

From Kriging to large data methods

$$Z_k = \color{violet}{\bullet} Y(S_k) + \varepsilon_k \quad k=1, n$$

$\uparrow \quad \quad \uparrow \quad \quad \nwarrow$ errors

$$\text{Var}(Y(s)) = \sigma^2 \quad \text{Cov}(Y(s), Y(s')) = k(s, s')$$

e.g. $k(s, s') = \sigma^2 e^{-\|s-s'\|/\theta} \quad \leftarrow \text{Exp} \quad \frac{1}{2}$
 $\sigma^2 e^{-(\|s-s'\|/\theta)^2} \quad \leftarrow \text{Gaussian} \quad \infty$

$\underline{\varepsilon}$ - i.i.d. variance 1 (τ^2)

Want to predict at s_0 $Y(s_0)$

• Missing the linear model !!

Assembling the matrices $\underline{z} - n \times 1$

$$C_z = \text{cov}(\underline{z}, \underline{z}) \quad n \times n \text{ matrix.}$$

$$= (K + I) \quad K_{ij} = k(s_i, s_j), \text{ e.g. } \sigma^2 e^{\frac{\|s_i - s_j\|}{\theta}}$$

from iid errors Exp

$$C_0 = \text{cov}(Y(s_0), \underline{z}) \equiv \text{cov}\left(Y(s_0), \begin{pmatrix} Y(s_1) \\ \vdots \\ Y(s_n) \end{pmatrix}\right)$$
$$= k\left(s_0, \begin{pmatrix} s_1 \\ \vdots \\ s_n \end{pmatrix}\right)$$

$$C_{00} = \text{Var}(Y(s_0)) = \sigma^2$$

$$\begin{pmatrix} \underline{z} \\ \vdots \\ Y(s_0) \end{pmatrix} = \text{Gau} \left(0, \begin{pmatrix} \overset{n \times n}{\underline{C_z}} & \overset{n \times 1}{\underline{C_0}} \\ \vdots & \vdots \\ \overset{1 \times 1}{\underline{C_0'}} & \overset{1 \times 1}{\underline{C_{00}}} \end{pmatrix} \right)$$

$$\begin{bmatrix} Y(s_0) \\ \vdots \\ \underline{z} \end{bmatrix} \sim \text{Gau} \left(\underbrace{C_0' C_z^{-1} \underline{z}}_{\text{kriging estimate}}, C_{00} - C_0' C_z^{-1} C_0 \right)$$

$$\hat{Y}(s_0) = C_0' C_z^{-1} \underline{z} = (\text{weights})^T \underline{z}$$

