Operator Action Predictions

Dominykas Asauskas, Christian Contreras, Jean-Roch Vlimant

Short Introduction

- Common issues are errors in grid jobs, that may be due to missing/corrupt input files, high memory usage, etc.
- Currently all handled manually in Operations:
 - An operator must look at the error codes and decide on what appropriate actions to take on the workflow
- General Goal:
 - Deliver error handling predictions and mature towards moving manual operator intervention into automated actions

For more info look at Chrisians slides (slides 2-4):

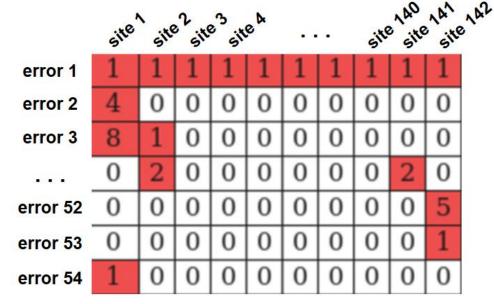
Short Introduction

Having errors that happened and where happened (at which site) predict (total examples = 9522):

- Which action to choose
- Requested memory
- Job splitting
- Enabling *xrootd* or not

Inputs / X

- Each example consists of matrix w/ shape (errors, sites)
- On average 99.75% of all numbers in matrix will be 0
- 66% out of all combinations (error x site) are never used (are always 0) in dataset with 9522 examples



single example shape = (54,142) total examples = 9522

For more stats which errors are most common or examples look at Chrisians slides 5-7:

Outputs / Y Targets

Action

- 1. acdc (88%)
- 2. clone (10%)
- 3. special (2%)

Splitting

- 1. 98.5% default
- 2. 0.59% 10x
- 3. 0.31% 2x
- 4. 0.19% max
- 5. 0.12% 100x
- 6. 0.09% 20x
- 7. 0.05% 3x
- 8. 0.03% 50x

Memory

1.	92.6% default	14.	0.03% 2k
2.	2.36% 20k	15.	0.03% 19k
3.	1.55% 18k	16.	0.03% 16k
4.	0.59% 12k	17.	0.02% 11k
5.	0.54% 4k	18.	0.01% 40k
6.	0.51% 9k	19.	0.01% 32k
7.	0.40% 6k	20.	0.01% 30k
8.	0.37% 10k	21.	0.01% 3k
9.	0.25% 5k	22.	0.01% 28k
10.	0.19% 8k	23.	0.01% 25k
11.	0.17% 14k	24.	0.01% 20k
12.	0.06% 7k	25.	0.01% 180k
13.	0.05% 15k	26.	0.01% 15k

Xrootd

- 1. default (72%)
- 2. enabled (28%)
- 3. disabled (0.01%)

Outputs / Y Targets (merged)

Action

- 1. acdc (88%)
- 2. clone (10%)
- 3. special (2%)

Memory

- 1. default (92%)
- 2. 18k-20k (4%)
- 3. 2k-9k (2%)
- 4. 10k-16k (1.2%)

Splitting

- 1. default (98.5%)
- 2. 10x-100x (1%)
- 3. 2x-3x (0.4%)

Xrootd

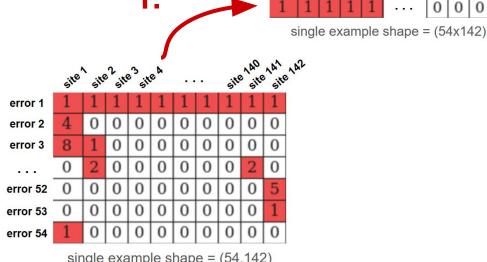
- 1. default (72%)
- 2. enabled (28%)
- 3. disabled (0.01%)

Models Ideas

- Because lack of examples, try to minimize model parameters (CNN Model)
- Change input so that model would generalize better (Create embeddings for each site and error)
- Try different ways of fighting class imbalance (SMOTE resampling, weighted cross entropy)
- Try to find a way to explain the output (by adding additional layers to network)
- Compare everything with simple feed forward network (Simple model)

Simple Model

- inputs are flatten
- fed to feed forward neural network
- everything is optimized with weighted cross entropy (wCE)



single example shape = (54.142)

ple shape = (54,142) Dense* (c** units)
$$J\left(heta
ight) = -\sum_{i}^{n}\left(W_{y_{i}}^{***}y_{i}\log\hat{y}_{i}
ight)$$

- All Dense layers are with 0.2 dropout w/ relu activations
- number of classes

*** _
$$W_{y_i} = rac{total\ examples}{\#\ classes} imes rac{1}{\#\ y_i\ examples}$$

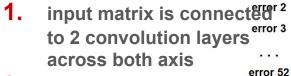
** when resampling (using SMOTE) all classes become same size, which results in W = 1 and loss = cross entropy_o

Dense* (50 units)

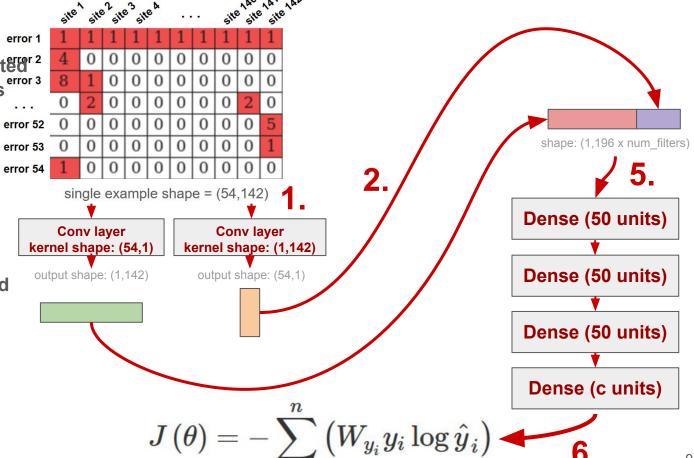
Dense* (50 units)

