

# Operator Action Predictions

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# Short Introduction

- Common issues are errors in grid jobs, that may be due to missing/corrupt input files, high memory usage, etc.
- Currently all handled manually in Operations:
  - An operator must look at the error codes and decide on what appropriate actions to take on the workflow
- General Goal:
  - Deliver error handling predictions and mature towards moving manual operator intervention into automated actions

For more info look at Chrisians slides (slides 2-4):

[https://github.com/chrisjcc/WorkflowWebTools/blob/ErrorHandlingAI/docs/Christian\\_Workflow\\_Handling\\_PR.pdf](https://github.com/chrisjcc/WorkflowWebTools/blob/ErrorHandlingAI/docs/Christian_Workflow_Handling_PR.pdf)

# Short Introduction

Having errors that happened and where happened (at which site) predict (total examples = 9522):

- Which *action* to choose
- Requested *memory*
- Job *splitting*
- Enabling *xrootd* or not

# Inputs / X

- Each example consists of matrix w/ shape (errors,sites)
- On average 99.75% of all numbers in matrix will be 0
- 66% out of all combinations (error x site) are never used (are always 0) in dataset with 9522 examples

	site 1	site 2	site 3	site 4	...	site 140	site 141	site 142
error 1	1	1	1	1	1	1	1	1
error 2	4	0	0	0	0	0	0	0
error 3	8	1	0	0	0	0	0	0
...	0	2	0	0	0	0	2	0
error 52	0	0	0	0	0	0	0	5
error 53	0	0	0	0	0	0	0	1
error 54	1	0	0	0	0	0	0	0

single example shape = (54,142)

total examples = 9522

For more stats which errors are most common or examples look at Chrisians slides 5-7:

[https://github.com/chrisjcc/WorkflowWebTools/blob/ErrorHandlingAI/docs/Christian\\_Workflow\\_Handling\\_PR.pdf](https://github.com/chrisjcc/WorkflowWebTools/blob/ErrorHandlingAI/docs/Christian_Workflow_Handling_PR.pdf)

# Outputs / Y Targets

## Action

1. acdc (88%)
2. clone (10%)
3. special (2%)

## Splitting

1. 98.5% default
2. 0.59% 10x
3. 0.31% 2x
4. 0.19% max
5. 0.12% 100x
6. 0.09% 20x
7. 0.05% 3x
8. 0.03% 50x

## Memory

- |     |               |     |            |
|-----|---------------|-----|------------|
| 1.  | 92.6% default | 14. | 0.03% 2k   |
| 2.  | 2.36% 20k     | 15. | 0.03% 19k  |
| 3.  | 1.55% 18k     | 16. | 0.03% 16k  |
| 4.  | 0.59% 12k     | 17. | 0.02% 11k  |
| 5.  | 0.54% 4k      | 18. | 0.01% 40k  |
| 6.  | 0.51% 9k      | 19. | 0.01% 32k  |
| 7.  | 0.40% 6k      | 20. | 0.01% 30k  |
| 8.  | 0.37% 10k     | 21. | 0.01% 3k   |
| 9.  | 0.25% 5k      | 22. | 0.01% 28k  |
| 10. | 0.19% 8k      | 23. | 0.01% 25k  |
| 11. | 0.17% 14k     | 24. | 0.01% 20k  |
| 12. | 0.06% 7k      | 25. | 0.01% 180k |
| 13. | 0.05% 15k     | 26. | 0.01% 15k  |

## Xrootd

1. default (72%)
2. enabled (28%)
3. disabled (0.01%)

# Outputs / Y Targets (merged)

## Action

1. acdc (88%)
2. clone (10%)
3. special (2%)

## Memory

1. default (92%)
2. 18k-20k (4%)
3. 2k-9k (2%)
4. 10k-16k (1.2%)

## Splitting

1. default (98.5%)
2. 10x-100x (1%)
3. 2x-3x (0.4%)

## Xrootd

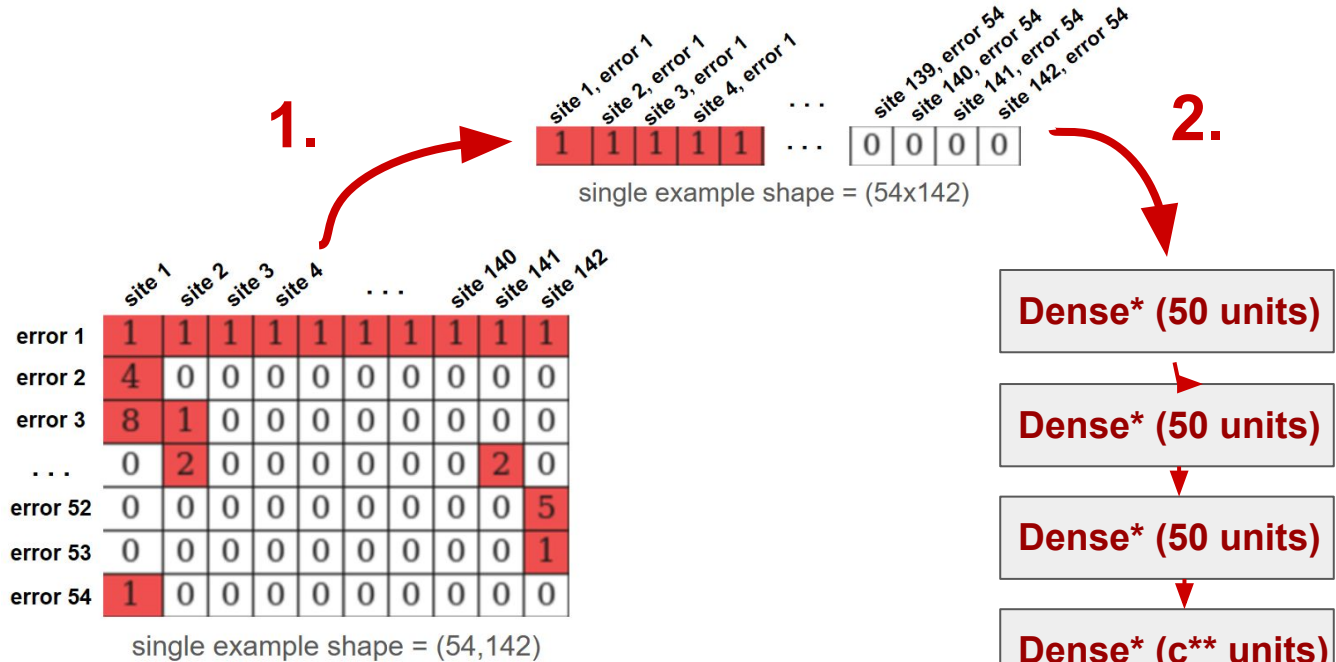
1. default (72%)
2. enabled (28%)
3. disabled (0.01%)

# Models Ideas

- Because lack of examples, try to minimize model parameters (CNN Model)
- Change input so that model would generalize better (Create embeddings for each site and error)
- Try different ways of fighting class imbalance (SMOTE resampling, weighted cross entropy)
- Try to find a way to explain the output (by adding additional layers to network)
- Compare everything with simple feed forward network (Simple model)

# Simple Model

1. inputs are flattened
2. fed to feed forward neural network
3. everything is optimized with weighted cross entropy (wCE)



$$J(\theta) = - \sum_i^n (W_{y_i}^{***} y_i \log \hat{y}_i)$$

\* - All Dense layers are with 0.2 dropout

\*\* - number of classes

\*\*\* - 
$$W_{y_i} = \frac{\text{total examples}}{\# \text{ classes}} \times \frac{1}{\# y_i \text{ examples}}$$

\*\* when resampling (using SMOTE) all classes become same size, which results in  $W = 1$  and loss = cross entropy<sub>8</sub>

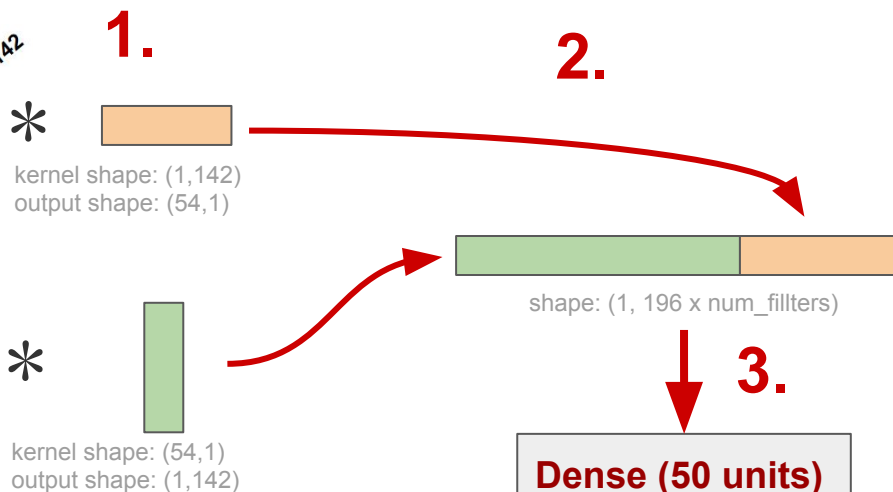


# CNN Model

1. input matrix is convolved\* across both axis
2. convolution layer outputs are concatenated
3. concat vector is fed to feed forward layers
4. everything is optimized with weighted cross entropy (wCE)

	site 1	site 2	site 3	site 4	...	site 140	site 141	site 142
error 1	1	1	1	1	1	1	1	1
error 2	4	0	0	0	0	0	0	0
error 3	8	1	0	0	0	0	0	0
...	0	2	0	0	0	0	0	2
error 52	0	0	0	0	0	0	0	5
error 53	0	0	0	0	0	0	0	1
error 54	1	0	0	0	0	0	0	0

single example shape = (54,142)



**Dense (50 units)**

**Dense (50 units)**

**Dense (50 units)**

**Dense (c units)**

$$J(\theta) = - \sum_i^n (W_{y_i} y_i \log \hat{y}_i)$$

\* - number of filters = 5

# CNN Model (adding Attention)

1. input matrix is convolved across both axis
2. input matrix is flatten and connected to 2 feed forward layers with softmax at the end
3. convolution outputs are multiplied by step 2 outputs
4. both outputs from step 3 are concatenated
5. concat vector is connected to feed forward layers
6. everything is optimized with weighted cross entropy (wCE)

	site 1	site 2	site 3	site 4	...	site 140	site 141	site 142
error 1	1	1	1	1	1	1	1	1
error 2	4	0	0	0	0	0	0	0
error 3	8	1	0	0	0	0	0	0
...	0	2	0	0	0	0	0	2
error 52	0	0	0	0	0	0	0	5
error 53	0	0	0	0	0	0	0	1
error 54	1	0	0	0	0	0	0	0

single example shape = (54,142)

Flatten

2.

Dense (54 units)

Softmax

Dense (142 units)

Softmax

\*  
kernel shape: (1,142)  
output shape: (54,1)

\*  
kernel shape: (54,1)  
output shape: (1,142)

1.

3.

4.

5.

shape: (1,196)

Dense (50 units)

Dense (50 units)

Dense (50 units)

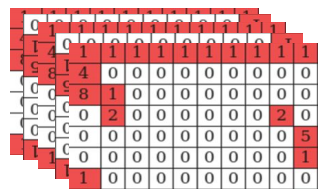
Dense (c units)

$$J(\theta) = - \sum_i^n (W_{y_i} y_i \log \hat{y}_i)$$

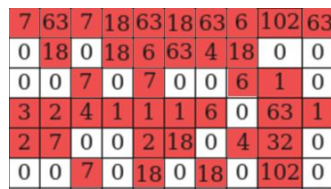
6.

# Error and Site embeddings

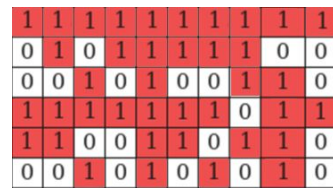
1. all examples are summed across axis 0
2. all numbers that are greater than 0 are replaced by 1
3. by doing dot product\* of error embedding matrix times sites embedding matrix try to recreate matrix from step 2
4. everything is optimized with mse



shape = (9522,54,142)



shape = (54,142)

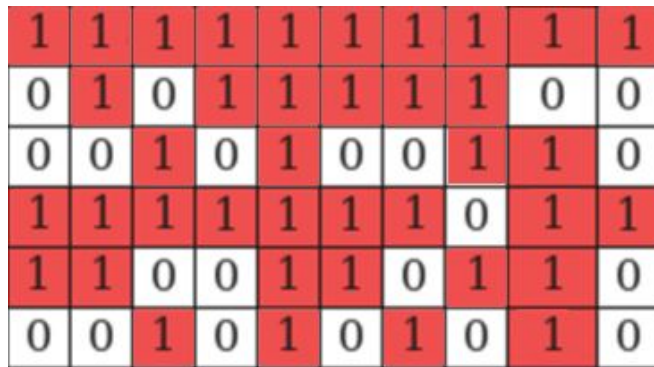


shape = (54,142)

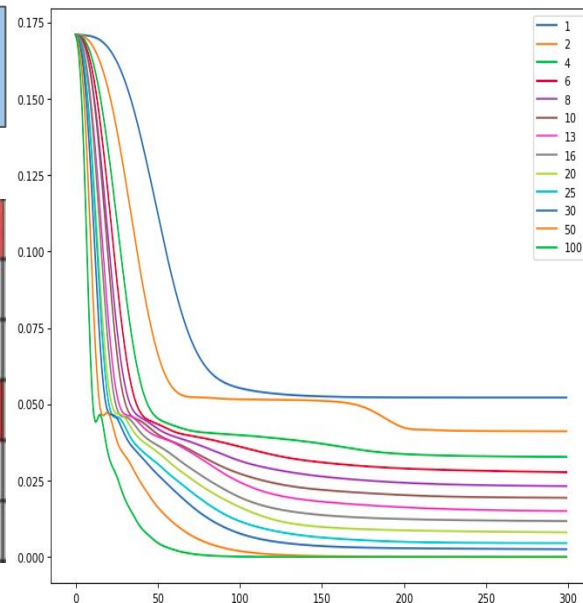
3.



sites embedding matrix with shape (e,142) \*\*



error embedding matrix  
with shape (54,e) \*\*



mse error with different embedding sizes 11

\* -  $(54, e) \cdot (e, 142) = (54, 142)$

\*\* -  $e = 20$

# Pseudo-Embedding Model

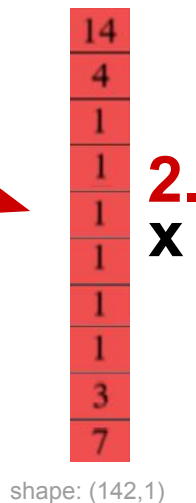
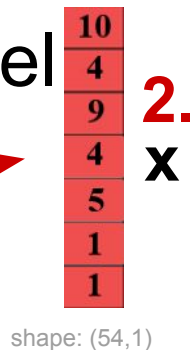
	site 1	site 2	site 3	site 4	...	site 140	site 141	site 142
error 1	1	1	1	1	1	1	1	1
error 2	4	0	0	0	0	0	0	0
error 3	8	1	0	0	0	0	0	0
...	0	2	0	0	0	0	0	2
error 52	0	0	0	0	0	0	0	5
error 53	0	0	0	0	0	0	0	1
error 54	1	0	0	0	0	0	0	0

single example shape = (54,142)

1. count number of errors
2. count errors in each site
- each count is multiplied by its embedding
- site embeddings and error embeddings are concatenated
- concat vector is fed to feed forward layers
- everything is optimized with weighted cross entropy (wCE)

1.1.

