## Research presentation for PhD admits

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### Overview

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Uncertainty quantification: calibratior

Fairness: Bayes-optimal classifiers

High-dim. statistics & deterministic equivalents

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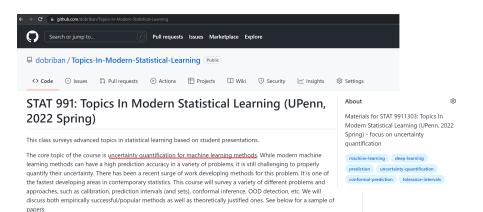
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  - Usually work closely on first project, then as hands-on/off as you would like.

## Research Interests: see my website for details

- the efficient statistical analysis of "big data" using advanced tools, such as those from random matrix theory
  - o dimension reduction, PCA: [1], [2], [3], [4], [5], [6]
  - multiple testing: [1], [2], [3]
  - o high-dimensional regression: [1], [2]
  - o invariance-based randomization tests
- the theoretical foundations of modern machine learning, including deep learning
  - o data augmentation: [1], [2]
  - · weight normalization
  - o (stochastic) gradient descent and flow: [1], [2]
  - overparametrization
  - o sketching and random projections, [1], [2], [3], [4], [5]
  - o distributed learning: [1], [2], [3]
  - o adversarial robustness: [1], [2]
  - retraining of ML models
  - o uncertainty quantification: [1], [2]
  - o fairness: [1]
  - o reinforcement learning inspired by child-like learning
- in addition, we occasionally work on important applications and methods, such as
  - genomics
  - o group testing for COVID-19

## Uncertainty quantification for ML - My course at Penn



## Topics in Deep Learning - My course at Penn

### STAT 991: Topics in deep learning (UPenn)

STAT 991: Topics in Deep Learning is a seminar class at UPenn started in 2018. It surveys advanced topics in deep learning based on student presentations.

### Fall 2019

- Syllabus.
- Lecture notes. (~170 pages, file size ~30 MB, mostly covering notes from previous semesters.)

#### Lectures

Lectures 1 and 2: Introduction and uncertainty quantification (jackknife+, and Pearce at al, 2018), presented by Edgar Dobriban.

Lecture 3: NTK by Jiayao Zhang. Blog post on the off-convex blog.

Lecture 4: Adversarial robustness by Yinjun Wu.

Lecture 5: ELMo and BERT by Dan Deutsch.

Lecture 6: TCAV by Ben Auerbach (adapted from Been Kim's slides).

Lecture 7: Spherical CNN by Arjun Guru and Claudia Zhu.

Lecture 8: DNNs and approximation by Yebiao Jin.

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denomination.





90.7 GDT

Computational prediction

Title: United Methodists Agree to Historic Split Subtitle: Those who oppose gay marriage will form their own denomination Article: After two days of intense debate, the United Methodist Church has agreed to a historic split - one that is expected to end in the creation of a new denomination, one that will be "theologically and socially conservative," according to The Washington Post. The majority of delegates attending the church's annual General Conference in May voted to strengthen a ban on the ordination of LGBTO clergy and to write new rules that will "discipline" clergy who officiate at same-sex weddings. But those who opposed these measures have a new plan: They say they will form a

separate denomination by 2020, calling their church the Christian Methodist Figure 3.14: The GPT-3 generated news article that humans had the greatest difficulty distinguishing from a human written article (accuracy: 12%).

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- Success stories: AlphaFold, cancer tissue image classification, computer vision, NLP ...





T1037/6vr4 T1049/6y41
90.7 GDT 93.3 GDT
INA polymerase domain) (adhesin tip)

© Experimental result

© Computational prediction

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Figure 3.14: The GPT-3 generated news article that humans had the greatest difficulty distinguishing from a human written article (accuracy: 12%).

 Meanwhile, growing concerns: safety, ethics, energy- and sample-efficiency, uncertainty

### Calibration

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Modern finding: powerful ML methods (e.g., deep CNNs) are over-confident and mis-calibrated

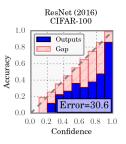
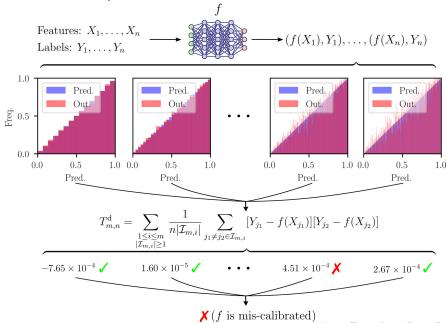


Figure: Guo et al, 2017

## T-Cal: An optimal test of calibration



### T-Cal

- ► Theoretical result: minimax optimal under Hölder smoothness
  - Empirical results: large power in simulations; can use it to detect mis-calibration of state-of-the-art deep networks

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### Motivation

- Machine learning algorithms are becoming integrated into more and more high-stakes decision-making processes.
- Algorithm-based decision-making systems could retain or even amplify historical unfairness in data.

