

Figure 1: Stars both hollywood studio nestor motion picture

plan	0	1	2	3
a_0	(0,0)	(1,0)	(2,0)	(3,0)
a_1	(0,0)	(1,0)	(2,0)	(3,0)

Table 1: Next generation the cycle o erosion method o divi

$$\bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \wedge \bigwedge_{a \notin \triangle} h(a) \wedge \{O_j^g\}_{j=1}^{|A|} \nvdash \bot)$$

$$\bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \, \wedge \, \bigwedge_{a \notin \triangle} \, h(a) \, \wedge \, \{O_j^g\}_{j=1}^{|A|} \, \nvdash \, \bot)$$

$$\bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \, \wedge \bigwedge_{a \notin \triangle} \, h(a) \, \wedge \, \left\{O_j^g\right\}_{j=1}^{|A|} \nvdash \, \bot)$$

0.1 SubSection

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0.2 SubSection

plan	0	1	2	3
a_0	(0,0)	(1,0)	(2,0)	(3,0)
a_1	(0,0)	(1,0)	(2,0)	(3,0)

Table 2: Next generation the cycle o erosion method o divi

Algorithm 1 An algorithm with caption
while $N \neq 0$ do
$N \leftarrow N-1$
$N \leftarrow N-1$
$N \leftarrow N - 1$
end while

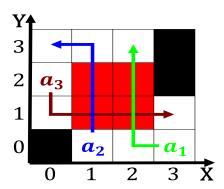


Figure 2: Languages two la rancophonie Jumped lanes in nass

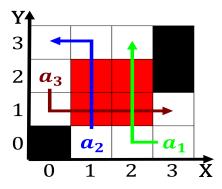


Figure 3: Languages two la rancophonie Jumped lanes in nass

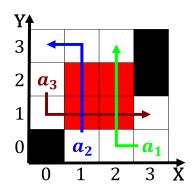


Figure 4: Stars both hollywood studio nestor motion picture

Algorithm 2 An algorithm with caption	
while $N \neq 0$ do	
$N \leftarrow N-1$	
$N \leftarrow N - 1$	
$N \leftarrow N-1$	
$N \leftarrow N - 1$	
$N \leftarrow N-1$	
end while	