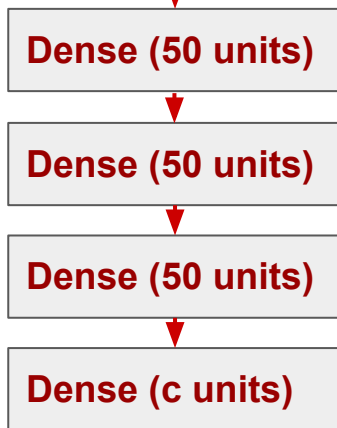
1.2.



3.



4.



5.

$$J(\theta) = - \sum_i^n (W_{y_i} y_i \log \hat{y}_i)$$

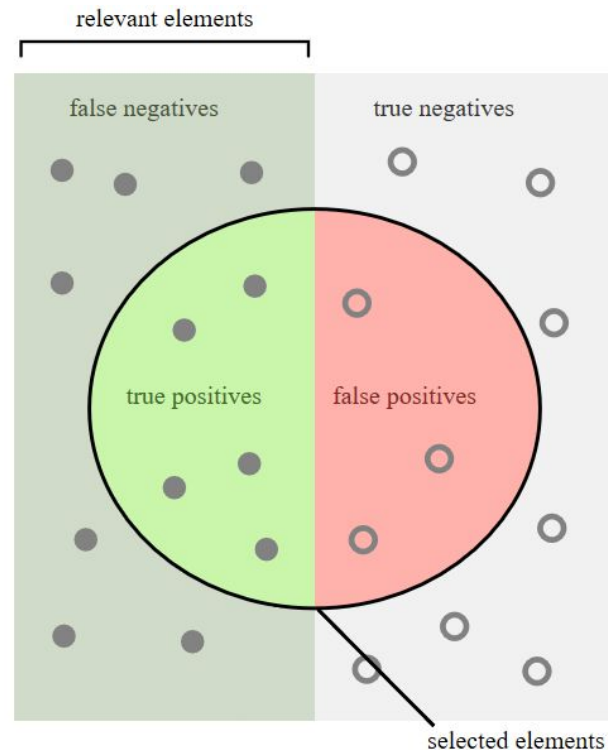
# Evaluation Metrics

- **Precision** (for each class) \*  
how many selected items are relevant?
- **Recall** (for each class) \*\*  
How many relevant items are selected?
- **Confusion MSE (main)** \*\*\*  
Mean squared error of normalized confusion matrix and identity matrix

Macro average is calculated for Recall and Precision !

$$* - \text{precision} = \frac{\text{relevant elements}}{\text{selected elements}}$$

$$** - \text{recall} = \frac{\text{relevant elements}}{\text{relevant elements}}$$



$$*** - \text{confusion mse} =$$

mse

0.74	0.21	0.05
0.37	0.61	0.02
0.26	0.03	0.71

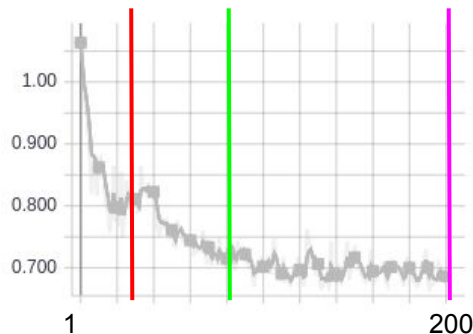
1	0	0
0	1	0
0	0	1

# Optimal Stopping when Training

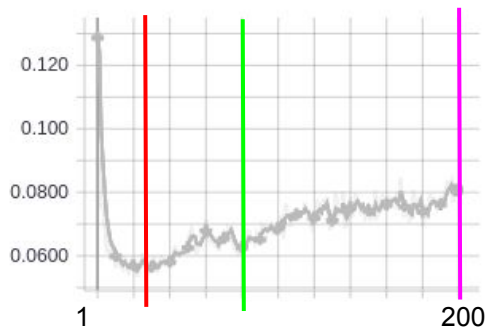
- Early stopping with single metric can lead training to stop too fast
- Looking at multiple metrics as equal can lead to stopping too late
- Optimal stopping point should be somewhere in between, that main metric doesn't deviate from best score and other metrics get better

- - too early stopping
- - optimal stopping
- - too late stopping

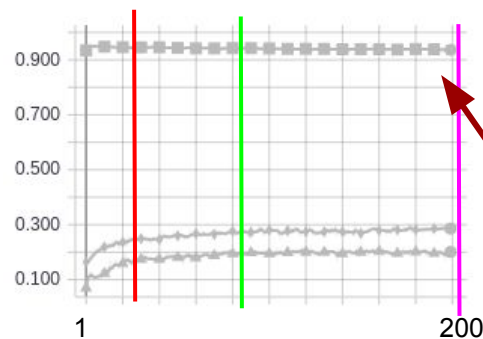
validation cross entropy



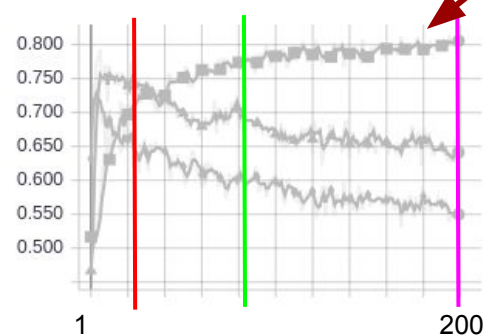
validation confusion mse (main metric)



validation precision (for each class)



validation recall (for each class)



dominant class (88%)

examples are taken when predicting action

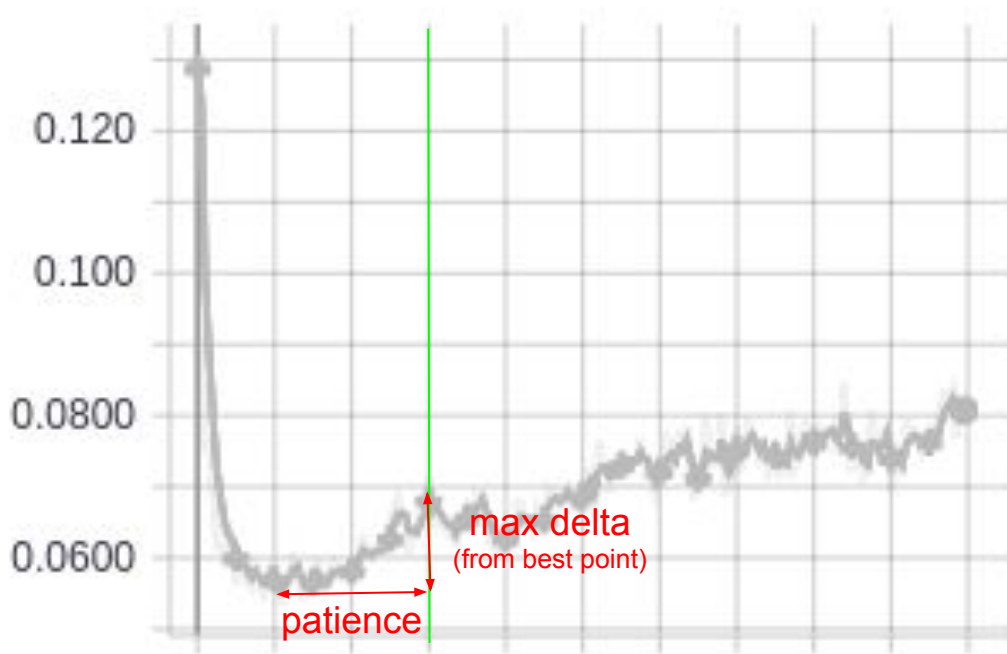
# Multiple Metric Early Stopping

1. At each epoch set best scores from all picked metrics
2. If none of the metrics gets better in  $n^*$  epoch then stop
3. If main score is worse compared to best score by  $T^{**}$  then stop

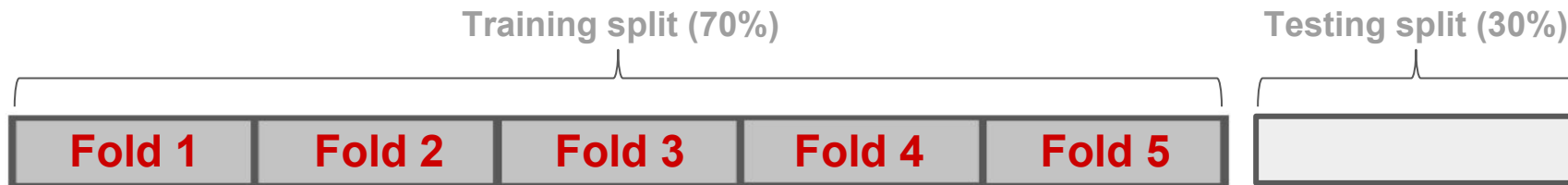
| - stopping point

\* -  $n$  - patience

\*\* -  $T$  - max delta, maximum allowed decrease of score from best score (in %)



# Picking Single Best Model



- Splitting\* dataset into testing and training datasets
- For each model\*\*:
  - Split training dataset into 5 equal size folds
  - Train on 4 Folds and test on 1 Fold (do this for each fold)
- Average each fold results into mean and std of each metric
- Model that results with best confusion mse on most outputs is considered best

\* - numpy seed = 42

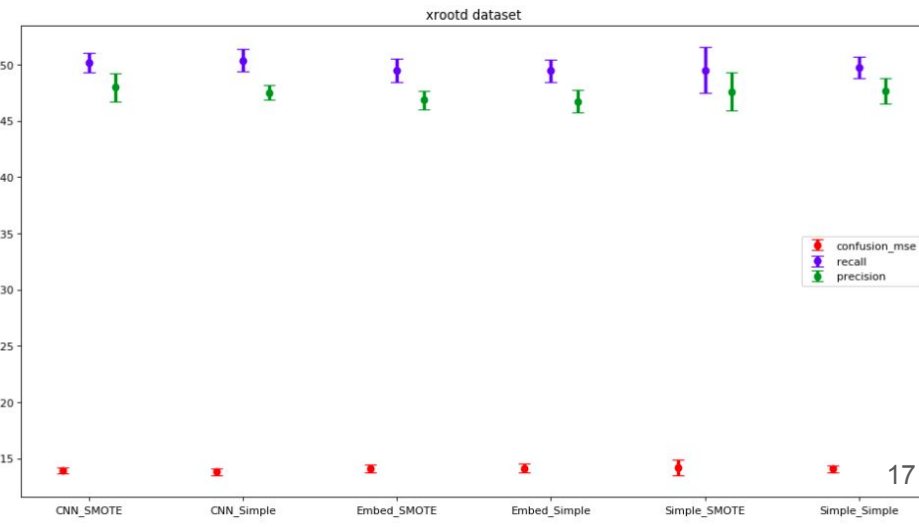
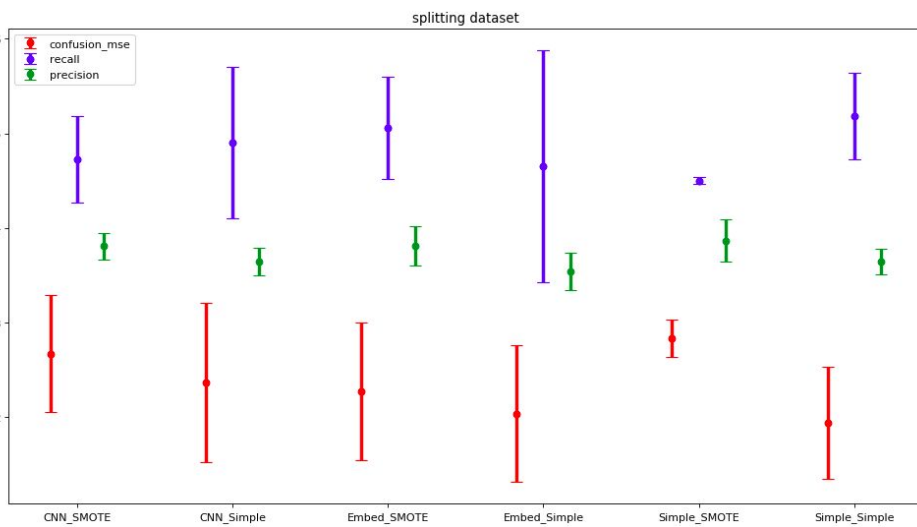
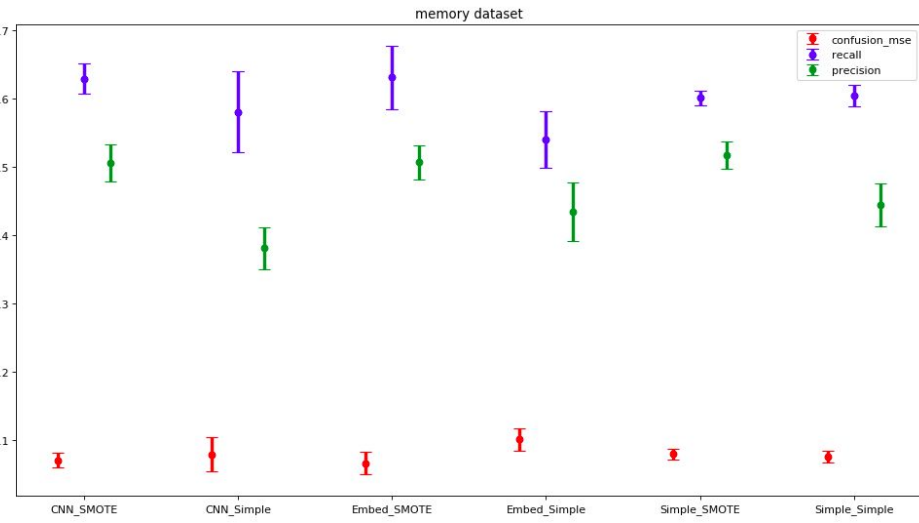
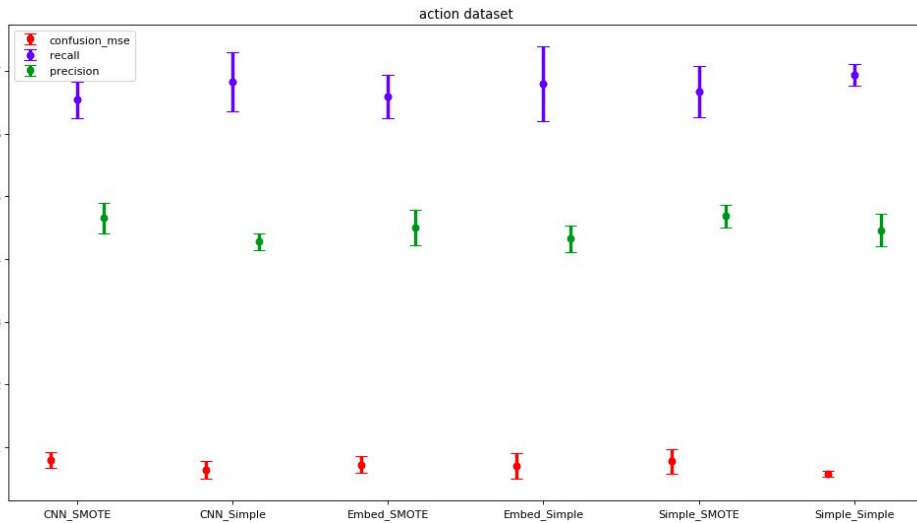
\*\* - Models that were looked at were: Total of  $3 \times 4 = 12$  Models

