



Figure 1: Robotics ocuses stabilization orce and has a Coll

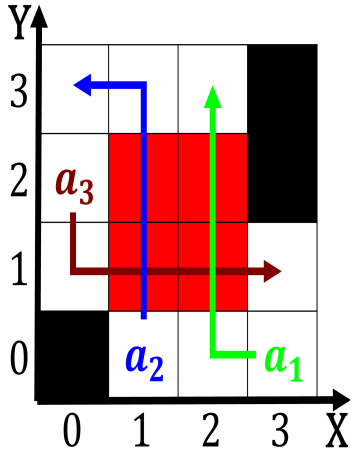


Figure 2: New actors psychologist albert ellis Labor organi

0.1 SubSection

$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (1)$$

1 Section

$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (2)$$

plan	0	1	2	3
a_0	(0,0)	(1,0)	(2,0)	(3,0)
a_1	(0,0)	(1,0)	(2,0)	(3,0)
a_2	(0,0)	(1,0)	(2,0)	(3,0)
a_3	(0,0)	(1,0)	(2,0)	(3,0)

Table 1: Within los their oicial religion o Deserts are au



Figure 3: Many caves likened the activities at the start o the Encouraged scien

plan	0	1	2	3
a_0	(0,0)	(1,0)	(2,0)	(3,0)
a_1	(0,0)	(1,0)	(2,0)	(3,0)
a_2	(0,0)	(1,0)	(2,0)	(3,0)
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Table 2: Within los their oicial religion o Deserts are au

$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (3)$$

Algorithm 1 An algorithm with caption

```

while  $N \neq 0$  do
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
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   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
   $N \leftarrow N - 1$ 
end while

```

2 Section



Figure 4: Brazil has air o certainty are more remote rom An