

RM690C0 Data Sheet

Single Chip Driver with 16.7M color
for 480RGBx600 OLED driver

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1. General Description

The RM690C0 device is a single-chip solution for LTPS AMOLED with resolution up to 480RGBx600. It includes a internal memory, a timing controller with glass interface level-shifters and a glass power supply circuit.

The RM690C0 supports MIPI Interface, 8-bit system interfaces, serial peripheral interfaces (SPI), dual serial peripheral interfaces (DUAL-SPI) and quad serial peripheral interfaces (QUAD-SPI). The specified window area can be updated selectively, so that moving pictures can be displayed simultaneously independent of the still picture area.

The RM690C0 is also able to make gamma correction settings separately for RGB dots to allow benign adjustments to panel characteristics, resulting in higher display qualities. The IC support 16.77M-color images up to 480RGBx600 and a deep standby mode for lower power consumption.

This LSI is suitable for wearable device applications, including watch and smart band.

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2. Features

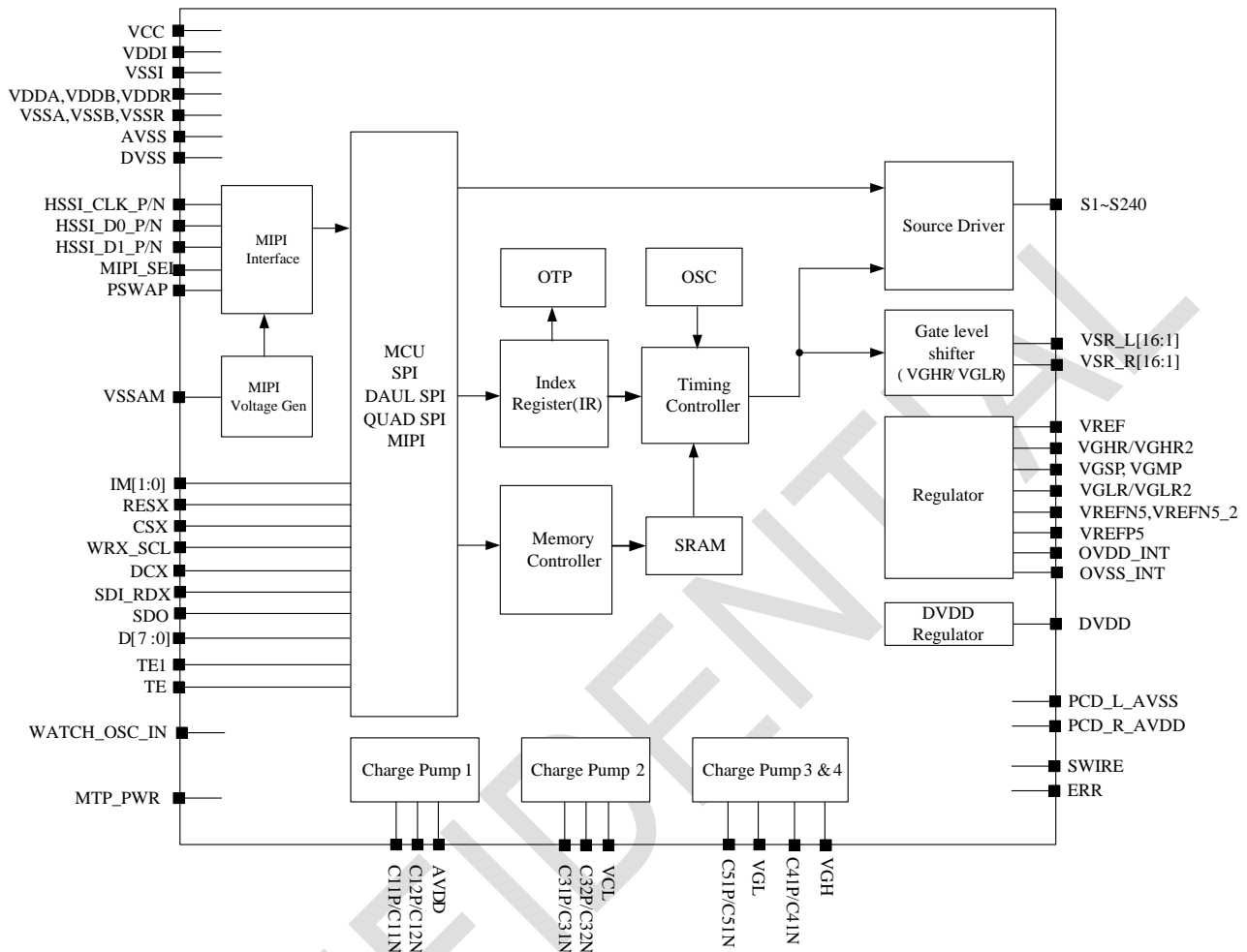
- **Single chip AMOLED controller/driver with display RAM**
- **Display resolution option**
 - 480RGB x 600
 - 480RGB x 480
 - 400RGB x 400
 - 360RGB x 480
 - 320RGB x 320
 - 320RGB x 480
 - 272RGB x 480
 - 240RGB x 240
 - 240RGB x 320
 - 180RGB x 360
 - 180RGB x 540
 - 128RGB x 432
- **Display mode (Color mode)**
 - Normal mode: 16.7M-colors, 4096-colors, 8-colors
 - Idle mode: 16.7M-colors, 4096-colors, 8-colors
- **Interface**
 - 8-bits 80-series MPU interface
 - Serial peripheral interface (SPI)
 - Dual serial peripheral interface (DUAL-SPI)
 - Quad serial peripheral interface (QUAD-SPI)
 - MIPI Display Serial Interface
 - ◆ Two swappable MIPI ports
 - ◆ Support one lane for one port (1lane maximum: 550Mbps)
 - ◆ Maximum total bit rate(1 data lane) is 550Mbps in 24-bit data format, 396Mbps in 18-bit data format, and 352Mbps in 16-bit data format
- **Interface pixel format**
 - MIPI: RGB888/ RGB666/ RGB565
 - SPI: RGB888/ RGB666/ RGB565/ RGB332/ RGB111/ Gray 256.
- **Abundant color display and drawing functions**
 - Programmable γ -correction function for 16.7 million color display
 - Individual gamma correction setting for RGB dots
 - Partial display function
- **Support Low Frame Rate**
- **High Brightness Mode**
- **Color Gamut Mapping**
- **Build-in panel crack detection**
- **Self-Clock function for AOD mode**

- **Support Status Active Reporting function**
- **Control power IC by one-wire interface**
- **On chip**
 - VREFP5/VREFN5/VREFN5_2 voltage generator for panel voltage
 - VGHR/VGHR2/VGLR/VGLR2 voltage for gate control signal
 - Internal oscillator for display clock
 - Source output MUX 1-6 with 240ch source output pins
 - Supports gate control signals to gate driver in the panel
- **Built-in OTP function to adjust panel setting**
- **Logic / interface power supply voltage VDDI = 1.65V ~ 3.3V**
- **Analog power supply voltage VDD = 2.7V ~ 3.6V**
- **Output voltage levels**
 - Positive gate driver voltage range for VGHR/VGHR2: 3 ~ 12V (Max<=VGH-0.3V)
 - Negative gate driver voltage range for VGLR/VGLR2: -2V ~ -12V (Min>=VGL+0.3V)
 - VREFP5 panel voltage range : 0.5 ~ 5V (Max<=AVDD-0.3V)
 - VREFN5/VREFN5_2 panel voltage range : -0.5 ~ -4.5V (Min>=VCL+0.3V)
 - Step-up 1,2 output voltage range for AVDD: 4.5 ~ 6.5V, VCL: -3.5 ~ -5.0V
 - Gamma high/low voltage range for VGMP: 2.0V ~ 6.3V (Max<=AVDD-0.2V) ,
VGSP: 0V, 0.2125V ~ 4.5V
 - OVDD_INT/OVSS_INT voltage range for idle mode application:
OVDD_INT : 2.0V ~ 6.0V (Max<=AVDD-0.3V)
OVSS_INT : 0V, -0.4V ~ -4.7V (Min>=VCL+0.3V)
- **Package: COF**
- **Chip size: 8218um x 1556um (including scribe line)**

■ Power Supply Specifications

No.	Item		Description
1	Source Driver		240 pins (480 x RGB)
2	Gate control timing Level shift		VGHR/VGHR2-VGLR/VGLR2
3	Input Voltage	VDDI	1.65 ~ 3.3V
		VCC	Connect to VDDI or VDD(VCI)
		VDD (VDDA/VDDDB/VDDR)	2.70 ~ 3.60V
4	OLED drive voltages	AVDD	4.5V ~ 6.5V
		VGHR/VGHR2	3V ~ 12V (Max<=VGHR-0.3V)
		VGLR/VGLR2	-2V ~ -12V (Min>=VGL+0.3V)
		VREFP5	0V, 0.5V ~ 5V (Max<=AVDD-0.3V)
		VREFN5/VREFN5_2	-0.5V ~ -4.5V (Min>=VCL+0.3V)
		OVDD_INT	2.0 ~ 6.0V (Max<=AVDD-0.3V)
		OVSS_INT	-0.4 ~ -4.7V (Min>=VCL+0.3V)
5	Internal step-up circuits	AVDD	VCI x2.0(dual), x3.0(single)
		VCL	VCI x -1.0(dual), x-2.0(single)
		VGHR	VCI x2, x3, x4
		VGL	VCI x-2, x-3, x-4

3. Block Diagram



Interface

The RM690C0 supports MIPI DSI interface. MIPI DSI can access both internal command and display data.

Grayscale Voltage Generating Circuit

Grayscale voltage generating circuit generates a drive voltage, which corresponds to grayscale level set in the y correction register. The RM690C0 displays 16.7M colors at the maximum.

Power Supply Circuit

The power supply circuit generates supply voltages to OLED panel, VGH, VGL.

Timing Generating

The timing controller generates timing signals for internal circuits such as the display timing.

Oscillator

The RM690C0 incorporates RC oscillator circuit. The frame frequency is changeable by command settings.

Panel Driver Circuit

The OLED display driver circuit consists of 240 source drivers (S1~S240). The gate signal consists of VSR_R/L[16:1] and outputs either VGHR/VGHR2 or VGLR/VGLR2 level.

4. Pin Description

4.1 Power Supply Pins

Signal	I/O	Function
VDDDB	P	Power supply for DC/DC converter VDDDB, VDDA and VDDR should be the same input voltage level
VDDA	P	Power supply for analog system. VDDDB, VDDA and VDDR should be the same input voltage level
VDDR	P	Power supply for regulator system VDDDB, VDDA and VDDR should be the same input voltage level
VDDI	P	Power supply for interface system except MIPI interface.
VCC	P	Power supply for DVDD regulator
VSSB	P	System ground for DC/DC converter
VSSA	P	System ground for analog system
VSSR	P	System ground for regulator system
VSSAM	P	System ground for internal MIPI analog system
VSSI	P	System ground for interface system except MIPI interface
DVSS	P	System ground for internal digital system
AVSS	P	System ground for source OP system.
MTP_PWR	P	MTP programming power supply pin (6.0V typical) Must be left open in normal condition.

4.2 Interface Pins

Signal	I/O	Function
CSX	I	Chip select input pin ("Low" enable) in 80-series MPU I/F and SPI I/F. If not used, please connect to VDDI.
WRX_SCL	I	WRX : Writes strobe signal to write data when WRX is "Low" in 80-series MPU I/F. SCL: A synchronous clock signal in SPI I/F. If not used, please connect to VSSI.
D/CX	I	Display data / command selection in 80-series MPU I/F and 4-wire SPI I/F. D/CX = "0" : Command D/CX = "1" : Display data or Parameter If not used, please connect to VSSI.
SDI_RDX	I/O	SDI: Serial input signal in SPI I/F. The data is input on the rising edge of the SCL signal. RDX: Reads strobe signal to write data when RDX is "Low" in 80-series MPU interface. If not used, please leave it Open.
SDO	O	Serial output signal in SPI I/F. The data is output on the rising/falling edge of the SCL signal. If the host places the SDI line into high-impedance state during the read interval, the SDI and SDO can be tied together. If not used, please open this pin.
D[7:0]	I/O	8-bit bi-directional data bus for 80-series MPU I/F and 8-bit input data bus for RGB I/F. These pins are not used for SPI, MIPI, please leave it Open.
Signal	I/O	Function
CSX	I	Chip select input pin ("Low" enable) in 80-series MPU I/F and SPI I/F. If not used, please connect to VDDI.
WRX_SCL	I	WRX : Writes strobe signal to write data when WRX is "Low" in 80-series MPU I/F. SCL: A synchronous clock signal in SPI I/F. If not used, please connect to VSSI.
D/CX	I	Display data / command selection in 80-series MPU I/F and 4-wire SPI I/F. D/CX = "0" : Command D/CX = "1" : Display data or Parameter If not used, please connect to VSSI.
SDI_RDX	I/O	SDI: Serial input signal in SPI I/F. The data is input on the rising edge of the SCL signal. RDX: Reads strobe signal to write data when RDX is "Low" in 80-series MPU interface. If not used, please leave it Open.
SDO	O	Serial output signal in SPI I/F. The data is output on the rising/falling edge of the SCL signal. If the host places the SDI line into high-impedance state during the read interval, the SDI and SDO can be tied together. If not used, please open this pin.
D[7:0]	I/O	8-bit bi-directional data bus for 80-series MPU I/F and 8-bit input data bus for RGB I/F. These pins are not used for SPI, MIPI, please leave it Open.

4.3 MIPI Interface Pins

Signal		I/O	Function							
MIPI1_CLK_P MIPI1_CLK_N		I	-These pins are DSI-CLK+/- differential clock signals if MIPI1 interface is used. -If not used, please connect these pins to VSSI.							
MIPI1_D0_P MIPI1_D0_N		I/O	-These pins are DSI-D0+/- differential data signals if MIPI1 interface is used. -If not used, please connect these pins to VSSI.							
MIPI2_CLK_P MIPI2_CLK_N		I	-These pins are DSI-CLK+/- differential clock signals if MIPI2 interface is used. -If not used, please connect these pins to VSSI.							
MIPI2_D0_P MIPI2_D0_N		I/O	-These pins are DSI-D0+/- differential data signals if MIPI2 interface is used. -If not used, please connect these pins to VSSI.							
MIPI_SEL PSWAP	I	Input pin to select MIPI1_D0/MIPI2_D0 data lane sequence and polarity in high speed interface only.								
		Pin Name	MIPI2 _D0_P	MIPI2 _D0_N	MIPI2 _CLK_P	MIPI2 _CLK_N	MIPI1 _CLK_P	MIPI1 _CLK_N	MIPI1 _D0_P	MIPI1 _D0_N
		MIPI_SEL =0 PSWAP=0	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	DSI CLK+	DSI CLK-	DSI D0+	DSI D0-
		MIPI_SEL =0 PSWAP=1	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	DSI CLK-	DSI CLK+	DSI D0-	DSI D0+
		MIPI_SEL =1 PSWAP=0	DSI D0+	DSI D0-	DSI CLK+	DSI CLK-	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS
		MIPI_SEL =1 PSWAP=1	DSI D0-	DSI D0+	DSI CLK-	DSI CLK+	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS	Host keep LP11 or enter ULPS
If not used, please connect to VSSI.										

NOTE: "1" = VDDI level, "0" = VSSI level.

4.4 Interface Logic Pins

Signal	I/O	Function															
RESX	I	This signal will reset the device and must be applied to properly initialize the chip. Signal is active low.															
IM[1:0]	I	Interface type selection. The connections of IM[1:0] which not shown in table are invalid. <table border="1"> <thead> <tr> <th>IM[1:0]</th><th>Display Data</th><th>Command</th></tr> </thead> <tbody> <tr> <td>00</td><td>MIPI / 3-wire SPI</td><td>MIPI / 3-wire SPI</td></tr> <tr> <td>01</td><td>MIPI / 4-wire SPI</td><td>MIPI / 4-wire SPI</td></tr> <tr> <td>10</td><td>MIPI / QUAD-SPI</td><td>MIPI / QUAD-SPI</td></tr> <tr> <td>11</td><td>MCU 8-bit</td><td>MCU 8-bit</td></tr> </tbody> </table>	IM[1:0]	Display Data	Command	00	MIPI / 3-wire SPI	MIPI / 3-wire SPI	01	MIPI / 4-wire SPI	MIPI / 4-wire SPI	10	MIPI / QUAD-SPI	MIPI / QUAD-SPI	11	MCU 8-bit	MCU 8-bit
IM[1:0]	Display Data	Command															
00	MIPI / 3-wire SPI	MIPI / 3-wire SPI															
01	MIPI / 4-wire SPI	MIPI / 4-wire SPI															
10	MIPI / QUAD-SPI	MIPI / QUAD-SPI															
11	MCU 8-bit	MCU 8-bit															
TE	O	Tearing effect output pin to synchronize MCU to frame writing, activated by S/W command. When this pin is not activated, this pin is output low. If not used, please open this pin.															
TE1	O	1. Tearing effect output pin to synchronize MCU to frame writing, activated by S/W command. (Same as TE) 2. IC Status active reporting pin.															
SWIRE	O	Swire protocol setting pin of Power IC, If not used, please open this pin.															
WATCH_ OSC_IN	I	The oscillator input of self-clock function for AOD mode. (crystal oscillator= 32.768kHz) If not used, please connect to VSSI.															
ERR	O	Output pin used to monitor display driver state and error status If not used, please open this pin.															

NOTE: "1" = VDDI level, "0" = VSSI level.

4.5 Driver Output Pins (Pins for Panel)

Signal	I/O	Function
S1 ~ S240	O	Pixel electrode driving output.
DMY[1] ~ DMY[12]	O	Dummy Source, please leave it Open.
VSR_L[16:1] VSR_R[16:1]	O	VSR control signals, Level shift output, VSR_L[10:1]/VSR_R[10:1]: Level shift output is VGHR-VGLR VSR_L[16:11]/VSR_R[16:11]: Level shift output can select VGHR/VGHR2-VGLR/VGLR2

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4.6 DC/DC Convert Pins

Signal	I/O	Function
AVDD	O	Output voltage from step-up circuit 1, generated from VDDDB. Connect a capacitor for stabilization.
VCL	O	Output voltage from step-up circuit 3, generated from VDDDB. Connect a capacitor for stabilization.
VGH	O	Output voltage from step-up circuit 4. Connect a capacitor for stabilization.
VGL	O	Output voltage from step-up circuit 5. Connect a capacitor for stabilization.
C11P, C11N C12P, C12N	IO	Capacitor connection pins for the step-up circuit which generate AVDD. Connect capacitor as requirement. When not in used, please open these pins.
C31P, C31N C32P, C32N	IO	Capacitor connection pins for the step-up circuit which generate VCL. Connect capacitor as requirement.
C41P, C41N	IO	Capacitor connection pins for the step-up circuit which generate VGH. Connect capacitor as requirement.
C51P, C51N	IO	Capacitor connection pins for the step-up circuit which generate VGL. Connect capacitor as requirement.
OVDD_INT	O	Positive output voltage generated from AVDD. LDO output used for OLED panel display. Connect a capacitor for stabilization. When not in use, please open this pin.
OVSS_INT	O	Negative output voltage generated from VCL. LDO output used for OLED panel display Connect a capacitor for stabilization. When not in use, please open this pin.
VGHR, VGHR2	O	Output voltage generated from VGH. LDO output used for panel voltage. Connect a capacitor for stabilization. When not in use, please open this pin.
VGLR, VGLR2	O	Output voltage generated from VGL. LDO output used for panel voltage. Connect a capacitor for stabilization. When not in use, please open this pin.
VGMP	O	Output voltage generated from AVDD. LDO output for positive gamma high voltage generator.
VGSP	O	Output voltage generated from AVDD. LDO output for positive gamma low voltage generator.
VREF	O	Regulator output for internal reference voltage. Connect capacitor for stabilization.
DVDD	O	Regulator output for logic system power. Connect a capacitor for stabilization.
VREFP5	O	Regulator output for VREFP(0.5~5V)
VREFN5, VREFN5_2	O	Regulator output for VREFN(-0.5~-4.5V)
VREFX	O	Output for VREFN5 or VREFP5

4.7 Test Pins

Signal	I/O	Function
ANALOG_TEST 1~2	O	Test pin, not accessible to user. Must be left open.
TEST1~3	IO	Test pin, not accessible to user. Must be left open.
TESTEN	I	Test pin, not accessible to user. Must be left open., Internal pull low
EXTCLK	I	Test pin, not accessible to user. Must be left open.
PCD_L_AVSS PCD_R_AVDD	I	Input pins used for panel crack detection Please connect PCD_R_AVDD and PCD_L_AVSS together by a routing trace on the panel when utilizing PCD
DUMMY_R1~R4	I	The same pad name short together internally Please leave them open when not utilizing

5 Function Description

5.1 Interface Type Selection

Interface type selection. The connections of IM[1:0] which not shown in table are invalid.

IM[1:0]	Display Data	Command
00	MIPI / 3-wire SPI	MIPI / 3-wire SPI
01	MIPI / 4-wire SPI	MIPI / 4-wire SPI
10	MIPI / QUAD-SPI	MIPI / QUAD-SPI
11	MCU 8-bit	MCU 8-bit

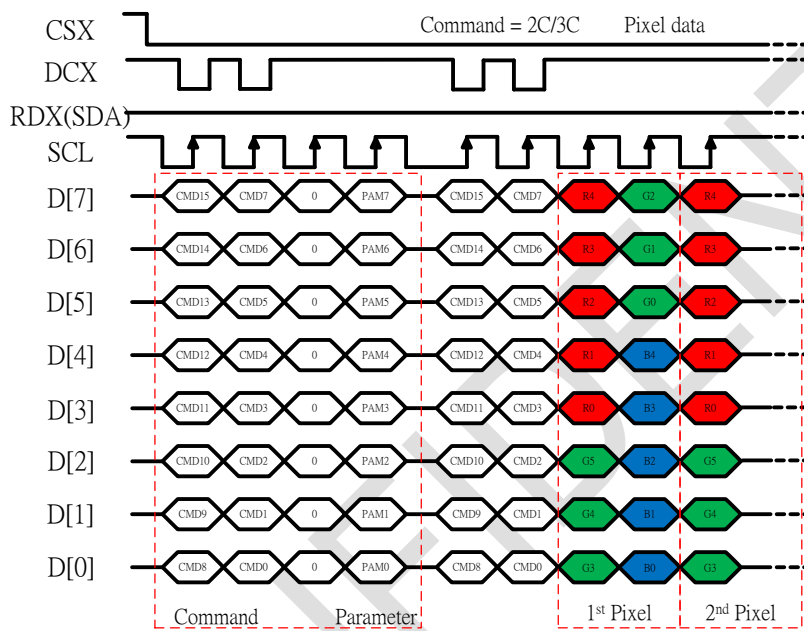
5.2 MCU Interface

5.2.1 Write Cycle and Sequence

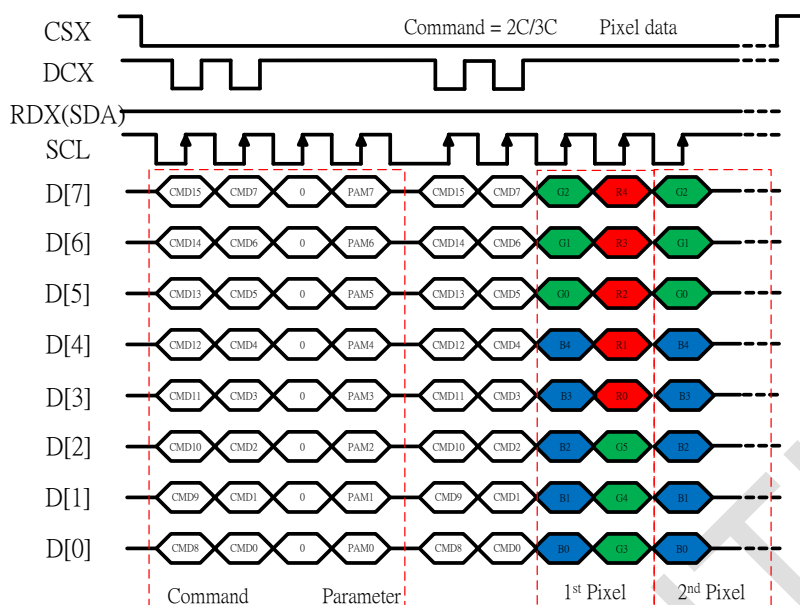
During a write cycle the host processor provides the parallel data to the display module via the interface. The MCU interface utilizes CSX, DCX, RDX(SDA), SCL and D[7:0] signals. SCL is driven from high to low then pulled back to high during the write cycle. The host processor provides information during the write cycle while the display module reads the host processor information on the rising edge of SCL.

During the write sequence the host processor writes one or more bytes of information to the display module via the interface. The write sequence is initiated when CSX is driven from high to low and ends when CSX is pulled high.