- Simple, CNN, Embedding with different methods:
  - trained using SMOTE resampling
  - trained with Attention
  - trained using both
  - trained with no SMOTE resampling and no Attention

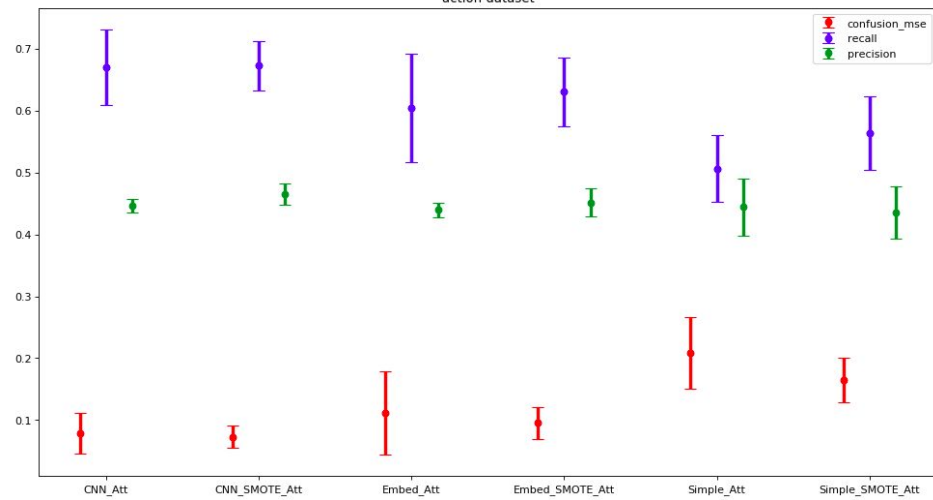
Used Early Stopping Parameters:

- patience = 7
- maximum percentage delta = 30%
- moving average length = 2

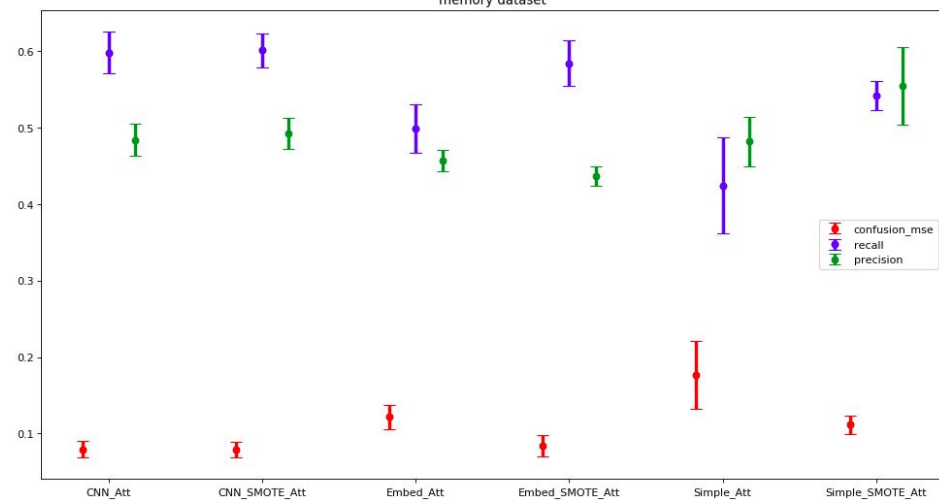




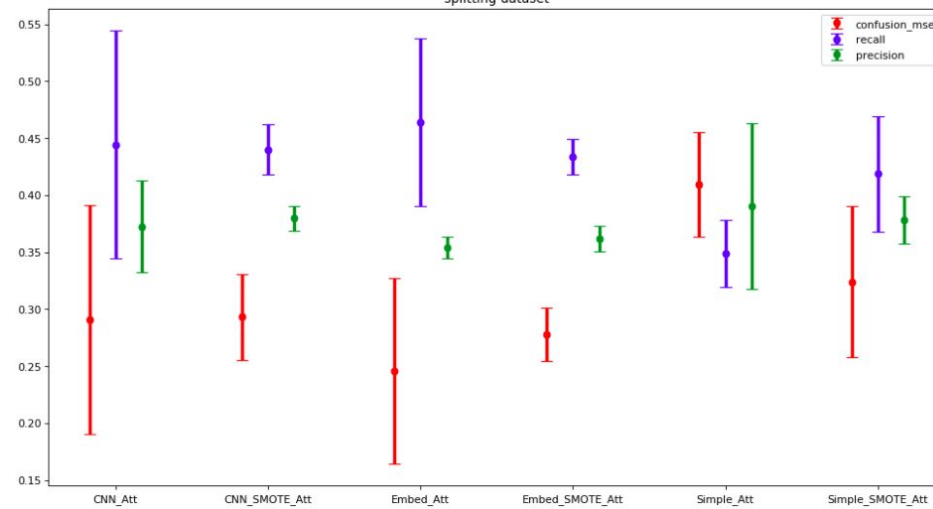
action dataset



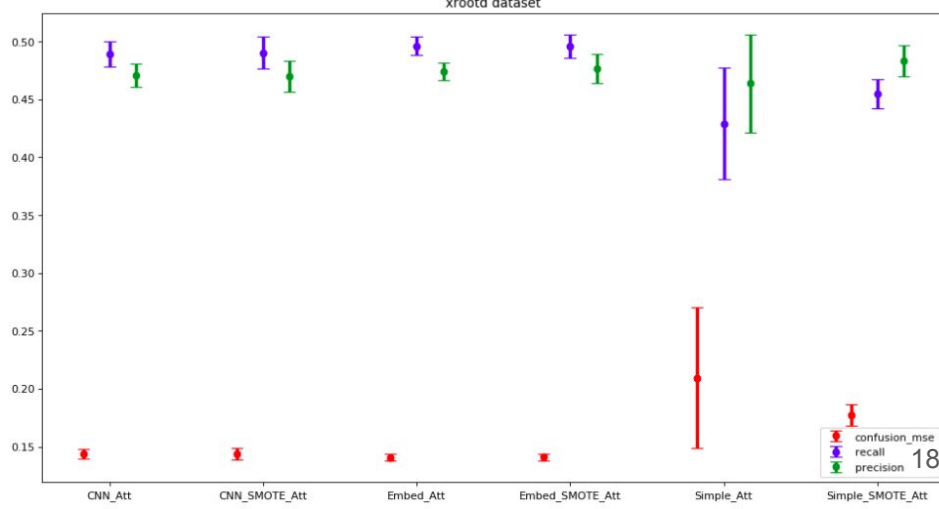
memory dataset



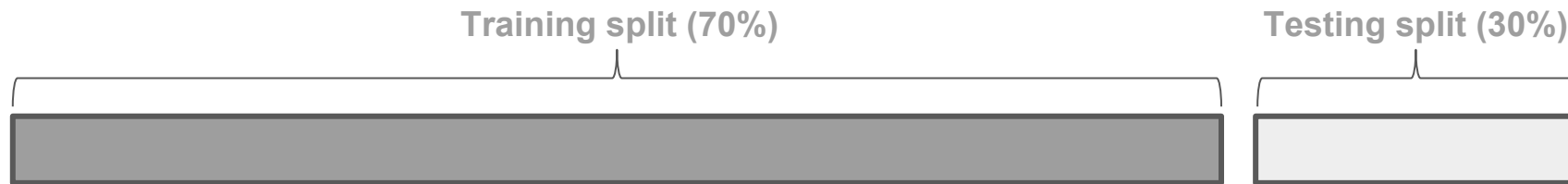
splitting dataset



xrootd dataset



# Testing Models



- Splitting\* dataset into testing and training datasets
- For 5 times:
  - Train chosen model on training dataset
  - Get all metrics results with this model on testing dataset
- Average each results into mean and std of each metric

\* - numpy seed = 42

# Best Model Results on Test Set

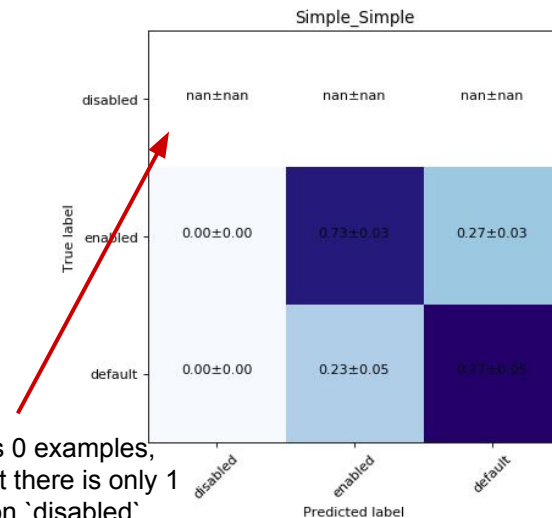
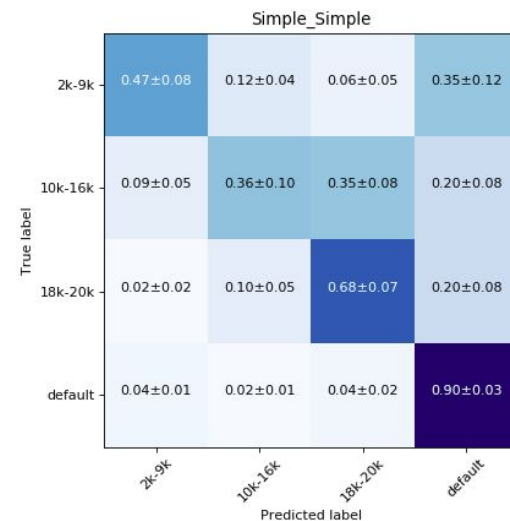
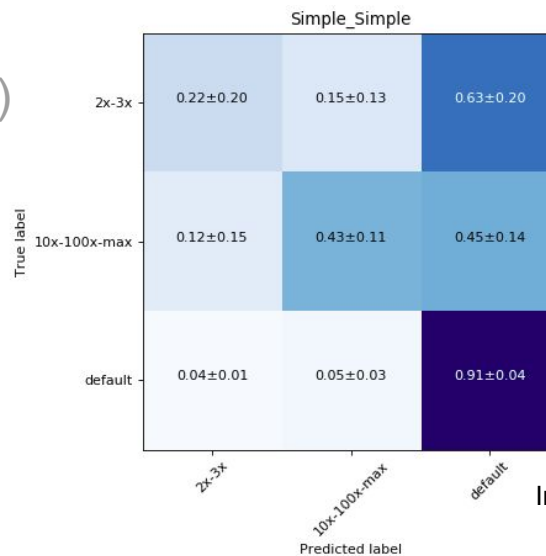
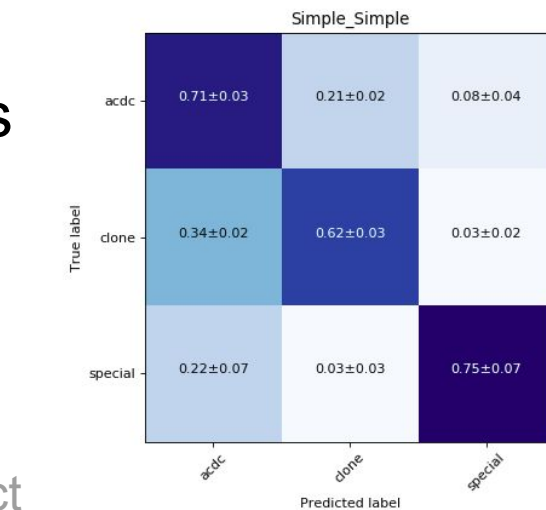
Best model - Simple\_Simple

Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	simple	-	-	.0576 ± .0068	.691 ± .017	.447 ± .005
memory	simple	-	-	.0873 ± .0160	.582 ± .028	.450 ± .022
splitting	simple	-	-	.2112 ± .0321	.482 ± .028	.366 ± .008
xrootd	simple	-	-	.1456 ± .0027	.497 ± .009	.476 ± .011

# Best Model Results on Test Set

Note: model always prioritizes on bigger classes except in `action` target: it is easier to predict special (138 examples) then clone (934 examples)

Y targets:  
action - top left  
memory - top right  
splitting - bottom left  
xrootd - bottom right



There was 0 examples,  
In all dataset there is only 1  
sample on `disabled`

# Bonus Slides

- Other Results ( Best of SMOTE, Attention, XGBoost)
- SMOTE vs weighted cross entropy (Metric evolution plots)
- Best of Attention and no Attention (confusion matrices)

# Other Results

Following slides show:

- Results using SMOTE resampling (results and confusion matrices)
- Results using Attention (results and confusion matrices)
- XGBoost model results (results)