Dense* (50 units)

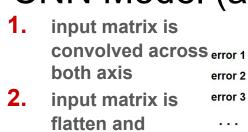
CNN Model



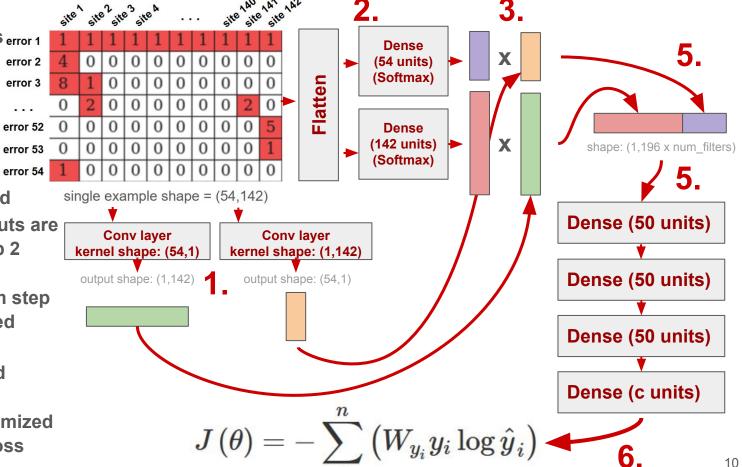
- 2. convolution layer outputs for each filter are concatenated
- 3. concat vector is connected to feed forward layers
- 4. everything is optimized with weighted cross entropy (wCE)



CNN Model (adding Attention)

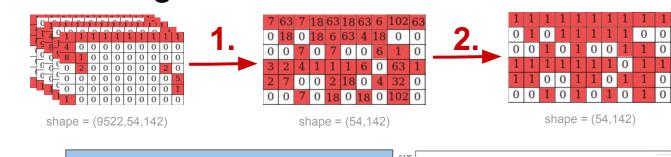


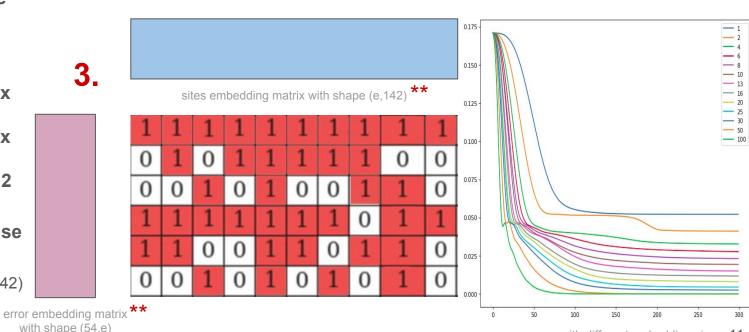
- 0 error 2 error 3 0 0 0 0 0 error 52 connected to 2 0 0 error 53 feed forward
- layers with softmax at the end
- 3. convolution outputs are multiplied by step 2 outputs
- both outputs from step 3 are concatenated
- **5**. concat vector is connected to feed forward layers
- **6**. everything is optimized with weighted cross entropy (wCE)

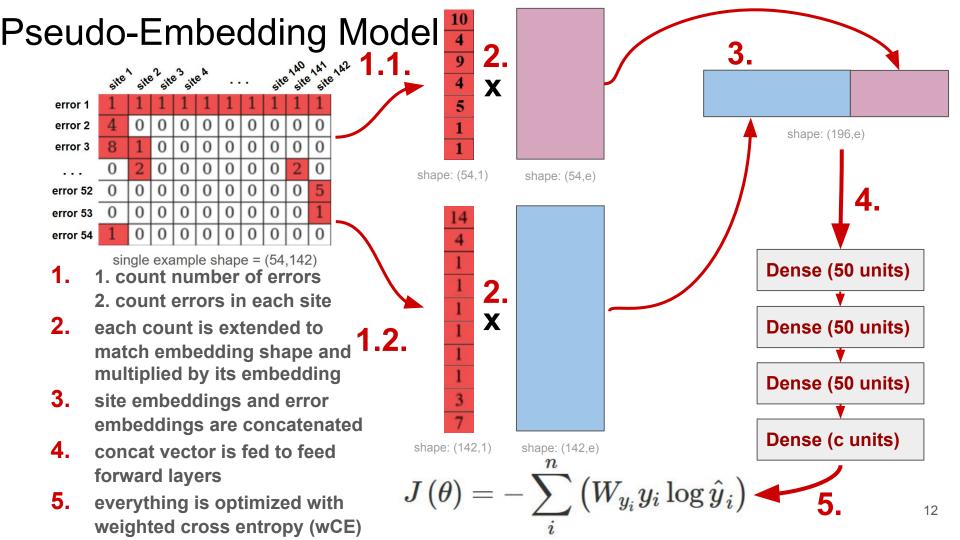


Error and Site embeddings

- 1. all examples are summed across axis 0
- 2. all numbers that are greater than 0 are replaced by 1
- 3. by doing dot product* of error embedding matrix times sites embedding matrix try to recreate matrix from step 2
- 4. everything is optimized with mse
- * (54,e) _• (e,142) = (54,142)
- ** e = 20



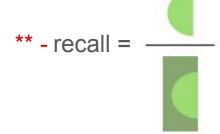


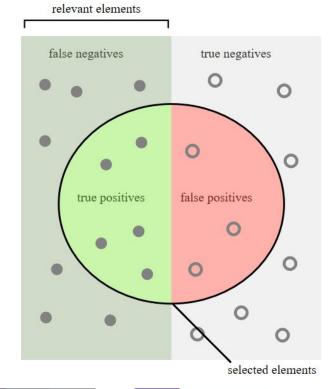


Evaluation Metrics

- Precision (for each class) *
 how many selected items are relevant?
- Recall (for each class) **
 How many relevant items are selected?
- Confusion MSE (main) ***
 Mean squared error of normalized
 confusion matrix and identity matrix

Macro average is calculated for Recall and Precision!

