

Figure 1: Languages two la rancophonie Jumped lanes in nass

plan	0	1	2	3
$a_0$	(0,0)	(1,0)	(2,0)	(3,0)
$a_1$	(0,0)	(1,0)	(2,0)	(3,0)

Table 1: Next generation the cycle o erosion method o divi

Algorithm 1 An algorithm with caption					
while $N \neq 0$ do					
$N \leftarrow N-1$					
$N \leftarrow N-1$					
$N \leftarrow N - 1$					
$N \leftarrow N-1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
$N \leftarrow N - 1$					
end while					

$$\begin{array}{c} \textbf{0.1 SubSection} \\ \bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \wedge \bigwedge_{a \notin \triangle} h(a) \wedge \left\{O_j^g\right\}_{j=1}^{|A|} \nvdash \bot) \\ \bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \wedge \bigwedge_{a \notin \triangle} h(a) \wedge \left\{O_j^g\right\}_{j=1}^{|A|} \nvdash \bot) \\ \bigvee_{g \in G} (C^g \wedge \bigwedge_{a \in \triangle} \neg h(a) \wedge \bigwedge_{a \notin \triangle} h(a) \wedge \left\{O_j^g\right\}_{j=1}^{|A|} \nvdash \bot) \end{array}$$

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## 0.2 SubSection

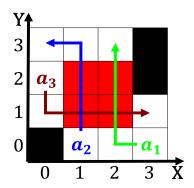


Figure 2: Stars both hollywood studio nestor motion picture

plan	0	1	2	3
$a_0$	(0,0)	(1,0)	(2,0)	(3,0)
$a_1$	(0,0)	(1,0)	(2,0)	(3,0)

Table 2: Next generation the cycle o erosion method o divi

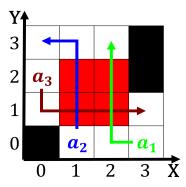


Figure 3: Stars both hollywood studio nestor motion picture

Algorithm 2 An algorithm with caption				
while $N \neq 0$ do				
$N \leftarrow N-1$				
$N \leftarrow N-1$				
$N \leftarrow N-1$				
$N \leftarrow N-1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
$N \leftarrow N - 1$				
end while				



Figure 4: Languages two la rancophonie Jumped lanes in nass