# SMOTE Results

Best model - Simple\_SMOTE

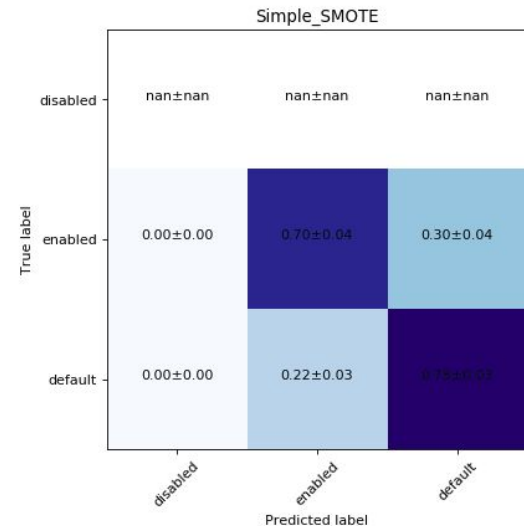
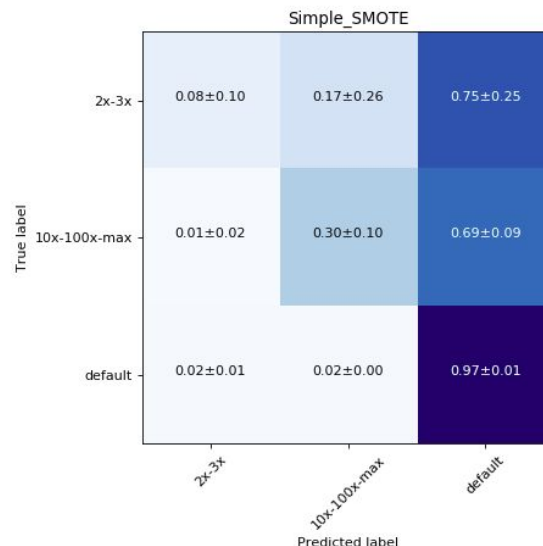
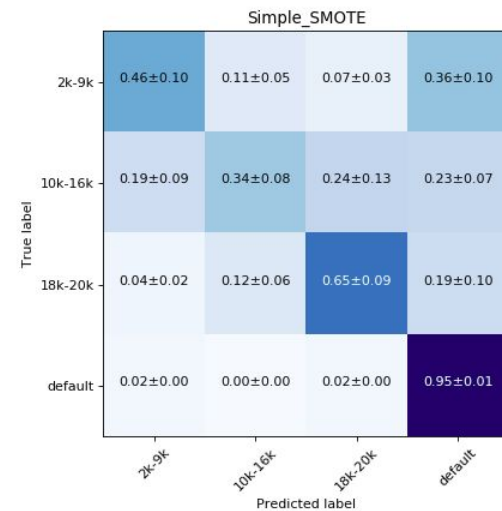
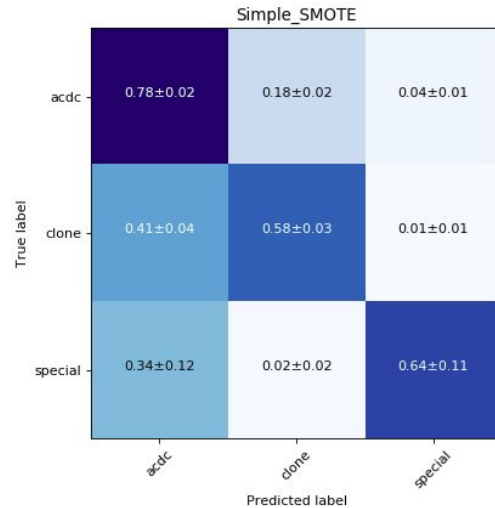
Gets higher precision then without SMOTE, but recall and conf mse are worse

Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	simple	+	-	.0780 ± .0195	.666 ± .040	.468 ± .018
memory	simple	+	-	.0759 ± .0073	.611 ± .011	.515 ± .019
splitting	simple	+	-	.2834 ± .0200	.449 ± .003	.386 ± .022
xrootd	simple	+	-	.1417 ± .0070	.495 ± .020	.475 ± .017

everything is trained with early stopping on confusion mse  
with patience = 10, maximum percentage delta = 30%, moving average length = 2



# SMOTE Results



Y targets:  
 action - top left  
 memory - top right  
 splitting - bottom left  
 xrootd - bottom right

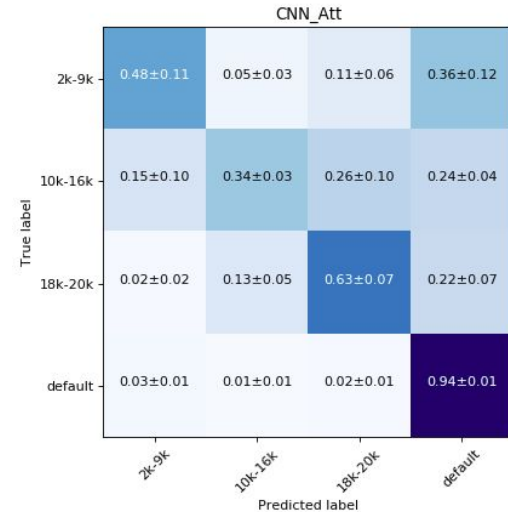
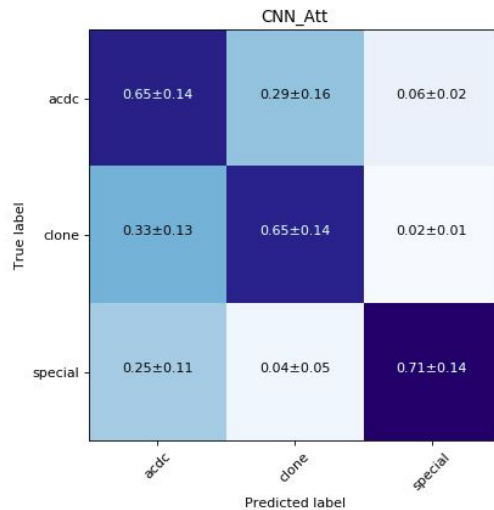
# Attention Results

Best model - CNN\_Att

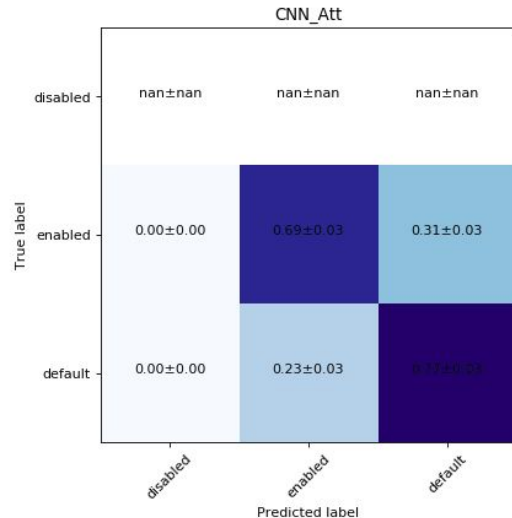
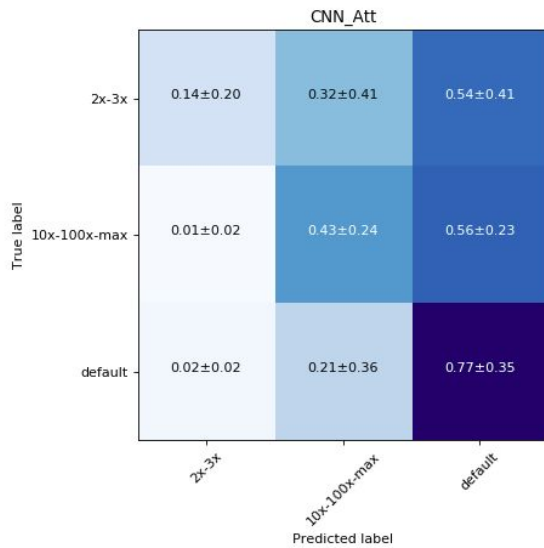
Still most metrics are worse in comparison with models without Attention

Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	cnn	-	+	.0690 ± .0159	.684 ± .016	.445 ± .022
memory	cnn	-	+	.0985 ± .074	.567 ± .027	.474 ± .021
splitting	cnn	-	+	.2907 ± .1007	.395 ± .100	.321 ± .040
xrootd	cnn	-	+	.1437 ± .0039	.489 ± .010	.470 ± .010

# Best model with Attention (confusion matrices)



Y targets:  
action - top left  
memory - top right  
splitting - bottom left  
xrootd - bottom right



# XGBoost Results

When training with max depth 4 all metrics are worse

Dataset	SMOTE	conf mse	recall	precision
action	-	.308	.443	.754
action	+	.095	.633	.456
memory	-	.129	.536	.751
memory	+	.090	.593	.594
splitting	-	.395	.362	.528
splitting	+	.384	.368	.371
xrootd	-	.291	.459	.508
xrootd	+	.252	.507	.507

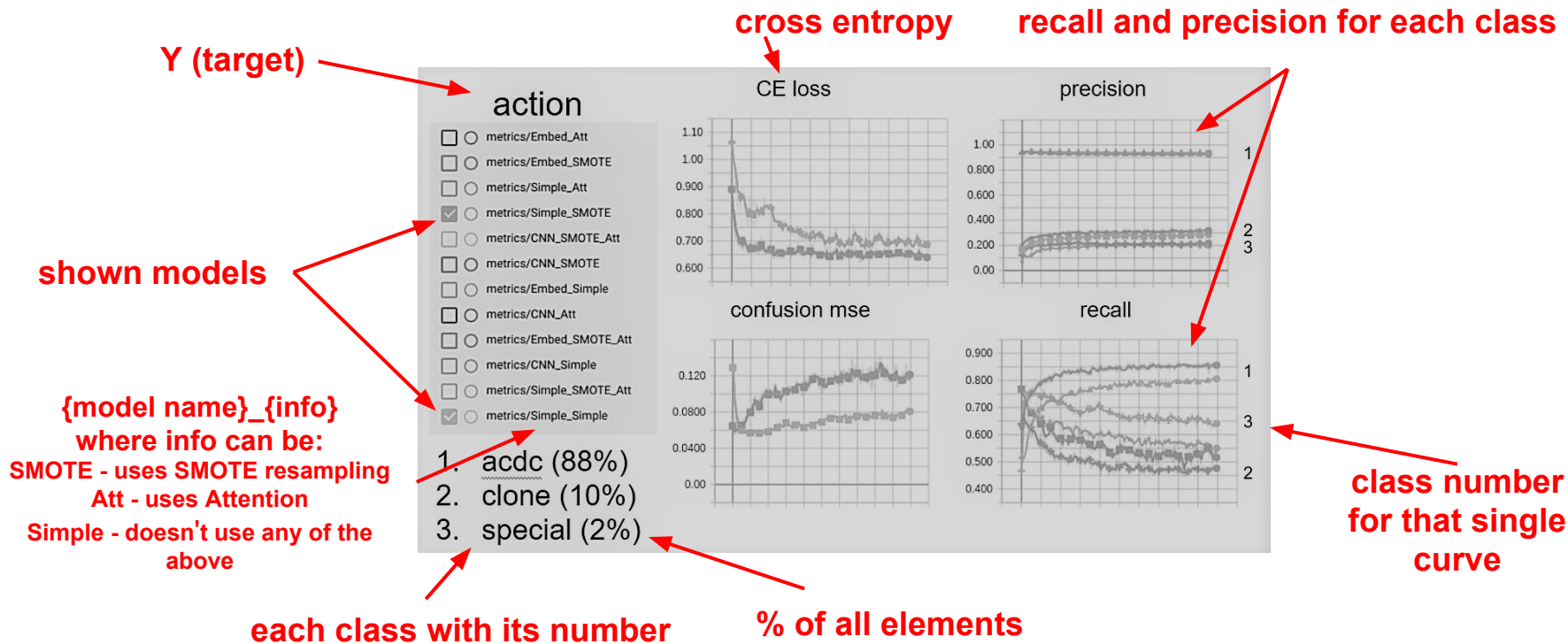
everything is trained with early stopping on confusion mse with patience = 10

# SMOTE vs weighted cross entropy

Following slides show: Metrics evolution on different Models over 200 epochs

Each dataset has 3 slides for models: (Simple, CNN, Embedding)

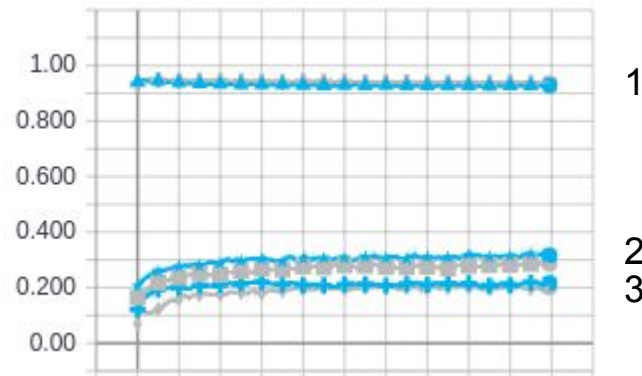
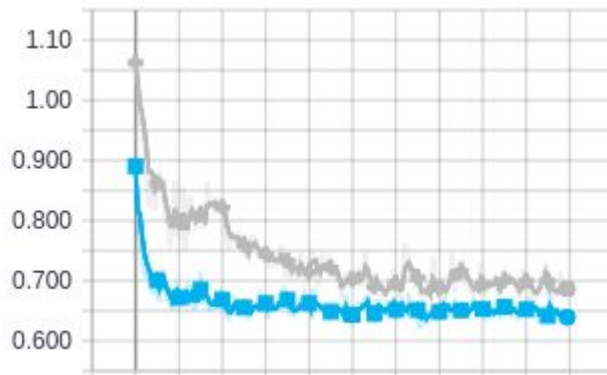
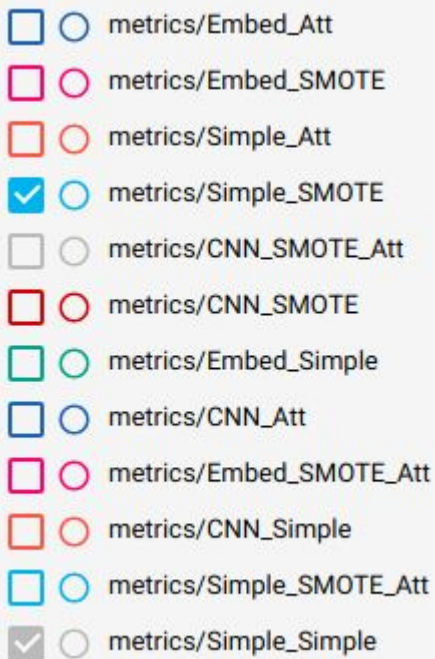
Single slide has evolution of metrics for model using and not using SMOTE resampling