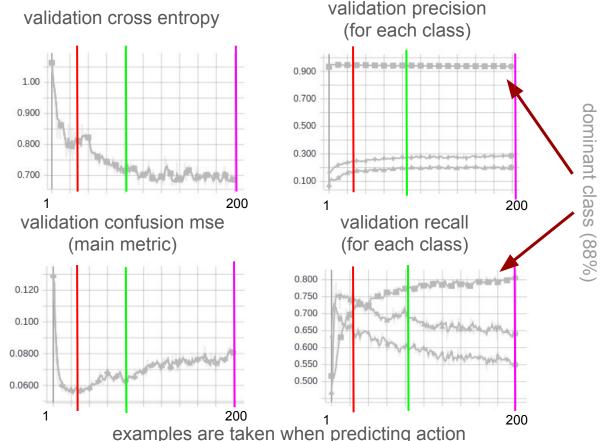






Optimal Stopping when Training

- Early stopping with single metric can lead training to stop too fast
- Looking at multiple metrics as equal can lead to stopping too late
- Optimal stopping point should be somewhere in between, that main metric doesn't deviate from best score and other metrics get better
 - too early stopping
 - optimal stopping
 - too late stopping



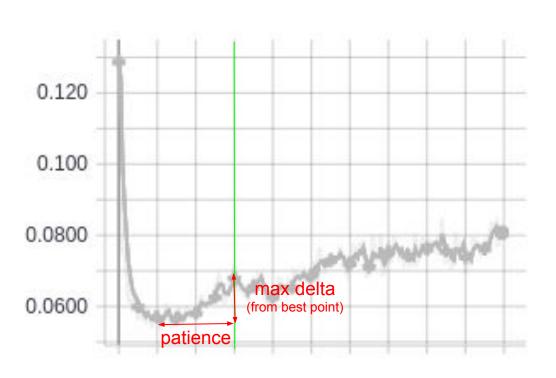
Multiple Metric Early Stopping

- At each epoch set best scores from all picked metrics
- If none of the metrics gets better in n* epoch then stop
- 3. If main score is worse compared to best score by T** then stop

