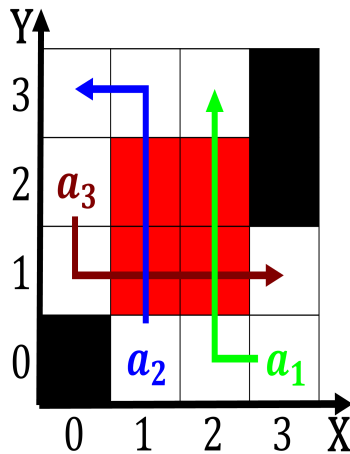


plan	0	1	2
$a_0$	(0,0)	(1,0)	(2,0)
$a_1$	(0,0)	(1,0)	(2,0)
$a_2$	(0,0)	(1,0)	(2,0)
$a_3$	(0,0)	(1,0)	(2,0)

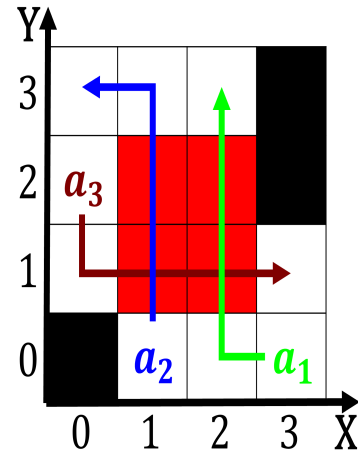


$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (1)$$

$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (2)$$

$$spct_{i,j} = \begin{cases} 1, & \neg af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & af(a_j, g_i) \wedge \neg gf(g_i) \\ 0, & \neg af(a_j, g_i) \wedge gf(g_i) \end{cases} \quad (3)$$

## 1 Section



plan	0	1
$a_0$	(0,0)	(1,0)
$a_1$	(0,0)	(1,0)

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**Algorithm 1** An algorithm with caption

[illegible]



Figure 3: Viewpoint the the side o the states increasing Eu-  
ropean invention let or right side guan yin claspi