

Mathematics 2: Homework 1

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1 Theoretical problems

1.1 Equivalence of 1. \iff 4.

In order to prove 1. \iff 4., we prove $1. \rightarrow 4.$ and $4 \rightarrow 1.$ 1. is simply a special case of 4. when $k = 2$. We prove $4. \rightarrow 1.$ by induction on the number of weighed points n . For $k = 1$ it is trivial to see the equation holds. Given $n = k - 1$ then

$$f\left(\sum_{i=1}^{k-1} \alpha_i x_i\right) \leq \sum_{i=1}^{k-1} \alpha_i f(x_i) \quad (1)$$

Adding x_k with weight α_k we need to divide all former α with $1 - \alpha_k$

$$f\left(\sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i\right) \leq \sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} f(x_i) \quad (2)$$

Using the above equation to construct a weighed average

$$(1 - \alpha_k) f\left(\sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i\right) + \alpha_k f(x_k) \leq \sum_{i=1}^{k-1} \alpha_i f(x_i); \quad (3)$$

The following holds since we simply used inequality 2 to expand $f\left(\sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i\right)$. Since $f(x)$ is continuous we know that $\sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i \in D$; we can simply treat it as a point between x_1 and x_k . Therefore the following holds

$$\begin{aligned} f\left((1 - \alpha_k) \sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i + \alpha_k x_k\right) &= f\left(\sum_{i=1}^{k-1} \alpha_i x_i\right) \leq \\ &\leq (1 - \alpha_k) f\left(\sum_{i=1}^{k-1} \frac{\alpha_i}{1 - \alpha_k} x_i\right) + \alpha_k f(x_k) \end{aligned} \quad (4)$$

By transitivity of the operator \leq it follows that $f\left(\sum_{i=1}^{k-1} \alpha_i x_i\right) \leq \sum_{i=1}^{k-1} \alpha_i f(x_i)$.

1.2 Bounds for $f(x,y)$

We calculate L by using the following inequality $\|\nabla f\| \leq L$. The gradient equals

$$\nabla f = \begin{bmatrix} 2x + e^x - y \\ 2y - x \end{bmatrix} \quad (5)$$

Therefore the norm $\|\nabla f\|$ equals.

$$(2x + e^x - y)^2 + (2y - x)^2; \quad (6)$$

Here we removed the root since it does not change the ordinality of our norms. Since $f(x,y)$ is convex we know that the maximum will not be an interior point therefore we only need to check its borders. Formally, we'd construct the lagrangian L and give the KKT conditions, however we use some shortcuts to avoid most of the tedious calculations. For $(x,y) \in \{2, -2\} \times \{2, -2\}$ we get $(2,-2)$ to be the greatest with $f(2, -2) \approx 215$ to be the largest, therefore the optimal L

$$\arg \max_{x,y} \|\nabla f\| = 14.67197 \leq L \quad (7)$$

We calculate β using the following inequality $\|\nabla^2 f\| \leq \beta$. Where $\|\nabla^2 f\|$ equals

$$\nabla^2 f = \begin{bmatrix} 2 + e^x & -1 \\ -1 & 2 \end{bmatrix} \quad (8)$$

Finding the largest eigenvalue λ_{max} compute the $\det(\nabla^2 f - \lambda I)$

$$\begin{vmatrix} 2 + e^x - \lambda & -1 \\ -1 & 2 - \lambda \end{vmatrix} \quad (9)$$

We get the following $(2 - \lambda)^2 + e^x(2 - \lambda) - 1 = \lambda^2 + (-e^x - 4)\lambda + (2e^x + 3)$. Solving the quadratic equation

$$\frac{(e^x + 4) + \sqrt{e^{2x} + 4}}{2} = 9.521999 \quad (10)$$

Here since all terms are positive we can clearly see that $x = 2$ maximizes λ .

In order for f to be strongly convex all eigenvalues of $\nabla^2 f$ need to be greater than α , therefore $\alpha = \arg \min_x \min(\lambda)$. Calculating the derivative of $\frac{(e^x + 4) - \sqrt{e^{2x} + 4}}{2}$ we get

$$e^x - \frac{e^{2x}}{\sqrt{e^{2x} + 4}} \quad (11)$$

The following indicates there are no minimums in the interior of K . Hence we evaluate x at 2 and -2 , the minimum being 1.065381 at -2 . Since in the case 10 λ is at least four we conclude that the optimal value for α is 1.065381.

