

# TapNet: Neural Network Augmented with Task-Adaptive Projection for Few-Shot Learning

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# Few-Shot Learning

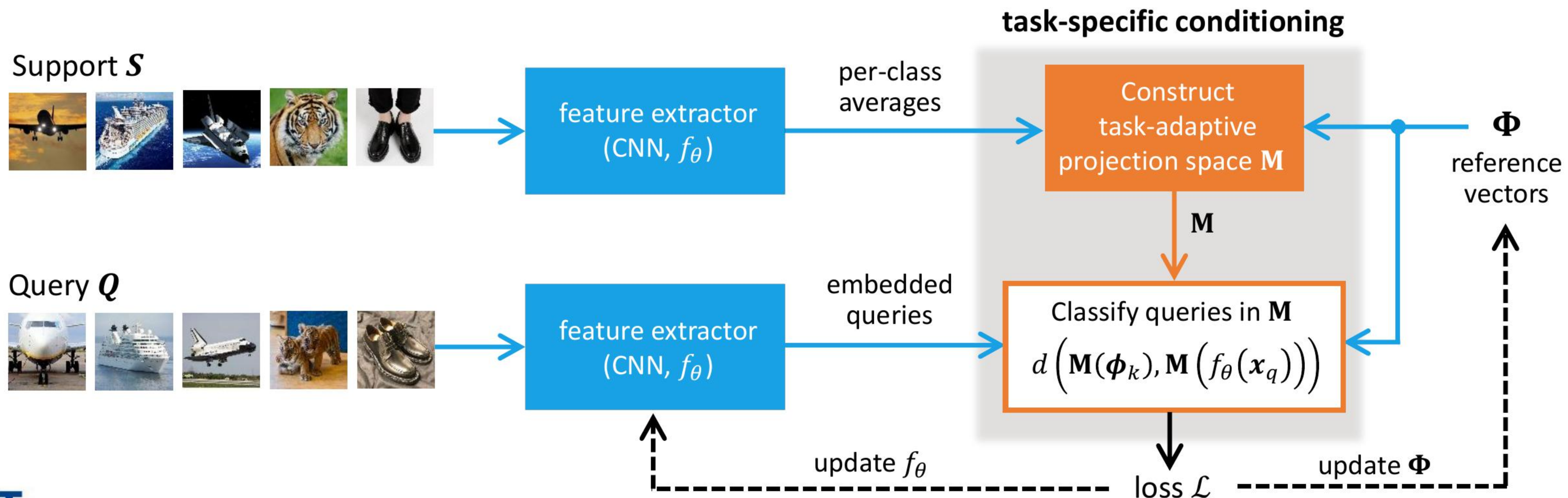
- Handling previously unseen classification tasks (episodes)
  - Training model with widely varying episodes (episodic training) [Vinyals et al., 2016]