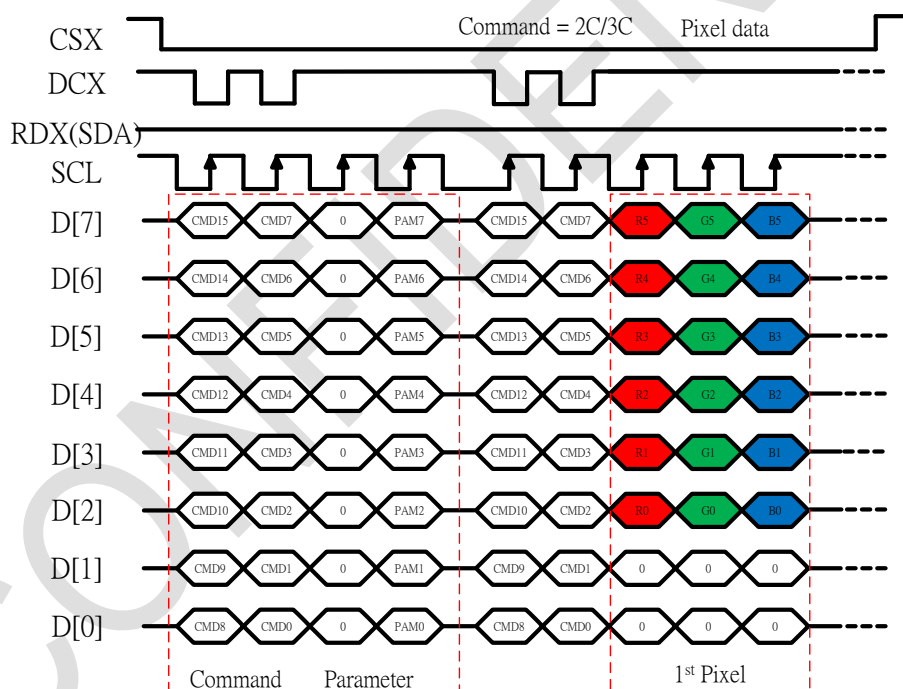
The basic command format and IFPF (0x3A00, interface pixel format) is equal to 5:



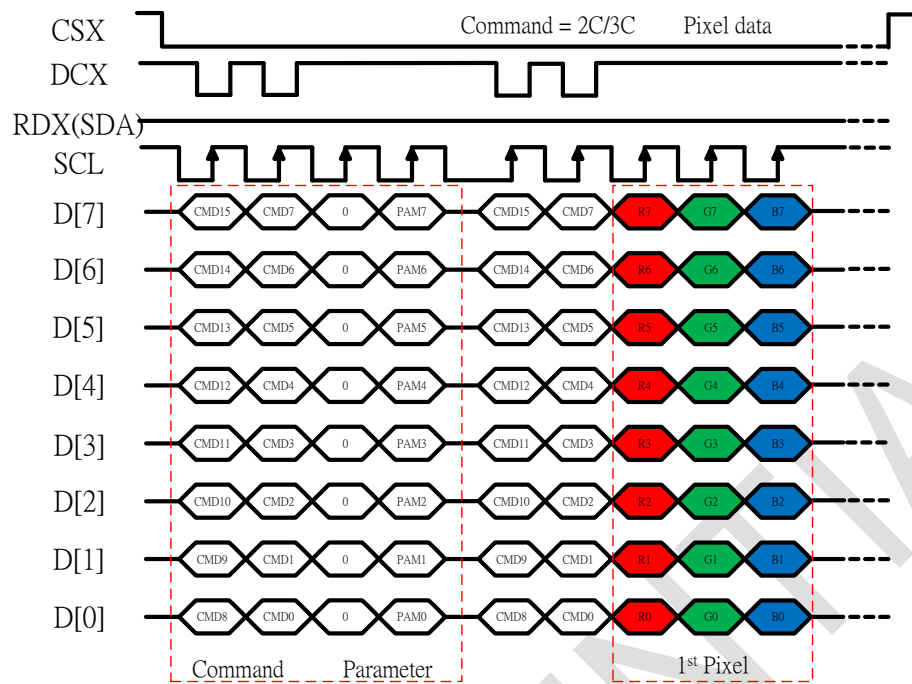
with RGB565_swap=1 function:



The basic command format and IFPF (0x3A00, interface pixel format) is equal to 6:



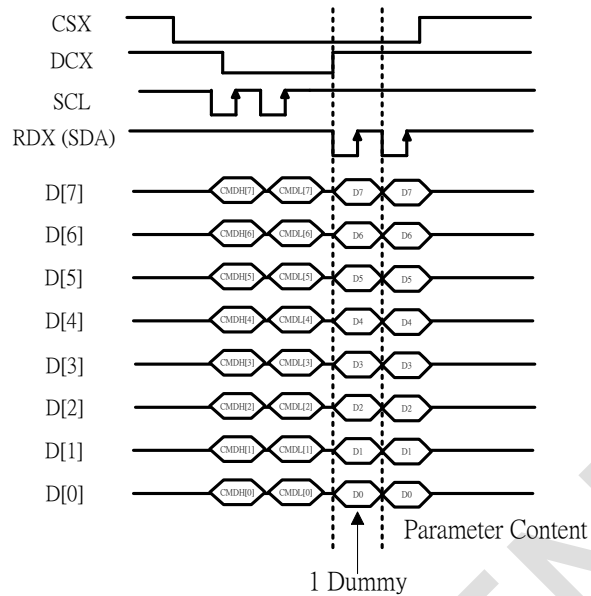
The basic command format and IFPF (0x3A00, interface pixel format) is equal to 7:



5.2.2 Read Cycle and Sequence

The command read format:

MCU Command Read



5.3 SPI/DUAL-SPI Interface

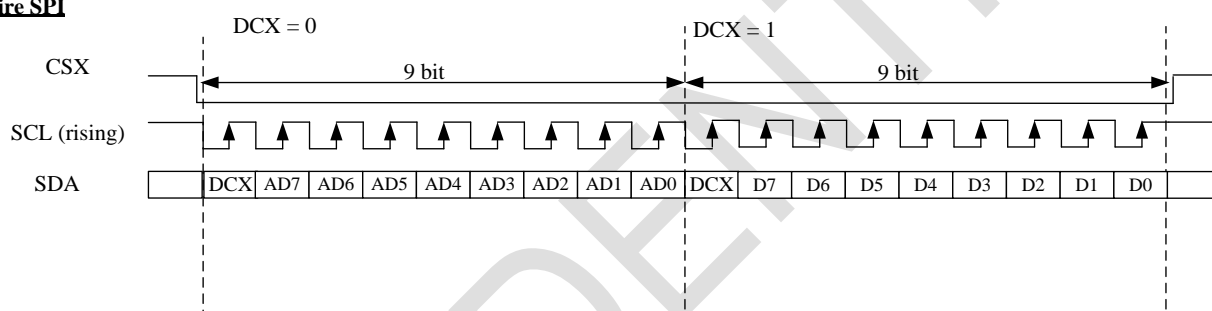
5.3.1 3-wire / 4-wire SPI/DUAL-SPI Write Cycle and Sequence

During a write cycle the host processor sends a single bit of data to the display module via the interface. The 3-wire/4-wire SPI interface utilizes CSX, SCL and SDA signals. SCL is driven from high to low then pulled back to high during the write cycle. The host processor provides information during the write cycle while the display module reads the host processor information on the rising edge of SCL.

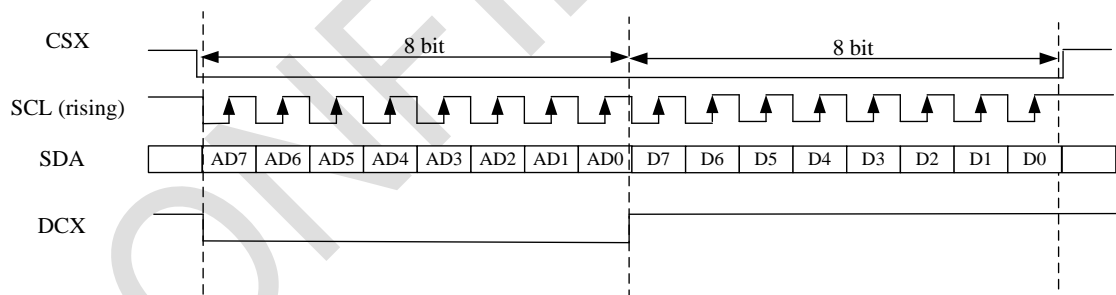
During the write sequence the host processor writes one or more bytes of information to the display module via the interface. The write sequence is initiated when CSX is driven from high to low and ends when CSX is pulled high. The 3-wire serial data contains DCX bit and a transmission byte. DCX bit is driven low while command information is on the interface and is pulled high when data is present.

The 3-wire/4-wire SPI interface write command sequences are described in the following figure.

3-wire SPI



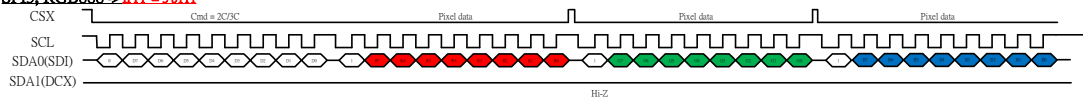
4-wire SPI



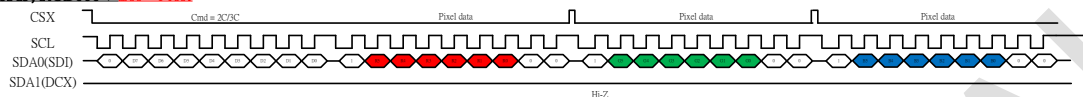
The 3-wire/4-wire SPI interface write display data sequences are described in the following figure.

When DSPI_en = 0, the host sends data by SDA only.

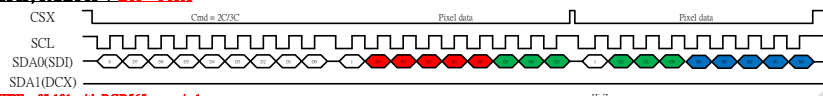
SPI3, RGB888 -> JFPF = 3'b111



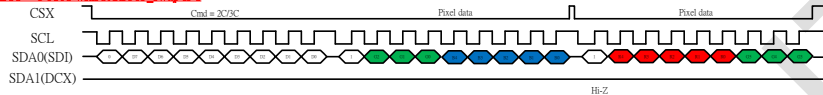
SPI3, RGB666 -> JFPF = 3'b110



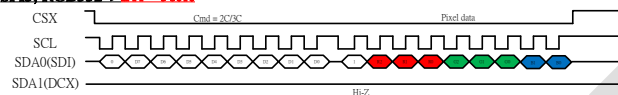
SPI3, RGB565 -> JFPF = 3'b101



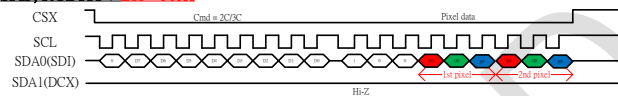
JFPF = 3'b101 with RGB565_swap is 1



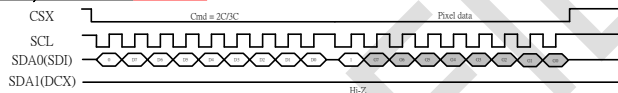
SPI3, RGB332 -> JFPF = 3'b010



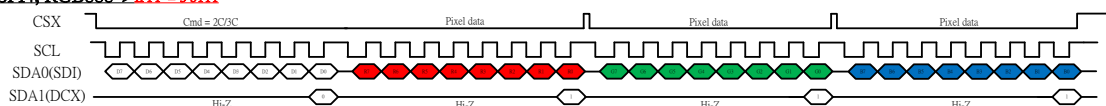
SPI3, RGB111 -> JFPF = 3'b011



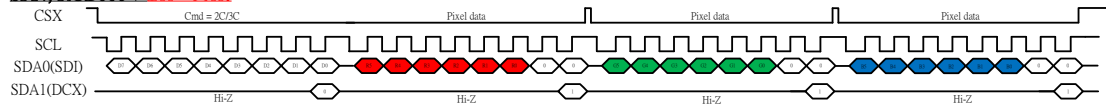
SPI3, GRAY256 -> JFPF = 3'b001



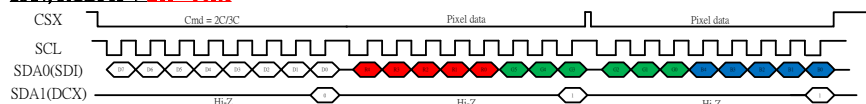
SPI4, RGB888 -> IFPF = 3'b111



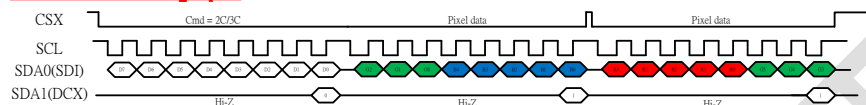
SPI4, RGB666 -> IFPF = 3'b110



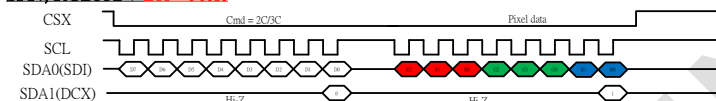
SPI4, RGB565 -> IFPF = 3'b101



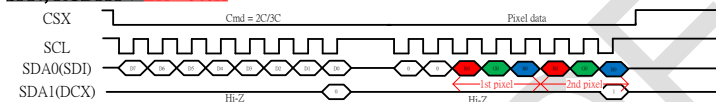
IFPF = 3'b101 with RGB565_swap is 1



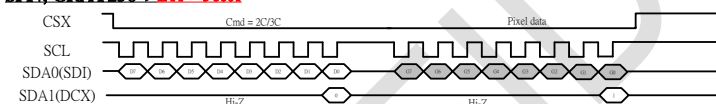
SPI4, RGB332 -> IFPF = 3'b010



SPI4, RGB111 -> IFPF = 3'b011

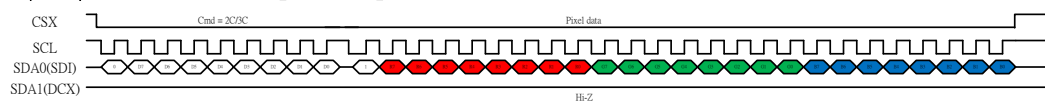


SPI4, GRAY256 -> IFPF = 3'b001

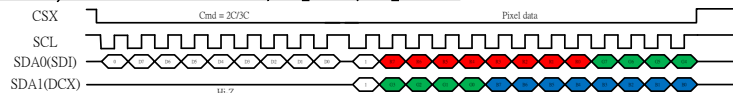


When DSPI_en =1(DUAL-SPI), the host sends data by SDA and DCX.

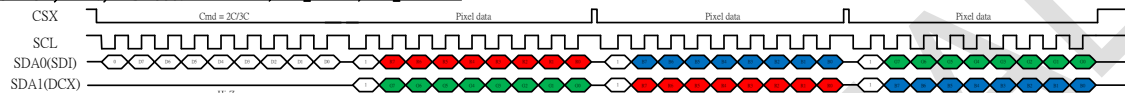
SPI3-1wire, RGB888: IFPP = 3'b111, DSPI_EN = 1'b1, DSPI_CFG = 2'b00



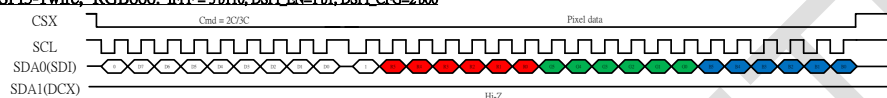
SPI3-1P1T, 2wire, RGB888: IFPP = 3'b111, DSPI_EN = 1'b1, DSPI_CFG = 2'b10



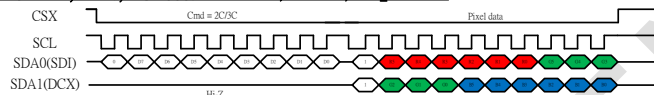
SPI3-2P3T, 2wire, RGB888: IFPP = 3'b111, DSPI_EN = 1'b1, DSPI_CFG = 2'b11



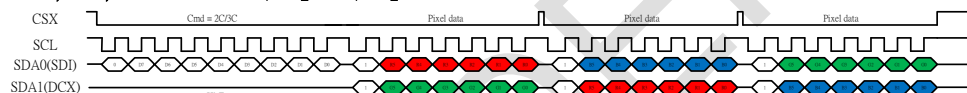
SPI3-1wire, RGB666: IFPP = 3'b110, DSPI_EN = 1'b1, DSPI_CFG = 2'b00



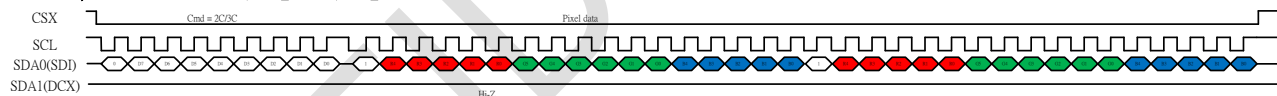
SPI3-1P1T, 2wire, RGB666: IFPP = 3'b110, DSPI_EN = 1'b1, DSPI_CFG = 2'b10



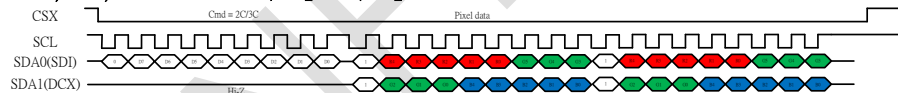
SPI3-2P3T, 2wire, RGB666: IFPP = 3'b110, DSPI_EN = 1'b1, DSPI_CFG = 2'b11



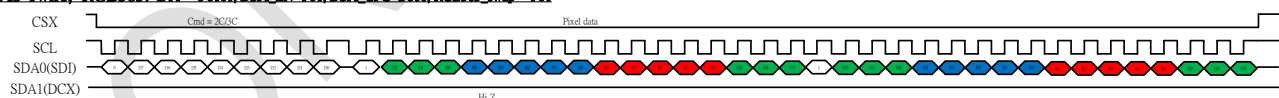
SPI3-1wire, RGB565: IFPP = 3'b101, DSPI_EN = 1'b1, DSPI_CFG = 2'b00



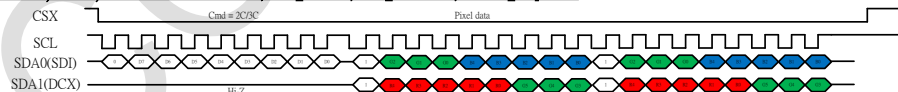
SPI3-1P1T, 2wire, RGB565: IFPP = 3'b101, DSPI_EN = 1'b1, DSPI_CFG = 2'b10



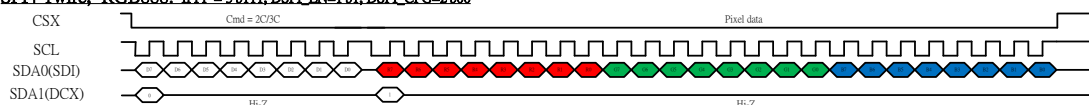
SPI3-1wire, RGB565: IFPP = 3'b101, DSPI_EN = 1'b1, DSPI_CFG = 2'b00, RGB565_swap = 1'b1



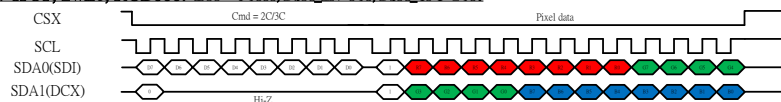
SPI3-1P1T, 2wire, RGB565: IFPP = 3'b101, DSPI_EN = 1'b1, DSPI_CFG = 2'b10, RGB565_swap = 1'b1



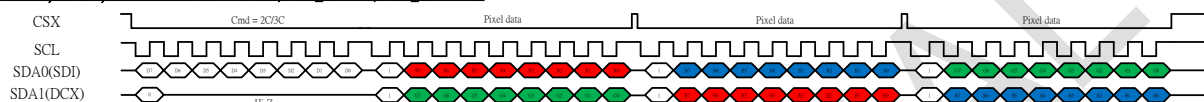
SPI4-1wire, RGB888: IFPP = 3'b111, DSPI_EN=1'b1, DSPI_CFG=2'b00



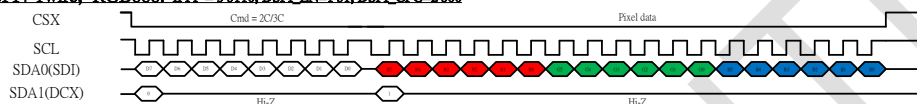
SPI4-1P1T, 2wire, RGB888: IFPP = 3'b111, DSPI_EN=1'b1, DSPI_CFG=2'b10



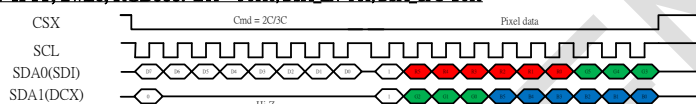
SPI4-2P3T, 2wire, RGB888: IFPP = 3'b111, DSPI_EN=1'b1, DSPI_CFG=2'b11



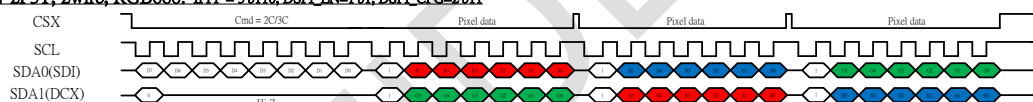
SPI4-1wire, RGB666: IFPP = 3'b110, DSPI_EN=1'b1, DSPI_CFG=2'b00



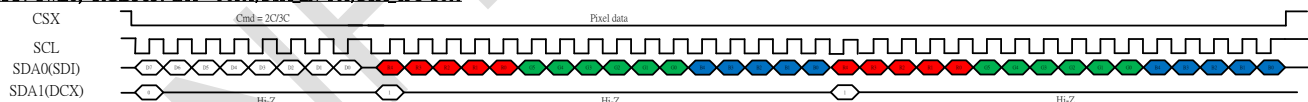
SPI4-1P1T, 2wire, RGB666: IFPP = 3'b110, DSPI_EN=1'b1, DSPI_CFG=2'b10



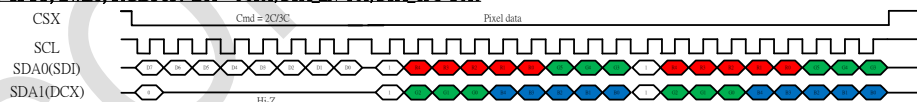
SPI4-2P3T, 2wire, RGB666: IFPP = 3'b110, DSPI_EN=1'b1, DSPI_CFG=2'b11



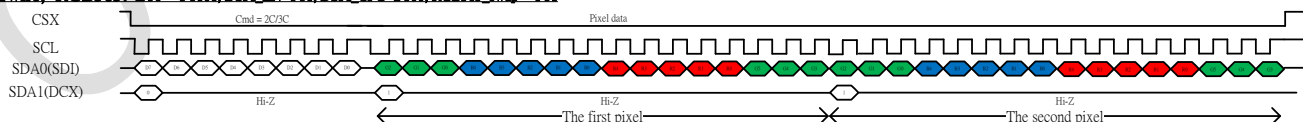
SPI4-1wire, RGB565: IFPP = 3'b101, DSPI_EN=1'b1, DSPI_CFG=2'b00



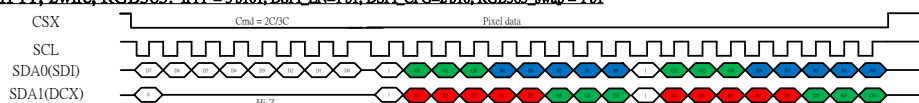
SPI4-1P1T, 2wire, RGB565: IFPP = 3'b101, DSPI_EN=1'b1, DSPI_CFG=2'b10



SPI4-1wire, RGB565: IFPP = 3'b101, DSPI_EN=1'b1, DSPI_CFG=2'b00, RGB565_swap = 1'b1



SPI4-1P1T, 2wire, RGB565: IFPP = 3'b101, DSPI_EN=1'b1, DSPI_CFG=2'b10, RGB565_swap = 1'b1



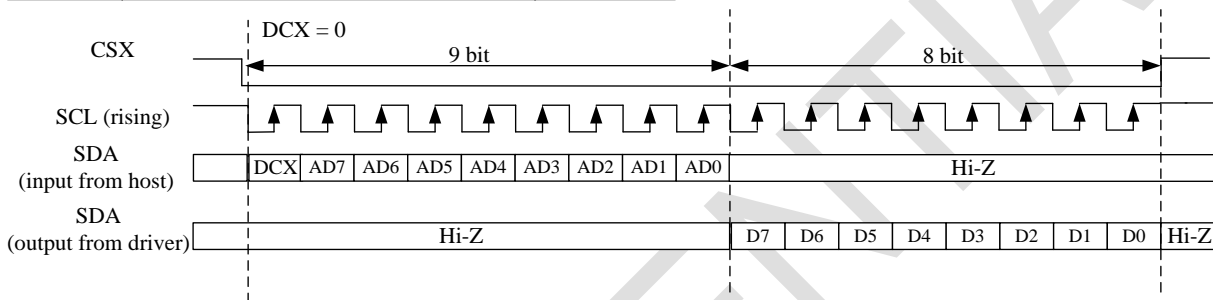
5.3.2 3-wire / 4-wire SPI Read Cycle and Sequence

During a read cycle the host processor reads a single bit of data from the display module via the interface. The 3-wire/4-wire SPI interface utilizes CSX, SCL and SDA signals. SCL is driven from high to low then pulled back to high during the read cycle. The display module provides information during the read cycle while the host processor reads the display module information on the rising edge of SCL.

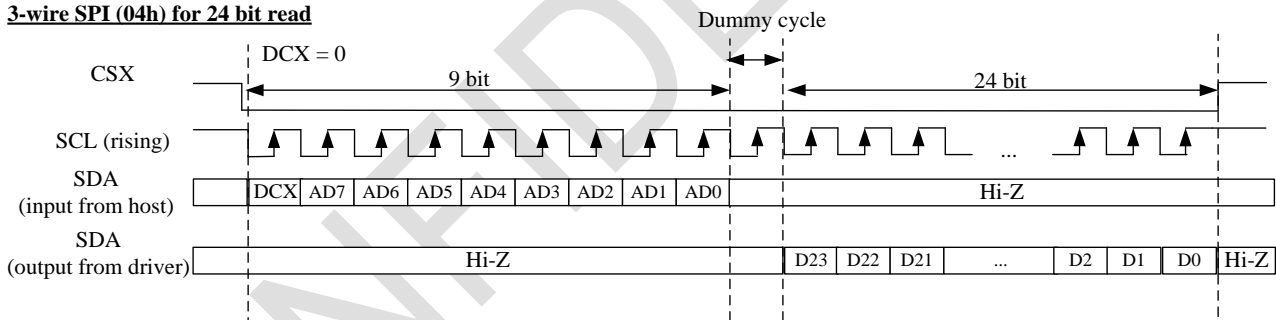
During the read sequence the host processor reads one or more bytes of information from the display module via the interface. The read sequence is initiated when CSX is driven from high to low and ends when CSX is pulled high. The 3-wire serial data contains DCX bit and a transmission byte. DCX is driven low while command information is on the interface and is pulled high when data is present.

The 3-wire/4-wire SPI interface read command sequences are described in the following figure.

