



plan	0	1	2	3
$a_0$	(0,0)	(1,0)	(2,0)	(3,0)
$a_1$	(0,0)	(1,0)	(2,0)	(3,0)
$a_2$	(0,0)	(1,0)	(2,0)	(3,0)

Table 2: Discovery as robots dog therapy robots collective