# TapNet: Task-Adaptive Projection Network

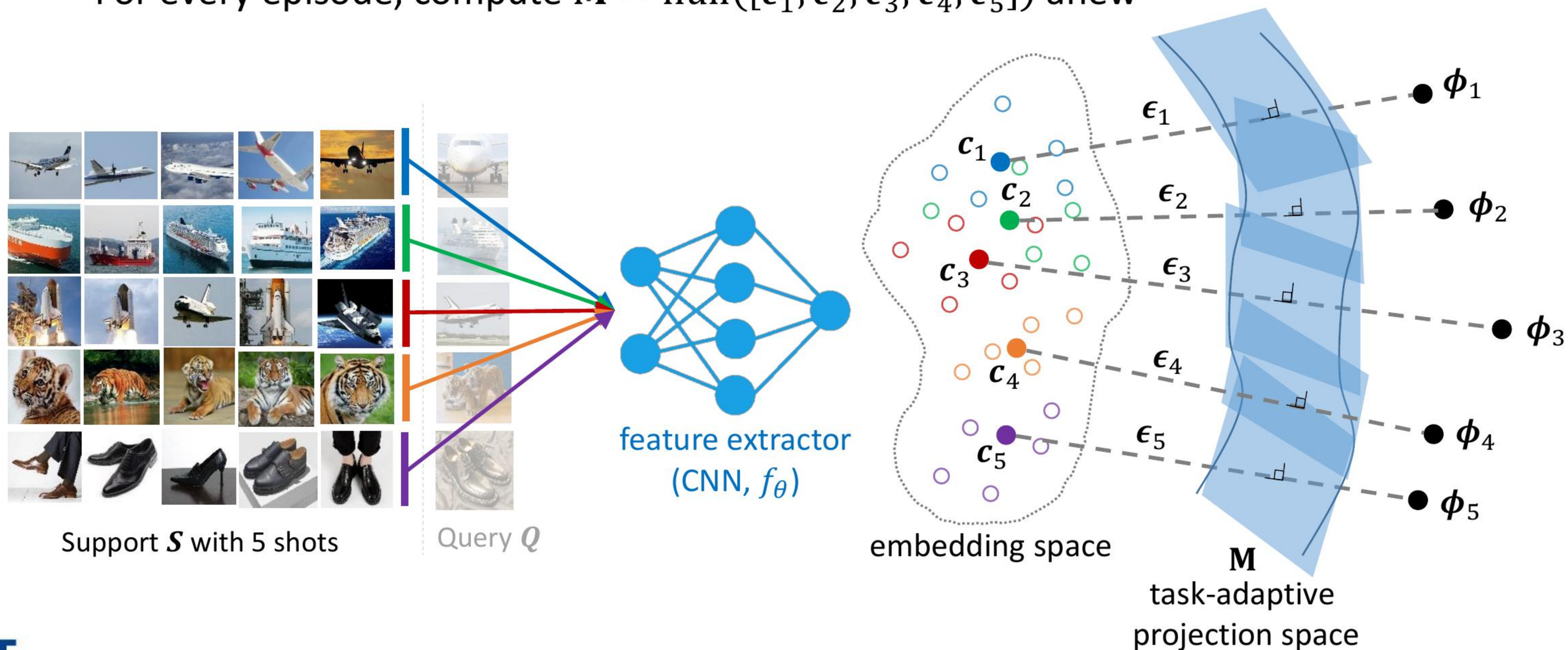
- Model description (three key elements)
  - Feature extractor  $f_\theta$
  - Learnable reference vectors  $\Phi = [\phi_1; \dots; \phi_N]$
  - Task-adaptive projection space  $\mathbf{M}$ 
    - Project references  $\Phi$  and embedded queries to  $\mathbf{M}$ , and apply metric-based classification