(standard error)²

$$= C_0' \left(C_z^{-1} \underline{z} \right)$$

Chris Kriging

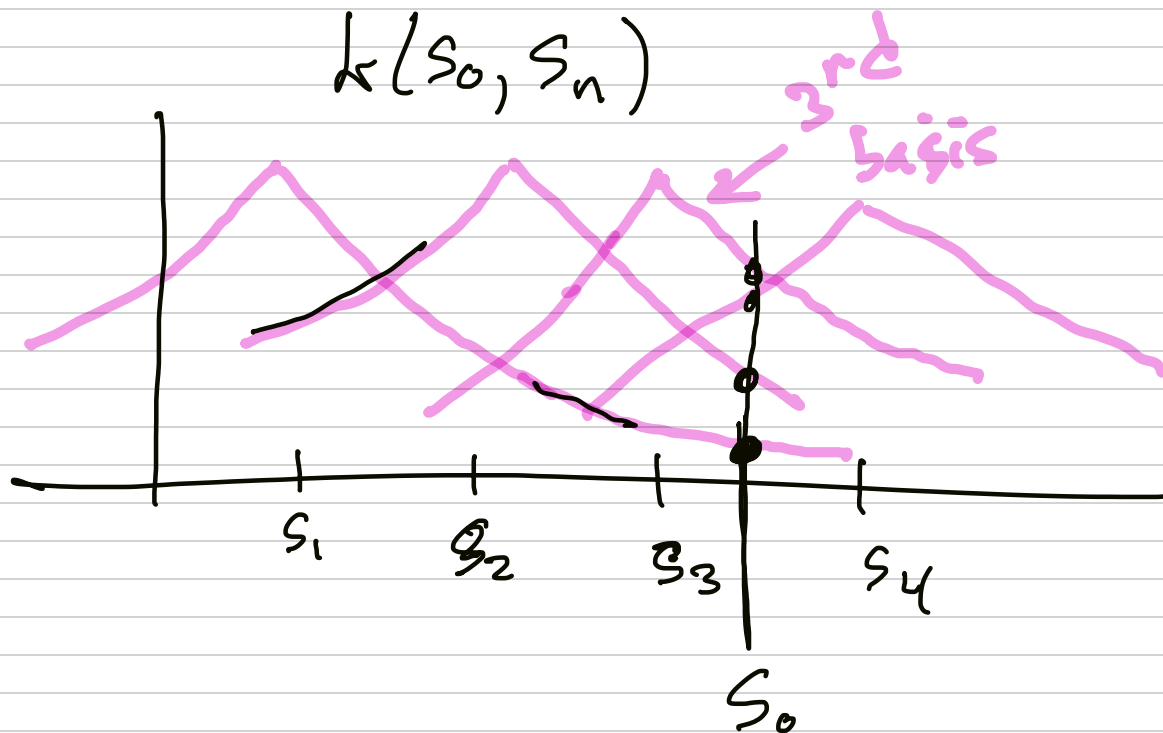
= basis functions x coefficients

$$\hat{\alpha} = (C_z^{-1} z)$$

$$C_0^T \hat{\alpha} = \sum_{k=1}^n k(s_0, s_k) \hat{\alpha}_k$$

$$C_0 = \begin{pmatrix} k(s_0, s_1) \\ \vdots \end{pmatrix}$$

$$= \sum_{k=1}^n \left[\sigma^2 e^{\frac{\|s_0 - s_k\|}{\theta}} \right] \hat{\alpha}_k$$



FRK - $\gamma(s)$ - Gaussian Process

$$\gamma(s) = \sum_{k=1}^n \phi_k(s) \alpha_k$$

$$\underline{\alpha} \sim \text{Gau}(0, C_\alpha) \quad \{\phi_k(s)\} \text{ fixed}$$

$$\underline{z} = \underbrace{\gamma}_{\text{process at } s_1, \dots, s_n} + \underline{\varepsilon} \quad \text{chosen out of laziness}$$

$$\underline{z} = \underline{\Phi} \underline{\alpha} + \underline{\varepsilon} \quad \Phi_{ij} = [\phi_j(s_i)]$$

Fun fact

$$C_z = \text{cov}(\underline{z}, \underline{z}) = (\underline{\Phi} C_\alpha \underline{\Phi}^T + I)$$

$\underline{u} \sim \text{Gau}(0, \Sigma)$ A - matrix.

$$\text{cov}(A \underline{u}) = A \Sigma A^T$$

$$C_0 = C_\alpha \Phi_0$$

$$\Phi_0 = \begin{bmatrix} \phi_1(s_0) \\ \vdots \\ \phi_n(s_0) \end{bmatrix}$$

cov.
driving
spatial
mode

$$\hat{y}(s_0) = \sum \phi_k(s_0) \hat{z}_k$$

$$\hat{\underline{z}} = \underbrace{(C_\alpha \Phi^T)}_{C_0^T} (C_z) \underline{z} = \underbrace{C_\alpha \Phi^T}_{\text{basis function matrix}} (\underbrace{\Phi C_\alpha \Phi^T + I}_{\text{cov. driving spatial mode}}) \underline{z}$$

$$\Phi_0^T \hat{\underline{z}} = \underbrace{\quad}_{\text{weight}} \underline{z}$$

ala Kriging

Thinking about

$$(C_z)^{-1}$$

$$C_z^{-1} = (\Phi C_\alpha \Phi^T + I)^{-1}$$

ordinary kriging

$$C_z = (K + I)^{-1}$$

n obs

$K = n \times n$

$C_z = n \times n$

Sherman-Morrison-Woodbury formula.