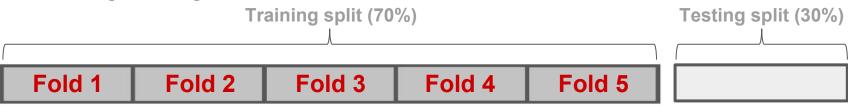


^{* -} n - patience

** - T - max delta, maximum allowed decrease of score from best score (in %)



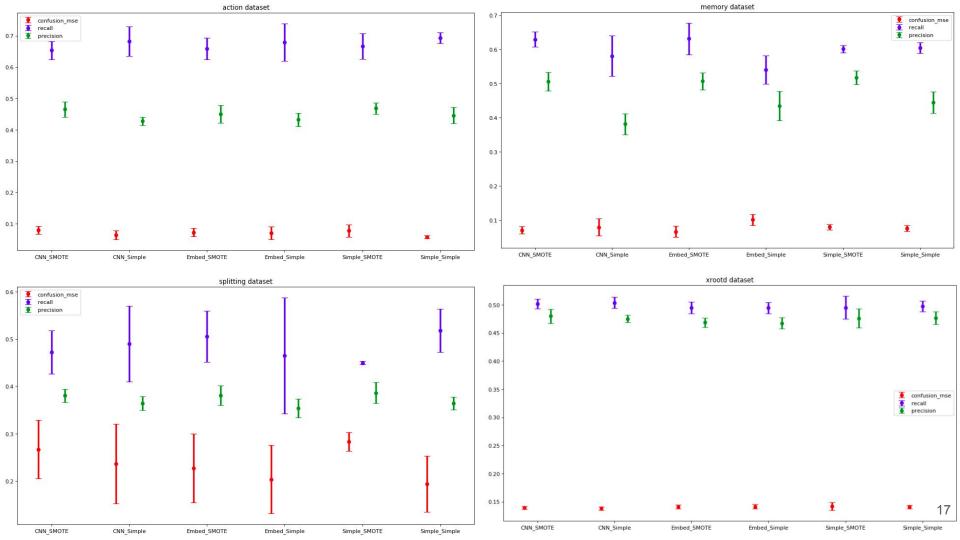
Picking Single Best Model

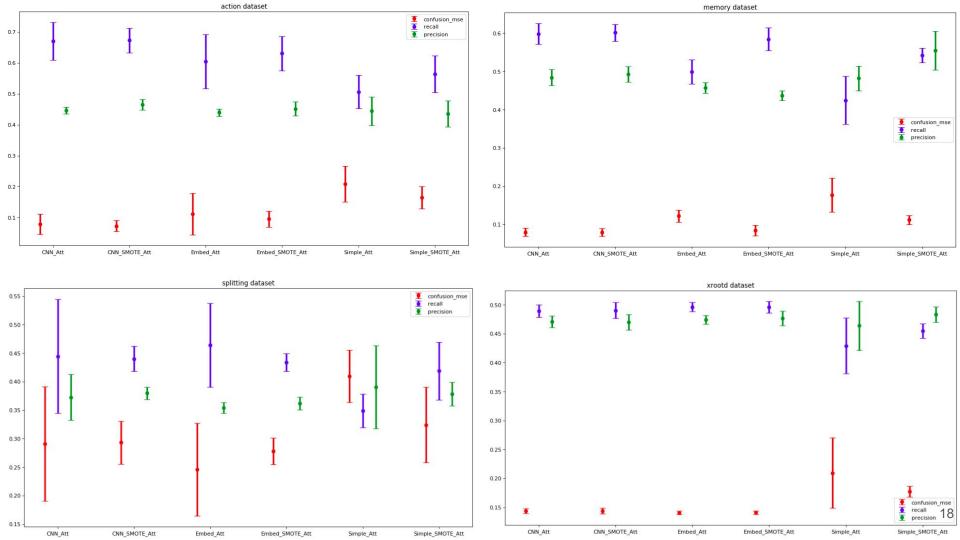


- Splitting* dataset into testing and training datasets
- For each model**:
 - Split training dataset into 5 equal size folds
 - Train on 4 Folds and test on 1 Fold (do this for each fold)
- Average each fold results into mean and std of each metric
- Model that results with best confusion mse on most outputs is considered best
- numpy seed = 42
- ** Modals that were looked at were: Total of 3 x 4 = 12 Models
 - Simple, CNN, Embedding with different methods:
 - trained using SMOTE resampling
 - trained with Attention
 - trained using both
 - trained with no SMOTE resampling and no Attention

Used Early Stopping Parameters:

- patience = 7
- maximum percentage delta = 30%
- moving average length = 2





Testing Models

Training split (70%)

Testing split (30%)

- Splitting* dataset into testing and training datasets
- For 5 times:
 - Train chosen model on training dataset
 - Get all metrics results with this model on testing dataset
- Average each results into mean and std of each metric

* - numpy seed = 42

Best Model Results on Test Set

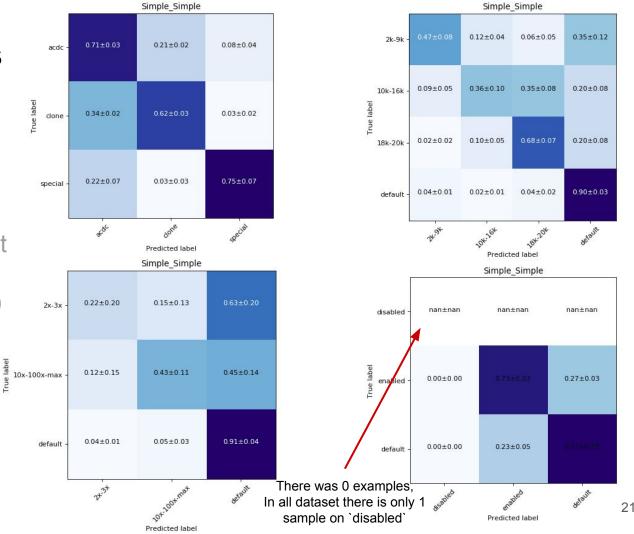
Best model - Simple_Simple

Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	simple	-	-	.0576 ± .0068	.691 ± .017	.447 ± .005
memory	simple	-	-	.0873 ± .0160	.582 ± .028	.450 ± .022
splitting	simple	-	-	.2112 ± .0321	.482 ± .028	.366 ± .008
xrootd	simple	-	-	.1456 ± .0027	.497 ± .009	.476 ± .011

Best Model Results on Test Set

Note: model always prioritizes on bigger classes except in `action` target: it is easier to predict special (138 examples) then clone (934 examples)

Y targets: action - top left memory - top right splitting - bottom left xrootd - bottom right



Bonus Slides

- Other Results (Best of SMOTE, Attention, XGBoost)
- SMOTE vs weighted cross entropy (Metric evolution plots)
- Best of Attention and no Attention (confusion matrices)

Other Results

Following slides show:

- Results using SMOTE resampling (results and confusion matrices)
- Results using Attention (results and confusion matrices)
- XGBoost model results (results)

SMOTE Results

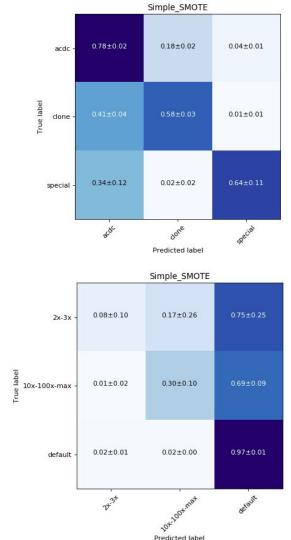
Best model - Simple SMOTE

Gets higher precision then without SMOTE, but recall and conf mse are worse

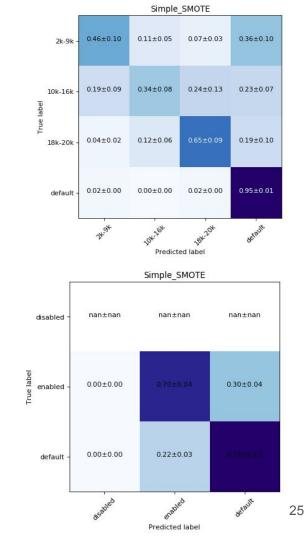
Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	simple	+	-	.0780 ± .0195	.666 ± 040	.468 ± .018
memory	simple	+	-	.0759 ± .0073	.611 ± .011	.515 ± .019
splitting	simple	+	-	.2834 ± .0200	.449 ± .003	.386 ± .022
xrootd	simple	+	-	.1417 ± .0070	.495 ± .020	.475 ± .017

everything is trained with early stopping on confusion mse with patience = 10, maximum percentage delta = 30%, moving average length = 2 $_{24}$