# How to Construct Projection Space $\mathbf{M}$

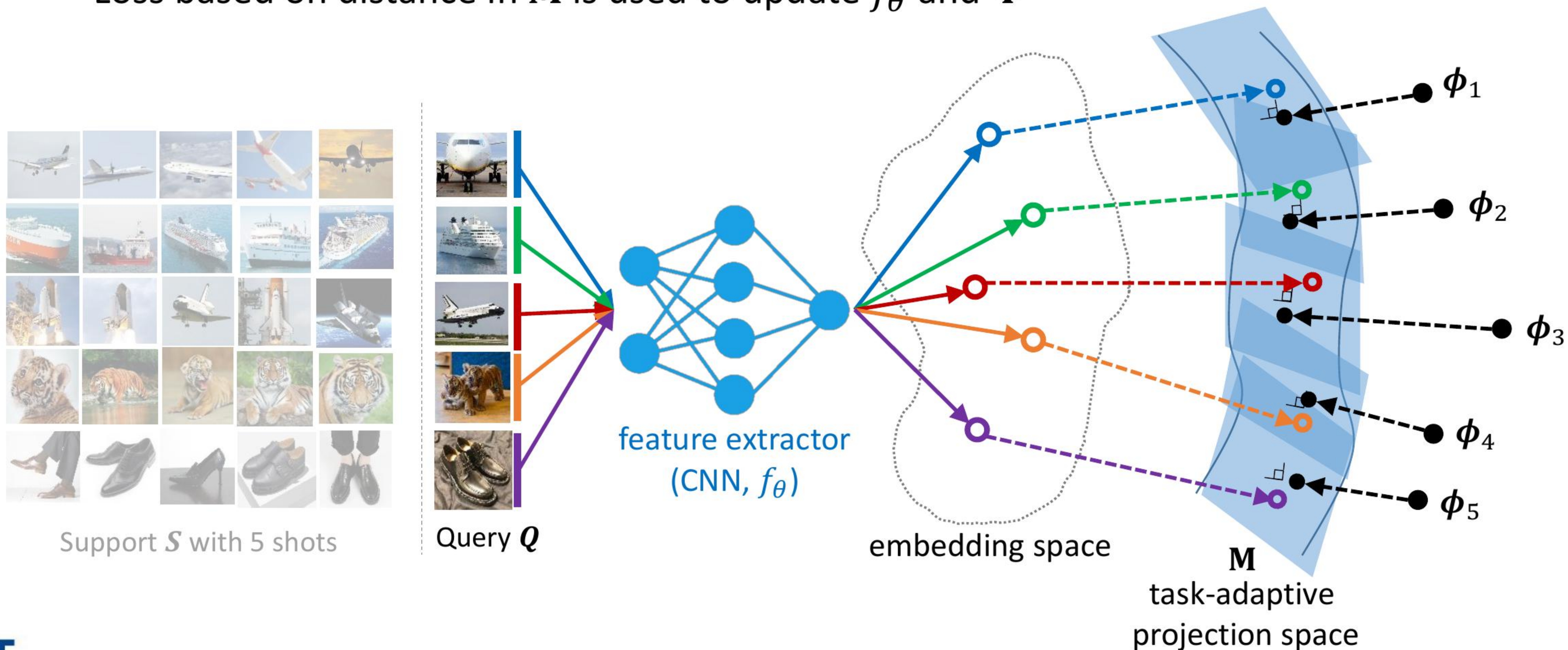
- Construction of projection space via linear nulling
  - Error vector between per-class average  $\mathbf{c}_k$  and reference  $\boldsymbol{\phi}_k$  should be zero-forced in  $\mathbf{M}$ .
  - For every episode, compute  $\mathbf{M} = \text{null}([\boldsymbol{\epsilon}_1; \boldsymbol{\epsilon}_2; \boldsymbol{\epsilon}_3; \boldsymbol{\epsilon}_4; \boldsymbol{\epsilon}_5])$  anew