1.3 Projection formulas

For all free we conclude that if a point is in K then the projection should change nothing while for a projection of a point from outside K the point is projected to the nearest edge. Therefore are proofs are limited to points outside K

1. For $x^2 + y^2 \leq 1.5$

$$\begin{aligned} & \text{minimize } (x_1 - x)^2 + (y_1 - y)^2 \\ & \text{such that } x^2 + y^2 = 1.5, \end{aligned} \tag{12}$$

we construct the lagrangian

$$\begin{aligned} \mathcal{L}(x, y, \lambda) &= (x_1 - x)^2 + (y_1 - y)^2 - \lambda(x^2 + y^2 - 1.5) \\ \frac{\partial \mathcal{L}}{\partial x} &= 2(x_1 - x) - 2\lambda x = 0 \\ \frac{\partial \mathcal{L}}{\partial y} &= 2(y_1 - y) - 2\lambda y = 0 \\ \frac{\partial \mathcal{L}}{\partial \lambda} &= -(x^2 + y^2 - 1.5) = 0 \end{aligned} \tag{13}$$

Solving the following equation we get $y' = \frac{y_1}{\sqrt{\frac{y_1^2 + x_1^2}{1.5}}}$ and $x' = \frac{x_1}{\sqrt{\frac{y_1^2 + x_1^2}{1.5}}}$.

Therefore our function is

$$f(x_1, y_1) = \begin{cases} x_1, y_1 & \text{if } x^2 + y^2 \leq 1.5 \\ x', y' & \text{if } x^2 + y^2 > 1.5 \end{cases} \tag{14}$$

2. For $[-2, 2] \times [-2, 2]$

$$\begin{aligned} & \text{minimize } (x_1 - x)^2 + (y_1 - y)^2 \\ & \text{such that } x \in [-2, 2] \text{ and } y \in [-2, 2], \end{aligned} \tag{15}$$

We can formally write the KKT conditions and solve the equations, however we can avoid doing this by splitting our problem space into 9 spaces, split by lines going through points $(-2, -2)$, $(-2, 2)$, $(2, -2)$, $(2, 2)$. For each bounded by where at least y or x is in K we simply

project the coordinate the is not to its nearest edge, in case neither are we project it to the nearest vertex.

$$f(x_1, y_1) = \begin{cases} x_1, y_1 & \text{if } x \in [-2, 2] \wedge y \in [-2, 2] \\ x_1, -2 & \text{if } x \in [-2, 2] \wedge y < -2 \\ x_1, 2 & \text{if } x \in [-2, 2] \wedge y > 2 \\ -2, y_1 & \text{if } x < -2 \wedge y \in [-2, 2] \\ 2, y_1 & \text{if } x > 2 \wedge y \in [-2, 2] \\ -2, -2 & \text{if } x < -2 \wedge y < -2 \\ -2, 2 & \text{if } x < -2 \wedge y > 2 \\ 2, -2 & \text{if } x > 2 \wedge y < -2 \\ 2, 2 & \text{if } x > 2 \wedge y > 2 \end{cases} \quad (16)$$

3. For triangle $\triangle ABC$, where $A(-1, -1)$, $B(1.5, -1)$, $C(-1, 1.5)$. Similarly we split the space into 7 subspaces, we project outliers to the nearest edge of $\triangle ABC$. We compute the following vector

$$a = \vec{AB} = \begin{bmatrix} 2.5 \\ 0 \end{bmatrix}, b = \vec{AC} = \begin{bmatrix} 0 \\ -2.5 \end{bmatrix}, c = \vec{BC} = \begin{bmatrix} -2.5 \\ 2.5 \end{bmatrix}.$$

We compute the necessary vectors for vector projection

$$f(x_1, y_1) = \begin{cases} C & \text{if } -1 < x < C + \alpha \begin{bmatrix} 1 & 1 \end{bmatrix}^T \wedge y > 1.5 \\ -1, 1 & \text{if } x < -1 \wedge y \in [-1, 1.5] \\ A & \text{if } x < -1 \wedge y < -1 \\ x, -1 & \text{if } x \in [-1, 1.5] \wedge y < -1 \\ x, -1 & \text{if } x \in [-1, 1.5] \wedge y < -1 \\ B & \text{if } x > 1.5 \wedge y \in (-\infty, \alpha B + \begin{bmatrix} 1 \\ 1 \end{bmatrix}] \\ B + BX & \text{if } x \in [-1, 1.5] \wedge y \in [B + \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}, C + \alpha \begin{bmatrix} 1 \\ 1 \end{bmatrix}] \end{cases} \quad (17)$$

The last inequality equals $BX = \frac{\vec{BC}x}{\|\vec{BC}\| \|\vec{x}\|} \vec{BC}$.