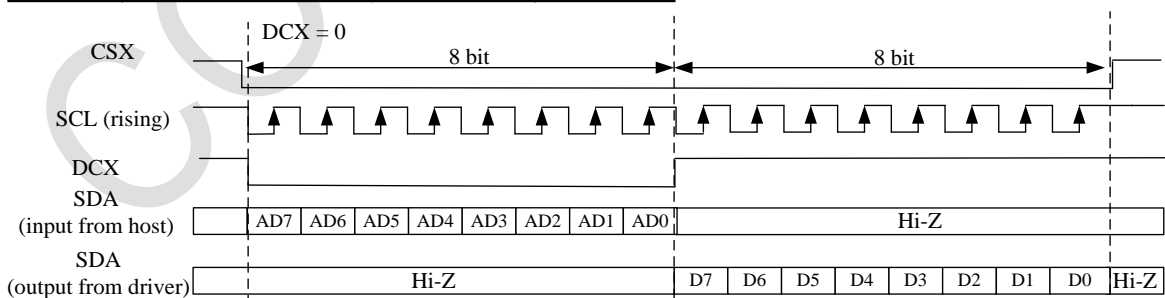
3-wire SPI (0Ah/0B/0Ch/0Dh/0Eh/0Fh/DAh/DBh/DCh) for 8 bit read



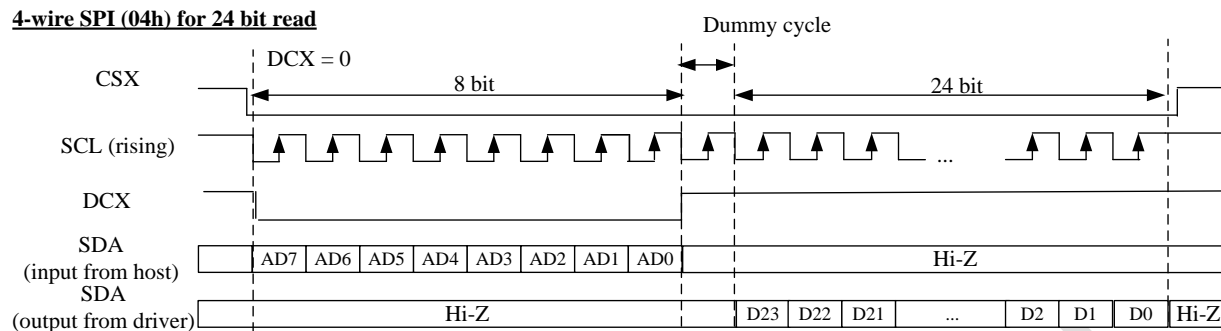
3-wire SPI (04h) for 24 bit read



4-wire SPI (0Ah/0B/0Ch/0Dh/0Eh/0Fh/DAh/DBh/DCh) for 8 bit read



4-wire SPI (04h) for 24 bit read



5.4 QUAD-SPI protocol

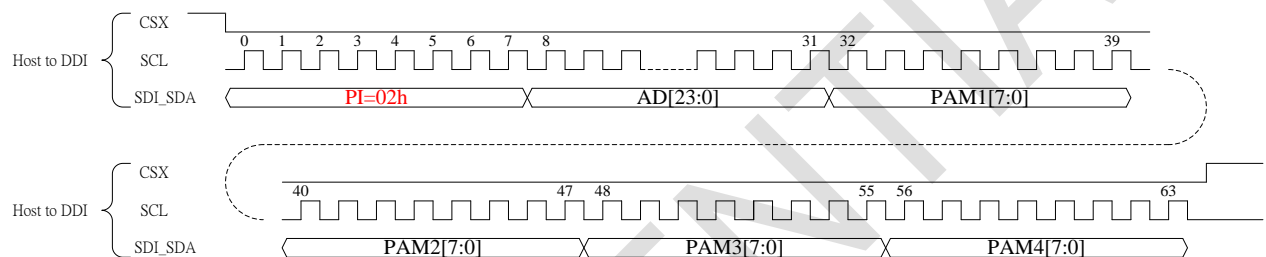
QUAD-SPI provides 1-wire for writing / reading command, and 4-wire for writing pixel data. CSX is the chip selection and it is low active property. SCL is driven from high to low then pulled back to high during the write cycle for clock input. SDI_SDA is for 1-wire command writing (PI=02h), 1-wire command reading (PI=03h) and 4-wire pixel data transmission (PI=12h or 32h). DCX and D[1:0] are for 4-wire mode pixel data transmission.

5.4.1 QUAD-SPI command format

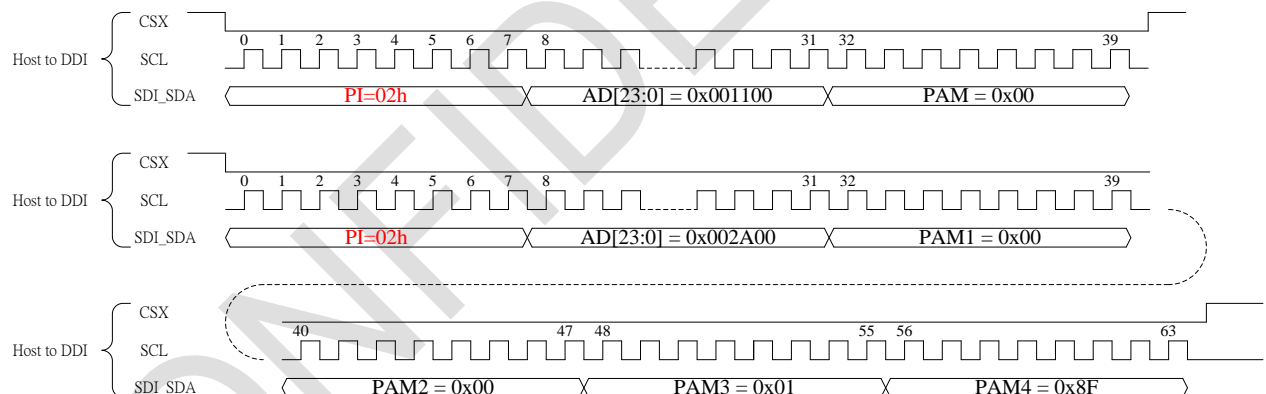
The QUAD-SPI interface write command sequences are described in the following figure.

AD[23:0] is the command address and its content is {8'h00, CMD[7:0], 8'h00}.

PAM*[7:0] is the command parameter, and PI[7:0] is the packet instruction for QUAD-SPI protocol format decoding.



For example: SLPOUT and memory column setting (multi parameters)



5.4.2 QUAD-SPI pixel writing format

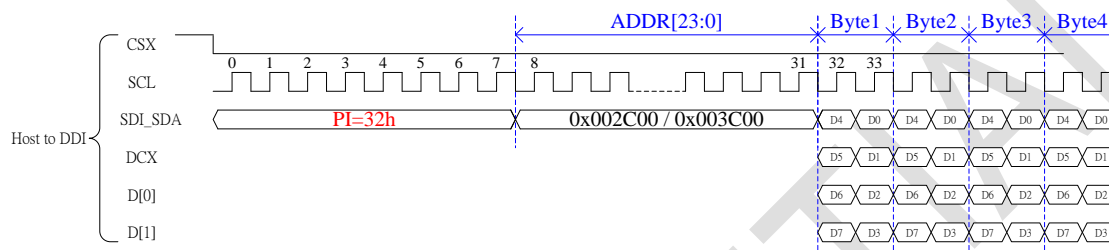
The QUAD-SPI interface write pixel data sequences are described in the following figure.

AD[23:0] is the driver IC command address, 0x002C00 or 0x003C00.

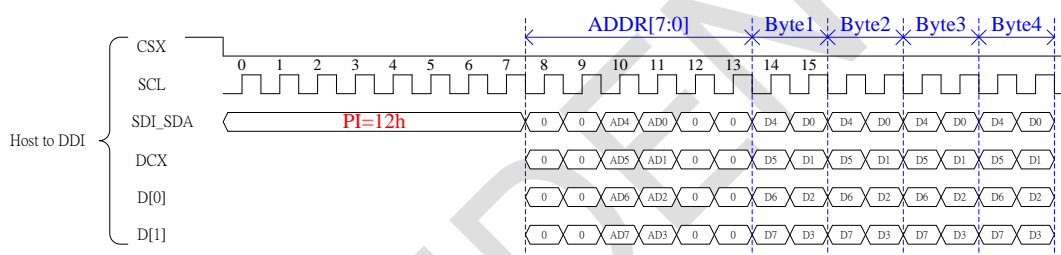
Data*[7:0]: the pixel data

Two kinds of ADDR format which is distinguished by the preceding packet (32h or 12h).

ADDR is 24bits: ADDR is made up 002C00 or 003C00



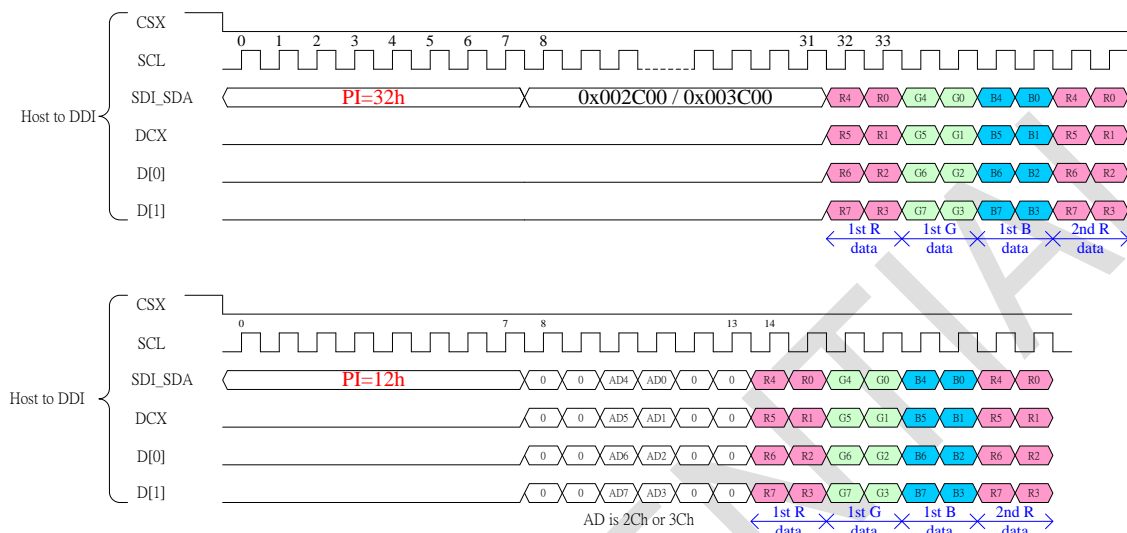
ADDR is 8bits: ADDR is 2C or 3C



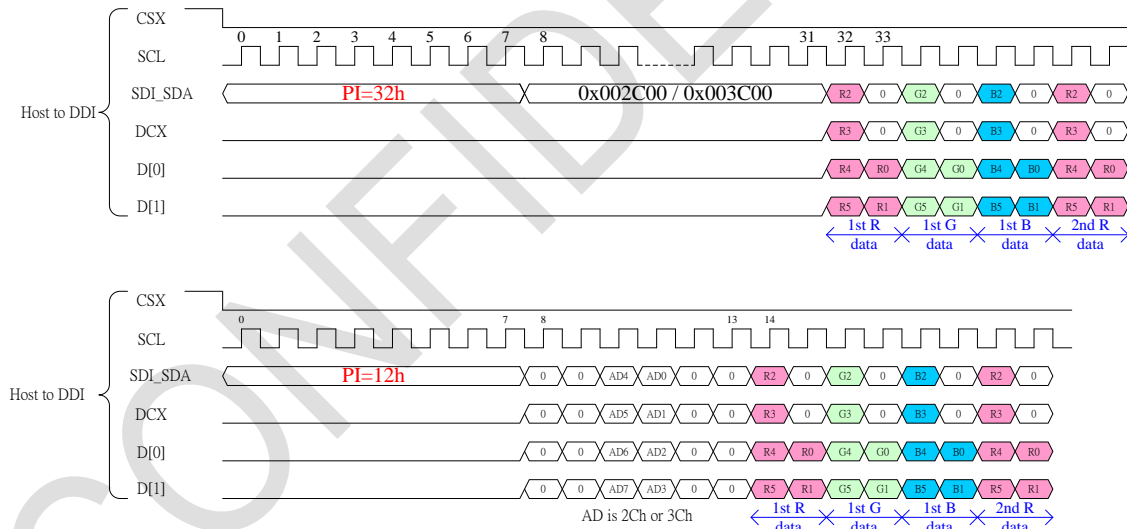
5.4.3 QUAD-SPI pixel writing color format

The QUAD-SPI interface supported RGB888, RGB666, RGB565, RGB332, RGB111, Gray256 for the following formats.

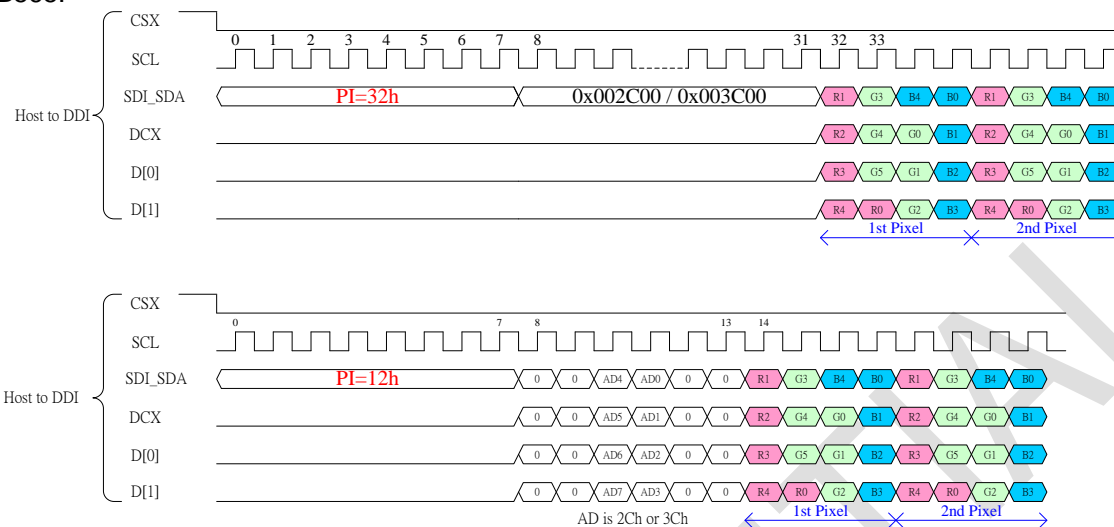
RGB888:



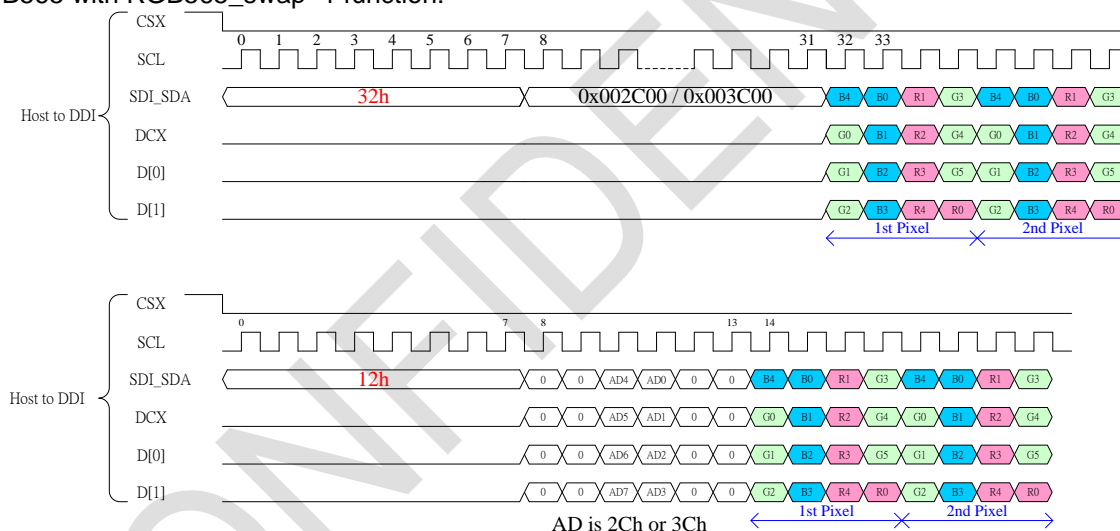
RGB666:



RGB565:



RGB565 with RGB565_swap=1 function:

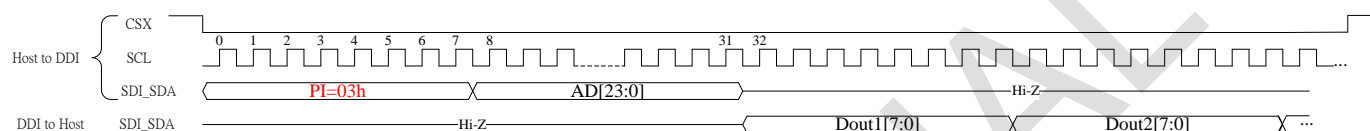


5.4.4 QUAD-SPI Read Cycle and Sequence

During a read cycle the host processor reads a single bit of data from the display module via the interface. The QUAD-SPI interface utilizes CSX, SCL and SDI_SDA signals. SCL is driven from high to low then pulled back to high during the read cycle. The display module provides information during the read cycle while the host processor reads the display module information on the rising edge of SCL.

During the read sequence the host processor reads one or more bytes of information from the display module via the interface. The read sequence is initiated when CSX is driven from high to low and ends when CSX is pulled high.

QUAD-SPI read format:



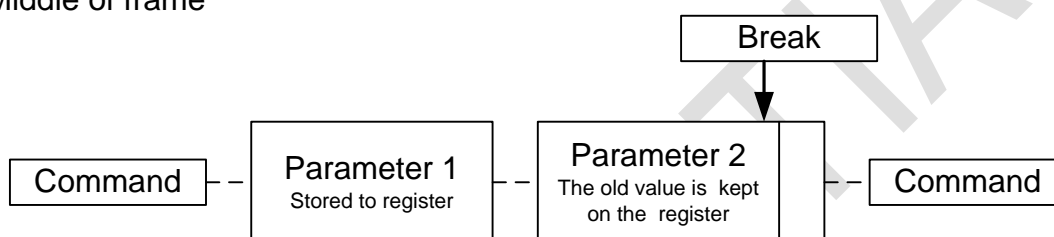
AD is made up {8'h00, CMD[7:0], 8'h00}

5.5 Break and Pause Sequence

The host processor can break a read or write sequence by pulling the CSX signal high during a command or data byte. The display module shall reset its interface so it will be ready to receive the same byte when CSX is again driven low.

The host processor can pause a read or write sequence by pulling the CSX signal high between command and data bytes. The display module shall wait for the host processor to drive CSX low before continuing the read or write sequence at the point where the sequence was paused.

1. Middle of frame

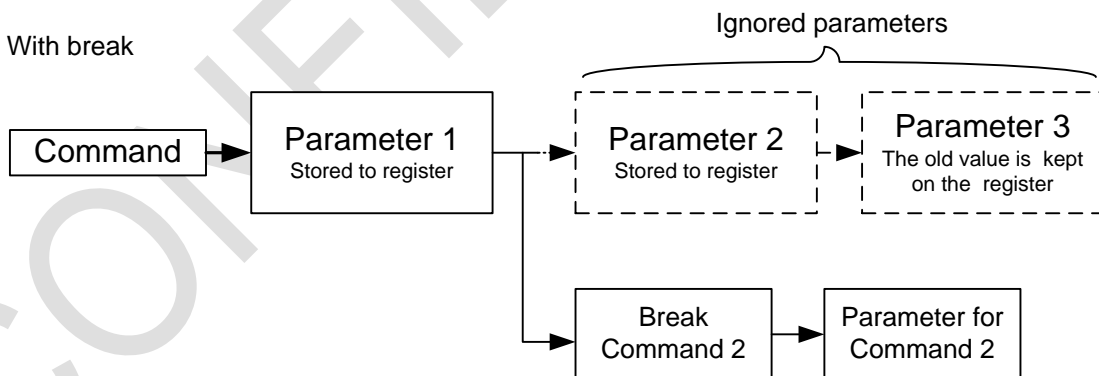


2. Between frames

Without break



With break



Break can be e.g. another command or noise pulse.

5.6 Display Serial Interface (DSI)

DSI-compliant peripherals support either of two basic modes of operation: Command Mode and Video Mode. The mode definitions reflect the primary intended use of DSI for display interconnect, but are not intended to restrict DSI from operating in other applications.

RM690C0 is capable of both Command Mode operation and Video Mode operation. Command Mode refers to operation in which transactions primarily take the form of sending commands and data to a display module that incorporates a display controller. The display controller may include local registers and a frame buffer. Systems using Command Mode write to, and read from, the registers and frame buffer memory. The host processor indirectly controls activity at the peripheral by sending commands, parameters and data to the display controller.

The host processor can also read display module status information or the contents of the frame memory. Command Mode operation requires a bidirectional interface. Video Mode refers to operation in which transfers from the host processor to the peripheral take the form of a real-time pixel stream. In normal operation, the display module relies on the host processor to provide image data at sufficient bandwidth to avoid flicker or other visible artifacts in the displayed image. Video information should only be transmitted using High Speed Mode.

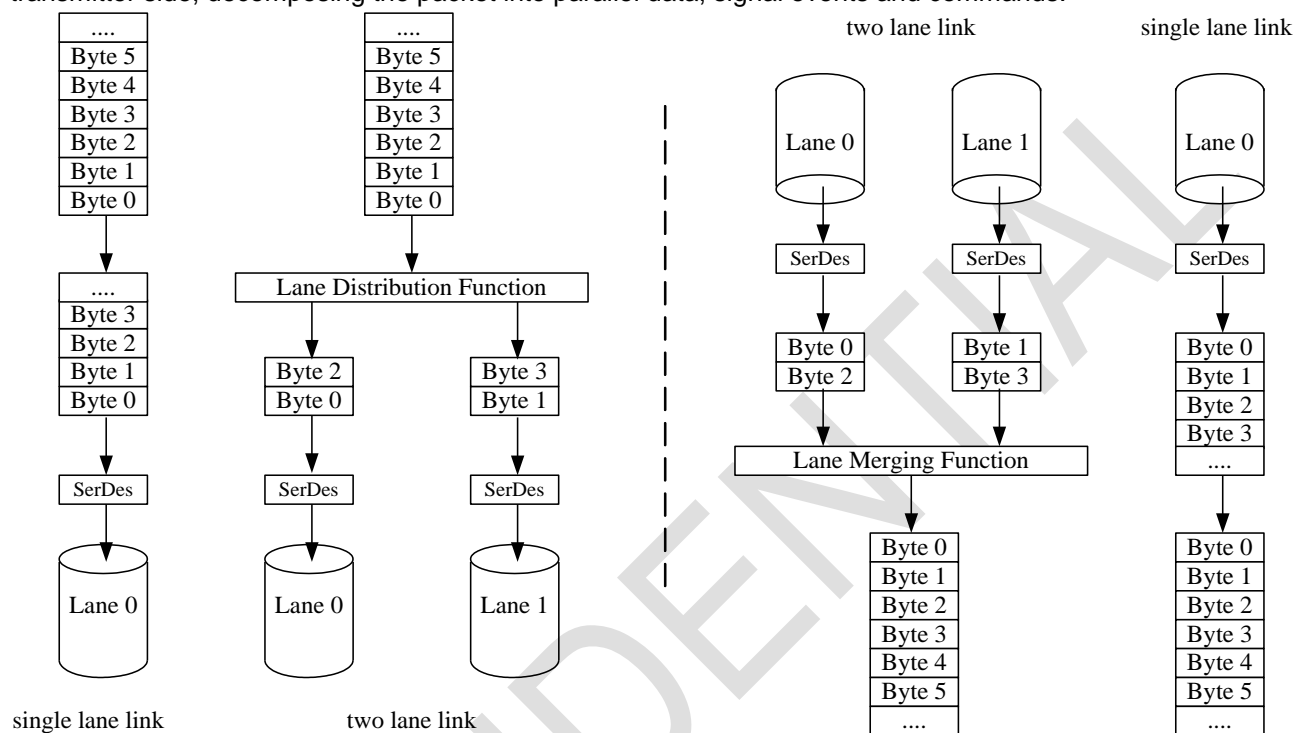
RM690C0 Video Mode architectures also include a simple timing controller and partial frame buffer, used to maintain a partial-screen or lower-resolution image in standby or Low Power Mode. This permits the interface to reduce power consumption.

RM690C0 Configuration:

Lane Pair	MCU(Host) RM690C0(Client)
Clock Lane	Unidirectional Lane Clock only
Data Lane 0	Bi-directional Lane Forward High-speed Bi-directional Escape Mode Bi-directional LPDT
Data Lane 1	Unidirectional Lane Forward High-Speed Escape Mode No LPDT

5.7 DSI Protocol

On the transmitter side of a DSI Link, parallel data, signal events, and commands are converted to packets. These packets are sent across the serial Link. The receiver side of a DSI Link performs the converse of the transmitter side, decomposing the packet into parallel data, signal events and commands.



There are two kinds of packets, **short packet and long packet**.

Short packet structure:

LP-11: low power mode

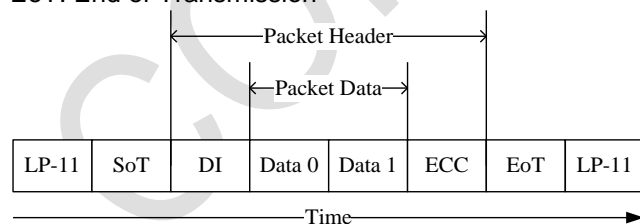
SoT: start of transmission

DI: data identification

Data 0, Data1: packet data

ECC: error correction code

EoT: End of Transmission



DI structure:

Virtual Channel: these two bits identify the data as directed to one of four virtual channels

Data Type: It specifies the packet structure and packet format

Virtual Channel (VC)		Data Type (DT)					
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

Long packet structure:

LP-11: low power mode

SoT: start of transmission

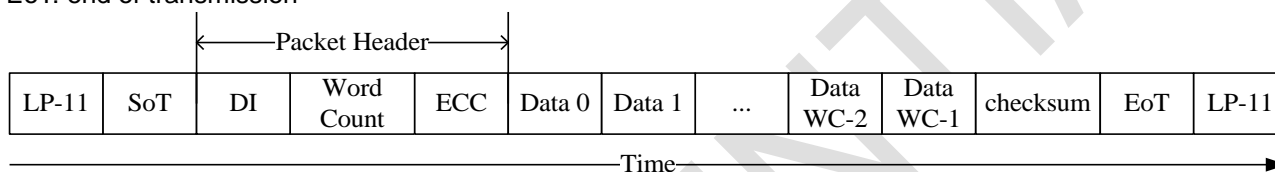
DI: data identification

Word Count: the number of data bytes of packet data

ECC: error correction code

Checksum: The 16-bit CRC generator to check packet data. If the calculated checksum of receiver are equal to the packet data, the packet data is correct. If the calculated checksum of receiver are not equal, the packet data are not correct.

EoT: end of transmission



5.8 Processor to Peripheral Transactions

Processor to Peripheral Direction Packet Data Types

Data Type	Data Type binary	Description	Packet Size
01h	00 0001	Sync Event, V Sync Start	Short
11h	01 0001	Sync Event, V Sync End	Short
21h	10 0001	Sync Event, H Sync Start	Short
31h	11 0001	Sync Event, H Sync End	Short
08h	00 1000	End of Transmission packet (EoTp)	Short
02h	00 0010	reserved	Short
12h	01 0010	reserved	Short
22h	10 0010	reserved	Short
32h	11 0010	reserved	Short
03h	00 0011	reserved	Short
13h	01 0011	Generic Short WRITE, 1 parameter	Short
23h	10 0011	Generic Short WRITE, 2 parameters	Short
04h	00 0100	reserved	Short
14h	01 0100	Generic READ, 1 parameter	Short
24h	10 0100	reserved	Short
05h	00 0101	DCS Short WRITE, no parameters	Short
15h	01 0101	DCS Short WRITE, 1 parameter	Short
06h	00 0110	DCS READ, no parameters	Short
37h	11 0111	Set Maximum Return Packet Size	Short
09h	00 1001	Null Packet, no data	Long
19h	01 1001	Blanking Packet, no data	Long
29h	10 1001	Generic Long Write	Long
39h	11 1001	DCS Long Write/write_LUT Command Packet	Long
0Eh	00 1110	Packed Pixel Stream, 16-bit RGB, 5-6-5 Format	Long
1Eh	01 1110	Packed Pixel Stream, 18-bit RGB, 6-6-6 Format	Long
2Eh	10 1110	reserved	Long
3Eh	11 1110	Packed Pixel Stream, 24-bit RGB, 8-8-8 Format	Long

Sync Event, Data Type = xx 0001

Sync Events are all short packets and time-accurately. They can perform like the start and end of sync pulses. To represent timing information as accurately as possible, a V Sync Start event represents the start of the VSA and also implies an H Sync Start event for the first line of the VSA. Hence, a V Sync End event implies an H Sync Start event for the last line of the VSA. Sync events may be concatenated with blanking packets to convey inter-line timing accurately and avoid the overhead of switching between LPS and HS for every event. Note there is a power penalty for keeping the data line in HS mode.

