

# Application Note BRT\_AN\_035 EVE Emulator Library User Guide

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This document describes the interface and usage of EVE emulator library.

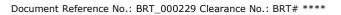
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#### 1 Introduction

EVE Emulator is the behavior modeling software for any FT8XX/BT8XX running on PC. It is designed as high level (behavior level) emulator other than low level (clock wise accuracy) emulator. It enables the user to evaluate FT8XX/BT8XX features on PC without hardware. EVE emulator library is the implementation and distribution package of EVE emulator. This document describes the interface of EVE Emulator library and shows one example on how to use it in user's project.

#### 1.1 Overview

EVE emulator has the exact SPI interface as well as memory map with **EVE** Series silicon, i.e., FT80X, FT81X and BT81X. Therefore, user application does not need to change the way to communicate with EVE emulator. In terms of behavior, EVE emulator has the maximum similarity, although there are a few limitations, which are mentioned at 1.4.

For touch functionality, EVE emulator requires the mouse of PC to simulate the input of touch.

For visual effect, EVE emulator employs the OS specific graphics driver to display on its monitor. It supports full set of display list commands and most of coprocessor commands.

Therefore, EVE emulator is one ideal tool for customers who would like to prototype or debug their EVE project on PC quickly and easily.

### 1.2 Scope

This document has covered the interface EVE emulator library provides and introduces how to use it in application. However, this document does not include the implementation details about EVE emulator. The FT8XX/BT8XX relative information, such as registers, memory map, commands, etc. is also not covered.

Although EVE emulator library has the respective version supporting Mac, Linux, Windows, this document only covers the Windows library usage and example.

## 1.3 Requirement

Currently, the EVE emulator library is built by **MSVC** 2015 Community Edition. So it may require the same tool chain to link it with users' project successfully.

In addition, the runtime "vcruntime140.dll" and "msvcp140.dll" is required on Windows to run the emulator project successfully.

#### 1.4 Limitation

EVE emulator does NOT have following functionality enabled till now:

- 1. Power management and host commands,
- 2. Coprocessor command "cmd snapshot" has no effect
- 3. Coprocessor engine reset,
- 4. Interrupt,
- 5. Registers which are reflecting hardware properties, e.g., the pressure value of touch and ADC related touch registers,
- 6. Performance or hardware related limitation due to EVE emulator is not clock level emulator.





# 2 EVE Emulator Library Introduction

## 2.1 EVE Emulator Library Interface

All the EVE Emulator library interface is written in C++ and resides in the "BT8XXEMU::" name space only. Within the "BT8XXEMU::" name space, there are two modules "Flash" and "Emulator". Here is the structure:

Table 1 EVE Emulator library interface structure

Name Space	Module Name	API Name	Parameter	Return	Description
BT8XXEMU::	Emulator	stop	None	None	Stop the running Emulator
BT8XXEMU::	Emulator	cs	Boolean	None	Make Chip selection to read / write one SPI transfer
BT8XXEMU::	Emulator	isRunning	None	Boolean	Check whether the Emulator is still running. True if running and false if not
BT8XXEMU::	Emulator	destroy	None	None	To destroy the emulator when it exits.
BT8XXEMU::	Emulator	transfer	One byte	One byte	Make one byte SPI transaction on SPI bus.
BT8XXEMU::	Emulator	getRam	None	One byte	Retrieve one byte of Ram data.
BT8XXEMU::	Flash	vTable	None	See below	Retrieve the vTable from the Flash.



#### 2.2 Emulator Module

#### 1. API to invoke and perform operations on Emulator

API Name	Function
BT8XXEMU_defaults	Initialize the default emulator parameters
BT8XXEMU_run	Run the emulator on the current thread. Returns when the emulator is fully stopped when a Main function is supplied, returns when the emulator is fully started otherwise.
BT8XXEMU_stop	Stop the emulator. Can be called from any thread. Returns when the emulator has fully stopped. Safe to call multiple times
BT8XXEMU_destroy	Destroy the emulator. Calls BT8XXEMU_stop implicitly. Emulator must be destroyed before process exits.
BT8XXEMU_isRunning	Poll if the emulator is still running. Returns 0 when the output window has been closed, or when the emulator has been stopped.
BT8XXEMU_transfer	Transfer data over the imaginary SPI bus. Call from the MCU thread (from the setup/loop callbacks).
BT8XXEMU_chipSelect	Set chip select. Must be set to 1 to start data transfer, 0 to end. See FT8XX documentation for CS_N
BT8XXEMU_hasInterrupt	Returns 1 if there is an interrupt flag set. Depends on mask.

