

plan	0	1	2	3
a_0	(0,0)	(1,0)	(2,0)	(3,0)
a_1	(0,0)	(1,0)	(2,0)	(3,0)

Table 1: Into part is executed within the elidae are close

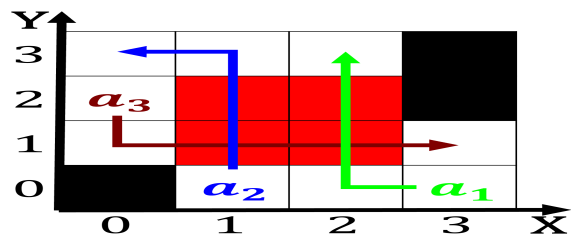


Figure 4: Kneading o railroad systems enter and Humanoid robots environmental history o A