SMOTE Results



Y targets:
action - top left
memory - top right
splitting - bottom left
xrootd - bottom right



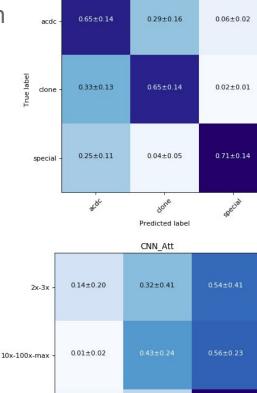
Attention Results

Best model - CNN_Att

Still most metrics are worse in comparison with models without Attention

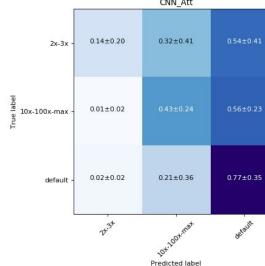
Dataset	Model	SMOTE	Attention	conf mse	recall	precision
action	cnn	-	+	.0690 ± .0159	.684 ± .016	.445 ± .022
memory	cnn	-	+	.0985 ± .074	.567 ± .027	.474 ± .021
splitting	cnn	-	+	.2907 ± .1007	.395 ± .100	.321 ± .040
xrootd	cnn	-	+	.1437 ± .0039	.489 ± .010	.470 ± .010

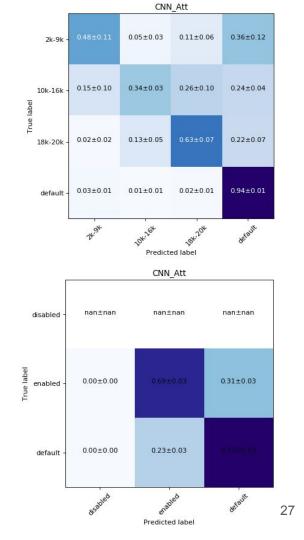
Best model with Attention (confusion matrices)



CNN Att

Y targets: action - top left memory - top right splitting - bottom left xrootd - bottom right





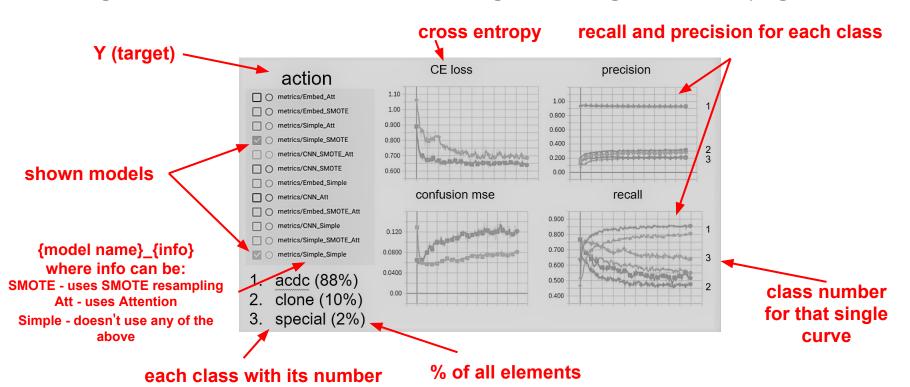
XGBoost Results When training with max depth 4 all metrics are worse

Dataset	SMOTE	conf mse	recall	precision
action	-	.308	.443	.754
action	+	.095	.633	.456
memory	-	.129	.536	.751
memory	+	.090	.593	.594
splitting	-	.395	.362	.528
splitting	+	.384	.368	.371
xrootd	-	.291	.459	.508
xrootd	+	.252	.507	.507

everything is trained with early stopping on confusion mse with patience = 10

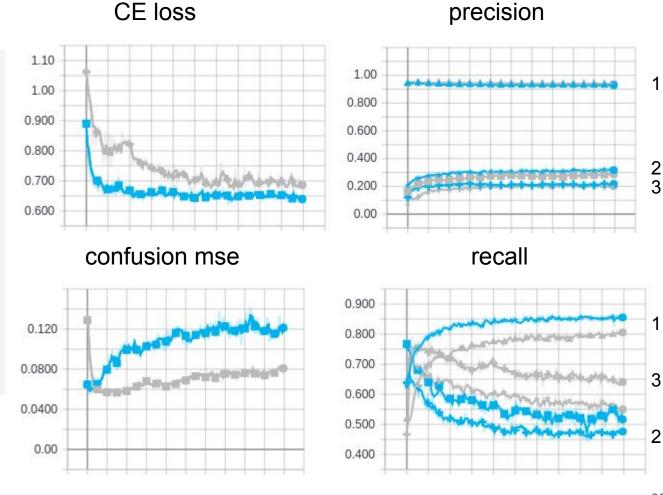
SMOTE vs weighted cross entropy

Following slides show: Metrics evolution on different Models over 200 epochs
Each dataset has 3 slides for models: (Simple, CNN, Embedding)
Single slide has evolution of metrics for model using and not using SMOTE resampling



action

- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
- metrics/Simple_SMOTE_Att
- metrics/Simple_Simple
- 1. acdc (88%)
- 2. clone (10%)
- 3. special (2%)