#### 2. Flags to configure the Emulator

The enumerate below defines the behavior of emulator flags to be run. You can "OR" these enumerates and assign these values to "Flags" field in the parameter structure "EmulatorParameters".

```
enum BT8XXEMU EmulatorFlags
     // enables the keyboard to be used as input
     BT8XXEMU EmulatorEnableKeyboard = 0 \times 01,
     // enables audio
     BT8XXEMU EmulatorEnableAudio= 0x02,
     // enables coprocessor
     BT8XXEMU EmulatorEnableCoprocessor=
     0x04,
     // enables mouse as touch
     BT8XXEMU EmulatorEnableMouse=
     // enable debug shortkeys
     BT8XXEMU_EmulatorEnableDebugShortkeys=
     // enable graphics processor multithreading
     BT8XXEMU EmulatorEnableGraphicsMultithread= 0x20,
     // enable dynamic graphics quality degrading by interlacing
     BT8XXEMU EmulatorEnableDynamicDegrade = 0x40,
     // enable emulating REG PWM DUTY by fading the rendered display
     to black
     BT8XXEMU_EmulatorEnableRegPwmDutyEmulation = 0 \times 100,
     // enable usage of touch transformation matrix
     BT8XXEMU EmulatorEnableTouchTransformation = 0x200,
     // enable output to stdout from the emulator
     BT8XXEMU EmulatorEnableStdOut = 0 \times 400,
     // enable performance adjustments for running the emulator
     as a background process without window
     BT8XXEMU EmulatorEnableBackgroundPerformance = 0x800,
     \ensuremath{//} enable performance adjustments for the main MCU thread
     BT8XXEMU_EmulatorEnableMainPerformance = 0 \times 1000,
 };
```

Figure 1 Emulator Flags field definition



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#### 3. API description

#### BT8XXEMU\_defaults

#### **Prototype**

void BT8XXEMU defaults (uint32 t versionApi, BT8XXEMU EmulatorParameters \*params, BT8XXEMU EmulatorMode mode);

#### **Description**

Call this API in order to initialize the default parameters of the Emulator by setting the parameters in the params argument and setting the mode in mode argument which are passed to this function.

#### **Return value**

None

#### **Parameter**

versionApi This parameter describe the version of the API. The version of API

changes whenever there is a change in the number of Emulator

parameters or the format and changes in the functions itself.

Emulator Parameters - (Refer figure 2 below for Emulator params

Parameters)

mode Defines which emulator needs to be invoked. See note below for

the different emulator modes.

```
typedef struct
     // Microcontroller main function. This will be run on a new thread managed by the
     // emulator. When not provided the calling thread is assumed to be the MCU thread
void(*Main)(BT8XXEMU_Emulator *sender, void *context);
     // See EmulatorFlags.
     int Flags;
     // Emulator mode
     BT8XXEMU_EmulatorMode Mode;
     // The default mouse pressure, default 0 (maximum).
     // See REG_TOUCH_RZTRESH, etc.
     uint32_t MousePressure;
     // External frequency. See CLK, etc.
     uint32_t ExternalFrequency;
     // Reduce graphics processor threads by specified number, default 0 // Necessary when doing very heavy work on the MCU or Coprocessor
     uint32 t ReduceGraphicsThreads;
     // Sleep function for MCU thread usage throttle. Defaults to generic system sleep
     void(*MCUSleep)(BT8XXEMU_Emulator *sender, void *context, int ms);
     // Replaces the default builtin ROM with a custom ROM from a file.
     // NOTE: String is copied and may be deallocated after call to run(...)
     wchar t RomFilePath[260];
     // Replaces the default builtin OTP with a custom OTP from a file.
     // NOTE: String is copied and may be deallocated after call to \operatorname{run}\left(\ldots\right)
     wchar t OtpFilePath[260];
     // Replaces the builtin coprocessor ROM.
     // NOTE: String is copied and may be deallocated after call to run(...)
     wchar_t CoprocessorRomFilePath[260];
     // Graphics driverless mode
     // Setting this callback means no window will be created, and all
// rendered graphics will be automatically sent to this function.
        For enabling touch functionality, the functions
        Memory.setTouchScreenXY and Memory.resetTouchScreenXY must be
         called manually from the host application.
     // Builtin keyboard functionality is not supported and must be
        implemented manually when using this mode. The output parameter is false (0) when the display is turned off.
        The contents of the buffer pointer are undefined after this
     // function returns. Create a copy to use it on another thread.
     // Return false (0) when the application must exit, otherwise return true (1).
     int(*Graphics)(BT8XXEMU_Emulator *sender, void *context, int output, const argb8888
*buffer, uint32_t hsize, uint32_t vsize, BT8XXEMU_FrameFlags flags);
     // Log callback
     void(*Log)(BT8XXEMU Emulator *sender, void *context, BT8XXEMU LogType type,
     const char *message);
```



