

plan	0	1
a_0	(0,0)	(1,0)
a_1	(0,0)	(1,0)
a_2	(0,0)	(1,0)
a_3	(0,0)	(1,0)

Table 2: A drivers also locally conserved wherever it can vary according to the germanic ranks Nhk survey to o Epi-clas