# action

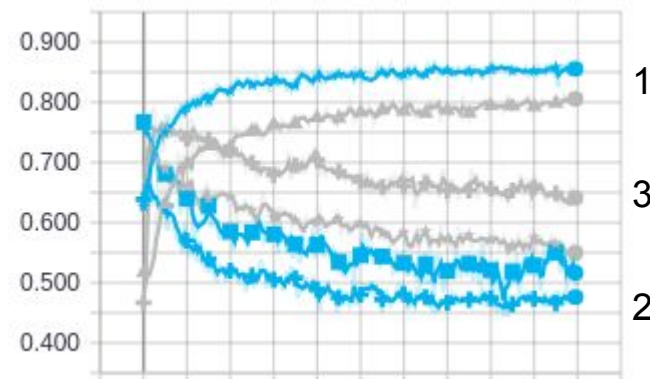
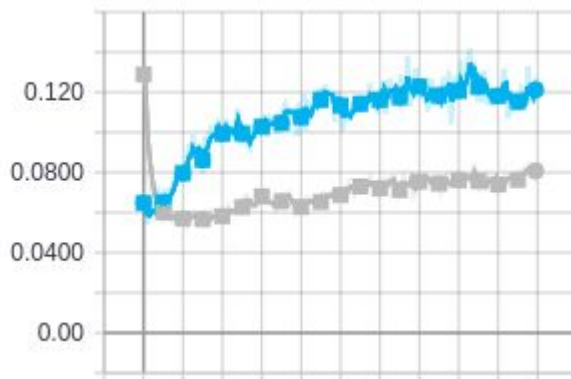
## CE loss

## precision



## confusion mse

## recall

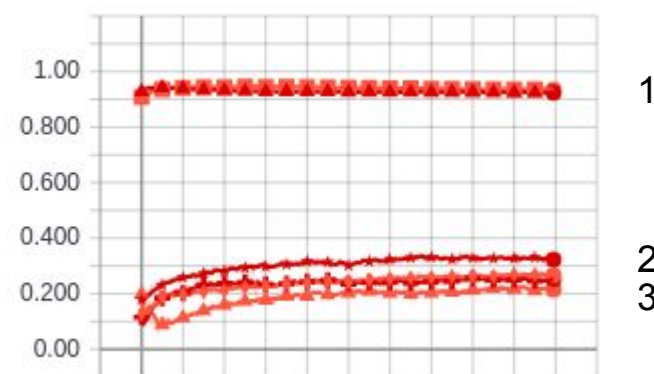
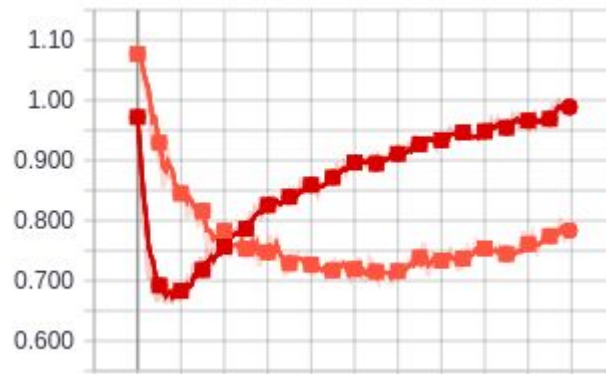
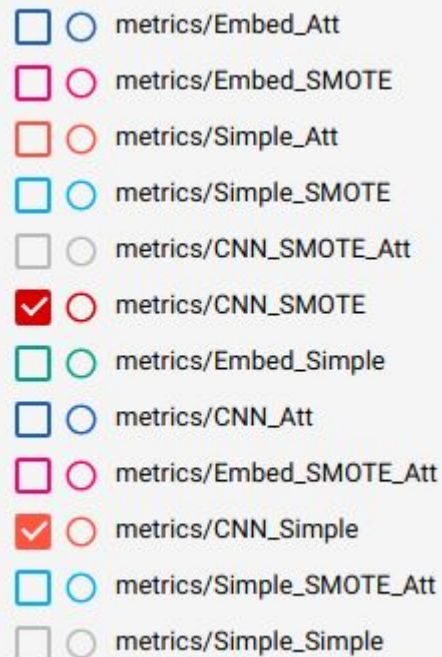


1. acdc (88%)
2. clone (10%)
3. special (2%)

# action

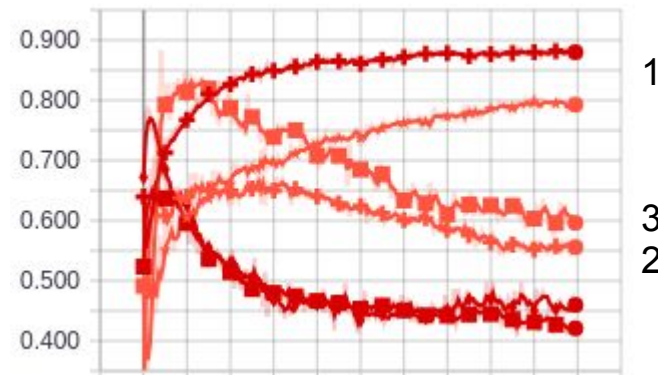
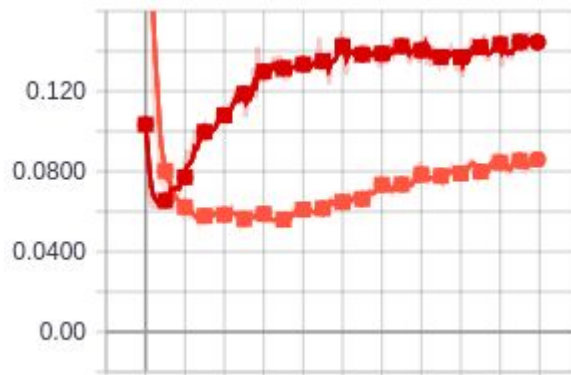
## CE loss

## precision



## confusion mse

## recall



1. acdc (88%)
2. clone (10%)
3. special (2%)

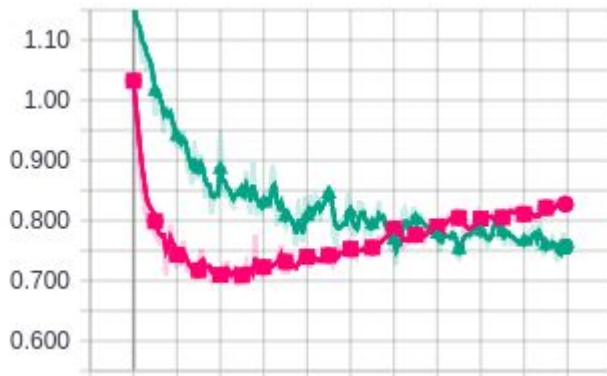


# action

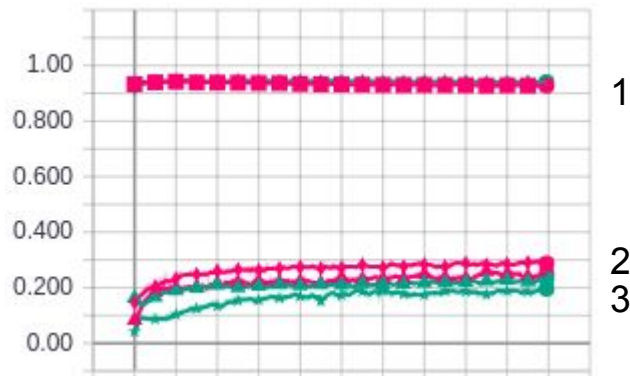
- ☐ ☐ metrics/Embed\_Att
- ☒ ☐ metrics/Embed\_SMOTE
- ☐ ☐ metrics/Simple\_Att
- ☐ ☐ metrics/Simple\_SMOTE
- ☐ ☐ metrics/CNN\_SMOTE\_Att
- ☐ ☐ metrics/CNN\_SMOTE
- ☒ ☐ metrics/Embed\_Simple
- ☐ ☐ metrics/CNN\_Att
- ☐ ☐ metrics/Embed\_SMOTE\_Att
- ☐ ☐ metrics/CNN\_Simple
- ☐ ☐ metrics/Simple\_SMOTE\_Att
- ☐ ☐ metrics/Simple\_Simple

1. acdc (88%)
2. clone (10%)
3. special (2%)

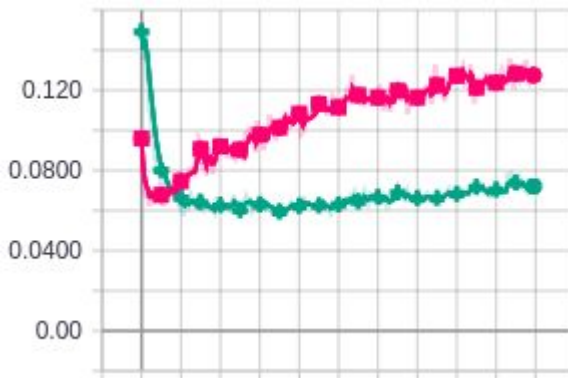
CE loss



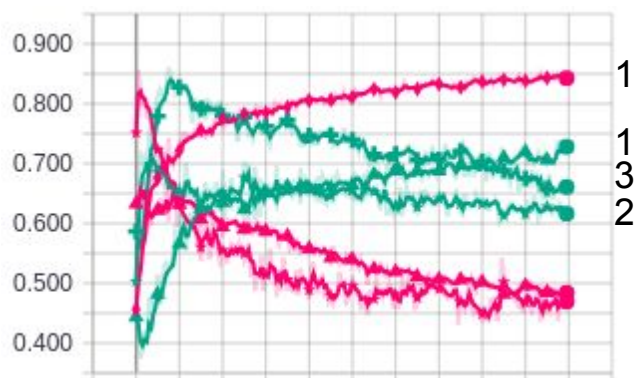
precision



confusion mse

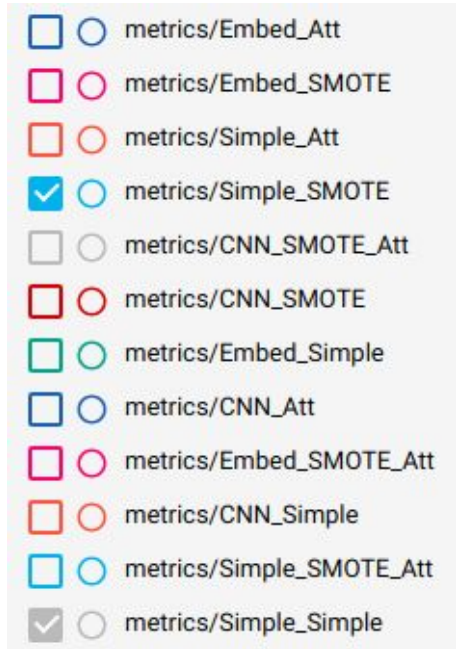


recall

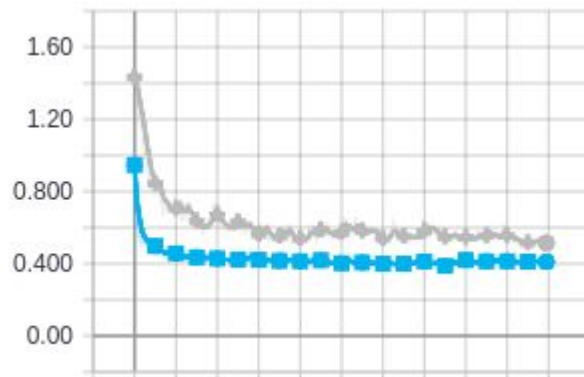




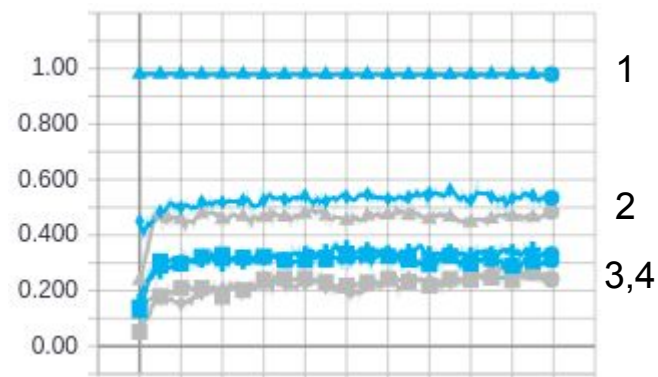
# memory



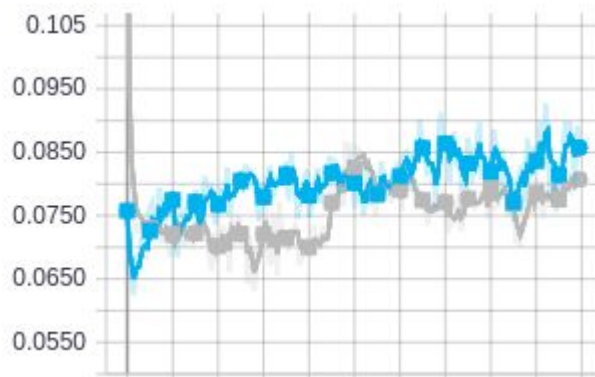
CE loss



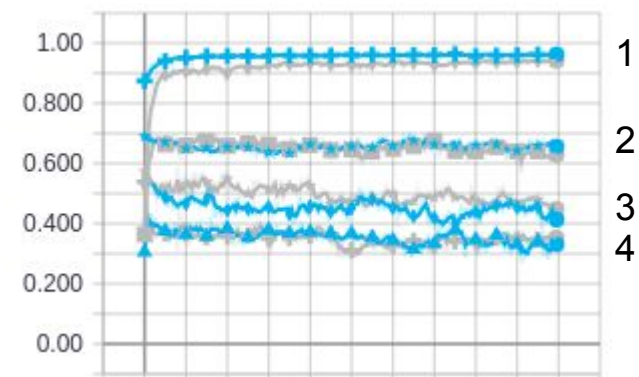
precision



confusion mse

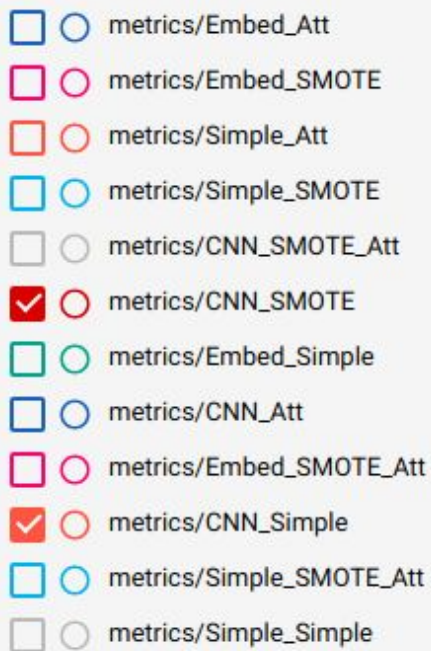


recall



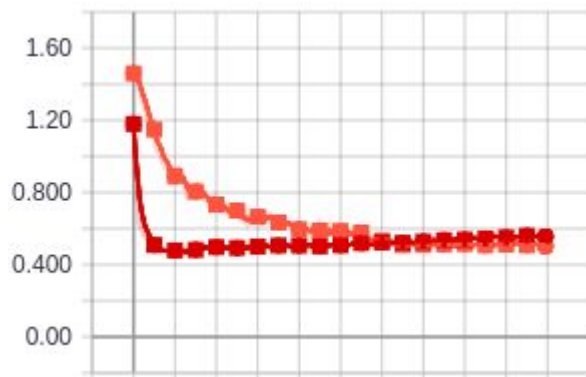
1. default (92%)
2. 18k-20k (4%)
3. 2k-9k (2%)
4. 10k-16k (1.2%)