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```
// Safe exit. Called when the emulator window is closed
void(*Close) (BT8XXEMU Emulator *sender, void *context);
// User context that will be passed along to callbacks
void *UserContext;
// Flash device to connect with, default NULL BT8XXEMU_Flash *Flash;
```

#### Figure 2 Emulator parameters

```
typedef enum
                BT8XXEMU_EmulatorFT800 = 0x0800,
                BT8XXEMU_EmulatorFT801 = 0x0801,
BT8XXEMU_EmulatorFT810 = 0x0810,
BT8XXEMU_EmulatorFT811 = 0x0811,
BT8XXEMU_EmulatorFT812 = 0x0812,
BT8XXEMU_EmulatorFT813 = 0x0813,
                BT8XXEMU EmulatorBT815 = 0x0815,
} BT8XXEMU_EmulatorMode;
```

} BT8XXEMU EmulatorParameters;

Figure 3 Emulator mode

#### BT8XXEMU\_run

#### **Prototype**

void BT8XXEMU\_run (uint32\_t versionApi, BT8XXEMU\_Emulator \*\*emulator, const BT8XXEMU EmulatorParameters \*params);

#### **Description**

This API runs the emulator on the current thread. The API returns when the emulator is fully stopped when a Main function is supplied or returns when the emulator is fully started otherwise.

#### **Return value**

None

#### **Parameter**

versionApi This parameter describe the version of the API. The version of API

> changes whenever there is a change in the number of emulator parameters or the format and changes in the functions itself.

This parameter is the handle to the global emulator instance. emulator

This parameter is used to set the emulator params. (Refer figure 2 params

above for emulator params)

#### BT8XXEMU chipSelect

#### **Prototype**

void BT8XXEMU\_chipSelect (BT8XXEMU\_Emulator \* emulator, int cs);

#### **Description**

This API does the chip selection by setting the cs value to 1 to start data transfer and 0 to stop the data transfer.

#### **Return value**

None

#### **Parameter**

This parameter is set to 1/0 to start/stop the data transfer. CS This parameter is the handle to the global emulator instance. emulator



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#### BT8XXEMU\_transfer

#### **Prototype**

uint8\_t BT8XXEMU\_transfer (BT8XXEMU\_Emulator \* emulator, uint8\_t data);

#### **Description**

Calling this API is equivalent to sending one byte data on the MOSI line of SPI bus, at same time receiving one byte data on the MISO line of SPI bus. The data to be sent is specified as parameter, while the data to be received is given as return value.

#### **Return value**

One byte data received from EVE emulator, equivalent to receiving from the MISO line of SPI bus.

#### **Parameter**

emulator This parameter is the handle to the global emulator instance.

One byte data sending to EVE emulator. In the case of SPI read data

transaction, this byte can be anything.)

#### BT8XXEMU\_stop

#### **Prototype**

void BT8XXEMU stop (BT8XXEMU Emulator \* emulator);

#### **Description**

Call to this API will stop the running emulator instance.

#### **Return value**

Nothing.

#### **Parameter**

emulator This parameter is the handle to the global emulator instance.

#### BT8XXEMU\_destroy

#### **Prototype**

void BT8XXEMU destroy (BT8XXEMU Emulator \* emulator);

#### **Description**

Call to this API will destroy the emulator instance.

#### **Return value**

Nothing.

#### **Parameter**

emulator This parameter is the handle to the global emulator instance.

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#### 4. Typical setting for EVE emulator

Currently, please note that only the settings as below are strongly recommended to use now.

The callback function "mcu()" **should be defined** by user project and they will be called by emulator. The mcu() implementation should call 2 more functions "setup()" and "loop()". Function "setup()" is assumed to run once by emulator for initialization purpose. Function "loop()" will be called periodically by emulator. These two functions make sure the user project is in the context of EVE emulator. The failure of calling "setup()" and "loop()" in callback function mcu() will cause no input to EVE emulator.

Figure 4 Setup and Run BT815 emulator

#### 5. Use of EVE Emulator library

This chapter will give one example on how to use EVE emulator in sample application. Users are encouraged to get familiar with BT815 sample application before starting this chapter.

#### • Start the BT815 emulator

To make use of BT815 emulator, user project requires to call the API "BT8XXEMU\_defaults()" with the specific parameter to set up the BT815 emulator, then it is required to call the API BT8XXEMU\_run() in order to start the emulator.

Please see Figure 3 Setup and Run BT815 emulator.





After porting the application to BT815 emulator according to the instructions above, to build the final executable, user project is needed to specify the path and name of EVE emulator library.

For debug/release build, please specify the BT815 emulator library named "bt8xxemu.lib".

Please note that Microsoft Visual Studio 2015 Community version is a must to build with your application.

The picture below shows the screenshot when the BT815 sample application run on top of BT815 emulator.



Figure 5 Sample applications running on top of BT815 emulator (Setting Font)

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#### 2.3 Flash Module

The latest BT8XX chips do support an external Flash memory using QSPI interface. The flash module could be simulated by sending and receiving data using the EVE emulator. Separate set of APIs are used exclusively to invoke flash emulator using the EVE emulator. Below are the APIs and its description of Flash emulator.

1. API to invoke and perform operations on Flash Emulator

API Name	Function
BT8XXEMU_Flash_defaults	Initialize the default flash emulator parameters
BT8XXEMU_Flash_create	Create the flash emulator instance
BT8XXEMU_Flash_destroy	Destroy the flash emulator instance
BT8XXEMU_Flash_transferSpi4	Transfer data using SPI or Quad SPI protocol. Bit 0:3 are data, bit 4 is cable select (0 active), SCK is clock. In single mode bit 0 is MOSI and bit 1 is MISO
BT8XXEMU_Flash_data	Vtable data in flash
BT8XXEMU_Flash_size	Size of Vtable data in flash

#### 2. API description

#### BT8XXEMU\_Flash\_defaults

#### Prototype

void BT8XXEMU\_Flash\_defaults(uint32\_t versionApi, BT8XXEMU\_FlashParameters \*params);

#### Description

Call this API in order to initialize the default parameters of the flash emulator by setting the parameters in the params argument and setting the mode in mode argument which are passed to this function.

#### Return value

None

#### Parameter

versionApi This parameter describe the version of the API. The version of API

changes whenever there is a change in the number of emulator  $% \left( 1\right) =\left( 1\right) \left( 1\right)$ 

parameters or the format and changes in the functions itself.

params This parameter is used to set the flash emulator params (Refer

figure 4 below for flash emulator parameters)