# Classification and Learning

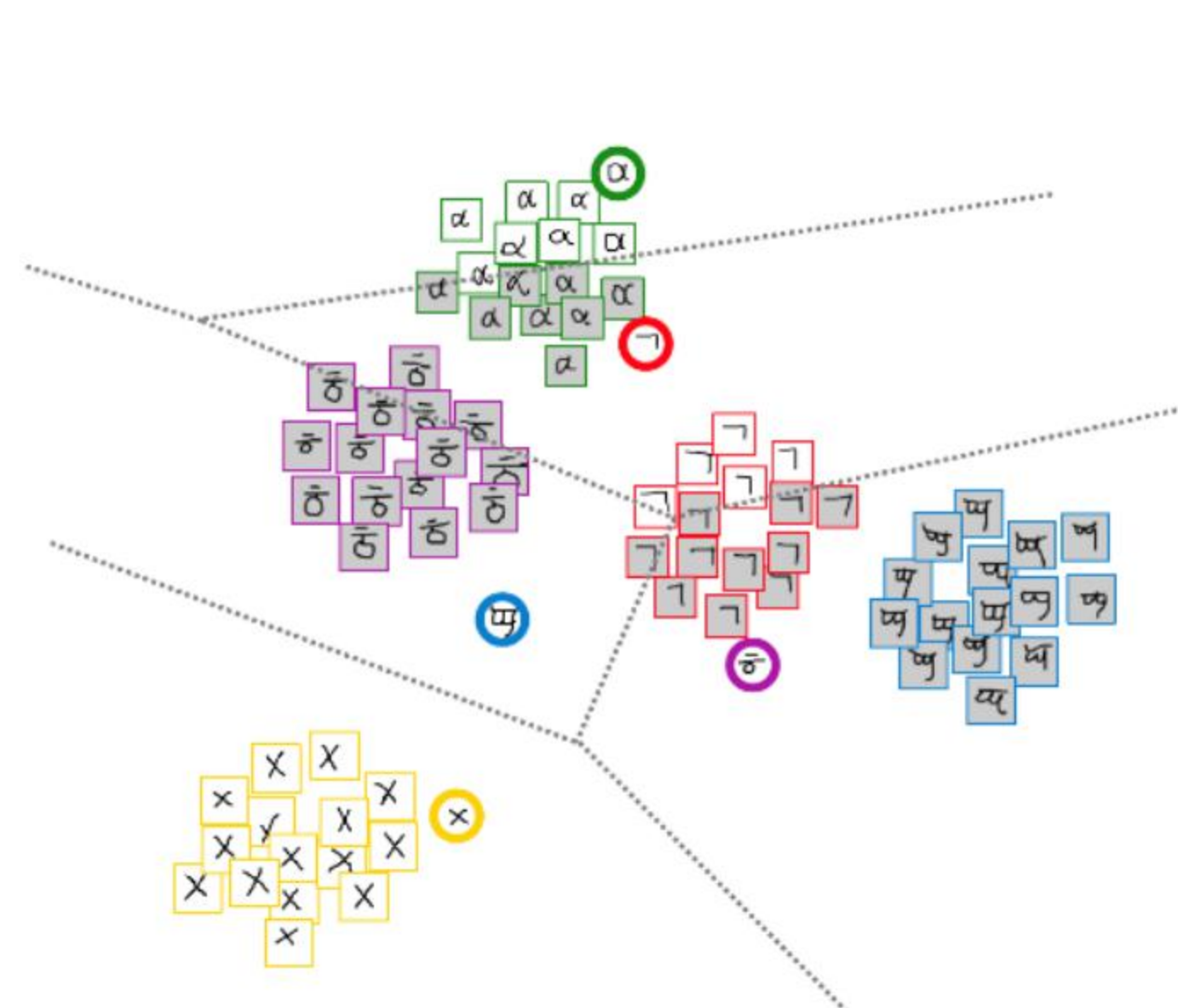
- Classifying in the task-adaptive space
  - Project  $\Phi$  and embedded queries to  $\mathbf{M}$   $\rightarrow$  Classify the projected queries with projected  $\Phi$ .
  - Loss based on distance in  $\mathbf{M}$  is used to update  $f_\theta$  and  $\Phi$