## **COMPAS Algorithm**



## Amazon Recruitment System

RETAIL OCTOBER 10, 2018 / 7:04 PM / UPDATED 3 YEARS AGO

# Amazon scraps secret AI recruiting tool that showed bias against women

By Jeffrey Dastin	8 MIN READ	f	

SAN FRANCISCO (Reuters) - Amazon.com Inc's <u>AMZN.O</u> machine-learning specialists uncovered a big problem: their new recruiting engine did not like women.

## Group Fairness

- ▶ Consider a classification problem with two types of feature: the usual feature  $X \in \mathcal{X}$ , and the protected (or, sensitive) feature  $A \in \mathcal{A} = \{0,1\}$ .
- ▶ Binary labels in  $\mathcal{Y} = \{0, 1\}$ , prediction  $\hat{Y}$ .

## Fair Bayes-optimal Classifier under Demographic Parity

Several group fairness measures have been proposed. Measure "unfairness" by *Difference in demographic parity*:

$$DDP = P(\hat{Y} = 1|A = 1) - P(\hat{Y} = 1|A = 0).$$

For input x, let  $f(x) := P(\hat{Y} = 1 | X = x)$ .

Goal: Find  $\delta$ -fair Bayes-optimal classifier with respect to demographic parity; defined as

$$f_{D,\delta}^{\star} \in \underset{f:|DDP(f)| \leqslant \delta}{\operatorname{argmin}} [P(Y \neq \widehat{Y})].$$

### Main Theorem

Denote

$$p_a:=P(A=a)$$
  $\eta_a(x):=P(Y=1|A=a,X=x)$   $S_a(t):=P(\eta_a(X)>t|A=a)$ 

## Theorem (Fair Bayes-optimal Classifier under Demographic Parity)

Let  $D^* = \mathsf{DDP}(f^*)$ , where  $f^*$  is unconstrained Bayes-optimal classifier. For any  $\delta > 0$ , all  $\delta$ -fair Bayes optimal classifiers  $f^*_{D,\delta}$  have the following form:

- When  $|D^*| \leq \delta$ ,  $f_{D,\delta}^* = f^*$ .
- When  $|D^*| > \delta$ , for all  $x \in \mathcal{X}$  and  $a \in \mathcal{A}$ ,

$$f_{D,\delta}^{\star}(x,a) = I\left(\eta_{a}(x) > \frac{1}{2} + \frac{(2a-1)t_{D,\delta}^{\star}}{2p_{a}}\right) + at_{D,\delta}^{\star}I\left(\eta_{a}(x) = \frac{1}{2} + \frac{(2a-1)t_{D,\delta}^{\star}}{2p_{a}}\right), \tag{1}$$

### Main Theorem

### Theorem (continued)

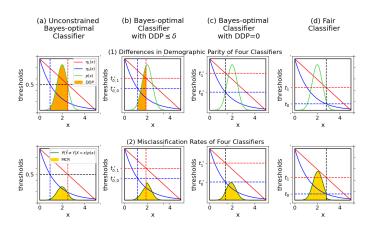
where  $t_{D,\delta}^{\star}$  is defined as

$$t_{D,\delta}^{\star} = \sup \left\{ t : S_1 \left( \frac{1}{2} + \frac{t}{2p_1} \right) > S_0 \left( \frac{1}{2} - \frac{t}{2p_0} \right) + \frac{D^{\star}}{|D^{\star}|} \delta \right\}.$$
 (2)

Here,  $au_{D,\delta}^{\star} \in [0,1]$  can be an arbitrary constant if  $P_{X|A=1}(\eta_1(X)=rac{1}{2}+rac{t}{2p_1})=0$ , and otherwise

$$\tau_{D,\delta}^{\star} = \frac{S_1 \left(\frac{1}{2} + \frac{t}{2p_1}\right) - S_0 \left(\frac{1}{2} - \frac{t}{2p_0}\right) - \frac{D^{\star}}{|D^{\star}|}}{P_{X|A=1}(\eta_1(X) = \frac{1}{2} + \frac{t}{2p_1})}.$$
 (3)