```
typedef struct
     // Device type, by library name, default "mx25lemu"
     wchar_t DeviceType[26];
     // Size of the flash memory in bytes, default 8MB
     size t SizeBytes;
     // Data file to load onto the flash, default {\tt NULL}
     wchar_t DataFilePath[260];
     // Internal flash status file, device specific, default NULL
     wchar_t StatusFilePath[260];
     // Write actions to the flash are persisted to the used file. // This is accomplished by memory mapping the file, instead of
     // the file being copied to memory. Default false
     bool Persistent;
     // Print log to standard output. Default false
     bool StdOut;
     // Data buffer that is written to the flash initially,
       overriding any existing contents that may have been
     // loaded from a flash file already, default NULL and 0
```



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void \*Data;
size\_t DataSizeBytes;

// Log callback
void(\*Log) (BT8XXEMU\_Flash \*sender, void \*context, BT8XXEMU\_LogType type,
const char \*message);

} BT8XXEMU FlashParameters;

void \*UserContext;

#### Figure 6 Flash Emulator Parameters

#### BT8XXEMU\_Flash\_create

#### Prototype

BT8XXEMU\_Flash \*BT8XXEMU\_Flash\_create(uint32\_t versionApi, const BT8XXEMU FlashParameters \*params);

// User context that will be passed along to callbacks

#### Description

This API creates a flash emulator instance and assigns the handle to the flash pointer.

#### Return value

BT8XXEMU\_Flash\* - Returns the pointer to the flash instance created.

#### Parameter

versionApi This parameter describe the version of the API. The version of API

changes whenever there is a change in the number of flash emulator parameters or the format and changes in the functions

itself.

params (Refer figure 4 above for flash emulator parameters)

#### BT8XXEMU\_Flash\_destroy

#### Prototype

void BT8XXEMU\_Flash\_destroy(BT8XXEMU\_Flash \*flash);

#### Description

This API destroys the flash emulator instance which was created earlier.

#### Return value

Nothing.

#### Parameter

flash Pointer to the flash emulator instance to be destroyed.

#### BT8XXEMU\_Flash\_transferSpi4

#### Prototype

uint8\_t BT8XXEMU\_Flash\_transferSpi4(BT8XXEMU\_Flash \*flash, uint8\_t signal);

#### **Description**

This API destroys the flash emulator instance which was created earlier.

#### Return value

uint8\_t Returns one byte of data while reading.

#### Parameter

flash Pointer to the flash emulator instance to which the data to be transferred.

signal sends one byte of data while writing.



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#### BT8XXEMU\_Flash\_data

#### Prototype

uint8\_t\* BT8XXEMU\_Flash\_data(BT8XXEMU\_Flash \*flash);

#### **Description**

This API retrieves the flash's vtable data.

#### Return value

uint8\_t\* Returns the pointer to the address of the vtable data.

#### Parameter

flash Pointer to the flash emulator instance.

#### BT8XXEMU\_Flash\_size

#### Prototype

size\_t BT8XXEMU\_Flash\_size(BT8XXEMU\_Flash \*flash);

#### **Description**

This API retrieves the size of the flash's vtable data.

#### Return value

size\_t Returns an unsigned byte of the size of the vtable in flash.

#### Parameter

flash Pointer to the flash emulator instance.



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#### 3. Typical setting for Flash module using EVE emulator

Currently, please note that only the settings as below are strongly recommended to use now.

Basically the flash module is a part of the EVE emulator itself only in the case of BT8XX chips, and it could be setup by calling the APIs as mentioned below in the code snippet.