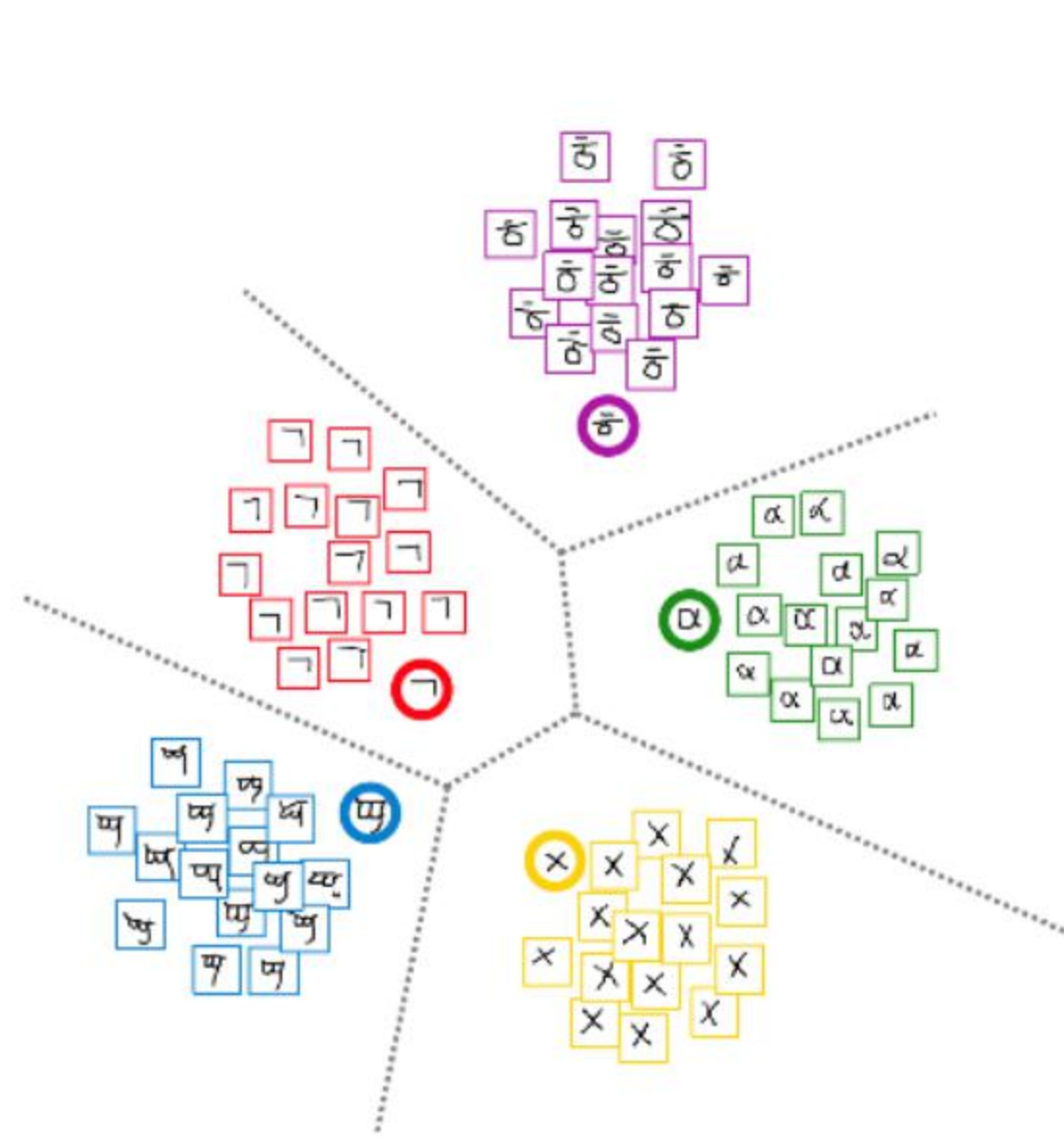
# Observations

- Projection space gives better separation of classes
- Reference vector tips actually grow apart with training

