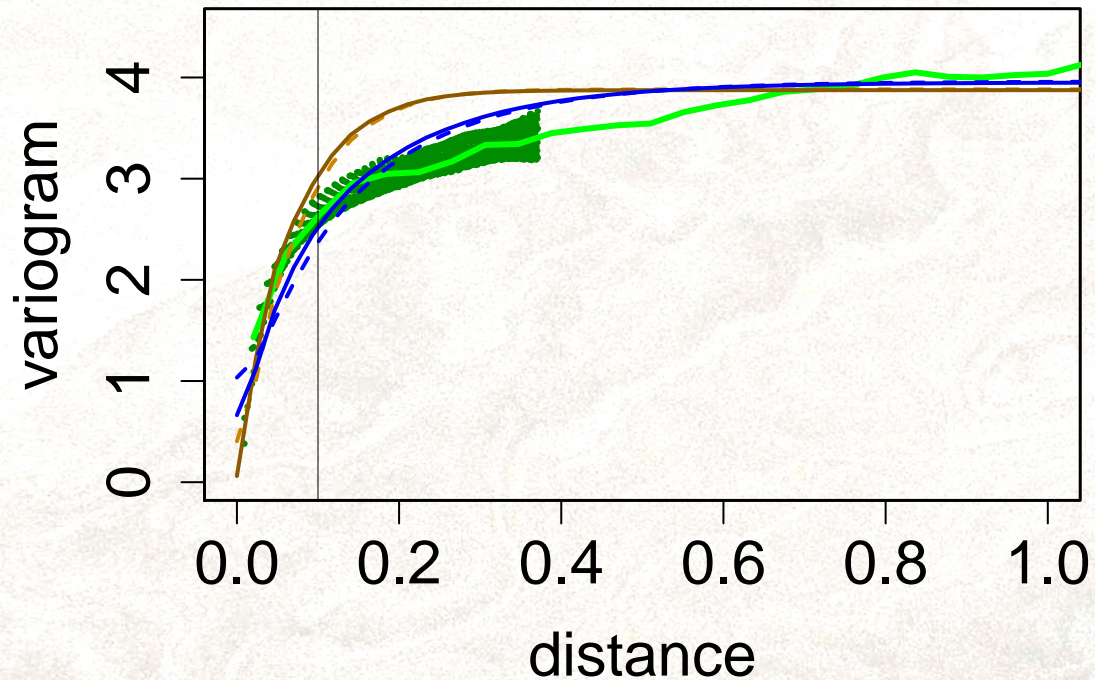


Surface temperatures



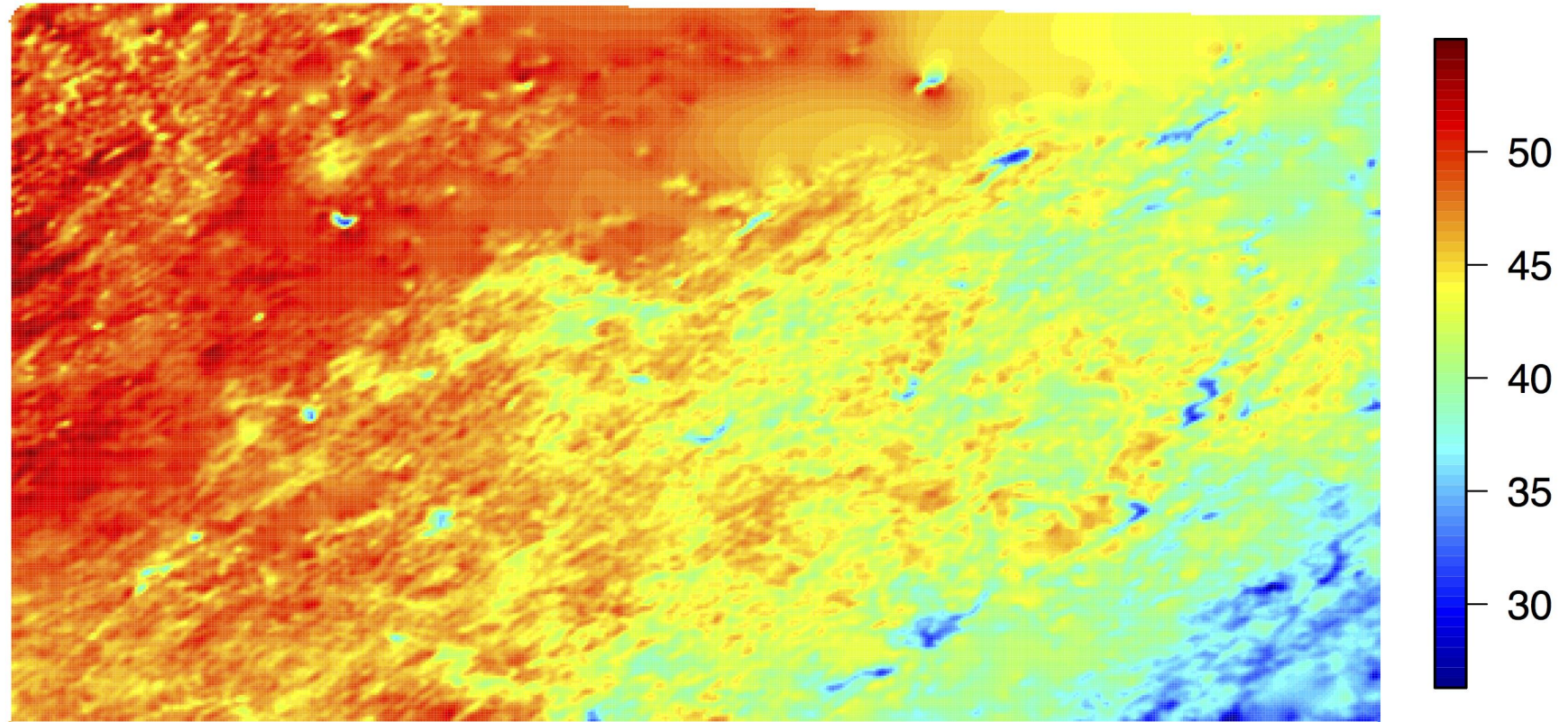
Variogram fitting

Sample Variogram with some different LatticeKrig models



- First level - 50 basis functions in longer dimension,
- $a = 10$, $a = 4.5$
- dashed - 3 levels, solid - 4 levels

Some results



Final model: `NC= 40, nlevel = 4, a.wght = 10.25, nu = .1`

LatticeKrig package

```
# x and y are the power use data for the NCAR/WY Supercomputing center

fit<- LatticeKrig( x,y, NC=10, nlevel=4) # takes about 10 seconds
print( fit)

quilt.plot( x, fit$residuals)

surface( fit, xlab="Temp", ylab="RH")

# Conditional simulation with fixed covariance parameters
# 50 draws 80X80 grid takes about 40 seconds

simFit<- LKrig.sim.conditional( fit, M=50)
```



```
print( fit)
```

Call:

```
LatticeKrig(x = x, y = y, nlevel = 4, NC = 10)
```

Number of Observations:	1677
Number of parameters in the fixed component	3
Effective degrees of freedom (EDF)	32.2
Standard Error of EDF estimate:	1.595
MLE tau	30.7
MLE sigma ²	21270
MLE lambda = tau ² /sigma ²	0.04432

Fixed part of model is a polynomial of degree 1 (m-1)

Basis function : Radial

Basis function used: WendlandFunction

Distance metric: Euclidean

Lattice summary:

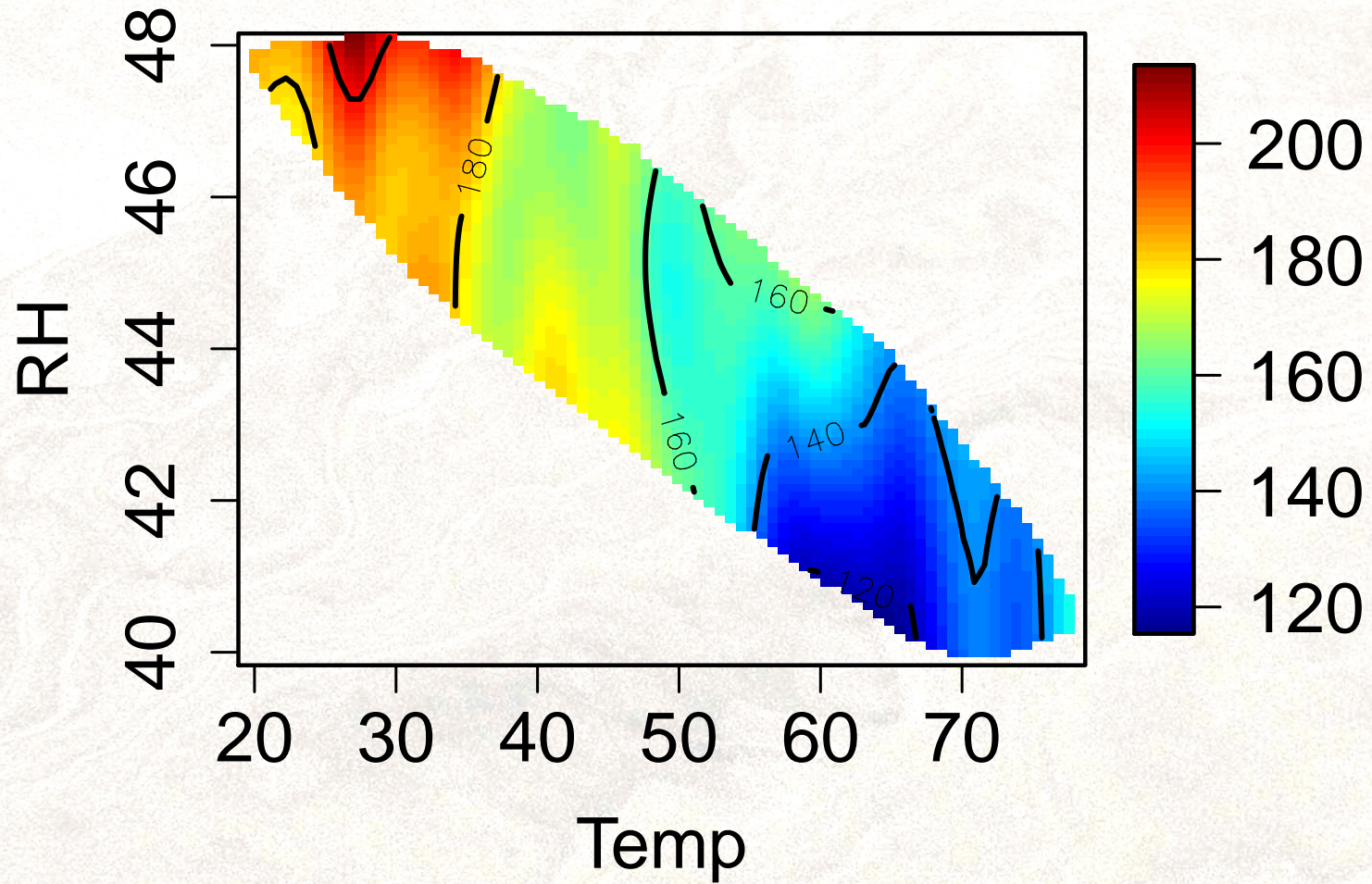
4 Level(s) 3112 basis functions with overlap of 2.5 (lattice units)

Level	Lattice points	Spacing
1	240	6.5664444
2	377	3.2832222
3	752	1.6416111
4	1743	0.8208056

Nonzero entries in Ridge regression matrix 357579

D. Nychka LatticeKrig


```
surface(fit, xlab="Temp", ylab="RH")
```



Final thoughts on the next steps

- Estimate parameters using score equations to avoid determinant
- Estimate parameters using cross validation.

Randomized trace Generalized Cross-Validation is amenable to iterative methods

- Parameter searching can be easily parallelized using `Rmpi`

Summary

- Computational efficiency gained by compact basis functions and sparse roughness (precision) matrix.
- Multi-resolution can approximate standard covariance families (e.g. Matern)
- Easy to generate uncertainty measures.

See `LatticeKrig` contributed package in R

Thank you!