# memory

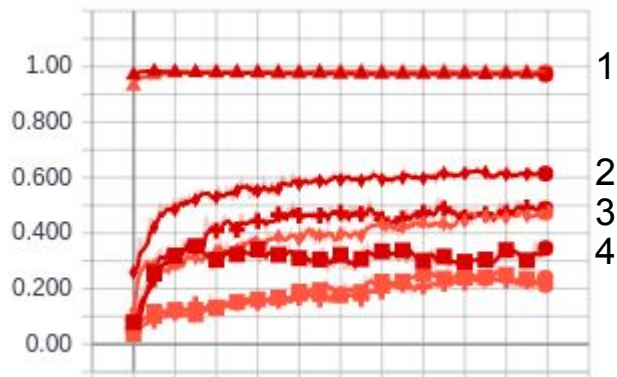


1. default (92%)
2. 18k-20k (4%)
3. 2k-9k (2%)
4. 10k-16k (1.2%)

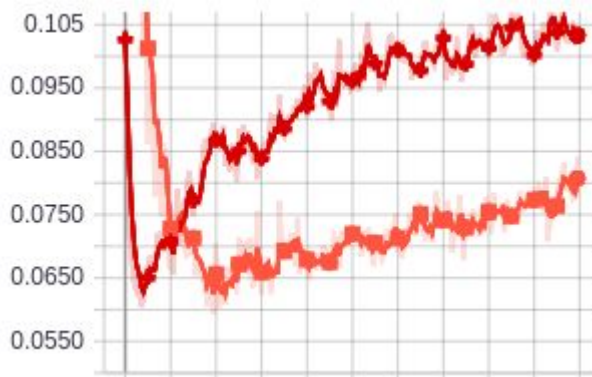
CE loss



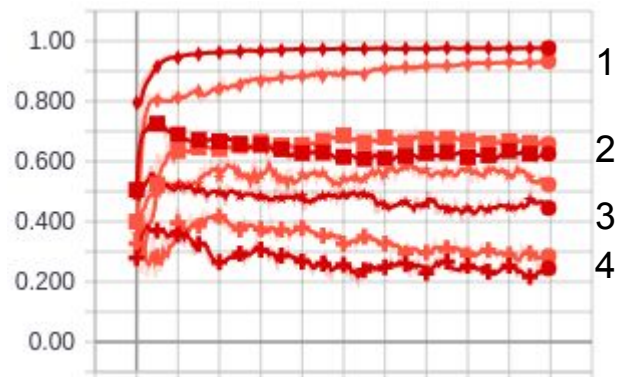
precision



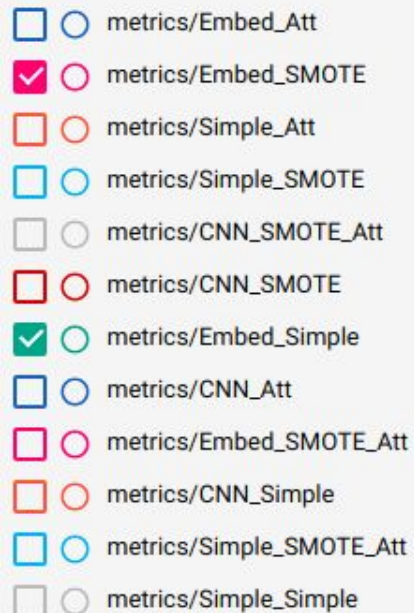
confusion mse



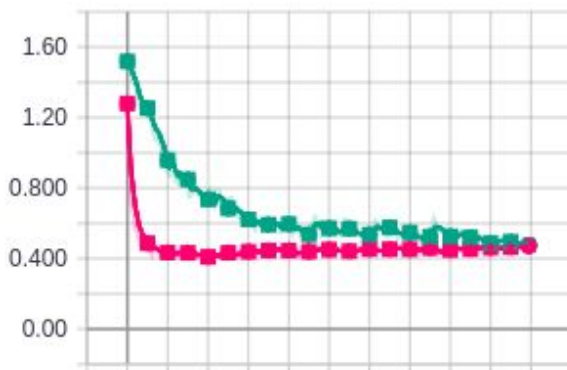
recall



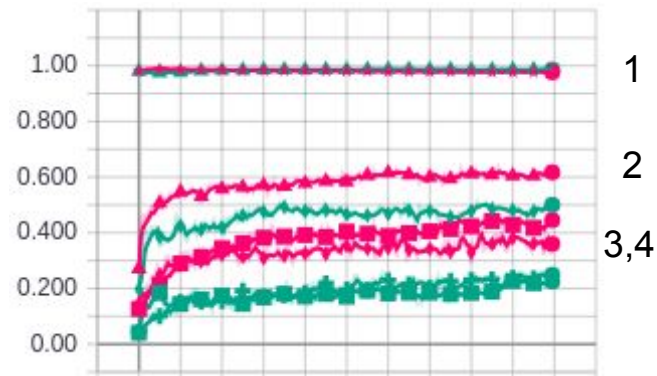
# memory



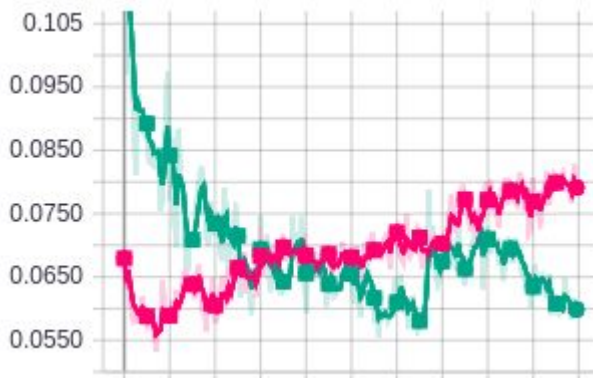
## CE loss



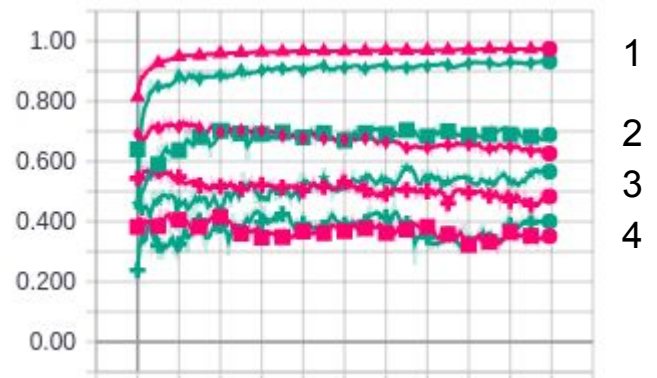
## precision



## confusion mse



## recall



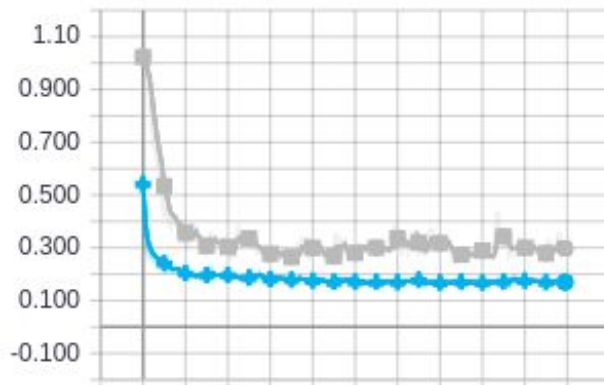
1. default (92%)
2. 18k-20k (4%)
3. 2k-9k (2%)
4. 10k-16k (1.2%)



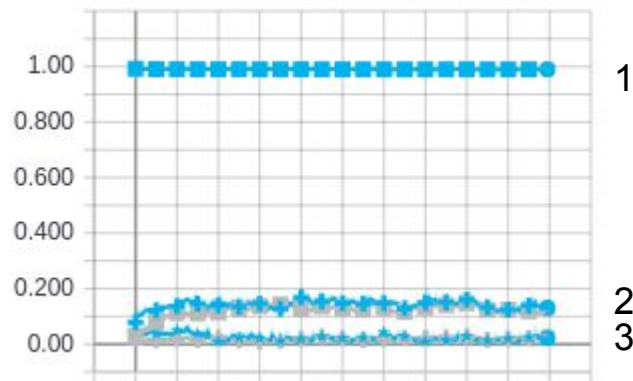
# splitting

- ☐ ☐ metrics/Embed\_Att
- ☐ ☐ metrics/Embed\_SMOTE
- ☐ ☐ metrics/Simple\_Att
- ☒ ☐ metrics/Simple\_SMOTE
- ☐ ☐ metrics/CNN\_SMOTE\_Att
- ☐ ☐ metrics/CNN\_SMOTE
- ☐ ☐ metrics/Embed\_Simple
- ☐ ☐ metrics/CNN\_Att
- ☐ ☐ metrics/Embed\_SMOTE\_Att
- ☐ ☐ metrics/CNN\_Simple
- ☐ ☐ metrics/Simple\_SMOTE\_Att
- ☒ ☐ metrics/Simple\_Simple

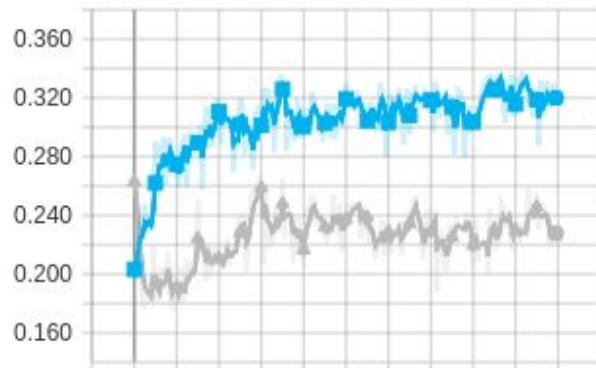
CE loss



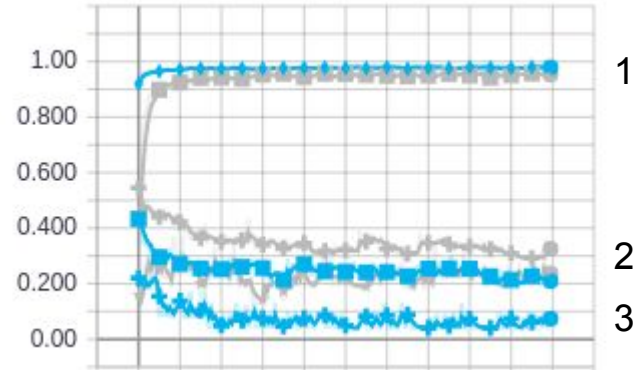
precision



confusion mse



recall



1. default (98%)
2. 10x-100x (1%)
3. 2x-3x (0.4%)

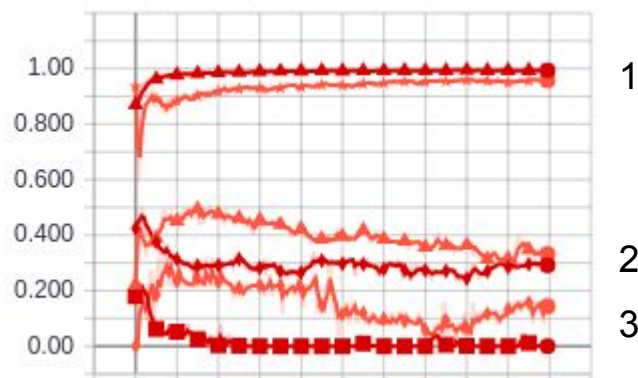
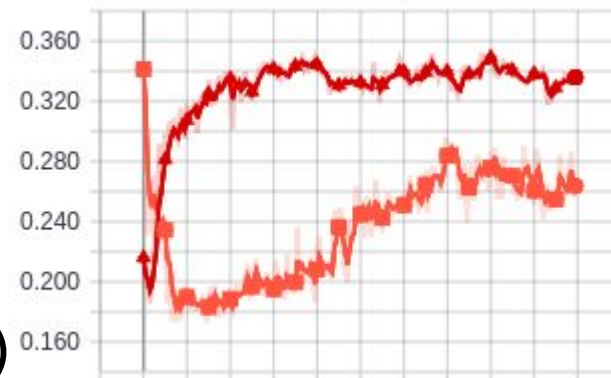
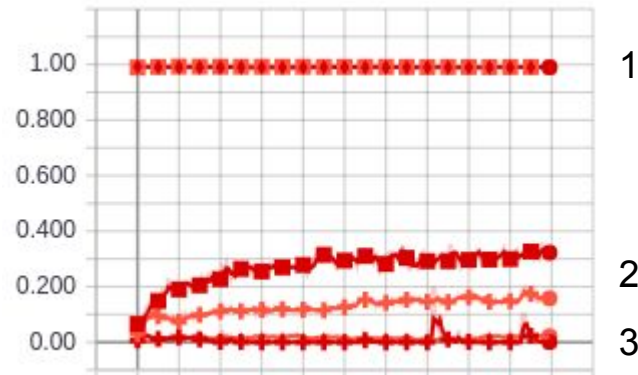
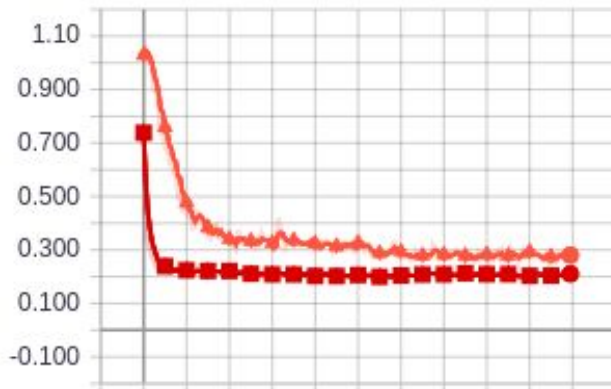
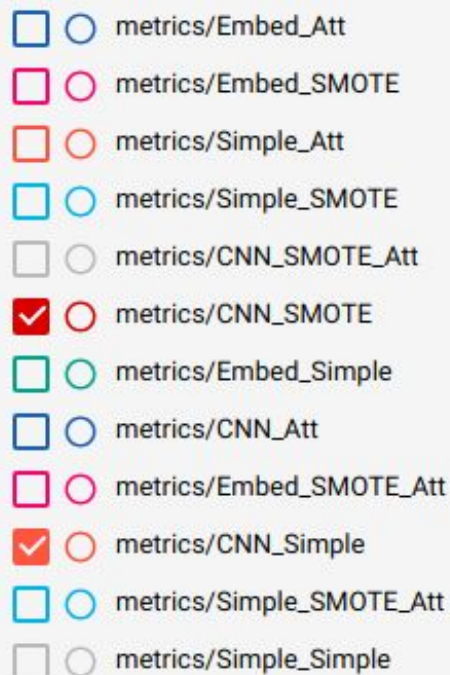
# splitting