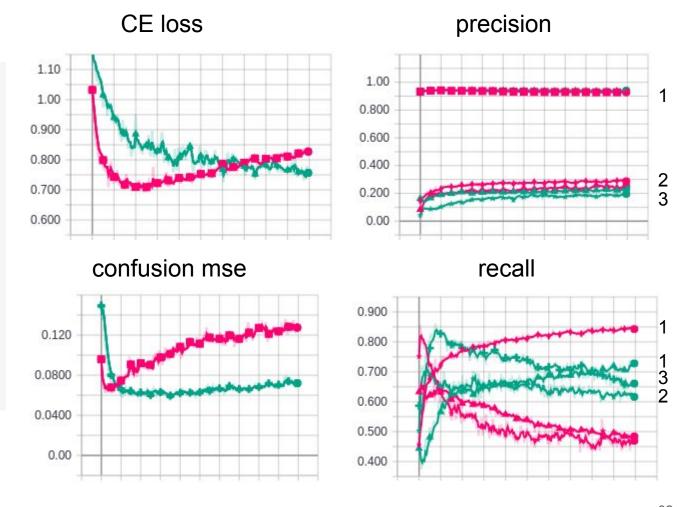


CE loss precision action 1.10 metrics/Embed_Att 1.00 1.00 metrics/Embed_SMOTE 0.800 0.900 metrics/Simple_Att 0.600 0.800 metrics/Simple_SMOTE 0.400 0.700 metrics/CNN_SMOTE_Att 0.200 metrics/CNN_SMOTE 0.600 0.00 metrics/Embed_Simple confusion mse recall metrics/CNN_Att metrics/Embed_SMOTE_Att 0.900 metrics/CNN_Simple 0.120 0.800 metrics/Simple_SMOTE_Att 0.700 0.0800 metrics/Simple_Simple 0.600 0.0400 acdc (88%) 0.500 2. clone (10%) 0.00 0.400

special (2%)

action

- metrics/Embed_Att
 - metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
- metrics/Simple_SMOTE_Att
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- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
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- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
- metrics/Simple_SMOTE_Att

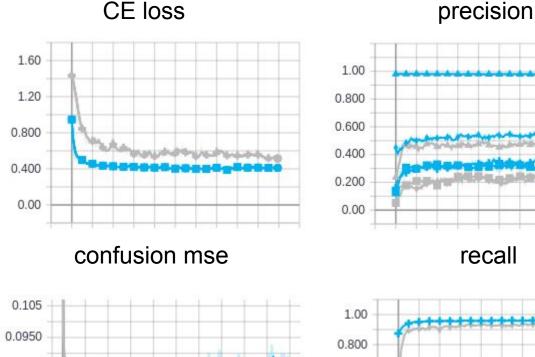
0.0850

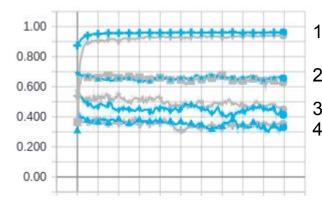
0.0750

0.0650

0.0550

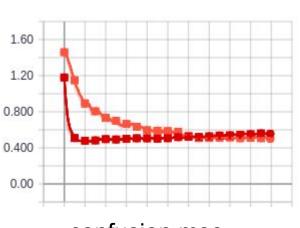
- metrics/Simple_Simple
- 1. default (92%)
- 2. 18k-20k (4%)
- 3. 2k-9k (2%)
- 4. 10k-16k (1.2%)





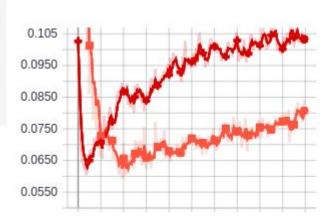
3,4

- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
- metrics/Simple_SMOTE_Att
- metrics/Simple_Simple
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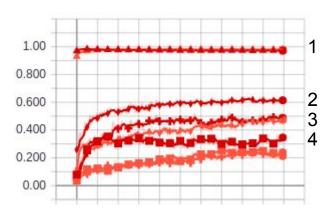