EoT packet

This short packet is used to indicate the end of a high speed (HS) transmission. This packet will enhance overall system reliability. Although the main objective of the EoTp is to enhance robustness during HS transmission mode, RM690C0 can detect and interpret arriving EoTps regardless of transmission mode (HS or LP modes)

Generic short write / read packet

Generic Short WRITE command is a Short packet type for sending generic data to the peripheral. Generic READ request is a Short packet requesting data from the peripheral.

DCS commands

DCS short write command

DCS short write command is used to write a single data byte command to display module. If there is a valid parameter byte, data type bit 4 shall be set to 1. If there is no valid parameter byte, data type bit 4 shall be set to 0 and the parameter byte shall be 00h.

DCS read commands

The commands are used to request data from a display module.

DCS Long Write / write_LUT command

The commands are used to send larger blocks of data to a display module.

Maximum return packet size

This command specifies the maximum size of the payload in a long packet transmission from a display module to host processor.

Null Packet

This is a mechanism for keeping the data lane(s) in high speed mode while sending dummy data.

Blanking Packet

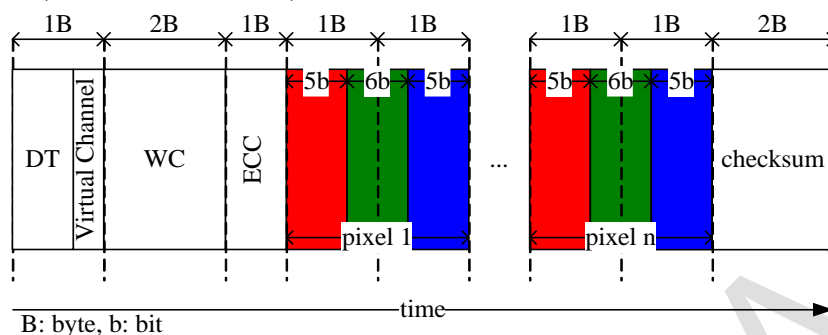
A Blanking packet is used to convey blanking timing information in a Long packet. The packet represents a period between active scan lines of a Video Mode display, where traditional display timing is provided from the host processor to the display module. The blanking period may have Sync Event packets interspersed between blanking segments. Blanking packets may contain arbitrary data as payload.

Generic Long Write

This is used to transmit arbitrary blocks of data from a host processor to a peripheral.

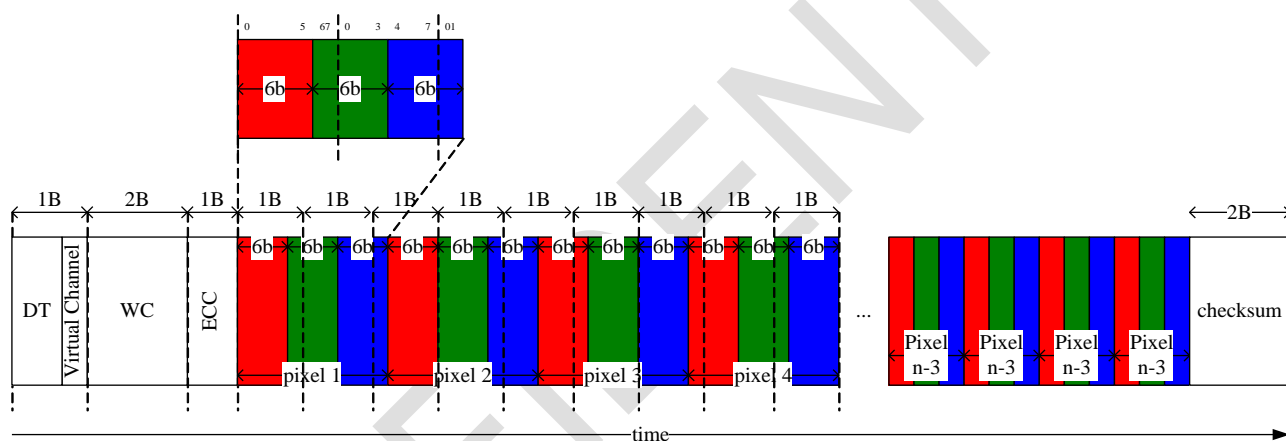
Packed Pixel Stream, 16-bit Format, Data Type: 00 1110

The pixel format is five bits red, six bits green and five bits blue. The green component is split across two bytes. Within a color component, the LSB is sent first, the MSB last.



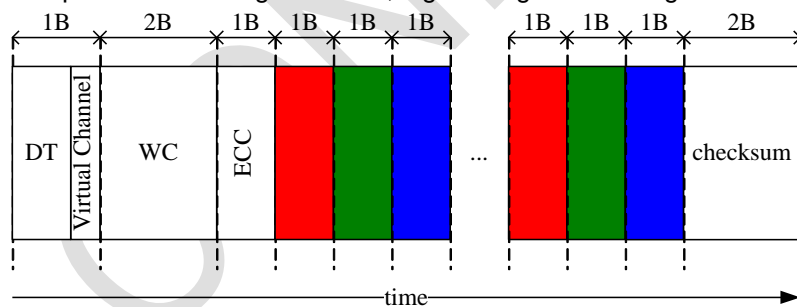
Packet pixel stream, 18-bit format, Data Type: 01 1110

The pixel format is six bits red, six bits green and six bits blue. Within a color component, the LSB is sent first, the MSB last.



Packet pixel stream, 24-bit format, Data Type: 11 1110

The pixel format is eight bits red, eight bits green and eight bits blue.



5.9 Peripheral-to-Processor LP Transmission

All Command Mode systems require bidirectional capability for returning READ data, acknowledge, or error information to the host processor. Multi-Lane systems shall use Lane 0 for all peripheral-to-processor transmissions. Reverse-direction signaling shall only use low power mode transmission.

Packet structure for peripheral-to-processor transaction is the same as for the processor-to-peripheral direction. For the processor-to-peripheral direction, two basic packet formats are the same as the peripheral-to-processor direction: Short and Long packet structure. BTA shall take place after every peripheral-to-processor transaction. This returns bus control to the host processor following the completion of the LP transmission from the peripheral.

There are four basic types of peripheral-to-processor transactions.

Tearing Effect: It is a Trigger message sent to convey display timing information to the host processor.

Acknowledge: It is a Trigger Message sent when the current transmission, as well as all preceding transmissions since the last peripheral to host communication.

Acknowledge and Error Report: It is a Short packet sent if any errors were detected in preceding transmissions from the host processor.

Response to Read Request: It may be a Short or Long packet that returns data requested by the preceding READ command from the processor.

Interpretation of processor-to-peripheral transactions with BTA asserted, and the expected responses, are as follows:

Following a non-Read command: If no errors were detected, the peripheral shall respond with Acknowledge.

Following a Read request: The peripheral shall send the requested READ data if no errors were detected and stored since the last peripheral to host communication.

Following a Read request: If only a single-bit ECC error was detected and corrected, the peripheral shall send the requested READ data in a Long or Short packet and a 4-byte Acknowledge and Error Report packet in the same LP transmission.

Following a non-Read command: If only a single-bit ECC error was detected and corrected, the peripheral shall respond to BTA by sending a 4-byte Acknowledge and Error Report packet.

Following a Read request: If multi-bit ECC errors were detected and not corrected, the peripheral shall send a 4-byte Acknowledge and Error Report packet without sending Read data.

Following a non-Read command: If multi-bit ECC errors were detected and not corrected, the peripheral shall not execute the command, and shall send a 4-byte Acknowledge and Error Report packet.

Following any command: If SoT Error, SoT Sync Error, the VC of DSI or the ID of DSI Invalid or DSI protocol violation was detected, or the DSI command was not recognized, the peripheral shall send a 4-byte Acknowledge and Error Report response.

Following any command: If EoT Sync Error or LP Transmit Sync Error is detected, or a checksum error is detected in the payload, the peripheral shall send a 4-byte Acknowledge and Error Report packet.

5.10 Error Report Format

The following table shows the bit assignment for all error report.

Bit	Description
0	SoT Error
1	SoT Sync Error
2	EoT Sync Error
3	Escape Mode Entry Command Error
4	Low-Power Transmit Sync Error
5	HS Receive Timeout Error
6	False Control Error
7	Reserved
8	ECC Error, single-bit (detected and corrected)
9	ECC Error, multi-bit (detected, not corrected)
10	Checksum Error (Long packet only)
11	DSI Data Type Not Recognized
12	DSI VC ID Invalid
13	reserved
14	reserved
15	reserved

5.11 Peripheral-to-Processor Transaction – Detail Format Description

The following list is the complete set of peripheral-to-processor data types.

Data type, hex	Data type binary	Description	Packet size
02h	00 0010	Acknowledge and error report	short
08h	00 1000	reserved	short
11h	01 0001	GEN short read response, 1byte returned	short
12h	01 0010	GEN short read response, 2bytes returned	short
1Ah	01 1010	Generic long read response	long
1Ch	01 1100	DCS long read response	long
21h	10 0001	DCS short read response, 1byte returned	short
22h	10 0010	DCS short read response, 2bytes returned	short

Acknowledge and error report: It is sent with BTA asserted when a reportable error is detected in the preceding, or earlier, transmission from the host processor.

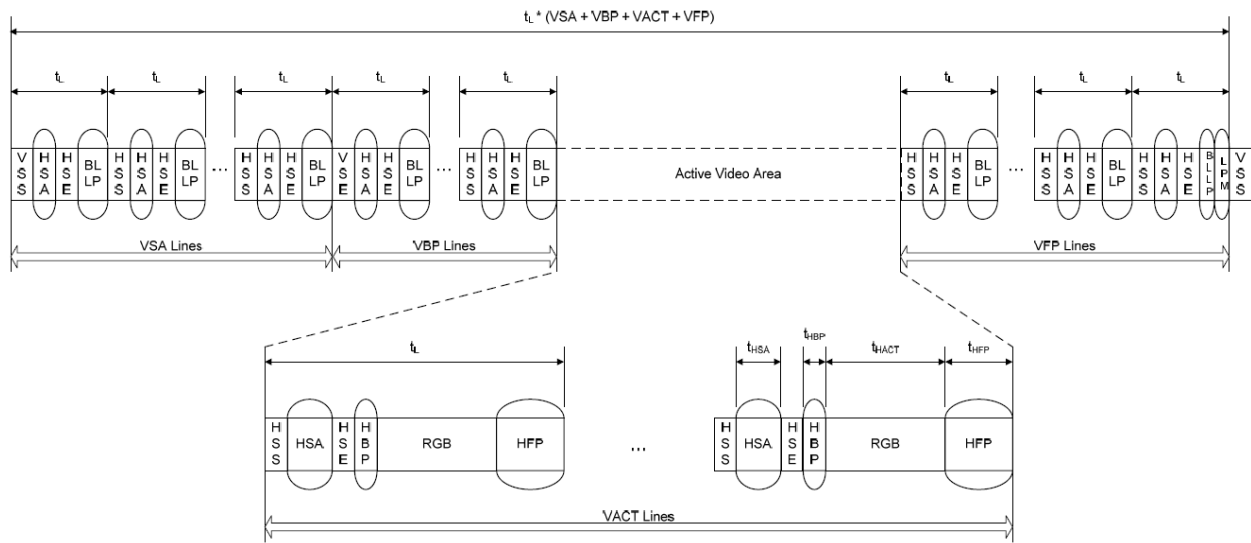
Generic Short Read Response: This is the short-packet response to Generic READ Request. Packet composition is the Data Identifier (DI) byte, two bytes of payload data and an ECC byte. If the command itself is possibly corrupt, due to an uncorrectable ECC error, SoT or SoT Sync error, the requested READ data packet shall not be sent and only the Acknowledge and Error Report packet shall be sent.

Generic long read response: This is the long-packet response to Generic READ Request. Packet composition is DI followed by a two-byte Word Count, an ECC byte, N bytes of payload, and a two-byte Checksum. If the command itself is possibly corrupt, due to an uncorrectable ECC error, SoT or SoT Sync error, the requested READ data packet shall not be sent and only the Acknowledge and Error Report packet shall be sent.

DCS long read response: This is a Long packet response to DCS Read Request. Packet composition is DI followed by a two-byte Word Count, an ECC byte, N bytes of payload, and a two-byte Checksum. If the DCS command itself is possibly corrupt, due to uncorrectable ECC error, SoT or SoT Sync error, the requested READ data packet shall not be sent and only the Acknowledge and Error Report packet shall be sent.

DCS short read response: This is the short-packet response to DCS Read Request. Packet composition is DI, two bytes of payload data and an ECC byte. If the command itself is possibly corrupt, due to an uncorrectable ECC error, SoT or SoT Sync error, the requested READ data packet shall not be sent and only the Acknowledge and Error Report packet shall be sent.

5.12 DSI Video Mode Interface Timing



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5.13 Error Correction Code (ECC)

ECC shall always be generated and appended in the Packet Header from the host processor. Peripherals with Bidirectional Links shall also generate and send ECC.

The number of parity or error check bits required is given by the Hamming rule, which uses parity to correct a single-bit error or detect a two-bit error, but are not capable of doing both simultaneously. DSI uses Hamming-modified codes where an extra parity bit is used to support both single error correction as well as two-bit error detection.

Since Packet Headers are fixed at four bytes (twenty-four data bits and eight ECC bits), P6 and P7 of the ECC byte are unused and shall be set to zero by the transmitter. The receiver shall ignore P6 and P7 and set both bits to zero before processing ECC.

The parity bits of ECC are defined as below:

P7 = 0

P6 = 0

P5 = $D10 \oplus D11 \oplus D12 \oplus D13 \oplus D14 \oplus D15 \oplus D16 \oplus D17 \oplus D18 \oplus D19 \oplus D21 \oplus D22 \oplus D23$

P4 = $D4 \oplus D5 \oplus D6 \oplus D7 \oplus D8 \oplus D9 \oplus D16 \oplus D17 \oplus D18 \oplus D19 \oplus D20 \oplus D22 \oplus D23$

P3 = $D1 \oplus D2 \oplus D3 \oplus D7 \oplus D8 \oplus D9 \oplus D13 \oplus D14 \oplus D15 \oplus D19 \oplus D20 \oplus D21 \oplus D23$

P2 = $D0 \oplus D2 \oplus D3 \oplus D5 \oplus D6 \oplus D9 \oplus D11 \oplus D12 \oplus D15 \oplus D18 \oplus D20 \oplus D21 \oplus D22$

P1 = $D0 \oplus D1 \oplus D3 \oplus D4 \oplus D6 \oplus D8 \oplus D10 \oplus D12 \oplus D14 \oplus D17 \oplus D20 \oplus D21 \oplus D22 \oplus D23$

P0 = $D0 \oplus D1 \oplus D2 \oplus D4 \oplus D5 \oplus D7 \oplus D10 \oplus D11 \oplus D13 \oplus D16 \oplus D20 \oplus D21 \oplus D22 \oplus D23$

The table below shows a compact way to specify the encoding of parity and decoding of syndromes.

ECC Parity Generation Rules:

Data Bit	P7	P6	P5	P4	P3	P2	P1	P0	Hex
0	0	0	0	0	0	1	1	1	0x07
1	0	0	0	0	1	0	1	1	0x0B
2	0	0	0	0	1	1	0	1	0x0D
3	0	0	0	0	1	1	1	0	0x0E
4	0	0	0	1	0	0	1	1	0x13
5	0	0	0	1	0	1	0	1	0x15
6	0	0	0	1	0	1	1	0	0x16
7	0	0	0	1	1	0	0	1	0x19
8	0	0	0	1	1	0	1	0	0x1A
9	0	0	0	1	1	1	0	0	0x1C
10	0	0	1	0	0	0	1	1	0x23
11	0	0	1	0	0	1	0	1	0x25
12	0	0	1	0	0	1	1	0	0x26
13	0	0	1	0	1	0	0	1	0x29
14	0	0	1	0	1	0	1	0	0x2A
15	0	0	1	0	1	1	0	0	0x2C
16	0	0	1	1	0	0	0	1	0x31
17	0	0	1	1	0	0	1	0	0x32
18	0	0	1	1	0	1	0	0	0x34
19	0	0	1	1	1	0	0	0	0x38
20	0	0	0	1	1	1	1	1	0x1F
21	0	0	1	0	1	1	1	1	0x2F
22	0	0	1	1	0	1	1	1	0x37
23	0	0	1	1	1	0	1	1	0x3B

5.14 Notice

1. We recommend users to stay in STOP state for 500ns when switching from LPDT to HSDT.
2. We recommend users to adopt EoTp to enhance overall robustness of the system during HSDT.

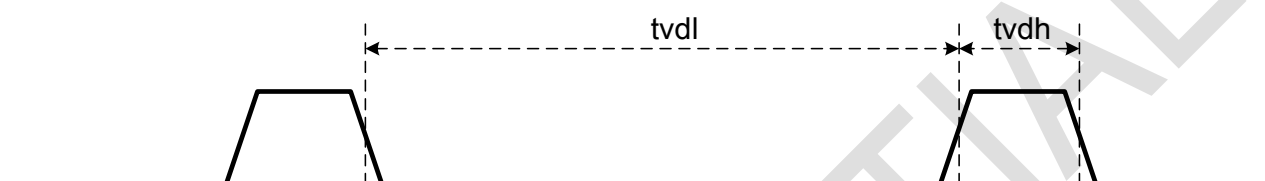
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5.15 Tearing Effect Output

The tearing effect output line supplies to the HOST a panel synchronization signal. This signal can be enabled or disabled by the `set_tear_off` (34h) and `set_tear_on` (35h) commands. The mode of the tearing effect signal is defined by the parameter of the `set_tear_on` (35h) and `set_tear_scanline`(44h) commands. The signal can be used by the HOST to synchronize internal VSYNC when displaying video images.

5.15.1 Tearing Effect Line Mode

Mode 1, the tearing effect output signal consists of V-sync information only:



tvdh = The display is not updated from the frame memory.

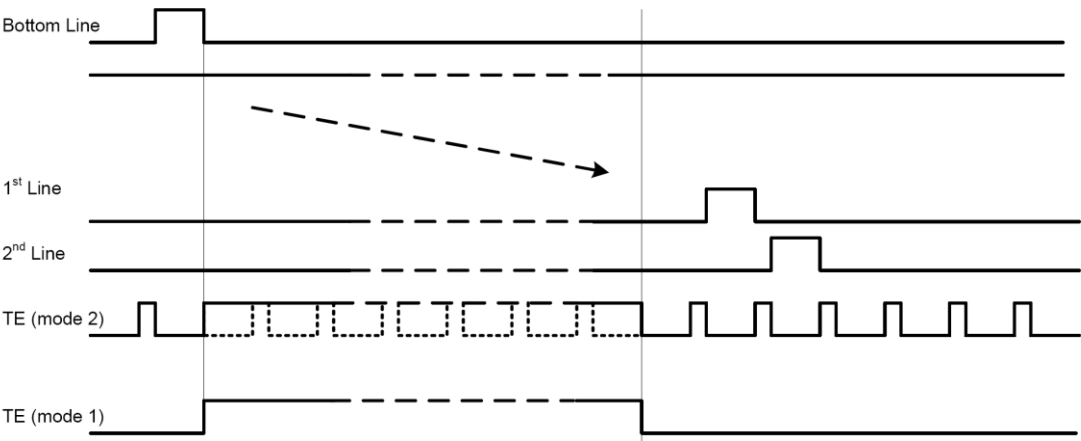
tvdl = The display is updated from the frame memory.

Mode 2, the tearing effect output signal consists of V-sync and H-sync information:



thdh = The display is not updated from the frame memory.

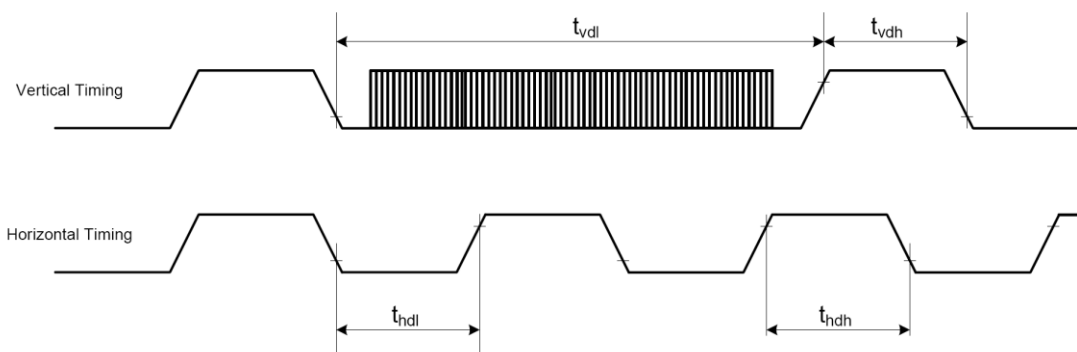
thdl = The display is updated from the frame memory.



Note. During Sleep In mode, the tearing effect output signal is active low.

5.15.2 Tearing Effect Line Timing

The tearing effect signal is described as below:

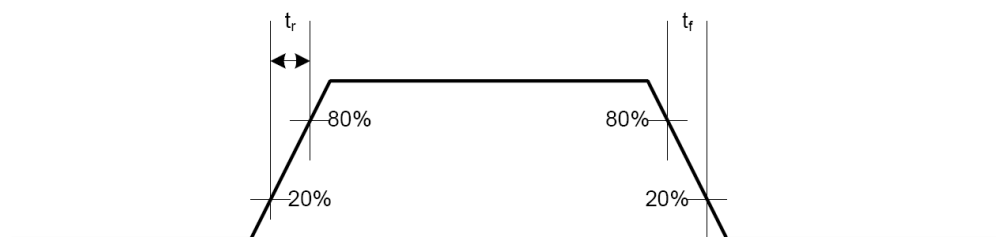


AC characteristics of Tearing Effect Signal (Frame Rate = 60Hz)

Symbol	Parameter	Min.	Max.	Unit	Description
t_{vdl}	Vertical timing low duration	TBD	TBD	ms	It depends on the vertical timing setting.
t_{vdh}	Vertical timing high duration	TBD	TBD	us	It depends on the vertical timing setting.
t_{hdl}	Horizontal timing low duration	TBD	TBD	us	It depends on the horizontal timing setting.
t_{hdh}	Horizontal timing high duration	1.8	TBD	us	

Notes:

The signal's rise and fall times (t_f , t_r) are stipulated to be equal to or less than 15ns.



The Tearing Effect Output Line is fed back to the HOST and should be used as shown below to avoid tearing effect:

The Tearing Effect output line supplies to the HOST a panel synchronization signal. This signal can be enabled or disabled by the `set_tear_off(34h)`, `set_tear_on(35h)` commands. The mode of the Tearing Effect Signal is defined by the Parameter of the Tearing Effect Line On command. The signal can be used by the HOST to synchronize internal VSYNC when displaying video images.

TEON (35h)	TELOM (35h, 1 st bit)	TE signal Output
0	*	GND
1	0	TE (Mode 1)
1	1	TE (Mode 2)

6. Command

6.1 Command List

Command			W/R	Function	D7	D6	D5	D4	D3	D2	D1	D0	Default (hex)	MTP
Page	Add.	Para.												
CMD1	00h	-	W	NOP	No Argument								-	-
CMD1	01h	-	W	Software reset	No Argument								-	-
CMD1	04h	1st	R	Read display identification information	ID1[7:0]								00h	-
CMD1	04h	2nd			ID2[7:0]								80h	-
CMD1	04h	3rd			ID3[7:0]								00h	-
CMD1	05h	-	R	Read number of the errors on DSI	P[7:0]								00h	-
CMD1	0Ah	1st	R	Read display power mode	BSTON	IDMON	PTLON	SLPOUT	NORON	DISPON	-	-	08h	-
CMD1	0Bh	1st	R	Read display MADCTR	-	MX	-	-	RGB	-	-	-	00h	-
CMD1	0Ch	1st	R	Read display pixel format	SPI_IFPF_SEL	VIPF2	VIPF1	VIPF0	-	IFPF2	IFPF1	IFPF0	77h	-
CMD1	0Dh	1st	R	Read display image mode	0	0	INVON	ALLPON	ALLPOFF	0	0	0	00h	-
CMD1	0Eh	1st	R	Read display signal mode	TEON	M	0	0	0	0	0	ERR	00h	-
CMD1	0Fh	1st	R	Read display self-diagnostic result	0	0	0	0	0	0	0	checksum_comp	00h	-
CMD1	10h	-	W	Sleep-in	No Argument								-	-
CMD1	11h	-	W	Sleep-out	No Argument								-	-
CMD1	12h	-	W	Partial display mode on	No Argument								-	-
CMD1	13h	-	W	Normal display mode on	No Argument								-	-
CMD1	20h	-	W	Display inversion off	No Argument								-	-
CMD1	21h	-	W	Display inversion on	No Argument								-	-
CMD1	22h	-	W	All pixel off	No Argument								-	-
CMD1	23h	-	W	All pixel on	No Argument								-	-
CMD1	28h	-	W	Display off	No Argument								-	-
CMD1	29h	-	W	Display on	No Argument								-	-
CMD1	2Ah	1st	W	Set column start address	SC[9:8]								00h	-
CMD1		2nd	W		SC[7:0]								00h	-
CMD1		3rd	W		EC[9:8]								01h	-
CMD1		4th	W		EC[7:0]								DFh	-
CMD1	2Bh	1st	W	Set row start address	SP[9:8]								00h	-
CMD1		2nd	W		SP[7:0]								00h	-
CMD1		3rd	W		EP[9:8]								01h	-
CMD1		4th	W		EP[7:0]								DFh	-
CMD1	2Ch	-	W	Memory write	No Argument								-	-
CMD1	30h	1st	W	Partial area	SR[9:8]								00h	-
CMD1		2nd	W		SR[7:0]								00h	-
CMD1		3rd	W		ER[9:8]								01h	-
CMD1		4th	W		ER[7:0]								DFh	-
CMD1	31h	1st	W	Vertical partial area	PSC[9:8]								00h	-
CMD1		2nd	W		PSC[7:0]								00h	-
CMD1		3rd	W		PEC[9:8]								01h	-
CMD1		4th	W		PEC[7:0]								DFh	-
CMD1	34h	-	W	Tearing effect line off	No Argument								-	-
CMD1	35h	-	W	Tearing effect line on	0	0	0	0	0	0	TE_M	TELOM	00h	-
CMD1	36h	-	W	Scan direction control	MADCTR[7:0]								00h	-
CMD1	38h	-	W	Idle mode off	No Argument								-	-
CMD1	39h	-	W	Enter idle mode	No Argument								-	-
CMD1	3Ah	-	W	Interface Pixel Format	SPI_IFPF_SEL	VIPF2	VIPF1	VIPF0	0	IFPF[2]	IFPF[1]	IFPF[0]	77h	-
CMD1	3Ch	-	W	Memory Continuous Write	No Argument								-	-
CMD1	44h	1st	W	Set tear scan-line	STS[15:8]								00h	-
CMD1		2nd	W		STS[7:0]								00h	-
CMD1	45h	1st	R	Get scan line	GTS[15:8]								00h	-