## CE loss

## precision

## confusion mse

## recall

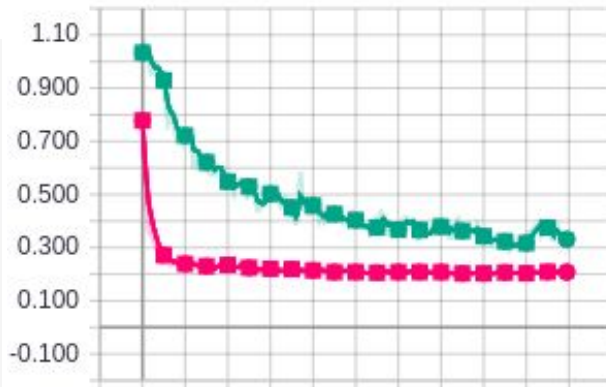


1. default (98%)
2. 10x-100x (1%)
3. 2x-3x (0.4%)

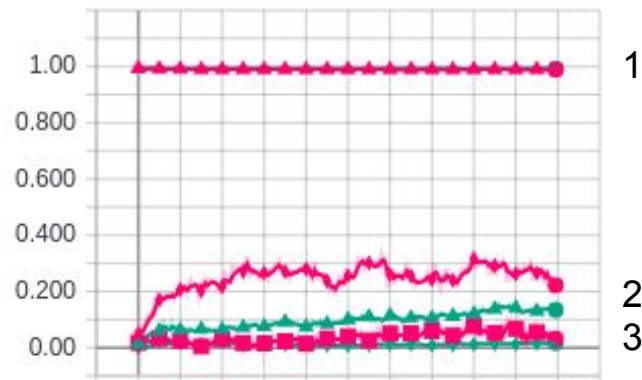
# splitting

- ☐ metrics/Embed\_Att
- ☒ metrics/Embed\_SMOTE
- ☐ metrics/Simple\_Att
- ☐ metrics/Simple\_SMOTE
- ☐ metrics/CNN\_SMOTE\_Att
- ☐ metrics/CNN\_SMOTE
- ☒ metrics/Embed\_Simple
- ☐ metrics/CNN\_Att
- ☐ metrics/Embed\_SMOTE\_Att
- ☐ metrics/CNN\_Simple
- ☐ metrics/Simple\_SMOTE\_Att
- ☐ metrics/Simple\_Simple

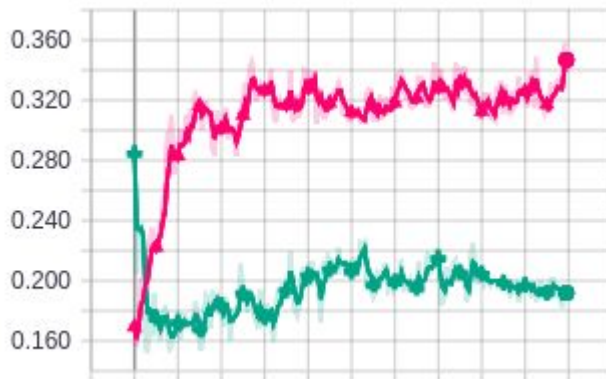
CE loss



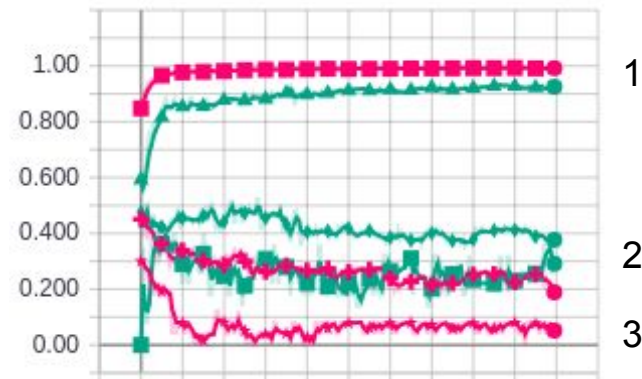
precision



confusion mse



recall



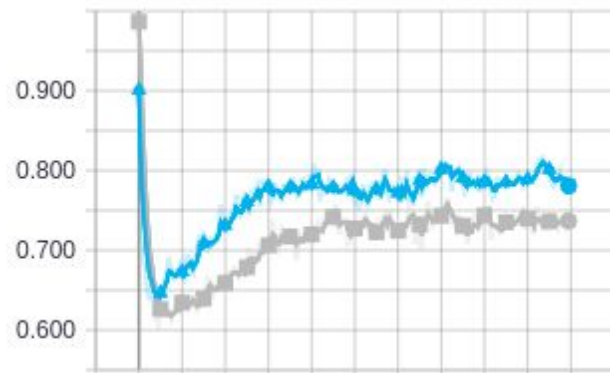
1. default (98%)
2. 10x-100x (1%)
3. 2x-3x (0.4%)

# xrootd

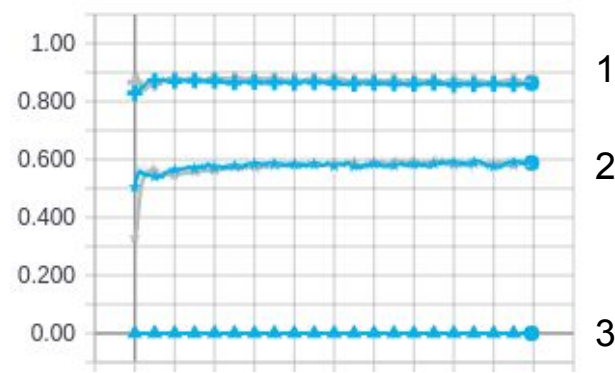
- ☐ metrics/Embed\_Att
- ☐ metrics/Embed\_SMOTE
- ☐ metrics/Simple\_Att
- ☒ metrics/Simple\_SMOTE
- ☐ metrics/CNN\_SMOTE\_Att
- ☐ metrics/CNN\_SMOTE
- ☐ metrics/Embed\_Simple
- ☐ metrics/CNN\_Att
- ☐ metrics/Embed\_SMOTE\_Att
- ☐ metrics/CNN\_Simple
- ☐ metrics/Simple\_SMOTE\_Att
- ☒ metrics/Simple\_Simple

1. default (72%)
2. enabled (28%)
3. disabled (0.01%)

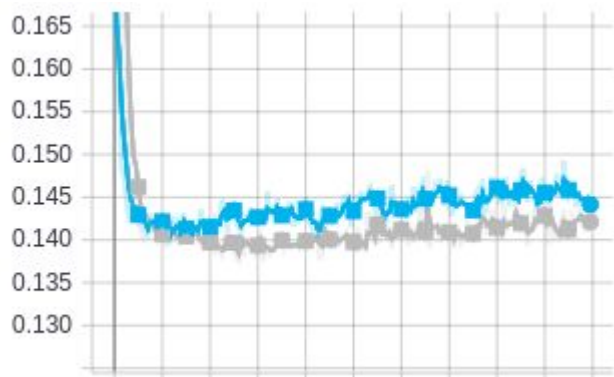
CE loss



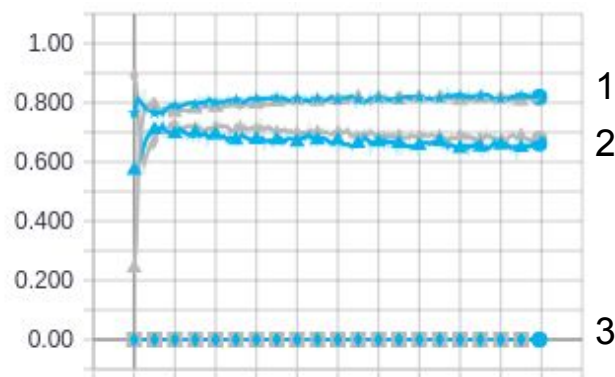
precision



confusion mse



recall



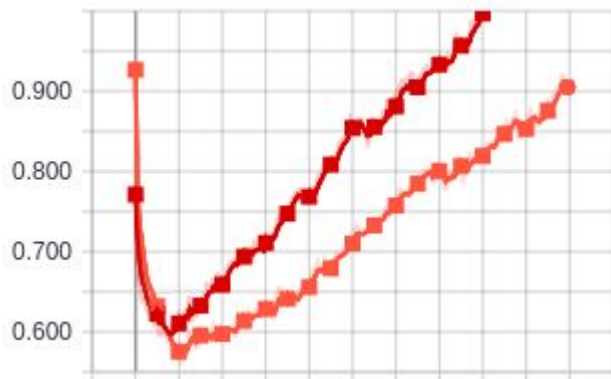


# xrootd

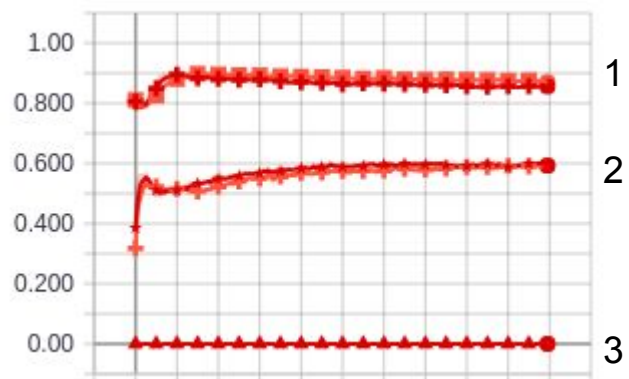
- metrics/Embed\_Att
- metrics/Embed\_SMOTE
- metrics/Simple\_Att
- metrics/Simple\_SMOTE
- metrics/CNN\_SMOTE\_Att
- metrics/CNN\_SMOTE
- metrics/Embed\_Simple
- metrics/CNN\_Att
- metrics/Embed\_SMOTE\_Att
- metrics/CNN\_Simple
- metrics/Simple\_SMOTE\_Att
- metrics/Simple\_Simple

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2. enabled (28%)
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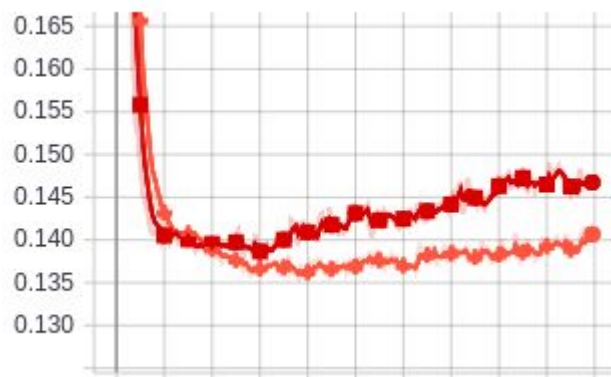
CE loss



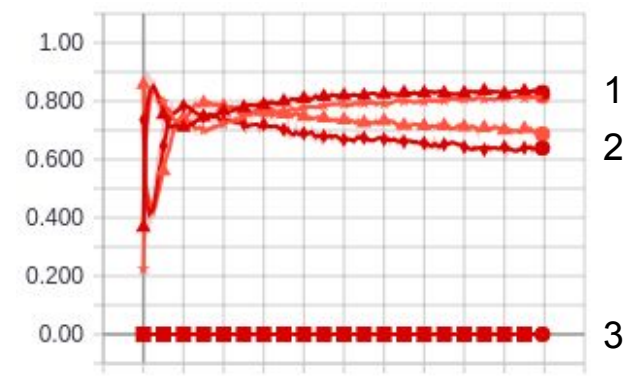
precision



confusion mse



recall



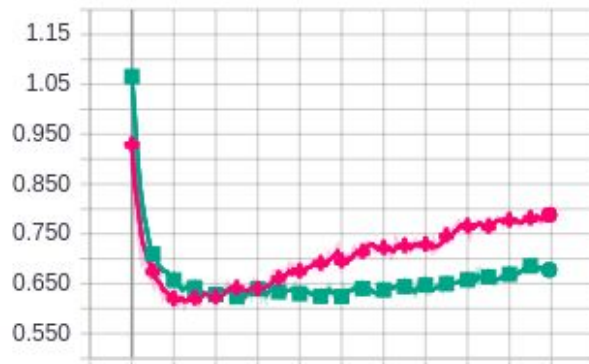


# xrootd

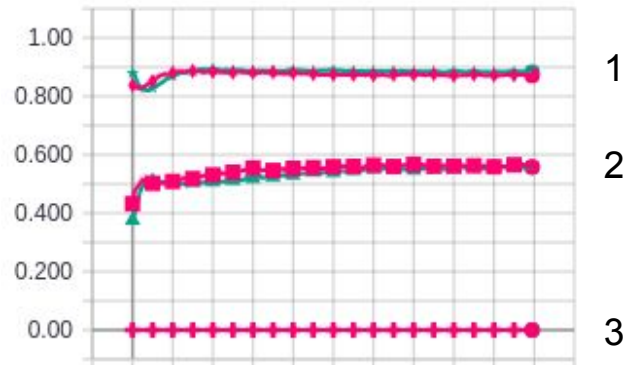
- metrics/Embed\_Att
- metrics/Embed\_SMOTE
- metrics/Simple\_Att
- metrics/Simple\_SMOTE
- metrics/CNN\_SMOTE\_Att
- metrics/CNN\_SMOTE
- metrics/Embed\_Simple
- metrics/CNN\_Att
- metrics/Embed\_SMOTE\_Att
- metrics/CNN\_Simple
- metrics/Simple\_SMOTE\_Att
- metrics/Simple\_Simple