$$(\Phi C_\alpha \Phi^T + I)^{-1} = I - \Phi (\Phi^T \Phi + C_\alpha^{-1})^{-1} \Phi^T$$

left $(C_z)^{-1}$

something else

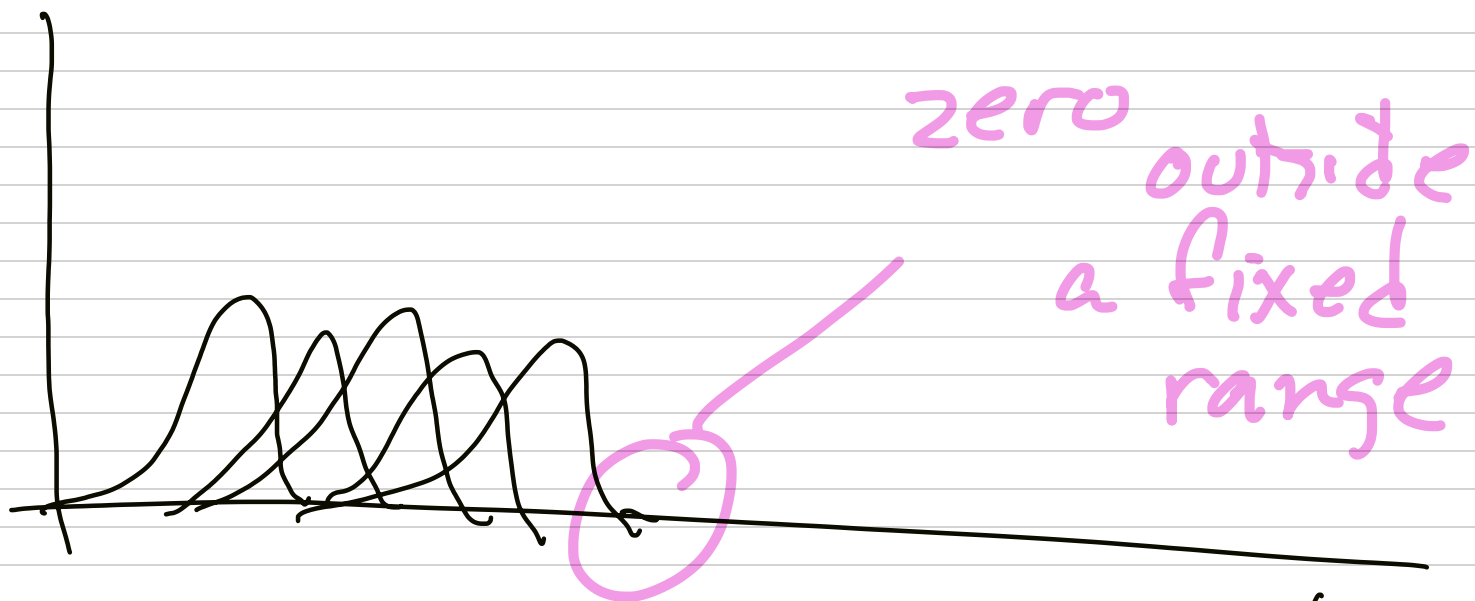
right

$n = 10^5$ 100 basis functions

right $\Phi^T \Phi = 100 \times 100$

left $\sim 10^5 \times 10^5$ matrix.

$C_\alpha = 100 \times 100$



$\Rightarrow \Phi$ - sparse matrix.