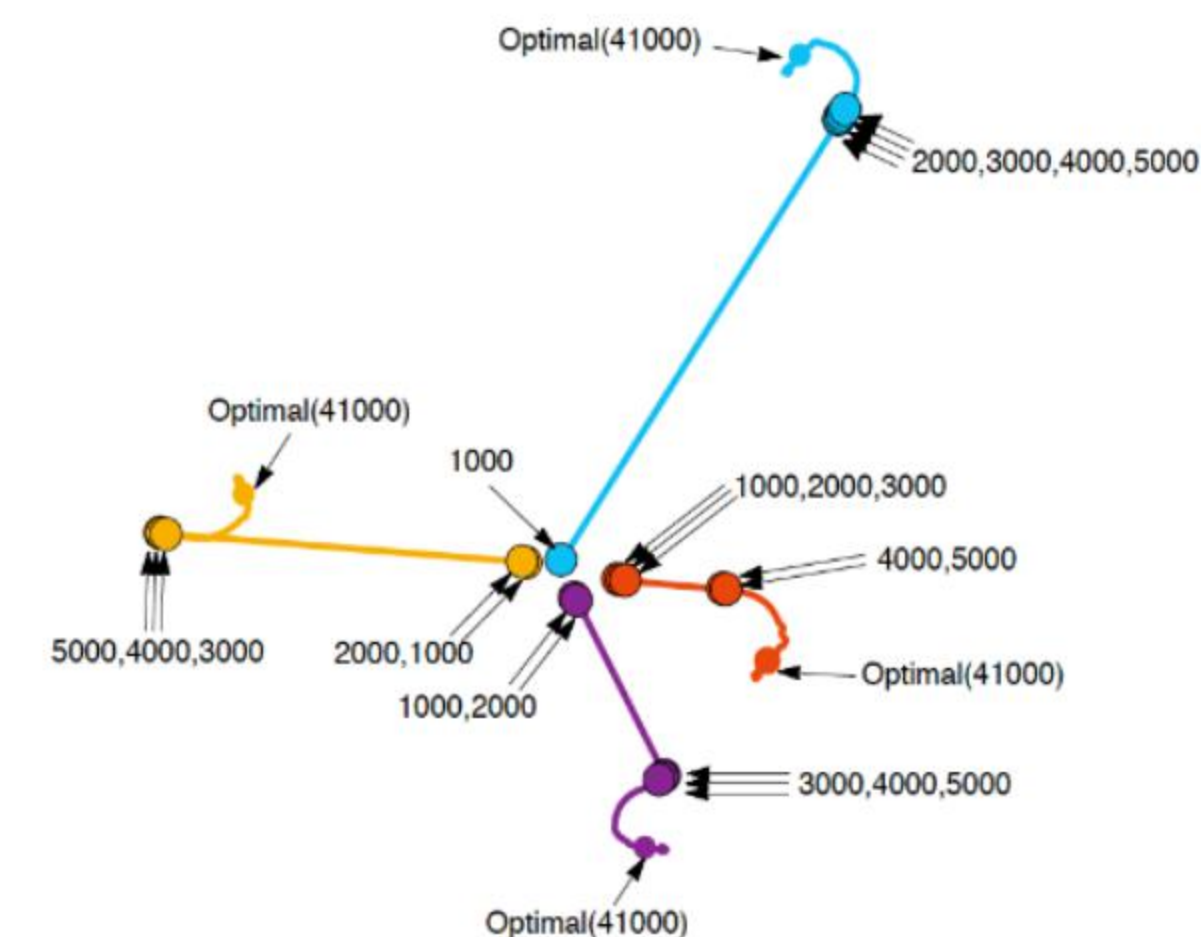


embedding space

t-SNE plot



projection space

Learning trend of  $\Phi$ 



# Results and Conclusions

Visit Poster **#4** in Pacific Ballroom for further results!

- Non-learning-based and explicit task-adaptation method
- Excellent generalization performance

Methods	5-way <i>mini</i> ImageNet	
	1-shot	5-shot
Matching Nets (Vinyals et al., 2016)	43.56 $\pm$ 0.84%	55.31 $\pm$ 0.73%
MAML (Finn et al., 2017)	48.70 $\pm$ 1.84%	63.15 $\pm$ 0.91%
Prototypical Nets (Snell et al., 2017)	49.42 $\pm$ 0.78%	68.20 $\pm$ 0.66%
SNAIL (Mishra et al., 2017)	55.71 $\pm$ 0.99%	68.88 $\pm$ 0.92%
adaResNet (Munkhdalai et al., 2018)	56.88 $\pm$ 0.62%	71.94 $\pm$ 0.57%
Transductive Propagation Nets (Liu et al., 2018)	55.51 $\pm$ 0.86%	69.86 $\pm$ 0.65%
TADAM- $\alpha$ (Oreshkin et al., 2018)	56.8 $\pm$ 0.3%	75.7 $\pm$ 0.2%
TADAM-TC (Oreshkin et al., 2018)	58.5 $\pm$ 0.3%	<b>76.7 <math>\pm</math> 0.3%</b>
<b>TapNet (Ours)</b>	<b>61.65 <math>\pm</math> 0.15%</b>	<b>76.36 <math>\pm</math> 0.10%</b>

Methods	5-way <i>tiered</i> ImageNet	
	1-shot	5-shot
MAML (as evaluated in (Liu et al., 2018))	51.67 $\pm$ 1.81%	70.30 $\pm$ 1.75%
Prototypical Nets (as evaluated in (Liu et al., 2018))	53.31 $\pm$ 0.89%	72.69 $\pm$ 0.74%
Relation Nets (as evaluated in (Liu et al., 2018))	54.48 $\pm$ 0.93%	71.31 $\pm$ 0.78%
Transductive Propagation Nets (Liu et al., 2018)	59.91 $\pm$ 0.94%	73.30 $\pm$ 0.75%
<b>TapNet (Ours)</b>	<b>63.08 <math>\pm</math> 0.15%</b>	<b>80.26 <math>\pm</math> 0.12%</b>