CE loss

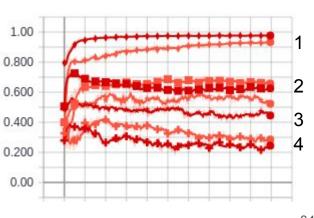




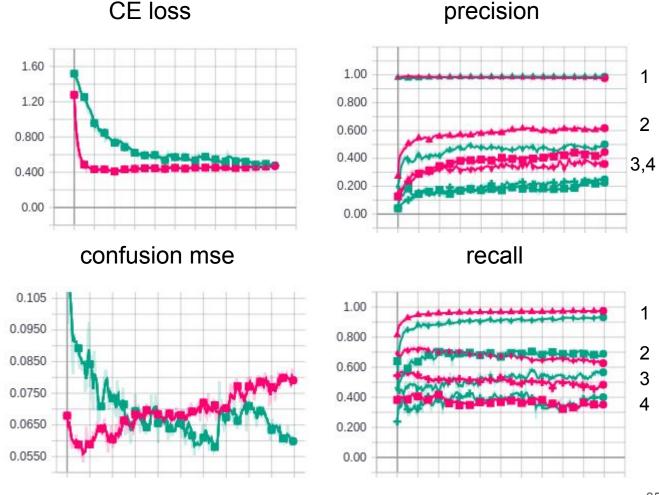
precision



recall

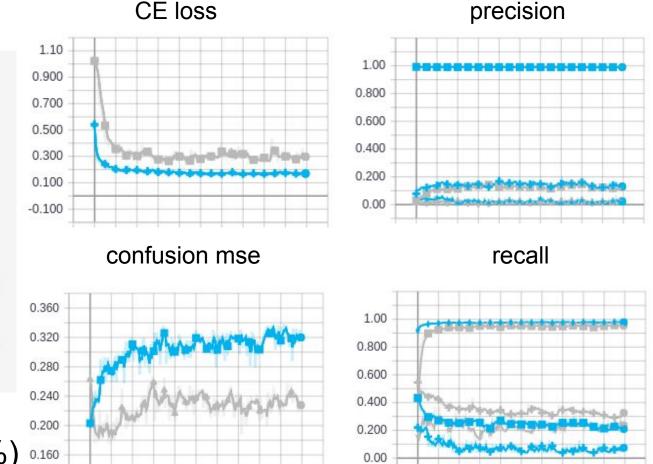


- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
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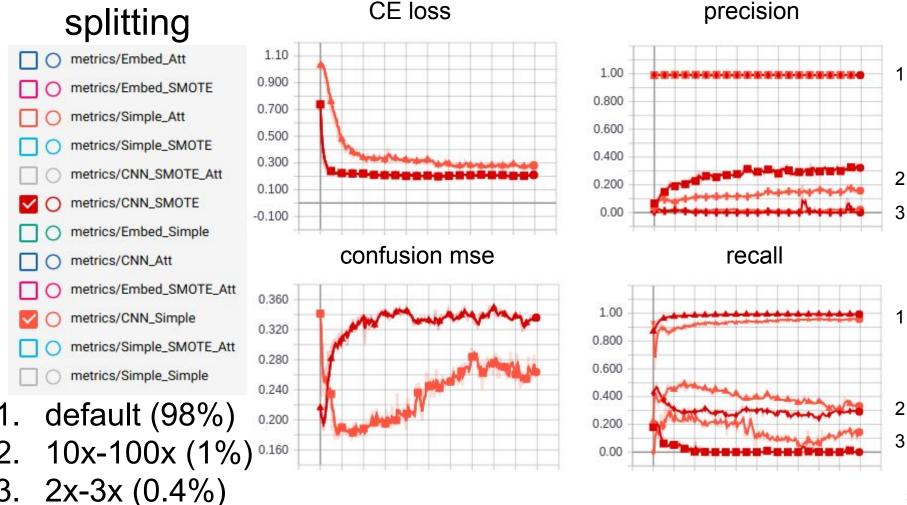


splitting

- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
- metrics/Simple_SMOTE_Att
- metrics/Simple_Simple
- 1. default (98%)
- 2. 10x-100x (1%)
- 3. 2x-3x (0.4%)

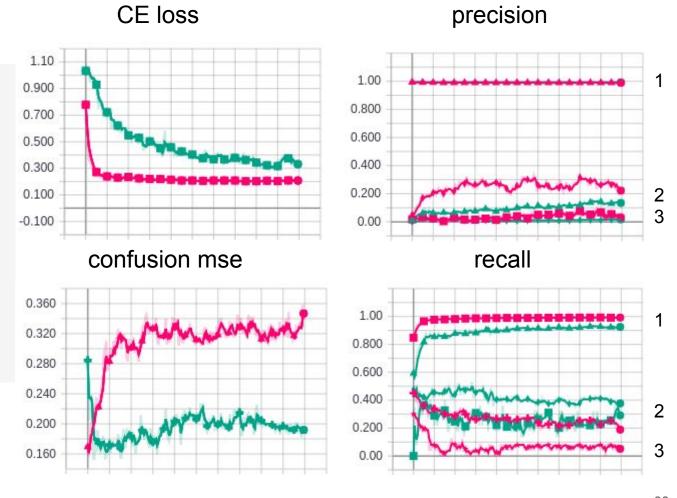


3

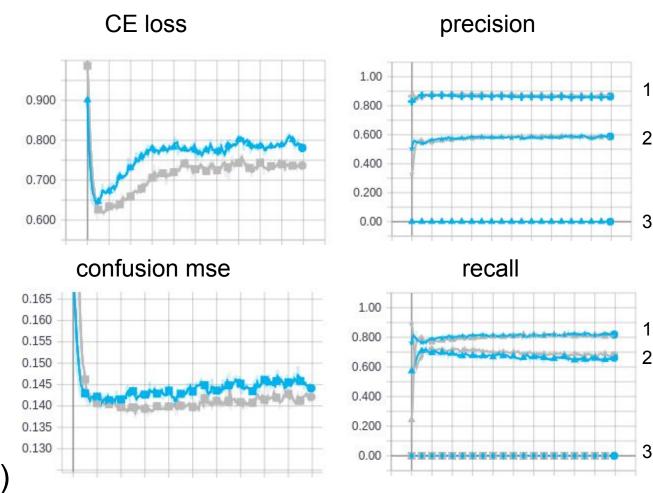


splitting

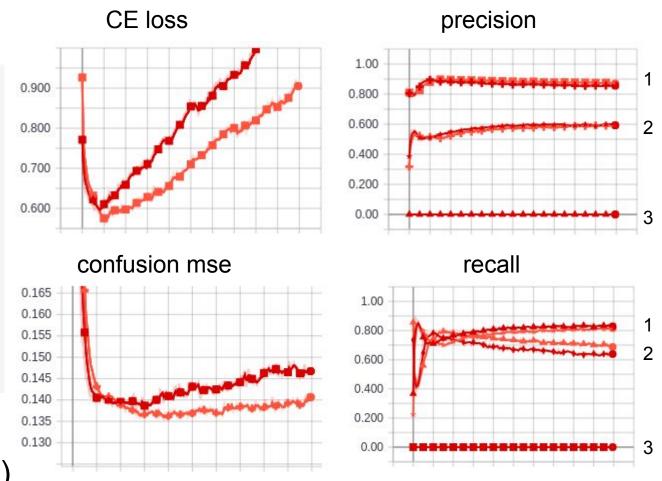
- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
- metrics/CNN_Att
- metrics/Embed_SMOTE_Att
- metrics/CNN_Simple
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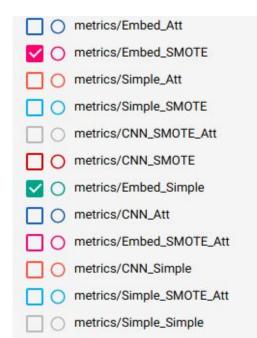