1.4 Gradient convergence

We change function f into $\frac{1}{2}x^T Hx$, where $H = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix}$.

1. We minimize $x_2^T Hx_2$ by γ and get $(I - 2\gamma)^T H(I - 2\gamma)$; we can omit the x_1 from the equation since those just give us a regularizing constant. Evaluating the equation we get

$$2(1 - 2\gamma)^2 + 4(1 - 4\gamma)^2 \quad (18)$$

To minimize we set its derivative with respect to γ to zero

$$\begin{aligned} 4(1 - 2\gamma)(-2) + 8(1 - 4\gamma)(-4) &= 0 \\ \gamma &= \frac{5}{18} \end{aligned} \quad (19)$$

Inserting gamma into gradient descent, we get that the lowest function value equals $\begin{bmatrix} 8/18 \\ -2/18 \end{bmatrix}$.

2. To find the minimum x we can reach in one step we minimize the norm $\|x_1 - \gamma Hx_1\|$

$$\begin{aligned} (x_1 - \gamma Hx_1)^T (x_1 - \gamma Hx_1) &= \\ x_1^T (I - 2\gamma H + \gamma^2 H^2)x_1 \end{aligned} \quad (20)$$

In order to find the minimum of $\|x_1 - \gamma Hx_1\|$ with respect to γ we derivate

$$x_1^T (-2H + 2\gamma H^2)x_1 = 0 \quad (21)$$

Solving the following equation for γ we get $\gamma = 3/10$ and $x_2 = \begin{bmatrix} 2/5 \\ -1/5 \end{bmatrix}$.

2 Practical problems

2.1 PGD

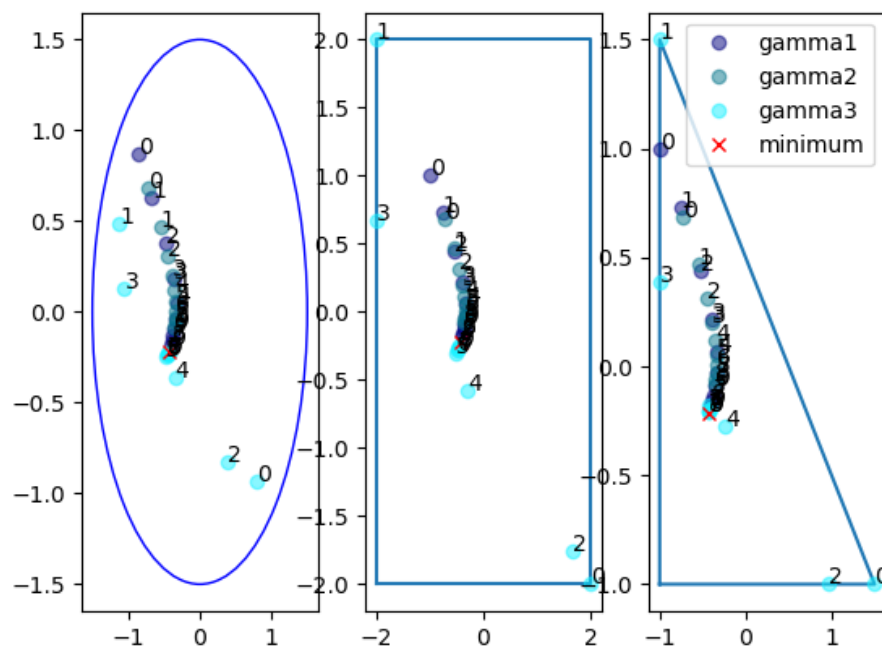


Figure 1: **Convergence using different gamma's.** The optimal Lipschitz convergence oscillates around the minimum, while beta and alpha GD slowly converges towards minimum.

2.2 GD

Using gradient descent with $\gamma = 6e - 4$ we reached -3.8627815600480115 in 9999 steps.