### Illustration of Theorem



### **Proof Sketch**

## Lemma (Generalized Neyman-Pearson lemma)

Let  $f_0, f_1, ..., f_m$  be m+1 real-valued functions defined on a Euclidean space  $\mathcal{X}$ . Assume they are  $\nu$ -integrable for a  $\sigma$ -finite measure  $\nu$ . Let  $\phi_0$  be any function of the form

$$\phi_0(x) = \begin{cases} 1, & f_0(x) > \sum_{i=1}^m c_i f_i(x); \\ \gamma(x) & f_0(x) = \sum_{i=1}^m c_i f_i(x); \\ 0, & f_0(x) < \sum_{i=1}^m c_i f_i(x), \end{cases}$$
(4)

where  $0 \leqslant \gamma(x) \leqslant 1$  for all  $x \in \mathcal{X}$ .

### **Proof Sketch**

## Lemma (continued)

For given constants  $t_1,...,t_m \in \mathbb{R}$ , let  $\mathcal{T}$  be the class of Borel functions  $\phi: \mathcal{X} \mapsto \mathbb{R}$  satisfying

$$\int_{\mathcal{X}} \phi f_i d\nu \le t_i, \quad i = 1, 2, ..., m.$$
 (5)

and  $\mathcal{T}_0$  be the set of  $\phi s$  in  $\mathcal{T}$  satisfying (5) with all inequalities replaced by equalities. If  $\phi_0 \in \mathcal{T}_0$ , then  $\phi_0 \in \underset{\phi \in \mathcal{T}_0}{\operatorname{argmax}} \int_{\mathcal{X}} \phi f_0 d\nu$ . Moreover, if  $c_i \geqslant 0$  for all  $i=1,\ldots,m$ , then  $\phi_0 \in \underset{\phi \in \mathcal{T}}{\operatorname{argmax}} \int_{\mathcal{X}} \phi f_0 d\nu$ .

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- ▶ Standard linear model  $Y = X\beta + \varepsilon$ , where
  - 1. Y is  $n \times 1$  outcome, X is  $n \times p$  feature matrix.
  - 2.  $\beta$  is *p*-dim parameter
- Ordinary least squares

$$\hat{\beta} = (X^{\top}X)^{-1}X^{\top}Y$$

▶ Mean squared error of OLS, assuming  $\mathbb{E}\varepsilon = 0$ ,  $\operatorname{cov}(\varepsilon) = \sigma^2 I_n$ 

$$\mathbb{E}\|\hat{\beta} - \beta\|^2 = \sigma^2 \operatorname{tr}[(X^\top X)^{-1}]$$

► How large is this? (How hard? How much error?)

### Motivation ctd

▶ When  $X_{ij} \sim \mathcal{N}(0,1)$  are iid standard normal,

$$\mathbb{E}\operatorname{tr}[(X^{\top}X)^{-1}] = \frac{p}{n-p-1}.$$

▶ More general data distributions? There are only approximate expressions.

## Deterministic equivalents

- We have sequences of (not necessarily symmetric)  $p_n \times p_n$  random matrices  $A_n$  and deterministic matrices  $B_n$  of growing dimensions
- **Definition**:  $B_n$  is a deterministic equivalent for  $A_n$ ,

$$A_n \simeq B_n$$

if

$$\lim_{n\to\infty}|\text{tr}(\mathit{C}_nA_n)-\text{tr}(\mathit{C}_nB_n)|=0$$

almost surely, for any  $p_n \times p_n$  sequence  $C_n$  of (not necessarily symmetric) deterministic real matrices with bounded trace norm, i.e.,

$$\lim \sup_{n\to\infty} \|C_n\|_{tr} = \lim \sup_{n\to\infty} \sum_i \sigma_i(C_n) < \infty.$$

e.g, 
$$C_n = c_n c_n^{\top}$$
,  $||c_n||_2$  bounded



## Sample covariance matrices

## Example (Mestre et al., 2011)

Let  $\hat{\Sigma} = X^{\top}X/n$ , where  $X = Z\Sigma^{1/2}$  and Z is an  $n \times p$  random matrix with iid entries of zero mean, unit variance and finite  $8+\eta$  moment. Also,  $\Sigma^{1/2}$  is any sequence of  $p \times p$  positive semi-definite matrices satisfying  $\sup \|\Sigma\|_2 < \infty$ . As  $n, p \to \infty$  proportionally, for any  $\lambda > 0$ 

$$(\widehat{\Sigma} + \lambda I_p)^{-1} \asymp (q_p \Sigma + \lambda I_p)^{-1},$$

where  $q_p$  is the solution of a fixed point equation.