- metrics/Embed_Att
- metrics/Embed_SMOTE
- metrics/Simple_Att
- metrics/Simple_SMOTE
- metrics/CNN_SMOTE_Att
- metrics/CNN_SMOTE
- metrics/Embed_Simple
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- metrics/Simple_SMOTE_Att
- metrics/Simple_Simple
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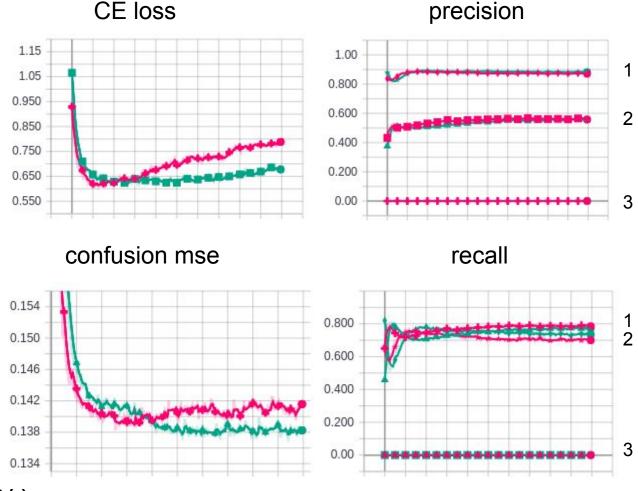


- metrics/Embed_Att
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- 1. default (72%)
- 2. enabled (28%)
- 3. disabled (0.01%)



Attention vs no Attention (confusion matrices)

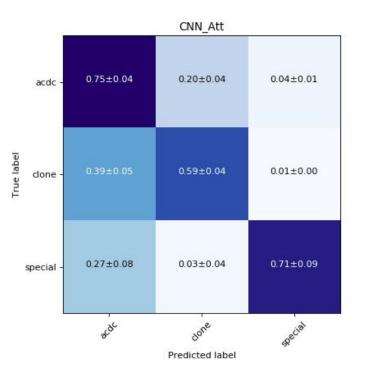
Following slides show:

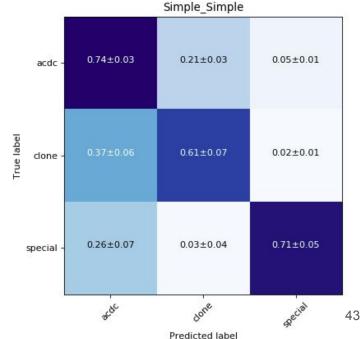
 Best confusion matrix on each Y target on validation dataset (averaged across 5 folds) using Attention (left matrix) and comparison on right with model without using Attention

action

- 1. acdc (88%)
- 2. clone (10%)
- 3. special (2%)

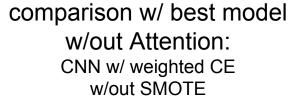
best: CNN model w/ weighted CE w/out SMOTE comparison w/ best model
w/out Attention:
Simple w/ weighted CE
w/out SMOTE





- default (92%)
- 18k-20k (4%)
- 2k-9k (2%)
- 10k-16k (1.2%)

best: Embed model w/ SMOTE



0.06±0.05

0.27±0.06

0.68±0.09

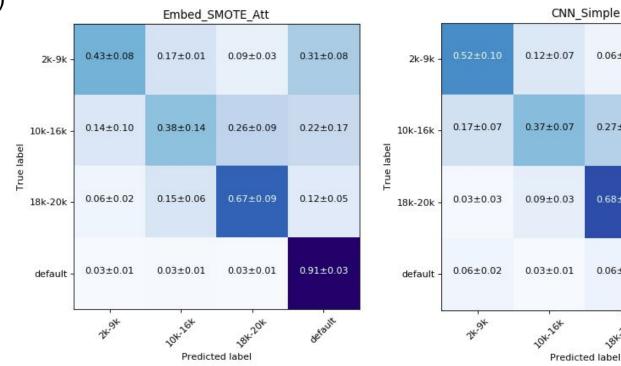
0.06+0.02

 0.30 ± 0.10

0.20±0.05

0.19±0.07

0.86±0.03

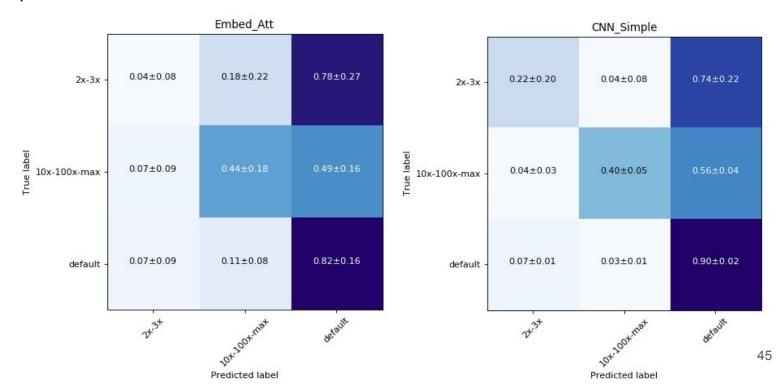


splitting

- 1. default (98%)
- 2. 10x-100x (1%)
- 3. 2x-3x (0.4%)

best: Embed model w/ weighted CE w/out SMOTE

comparison w/ best model
w/out Attention:
CNN w/ weighted CE
w/out SMOTE



- 1. default (72%)
- 2. enabled (28%)
- 3. disabled (0.01%)

best: Embed model w/ weighted CE w/out SMOTE

comparison w/ best model
w/out Attention:
CNN w/ weighted CE
w/out SMOTE