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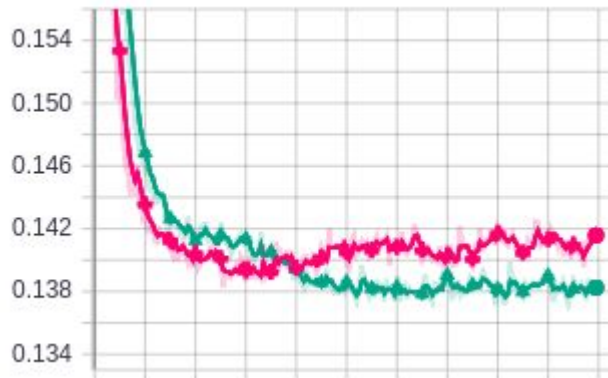
CE loss



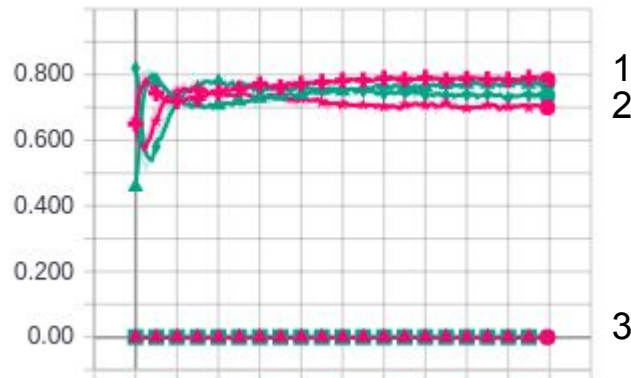
precision



confusion mse



recall



# Attention vs no Attention (confusion matrices)

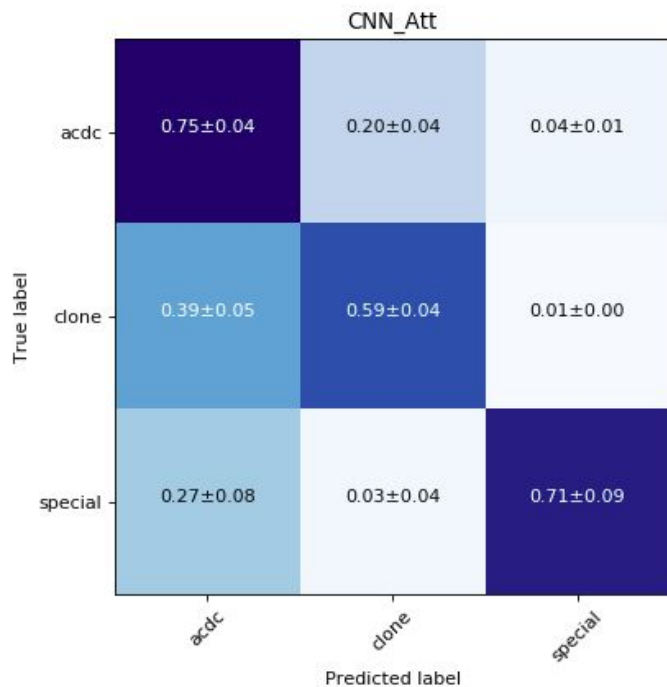
Following slides show:

- Best confusion matrix on each Y target on validation dataset (averaged across 5 folds) using Attention (left matrix) and comparison on right with model without using Attention

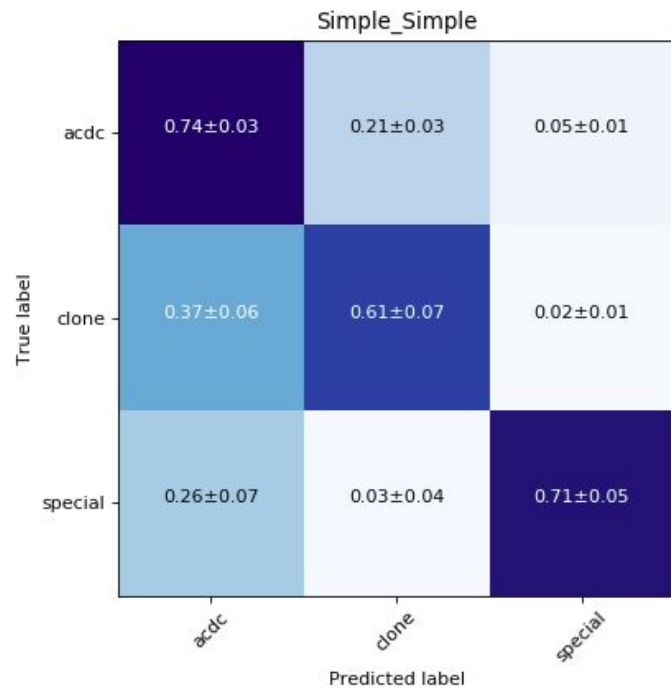
# action

1. acdc (88%)
2. clone (10%)
3. special (2%)

best: CNN model  
w/ weighted CE  
w/out SMOTE



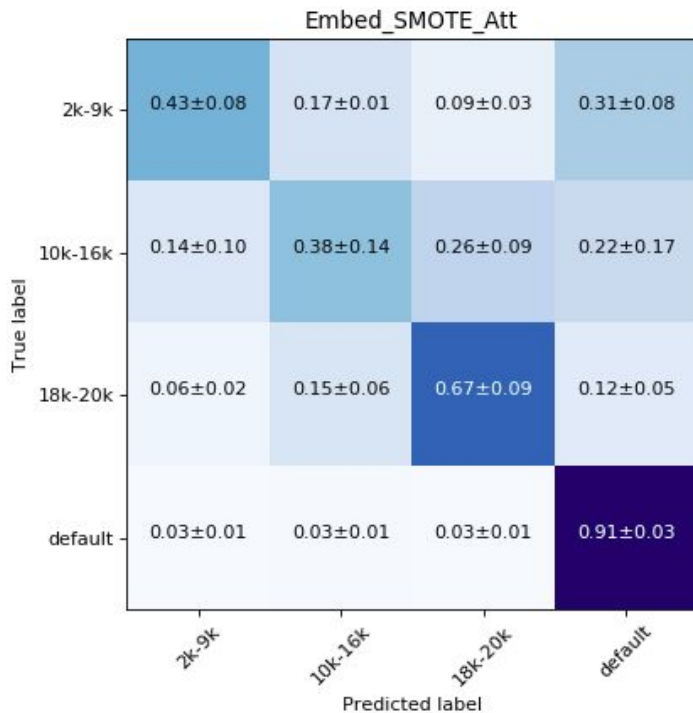
comparison w/ best model  
w/out Attention:  
Simple w/ weighted CE  
w/out SMOTE



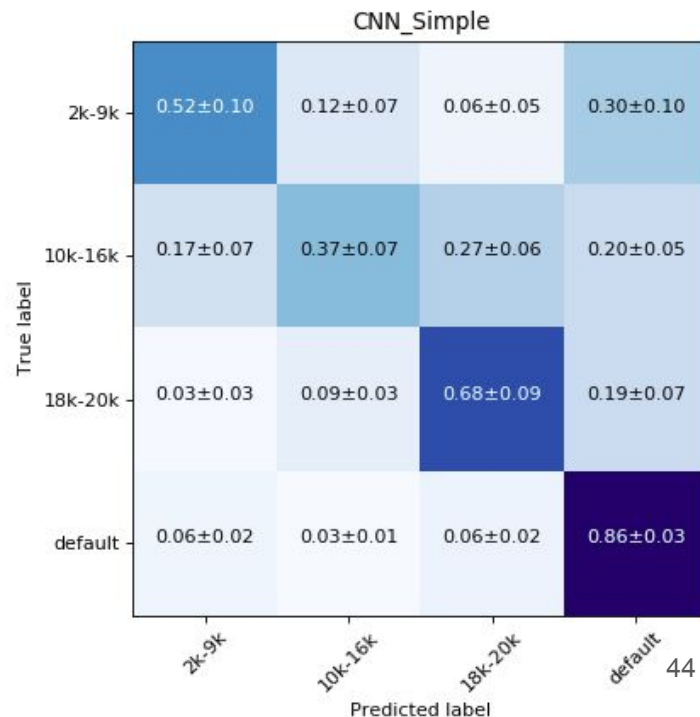
# memory

1. default (92%)
2. 18k-20k (4%)
3. 2k-9k (2%)
4. 10k-16k (1.2%)

best: Embed model  
w/ SMOTE



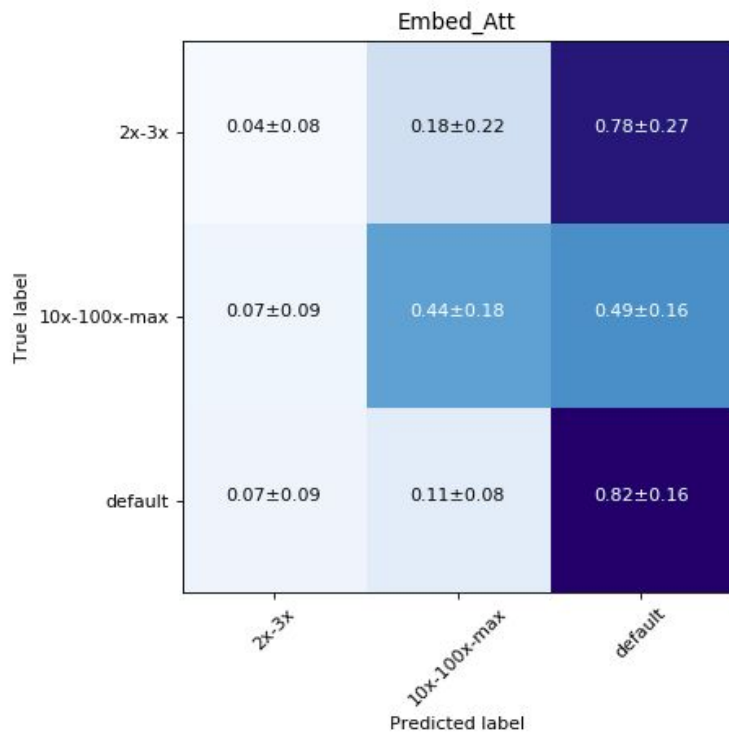
comparison w/ best model  
w/out Attention:  
CNN w/ weighted CE  
w/out SMOTE



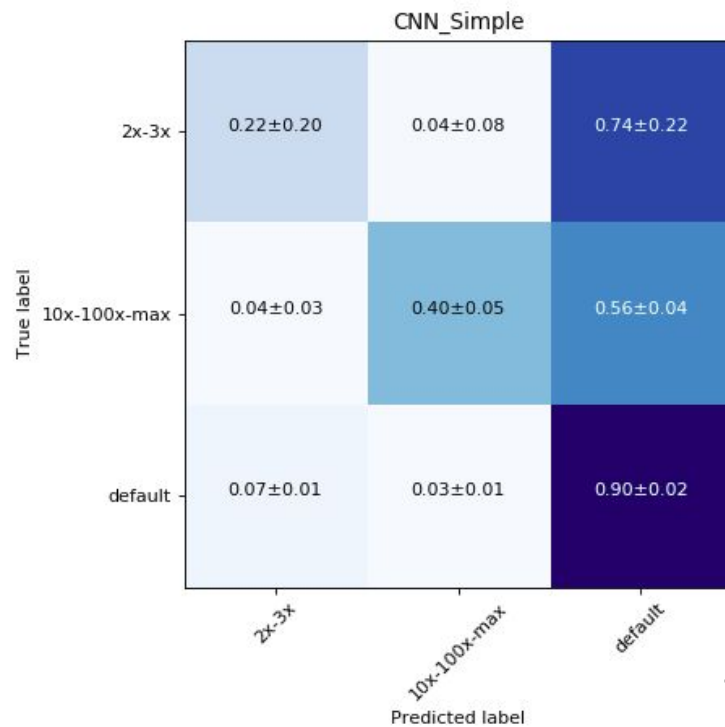
# splitting

1. default (98%)
2. 10x-100x (1%)
3. 2x-3x (0.4%)

best: Embed model  
w/ weighted CE  
w/out SMOTE



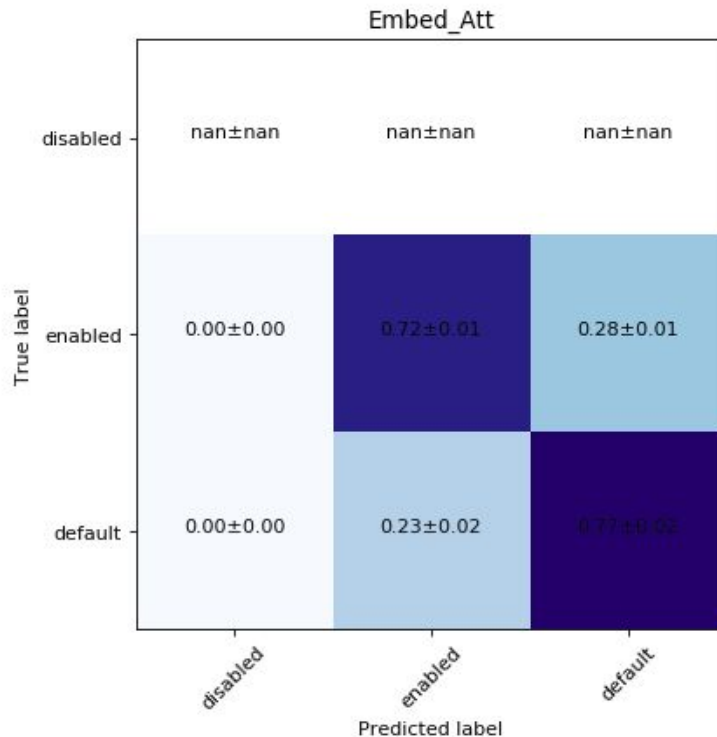
comparison w/ best model  
w/out Attention:  
CNN w/ weighted CE  
w/out SMOTE



# xrootd

1. default (72%)
2. enabled (28%)
3. disabled (0.01%)

best: Embed model  
w/ weighted CE  
w/out SMOTE



comparison w/ best model  
w/out Attention:  
CNN w/ weighted CE  
w/out SMOTE