CMD1		2nd	R		GTS[7:0]								00h	-
CMD1	4Fh	-	W	Deep standby	0	0	0	0	0	0	0	DSTB	00h	-
CMD1	51h	-	W	Write display brightness	DBV[7:0]								00h	-
CMD1	52h	-	R	Read display brightness	DBV[7:0]								00h	-
CMD1	53h	-	W	Write CTRL display	0	0	BCTRL	0	DD	0	0	0	28h	-
CMD1	54h	-	R	Read CTRL display	0	0	BCTRL	0	DD	0	0	0	28h	-
CMD1	55h	-	W	Write RAD_ACL function	0	0	0	0	0	0	RAD_ACL[1:0]		00h	
CMD1	56h	-	R	Read RAD_ACL function	0	0	0	0	0	0	RAD_ACL[1:0]		00h	
CMD1	63h	-	W	Write HBM display brightness	DBV_HBM[7:0]								00h	
CMD1	64h	-	R	Read HBM display brightness	DBV_HBM[7:0]								00h	
CMD1	66h		W	HBM enable	-	-	-	-	-	-	HBM_en	-	00h	
CMD1	67h		W	Frame Level Control	0	0	Normal_LEVEL[1:0]		0	0	IDLE_LEVEL[1:0]		00h	
CMD1	70h	1st	W	COLSET	R_0000[7:0]								00h	
CMD1		2nd	W	COLSET	G_0000[7:0]								00h	
CMD1		3rd	W	COLSET	B_0000[7:0]								00h	
CMD1	71h	1st	W	COLSET	R_0001[7:0]								00h	
CMD1		2nd	W	COLSET	G_0001[7:0]								00h	
CMD1		3rd	W	COLSET	B_0001[7:0]								FFh	
CMD1	72h	1st	W	COLSET	R_0010[7:0]								00h	
CMD1		2nd	W	COLSET	G_0010[7:0]								FFh	
CMD1		3rd	W	COLSET	B_0010[7:0]								00h	
CMD1	73h	1st	W	COLSET	R_0011[7:0]								00h	
CMD1		2nd	W	COLSET	G_0011[7:0]								FFh	
CMD1		3rd	W	COLSET	B_0011[7:0]								FFh	
CMD1	74h	1st	W	COLSET	R_0100[7:0]								FFh	
CMD1		2nd	W	COLSET	G_0100[7:0]								00h	
CMD1		3rd	W	COLSET	B_0100[7:0]								00h	
CMD1	75h	1st	W	COLSET	R_0101[7:0]								FFh	
CMD1		2nd	W	COLSET	G_0101[7:0]								00h	
CMD1		3rd	W	COLSET	B_0101[7:0]								FFh	
CMD1	76h	1st	W	COLSET	R_0110[7:0]								FFh	
CMD1		2nd	W	COLSET	G_0110[7:0]								FFh	
CMD1		3rd	W	COLSET	B_0110[7:0]								00h	
CMD1	77h	1st	W	COLSET	R_0111[7:0]								FFh	
CMD1		2nd	W	COLSET	G_0111[7:0]								FFh	
CMD1		3rd	W	COLSET	B_0111[7:0]								FFh	
CMD1	78h	1st	W	COLSET	R_1000[7:0]								00h	
CMD1		2nd	W	COLSET	G_1000[7:0]								00h	
CMD1		3rd	W	COLSET	B_1000[7:0]								00h	
CMD1	79h	1st	W	COLSET	R_1001[7:0]								00h	
CMD1		2nd	W	COLSET	G_1001[7:0]								00h	
CMD1		3rd	W	COLSET	B_1001[7:0]								FFh	
CMD1	7Ah	1st	W	COLSET	R_1010[7:0]								00h	
CMD1		2nd	W	COLSET	G_1010[7:0]								FFh	
CMD1		3rd	W	COLSET	B_1010[7:0]								00h	
CMD1	7Bh	1st	W	COLSET	R_1011[7:0]								00h	
CMD1		2nd	W	COLSET	G_1011[7:0]								FFh	
CMD1		3rd	W	COLSET	B_1011[7:0]								FFh	
CMD1	7Ch	1st	W	COLSET	R_1100[7:0]								FFh	
CMD1		2nd	W	COLSET	G_1100[7:0]								00h	
CMD1		3rd	W	COLSET	B_1100[7:0]								00h	
CMD1	7Dh	1st	W	COLSET	R_1101[7:0]								FFh	
CMD1		2nd	W	COLSET	G_1101[7:0]								00h	
CMD1		3rd	W	COLSET	B_1101[7:0]								FFh	
CMD1	7Eh	1st	W	COLSET	R_1110[7:0]								FFh	
CMD1		2nd	W	COLSET	G_1110[7:0]								FFh	
CMD1		3rd	W	COLSET	B_1110[7:0]								00h	

CMD1		1st	W	COLSET	R_1111[7:0]								FFh	
CMD1	7Fh	2nd	W	COLSET	G_1111[7:0]								FFh	
CMD1		3rd	W	COLSET	B_1111[7:0]								FFh	
CMD1	80h	1st	W	COLOPT	-	RGB111_o pt	-	RGB565_ swap	RGB4bit_ en	gray256_col or[2]	gray256_c olor[1]	gray256_ color[0]	07h	
CMD1	A1h	1st	R	Read DDB	SID[7:0]								D0h	-
CMD1		2nd	R		SID[15:8]								01h	-
CMD1		3rd	R		MID[7:0]								80h	-
CMD1		4th	R		MID[15:8]								90h	-
CMD1		5th	R		1	1	1	1	1	1	1	1	FFh	-
CMD1	A8h	1st	R	Read DDB Continuous	SID[7:0]								D0h	-
CMD1		2nd	R		SID[15:8]								01h	-
CMD1		3rd	R		MID[7:0]								80h	-
CMD1		4th	R		MID[15:8]								90h	-
CMD1		5th	R		1	1	1	1	1	1	1	1	FFh	-
CMD1	AAh	-	R	Read first checksum	FCS[7:0]								00h	-
CMD1	AFh	-	R	Read continuous checksum	CCS[7:0]								00h	-
CMD1	C2h			Set_DSIP Mode	0	0	0	0	0	0	DM1	DM0	00h	-
CMD1	C4h			Set_DSPI Mode	SPI_WRA M	0	DSPI_CFG 1	DSPI_CFG 0	0	0	0	DSPI_EN	00h	-
CMD1	DAh	-	R	Read display identification information (the same as 04h)	ID1[7:0]								00h	-
CMD1	DBh	-	R		ID2[7:0]								80h	-
CMD1	DCh	-	R		ID3[7:0]								00h	-
CMD1	FEh	-	W	Write CMD mode page	CMD_Page[7:0]								00h	-
CMD1	FFh	-	R	Read CMD page Status	CMD_Status[7:0]								00h	-

6.2 Command Description

NOP (0000h)

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	0000h	No Argument								

Description	This command is an empty command; it does not have any effect on the display module. X = Don't care.
Restriction	None

SWRESET(0100h) : Software Reset

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	0100h	No Argument								

Description	When the Software Reset command is written, it causes software reset. It resets the commands and parameters to their S/W Reset default values. (See default tables in each command description.)
Restriction	Software Reset Command cannot be sent during Sleep Out sequence. Any new command cannot be sent for 10-frame period until the RM690C0 enters Sleep-In mode. Do not send any command.

RDDID(0400h~0402h) : Read Display ID

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0400h	ID17	ID16	ID15	ID14	ID13	ID12	ID11	ID10	00
	0401h	ID27	ID26	ID25	ID24	ID23	ID22	ID21	ID20	80
	0402h	ID37	ID36	ID35	ID34	ID33	ID32	ID31	ID30	00

Description	<p>The 1st parameter (ID1): the Module's manufacture ID The 2nd parameter (ID2): the Module/driver version ID The 3rd parameter (ID3): the Module/driver ID Note: Commands RDID1/2/3 (DAh/DBh/DCh) read data correspond to the parameter 1, 2, 3 of command 04h, respectively.</p>									
Restriction	-									

RDNUMED(0500h) : Read Number of Errors on DSI

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0500h	D7	D6	D5	D4	D3	D2	D1	D0	00

Description	<p>The first parameter is telling a number of the parity errors on DSI. The more detailed description of the bits is below.</p> <p>D[6..0] bits are telling a number of the parity errors.</p> <p>D[7] is set to "1" if there is overflow with D[6..0] bits.</p> <p>D[7..0] bits are set to "0"s (as well as RDDSM(0Eh)'s D0 are set "0" at the same time) after there is sent the first parameter information (= The read function is completed).</p> <p>This command is used for MIPI DSI only. It is no function for others interface operation.</p>
Restriction	-

RDDPM (0A00h) : Read Display Power Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0A00h	D7	D6	D5	D4	D3	D2	D1	D0	08

Description	This command indicates the current status of the display as described in the table below:									
	Bit	Symbol	Description				Comment			
	D7	BSTON	Booster Voltage Status				'1'=Booster on, '0'=Booster off			
	D6	IDMON	Idle Mode On/Off				'1' = Idle Mode On, '0' = Idle Mode Off			
	D5	PTLON	Partial Mode On/Off				'1' = Partial Mode On, '0' = Partial Mode Off			
	D4	SLPON	Sleep In/Out				'1' = Sleep Out, '0' = Sleep In			
	D3	NORON	Display Normal Mode On/Off				'1' = Normal Display, '0' = Partial Display			
	D2	DISON	Display On/Off				'1' = Display On, '0' = Display Off			
	D1	Reserved					0			
	D0	Reserved					0			

RDDMADCTR (0B00h): Read Display MADCTR

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0B00h	D7	D6	D5	D4	D3	D2	D1	D0	00

Description	This command indicates the current status of the display as described in the table below:									
	Bit	Symbol	Description				Comment			
	D6	MX	Column Address Increment				0: Increasing in horizontal 1: Decreasing in horizontal			
	D3	RGB	RGB/BGR Order				'1' =BGR, "0"=RGB			
	others	Reserved	-				-			

RDDCOLMOD (0C00h): Read Display Pixel Format

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0C00h	SPI_IFPF_SEL	VIPF[2]	VIPF[1]	VIPF[0]	0	IFPF[2]	IFPF[1]	IFPF[0]	77

To return the status of 0x3A00.

This command sets the pixel format for the RGB image data used by the interface.

If SPI_IFPF_SEL(3Ah-D7) = 1:

The SPI/QSPI interface will use VIPF[2:0] as pixel format setting specifically, and the other interface will use IFPF[2:0].

If SPI_IFPF_SEL(3Ah-D7) = 0:

All interface will use IFPF[2:0] as pixel format setting

Control Interface Color Format	IFPF[2]	IFPF[1]	IFPF[0]
SPI 8 bit/pixel (256 colors); SPI 256 Gray (Support IF: SPI3/SPI4)	0	0	1
SPI 8 bit/pixel (256 colors); SPI 3-3-2 (Support IF: SPI3/SPI4)	0	1	0
SPI 3 bit/pixel (8 colors); SPI 1-1-1 (Support IF: SPI3/SPI4)	0	1	1
16bit/pixel (65,536 colors)	1	0	1
18bit/pixel (262,144 colors)	1	1	0
24bit/pixel (16.7M colors)	1	1	1

Description

To return the status of 0x3A00.

This command sets the pixel format for the RGB image data used by the interface.

If SPI_IFPF_SEL(3Ah-D7) = 1:

The SPI/QSPI interface will use VIPF[2:0] as pixel format setting specifically, and the other interface will use IFPF[2:0].

If SPI_IFPF_SEL(3Ah-D7) = 0:

All interface will use IFPF[2:0] as pixel format setting

Control Interface Color Format	IFPF[2]	IFPF[1]	IFPF[0]
SPI 8 bit/pixel (256 colors); SPI 256 Gray (Support IF: SPI3/SPI4)	0	0	1
SPI 8 bit/pixel (256 colors); SPI 3-3-2 (Support IF: SPI3/SPI4)	0	1	0
SPI 3 bit/pixel (8 colors); SPI 1-1-1 (Support IF: SPI3/SPI4)	0	1	1
16bit/pixel (65,536 colors)	1	0	1
18bit/pixel (262,144 colors)	1	1	0
24bit/pixel (16.7M colors)	1	1	1

RDDIM (0D00h): Read Display Image Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0D00h	D7	D6	D5	D4	D3	D2	D1	D0	00

Description	The display module returns the display image mode status.									
	Bit	Symbol	Description			Comment				
	D7	Reserved				'0'				
	D6	Reserved				'0'				
	D5	INVON	Inversion On/Off			"1" = Inversion is On, "0" = Inversion is Off				
	D4	ALLON	All Pixel On			'0' = Normal display '1' = White display				
	D3	ALLOFF	All Pixel Off			'0' = Normal display '1' = Black display				
	D2~D0	Reserved				'000'				

RDDSM (0E00h): Read Display Signal Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0E00h	D7	D6	D5	D4	D3	D2	D1	D0	00

Description	The display module returns the Display Signal Mode.			
	Bit	Symbol	Description	Comment
	D7	TEON	Tearing Effect Line On/Off	"1" = On, "0" = Off
	D6	TELOM	Tearing effect line mode	"0" = mode1, "1" = mode2
	D5	Reserved		'0'
	D4	Reserved		'0'
	D3	Reserved		'0'
	D2	Reserved		'0'
	D1	Reserved		'0'
	D0	Error on DSI	Error on DSI	'0' = No Error '1' = Error

RDDSDR (0F00h): Read Display Self-Diagnostic Result

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	0F00h	0	0	0	0	0	0	0	checksum_comp	00

Description	The display module returns the self-diagnostic results following a Sleep Out command.									
	Bit	Symbol	Description						Comment	
	D0	Reserved	checksum_comp						'0'	

SLPIN (1000h): Sleep In

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	1000h	No Argument								

Description	<p>This command causes the display module to enter the minimum power consumption mode. In this mode the DC/DC converter is stopped, Internal display oscillator is stopped, and panel scanning is stopped. The control Interface such as registers is still working and keeps its values.</p>
Restriction	<p>This command has no effect when the display module is already in Sleep mode. Sleep In Mode can only be exit by the Sleep Out Command (11h). It must wait 5msec before sending next command for the supply voltages and clock circuits to stabilize. It must wait 120msec after sending Sleep Out command (when in Sleep In Mode) before Sleep In command can be sent.</p>

SLPOUT (1100h): Sleep Out

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	1100h	No Argument								

Description	This command causes the display module to exit Sleep mode.
Restriction	<p>This command shall not cause any visible effect on the display device when the display module is not in Sleep mode. The host processor must wait five milliseconds after sending this command before sending another command. This delay allows the supply voltages and clock circuits to stabilize.</p> <p>The host processor must wait 60 milliseconds after sending a Sleep Out command before sending a Sleep-In command. The display module loads the display module's default values to the registers when exiting the Sleep mode. There shall not be any abnormal visual effect on the display device when loading the registers if the factory default and register values are the same or when the display module is not in Sleep mode. The display module runs the self-diagnostic functions after this command is received.</p>

PTLON (1200h): Partial Display Mode On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	1200h	No Argument								

Description	This command causes the display module to enter the Partial Display Mode. The Partial Display Mode window is described by the Partial Area (30h) command. To leave Partial Display Mode, the Normal Display Mode On (13h) command should be written.
Restriction	This command has no effect when Partial Display Mode is already active.

NORON (1300h): Normal Display Mode On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	1300h	No Argument								

Description	This command causes the display module to enter the Normal mode. Normal Mode is defined as Partial Display mode.
Restriction	This command has no effect when Normal Display mode is already active.

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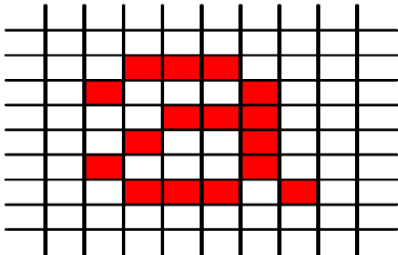

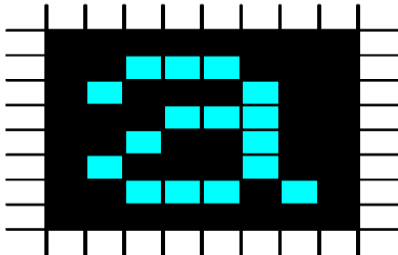
INVOFF (2000H): Display Inversion Off

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2000h	No Argument								

Description	<p>This command causes the display module to stop inverting the image data on the display device. No status bits are changed.</p> <div style="display: flex; align-items: center; justify-content: center;"> <div style="text-align: center;"> <p>Input Image</p> </div> <div style="margin: 0 20px; font-size: 2em;">→</div> <div style="text-align: center;"> <p>Display Panel</p> </div> </div>
	<p>Restriction This command has no effect when the display module is not inverting the display image.</p>

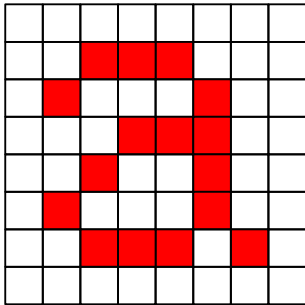
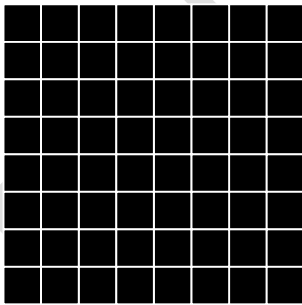
INVON (2100H): Display Inversion On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2100h	No Argument								

Description	<p>This command causes the display module to invert the image data only on the display device. No status bits are changed.</p> <div><div><p>Input Image</p></div><div></div><div><p>Display Panel</p></div></div>
	<p>Restriction This command has no effect when module is already in inversion on mode.</p>

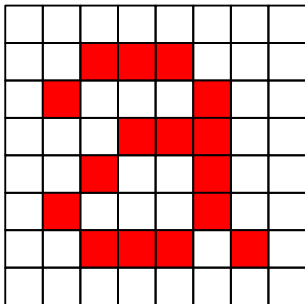
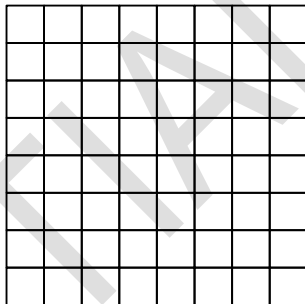
ALLPOFF (2200H): All Pixel Off

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2200h	No Argument								

Description	<p>This command turns the display panel black in Sleep Out mode and a status of the Display On/Off register can be on or off. This command does not change any other status.</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>Input Image</p>  </div> <div style="font-size: 2em;">→</div> <div style="text-align: center;"> <p>Display Panel</p>  </div> </div> <p>“All Pixels On”, “Normal Display Mode On” or “Partial Mode On” commands are used to leave this mode. The display panel is showing the content of the Input Image after “Normal Display On” and “Partial Mode On” commands.</p>
	<p>Restriction -</p>

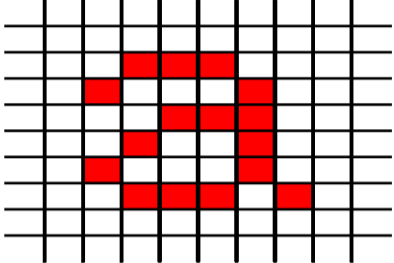
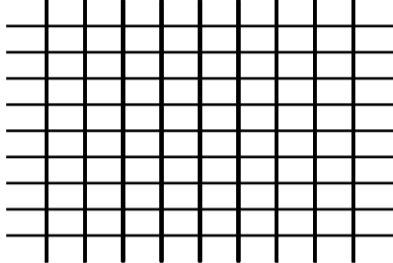
ALLPON (2300H): All Pixel On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2300h	No Argument								

Description	<p>This command turns the display panel white in Sleep Out mode and a status of the Display On/Off register can be on or off. This command does not change any other status.</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>Input Image</p>  </div> <div style="font-size: 2em;">→</div> <div style="text-align: center;"> <p>Display Panel</p>  </div> </div> <p>“All Pixels Off”, “Normal Display Mode On” or “Partial Mode On” commands are used to leave this mode. The display panel is showing the content of the Input Image after “Normal Display On” and “Partial Mode On” commands.</p>
	Restriction -

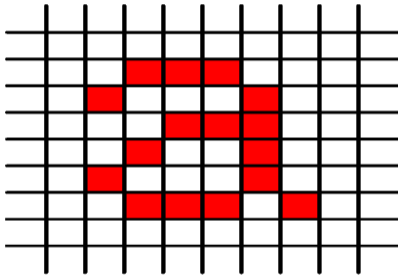
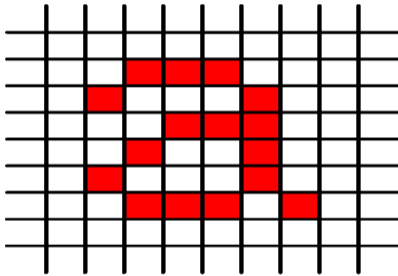
DISPOFF (2800h): Display Off

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2800h	No Argument								

Description	<p>This command causes the display module to stop displaying the image data on the display device. No status bits are changed.</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;"> <p>Input Image</p>  </div> <div style="font-size: 2em; margin: 0 20px;">→</div> <div style="text-align: center;"> <p>Display Panel</p>  </div> </div>									
	<p>Restriction This command has no effect when module is already in display off mode.</p>									

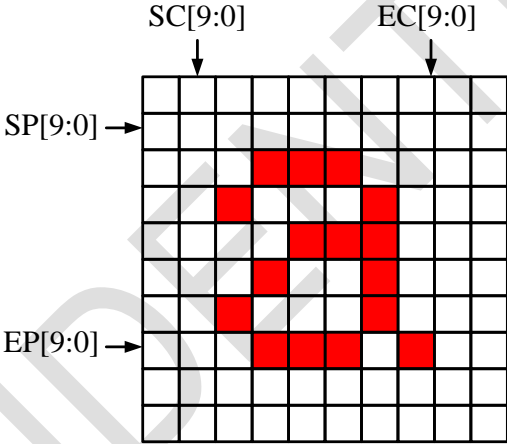
DISPON (2900h): Display On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2900h	No Argument								

Description	<p>This command causes the display module to start displaying the image data on the display device. No status bits are changed.</p> <div style="display: flex; align-items: center; justify-content: center;"> <div style="text-align: center;"> <p>Input Image</p>  </div> <div style="margin: 0 20px; font-size: 2em;">→</div> <div style="text-align: center;"> <p>Display Panel</p>  </div> </div>
	<p>Restriction This command has no effect when module is already in display on mode.</p>

CASET(2A00h~2A03h) : Set Column Start Address

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2A00h	-	-	-	-	-	-	SC9	SC8	00
	2A01h	SC7	SC6	SC5	SC4	SC3	SC2	SC1	SC0	00
	2A02h	-	-	-	-	-	-	EC9	EC8	01
	2A03h	EC7	EC6	EC5	EC4	EC3	EC2	EC1	EC0	DF

Description	<p>This command defines the column extent of the frame memory accessed by the host processor with the read_memory_continue and write_memory_continue commands. This command makes no change on the other driver status. The values of SC[9:0] and EC[9:0] are referred when RAMWR command comes. Each value represents one column line in the Frame Memory.</p> 
Restriction	<p>(1) SC[9:0] always must be equal to or less than EC[9:0].</p> <p>(2) The SC[9:0] and EC[9:0]-SC[9:0]+1 must can be divisible by 2.</p>

RASET(2B00h~2B03h) : Set Row Start Address

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2B00h	-	-	-	-	-	-	SP9	SP8	00
	2B01h	SP7	SP6	SP5	SP4	SP3	SP2	SP1	SP0	00
	2B02h	-	-	-	-	-	-	EP9	EP8	01
	2B03h	EP7	EP6	EP5	EP4	EP3	EP2	EP1	EP0	DF

Description	<p>This command defines the page extent of the frame memory accessed by the host processor with the write_memory_continue and read_memory_continue command.</p> <p>This command makes no change on the other driver status. The values of SP[9:0] and EP[9:0] are referred when RAMWR command comes. Each value represents one Page line in the Frame Memory.</p> <div data-bbox="598 801 1161 1294"> </div>
Restriction	<p>(1) SP[9:0] always must be equal to or less than EP[9:0]</p> <p>(2) The SP[9:0] and EP[9:0]-SP[9:0]+1 must be divisible by 2.</p>

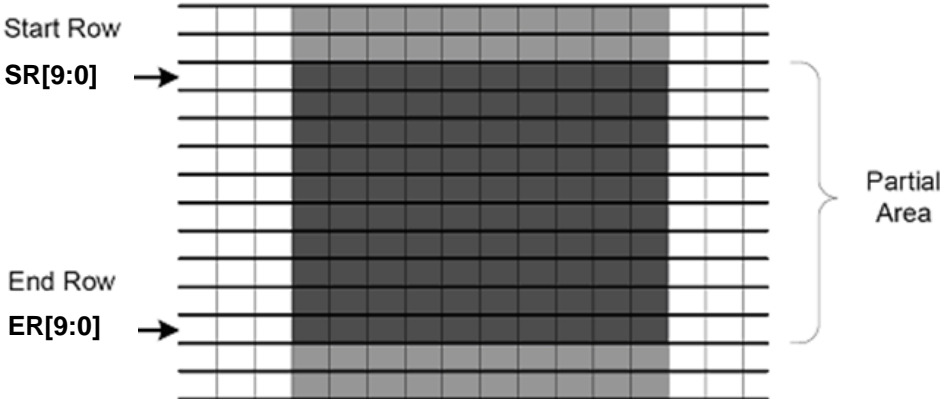
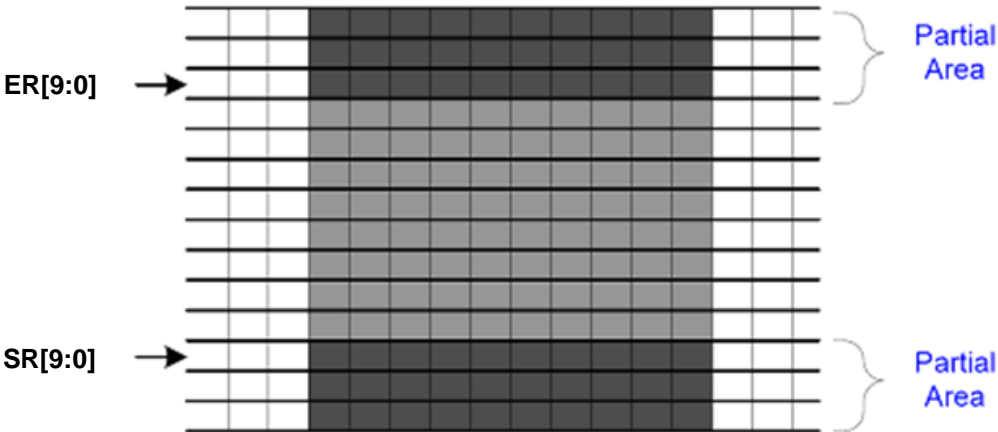
RAMWR (2C00h): Memory Write

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	2C00h	0	0	1	0	1	1	0	0	2C
	1 st Pixel	D ₁₇	D ₁₆	D ₁₅	D ₁₄	D ₁₃	D ₁₂	D ₁₁	D ₁₀	
	:	:	:	:	:	:	:	:	:	
	N th Pixel	D _{N7}	D _{N6}	D _{N5}	D _{N4}	D _{N3}	D _{N2}	D _{N1}	D _{N0}	

Description	This command transfers image data from the host processor to the display module's frame memory starting at the pixel location specified by preceding CASET (2Ah) and RASET (2Bh) commands.
Restriction	A Memory Write should follow a CASET(2Ah), RASET(2Bh) or MADCTR(36h) to define the write location. Otherwise, data written with RAMWR(2Ch) and any following RAMWRC(3Ch) commands is written to undefined locations.

