# **Bayesian Learning**

#### Bayesian Learning

- It involves direct manipulation of probabilities in order to find correct hypotheses
- The quantities of interest are governed by probability distributions
- Optimal decisions can be made by reasoning about those probabilities

#### **Bayesian Learning**

- Bayesian learning algorithms are among the most practical approaches to certain type of learning problems
- They provide a useful perspective for understanding many learning algorithms that do not explicitly manipulate probabilities

## Features of Bayesian Learning

- Each training example can incrementally decrease or increase the estimated probability that a hypothesis is correct
- Prior knowledge can be combined with observed data to determine the final probability of a hypothesis
- Hypotheses with probabilities can be accommodated
- New instances can be classified by combining multiple hypotheses weighted by their probabilities

$$P(h \mid D) = \frac{P(D \mid h)P(h)}{P(D)}$$

- P(h): prior probability of hypothesis h
- P(D): prior probability of training data D
- P(h | D): probability that h holds given D
- P(D | h): probability that D is observed given h

 Maximum A-posteriori hypothesis (MAP): (dependent on experience)

$$h_{MAP} = argmax_{h \in H} P(h \mid D) = argmax_{h \in H} P(D \mid h)P(h)$$

P(h) is not a uniform distribution over H.

$$P(h \mid D) = \frac{P(D \mid h)P(h)}{P(D)}$$

Maximum Likelihood hypothesis (ML):

$$h_{ML} = argmax_{h \in H} P(h \mid D) = argmax_{h \in H} P(D \mid h)$$

P(h) is a uniform distribution over H.

$$P(h \mid D) = \frac{P(D \mid h)P(h)}{P(D)}$$

- 0.008 of the population have cancer
- Only 98% patients are correctly classified as positive
- Only 97% non-patients are correctly classified as negative

Would a person with a positive result have cancer or not?

- 0.008 of the population have cancer
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Would a person with a positive result have cancer or not?

$$P(cancer|\oplus) >< P(\neg cancer|\oplus) ?$$

Maximum A-posteriori hypothesis (MAP):

$$h_{MAP} = argmax_{h \in \{cancer, \neg cancer\}} P(h \mid \oplus)$$

= 
$$argmax_{h \in \{cancer, \neg cancer\}} P(\oplus | h)P(h)$$

- P(cancer) =  $.008 \Rightarrow P(\neg cancer) = .992$
- P(⊕|cancer) = .98
- $P(\ominus|\neg cancer) = .97 \Rightarrow P(\oplus|\neg cancer) = .03$

 $P(cancer|\oplus) \approx P(\oplus|cancer)P(cancer) = .0078$ 

 $P(\neg cancer| \oplus) \approx P(\oplus | \neg cancer) P(\neg cancer) = .0298$ 

Maximum A-posteriori hypothesis (MAP):

$$h_{MAP} = argmax_{h \in \{cancer, \neg cancer\}} P(h \mid \oplus)$$

= 
$$argmax_{h \in \{cancer, \neg cancer\}} P(\oplus | h)P(h)$$

= ¬cancer

# **Bayes Optimal Classifier**

 What is the most probable hypothesis given the training data?

?

 What is the most probable classification of a new instance given the training data?

## Bayes Optimal Classifier

- Hypothesis space = {h<sub>1</sub>, h<sub>2</sub>, h<sub>3</sub>}
- Posterior probabilities = {.4, .3., .3} (h<sub>1</sub> is h<sub>MAP</sub>)
- New instance x is classified positive by h<sub>1</sub> and negative by h<sub>2</sub> and h<sub>3</sub>

What is the most probable classification of x?

#### **Bayes Optimal Classifier**

 The most probable classification of a new instance is obtained by combining the predictions of all hypotheses weighted by their posterior probabilities:

$$\operatorname{argmax}_{c \in C} P(c \mid D)$$

= argmax<sub>c∈C</sub>  $\sum_{h \in H} P(c \mid h).P(h \mid D)$ 

Example	Sky	AirTemp	Humidity	Wind	Water	Forecast	EnjoySport
1	Sunny	Warm	Normal	Strong	Warm	Same	Yes
2	Sunny	Warm	High	Strong	Warm	Same	Yes
3	Rainy	Cold	High	Strong	Warm	Change	No
4	Sunny	Warm	High	Strong	Cool	Change	Yes
5	Cloudy	Warm	High	Weak	Cool	Same	Yes
6	Cloudy	Cold	High	Weak	Cool	Same	No

7	Sunny	Warm	Normal	Strong	Warm	Same	?
8	Sunny	Warm	Low	Strong	Cool	Same	?

- Each instance x is described by a conjunction of attribute values <a<sub>1</sub>, a<sub>2</sub>, ..., a<sub>n</sub>>
- The target function f(x) can take on any value from a finite set C
- It is to assign the most probable target value to a new instance

$$c_{MAP} = argmax_{c \in C} P(c \mid a_1, a_2, ..., a_n)$$
  
=  $argmax_{c \in C} P(a_1, a_2, ..., a_n \mid c).P(c)$ 

$$c_{MAP} = argmax_{c \in C} P(c \mid a_1, a_2, ..., a_n)$$
  
=  $argmax_{c \in C} P(a_1, a_2, ..., a_n \mid c).P(c)$ 

$$c_{NB} = argmax_{c \in C} \prod_{i=1,n} P(a_i | c).P(c)$$

assuming that  $a_1$ ,  $a_2$ , ...,  $a_n$  are independent given c

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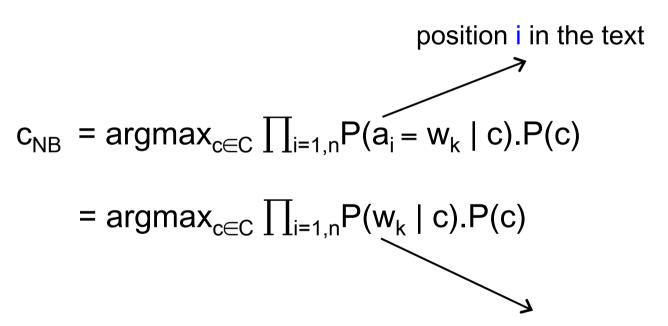
#### Estimating probabilities:

- n: total number of training examples of a particular class
- n<sub>c</sub>: number of training examples having a particular attribute value in that class
- m: equivalent sample size
- p: prior estimate of the probability (= 1/k where k is the number of possible values of the attribute)

#### Learning to classify text:

position i in the text 
$$c_{NB} = argmax_{c \in C} \prod_{i=1,n} P(a_i = w_k \mid c).P(c)$$

#### Learning to classify text:



assuming that all words have equal chance occurring in every position