

$$\bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \Delta} \neg h(a) \wedge \bigwedge_{a \notin \Delta} h(a) \wedge \{O_j^g\}_{j=1}^{|A|} \not\models \perp)$$
**while**  $N \neq 0$  **do**[illegible]
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Figure 1 shows a 4x4 grid with X and Y axes. The start cell is at (1,1) and the goal cell is at (3,1). The grid is divided into three regions: a 3x3 area (red), a 4x4 area (green), and a 5x5 area (blue). The shortest path from the start cell to the goal cell is highlighted in red, passing through (1,2) and (2,2). The goal cell is green.

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**Algorithm 2** An algorithm with caption

[illegible]

end while

plan	0	1	2	3
$a_0$	(0,0)	(1,0)	(2,0)	(3,0)
$a_1$	(0,0)	(1,0)	(2,0)	(3,0)

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