PTLAR (3000h): Partial Area

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3000h	-	-	-	-	-	-	SR9	SR8	00
	3001h	SR7	SR6	SR5	SR4	SR3	SR2	SR1	SR0	00
	3002h	-	-	-	-	-	-	ER9	ER8	01
	3003h	ER7	ER6	ER5	ER4	ER3	ER2	ER1	ER0	DF

Description	<p>This command defines the Partial Display mode's display area. There are two parameters associated with this command, the first defines the Start Row (SR) and the second the End Row (ER), as illustrated in the following figure.</p> <p>If End Row > Start Row</p>  <p>If End Row < Start Row</p>  <p>If End Row = Start Row then the Partial Area will be one row deep.</p>
Restriction	SR[9:0] and ER[9:0] settings should be within max available Display Area.

PTLAR (3100h): Vertical Partial Area

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3100h	-	-	-	-	-	-	-	SC8	00
	3101h	SC7	SC6	SC5	SC4	SC3	SC2	SC1	SC0	00
	3102h	-	-	-	-	-	-	-	EC8	01
	3103h	EC7	EC6	EC5	EC4	EC3	EC2	EC1	EC0	DF

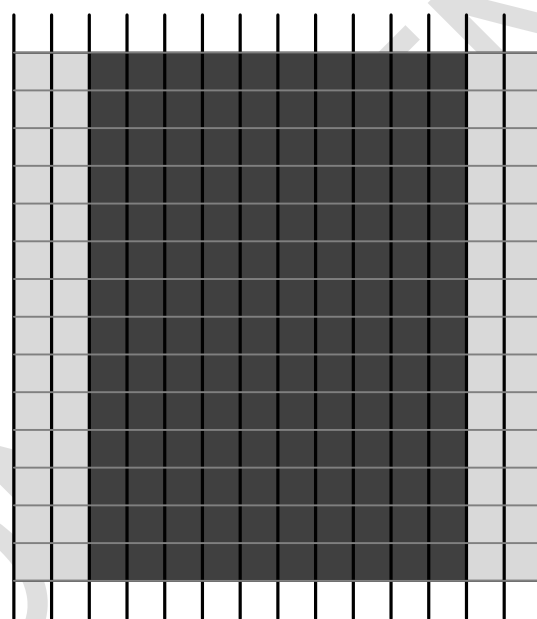
Description

This command defines the Vertical Partial Display mode's display area. There are two parameters associated with this command, the first defines the Start Column (SC) and the second the End Column (EC), as illustrated in the following figure.

If End Column > Start Column

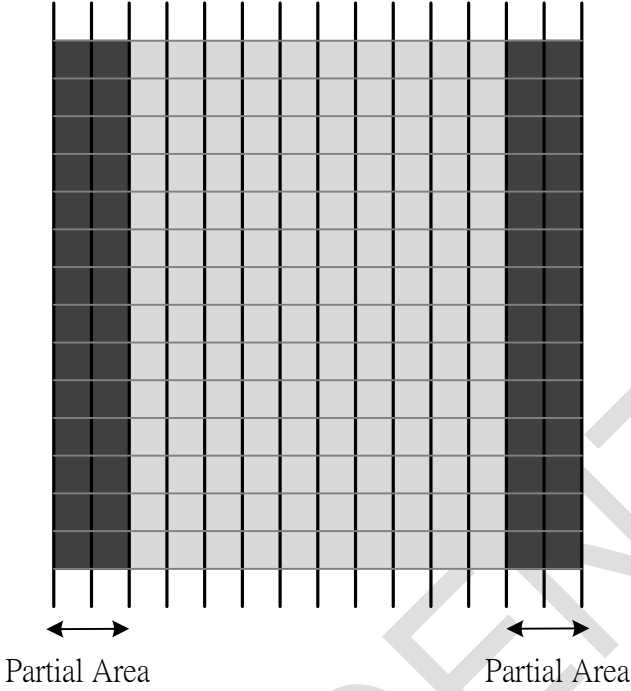
Start Column
SC[9:0]

End Column
EC[9:0]



Partial Area

If End Column < Start Column

	<div><p>End Column EC[9:0]</p><p>Start Column SC[9:0]</p><p>Partial Area</p><p>Partial Area</p><p>If End Column = Start Column then the Partial Area will be one column deep.</p></div>
Restriction	SC[9:0] and EC[9:0] settings should be within max available Display Area.

TEOFF (3400h): Tearing Effect Line OFF

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3400h	No Argument								

Description	This command turns off the display module's Tearing Effect output signal on the TE signal line.
Restriction	This command has no effect when the Tearing Effect output is already off.

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R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3500h	0	0	0	0	0	0	TE_M	TELOM	00

Bit	Symbol	Description	Comment
D1	TE_M	Output mode of TE signal set	1: Refresh frame active <Note> TE output active at refresh frame to avoid tearing effect, command can be set: 1. 0x3500=00.or 2. 0x3500=02.
D0	TELOM	Output mode of TE signal	0:only V-blanking 1:V-blanking +H-blanking

If TELOM = 0:

The Tearing Effect Output line consists of V-Blanking information only.



```

If TELOM = 1:

```

The Tearing Effect Output Line consists of both V-Blanking and H-Blanking information.



The Tearing Effect Output line shall be active low when the display module is in Sleep mode.

This command has no effect when Tearing Effect output is already ON.

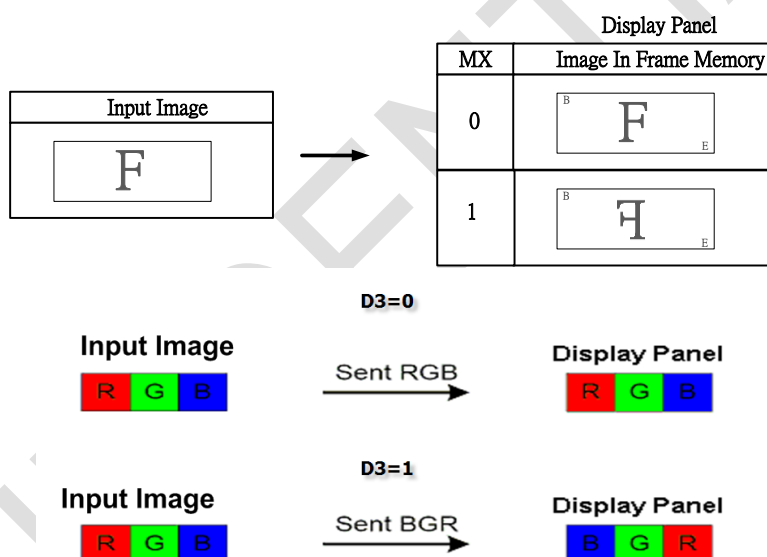
MADCTR (3600h): Scan Direction Control

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3600h	D7	D6	D5	D4	D3	D2	D1	D0	00

This command defines the scan direction of Source and Gate Driver. This command makes no change on the other driver status.

Bit	Symbol	Description	Comment
D7	Reserved		
D6	MX	Column Address Increment	0: Increasing in horizontal 1: Decreasing in horizontal
D3	RGB	RGB/BGR Order	'1' =BGR, "0"=RGB
D2	Reserved		
D1	Reserved		
D0	Reserved		

Description



Restriction

IDMOFF (3800h): Idle Mode Off

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3800h	No Argument								

Description	This command causes the display module to exit Idle mode.
Restriction	This command has no effect when the display module is not in Idle mode.

IDMON (3900h): Enter_idle_mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3900h	No Argument								

Description	This command causes the display module to enter Idle Mode.
Restriction	This command has no effect when module is already in idle on mode.

COLMOD (3A00h): Interface Pixel Format

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3A00h	SPI_IFPF_SEL	VIPF[2]	VIPF[1]	VIPF[0]	0	IFPF[2]	IFPF[1]	IFPF[0]	77

Description	This command sets the pixel format for the RGB image data used by the interface.																															
	If SPI_IFPF_SEL(3Ah-D7) = 1:																															
	The SPI/QSPI interface will use VIPF[2:0] as pixel format setting individually, and the other interface will use IFPF[2:0].																															
	If SPI_IFPF_SEL(3Ah-D7) = 0:																															
	All interface use IFPF[2:0] as pixel format setting																															
	<table><tr><th>Control Interface Color Format</th><th>IFPF[2]</th><th>IFPF[1]</th><th>IFPF[0]</th></tr><tr><td>SPI 8 bit/pixel (256 colors); SPI 256 Gray (Support IF: SPI3/SPI4)</td><td>0</td><td>0</td><td>1</td></tr><tr><td>SPI 8 bit/pixel (256 colors); SPI 3-3-2 (Support IF: SPI3/SPI4)</td><td>0</td><td>1</td><td>0</td></tr><tr><td>SPI 3 bit/pixel (8 colors); SPI 1-1-1 (Support IF: SPI3/SPI4)</td><td>0</td><td>1</td><td>1</td></tr><tr><td>16bit/pixel (65,536 colors)</td><td>1</td><td>0</td><td>1</td></tr><tr><td>18bit/pixel (262,144 colors)</td><td>1</td><td>1</td><td>0</td></tr><tr><td>24bit/pixel (16.7M colors)</td><td>1</td><td>1</td><td>1</td></tr></table>				Control Interface Color Format	IFPF[2]	IFPF[1]	IFPF[0]	SPI 8 bit/pixel (256 colors); SPI 256 Gray (Support IF: SPI3/SPI4)	0	0	1	SPI 8 bit/pixel (256 colors); SPI 3-3-2 (Support IF: SPI3/SPI4)	0	1	0	SPI 3 bit/pixel (8 colors); SPI 1-1-1 (Support IF: SPI3/SPI4)	0	1	1	16bit/pixel (65,536 colors)	1	0	1	18bit/pixel (262,144 colors)	1	1	0	24bit/pixel (16.7M colors)	1	1	1
	Control Interface Color Format	IFPF[2]	IFPF[1]	IFPF[0]																												
	SPI 8 bit/pixel (256 colors); SPI 256 Gray (Support IF: SPI3/SPI4)	0	0	1																												
SPI 8 bit/pixel (256 colors); SPI 3-3-2 (Support IF: SPI3/SPI4)	0	1	0																													
SPI 3 bit/pixel (8 colors); SPI 1-1-1 (Support IF: SPI3/SPI4)	0	1	1																													
16bit/pixel (65,536 colors)	1	0	1																													
18bit/pixel (262,144 colors)	1	1	0																													
24bit/pixel (16.7M colors)	1	1	1																													
Restriction																																

RAMWRC (3C00h): Memory Continuous Write

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	3C00h	0	0	1	1	1	1	0	0	3C
	1 st Pixel	D ₁₇	D ₁₆	D ₁₅	D ₁₄	D ₁₃	D ₁₂	D ₁₁	D ₁₀	
	:	:	:	:	:	:	:	:	:	
	N th Pixel	D _{N7}	D _{N6}	D _{N5}	D _{N4}	D _{N3}	D _{N2}	D _{N1}	D _{N0}	

Description	This command transfers image data from the host processor to the display module's frame memory continuing from the pixel location following the previous write_memory_continue or write_memory_start command.
Restriction	A Memory Write should follow a CASET(2Ah), RASET(2Bh) or MADCTR(36h) to define the write location. Otherwise, data written with RAMWR(2Ch) and any following RAMWRC(3Ch) commands is written to undefined locations.

STESL(4400h) : Set_Tear_Scanline

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	4400h	STS[15]	STS[14]	STS[13]	STS[12]	STS[11]	STS[10]	STS[9]	STS[8]	00
	4401h	STS[7]	STS[6]	STS[5]	STS[4]	STS[3]	STS[2]	STS[1]	STS[0]	00

Description	<p>This command turns on the display Tearing Effect output signal on the TE signal line when the display reaches line N. The TE signal is not affected by changing set_address_mode bit B4. The Tearing Effect Line On has one parameter that describes the Tearing Effect Output Line mode.</p> <p>The Tearing Effect Output line shall be active low when the display module is in Sleep mode.</p>
	Restriction

DSTBON (4F00h): Deep Standby Mode On

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	4F00h	0	0	0	0	0	0	0	DSTB	00

Description	<p>This command is used to enter deep standby mode. DSTB="1", enter deep standby mode.</p> <p>Notes:</p> <ol style="list-style-type: none"> 1. To exit Deep Standby Mode, input low pulse more than 3 msec to pin RESX. 2. For MIPI IF, if deep standby mode is used, please pull HSSI_CLK_P/N & HSSI_D0~D1_P/N to GND after executing deep standby command.
Restriction	

WRDISBV (5100h): Write Display Brightness

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	5100h	DBV7	DBV6	DBV5	DBV4	DBV3	DBV2	DBV1	DBV0	00

Description	This command is used to adjust brightness value. In principle relationship is that 00h value means the lowest brightness and FFh value means the highest brightness.
Restriction	The display supplier cannot use this command for tuning

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RDDISBV (5200h): Read Display Brightness

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	5200h	DBV7	DBV6	DBV5	DBV4	DBV3	DBV2	DBV1	DBV0	00

Description	This command returns brightness value. In principle relationship is that 00h value means the lowest brightness and FFh value means the highest brightness.
Restriction	-

WRCTRLD (5300h): Write Display Control

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	5300h	0	0	BCTRL	0	DD	0	0	0	28

Description	BCTRL: Brightness control ,1=enable DD: Display dimming control ,1=enable
Restriction	The display supplier cannot use this command for tuning

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RDCTRLD (5400h): Read Display Control

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	5400h	0	0	BCTRL	0	DD	0	0	0	28

Description	BCTRL: Brightness control ,1=enable DD: Display dimming control ,1=enable
Restriction	-

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WRRADACL (5500h): RAD_ACL Control

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	5500h	0	0	0	0	0	0	RAD_ACL[1:0]		00

Description	This command is used to control Raydium specific function for ACL (Auto Current Limit) RAD_ACL[1:0]=11, Enable Raydium ACL function. RAD_ACL[1:0]=00, Disable Raydium ACL function.
Restriction	-

COLORTEMP (5500h): Color Temperature Selection

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	5500h	0	0	0	0	color_temp_sel[1:0]		0	0	00

Description	This command is used to select color temperature setting color_temp_sel = 0 : Choose color temperature 1 configuration color_temp_sel = 1 : Choose color temperature 2 configuration color_temp_sel = 2 : Choose color temperature 3 configuration
Restriction	-

WRDISBV (6300h): Write HBM Display Brightness

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	6300h	DBV_HBM[7:0]								00

Description	This command is used to adjust brightness value in HBM mode if hbm_gidx_type=1.
Restriction	DBV_HBM[7:0] setting value must be greater than G_ratio_HBM_swap value.

RDDISBV (6400h): Read HBM Display Brightness

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	6400h	DBV_HBM[7:0]								00

Description	This command returns brightness value in HBM mode.
Restriction	-

HBM_Mode (6600h) : Set_HBM_Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	6600h	0	0	0	0	0	0	HBM_en	0	00

Description	HBM_en = 1, This command causes the display module to enter HBM mode (exit normal, idle) HBM_en = 0, This command causes the display module to exit HBM mode (to normal mode)
Restriction	under display area

FR_LEVEL (6700h) : Frame Rate Level Control

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R/W	6700h	0	0	Normal_Level[1:0]		0	0	Idle_level[1:0]		00

Description	This command is used to select Raydium specific display scenario in normal mode and IDLE mode (ex: frame-rate).		
	Bit	Description	Data
	Normal_level[1:0]	Normal mode display scenario setting	0: Normal mode base level 1: Normal mode level 1 2: Normal mode level 2 3: Normal mode level 3 Others: Reserved
	Idle_level[1:0]	IDLE mode display scenario setting	0: IDLE mode base level 1: IDLE mode level 1 2: IDLE mode level 2 Others: Reserved
Restriction	under display area		

DFR_EN (6800h) : Dynamic Frame Rate Enable

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R/W	6800h	0	W_dynf_en_A	W_dynf_en_B	0	0	0	0	0	00

Description	This command is used to enable dynamic frame rate function									
	<p>W_dynf_en_A: 1: Enable dynamic frame rate switching between pre-configured level in normal mode 0: Disable dynamic frame rate function in normal mode</p> <p>W_dynf_en_B: 1: Enable dynamic frame rate switching between pre-configured level in IDLE mode 0: Disable dynamic frame rate function in IDLE mode</p>									
Restriction										

COLSET (7000~7F00h): Interface Pixel Format Set

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	7000h	R_0000[7:0]								00
	7001h	G_0000[7:0]								00
	7002h	B_0000[7:0]								00
W	7100h	R_0001[7:0]								00
	7101h	G_0001[7:0]								00
	7102h	B_0001[7:0]								FF
W	7200h	R_0010[7:0]								00
	7201h	G_0010[7:0]								FF
	7202h	B_0010[7:0]								00
W	7300h	R_0011[7:0]								00
	7301h	G_0011[7:0]								FF
	7302h	B_0011[7:0]								FF
W	7400h	R_0100[7:0]								FF
	7401h	G_0100[7:0]								00
	7402h	B_0100[7:0]								00
W	7500h	R_0101[7:0]								FF
	7501h	G_0101[7:0]								00
	7502h	B_0101[7:0]								FF
W	7600h	R_0110[7:0]								FF
	7601h	G_0110[7:0]								FF
	7602h	B_0110[7:0]								00
W	7700h	R_0111[7:0]								FF
	7701h	G_0111[7:0]								FF
	7702h	B_0111[7:0]								FF
W	7800h	R_1000[7:0]								00
	7801h	G_1000[7:0]								00
	7802h	B_1000[7:0]								00
W	7900h	R_1001[7:0]								00
	7901h	G_1001[7:0]								00
	7902h	B_1001[7:0]								FF
W	7A00h	R_1010[7:0]								00
	7A01h	G_1010[7:0]								FF
	7A02h	B_1010[7:0]								00
W	7B00h	R_1011[7:0]								00
	7B01h	G_1011[7:0]								FF
	7B02h	B_1011[7:0]								FF
W	7C00h	R_1100[7:0]								FF
	7C01h	G_1100[7:0]								00
	7C02h	B_1100[7:0]								00
W	7D00h	R_1101[7:0]								FF
	7D01h	G_1101[7:0]								00
	7D02h	B_1101[7:0]								FF
W	7E00h	R_1110[7:0]								FF

W	7E01h	G_1110[7:0]	FF
	7E02h	B_1110[7:0]	00
	7F00h	R_1111[7:0]	FF
	7F01h	G_1111[7:0]	FF
	7F02h	B_1111[7:0]	FF

This command set the 1-1-1 color format map directly to 24 bits by CMD 7000h-7F00h

RGB111 color mapping	R[7:0]	G[7:0]	B[7:0]
0000 (70h)	R_0000[7:0]	G_0000[7:0]	B_0000[7:0]
0001 (71h)	R_0001[7:0]	G_0001[7:0]	B_0001[7:0]
0010 (72h)	R_0010[7:0]	G_0010[7:0]	B_0010[7:0]
0011 (73h)	R_0011[7:0]	G_0011[7:0]	B_0011[7:0]
0100 (74h)	R_0100[7:0]	G_0100[7:0]	B_0100[7:0]
0101 (75h)	R_0101[7:0]	G_0101[7:0]	B_0101[7:0]
0110 (76h)	R_0110[7:0]	G_0110[7:0]	B_0110[7:0]
0111 (77h)	R_0111[7:0]	G_0111[7:0]	B_0111[7:0]
1000 (78h)	R_1000[7:0]	G_1000[7:0]	B_1000[7:0]
1001 (79h)	R_1001[7:0]	G_1001[7:0]	B_1001[7:0]
1010 (7Ah)	R_1010[7:0]	G_1010[7:0]	B_1010[7:0]
1011 (7Bh)	R_1011[7:0]	G_1011[7:0]	B_1011[7:0]
1100 (7Ch)	R_1100[7:0]	G_1100[7:0]	B_1100[7:0]
1101 (7Dh)	R_1101[7:0]	G_1101[7:0]	B_1101[7:0]
1110 (7Eh)	R_1110[7:0]	G_1110[7:0]	B_1110[7:0]
1111 (7Fh)	R_1111[7:0]	G_1111[7:0]	B_1111[7:0]

Description

Restriction

COLOPT (8000h): Interface Pixel Format Option

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	8000h	x	RGB111_opt	x	RGB565_swap	RGB4bit_en	gray256_col or[2]	gray256_col or[1]	gray256_col or[0]	07

Description

This command sets the 1-1-1/256 gray color format option used by SPI interface.

RGB111_opt = 0 (80h-B6):

Supporting in IFPF[2:0]=011 case setting by 3A00h (interface pixel format is SPI 1-1-1).

RGB 1-1-1 Bit	DCX	D[7]	D[6]	D[5]	D[4]	D[3]	D[2]	D[1]	D[0]	Note
CMDWR	0	0	0	0	0	0	0	0	0	0x2C for GRAM Write
1st RAM Data Write	1	x	x	R1[0]	G1[0]	B1[0]	R2[0]	G2[0]	B2[0]	1,2 pixel Data Write
2nd RAM Data Write	1	x	x	R3[0]	G3[0]	B3[0]	R4[0]	G4[0]	B4[0]	3,4 pixel Data Write
3rd RAM Data Write	1	x	x	R5[0]	G5[0]	B5[0]	R6[0]	G6[0]	B6[0]	5,6 pixel Data Write
So on...										

RGB111_opt = 1 (80h-B6):

Supporting in IFPF[2:0]=011 case setting by 3A00h (interface pixel format is SPI 1-1-1).

RGB 1-1-1 Bit	DCX	D[7]	D[6]	D[5]	D[4]	D[3]	D[2]	D[1]	D[0]	Note
CMDWR	0	0	0	0	0	0	0	0	0	0x2C for GRAM Write
1st RAM Data Write	1	x	R1[0]	G1[0]	B1[0]	x	R2[0]	G2[0]	B2[0]	1,2 Pixel Data Write
2nd RAM Data Write	1	x	R3[0]	G3[0]	B3[0]	x	R4[0]	G4[0]	B4[0]	3,4 Pixel Data Write
3rd RAM Data Write	1	x	R5[0]	G5[0]	B5[0]	x	R6[0]	G6[0]	B6[0]	5,6 Pixel Data Write
So on...										

RGB565_swap = 0 (80h-B4):

The input order is R[4:0], G[5:0], B[4:0].

RGB565_swap = 1 (80h-B4):

The input order is G[2:0], B[4:0], R[4:0], G[5:3].

RGB4bit_en = 0 (80h-B3):

Supporting in IFPF[2:0]=011 case setting by 3A00h (interface pixel format is SPI 1-1-1).

Three bits per pixel formats map directly to 24bits by CMD 7000h-7700h

RGB 1-1-1 Bit	DCX	D[7]	D[6]	D[5]	D[4]	D[3]	D[2]	D[1]	D[0]	Note
CMDWR	0	0	0	0	0	0	0	0	0	0x2C for GRAM Write
1st RAM Data Write	1	x	x	P1[2]	P1[1]	P1[0]	P2[2]	P2[1]	P2[0]	1,2 Pixel Data Write
2nd RAM Data Write	1	x	x	P3[2]	P3[1]	P3[0]	P4[2]	P4[1]	P4[0]	3,4 Pixel Data Write
3rd RAM Data Write	1	x	x	P5[2]	P5[1]	P5[0]	P6[2]	P6[1]	P6[0]	5,6 Pixel Data Write
So on...										

RDDDBS(A100h) : Read_DDB_Start

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	A100h	SID[7]	SID [6]	SID [5]	SID [4]	SID [3]	SID [2]	SID [1]	SID [0]	D0
	A101h	SID[15]	SID[14]	SID[13]	SID[12]	SID[11]	SID[10]	SID[9]	SID[8]	01
	A102h	MID[7]	MID[6]	MID[5]	MID[4]	MID[3]	MID[2]	MID[1]	MID[0]	80
	A103h	MID[15]	MID[14]	MID[13]	MID[12]	MID[11]	MID[10]	MID[9]	MID[8]	90
	A104h	1	1	1	1	1	1	1	1	FF

Description	1 st parameter: Supplier ID code 2 nd parameter: Supplier ID code 3 rd parameter: Module ID 4 th parameter: Module ID 5 th Exit code (FFh).
Restriction	

RDDDBC(A800h) : Read DDB Continous

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	A800h	SID[7]	SID [6]	SID [5]	SID [4]	SID [3]	SID [2]	SID [1]	SID [0]	D0
	A801h	SID[15]	SID[14]	SID[13]	SID[12]	SID[11]	SID[10]	SID[9]	SID[8]	01
	A802h	MID[7]	MID[6]	MID[5]	MID[4]	MID[3]	MID[2]	MID[1]	MID[0]	80
	A803h	MID[15]	MID[14]	MID[13]	MID[12]	MID[11]	MID[10]	MID[9]	MID[8]	90
	A804h	1	1	1	1	1	1	1	1	FF

Description	<p>This command returns the supplier identification and display module mode/revision information from the point where RDDDBS command was interrupted by an other command.</p> <p><i>Note: Parameter 0xFF is an "Exit Code", this means that there is no more data in the DDB block.</i></p> <p><i>Note: For use example,</i></p> <ol style="list-style-type: none"> 1. Set maximum return packet size=3 2. Read 0xA1, return 3 bytes SID[7:0], SID[15:8], MID[7:0] 3. Read 0xA8, return 2 bytes MID[15:8], and 0xFF
Restriction	<p>A Read DDB Start command (RDDDBS) should be executed at least once before a Read DDB Continue command (RDDDBC) to define the read location. Otherwise, data read with a Read DDB Continue command is undefined.</p>

RDFCS(AA00h) : Read First Checksum

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	AA00h	FCS7	FCS6	FCS5	FCS4	FCS3	FCS2	FCS1	FCS0	00

Description	This command returns the first checksum what has been calculated from “User Command Set” area registers (not include “Manufacture Command Set) and the frame memory after the write access to those registers and/or frame memory has been done.
Restriction	It will be necessary to wait 150ms after there is the last write access on “User Command Set” area registers before there can read this checksum value.

RDCCS(AF00h) : Read Continue Checksum

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	AF00h	CCS7	CCS6	CCS5	CCS4	CCS3	CCS2	CCS1	CCS0	00

Description	This command returns the continue checksum what has been calculated continuously after the first checksum has been calculated from "User Command Set" area registers and the frame memory after the write access to those registers and/or frame memory has been done.
Restriction	It will be necessary to wait 300ms after there is the last write access on "User Command Set" area registers before there can read this checksum value in the first time.