This is the simplest way I know how to think of a broad class of results in random matrix theory.

## Distributed linear regression

- ▶ Standard linear model  $Y = X\beta + \varepsilon$
- ▶ Data distributed across k machines. The i-th machine has matrix  $X_i$   $(n_i \times p)$  and outcomes  $Y_i$ .

$$X = \begin{bmatrix} X_1 \\ \dots \\ X_k \end{bmatrix}, Y = \begin{bmatrix} Y_1 \\ \dots \\ Y_k \end{bmatrix}$$

- ► Global least squares infeasible
- ▶ Local least squares estimator  $\hat{\beta}_i = (X_i^\top X_i)^{-1} X_i^\top Y_i$  (assume  $n_i > p$ )
- Send to parameter server, average
- ▶ How does this compare to OLS on full data?

## A general framework

- ► Important to study not only estimation, but also prediction/test error, residual error, confidence intervals etc
- Predict the linear functional

$$L_A = A\beta + Z$$

Using the plug-in estimator

$$\hat{L}_A(\hat{\beta}_0) = A\hat{\beta}_0$$

- ► A fixed  $d \times p$  matrix; mean and covariance of Z has the structure:  $Z \sim (0, h\sigma^2 I_d), h \geqslant 0$
- ▶ The noise can be correlated with  $\varepsilon$ : Cov  $[\varepsilon, Z] = N$  (e.g., to study residuals)
- ► Relative efficiency:

$$E(A; X_1, \ldots, X_k) := \frac{\mathbb{E}\|L_A - \hat{L}_A(\hat{\beta})\|^2}{\mathbb{E}\|L_A - \hat{L}_A(\hat{\beta}_{dist})\|^2}.$$



## Examples: Predict $L_A = A\beta + Z$ by $\hat{L}_A(\hat{\beta}_0) = A\hat{\beta}_0$

Statistical learning problem	$L_A$	ĹΑ	Α	h	Ν
Parameter estimation	β	$\hat{eta}$	$I_p$	0	0
Regression function estimation	Xβ	Xβ̂	Χ	0	0
Confidence interval for marginal effect	$\beta_j$	$\hat{eta}_j$	$E_j^{ op}$	0	0
Test error	$x_t^{\top} \beta + \varepsilon_t$	$x_t^{\top} \hat{\beta}$	$x_t^{\top}$	1	0
Training error/Residual	$X\beta + \varepsilon$	Xβ̂	Χ	1	$\sigma^2 I_n$

## Finite sample results

When h = 0 (no noise), the MSE of estimating  $L_A = A\beta$  by OLS  $\hat{L}_A = A\hat{\beta} = A(X^\top X)^{-1}X^\top Y$  is

$$M(\hat{\beta}) = \sigma^2 \cdot \operatorname{tr}\left[ (X^\top X)^{-1} A^\top A \right].$$

For the distributed estimator  $\hat{\beta}_{dist}(w) = \sum_i w_i \hat{\beta}_i$ ,  $\sum_i w_i = 1$ 

$$M(\hat{\beta}_{dist}) = \sigma^2 \cdot \sum_{i=1}^k w_i^2 \cdot \operatorname{tr}\left[ (X_i^\top X_i)^{-1} A^\top A \right].$$

So optimal efficiency is

$$E(A; X_1, \dots, X_k) = \operatorname{tr}\left[(X^\top X)^{-1} A^\top A\right] \cdot \sum_{i=1}^k \frac{1}{\operatorname{tr}\left[(X_i^\top X_i)^{-1} A^\top A\right]}.$$

CDE: 
$$\operatorname{tr}[(X_i^\top X_i)^{-1} A^\top A] \simeq \frac{p}{n_i - p} \cdot \operatorname{tr}[\Sigma^{-1} A^\top A]/p$$
.



### Plot efficiencies

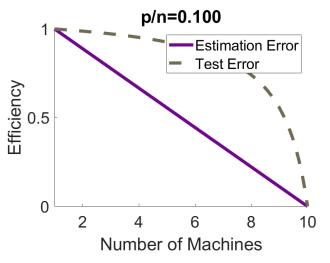


Figure: The loss of efficiency is much worse for estimation  $(\frac{\mathbb{E}\|\hat{\beta}-\beta\|^2}{\mathbb{E}\|\hat{\beta}_{dist}-\beta\|^2})$  than for test error  $(\frac{\mathbb{E}(\mathbf{x}_t^\top\hat{\beta}-\mathbf{y}_t)^2}{\mathbb{E}(\mathbf{x}_t^\top\hat{\beta}_{dist}-\mathbf{y}_t)^2})$ .