```
#define BTFLASH_DEVICE_TYPE L"mx25lemu"
#define BTFLASH_SIZE (8 * 1024 * 1024)
#define BTFLASH_DATA_FILE L"C:/Projects/FT8XXEmulator/reference/vc3roms/stdflash.bin"
#define BTFLASH_DIANAFIN API 11
#define BTFLASH_FIRMWARE L"C:/Projects/FT8XXEmulator/fteditor/firmware/mx251.blob"
int main(int, char*[])
           printf("%s\n\n", BT8XXEMU version());
           BT8XXEMU_FlashParameters flashParams;
           BT8XXEMU_Flash_defaults(BT8XXEMU_VERSION_API, &flashParams);
           wcscpy(flashParams.DeviceType, BTFLASH_DEVICE_TYPE);
           flashParams.SizeBytes = BTFLASH_SIZE;
           wcscpy(flashParams.DataFilePath, BTFLASH_DATA_FILE);
           flashParams.StdOut = true;
           BT8XXEMU Flash *flash;
           //// Test different memory sizes
           int sizes[8] = { 2, 4, 8, 16, 32, 64, 128, 256 };
           for (int si = 0; si < 8; ++si)</pre>
                     int sz = sizes[si];
                     printf("SIZE %i\n", sz);
                     flashParams.SizeBytes = sz * 1024 * 1024;
                     wcscpy(flashParams.DataFilePath, BTFLASH FIRMWARE);
                     flash = BT8XXEMU Flash create(BT8XXEMU VERSION API, &flashParams);
                     data = BT8XXEMU_Flash_data(flash);
assert(data[0] == 0x70);
                     size = BT8XXEMU Flash size(flash);
                     assert(size == \bar{sz} * 1024 * 1024);
                     BT8XXEMU_EmulatorParameters params;
BT8XXEMU_defaults(BT8XXEMU_VERSION_API, &params, BT8XXEMU_EmulatorBT815);
                     params.Flags |= BT8XXEMU EmulatorEnableStdOut;
                     params.Flash = flash;
                     BT8XXEMU Emulator *emulator = NULL;
                     BT8XXEMU_run(BT8XXEMU_VERSION_API, &emulator, &params);
uint8_t *ram = BT8XXEMU_getRam(emulator);
                     wr32(emulator, REG_HSIZE, 480);
wr32(emulator, REG_VSIZE, 272);
                     wr32 (emulator, REG PCLK, 5);
                     flush (emulator);
                     while (!rd32(emulator, REG_FLASH_STATUS));
assert(rd32(emulator, REG_FLASH_STATUS) == FLASH_STATUS_BASIC);
                     //// Enter full speed mode
                                printf("CMD FLASHFAST\n");
                               wr32(emulator, REG_CMDB_WRITE, CMD_FLASHFAST);
uint32_t resAddr = rd32(emulator, REG_CMD_WRITE);
                                wr32(emulator, REG CMD WRITE, resAddr + 4);
                                flush(emulator);
                                assert(rd32(emulator, resAddr) == 0);
                                \verb|assert(rd32(emulator, REG_FLASH_STATUS)| == FLASH STATUS FULL);
```



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```
for (int i = 0; i < 4096; ++i)
                           ram[i] = 0x55;
              }
                           printf("CMD FLASHREAD (FLASH STATUS FULL) \n");
                          wr32(emulator, REG_CMDB_WRITE, CMD_FLASHREAD);
wr32(emulator, REG_CMDB_WRITE, 128); // dest
wr32(emulator, REG_CMDB_WRITE, 128); // src
wr32(emulator, REG_CMDB_WRITE, 512); // num
                           flush(emulator);
                           for (int i = 128; i < 128 + 512; ++i)
                                        assert(ram[i] == data[i]);
              }
              int idx = (sz * 1024 * 1024) - 12288;
              for (int i = 0; i < 256; ++i)
                          data[idx + i] = i;
                           printf("CMD_FLASHREAD (%i)\n", idx);
                          wr32(emulator, REG_CMDB_WRITE, CMD_FLASHREAD); wr32(emulator, REG_CMDB_WRITE, 128); // dest wr32(emulator, REG_CMDB_WRITE, idx); // src wr32(emulator, REG_CMDB_WRITE, 256); // num
                           flush(emulator);
                           for (int i = 0; i < 256; ++i)
                                        assert(ram[128 + i] == i);
             BT8XXEMU stop(emulator);
             BT8XXEMU_destroy(emulator);
emulator = NULL;
              BT8XXEMU Flash destroy(flash);
              flash = \overline{\text{NULL}};
             data = NULL;
}
```