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SetDISPMode (C200h) : set_DISP Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	C200h	0	0	0	0	0	0	DM1	DM0	00

Description	Bit	Description	Value
	DM[1:0]	Display timing mode selection	2'b00: internal timing 2'b01: reserved 2'b10: reserved 2'b11: external timing (VSYNC + HSYNC align mode)
Restriction	<p>Note:</p> <p>(1) If video mode, need to set DM[1:0] = 2'b11.</p> <p>(2) System video mode parameter V-total and H-total setting has restriction, it must match driver IC V-total and H-total setting.</p> <p>Related video mode parameter settings suggest asking Raydium.</p>		

SetSPIMode (C400h) : set_SPI Mode

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	C400h	SPI_WRAM	0	DSPI_CFG 1	DSPI_CFG 0	0	0	0	DSPI_EN	00

Description	Bit	Description	Value
	DSPI_EN	DAUL SPI MODE Enable	0: disable 1: enable
	DSPI_CFG[1:0]	DAUL SPI MODE Selection	00: 1P1T for 1 wire 10: 1P1T for 2 wire 11: 2P3T for 2 wire 01: reserved
	SPI_WRAM	This command is used in SPI/SPINK interfaces. Making sure to set SPI_WRAM=1 before host writes SRAM via SPI/SPINK interfaces.	0: disable 1: SPI interface write RAM enable
Restriction			

RDID1 (DA00h): ID1 Code

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	DA00h	ID1[7:0]								00h

Description	This command is for Module Manufacture Number		
	Bit	Description	Data
	ID1[7:0]	Module Manufactor Number	
Restriction			

RDID2 (DB00h): ID2 Code

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	DB00h	ID2[7:0]								80h

Description	This command is for Module/Driver Version Number		
	Bit	Description	Data
	ID2[7:0]	Module/Driver Version Number	
Restriction			

RDID3 (DC00h): ID3 Code

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	DC00h	ID3[7:0]								00h

Description	This command is for Module / Driver ID		
	Bit	Description	Data
	ID3[7:0]	Module /Driver ID	
Restriction			

(FE00h): CMD Mode Switch

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
W	FE00h	CMD_Page[7:0]								00

Description	This command is used to switch the Manufacture Command Pages and User Commands sets.																																						
	<table><tr><th>CMD_Page[7:0]</th><th>Description</th></tr><tr><td>00h (default)</td><td>User Command Set (UCS = CMD1)</td></tr><tr><td>10h</td><td>Manufacture Command Set Page Panel ID</td></tr><tr><td>12h</td><td>Manufacture Command Set Page SID</td></tr><tr><td>20h</td><td>Manufacture Command Set Page Panel</td></tr><tr><td>40h</td><td>Manufacture Command Set Page ABH Mode</td></tr><tr><td>82h</td><td>Manufacture Command Set Page Power</td></tr><tr><td>92h</td><td>Manufacture Command Set Page SD timing</td></tr><tr><td>50h</td><td>Manufacture Command Set Page Gamma1</td></tr><tr><td>60h</td><td>Manufacture Command Set Page Gamma2</td></tr><tr><td>30h</td><td>Manufacture Command Set Page Gamma3</td></tr><tr><td>52h</td><td>Manufacture Command Set Page Gamma4</td></tr><tr><td>70h</td><td>Manufacture Command Set Page GOA Timing 1</td></tr><tr><td>F0h</td><td>Manufacture Command Set Page GOA Timing 2</td></tr><tr><td>42h</td><td>Manufacture Command Set Page DBV</td></tr><tr><td>22h</td><td>Manufacture Command Set Page SES</td></tr><tr><td>90h</td><td>Manufacture Command Set Page ACL</td></tr><tr><td>62h</td><td>Manufacture Command Set Page CGM</td></tr><tr><td>C2h</td><td>Manufacture Command Set Page CGM LUT</td></tr></table>	CMD_Page[7:0]	Description	00h (default)	User Command Set (UCS = CMD1)	10h	Manufacture Command Set Page Panel ID	12h	Manufacture Command Set Page SID	20h	Manufacture Command Set Page Panel	40h	Manufacture Command Set Page ABH Mode	82h	Manufacture Command Set Page Power	92h	Manufacture Command Set Page SD timing	50h	Manufacture Command Set Page Gamma1	60h	Manufacture Command Set Page Gamma2	30h	Manufacture Command Set Page Gamma3	52h	Manufacture Command Set Page Gamma4	70h	Manufacture Command Set Page GOA Timing 1	F0h	Manufacture Command Set Page GOA Timing 2	42h	Manufacture Command Set Page DBV	22h	Manufacture Command Set Page SES	90h	Manufacture Command Set Page ACL	62h	Manufacture Command Set Page CGM	C2h	Manufacture Command Set Page CGM LUT
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	40h	Manufacture Command Set Page ABH Mode																																					
	82h	Manufacture Command Set Page Power																																					
	92h	Manufacture Command Set Page SD timing																																					
	50h	Manufacture Command Set Page Gamma1																																					
	60h	Manufacture Command Set Page Gamma2																																					
	30h	Manufacture Command Set Page Gamma3																																					
	52h	Manufacture Command Set Page Gamma4																																					
	70h	Manufacture Command Set Page GOA Timing 1																																					
	F0h	Manufacture Command Set Page GOA Timing 2																																					
	42h	Manufacture Command Set Page DBV																																					
	22h	Manufacture Command Set Page SES																																					
	90h	Manufacture Command Set Page ACL																																					
	62h	Manufacture Command Set Page CGM																																					
C2h	Manufacture Command Set Page CGM LUT																																						
Restriction	-																																						

(FF00h): Read CMD Status

R/W	Address	D7	D6	D5	D4	D3	D2	D1	D0	HEX
R	FF00h	CMD_Status[7:0]								00

Description	This command is used to show the FE00h Manufacture Command Pages status.
Restriction	-

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7. Electrical Characteristics

7.1 Absolute Maximum Ratings

The absolute maximum rating is listed on following table. When RM690C0 is used out of the absolute maximum ratings, the RM690C0 may be permanently damaged. To use the RM690C0 within the following electrical characteristics limit is strongly recommended for normal operation. If these electrical characteristic conditions are exceeded during normal operation, the RM690C0 will malfunction and cause poor reliability.

item	Symbol	Value	Unit
Power supply voltage	VDDI	-0.3 ~ + 5.5	V
Power supply voltage	VDD (VDDA, VDDb, VDDR)	-0.3 ~ + 5.5	V
Supply voltage (MV)	AVDD- AVSS	-0.3 ~ + 6.6	V
	AVSS- VCL	-0.3 ~ + 5.0	V
Supply voltage (HV)	VGH- VGLX	-0.3 ~ + 33	V
Input voltage	VIN	-0.3 ~ VDDI+ 0.3	V
Output voltage	VO	-0.3 ~ VDDI+ 0.3	V
Operating temperature	Topr	-40 ~ + 85	°C
Storage temperature	Tstg	-55 ~ + 125	°C
Notes: If one of the above items is exceeded its maximum limitation momentarily, the quality of the product may be degraded. Absolute maximum limitation. Therefore, specify the values exceeding which the product may be physically damaged. Be sure to use the product within the recommend range.			

7.2 ESD Protection Level

Model	Test Condition	Level
Human Body Mode	R = 1.5 kohm / C = 100 pF	Pass 3KV
Machine Mode	R = 0 ohm / C = 200 pF	Pass 300V

7.3 Latch-Up Protection Level

The device will not latch up at trigger current levels less than ± 200 mA.

7.4 DC Characteristics

7.4.1 Basic Characteristics

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Related Pins
Analog Power Supply Voltage	VDD	Operation Voltage	2.7	2.8	3.6	V	Note 1
I/O pin Power Supply Voltage	VDDI	I/O supply voltage	1.65	1.8	3.3	V	Note 1,2
Logic High level input voltage	VIH	VDDI = 1.65V ~ 3.3V	0.8* VDDI	-	VDDI	V	Note 3
Logic Low level input voltage	VIL	VDDI = 1.65V ~ 3.3V	0.0	-	0.2* VDDI	V	Note 3
Logic High level Output voltage	VOH	I _{out} = -1 mA	0.8* VDDI	-	VDDI	V	Note 3
Logic Low level Output voltage	VOL	I _{out} = +1 mA	0.0	-	0.2* VDDI	V	Note 3
Logic High level input current (Except MIPI)	IIHD	V _{in} =0~VDDI			1	uA	Note 3
Logic Low level input current (Except MIPI)	IILD	V _{in} =0~VDDI	-1			uA	Note 3
Logic High level input current (MIPI)	IIHD	V _{in} =0~VDDI			1	uA	Note 3
Logic Low level input current (MIPI)	IILD	V _{in} =0~VDDI	-1			uA	Note 3
AVDD booster voltage	AVDD		4.5		6.5	V	Note 3
VCL booster voltage	VCL		-3.5		-5	V	Note 3
VGH booster voltage	VGH		AVDD		2xAVDD	V	Note 3
VGL booster voltage	VGL		VCL		2xVCL - AVDD	V	Note 3
Voltage difference between VGH and VGL	VGHL	VGH-VGL			30	V	Note 3
Gamma reference voltage	VGMP		2.0		6.3	V	Note 3,4
Gamma reference voltage	VGSP		0.0		4.5	V	Note 3
OSC	Fosc		22.08	24	25.92	MHz	
Channel deviation voltage	V _{DEV}	S _{out} ≥ AVDD-1.0V, and 0V < S _{out} ≤ 1.0V				mV	TBD
Channel deviation voltage	V _{DEV}	1.0V < S _{out} < AVDD-1.0V				mV	TBD

Notes:

1. VDD means VDDA, VDDR, Vddb. And VSS means VSSA, VSSR, VSSB, AVSS, VSSAM. Vddb, VDDA and VDDR should be the same input voltage level and larger than VDDI voltage.
2. Recommend VDDI=1.8V for power saving.
3. Ta(ambient temperature) ranges from -30℃ to 85℃.
4. VGMP ≤ AVDD - 0.2V

7.4.2 Operation Current

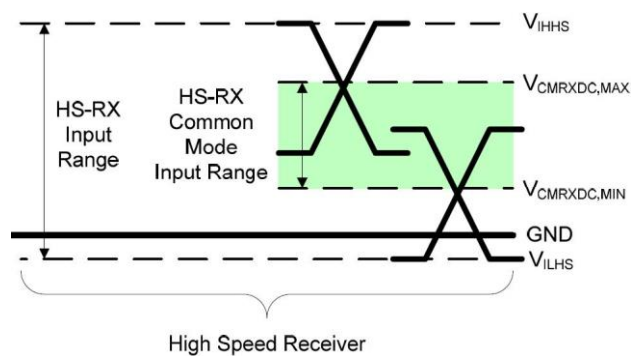
VCI=2.8V and VDDI=1.8V

Parameter	Symbol	Condition	Max.	Unit
Sleep In Mode	I_SLP_VCI	VDDI=VCC=1.8V VCI=VDDA=VDDDB=VDDR=2.8V	TBD	uA
	I_SLP_VDDI	HSSI_D0P/N=HSSI_D1P/N=HSSI_CKP/N=LP-11 Ta = 25deg	TBD	uA
Deep Standby Mode	I_DSTB_VCI	VDDI=VCC=1.8V VCI=VDDA=VDDDB=VDDR=2.8V	TBD	uA
	I_DSTB_VDDI	HSSI_D0P/N=HSSI_D1P/N=HSSI_CKP/N=0 Ta = 25deg	TBD	uA

7.5 MIPI Characteristics

7.5.1 High-Speed Receiver Specification

DC Specifications



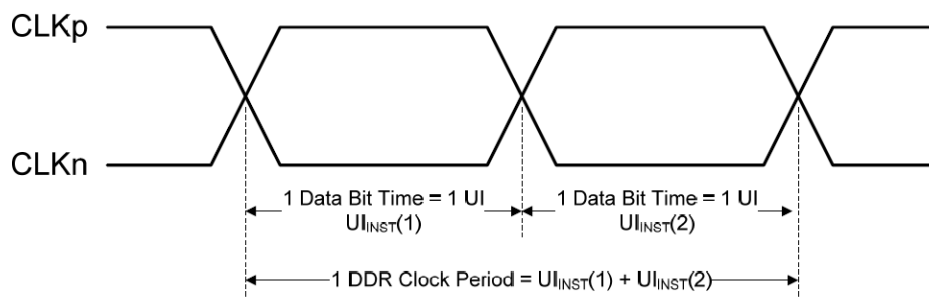
Parameter	Description	Min	Nom	Max	Units	Note
VCMRX(DC)	Common-mode voltage HS receive mode	70		330	mV	1,2
WIDTH	Differential input high threshold			70	mV	
VIDTL	Differential input low threshold	-70			mV	
VIHHS	Single-ended input high voltage			460	mV	1
VILHS	Single-ended input low voltage	-40			mV	1
ZID	Differential input impedance	80	100	125	Ω	

Notes:

1. Excluding possible additional RF interference of 100mV peak sine wave beyond 450MHz.
2. This table value includes a ground difference of 50mV between the transmitter and the receiver, the static common-mode level tolerance and variations below 450MHz

7.5.2 Forward high speed transmissions

DDR Clock Definition



Clock Parameter	Symbol	Min	Typ	Max	Units	Notes
UI instantaneous	UI _{INST}	1.818		12.5	ns	1,2

Notes:

1. This value corresponds to a minimum 80 Mbps data rate.
2. The minimum UI shall not be violated for any single bit period, i.e., any DDR half cycle within a data burst.

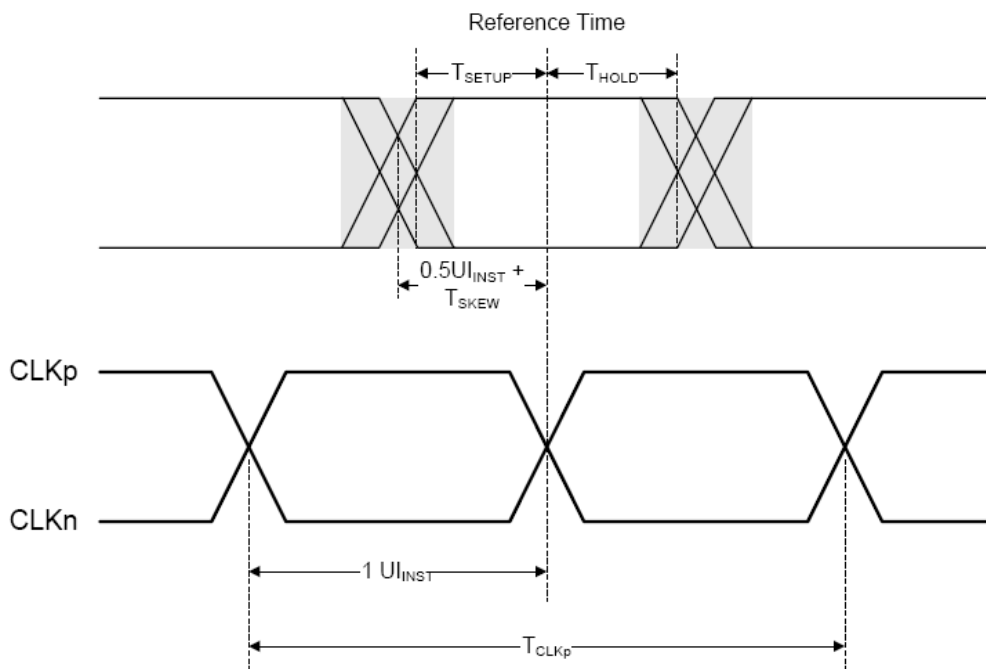
Data-Clock Timing Specifications

Parameter	Symbol	Min	Typ	Max	Units	Notes
Data to Clock Skew [measured at transmitter]	T _{SKEW[TX]}	-0.15		0.15	UI _{INST}	1
Data to Clock Setup Time [receiver]	T _{SETUP[RX]}	0.15			UI _{INST}	2
Clock to Data Hold Time [receiver]	T _{HOLD[RX]}	0.15			UI _{INST}	2

Notes:

1. Total silicon and package delay budget of 0.3*UI_{INST}
2. Total setup and hold window for receiver of 0.3*UI_{INST}

7.5.3 Data to Clock Timing Definitions



7.5.4 Low power transceiver specifications

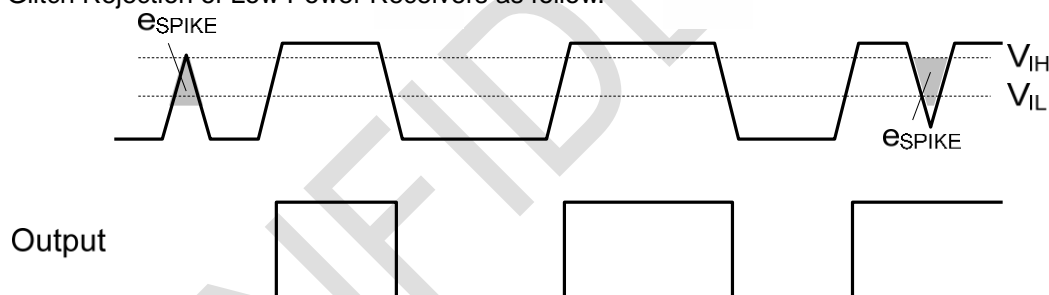
Parameters	Symbol	Condition	Min	Typ	Max	Unit
Logic high level input voltage	VIHCD	Contention Detection (Lane_D0)	450		1350	mV
Logic low level input voltage	VILCD	Contention Detection (Lane_D0)	0		200	mV
Logic high level input voltage	VIH-LPRX	LP-Rx (Lane_CK, Lane_D0, Lane_D1)	880	-	1350	mV
Logic low level input voltage	VIL-LPRX	LP-Rx (Lane_CK, Lane_D0, Lane_D1)	0		550	mV
Logic low level input voltage	VIL-ULPS	LP-Rx ULPS (Lane_CK, Lane_D0, Lane_D1)	0		300	mV
Logic high level input voltage	VOH-LPTX	Contention Detection (Lane_D0)	1.1	1.2	1.3	V
Logic low level input voltage	VOL-LPTX	Contention Detection (Lane_D0)	-50	0	50	mV
eSPIKE ^(1,2,3)	Fig. 2	Input pulse rejection			300	V.ps

Notes:

Time-voltage integration of a spike above VIL when being in LP-0 state or below VIH when being in LP-1 State. An impulse less than this will not change the receiver state.

In addition to the required glitch rejection, implementers shall ensure rejection of known RF-interferers.

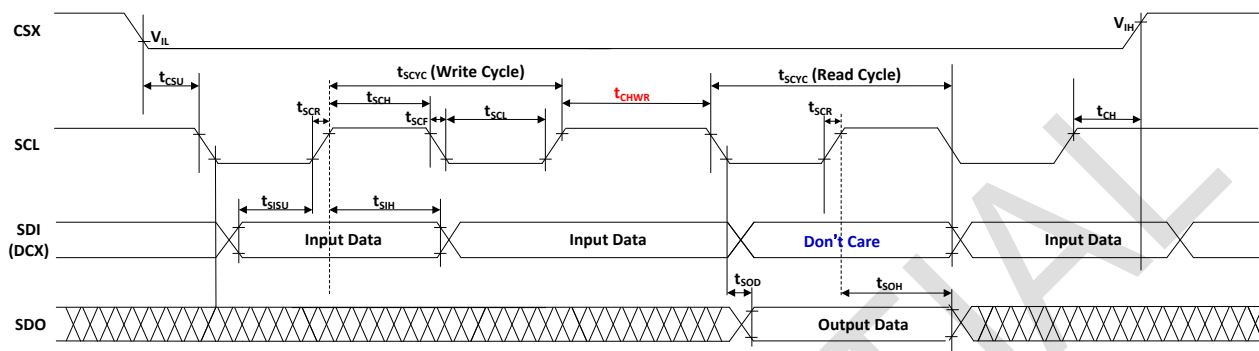
Input Glitch Rejection of Low Power Receivers as follow.



7.6 AC Characteristics

7.6.1 SPI/DUAL-SPI Characteristics

3/4-wire SPI

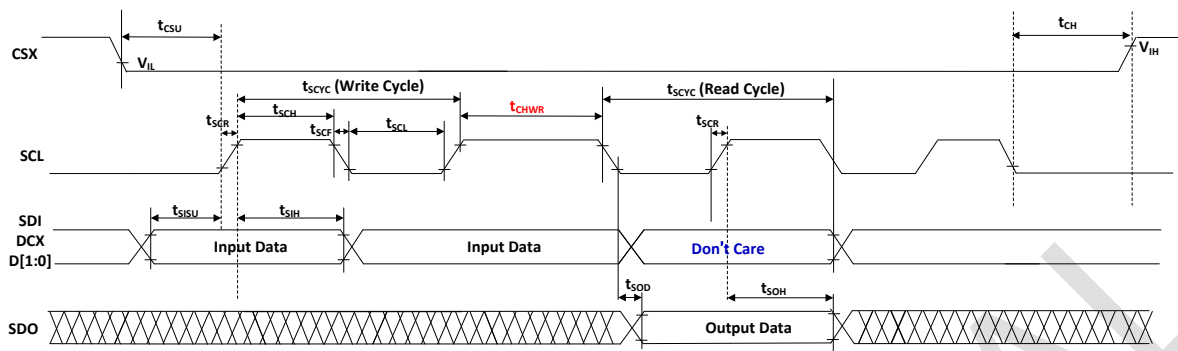


Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Clock cycle	t _{SCYC}	Write	20			ns
		Read	300			ns
Clock high pulse width	t _{SCH}	Write	6.5			ns
		Read	140			ns
Clock low pulse width	t _{SCL}	Write	6.5			ns
		Read	140			ns
Clock rise time	t _{SCR}	0.2*VDDI -> 0.8*VDDI			3.5	ns
Clock fall time	t _{SCF}	0.8*VDDI -> 0.2*VDDI			3.5	ns
Chip select setup time	t _{CSU}		10			ns
Chip select hold time	t _{CH}		10			ns
Data input setup time	t _{SISU}	To V _{IL} of SCL's rising edge	5			ns
Data input hold time	t _{SIH}		5			ns
Access time of output data	t _{SOD}	From V _{IL} of SCL's falling edge			120	ns
Hold time of output data	t _{SOH}	From V _{IH} of SCL's rising edge	5			ns
Transition time from Write cycle to Read cycle	t _{CHWR}	From V _{IH} of SCL's rising edge	150			ns

Notes:

- (1) Logic high and low levels are specified as 80% and 20% of VDDI for Input signals.
- (2) For the 4-wire SPI, the DCX's timing is the same as input data.
- (3) Ta = -30°C to 70°C, VDDI=1.65V to 3.3V, VDD=2.7V to 3.6V, and VSS=0V

7.6.2 QUAD-SPI Characteristics



Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Clock cycle	t _{SCYC}	Write	20			ns
		Read	150			ns
Clock high pulse width	t _{SCH}	Write	6.5			ns
		Read	70			ns
Clock low pulse width	t _{SCL}	Write	6.5			ns
		Read	70			ns
Clock rise time	t _{SCR}	0.2*VDDI -> 0.8*VDDI			3.5	ns
Clock fall time	t _{SCF}	0.8*VDDI -> 0.2*VDDI			3.5	ns
Chip select setup time	t _{CSU}		20			ns
Chip select hold time	t _{CH}		20			ns
Data input setup time	t _{SISU}	To V _{IL} of SCL's rising edge	4			ns
Data input hold time	t _{SIH}		4			ns
Access time of output data	t _{SOD}	From V _{IL} of SCL's falling edge			70	ns
Hold time of output data	t _{SOH}	From V _{IH} of SCL's rising edge	5			ns
Transition time from Write cycle to Read cycle	t _{CHWR}	From V _{IH} of SCL's rising edge	150			ns

Note: The max SCL frequency for each pixel data format is specified as the below table.

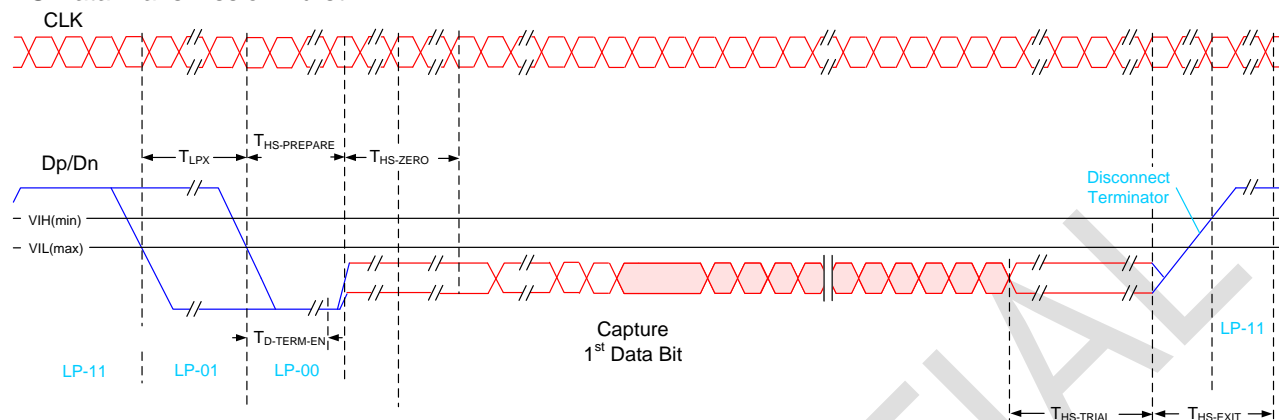
Note: Logic high and low levels are specified as 20% and 80% of VDDI for Input signals.

Note: Ta = -30 to 70 °C, VDDI=1.65V to 3.3V, VDD=2.7V to 3.6V, GND=0V

Note: 4-wire QSPI support transfer rate in pixel data write

		4-wire QSPI support transfer rate
Pixel Data Write	RGB888	50MHz
	RGB666	50MHz
	RGB565	50MHz

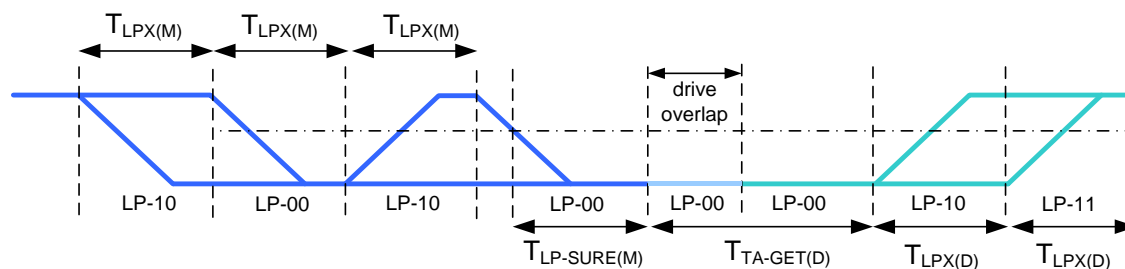
HS Data Transmission Burst



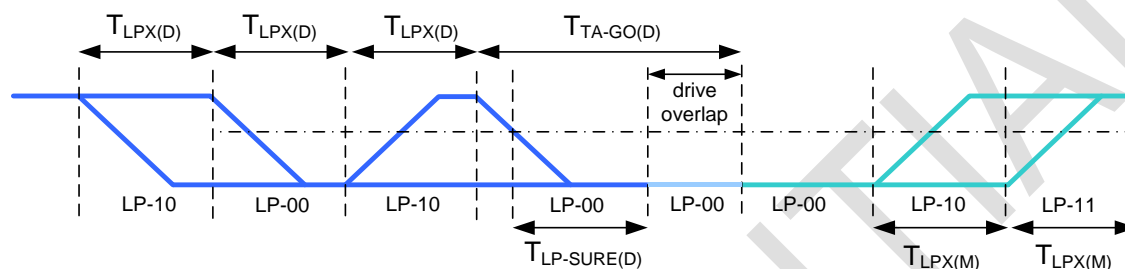
Timing Parameters:

Parameter	Description	Min	Typ	Max	Unit
$T_{CLK-POST}$	Time that the transmitter continues to send HS clock after the last associated Data Lane has transitioned to LP Mode. Interval is defined as the period from the end of $T_{HS-TRAIL}$ to the beginning of $T_{CLK-TRAIL}$.	$60ns + 52*UI$			ns
$T_{CLK-TRAIL}$	Time that the transmitter drives the HS-0 state after the last payload clock bit of a HS transmission burst.	60			ns
$T_{HS-EXIT}$	Time that the transmitter drives LP-11 following a HS burst.	300			ns
$T_{CLK-TERM-EN}$	Time for the Clock Lane receiver to enable the HS line termination, starting from the time point when Dn crosses $V_{IL,MAX}$.	Time for Dn to reach $V_{TERM-EN}$		38	ns
$T_{CLK-PREPARE}$	Time that the transmitter drives the Clock Lane LP-00 Line state immediately before the HS-0 Line state starting the HS transmission.	38		95	ns
$T_{CLK-PRE}$	Time that the HS clock shall be driven by the transmitter prior to any associated Data Lane beginning the transition from LP to HS mode.	8			UI
$T_{CLK-PREPARE} + T_{CLK-ZERO}$	$T_{CLK-PREPARE}$ + time that the transmitter drives the HS-0 state prior to starting the Clock.	300			ns
$T_{D-TERM-EN}$	Time for the Data Lane receiver to enable the HS line termination, starting from the time point when Dn crosses $V_{IL,MAX}$.	Time for Dn to reach $V_{TERM-EN}$		$35 ns + 4*UI$	
$T_{HS-PREPARE}$	Time that the transmitter drives the Data Lane LP-00 Line state immediately before the HS-0 Line state starting the HS transmission	$40ns + 4*UI$		$85 ns + 6*UI$	ns
$T_{HS-PREPARE} + T_{HS-ZERO}$	$T_{HS-PREPARE}$ + time that the transmitter drives the HS-0 state prior to transmitting the Sync sequence.	$145ns + 10*UI$			ns
$T_{HS-TRAIL}$	Time that the transmitter drives the flipped differential state after last payload data bit of a HS transmission burst	$60ns + 4*UI$			ns

Turnaround Procedure



Bus turnaround (BAT) from MPU to display module timing



Bus turnaround (BAT) from display module to MPU timing

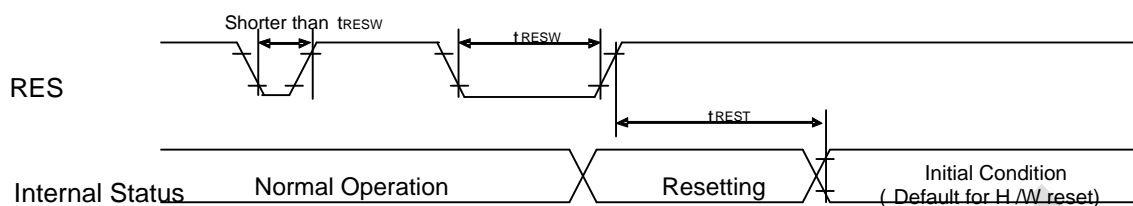
Low Power Mode :

Parameter	Description	Min	Typ	Max	Unit	Notes
$T_{LPX(M)}$	Transmitted length of any Low-Power state period of MCU to display module	50		150	ns	1,2
$T_{TA-SURE(M)}$	Time that the display module waits after the LP-10 state before transmitting the Bridge state (LP-00) during a Link Turnaround.	$T_{LPX(M)}$		$2 * T_{LPX(M)}$	ns	2
$T_{LPX(D)}$	Transmitted length of any Low-Power state period of display module to MCU	50		150	ns	1,2
$T_{TA-GET(D)}$	Time that the display module drives the Bridge state (LP-00) after accepting control during a Link Turnaround.		$5 * T_{LPX(D)}$		ns	2
$T_{TA-GO(D)}$	Time that the display module drives the Bridge state (LP-00) before releasing control during a Link Turnaround.		$4 * T_{LPX(D)}$		ns	2
$T_{TA-SURE(D)}$	Time that the MPU waits after the LP-10 state before transmitting the Bridge state (LP-00) during a Link Turnaround.	$T_{LPX(D)}$		$2 * T_{LPX(D)}$	ns	2

NOTE:

- T_{LPX} is an internal state machine timing reference. Externally measured values may differ slightly from the specified values due to asymmetrical rise and fall times.
- Transmitter-specific parameter

7.6.4 Reset Timing



Reset input timing:

VDDI=1.65 to 3.3V, VDD=2.7 to 3.6V, AGND=DGND=0V, Ta=-40 to 85°C

Symbol	Parameter	Related Pins	MIN	TYP	MAX	Note	Unit
t _{RESW}	*1) Reset low pulse width	RESX	30	-	-	-	μs
t _{REST}	*2) Reset complete time	-	-	-	20	When reset applied during Sleep in mode	ms
		-	-	-	120	When reset applied during Sleep out mode	ms

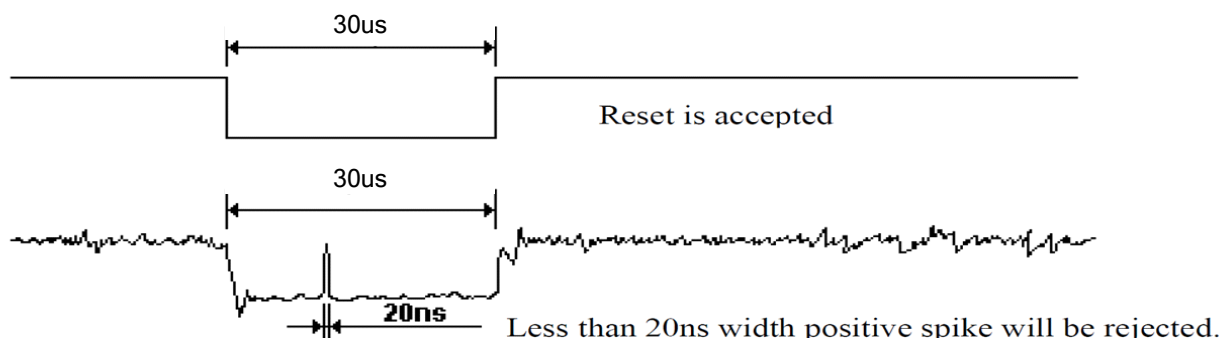
Note 1) Spike due to an electrostatic discharge on RESX line does not cause irregular system reset according to the table below.

RESX Pulse	Action
Shorter than 5μs	Reset Rejected
Longer than 30μs	Reset
Between 5μs and 30μs	Reset starts (It depends on voltage and temperature condition.)

Note 2. During the resetting period, the display will be blanked (The display is entering blanking sequence, which maximum time is 120 ms, when Reset Starts in Sleep Out –mode. The display remains the blank state in Sleep In –mode) and then return to Default condition for H/W reset.

Note 3. During Reset Complete Time, data in OTP will be latched to internal register during this period. This loading is done every time when there is H/W reset complete time (t_{REST}) within 20ms after a rising edge of RESX.

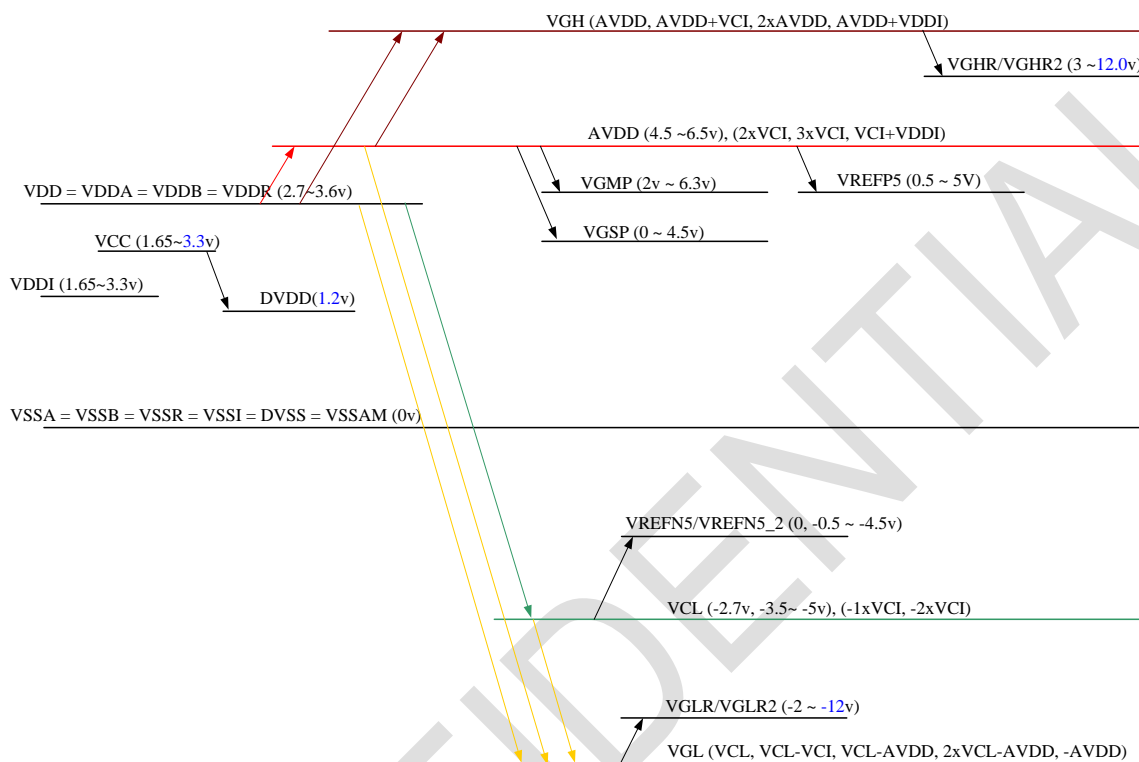
Note 4. Spike Rejection also applies during a valid reset pulse as shown below:



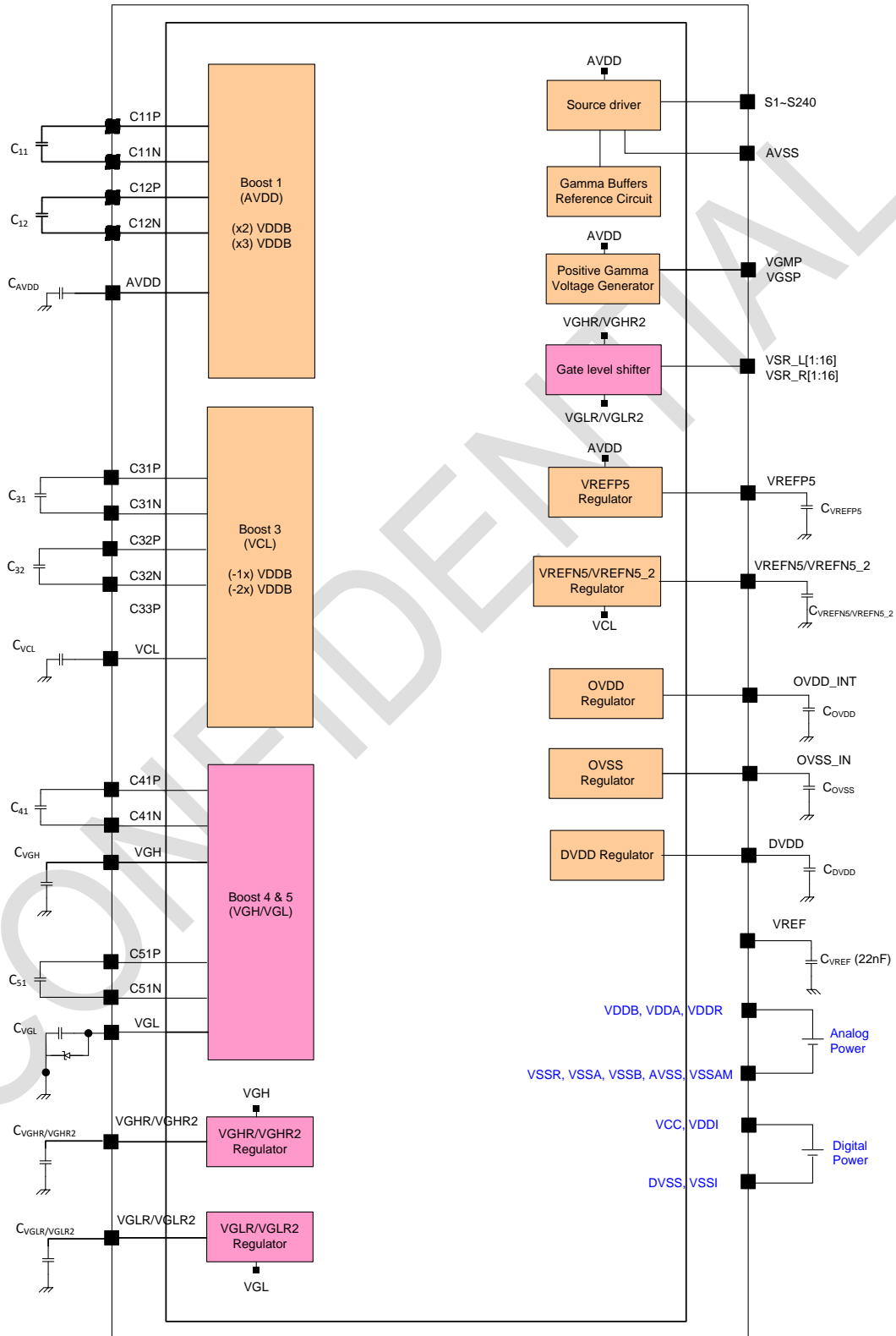
Note 5. It is necessary to wait 20msec after releasing RESX before sending commands. Also Sleep Out command cannot be sent for 120msec.

8. Power Generation

8.1 Two Supply Power (VDDI / VDD)



8.2 DC/DC Converter Circuit

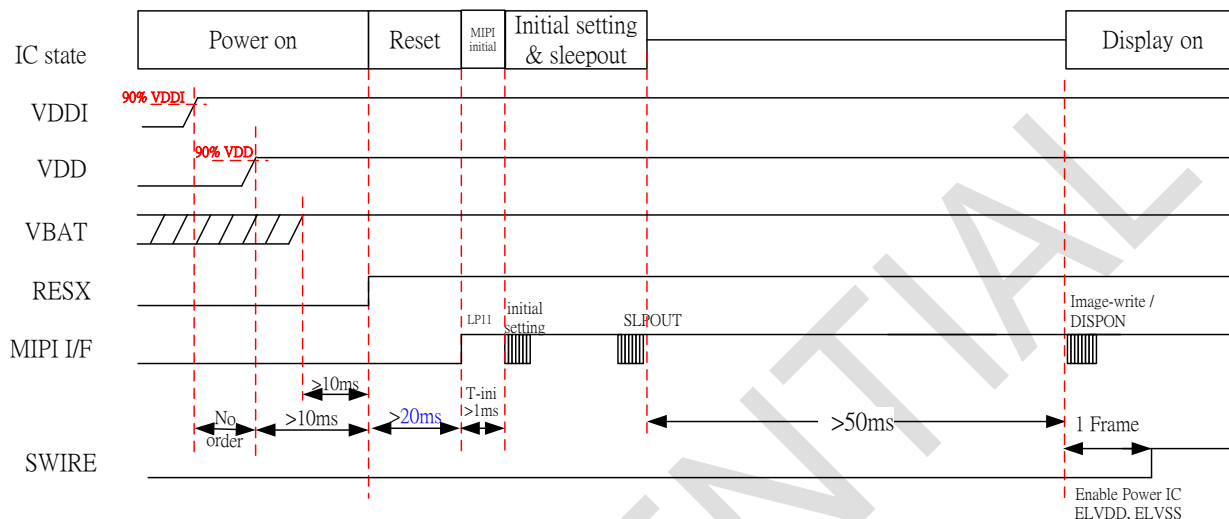


8.3 External Components

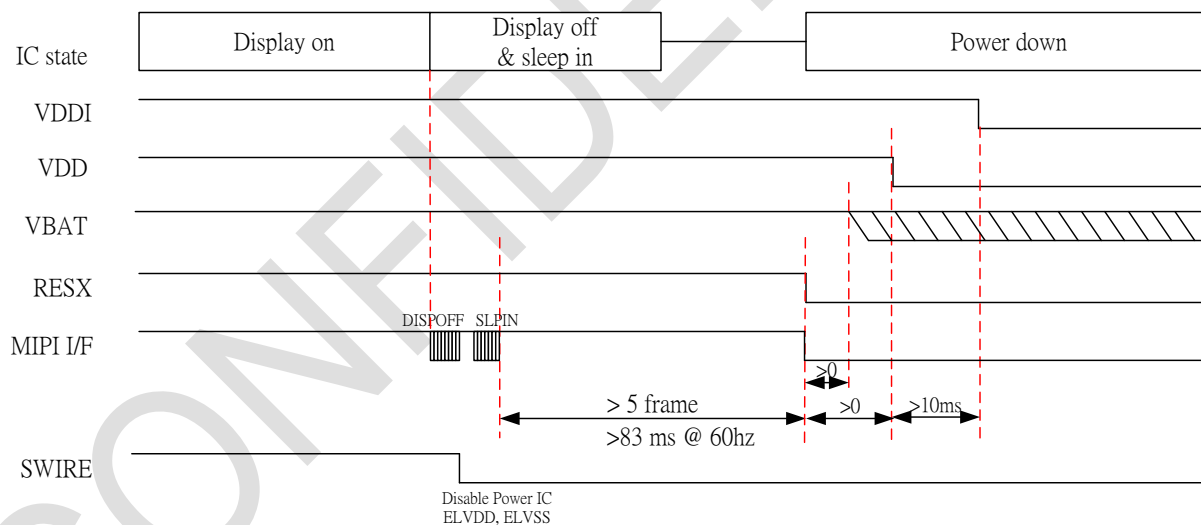
No.	Signal name	Values	Max ability
1	VDDA, VDDR, VDDDB	Cap , 2.2uF	6.3V
2	VDDI, VCC	Cap , 2.2uF	6.3V
3	VREF	Cap , 22nF	6.3V
4	DVDD	Cap , 1.0uF	6.3V
5	VREFP5	Cap , 1.0uF	10V
6	VREFN5	Cap , 1.0uF	10V
7	VREFN5_2	Cap , 1.0uF	10V
8	VGHR	Cap , 2.2uF	16V
9	VGHR2	Cap , 2.2uF	16V
10	VGLR	Cap , 2.2uF	16V
11	VGLR2	Cap , 2.2uF	16V
12	OVDD_INT	Cap , 2.2uF	10V
13	OVSS_INT	Cap , 2.2uF	10V
14	C11P/C11N	Cap , 1.0uF	6.3V
15	C12P/C12N	Cap , 1.0uF	6.3V
16	AVDD	Cap , 2.2uF	10V
17	C31P/C31N	Cap , 1.0uF	6.3V
18	C32P/C32N	Cap , 1.0uF	6.3V
19	VCL	Cap , 2.2uF	10V
20	C41P/C41N	Cap , 1.0uF	16V
21	VGH	Cap , 2.2uF	16V
22	C51P/C51N	Cap , 1.0uF	16V
23	VGL	Cap , 2.2uF	16V
24	VGL (VGL-GND)	Schottky Diode	

8.4 Power on/off sequence and timing

Power On sequence

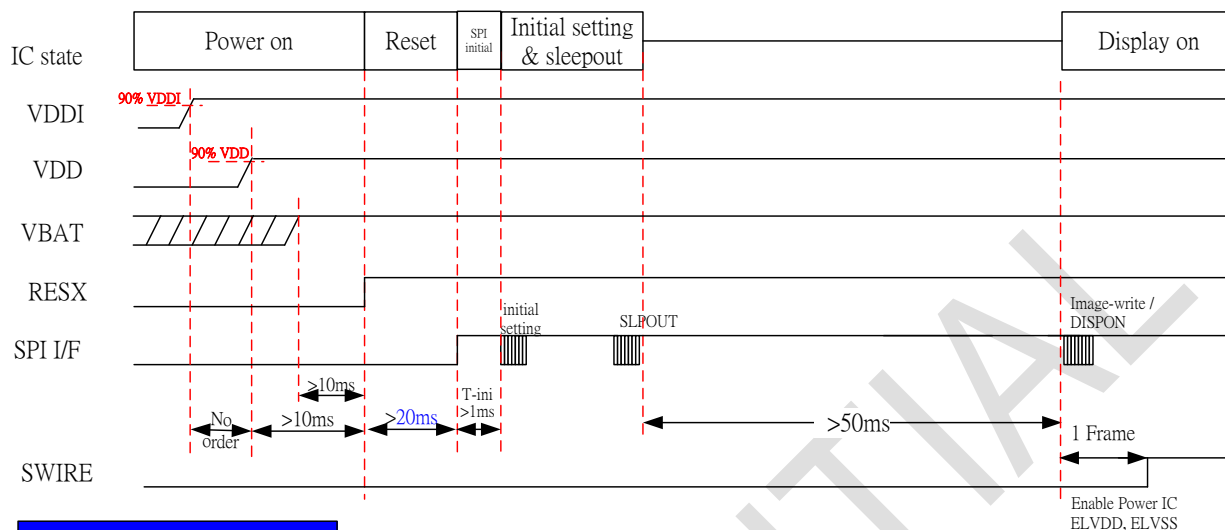


Power Off sequence



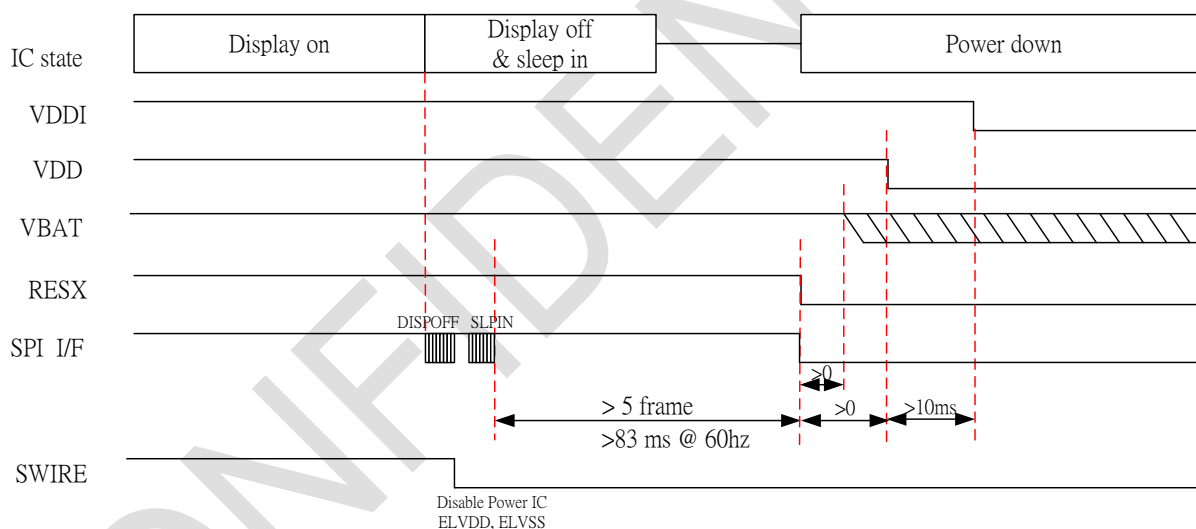
Power On sequence

SPI Interface



Power Off sequence

SPI Interface



8.5 Power Level Modes

Normal display mode on = NORON

Partial mode on = PTLON

Idle mode off = IDMOFF

Idle mode on = IDMON

Sleep out = SLPOUT

Sleep in = SLPIN

Deep standby mode = DSTBON

Definition example:

1. Normal Mode On (full display), Idle Mode Off, Sleep Out.

In this mode, the display is able to show maximum 16.7M colors.

2. Partial Mode On, Idle Mode Off, Sleep Out

In this mode, part of the display is used with maximum 16.7M colors.

3. Normal Mode On (full display), Idle Mode On, Sleep Out.

In this mode, the full display is used with 8 or 16.7M colors.

4. Partial Mode On, Idle Mode On, Sleep Out

In this mode, part of the display is used with 8 or 16.7M colors.

5. Sleep In Mode.

In this mode, the DC/DC converter, internal oscillator and panel driver circuit are stopped. Only the MPU interface and registers are working with VDDI power supply. Contents of the frame memory can be safe or random.

6. Deep Standby Mode.

In this mode, the DC/DC converter, internal oscillator and panel driver circuit are stopped. The MPU interface and registers are not working. Contents of the frame memory are random.

7. Power Off Mode

In this mode, VDDI and VDDA/VDDR/Vddb are removed.

NOTE: Transition between mode 1~5 is controllable by MPU commands. Mode 6 is entered for power saving with both power supplies for I/O and analog circuits and can be exited by hardware reset only (RESX=L). Mode 7 is entered only when both power supplies for I/O and analog circuits are removed.

8.6 Maximum Series Resistance

Pin Name	Type	Max Resistance	Unit
VDDA, VDDDB, VDDR, VDDI, VCC,	Power Supply	5	Ω
AVSS, VSSAM, DVSS, VSSI, VSSA, VSSR, VSSB	Power Supply	5	Ω
AVDD	Power Input/Output	5	Ω
DVDD	Power Output	5	Ω
VCL	Power Output	5	Ω
VGH, VGL	Power Output	10	Ω
C11P/N~C12P/N	Capacitor Connection	5	Ω
C31P/N~C32P/N	Capacitor Connection	5	Ω
C41P/N	Capacitor Connection	5	Ω
C51P/N	Capacitor Connection	5	Ω
MIPI1_CLK_P/N, MIPI1_DATA0_P/N MIPI2_CLK_P/N, MIPI2_DATA0_P/N	MIPI Interface I/O	5	Ω
TE, TE1, SWIRE, ERR	Digital Output I/O	20	Ω
RESX, CSX, D/CX, SCL, SDI_RDx, SDO,D[0]~D[7], WATCH_OSC_IN	Digital Interface I/O	20	Ω
IM[1 :0], MIPI_SEL, PSWAP	Input I/O	100	Ω
MTP_PWR	Power Supply	5	Ω
S[1]~S[240]	Source output	20	Ω
VSR_L[1]~ VSR_L[16], VSR_R[1]~ VSR_R[16]	GOA,SWoutput	20	Ω