Figure 7 Setup and Run flash module using EVE emulator

#### 4. Use of Flash Emulator library

This chapter will give one example on how to use Flash emulator in sample application.

#### • Start the Flash module using EVE emulator

To make use of Flash emulator, user project requires to call the API "BT8XXEMU\_Flash\_defaults()" with the specific parameter to set up the Flash module, then it is required to call the API BT8XXEMU\_Flash\_create() in order to create an instance of the Flash module by loading flash module library (mx25lemu.dll).

The data transfer to Flash module either in or out is started using the BT8XXEMU\_Flash\_transferSpi4() API. The flash data is retrieved using the vTable pointer to data in Flash module. The API BT8XXEMU\_Flash\_data() will in turn invoke the vTable pointer to give access to the data location.

Please see Figure 4 Setup and Run Flash module using EVE emulator.





#### **Build and Run**

After porting the application to run flash module using BT815 emulator according to the instructions above, to build the final executable, user project is needed to specify the path and name of EVE emulator library and the flash module library should be present in the final executable path as well.

For debug/release build, please specify the EVE emulator library named "bt8xxemu.lib".

Please note that Microsoft Visual Studio 2015 Community version is a must to build with your application.

The picture below shows the screenshot when the flash emulator sample application run on top of EVE emulator using flash module.

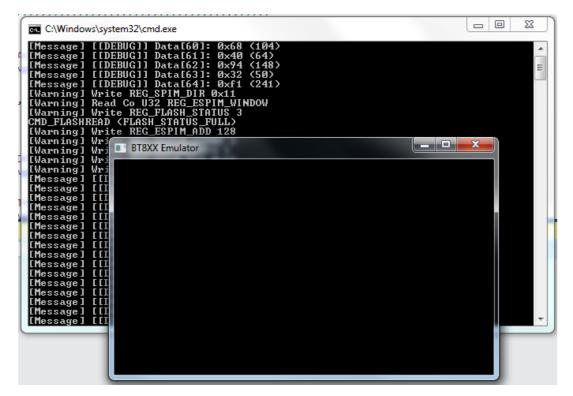


Figure 8 Sample flash module application running on top of BT815 emulator



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# **Appendix A - References**

## **Acronyms and Abbreviations**

Terms	Description
USB	Universal Serial Bus
USB-IF	USB Implementers Forum
PC	Personal Computer
Windows	Microsoft Windows Desktop operating system







# **Appendix B – List of Tables & Figures**

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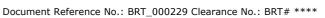




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